## 计算方法实验报告

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1. Lagrange 插值
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x=input('Enter x vector in the table: ');
y=input('Enter y vector in the table: ');
x_0=input('Enter the interpolation point: ');
n=length(x);
L=0;
for i=1:n
   M=y(i);
  for j=1:n
      if j == i
          continue;
      else
          M=M*(x_0-x(j))/(x(i)-x(j));
  end
   L=L+M;
end
L
实验结果:
>> Lagrange
Enter x vector in the table: [0 1 2 3]
Enter y vector in the table: [1 1.6487 2.7183 4.4817]
Enter the interpolation point: 2.8
L =
  4.060416800000000
2. Newton 插值
x_0=input('Enter the interpolation point: ');
n=length(x);
dqtable=zeros(n,n-1);
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for i=2:n
  dqtable(i,1)=(y(i)-y(i-1))/(x(i)-x(i-1));
end
for i=2:n
  for j=(i+1):n
      dqtable(j,i)=(dqtable(j,i-1)-dqtable(j-1,i-1))/(x(j)-x(j-i));
  end
end
N=y(1);
M=x_0-x(1);
for i=1:(n-1)
   N=N+dqtable((i+1),i)*M;
   M=M*(x_0-x(i+1));
end
Ν
实验结果:
>> Newton
Enter x vector in the table: [0 1 2 3]
Enter y vector in the table: [1 1.6487 2.7183 4.4817]
Enter the interpolation point: 2.8
N =
  4.060416800000000
3. 复化 Simpson 求积公式
function y=f(x)
if x ~= 0
  y=sin(x)/x;
else
  y=1;
end
a=input('Type the lower bound(a): ');
b=input('Type the upper bound(b): ');
n=input('Type the number of intervals(n): ');
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h=(b-a)/n;
Sn=f(a)+f(b);
for i=1:n-1
   Sn=Sn+2*f(a + i*h);
end
for i=0:n-1
  Sn=Sn+4*f(a+ h/2 + i*h);
end
Sn=(h/6)*Sn
实验结果:
>> Simpson
Type the lower bound(a): 0
Type the upper bound(b): 1
Type the number of intervals(n): 4
Sn =
  0.946083310888472
4. Romberg 求积公式
function y=f(x)
if x ~= 0
  y=sin(x)/x;
else
  y=1;
end
a=input('Type the lower bound(a): ');
b=input('Type the upper bound(b): ');
e=input('Type the minimal error(epsilon): ');
k=0;
n=1;
h=b-a;
T(1,1)=h/2*(f(a)+f(b));
err=10;
while err>=e
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```
k=k+1;
   h=h/2;
   tmp=0;
   for i=1:n
       tmp=tmp+f(a+(2*i-1)*h);
   end
   T(k+1,1)=T(k,1)/2+h*tmp;
   if k<3
       for j=1:k
          T(k+1,j+1)=(4^j*T(k+1,j) - T(k,j))/(4^j-1);
       end
   else
       for j=1:3
          T(k+1,j+1)=(4^j*T(k+1,j) - T(k,j))/(4^j-1);
       end
   end
   n=n*2;
   if k<3
       err=abs(T(k+1,k+1)-T(k+1,k));
   else
       err=abs(T(k+1,4)-T(k+1,3));
   end
end
R=T(k+1,4)
实验结果:
>> Romberg
Type the lower bound(a): 0
Type the upper bound(b): 1
Type the minimal error(epsilon): 5e-8
R =
  0.946083070387223
5. 改进Euler公式
function [f] = f(x, y)
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```
f=-(0.9*y)/(1+2*x);
end
field= input('Type the interval for x: ');
      input('Type the step length h: ');
y=zeros(floor((field(2)-field(1))/h+1));
y(1)=input('Type the initial condition y(1): ');
k_max=floor((field(2)-field(1))/h+1);
x=field(1);
for k=1:k max
   y(k+1)=y(k)+h*f(x,y(k));
   y(k+1)=y(k)+(h/2)*(f(x,y(k)) + f(x+h, y(k+1)));
   fprintf('x = %f, y(%d) = %f \n', x, k, y(k));
   x=x+h;
end
实验结果:
>> Euler Advanced
Type the interval for x: [0 \ 0.1]
Type the step length h: 0.02
Type the initial condition y(1): 1
x = 0.000000, y(1) = 1.000000
