# 6. Electric Control System

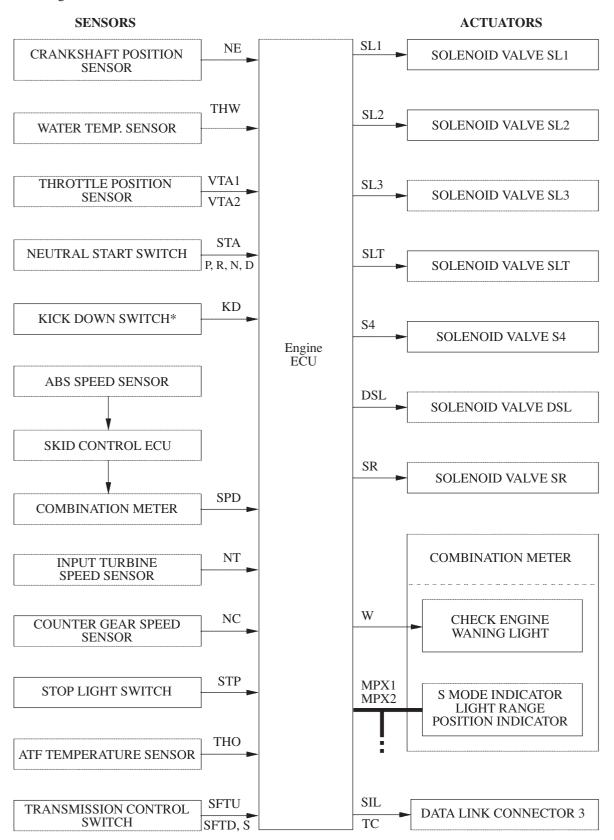
# General

The electronic control systems of the U151E automatic transaxle consists of the control listed below.

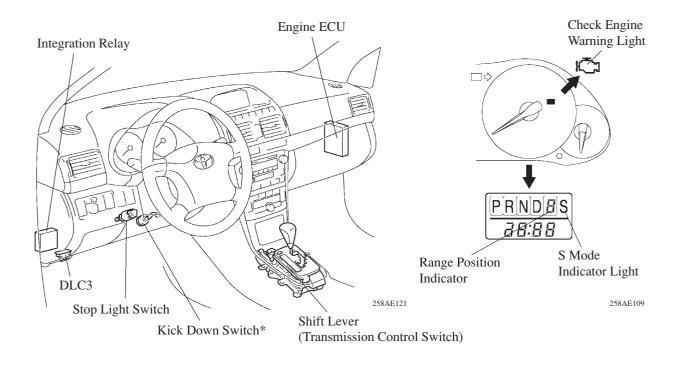
System	Function				
Clutch Pressure Control (See page 112)	<ul> <li>Controls the pressure that is applied directly to B<sub>1</sub> brake, C<sub>0</sub> and C<sub>1</sub> clutches by actuating 3 solenoid valves (SL1, SL2, and SL3) in accordance with engine ECU signals.</li> <li>3 solenoid valves (SL1, SL2, and SL3) minutely controls the clutch pressure in accordance with the engine output and driving conditions.</li> </ul>				
Line Pressure Optimal Control (See page 114)	Actuates the solenoid valve SLT to control the line pressure in accordance with information from the engine ECU and the operating conditions of the transaxle.				
Engine Torque Control	Retards the engine ignition timing temporarily to improve shift feeling during up or down shifting.				
Shifting Control in Uphill/Downhill Traveling (See page 113)	Controls to restrict the 4th or 5th upshift or to provide appropriate engine braking by the engine ECU to determine whether the vehicle is traveling uphill or downhill.				
Shift Timing Control	The engine ECU sends current to 3 solenoid valves (SL1, SL2, and/or SL3) based on signals from each sensor and shifts the gear.				
Flex Lock-up Clutch Control (See page 115)	Controls the solenoid valve SL2 and DSL, provides an intermediate mode between the ON/OFF operation of the lock-up clutch, and increase the operating range of the lock-up clutch to improve fuel economy.  However, this control operates only during deceleration.				
Lock-up Timing Control	The engine ECU sends current to the solenoid valve DSL and SL2 based on signals from each sensor and engages or disengages the lock-up clutch.				
"N" to "D" Squat Control	When the shift lever is shifted from "N" to "D" position, the gear is temporarily shifted to 2nd or 3rd and then to 1st to reduce vehicle squat.				
Diagnosis (See page 116)	When the engine ECU detects a malfunction, the engine ECU makes a diagnosis and memorizes the failed section.				
Fail-safe (See page 116)	Even if a malfunction is detected in the sensors or solenoids, the engine ECU effects fail-safe control to prevent the vehicle's drivability from being affected significantly.				

