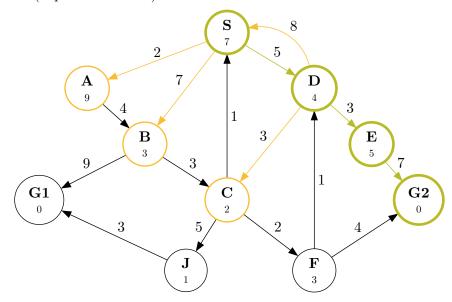
# 1 E.A.3.1

## 1.1 Ricerca in profondità

DFS (depth first search)



#		azioni	esplorati	frontiera
0	Ø	{}	{}	[ (S, g: 0, h: 7, f: 7, d: 0), ]
1	S	{A, B, D}	{S}	[     (A, g: 2, h: 9, f: 11, d: 1),     (B, g: 7, h: 3, f: 10, d: 1),     (D, g: 5, h: 4, f: 9, d: 1), ]
2	D	{C, E, S}	{D, S}	[ (A, g: 2, h: 9, f: 11, d: 1), (B, g: 7, h: 3, f: 10, d: 1), (C, g: 8, h: 2, f: 10, d: 2), (E, g: 8, h: 5, f: 13, d: 2), ]
3	E	{G2}	{D, E, S}	[     (A, g: 2, h: 9, f: 11, d: 1),     (B, g: 7, h: 3, f: 10, d: 1),     (C, g: 8, h: 2, f: 10, d: 2),     (G2, g: 15, h: 0, f: 15, d: 3), ]
4	G2	{}	{D, E, G2, S}	is goal

**Percorso**  $S \to D \to E \to G2$ 

Costo 5 + 3 + 7 = 15

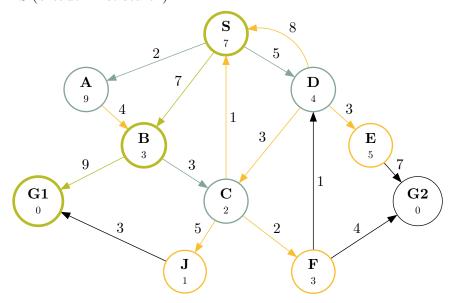
Iterazioni 1

Ottimalità il cammino non è ottimale (il costo ottimale è 14)

Generalmente la DFS non garantisce l'ottimalità

# 1.2 Ricerca in ampiezza

BFS (breadth first search)



#		azioni	esplorati	frontiera
0	Ø	{}	{}	[ (S, g: 0, h: 7, f: 7, d: 0), ]
1	S	{A, B, D}	{S}	[ (A, g: 2, h: 9, f: 11, d: 1), (B, g: 7, h: 3, f: 10, d: 1), (D, g: 5, h: 4, f: 9, d: 1), ]
2	А	{B}	{A, S}	[ (A, g: 2, h: 9, f: 11, d: 1), (B, g: 7, h: 3, f: 10, d: 1), (D, g: 5, h: 4, f: 9, d: 1), ]
3	В	{C, G1}	{A, B, S}	[     (D, g: 5, h: 4, f: 9, d: 1),     (C, g: 10, h: 2, f: 12, d: 2),     (G1, g: 16, h: 0, f: 16, d: 2), ]
4	D	{C, E, S}	{A, B, D, S}	[ (C, g: 10, h: 2, f: 12, d: 2), (G1, g: 16, h: 0, f: 16, d: 2), (E, g: 8, h: 5, f: 13, d: 2), ]

#		azioni	esplorati	frontiera
5	С	{F, J, S}	{A, B, C, D, S}	[ (G1, g: 16, h: 0, f: 16, d: 2), (E, g: 8, h: 5, f: 13, d: 2), (F, g: 12, h: 3, f: 15, d: 3), (J, g: 15, h: 1, f: 16, d: 3), ]
6	G1	{}	{A, B, D, G1, S}	is goal

**Percorso**  $S \to B \to G1$ 

Costo 7 + 9 = 16

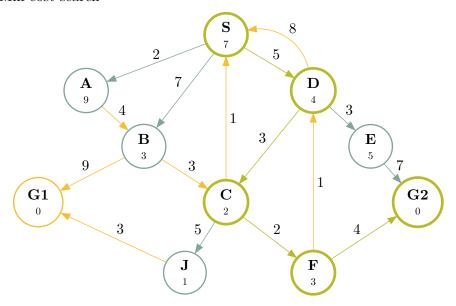
Iterazioni 1

Ottimalità il cammino non è ottimale

Generalmente la BFS garantisce l'ottimalità solo se il costo per tutte le azioni è lo stesso (perché la BFS trova il minor numero di azioni per raggiungere l'obiettivo)

