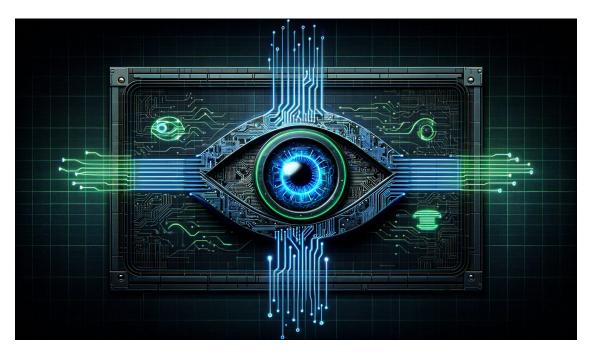
## AlexNet

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## 1 The Code Behind AlexNet

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```
[1]: # PyTorch for creating and training the neural network
import torch
import torch.nn as nn
import torch.optim as optim
from torch.utils.data.dataset import random_split

# platform for getting the operating system
import platform

# torchvision for loading and transforming the dataset
import torchvision
import torchvision.transforms as transforms

# ReduceLROnPlateau for adjusting the learning rate
```

```
from torch.optim.lr_scheduler import ReduceLROnPlateau

# numpy for numerical operations
import numpy as np

# matplotlib for plotting
import matplotlib.pyplot as plt
```

```
[]: class AlexNet(nn.Module):
         AlexNet model
         Args:
             num_classes (int): number of classes in the dataset. Default is 1000.
         def __init__(self, num_classes=1000):
             super(AlexNet, self). init ()
             self.features = nn.Sequential(
                 nn.Conv2d(3, 64, kernel_size=11, stride=4, padding=2),
                 nn.ReLU(inplace=True),
                 nn.MaxPool2d(kernel_size=3, stride=2),
                 nn.Conv2d(64, 192, kernel_size=5, padding=2),
                 nn.ReLU(inplace=True),
                 nn.MaxPool2d(kernel_size=3, stride=2),
                 nn.Conv2d(192, 384, kernel_size=3, padding=1),
                 nn.ReLU(inplace=True),
                 nn.Conv2d(384, 256, kernel_size=3, padding=1),
                 nn.ReLU(inplace=True),
                 nn.Conv2d(256, 256, kernel_size=3, padding=1),
                 nn.ReLU(inplace=True),
                 nn.MaxPool2d(kernel_size=3, stride=2),
             self.avgpool = nn.AdaptiveAvgPool2d((6, 6))
             self.classifier = nn.Sequential(
                 nn.Dropout(),
                 nn.Linear(256 * 6 * 6, 4096),
                 nn.ReLU(inplace=True),
                 nn.Dropout(),
                 nn.Linear(4096, 4096),
                 nn.ReLU(inplace=True),
                 nn.Linear(4096, num_classes),
             )
         def forward(self, x):
             Forward pass of the model
```

```
Args:
    x (torch.Tensor): input tensor of shape (N, C, H, W)

Returns:
    torch.Tensor: output tensor of shape (N, num_classes)
"""

x = self.features(x)
x = self.avgpool(x)
x = torch.flatten(x, 1)
x = self.classifier(x)
return x
```

```
[2]: class EarlyStopping:
         11 11 11
         Early stopping to stop the training when the loss does not improve after
         Args:
             patience (int): Number of epochs to wait before stopping the training.
             verbose (bool): If True, prints a message for each epoch where the loss
                              does not improve.
             delta (float): Minimum change in the monitored quantity to qualify as \sqcup
      \hookrightarrow an improvement.
         n n n
         def __init__(self, patience=7, verbose=False, delta=0):
             self.patience = patience
             self.verbose = verbose
             self.counter = 0
             self.best_score = None
             self.early_stop = False
             self.delta = delta
         def __call__(self, val_loss):
             Arqs:
                 val_loss (float): The validation loss to check if the model_
      ⇒performance improved.
             Returns:
                 bool: True if the loss did not improve, False if it improved.
             score = -val_loss
             if self.best_score is None:
                 self.best_score = score
```

```
elif score < self.best_score + self.delta:
    self.counter += 1
    if self.counter >= self.patience:
        self.early_stop = True
else:
    self.best_score = score
    self.counter = 0
```

