

Polynomial Chaos on Discontinuous Models

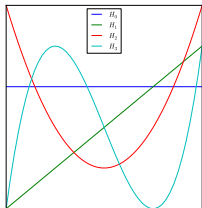
Jonathan Feinberg

Advisors: Arne Bang Huseby,
Hans Petter Langtangen and Stuart Clark

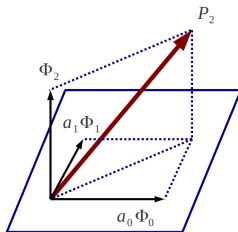
Simula Research Laboratory AS

13th May 2013

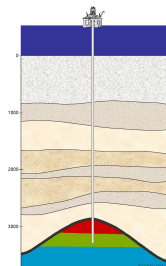
Overview



Polynomial Chaos



New Method



Case Study

Defining the general model and it's variables



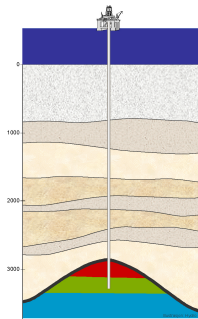
Time t



Coordinate x



Uncertain parameters q
w/density $p(q)$



Solver $u(x, t; q)$

Defining the general model and it's variables



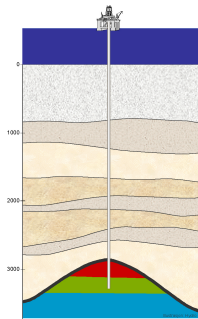
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Solver $u(x, t; q)$



Uncertainty analysis
 $\mathbb{E}[u]$, $\text{Var}(u)$

$u(q)$ -model is approximated non-intrusively from polynomial chaos expansion and stochastic collocation

Model solver

$$u(x, t; q) \approx \hat{u}_M(x, t; q) = \sum_{n=0}^N$$

Orthogonal poly.

$$\Phi_i(q)$$

Fourier coef.

$$\hat{c}_i(x, t)$$

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Askey-scheme

Discretized Stieltjes

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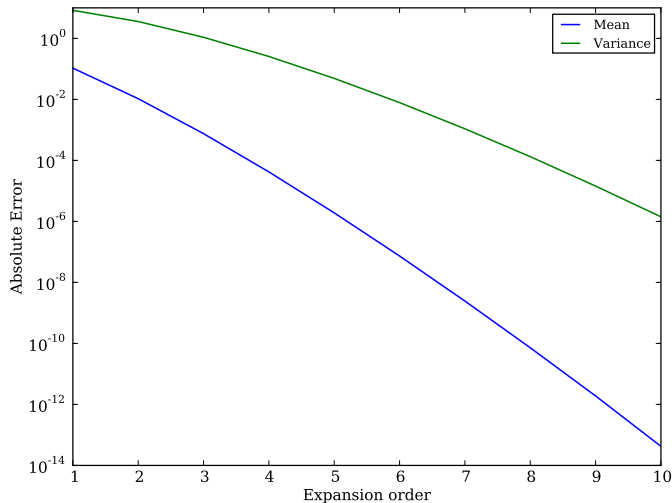