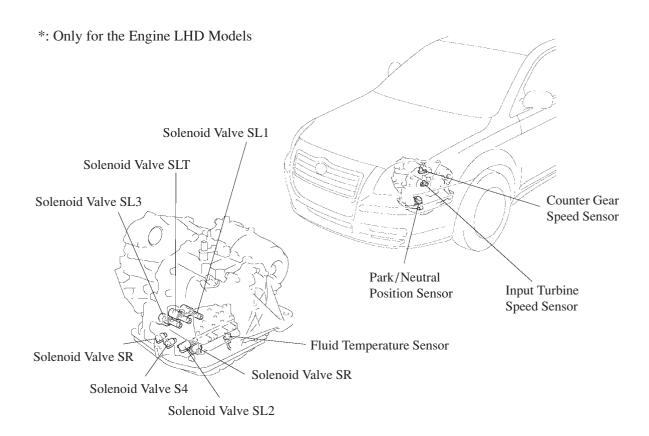
## Construction

The configuration of the electronic control system in the U151E automatic transaxles is as shown in the following chart.



# **Layout of Main Components**

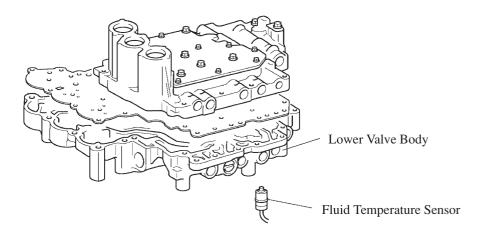




## **Construction and Operation of Main Components**

## 1) Fluid Temperature Sensor

A fluid temperature sensor is installed in the valve body for direct detection of the fluid temperature. Fluid temperature sensor is used for revision of clutches and brakes pressure to keep smooth shift quality every time.

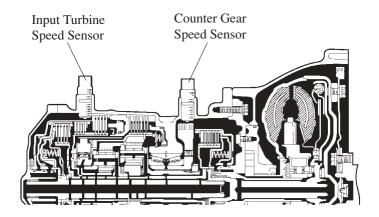


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# 2) Speed Sensors

The U151E automatic transaxle has adopted an input turbine speed sensor (for the NT signal) and a counter gear speed sensor (for the NC signal). Thus, the engine ECU can detect the timing of the shifting of the gears and appropriately control the engine torque and hydraulic pressure in response to the various conditions.

- The input turbine speed sensor detects the input speed of the transaxle. The direct clutch (C<sub>2</sub>) drum is used as the timing rotor for this sensor.
- The counter gear speed sensor detects the speed of the counter gear. The counter drive gear is used as the timing rotor for this sensor.



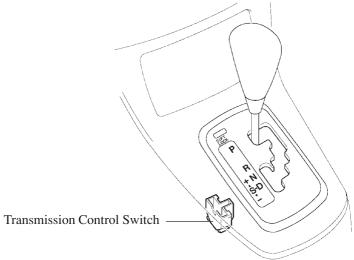
## **Transmission Control Switch**

## 1) General

The transmission control switch is composed of a switch that detects whether the shift lever is shifted into the S position and a momentary type up-shift range and down-shift range switches that detect whether these are operated in the + direction or – direction.

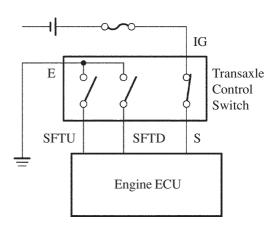
#### 2) Operation

- When the shift lever is engaged into the S position, there is continuity between the S terminal and the IG terminal in the transmission control switch.
- When the shift lever is moved to the + direction, the up-shift range switch turns on and there is continuity between the SFTU terminal and the E terminal in the transmission control switch. Then, this signal is output to the engine ECU as a up-shift range signal.
- When the shift lever is moved to the direction, the down-shift range switch turns on and there is continuity between the SFTD terminal and the E terminal in the transmission control switch. Then, this signal is output to the engine ECU as a down-shift range signal.