```
[3]: class Trainer:
         Trainer class to train the model.
         Arqs:
             model (nn.Module): Neural network model.
              criterion (torch.nn.modules.loss): Loss function.
              optimizer (torch.optim): Optimizer.
              device (torch.device): Device to run the model on.
             patience (int): Number of epochs to wait before stopping the training.
         def __init__(self, model, criterion, optimizer, device, patience=7):
             self.model = model
             self.criterion = criterion
             self.optimizer = optimizer
             self.device = device
             self.early_stopping = EarlyStopping(patience=patience)
             self.scheduler = ReduceLROnPlateau(self.optimizer, 'min', patience=3,__
      →verbose=True, factor=0.5, min_lr=1e-6)
             self.train losses = []
             self.val losses = []
             self.gradient_norms = []
         def train(self, train_loader, val_loader, epochs):
              ,, ,, ,,
              Train the model.
             Args:
                  train\_loader\ (torch.utils.data.DataLoader) \colon \textit{DataLoader for training} \sqcup
      \hookrightarrow dataset.
                  val_loader (torch.utils.data.DataLoader): DataLoader for validation
      \hookrightarrow dataset.
                  epochs (int): Number of epochs to train the model.
              for epoch in range(epochs):
                  self.model.train()
                  for images, labels in train_loader:
```

```
images, labels = images.to(self.device), labels.to(self.device)
               self.optimizer.zero_grad()
               outputs = self.model(images)
               loss = self.criterion(outputs, labels)
               loss.backward()
               self.optimizer.step()
           self.train_losses.append(loss.item())
           val_loss = self.evaluate(val_loader)
           self.val_losses.append(val_loss)
           self.scheduler.step(val loss)
           self.early_stopping(val_loss)
           # Log the training and validation loss
           print(f'Epoch {epoch+1}, Training Loss: {loss.item():.4f},

¬Validation Loss: {val_loss:.4f}')
           if self.early_stopping.early_stop:
               print("Early stopping")
               break
  def evaluate(self, test_loader):
      Evaluate the model on the test dataset.
      Args:
           test\_loader (torch.utils.data.DataLoader): DataLoader for test_{\sqcup}
\hookrightarrow dataset.
       Returns:
           float: Average loss on the test dataset.
      self.model.eval()
      total_loss = 0
      with torch.no_grad():
           for images, labels in test_loader:
               images, labels = images.to(self.device), labels.to(self.device)
               outputs = self.model(images)
               loss = self.criterion(outputs, labels)
               total_loss += loss.item()
      return total_loss / len(test_loader)
```

```
def accuracy(self, test_loader):
      Calculate the accuracy of the model on the test dataset.
      Args:
           test_loader (torch.utils.data.DataLoader): DataLoader for test⊔
\hookrightarrow dataset.
      Returns:
          float: Accuracy of the model on the test dataset.
      self.model.eval()
      correct = 0
      total = 0
      with torch.no_grad():
          for images, labels in test_loader:
               images, labels = images.to(self.device), labels.to(self.device)
               outputs = self.model(images)
               _, predicted = torch.max(outputs.data, 1)
               total += labels.size(0)
               correct += (predicted == labels).sum().item()
      return correct / total
  def plot_losses(self, window_size=100):
      # Compute moving averages
      train_losses_smooth = self.moving_average(self.train_losses,__
→window size)
      val_losses_smooth = self.moving_average(self.val_losses, window_size)
      plt.plot(train_losses_smooth, label='Train Loss')
      plt.plot(val_losses_smooth, label='Validation Loss')
      plt.legend()
      plt.grid()
      plt.title('Losses')
  def moving_average(self, data, window_size):
      return np.convolve(data, np.ones(window_size)/window_size, mode='valid')
```

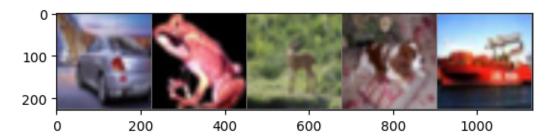
```
[4]: # Define a transform to normalize the data transform = transforms.Compose(
```

