Keyu Chen

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CurryChen77 | \$\mathbf{9}\$ Google Scholar

Beijing, China

RESEARCH INTERESTS

My research centers on traffic simulation and motion planning for autonomous driving, with a particular emphasis on creating realistic, interactive, and controllable traffic scenarios. I am passionate about developing reliable closed-loop simulation frameworks to accelerate the safe, robust, and scalable advancement of autonomous driving systems.

EDUCATION

• Tsinghua University (THU)

September 2023 - July 2028(Expected)

Ph.D. student at the School of Vehicle and Mobility, supervised by Prof. Sifa Zheng.

Beijing, China

• Nanjing University of Aeronautics and Astronautics (NUAA)

September 2019 - July 2023

B.Eng. in Vehicle Engineering. Grade: 4.1/5 (Top 2%)

Nanjing, China

FIRST AUTHOR PUBLICATIONS

[arXiv 2025] RIFT: Group-Relative RL Fine-Tuning for Realistic and Controllable Traffic Simulation.

Keyu Chen, Wenchao Sun, Hao Cheng, Sifa Zheng.

Paper, Project Page, Code

[CoRL 2025] FREA: Feasibility-Guided Generation of Safety-Critical Scenarios with Reasonable Adversariality.

Keyu Chen, Yuheng Lei, Hao Cheng, Haoran Wu, Wenchao Sun, Sifa Zheng. (Oral 4.3%)

Paper, Project Page, Code

[KBS 2023] IGT: Illumination-guided RGB-T object detection with transformers.

Keyu Chen, Jinqiang Liu, Han Zhang. (Bachelors thesis)

Paper

CO-AUTHOR PUBLICATIONS

[arXiv 2025] DriveCamSim: Generalizable Camera Simulation via Explicit Camera Modeling for Autonomous

Driving.

Wenchao Sun, Xuewu Lin, Keyu Chen, Zixiang Pei, Yining Shi, Chuang Zhang, Sifa Zheng.

Paper, Code

[TRC 2025] Emergency Index (EI): A two-dimensional surrogate safety measure considering vehicles interaction

Hao Cheng, Yanbo Jiang, Hailun Zhang, Keyu Chen, Heye Huang, Shaobing Xu, Jianqiang Wang, Sifa

Zheng.

Paper, Code

HONORS AND AWARDS

Outstanding Graduate (Top 1%), NUAA

June 2023

Outstanding Bachelor Thesis Award (Top 5%), NUAA

June 2023

National Scholarship (Top 1%), NUAA

December 2021