$091\mathrm{M}4041\mathrm{H}$ - Algorithm Design and Analysis

Assignment 1

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1 Problem One

You are interested in analyzing some hard-to-obtain data from two separate databases. Each database contains n numerical values, so there are 2n values total and you may assume that no two values are the same. You'd like to determine the median of this set of 2n values, which we will define here to be the nth smallest value.

However, the only way you can access these values is through queries to the databases. In a single query, you can specify a value k to one of the two databases, and the chosen database will return the kth smallest value that it contains. Since queries are expensive, you would like to compute the median using as few queries as possible.

Give an algorithm that finds the median value using at most O(logn) queries.

1.1 Algorithm Description

To find the midian value of the two databases, the algorithm finds the middle of two databases and compare them. In every operation, find the correct part midian value should exist in. Repeat find the middle of the remain part until the two middles are equal.

Algorithm 1 Find the midian value in two databases

```
1: function MIDIANSEARCH(arrayA, arrayB, n)
       leftA = leftB = 0;
2:
       rightA = rightB = n;
3:
       while true do
4:
          midianA = arrayA[[(rightA - leftA)/2] - 1];
5:
          midianB = arrayB[[(rightB - leftB)/2] - 1];
6:
          if \lceil (rightA - leftA)/2 \rceil == 1 then
7:
              return min(arrayA[0], arrayB[0]);
8:
          end if
9:
          if midianA == midianB then
10:
              return midianA;
11:
          end if
12:
          if midian A > midian B then
13:
              rightA = (rightA - leftA)/2;
14:
             leftB = (rightB - leftB)/2
15:
          else
16:
              rightB = (rightB - leftB)/2;
17:
             leftA = (rightA - leftA)/2
18:
          end if
19:
       end while
20:
21: end function
```

1.2 subproblem reduction graph

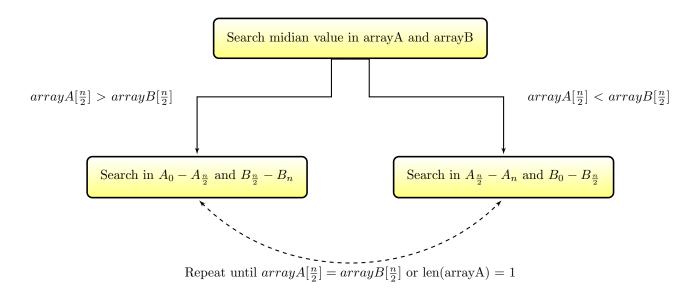


Figure 1: Subproblem reduction graph in problem one

1.3 the correctness of the algorithm

For n = 1, the answer is min(A[0], B[0]).

For n > 1, we choose the midian value of the two databases $A[\frac{n}{2}]$ and $B[\frac{n}{2}]$. If $A[\frac{n}{2}] > B[\frac{n}{2}]$, because the two databases are already sorted, the midian value must be in the part that the value is smaller than $A[\frac{n}{2}]$ and bigger than $B[\frac{n}{2}]$. Also if $A[\frac{n}{2}] < B[\frac{n}{2}]$, the midian value must be in the part that the value is bigger than $A[\frac{n}{2}]$ and smaller than $B[\frac{n}{2}]$. In the next operation, we can find the remain of the part in two databases. And if $A[\frac{n}{2}] = B[\frac{n}{2}]$, we can know that the number the front part of $A[\frac{n}{2}]$ and $B[\frac{n}{2}]$ is equal to the later part. So the answer is $A[\frac{n}{2}]$ or $A[\frac{n}{2}]$. So repeat the operation of finding the midian of the two searchable parts until we find $A[\frac{n}{2}] = B[\frac{n}{2}]$ or the number of the remain part is 1. The answer is indeed correct.

1.4 the complexity of the algorithm

Because we only find the middle of two array, we can describe the complexity as $T(n) = 2T(n/2) = O(\log n)$.

2 Problem Two

Given a binary tree, suppose that the distance between two adjacent nodes is 1, please give a solution to find the maximum distance of any two node in the binary tree.

2.1 Algorithm Description

The algorithm finds the maximum distance in left and right subtree throung the current root node.

Algorithm 2 Find the max distance in a binary tree

```
1: static MaxLen = 0;
 2: function FINDMAXLEN(BTreeroot)
        if root == NULL then
            return 0;
 4:
        end if
 5:
        if root \rightarrow left == NULL then
 6:
 7:
            root \rightarrow MaxLeftDistance = 0;
        end if
 8:
        if root \rightarrow right == NULL then
 9:
            root \rightarrow MaxRightDistance = 0;
10:
        end if
11:
12:
        if root \rightarrow left! = NULL then
            FindMaxLen(root \rightarrow left);
13:
            if root\rightarrow left \rightarrow MaxLeftDistance > root \rightarrow left \rightarrow MaxRightDistance then
14:
                root \rightarrow MaxLeftDistance = root \rightarrow left \rightarrow MaxLeftDistance + 1
15:
            else
16:
                \operatorname{root} \to MaxLeftDistance = root \to left \to MaxRightDistance + 1
17:
            end if
18:
        end if
19:
        if root \rightarrow right! = NULL then
20:
            FindMaxLen(root \rightarrow right);
21:
            if root \rightarrow right \rightarrow MaxLeftDistance > root \rightarrow right \rightarrow MaxRightDistance then
22:
                \text{root} \rightarrow MaxRightDistance = root \rightarrow right \rightarrow MaxLeftDistance + 1
23:
24:
            else
                root \rightarrow MaxRightDistance = root \rightarrow right \rightarrow MaxRightDistance + 1
25:
            end if
26:
        end if
27:
        if root \rightarrow MaxRightDistance + root \rightarrow MaxRightDistance > MaxLen then
28:
29:
            MaxLen = root \rightarrow MaxRightDistance + root \rightarrow MaxRightDistance;
        end if
30:
31: end function
```