## 1.3 Ricerca a costi uniformi

Min cost search



#		azioni	esplorati	frontiera
0	Ø	{}	{}	{     (S, g: 0, h: 7, f: 7, d: 0), }
1	S	{A, B, D}	{S}	{     (A, g: 2, h: 9, f: 11, d: 1),     (D, g: 5, h: 4, f: 9, d: 1),     (B, g: 7, h: 3, f: 10, d: 1), }
2	А	{B}	{A, S}	{     (D, g: 5, h: 4, f: 9, d: 1),     (B, g: 6, h: 3, f: 9, d: 2), }
3	D	{C, E, S}	{A, D, S}	{     (B, g: 6, h: 3, f: 9, d: 2),     (C, g: 8, h: 2, f: 10, d: 2),     (E, g: 8, h: 5, f: 13, d: 2), }
4	В	{C, G1}	{A, B, D, S}	{     (C, g: 8, h: 2, f: 10, d: 2),     (E, g: 8, h: 5, f: 13, d: 2),     (G1, g: 15, h: 0, f: 15, d: 3), }

#		azioni	esplorati	frontiera
5	С	{F, J, S}	{A, B, C, D, S}	{     (E, g: 8, h: 5, f: 13, d: 2),     (F, g: 10, h: 3, f: 13, d: 3),     (J, g: 13, h: 1, f: 14, d: 3),     (G1, g: 15, h: 0, f: 15, d: 3), }
6	E	{G2}	{A, B, C, D, E, S}	{     (F, g: 10, h: 3, f: 13, d: 3),     (J, g: 13, h: 1, f: 14, d: 3),     (G1, g: 15, h: 0, f: 15, d: 3),     (G2, g: 15, h: 0, f: 15, d: 3), }
7	F	{D, G2}	{A, B, C, D, E, F, S}	{     (J, g: 13, h: 1, f: 14, d: 3),     (G2, g: 14, h: 0, f: 14, d: 4),     (G1, g: 15, h: 0, f: 15, d: 3), }
8	J	{G1}	{A, B, C, D, E, F, J, S}	{     (G2, g: 14, h: 0, f: 14, d: 4),     (G1, g: 15, h: 0, f: 15, d: 3), }
9	G2	{}	{A, B, C, D, E, F, G2, J, S}	is goal

**Percorso**  $S \to D \to C \to F \to G2$ 

Costo 5 + 3 + 2 + 4 = 14

Iterazioni 1

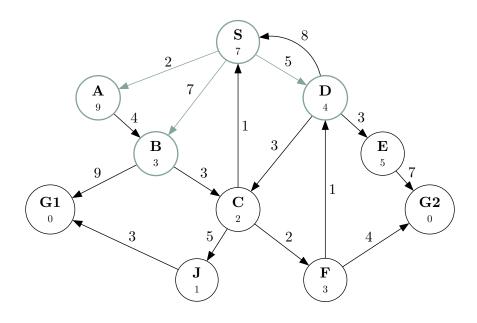
Ottimalità il costo è quello ottimale

 $\operatorname{L'algoritmo}$  Min cost trova sempre il cammino ottimale (tranne in grafi infiniti)

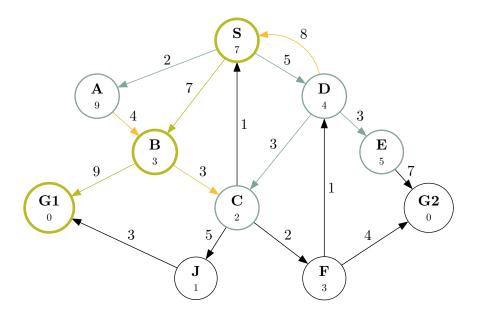
## 1.4 Ricerca ad approfondimento iterativo