Least squares

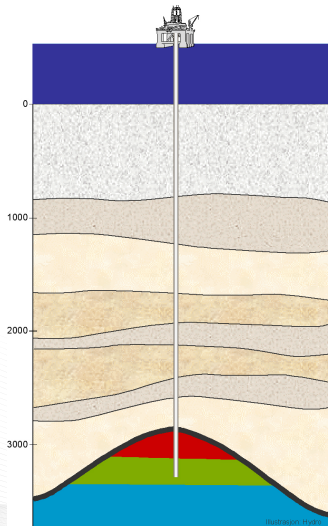
Discretized Stieltjes

Quadrature

The statistics of the approximation converges with exponential rate

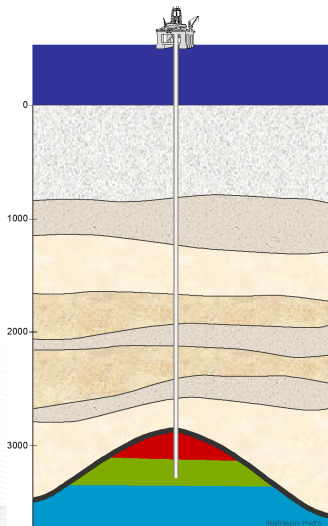


Case study: 1-dimensional diffusion equation



$$\frac{d}{dz} \left(a \frac{du}{dz} \right) = 0$$

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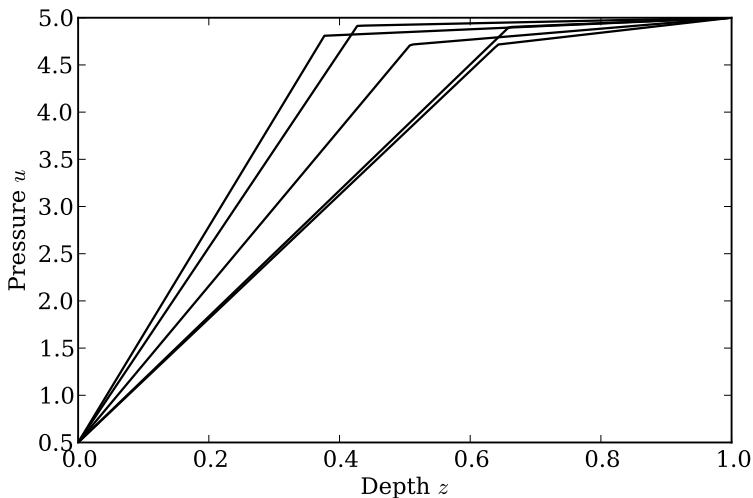
$$a(z, q) = \begin{cases} q_1 & \text{if } q_3 < t \\ q_2 & \text{if } q_3 \geq t \end{cases}$$

$$q_1 \sim \text{Uni}(0, 1)$$

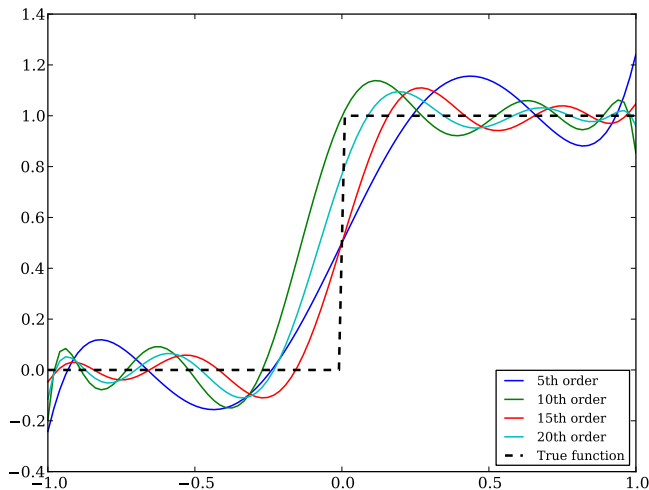
$$q_2 \sim \text{Uni}(8, 10)$$

$$q_3 \sim \text{Uni}(0.3, 0.7)$$

Solution of equation is not smooth because of the discontinuity in layered medium



Polynomials are bad at approximating discontinuities



Remedy: transform the variables to deal with discontinuities

$$u(x, t; q) = u^*(x, t; T(x, t; q)) \approx \sum_{i=0}^N \Psi_i(T(x, t; q)) \hat{c}_i^*(x, t)$$

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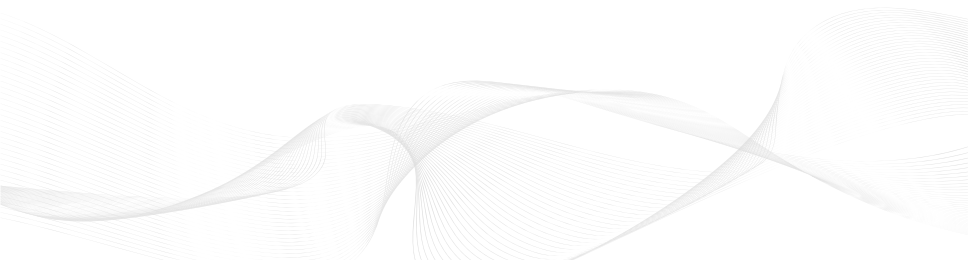
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Problems...