x = 0.020000, y(2) = 0.982502
x = 0.040000, y(3) = 0.965954
x = 0.060000, y(4) = 0.950271
x = 0.080000, y(5) = 0.935381
x = 0.100000, y(6) = 0.921217
6. 四阶Runge-Kutta公式
function [f] = f(x, y)
f=-(0.9*y)/(1+2*x);
end
field= input('Type the interval for x: ');
      input('Type the step length h: ');
y=zeros(floor((field(2)-field(1))/h+1));
y(1)=input('Type the initial condition y(1): ');
k max=floor((field(2)-field(1))/h+1);
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```
x=field(1);
for k=1:k_max
   K1= f(x,y(k));
   K2= f(x+h/2, y(k) + h/2 *K1);
   K3 = f(x+h/2, y(k) + h/2 *K2);
   K4= f(x+h, y(k) +h*K3);
   y(k+1)=y(k) + h/6 *(K1 + 2*K2 + 2*K3 +K4);
   fprintf('x = %f, y(%d) = %f \n', x, k, y(k));
   x=x+h;
end
实验结果:
>> Runge Kutta
Type the interval for x: [0 \ 0.1]
Type the step length h: 0.02
Type the initial condition y(1): 1
x = 0.000000, y(1) = 1.000000
x = 0.020000, y(2) = 0.982506
x = 0.040000, y(3) = 0.965960
x = 0.060000, y(4) = 0.950281
x = 0.080000, y(5) = 0.935393
x = 0.100000, y(6) = 0.921231
7. Newton迭代法
function [ f, diff_f ] = f( a )
syms y x
y=x^3+10*x-20;
f=double(subs(y,a));
diff_f=double(subs(diff(y), a));
end
I=input('Type the interval of root: ');
epsilon=input('Type the maximal error: ');
x_pre=I(1);
x_for=0;
e=100;
steps=0;
while(e > epsilon)
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[fun, diff_fun]=f(x_pre);
   x_for = x_pre -fun/diff_fun ;
   e=abs(x_pre-x_for);
   x_pre=x_for;
   steps=steps+1;
end
fprintf('The root is x=%f \ n', x_for);
fprintf('Iteration steps is: %d \n', steps);
实验结果:
>> Newton
Type the interval of root: [1.5 2]
Type the maximal error: 1e-8
The root is x=1.594562
Iteration steps is: 4
8. Gauss列主元消去法
function [x]=ColumnElimination_f(A,b)
[n,\sim]=size(A);
x=zeros(n,1);
for k=1:n-1
   a_max=0;
   for i=k:n
       if abs(A(i,k))>a_max
           a_max=abs(A(i,k));
           r=i;
       end
   end
   if a_max<1e-10</pre>
       return;
   end
   if r>k
       for j=k:n
           z=A(k,j);
           A(k,j)=A(r,j);
           A(r,j)=z;
       end
       z=b(k);
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b(k)=b(r);
       b(r)=z;
   end
   for i=k+1:n
       m=A(i,k)/A(k,k);
       for j=k:n
           A(i,j)=A(i,j)-m*A(k,j);
       b(i)=b(i)-m*b(k);
   end
end
if abs(A(n,n))==0
  return;
end
x(n)=b(n)/A(n,n);
for i=n-1:-1:1
   for j=i+1:n
       b(i)=b(i)-A(i,j)*x(j);
   end
   x(i)=b(i)/A(i,i);
end
实验结果:
>> A=[1 -1 1; 5 -4 3; 2 1 1];
>> b=[-4; -12; 11];
>> ColumnElimination_f(A,b)
ans =
  3.0000000000000000
  6.0000000000000000
  -1.0000000000000000
9. Gauss-Seidel迭代法
function x=GaussSeidel_f(A,b)
D=diag(diag(A));
x=zeros(size(A,1),1);
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```
X=ones(size(x));
L=zeros(size(A));
for i=2:size(A,1)
    for j=1:(i-1)
       L(i,j)=-A(i,j);
   end
end
U=D-L-A;
max_iter_num=100;
epsilon=1e-6;
for iter_num=0:max_iter_num
   X=(D-L)\setminus(U^*x)+(D-L)\setminus b;
   if max(abs(X-x))<=epsilon</pre>
       break
    end
   x=X;
end
end
实验结果:
>> A=[10 -1 -2; -1 10 -2; -1 -1 5];
>> b=[7.2; 8.3; 4.2];
>> GaussSeidel_f(A,b)
ans =
  1.099999781713155
   1.199999866227841
  1.299999929588199
```