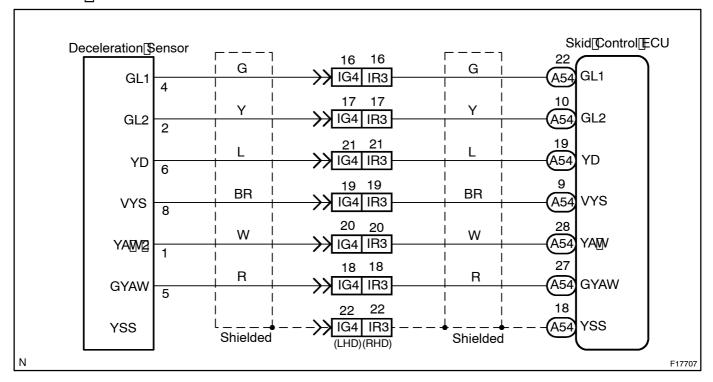
DIARP-01

DTC	C1336[[]39[]	Zero[Point[Calibration]of[Deceleration Sensor[Undone

CIRCUIT DESCRIPTION

DTC[No.	DTC[Detecting[Condition	Trouble _ Area
C1236 ∏ 39	When any of following . Through . To state the state of the shift of t	Deceleration[sensor Deceleration[sensor@ircuit Neutral[start[switch@ircuit[]R[]ange)

WIRING DIAGRAM



INSPECTION PROCEDURE

1 Perform zero point calibration of the yaw rate (deceleration) sensor (See page DI-185).



2 | Is[DTC[still]output?

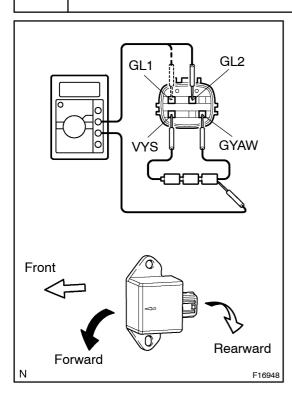
Check DTC on page DI-185.

NO

End.

YES

3 Check yaw rate (deceleration) sensor.



PREPARATION:

- (a) Connect 3 dry batteries of 1.5 V in series.
- (b) Connect VYS terminal to the batteries' positive (+) terminal, and GYAW terminal to the batteries' negative (-) terminal. Apply about 4.5 V between VYS and GYAW terminals.

NOTICE:

Do not apply voltage of 6 V or more to terminals VYS and GYAW.

CHECK:

Check the output voltage of GL1 and GL2 terminals when the sensor is tilted forward and rearward.

<u>OK:</u>

Symbols	Condition	Standard Value
GL1	Horizontal	About 2.3 V
GL1	Lean rearward	1.0 V - about 2.3 V
GL1	Lean forward	About 2.3 V – 3.5 V
GL2	Horizontal	About 2.3 V
GL2	Lean rearward	About 2.3 V – 3.5 V
GL2	Lean forward	1.0 V - about 2.3 V

HINT:

- If the sensor is tilted too much it may show the wrong value.
- If dropped, the sensor should be replaced with a new one.
- The sensor removed from the vehicle should not be placed upside down.

NG

Replace yaw rate sensor.

ок

4 Check[for[open[or[short[circuit]]n[harness[and[connector[between[yaw[rate][deceleration]]]sensor[and[skid[control[ECU[See[page]]N-38]].

NG

Repair or replace harness or connector.

OK

Check and replace skid control ECU.