- ▶ Selection of $r = T(x, t; q)$ non-trivial
- ▶ Distribution of $r = T(x, t; q)$ is unknown/difficult to calculate
- ▶ Polynomials spatio-temporal dependent
- ▶ Random variables not statistically independent

Construct orthogonal polynomials from covariance



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$\{\Phi_i\}_i$ is orthogonal \iff $\text{Cov}([\Phi_i]_i)$ is uncorrelated

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(Except for $\Phi_0 = 1$)

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$\{\Phi_i\}_i$ is orthogonal \iff Cov $([\Phi_i]_i)$ is uncorrelated

(Except for $\Phi_0 = 1$)

Polynomial basis:

ex. $v_r = r_1, r_1^2, r_1^3, \dots$
 $r_2, r_1 r_2, r_1^2 r_2,$
 $r_2^2, r_1 r_2^2,$
 $r_2^3,$

Construct orthogonal polynomials from covariance

$$\{\Phi_i\}_i \text{ is orthogonal} \quad \Longleftrightarrow \quad \text{Cov}([\Phi_i]_i) \text{ is uncorrelated}$$

(Except for $\Phi_0 = 1$)

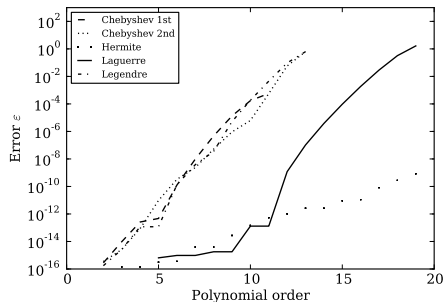
Polynomial basis:

$$\begin{aligned} \text{ex. } v_r = & r_1, \quad r_1^2, \quad r_1^3, \dots \\ & r_2, \quad r_1 r_2, \quad r_1^2 r_2, \\ & \quad r_2^2, \quad r_1 r_2^2, \\ & \quad \quad r_2^3, \end{aligned}$$

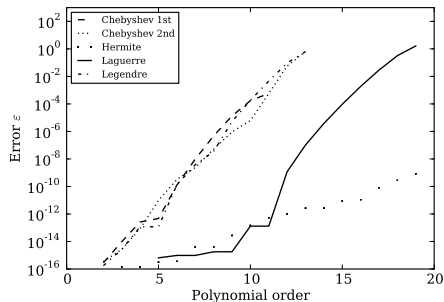
$$\begin{aligned} [\Phi_i]_i \setminus \Phi_0 &= L^{-1}(v_r - \mathbb{E}[v_r]) \\ \Sigma_{v_r} &= L^T L \end{aligned}$$

$$\mathbb{E}_r [r_1^{k_1} \dots r_C^{k_C}] = \mathbb{E}_q [T_1(q, x, t)^{k_1} \dots T_C(q, x, t)^{k_C}]$$

Generating orthogonal polynomials is ill-posed: Solution is unstable

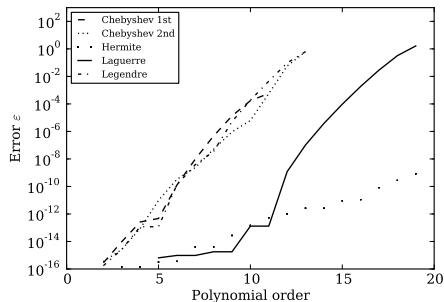


Generating orthogonal polynomials is ill-posed: Solution is unstable



Error is small
for low order

Generating orthogonal polynomials is ill-posed: Solution is unstable



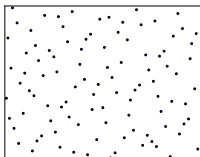
Error is small
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Pivoted Cholesky
Decomposition for
numerical stability