2.2 subproblem reduction graph

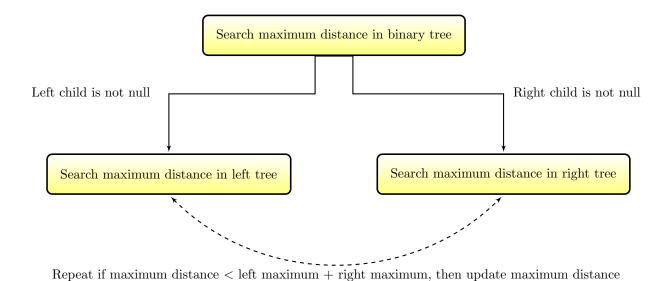


Figure 2: Subproblem reduction graph in problem two

2.3 the correctness of the algorithm

We assumpe the two nodes farthest from the Kth subtree: u_k and v_k , whose distance is defined as $d(u_k, v_k)$, then the node u_k or v_k is the node with the longest distance from the subtree K to the root node R_k . Without loss of generality, we set u_k to be the node with the longest distance R_k from the root node in subtree K, and its distance from the root node is defined as $d(u_k, R)$. Taking the two largest values max_1 and max_2 of $d(u_i, R)(1 \ge i \ge k)$, then the longest path through the root node R is $max_1 + max_2 + 2$, so the farthest distance in the tree R is The distance between the two points is: $max(d(u_i, v_i), ..., d(u_k, v_k), max_1 + max_2 + 2)$. So the algorithm is correct.

2.4 the complexity of the algorithm

Beccause the algorithm searches the left and right child in the binary tree, the complexity is equal to the problem of searching in binary tree as O(logn).

3 Problem Three

Consider an n-node complete binary tree T, where $n = 2^d - 1$ for some d. Each node v of T is labeled with a real number x_v . You may assume that the real numbers labeling the nodes are all distinct. A node v of T is a local minimum if the label x_v is less than the label x_w for all nodes w that are joined to v by an edge.

You are given such a complete binary tree T, but the labeling is only specifed in the following implicit way: for each node v, you can determine the value x_v by probing the node v. Show how to find a local minimum of T using only $O(\log n)$ probes to the nodes of T.

3.1 Algorithm Description

The algorithm searches a local minimum in complete binary tree. In every operation, find the left and right child who is smaller than current nodes.

Algorithm 3 Find a local minimum in complete binary tree

```
1: function FINDLOCALMIN(BTreeroot)
         if root == NULL then
 2:
             return 0;
 3:
         end if
 4:
         if root \rightarrow left == NULL and root \rightarrow right == NULL then
 5:
 6:
             return root \rightarrow value;
         end if
 7:
         if root \rightarrow value < root \rightarrow left \rightarrow value and root \rightarrow value < root \rightarrow right \rightarrow value then
 8:
             return root \rightarrow value;
 9:
         end if
10:
         if root \rightarrow value \geq root \rightarrow left \rightarrow value then
11:
12:
             FindLocalMin(root \rightarrow left);
         end if
13:
         if root \rightarrow value \geq root \rightarrow right \rightarrow value then
14:
             FindLocalMin(root \rightarrow right);
15:
         end if
16:
17: end function
```

3.2 subproblem reduction graph

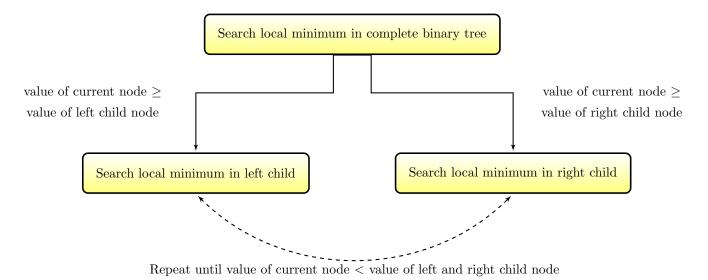


Figure 3: Subproblem reduction graph in problem three

3.3 the correctness of the algorithm

We know that a local minimum is smaller than the other nodes connect with it. From the root of the binary tree, searching in the root's left and right subtree, we must be able to find a set of descending nodes described as $(v_0, v_1, ..., v_n)$ and the n th node is indeed the local minimum we look for. So the algorithm is correct.

3.4 the complexity of the algorithm

Beccause the algorithm searches the left and right child in the binary tree, the complexity is equal to the problem of searching in binary tree as O(logn).