

# Problem Set 1)

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CS 2500

$$1. P = \{V_1, \dots, V_n\}$$

$$P_{ij} = \{V_i, \dots, V_j\}$$

$$G = (V, E)$$

shortest path  $P = (V_0, V_1, \dots, V_k)$

$$V_0 \xrightarrow{P_{0,i}} V_i \xrightarrow{P_{i,j}} V_j \xrightarrow{P_{j,k}} V_k$$

$$w(P) = w(P_{0,i}) + w(P_{i,j}) + w(P_{j,k})$$

shortest path between  $V_i$  and  $V_j \Rightarrow P'_{i,j}$

$$w(P'_{i,j}) < w(P_{i,j}) \text{ then}$$

$$V_0 \xrightarrow{P_{0,i}} V_i \xrightarrow{P'_{i,j}} V_j \xrightarrow{P_{j,k}} V_k$$

$$w(P_{0,i}) + w(P'_{i,j}) + w(P_{j,k}) < w(P)$$

↑

This is impossible

2) negative weight cycle  $G = (V, E)$

neg-weightcycle( $G$ )

matrix[0, n] = 0 // makes new graph same size as G

for i = 1 to V

for j = 1 to V

matrix[i, j] = G[i, j] // copy graph to temp matrix

for i = 1 to V

for j = 1 to V

for k = 1 to V

if matrix[j, i] + matrix[i, k] < matrix[j, k]

matrix[j, i] = matrix[j, i] + matrix[i, k]

for i = 1 to V

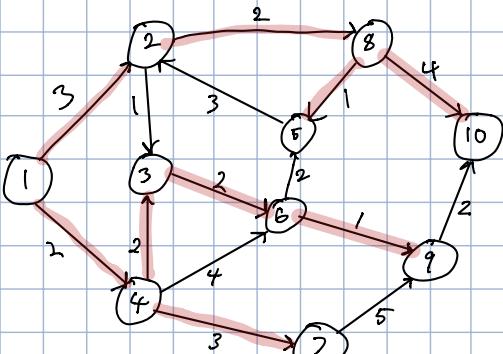
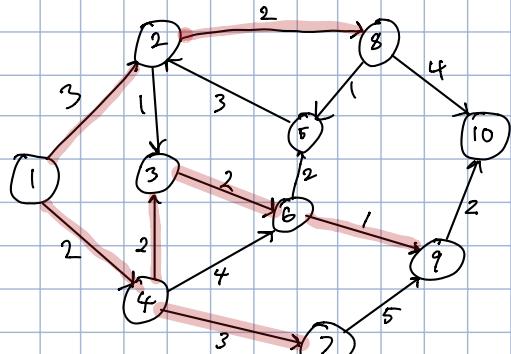
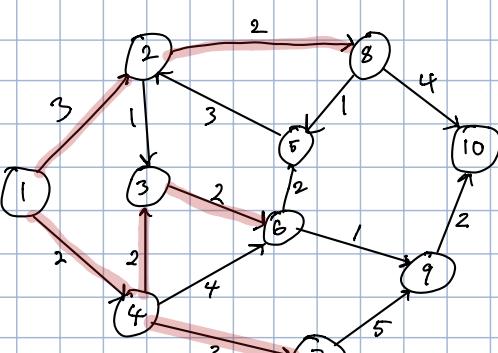
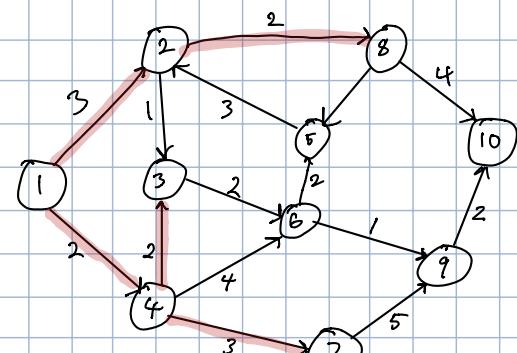
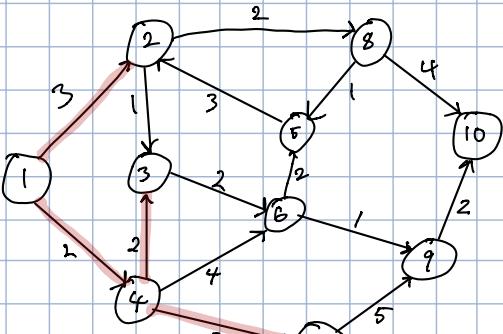
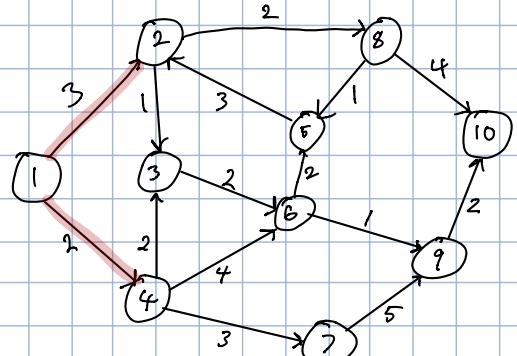
if matrix[i, i] < 0 // if total distance is negative graph has a negative weight cycle