```
[transforms.Resize((224, 224)), # Resize images to 224x224 to match the
       ⇒input size of AlexNet
           transforms.ToTensor(),
           transforms.Normalize((0.5, 0.5, 0.5), (0.5, 0.5, 0.5))])
      # Load the training set
      trainset = torchvision.datasets.CIFAR10(root='./data', train=True,
                                              download=True, transform=transform)
      # Load the test set
      testset = torchvision.datasets.CIFAR10(root='./data', train=False,
                                             download=True, transform=transform)
      # Define the classes
      classes = ('plane', 'car', 'bird', 'cat',
                 'deer', 'dog', 'frog', 'horse', 'ship', 'truck')
     Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz to
     ./data/cifar-10-python.tar.gz
     100%
                | 170498071/170498071 [00:14<00:00, 11420599.46it/s]
     Extracting ./data/cifar-10-python.tar.gz to ./data
     Files already downloaded and verified
 [5]: # Split the dataset into training and validation sets
      train_split = 0.8
      train_size = int(train_split * len(trainset))
      val_size = len(trainset) - train_size
      # Split the dataset
      train_dataset, val_dataset = random_split(trainset, [train_size, val_size])
      # Create DataLoaders for each dataset
      train_loader = torch.utils.data.DataLoader(train_dataset, batch_size=64,_u
       ⇔shuffle=True)
      val_loader = torch.utils.data.DataLoader(val_dataset, batch_size=64,_u
       ⇒shuffle=False)
      test_loader = torch.utils.data.DataLoader(testset, batch_size=64, shuffle=False)
[16]: # Get the first batch of images from the trainloader
      dataiter = iter(train_loader)
      images, labels = next(dataiter)
      # Function to show an image
      def imshow(img):
          img = img / 2 + 0.5 \# unnormalize
          npimg = img.numpy()
```

```
plt.imshow(np.transpose(npimg, (1, 2, 0)))
   plt.show()

# Show images
imshow(torchvision.utils.make_grid(images[:5]))

# Print labels
print(' '.join('%5s' % classes[labels[j]] for j in range(5)))
```



car frog deer dog ship

## [6]: 'mps'

```
[7]: model = AlexNet(num_classes=10).to(device)
    criterion = nn.CrossEntropyLoss()
    optimizer = optim.SGD(model.parameters(), lr=0.01, momentum=0.9)
    trainer = Trainer(model, criterion, optimizer, device, patience=7)

# Train the model
    trainer.train(train_loader, val_loader, epochs=50)

# Evaluate the model on the test set
    test_loss = trainer.evaluate(test_loader)
```

```
print(f'Test Loss: {test_loss:.4f}')
# Calculate the accuracy on the test set
accuracy = trainer.accuracy(test_loader)
print(f'Test Accuracy: {accuracy :.2%}%')
/Library/Frameworks/Python.framework/Versions/3.12/lib/python3.12/site-
packages/torch/optim/lr scheduler.py:28: UserWarning: The verbose parameter is
deprecated. Please use get_last_lr() to access the learning rate.
 warnings.warn("The verbose parameter is deprecated. Please use get_last_lr() "
Epoch 1, Training Loss: 1.6848, Validation Loss: 1.6276
Epoch 2, Training Loss: 1.3936, Validation Loss: 1.1688
Epoch 3, Training Loss: 1.1116, Validation Loss: 0.9545
Epoch 4, Training Loss: 1.0321, Validation Loss: 0.8030
Epoch 5, Training Loss: 0.6169, Validation Loss: 0.7211
Epoch 6, Training Loss: 0.9001, Validation Loss: 0.7083
Epoch 7, Training Loss: 0.4127, Validation Loss: 0.6414
Epoch 8, Training Loss: 0.6169, Validation Loss: 0.6527
Epoch 9, Training Loss: 0.3146, Validation Loss: 0.6049
Epoch 10, Training Loss: 0.3554, Validation Loss: 0.5970
Epoch 11, Training Loss: 0.4381, Validation Loss: 0.6061
Epoch 12, Training Loss: 0.2960, Validation Loss: 0.6084
Epoch 13, Training Loss: 0.3705, Validation Loss: 0.6111
Epoch 14, Training Loss: 0.2831, Validation Loss: 0.5851
Epoch 15, Training Loss: 0.2090, Validation Loss: 0.6404
Epoch 16, Training Loss: 0.1800, Validation Loss: 0.6465
Epoch 17, Training Loss: 0.0556, Validation Loss: 0.6235
Epoch 18, Training Loss: 0.2044, Validation Loss: 0.6553
Epoch 19, Training Loss: 0.0549, Validation Loss: 0.7006
Epoch 20, Training Loss: 0.0598, Validation Loss: 0.7751
Epoch 21, Training Loss: 0.0045, Validation Loss: 0.7196
Early stopping
Test Loss: 0.7332
Test Accuracy: 84.50%%
```

[17]: trainer.plot\_losses(window\_size=3)