## **▶** System Diagram **◄**

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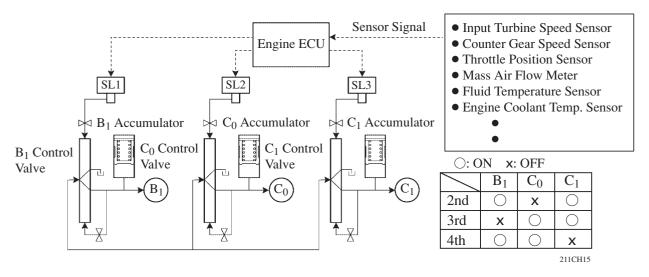
## **Clutch Pressure Control**

#### 1) Clutch to Clutch Pressure Control

This control has been adopted for shifting from the 1st to 2nd gear, from the 2nd to 3rd gear, and from the 3rd to 4th gear.

Actuates solenoid valves SL1, SL2, and SL3 in accordance with the signals from the engine ECU, and guides this output pressure directly to the control valves  $B_1$ ,  $C_0$ , and  $C_1$  in order to regulate the line pressure that acts on the  $B_1$  brake,  $C_0$ , and  $C_1$  clutches.

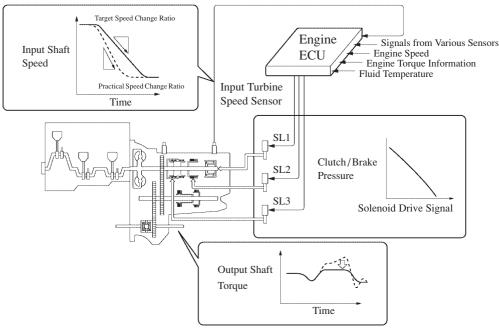
As a result, compact  $B_1$ ,  $C_0$ , and  $C_1$  accumulators without a back pressure chamber have been realized.



#### 2) Clutch Pressure Optimal Control

The engine ECU monitors the signals from various types of sensor such as the input turbine speed sensor, allowing shift solenoid valves SL1, SL2, and SL3 to minutely control the clutch pressure in accordance with engine output and driving conditions.

As a result, smooth shift characteristics have been realized.



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## **Shifting Control in Uphill/Downhill Traveling**

## 1) General

This control minimizes the shifting of gears when the driver operates the accelerator pedal while driving on a winding road with ups and downs, in order to ensure a smooth drive.

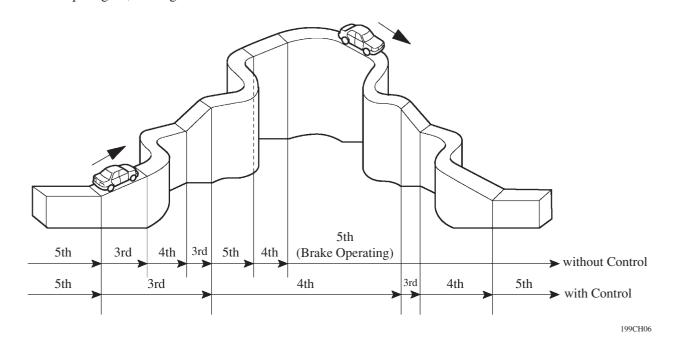
## 2) Shift control in uphill traveling

When the engine ECU determines uphill travel before the transaxle attempts to shift up into 5th, it prohibits the transaxle from shifting up into 5th.

When the engine ECU determines uphill travel with a steeper grade, prevents the transaxle from shifting up into 4th.

## 3) Shift control in downhill traveling

When the engine ECU determines downhill travel, it shifts down the transaxle from 5th to 4th in accordance with the brake operation signal that is input when the driver operates the brake pedal. When the engine ECU determines downhill travel with a steeper grade, and a brake operation signal is input again, the engine ECU shifts the transaxle down from 4th to 3rd.



## 4) Uphill/Downhill Judgment

The actual acceleration calculated from the speed sensor signal is compared with the reference acceleration stored in the engine ECU to judge uphill or downhill traveling.

Actual Acceleration < Reference Acceleration

Reference acceleration

Actual Acceleration > Reference Acceleration

Actual acceleration

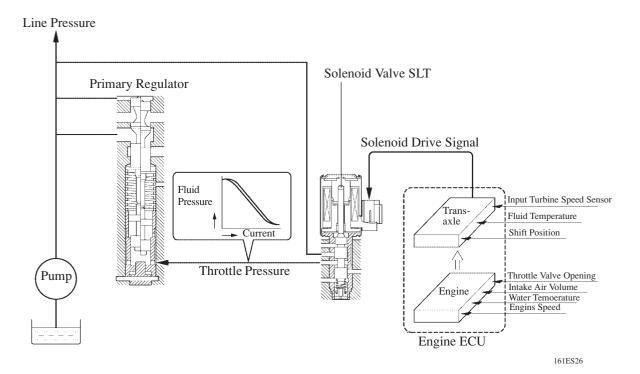
Actual acceleration



# **Line Pressure Optimal Control**

Through the use of the solenoid valve SLT, the line pressure is optimally controlled in accordance with the engine torque information, as well as with the internal operating conditions of the torque converter and the transaxle.