return true ← matrix has negative weight CYCLE

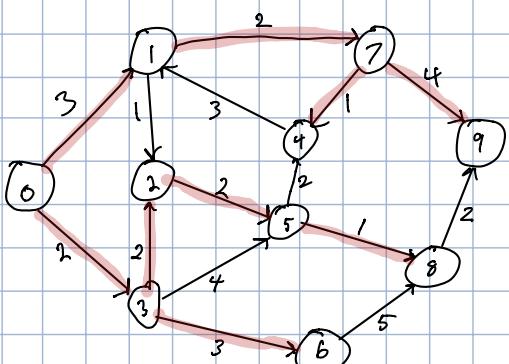
return false

### Bonus Problem

### Dijkstra's Algorithm



### Dijkstra's code fix

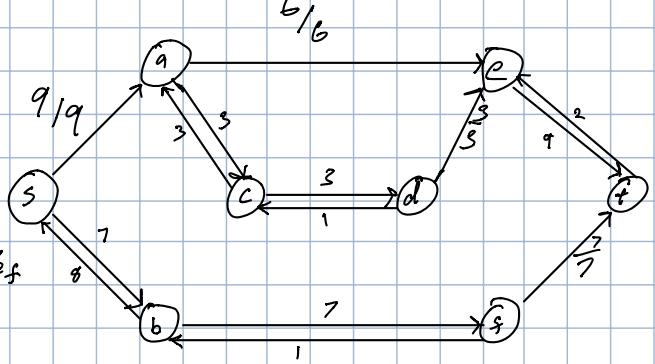


## Problem Set 2

1) Define Slack ( $R$ esidual flow) in an edge  $(u, v) \in E$  in the residual graph of a given graph  $G = (V, E)$ .

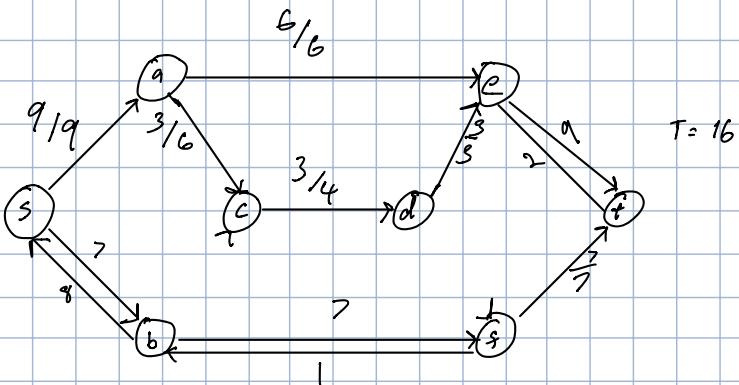
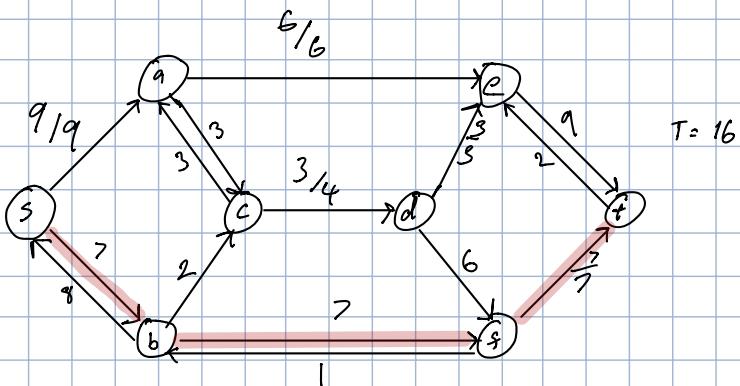
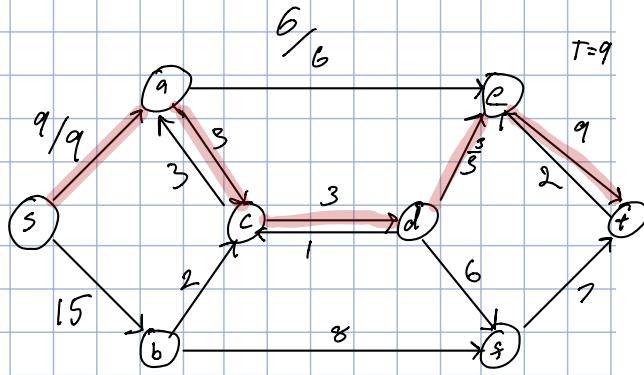
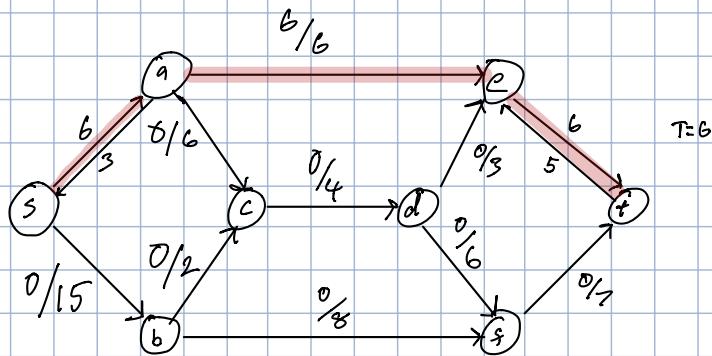
$$c_f(u, v) = \begin{cases} c(u, v) - f(u, v), & \text{if } (u, v) \in E \\ f(v, u), & \text{if } (v, u) \in E \\ 0, & \text{otherwise} \end{cases}$$