Iterative deepening search

#### 1.4.1 Iterazione 1



#### 1.4.2 Iterazione 2

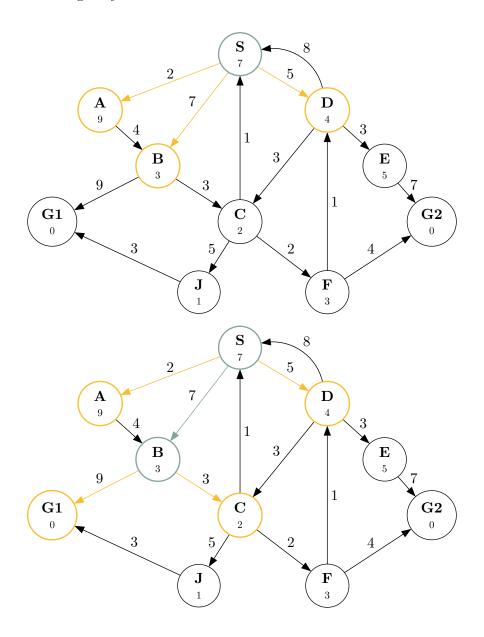


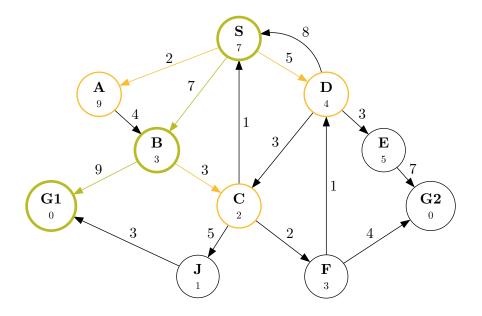
#		azioni	esplorati	frontiera
0	Ø	{}	{}	[ (S, g: 0, h: 7, f: 7, d: 0), ]
1	S	{A, B, D}	{S}	[ (A, g: 2, h: 9, f: 11, d: 1), (B, g: 7, h: 3, f: 10, d: 1), (D, g: 5, h: 4, f: 9, d: 1), ]
2	D	{}	{D, S}	[     (A, g: 2, h: 9, f: 11, d: 1),     (B, g: 7, h: 3, f: 10, d: 1), ]
3	В	{}	{B, D, S}	[ (A, g: 2, h: 9, f: 11, d: 1), ]
4	Α	{}	{A, B, D, S}	[]
5	Ø	{}	{}	[ (S, g: 0, h: 7, f: 7, d: 0), ]
6	S	{A, B, D}	<b>{</b> S}	[ (A, g: 2, h: 9, f: 11, d: 1), (B, g: 7, h: 3, f: 10, d: 1), (D, g: 5, h: 4, f: 9, d: 1), ]
7	D	{C, E, S}	{D, S}	[ (A, g: 2, h: 9, f: 11, d: 1), (B, g: 7, h: 3, f: 10, d: 1), (C, g: 8, h: 2, f: 10, d: 2), (E, g: 8, h: 5, f: 13, d: 2), ]
8	E	{}	{D, E, S}	[     (A, g: 2, h: 9, f: 11, d: 1),     (B, g: 7, h: 3, f: 10, d: 1),     (C, g: 8, h: 2, f: 10, d: 2), ]
9	С	{}	{C, D, E, S}	[     (A, g: 2, h: 9, f: 11, d: 1),     (B, g: 7, h: 3, f: 10, d: 1), ]
10	В	{C, G1}	{B, C, D, E, S}	[     (A, g: 2, h: 9, f: 11, d: 1),     (G1, g: 16, h: 0, f: 16, d: 2), ]
11	G1	{}	{B, C, D, E, G1, S}	is goal

 $\begin{tabular}{ll} \bf Percorso & S \rightarrow B \rightarrow G1 \\ \bf Costo & 7 + 9 = 16 \\ \bf Iterazioni & 2 \\ \bf Ottimalità & il percorso non è ottimale \\ \end{tabular}$ 

