To do:

* System description (what does the system do, and why)
  + List the different parts of the system in this paragraph
  + List of ideas associated with developing this project
  + Hardware list
* Glossary (meanings of terms used which aren’t “conventional”)
* Should/could list
* Maths
* Hardware
  + Morobot
    - Movement/aiming
  + ESP32 and Arduino Uno
    - Controlling Morobot
    - Communication via MQTT
  + Zed 2 Stereo Camera
    - Input for Machine learning
  + Jetson Nano
    - Process Zed Camera input
    - Berry/bug detection

Short explanation of the system flow:

* a bug is on the Zed 2 Camera feed
  + bug detection algorithm running on Jetson Nano detects the bug
    - message is sent to ESP32/Arduino which controls Morobot
      * for example, Morobot aims and shoots bug repellent at the bug