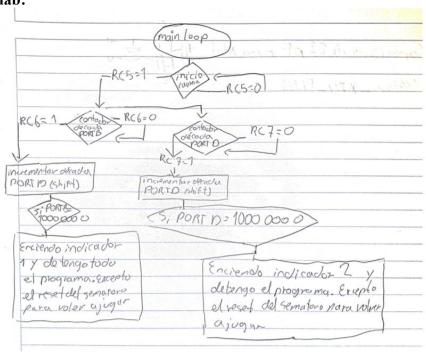
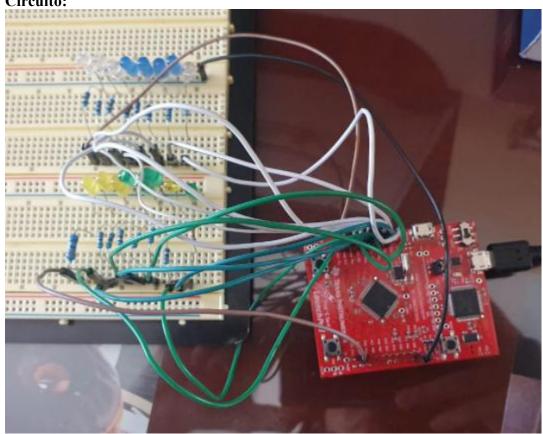
## **REPORTE #4:** Juego de Carreras en TIVA C

Link de repositorio: <a href="https://github.com/Cue19275/Digital2">https://github.com/Cue19275/Digital2</a> Pre-lab:



## Circuito:



## Código:

```
#define J1 1 PB_5
#define J1 2 PB 0
#define J1 3 PB 1
#define J1 4 PE 4
#define J1 5 PE 5
#define J1 6 PB 4
#define J1 7 PA 5
#define J1 8 PA 6
#define J2 1 PD 0
#define J2 2 PD 1
#define J2 3 PD 2
#define J2 4 PD 3
#define J2 5 PE 1
#define J2 6 PE 2
#define J2 7 PE 3
#define J2 8 PD 7
     estadoSalida;
int
int
     estado;
int
     estadoSalidaC2;
int
     estadoC2;
int
     enable J = 0;
int
     terminado = 0;
int
     flagJ1 = 0;
int
     flagJ2 = 0;
     contaJ1 = 0;
int
     contaJ2 = 0;
int
void semaforo (void);
void cont1 (void);
void cont2 (void);
void ganador (void);
void debounce (void);
void debounce2 (void);
void apagado(void);
void setup() {
  pinMode(J1 1, OUTPUT);
  pinMode(J1 2, OUTPUT);
  pinMode(J1 3, OUTPUT);
  pinMode(J1 4, OUTPUT);
  pinMode(J1_5, OUTPUT);
  pinMode(J1 6, OUTPUT);
  pinMode(J1 7, OUTPUT);
  pinMode(J1 8, OUTPUT);
```

