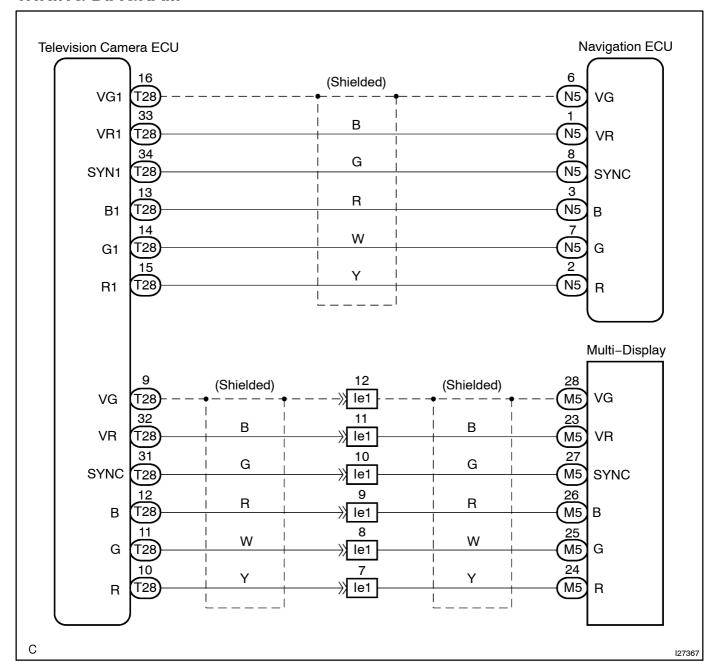
DICCS\_03

# **Display Signal Circuit**

### **CIRCUIT DESCRIPTION**

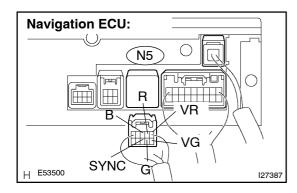
This is the display signal circuit from the multi-display controller sub-assy to the multi-display assy.

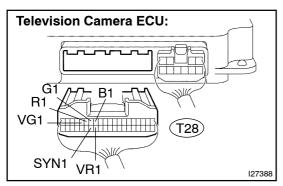
#### **WIRING DIAGRAM**



## **INSPECTION PROCEDURE**

Check for open or short circuit in harness and connector between navigation ECU and television camera ECU.





- (a) Disconnect the connector from navigation ECU and television camera ECU.
- (b) Measure the resistance according to the value(s) in the table below.

#### Standard:

Tester connection	Condition	Specified condition
R – R1	Always	Below 1 Ω
G – G1	Always	Below 1 Ω
B – B1	Always	Below 1 Ω
SYNC - SYN1	Always	Below 1 Ω
VR – VR1	Always	Below 1 Ω
VG – VG1	Always	Below 1 Ω
R – Body ground	Always	10 k $\Omega$ or higher
G – Body ground	Always	10 k $\Omega$ or higher
B – Body ground	Always	10 k $\Omega$ or higher
SYNC – Body ground	Always	10 k $\Omega$ or higher
VR – Body ground	Always	10 k $\Omega$ or higher

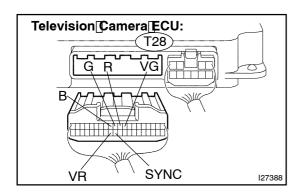
NG

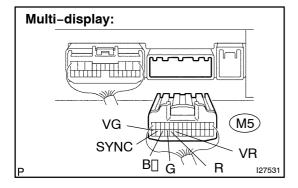
Repair or replace harness or connector.



1

# 2 Check[for[open[or[short[circuit]]n[harness[and[connector[between[television camera[ECU[and[malti-display[assembly.





- (a) Disconnect in element in the levision camera ECU and multi-display assy.
- (b) Measure the resistance according to the value (s) in the table below.

#### Standard:

Tester[connection	Condition	Specified@condition
R –[]R	Always	Below 1 Ω
G -[G	Always	Below 1 Ω
B –[ <b>B</b>	Always	Below 1 Ω
SYNC -[\$YNC	Always	Below 1 Ω
VR -[]VR	Always	Below 1 Ω
VG -[VG	Always	Below 1 Ω
R –[Body[ground	Always	10 kΩ[þr[ħigher
G – <u>⊪</u> Body <u></u> ground	Always	10 kΩ[þr[ħigher
B –[Body[ground	Always	10 kΩ[þr[ħigher
SYNC -[Body[ground	Always	10 kΩ[þr[ħigher
VR –[Body[ground	Always	10 kΩ[þr[ħigher

NG

Repair or replace harness or connector.

ОК

Proceed[to[next[circuit[]nspection[shown[]n[problem[symptoms[]able.[[See[page[DI-209]