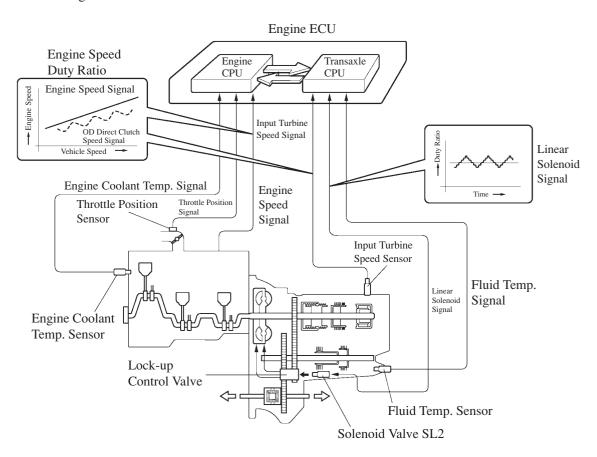
Accordingly, the line pressure can be controlled minutely in accordance with the engine output, traveling condition, and the ATF temperature, thus realizing smooth shift characteristics and optimizing the workload in the oil pump.



# Flex Lock-up Clutch Control

In addition to the conventional lock-up timing control, flex lock-up clutch control is used.

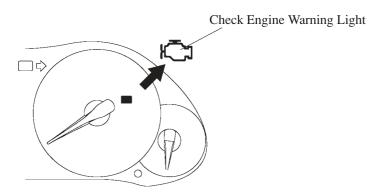
During deceleration, this flex lock-up clutch control regulates the solenoid valve SL2 as an intermediate mode between the ON/OFF operation of the lock-up clutch, in order that lock-up clutch is made to operate in low speeds. Therefore fuel-cut area has been expended and fuel-economy has been improved. The flex lock-up clutch control operates during deceleration, in the 4th and 5th gears in the D range, and in the 4th gear in the 4 range.



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## **Diagnosis**

- When the engine ECU detected a malfunction, the engine ECU makes a diagnosis and memorizes the failed section. Furthermore, the check engine warning light in the combination meter illuminates or blinks to inform the driver.
- At the same time, the DTCs (Diagnosis Trouble Codes) are stored in memory. The DTCs can be read by connecting a hand-held tester. For details, see the Avensis Repair Manual Supplement (Pub. No. RM1045E).



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## **Service Tip**

The length of time to clear the DTC by the battery terminal disconnection has been changed from the previous 10 seconds to 1 minute.

# Fail-Safe

This function minimizes the loss of operability when any abnormality occurs in each sensor or solenoid.

# **▶** Fail-Safe Control List **◄**

Malfunction Part	Function			
Speed Sensor	During a speed sensor malfunction, the vehicle speed is detected through the signals from the counter gear speed sensor to effect normal control.			
Fluid Temp. Sensor	During a fluid temp. sensor malfunction, 5th upshift is prohibited.			
Counter Gear Speed Sensor	During a counter gear speed sensor malfunction, 5th upshift is prohibited.			
Solenoid Valve SL1, SL2, SL3 and S4	The current to the failed solenoid valve is cut off and control is effected by operating the other solenoid valves with normal operation.  Shift control is effected as described in the table below, depending on the failed solenoid.  Even if starting the engine under this condition, the gear position remains where it was before.			

