



## INDICATIONS ON THE DISPLAY + USAGE OF INTERFACE

• SWITCH 2 = toggle between operational settings (NCO → PWM → Servo)

### ★ NCO - NUMERICALLY CONTROLLED OSCILLATOR

Actual frequency output

Fr: XXXXXX Hz  
St: XXX

Selected Oscillator

• HI = HFINTOSC (10 ÷ 16 MHz)  
• LO = MFINTOSC (10 ÷ 31250 Hz)  
(10 ÷ 15625 in LO)

Mode:

FD = Fixed (50%) Duty cycle  
PF = Pulse Frequency  
(slightly variable duty)

Increment/Decrement  
per Encoder rotation  
(Steps)

Value visible only in PF mode:  
it's the N1PWS value from NCO1CLK  
register: Output pulse Width

- ENCODER ROTATION: Sets the output frequency
- ENCODER PUSH: Switch between frequency steps
- POTENTIOMETER: Change duty cycle in PF mode
- SWITCH 0: Toggle between Oscillator (HI/LO)
- SWITCH 1: Toggle between Mode (FD/PF)

### ★ PWM - PULSE WIDTH MODULATION

Fr: XXXXXX Hz  
DC: XXX% Res: XX

Actual frequency outputs

Number of bits of duty  
resolution available for  
the selected frequency

Duty Cycle Percent  
(calculated on the high pulse)

- ENCODER ROTATION: Set the outputs frequency
- POTENTIOMETER: Change duty cycle

### ★ SERVO CHECK

Pul: XXXX ms  
Deg: XXX

Duration of high-level  
pulse (1500ms → Servo at  
center position)

Supposed angle servo  
could move at selected  
pulse value

- ENCODER ROTATION: Set pulse value/degrees
- ENCODER PUSH: Set pulse at 1500ms → Servo at center
- SWITCH 0: Set pulse at 600ms
- SWITCH 1: Set pulse at 2400ms

