

rapp-platform

```
graph LR; subgraph rapp_platform [rapp-platform]; subgraph inner_box; direction LR; A[rapp_path_planning]; B[rapp_map_server]; C[rapp_costmap2d]; D[rapp_path_planning]; end; end;
```

rapp_path_planning

rapp_map_server

rapp_costmap2d

rapp_path_planning