○: ON ∆: According to Flex Lock-up x: OFF

Normal   Normal   Valve   SL3	Normal		SL1	0	х		х	Х	
Normal Normal Valve   SL3		Solenoid			0		Δ	Δ	
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$						X	0	0	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $				х	х	X		<b>+</b>	
SL1   Solenoid (During driving at 1st or 2nd)   Solenoid (During driving at 1st or 2nd)   Solenoid (During driving at 1st or 2nd)   Solenoid (During driving at 3rd)   Solenoid (During driv		Gear Position	on	1st	2nd	3rd	4th	5th	
Malfunction (During driving at 1st or 2πd)   Solenoid (During driving at 1st or 2πd)   Solenoid (During driving at 3πd)   Solenoid (During driving at 4πd)   Solenoid (During at 3πd)   Solenoid	CI 1		SL1						
During driving at 1st or 2nd )   Course driving arise at 3rd )   Course driving arise at 3rd )   Course driving at 3rd )   Course driving at 4th or 5th )   Course driving at 4th )   Course dri		Solenoid	SL2	0				0	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	1		SL3						
or 2nd)         Gear Posits	driving at 1st		S4	х	X	X			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $				$1st \rightarrow 2nd$	2nd	$3rd \rightarrow 2nd$	$4\text{th} \rightarrow 2\text{nd}$		
$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$		<del> </del>							
Malfunction (During driving at 3rd)         Valve (Bar Position)         SL3         x         x         x $0 \rightarrow x$ $0 \rightarrow x$ $0 \rightarrow x$ SL1 (During driving at 4th or 5th)         Solenoid (During driving at 4th or 5th)         SL2 $0 \rightarrow \Delta$ $0$	SL1	Solenoid	SL2	$\bigcirc \rightarrow \Delta$	$\bigcirc \rightarrow \Delta$	Δ	Δ	Δ	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			SL3	Х	X	x	$\bigcirc \rightarrow x$	$\bigcirc \rightarrow x$	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	' '		S4	x → ○	x → ○	x → ○	x → ○	0	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	at 3rd)	Gear Position	on	$1st \rightarrow 4th$	$2nd \rightarrow 4th$	$3rd \rightarrow 4th$	4th	$5\text{th} \rightarrow 4\text{th}$	
$ \begin{tabular}{ c c c c c c c c c c c } \hline Malfunction & Solenoid (During driving at 4th or 5th) & SL2 & \bigcirc + \Delta & \bigcirc + \Delta & \triangle & \triangle & \triangle & \triangle & \triangle \\ \hline Null (During driving at 4th or 5th) & SL2 & X & X & X & X & X & X & X & X & X & $	CI 1		SL1			X			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		Solenoid	SL2	$\bigcirc \rightarrow \Delta$	$\bigcirc \rightarrow \Delta$	Δ	Δ	Δ	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL3	x → ○	x → ○	x → ○	0	0	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	driving at 4th		S4	Х	X	х	х	0	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	or 5th)			$1st \rightarrow 4th$	$2nd \rightarrow 4th$	$3rd \rightarrow 4th$	4th	5th	
$ \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$			SL1	0	x → ○	0	x → ○	x → ○	
$ \begin{tabular}{ c c c c c c c c c c c c c c c c c c c$		Solenoid	SL2						
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL3	х	Х	х	$\bigcirc \rightarrow X$	$\bigcirc \rightarrow X$	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			S4	x → ○	x → ○	x → ○	x → ○	0	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		Gear Position		$1st \rightarrow 4th$	$2nd \rightarrow 4th$	$3rd \rightarrow 4th$	4th	$5\text{th} \rightarrow 4\text{th}$	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL1	0	х	0	x → ○	x → ○	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL2	0	0	х	Δ	Δ	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL3			Х	ı		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			S4	х	х	х	x → ○	0	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		Gear Position		1st	2nd	3rd	4th	$5\text{th} \rightarrow 4\text{th}$	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL1	0	х	0	х	х	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL2	0	0	х	Δ	Δ	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			SL3	х	х	х	0	0	
SL1, SL2,         Solenoid         SL2         X           SL3, and S4 Malfunction         SL3         X           S4         X			S4			Х	•	•	
SL1, SL2, SL3, and S4 Malfunction SL2 X  X  Sl3 X  X  X  X  X  X  X  X  X  X  X  X  X		Gear Position		1st	2nd	3rd	4th	$5\text{th} \rightarrow 4\text{th}$	
SL3, and S4 Malfunction SL3  X  X	SL3, and S4	SL1		x					
SL3, and S4 Malfunction  Valve SL3  X  X			SL2	×					
			SL3	×					
Gear Position $1st \rightarrow 4th$ $2nd \rightarrow 4th$ $3rd \rightarrow 4th$ $4th$ $5th \rightarrow 4th$			S4	х					
		Gear Position		$1st \rightarrow 4th$	$2nd \rightarrow 4th$	$3rd \rightarrow 4th$	4th	$5\text{th} \rightarrow 4\text{th}$	