pinMode(J2 1, OUTPUT);

```
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  pinMode(J2 2, OUTPUT);
  pinMode(J2 3, OUTPUT);
  pinMode(J2 4, OUTPUT);
  pinMode(J2 5, OUTPUT);
  pinMode(J2 6, OUTPUT);
  pinMode(J2 7, OUTPUT);
  pinMode(J2 8, OUTPUT);
  pinMode(BLUE LED, OUTPUT);
  pinMode(GREEN LED, OUTPUT);
  pinMode(RED LED, OUTPUT);
  pinMode(PUSH1, INPUT PULLUP);
  pinMode(PUSH2, INPUT PULLUP);
}
void loop() {
  // put your main code here, to run repeatedly:
  if (enable J == 0)
    semaforo();
  else if (enable J == 1){
    cont1();
    cont2();
    /*if (terminado == 1)
               estado = digitalRead(PUSH1);
                if (estado == LOW) {
                    estadoSalida=1;
                }
                if (estadoSalida==1){
                    if (estado == HIGH) {
                         estadoSalida =0;
                         flagJ1 = 1;
                    }
                }
                       estadoC2 = digitalRead(PUSH2);
                if (estadoC2 == LOW){}
                    estadoSalidaC2=1;
                }
                if (estadoSalidaC2==1){
                    if (estadoC2 == HIGH){
                         estadoSalidaC2 =0;
                         flagJ2 = 1;
                if (flag J1 == 1 \&\& flag J2 == 1){
                  flagJ2 = 0;
                  flagJ1 = 0;
```

```
enable J = 0;
                  terminado = 0;
    }*/
  delay(200);
void semaforo(void){
         estado = digitalRead(PUSH1);
         if (estado == LOW) {
             estadoSalida=1;
         if (estadoSalida==1){
             if (estado == HIGH) {
                  estadoSalida =0;
                  flagJ1 = 1;
              }
         estadoC2 = digitalRead(PUSH2);
    if (estadoC2 == LOW){}
         estadoSalidaC2=1;
    }
    if (estadoSalidaC2==1){
         if (estadoC2 == HIGH){
             estadoSalidaC2 =0;
             flagJ2 = 1;
    }
         if(flagJ1 == 1 \&\& flagJ2 == 1){
                  apagado();
                  enable J = 1;
                  flagJ1 = 0;
                  flagJ2 = 0;
                  digitalWrite(RED LED, HIGH);
                  digitalWrite(GREEN LED, LOW);
                  digitalWrite(BLUE LED, LOW);
                  delay(500);
                  digitalWrite(BLUE LED, LOW);
                  digitalWrite(RED LED, HIGH);
                  digitalWrite(GREEN LED, HIGH);
                  delay(500);
                  digitalWrite(GREEN LED, HIGH);
                  digitalWrite(RED LED, LOW);
                  digitalWrite(BLUE LED, LOW);
         }
}
```

```
void apagado (void){
  digitalWrite(RED LED, LOW);
  digitalWrite(BLUE LED, LOW);
  digitalWrite(GREEN_LED, LOW);
  digitalWrite(J1 1, LOW);
  digitalWrite(J1 2, LOW);
  digitalWrite(J1 3, LOW);
  digitalWrite(J1 4, LOW);
  digitalWrite(J1 5, LOW);
  digitalWrite(J1 6, LOW);
  digitalWrite(J1 7, LOW);
  digitalWrite(J1 8, LOW);
  digitalWrite(J2 1, LOW);
  digitalWrite(J2 2, LOW);
  digitalWrite(J2 3, LOW);
  digitalWrite(J2 4, LOW);
  digitalWrite(J2_5, LOW);
  digitalWrite(J2 6, LOW);
  digitalWrite(J2 7, LOW);
  digitalWrite(J2 8, LOW);
}
void cont1 (void) {
  estado = digitalRead(PUSH1);
    if (estado == LOW) 
         estadoSalida=1;
    }
    if (estadoSalida==1){
         if (estado == HIGH){
              estadoSalida =0;
              contaJ1++;
              switch(contaJ1){
                case 1:
                digitalWrite(J1 1, HIGH);
                digitalWrite(J1 2, LOW);
                digitalWrite(J1 3, LOW);
                digitalWrite(J1 4, LOW);
                digitalWrite(J1 5, LOW);
                digitalWrite(J1 6, LOW);
                digitalWrite(J1 7, LOW);
                digitalWrite(J1 8, LOW);
                break:
                case 2:
                digitalWrite(J1 1, LOW);
                digitalWrite(J1 2, HIGH);
                digitalWrite(J1 3, LOW);
                digitalWrite(J1 4, LOW);
```

```
digitalWrite(J1 5, LOW);
digitalWrite(J1 6, LOW);
digitalWrite(J1 7, LOW);
digitalWrite(J1 8, LOW);
break;
case 3:
digitalWrite(J1 1, LOW);
digitalWrite(J1 2, LOW);
digitalWrite(J1 3, HIGH);
digitalWrite(J1 4, LOW);
digitalWrite(J1 5, LOW);
digitalWrite(J1 6, LOW);
digitalWrite(J1 7, LOW);
digitalWrite(J1 8, LOW);
break;
case 4:
digitalWrite(J1_1, LOW);
digitalWrite(J1 2, LOW);
digitalWrite(J1 3, LOW);
digitalWrite(J1 4, HIGH);
digitalWrite(J1 5, LOW);
digitalWrite(J1 6, LOW);
digitalWrite(J1 7, LOW);
digitalWrite(J1 8, LOW);
break;
case 5:
digitalWrite(J1 1, LOW);
digitalWrite(J1 2, LOW);
digitalWrite(J1 3, LOW);
digitalWrite(J1 4, LOW);
digitalWrite(J1_5, HIGH);
digitalWrite(J1 6, LOW);
digitalWrite(J1 7, LOW);
digitalWrite(J1 8, LOW);
break;
case 6:
digitalWrite(J1 1, LOW);
digitalWrite(J1 2, LOW);
digitalWrite(J1 3, LOW);
digitalWrite(J1 4, LOW);
digitalWrite(J1 5, LOW);
digitalWrite(J1 6, HIGH);
digitalWrite(J1 7, LOW);
digitalWrite(J1 8, LOW);
break:
case 7:
digitalWrite(J1 1, LOW);
digitalWrite(J1 2, LOW);
digitalWrite(J1 3, LOW);
```