## 1.5 Ricerca best-first greedy

Best-first greedy search





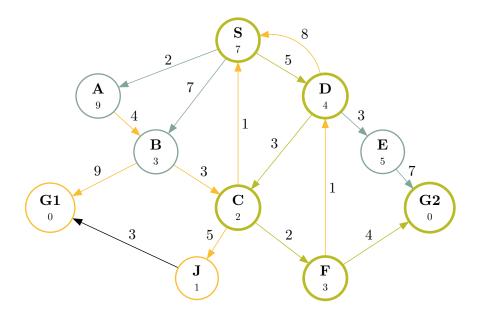
#		azioni	esplorati	frontiera
0	Ø	{}	{}	{     (S, g: 0, h: 7, f: 7, d: 0), }
1	S	{A, B, D}	<b>{S</b> }	{     (B, g: 7, h: 3, f: 10, d: 1),     (D, g: 5, h: 4, f: 9, d: 1),     (A, g: 2, h: 9, f: 11, d: 1), }
2	В	{C, G1}	{B, S}	{     (G1, g: 16, h: 0, f: 16, d: 2),     (C, g: 10, h: 2, f: 12, d: 2),     (D, g: 5, h: 4, f: 9, d: 1),     (A, g: 2, h: 9, f: 11, d: 1), }
3	G1	{}	{B, <b>G1</b> , S}	is goal

 $\mathbf{Percorso}\ \mathrm{S} \to \mathrm{B} \to \mathrm{G1}$ 

Costo 7 + 9 = 16

Iterazioni 1

Ottimalità la soluzione non è ottimale



#		azioni	esplorati	frontiera
0	Ø	{}	{}	{ (S, g: 0, h: 7, f: 7, d: 0), }
1	S	{A, B, D}	<b>{</b> S <b>}</b>	{     (D, g: 5, h: 4, f: 9, d: 1),     (B, g: 7, h: 3, f: 10, d: 1),     (A, g: 2, h: 9, f: 11, d: 1), }
2	D	{C, E, S}	{D, S}	{     (B, g: 7, h: 3, f: 10, d: 1),     (C, g: 8, h: 2, f: 10, d: 2),     (A, g: 2, h: 9, f: 11, d: 1),     (E: g: 8, h: 5, f: 13, d: 2), }
3	В	{C, G1}	{B, D, S}	{     (C, g: 8, h: 2, f: 10, d: 2),     (A, g: 2, h: 9, f: 11, d: 1),     (E: g: 8, h: 5, f: 13, d: 2),     (G1: g: 16, h: 0, f: 16, d: 2), }
4	С	{F, J, S}	{B, C, D, S}	{     (A, g: 2, h: 9, f: 11, d: 1),

#		azioni	esplorati	frontiera
				(E: g: 8, h: 5, f: 13, d: 2), (F: g: 10, h: 3, f: 13, d: 3), (J: g: 13, h: 1, f: 14, d: 3), (G1: g: 16, h: 0, f: 16, d: 2), }
5	А	{B}	{A, B, C, D, S}	{     (E: g: 8, h: 5, f: 13, d: 2),     (F: g: 10, h: 3, f: 13, d: 3),     (J: g: 13, h: 1, f: 14, d: 3),     (G1: g: 16, h: 0, f: 16, d: 2), }
6	E	{G2}	{A, B, C, D, E, S}	{     (F: g: 10, h: 3, f: 13, d: 3),     (J: g: 13, h: 1, f: 14, d: 3),     (G2: g: 15, h: 0, f: 15, d: 3),     (G1: g: 16, h: 0, f: 16, d: 2), }
7	F	{D, G2}	{A, B, C, D, E, F, S}	{     (G2, g: 14, h: 0, f: 14, d: 4),     (J: g: 13, h: 1, f: 14, d: 3),     (G1, g: 16, h: 0, f: 16, d: 2), }
8	G2	{}	{A, B, C, D, E, F, G2, S}	is goal

**Percorso**  $S \to D \to C \to F \to G2$ 

Costo 5 + 3 + 2 + 4 = 14

Iterazioni 1

Ottimalità la soluzione è ottimale

L'algoritmo  $\mathbf{A}^*$  è ottimale quando la funzione h(s) è consistente (quindi anche ammissibile)

#### 1.7 Euristica

Come si nota dalla tabella sotto l'euristica **è ammissibile**, perché per ogni stato s vale h(s) è minore o uguale al costo minimo per raggiungere un obiettivo.

s	h(s)	$\operatorname{dist}(s)$
A	4	13
В	3	9
С	2	6
D	4	9
Е	5	7
F	3	4
G1	0	0
G2	0	0
J	1	3
S	7	14

L'euristica non è consistente perché 9 = h(A) > 4 + h(B) = 4 + 3 = 7, è solo un caso che  $A^*$  trova il percorso ottimale in questo esempio.