Estimate Fourier coefficients using collocation and linear least squares

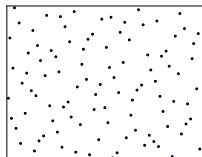
Select collocation nodes in q



Q_1, \dots, Q_K

Estimate Fourier coefficients using collocation and linear least squares

Select collocation nodes in q



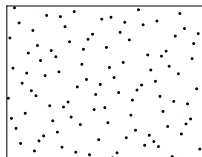
Q_1, \dots, Q_K

$$L = \begin{bmatrix} \Psi_0(T(Q_1)) & \cdots & \Psi_N(T(Q_1)) \\ \vdots & & \vdots \\ \Psi_0(T(Q_K)) & \cdots & \Psi_N(T(Q_K)) \end{bmatrix} \quad U = \begin{bmatrix} u(x, t; Q_1) \\ \vdots \\ u(x, t; Q_K) \end{bmatrix}$$

$$c = (L^T L)^{-1} L^T U$$

Estimate Fourier coefficients using collocation and linear least squares

Select collocation nodes in q



Q_1, \dots, Q_K

Independent of T

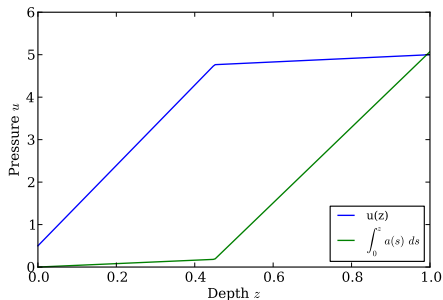


$$L = \begin{bmatrix} \Psi_0(T(Q_1)) & \cdots & \Psi_N(T(Q_1)) \\ \vdots & & \vdots \\ \Psi_0(T(Q_K)) & \cdots & \Psi_N(T(Q_K)) \end{bmatrix}$$

$$U = \begin{bmatrix} u(x, t; Q_1) \\ \vdots \\ u(x, t; Q_K) \end{bmatrix}$$

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Case study: Select a transformation that has discontinuity in the same location



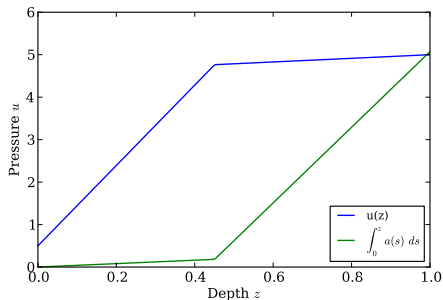
$$r_1 = q_1$$

$$r_2 = q_2$$

$$r_3 = q_3$$

$$r_4 = \int_0^z a(s) ds$$

Case study: Select a transformation that has discontinuity in the same location



$$r_1 = q_1$$

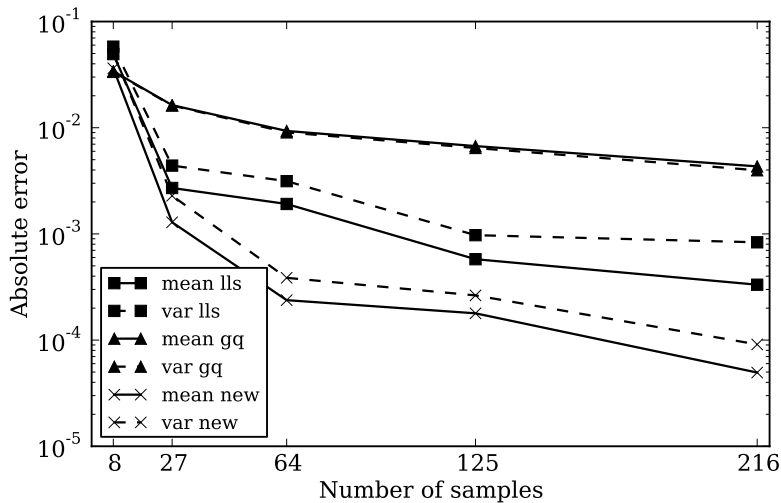
$$r_2 = q_2$$

$$r_3 = q_3$$

$$r_4 = \int_0^z a(s) ds$$

$$\mathbb{E}_r \left[r_1^{k_1} r_2^{k_2} r_3^{k_3} r_4^{k_4} \right] = \mathbb{E}_q \left[q_1^{k_1} q_2^{k_2} q_3^{k_3} \left(\int_0^z a(s) ds \right)^{k_4} \right]$$

New method converges to true values fast



Concluding marks

- ▶ Discontinuous media: slowdown of poly chaos convergence
- ▶ Remedy: transform stochastic variables
- ▶ Problem: stochastic variables become *dependent*
- ▶ New method for constructing orthogonal polynomials in the dependent case
- ▶ Major computational enhancement in the model problem