digitalWrite(J1 4, LOW);

```
digitalWrite(J1_5, LOW);
                digitalWrite(J1 6, LOW);
                digitalWrite(J1_7, HIGH);
                digitalWrite(J1_8, LOW);
                break;
                case 8:
                digitalWrite(J1 1, LOW);
                digitalWrite(J1 2, LOW);
                digitalWrite(J1 3, LOW);
                digitalWrite(J1 4, LOW);
                digitalWrite(J1 5, LOW);
                digitalWrite(J1 6, LOW);
                digitalWrite(J1 7, LOW);
                digitalWrite(J1 8, HIGH);
                break;
                case 9:
                contaJ1 = 0;
                contaJ2 = 0;
                enable J = 0;
                digitalWrite(GREEN LED, LOW);
                digitalWrite(RED_LED, HIGH);
                digitalWrite(BLUE LED, HIGH);
                break;
         }
    }
}
void cont2 (void) {
         estadoC2 = digitalRead(PUSH2);
    if(estadoC2 == LOW){
         estadoSalidaC2=1;
    }
    if (estadoSalidaC2==1){
         if (estadoC2 == HIGH){
              estadoSalidaC2 =0;
              contaJ2++;
              switch(contaJ2){
                case 1:
                digitalWrite(J2 1, HIGH);
                digitalWrite(J2 2, LOW);
                digitalWrite(J2 3, LOW);
                digitalWrite(J2 4, LOW);
                digitalWrite(J2 5, LOW);
                digitalWrite(J2 6, LOW);
                digitalWrite(J2 7, LOW);
```

```
digitalWrite(J2 8, LOW);
break;
case 2:
digitalWrite(J2 1, LOW);
digitalWrite(J2_2, HIGH);
digitalWrite(J2 3, LOW);
digitalWrite(J2 4, LOW);
digitalWrite(J2 5, LOW);
digitalWrite(J2 6, LOW);
digitalWrite(J2 7, LOW);
digitalWrite(J2 8, LOW);
break;
case 3:
digitalWrite(J2 1, LOW);
digitalWrite(J2 2, LOW);
digitalWrite(J2_3, HIGH);
digitalWrite(J2 4, LOW);
digitalWrite(J2 5, LOW);
digitalWrite(J2 6, LOW);
digitalWrite(J2 7, LOW);
digitalWrite(J2 8, LOW);
break;
case 4:
digitalWrite(J2 1, LOW);
digitalWrite(J2 2, LOW);
digitalWrite(J2 3, LOW);
digitalWrite(J2 4, HIGH);
digitalWrite(J2 5, LOW);
digitalWrite(J2 6, LOW);
digitalWrite(J2 7, LOW);
digitalWrite(J2 8, LOW);
break;
case 5:
digitalWrite(J2 1, LOW);
digitalWrite(J2 2, LOW);
digitalWrite(J2 3, LOW);
digitalWrite(J2 4, LOW);
digitalWrite(J2 5, HIGH);
digitalWrite(J2 6, LOW);
digitalWrite(J2 7, LOW);
digitalWrite(J2 8, LOW);
break;
case 6:
digitalWrite(J2 1, LOW);
digitalWrite(J2 2, LOW);
digitalWrite(J2 3, LOW);
digitalWrite(J2 4, LOW);
digitalWrite(J2 5, LOW);
digitalWrite(J2 6, HIGH);
digitalWrite(J2 7, LOW);
```

```
digitalWrite(J2_8, LOW);
                break;
                case 7:
                digitalWrite(J2_1, LOW);
                digitalWrite(J2_2, LOW);
                digitalWrite(J2_3, LOW);
                digitalWrite(J2 4, LOW);
                digitalWrite(J2 5, LOW);
                digitalWrite(J2_6, LOW);
                digitalWrite(J2 7, HIGH);
                digitalWrite(J2 8, LOW);
                break;
                case 8:
                digitalWrite(J2 1, LOW);
                digitalWrite(J2 2, LOW);
                digitalWrite(J2_3, LOW);
                digitalWrite(J2 4, LOW);
                digitalWrite(J2_5, LOW);
                digitalWrite(J2 6, LOW);
                digitalWrite(J2 7, LOW);
                digitalWrite(J2 8, HIGH);
                break;
                case 9:
                contaJ2 = 0;
                contaJ1 = 0;
                enable J = 0;
                digitalWrite(GREEN_LED, HIGH);
                digitalWrite(BLUE LED, HIGH);
                break;
             }
         }
    }
}
```