

MEETING: 11.4.2022 (WITH SUPERVISORS)

·) PARTICIPANTS: EVERYONE BUT MIKO, LAURA

·) AGENDA: ① PRESENTATION OF WORK / SPRINT DEMO

② NEXT SPRINT

① → DEMOS HAVE BEEN PRESENTED

·) ROBOT MOV. : ABS. ANGLES, BUTTONS AS INPUT, ESP NOT DONE

·) ESP AND NODE-RED (MQTT) : CAMERA ALSO CONNECTED, MESSAGES ARE COMING IN

·) RIPENESS DETECTION : RED / GREEN WORKS, MAKE IT WORK ON ZED

·) PROTOCOL : 0 → NOT RIPE, 1 → RIPE

·) SYSTEM DOCUMENT : (JUST HAS BEEN SHOWN / CAN BE FOUND ON GITHUB)

L> THINK ABOUT THE BIG PICTURE

L> LOOK AT THE SYSTEM AS A WHOLE

L> SMART - GOAL

L> THINK ABOUT ROBOT CHALLENGES / TASKS

FOR EVERYONE WHO DOESN'T KNOW:

⇒ TECHNIQUE TO DEFINE PROJECT GOALS PRECISE

② → SYSTEM SET UP

→ TEST WITH PING PONG BALLS

→ BETTER VISUALISATION

→ DOCUMENT CORRECTION

→ WORK DISTRIBUTION CAN BE SEEN ON TRELLO

·) MORE DETAILED CARDS ⇒ CHECK TRELLO