$$(f \nabla f^{\dagger})(u, v) = \begin{cases} f(u, v) - f^{\dagger}(u, v) - f^{\dagger}(v, u), & \text{if } (u, v) \in G_f \\ 0 & \text{otherwise} \end{cases}$$



The Residual flow is the left over capacity in each of the edges on the network after the completion of augmentation.

2)



## Problem set 3

1) Prove that there are uncountable number of unsolvable binary decision problems. Furthermore give an example of an unsolvable binary decision problem.

If every program can be represented as a single contiguous string (machine code)

Then every binary string can be represented as a natural number.

Therefore each program can be uniquely identified and mapped to a natural number ( $\mathbb{N}$ )

A decision problem binary (yes/no) can be mapped to a real number ( $\mathbb{R}$ ).

$|\mathbb{R}| \gg |\mathbb{N}|$ , since  $\mathbb{R}$  is uncountable, where  $\mathbb{N}$  is countable.

## 2) Define

$\text{NP}$ : A set of decision problems that are solvable in polynomial time and verifiable by a non-deterministic turing machine.

An example of  $\text{NP}$  problem is the satisfiability (SAT)

$$f = (x_1 + \bar{x}_2)(\bar{x}_1 + x_2 + x_3)(\bar{x}_2 + \bar{x}_3) \quad (\text{not sure this works as markuski slides show it as NP-complete})$$

↑

According to slides Sat problems are NP

Another NP problem is Integer factorization

Given integers  $n$  and  $m$  there is an integer  $f$  with  $1 < f < m$  such that  $f$  divides  $n$  ( $f$  is a small factor of  $n$ ).

$$x = x$$

$$\bar{x} = \text{not } x$$

$$(x)(y) = \text{anded}$$

$$x+y = x \text{ or } y$$

$\text{NP-Complete}$ : A class of problems  $X$  in  $\text{NP}$  for which it is possible to reduce any other  $\text{NP}$  problem  $Y$  to  $X$  in polynomial time.

An example of an NP-Complete problem is the 0-1 knapsack problem.

Were you want to store a set number of items in a knapsack with a given limit.

Each item of varying weight is added to the knapsack without going over the knapsacks limit. With each item of varying weight, the goal is to maximize the space in the knapsack within its weight limit. Each item has differing worth to weight.

$\text{NP-Hard}$ : A class of problems that are at least as hard as NP-Complete problems.

Not limited to decision problems and do not have to be NP problems.

If  $X$  is NP-hard, it there is a NP-complete problem  $Y$  such that  $Y$  is reducible to  $X$  in polynomial time.

Example: the Halting problem, given a program  $P$  and input  $I$ , will it halt?

A perfect example of a decision problem but is not NP.

Interesting note is that any NP-complete problem can be reduced to the Halting problem. Any NP-complete is NP-hard.

3) Assuming that Hamiltonian circuit problem is NP-complete, prove that traveling salesman problem is NP-complete via reduction.

$TSP \in NP$ ,  $TSP \leq \text{Hamiltonian Circuit}$

$G = (V, E)$  that we want to test for a Hamiltonian cycle

A TSP instance  $D$  consists of  $n$  cities and  $n(n-1)$  distances  
City  $C_i$  for every node  $V$

$$\text{let } d(C_i, C_j) = \begin{cases} 1 & \text{if edge } (V_i, V_j) \in E \\ 2 & \text{otherwise} \end{cases}$$

$G$  has a Hamiltonian cycle  $\Leftrightarrow D$  has a tour of length  $\leq n$

if  $G$  has a Hamiltonian cycle the the ordering of cities to be visited gives a tour of length  $\leq n$  in  $D$  (each edge in  $G$  has a length of 1)

A given tour length that follows the hamiltonian cycle has a sum of  $n$  terms with each term being 1, the cities to be visited must be visited consecutively by their connected edges along the formed hamiltonian circuit.

$TSP$  is NP-complete even if the  $d(i, j)$  between the cities are set to the real distances on a map.

$TSP \leq \text{Hamiltonian Circuit} \leq \text{Vertex Cover} \leq 3\text{-SAT} \leq 4\text{-SAT}$