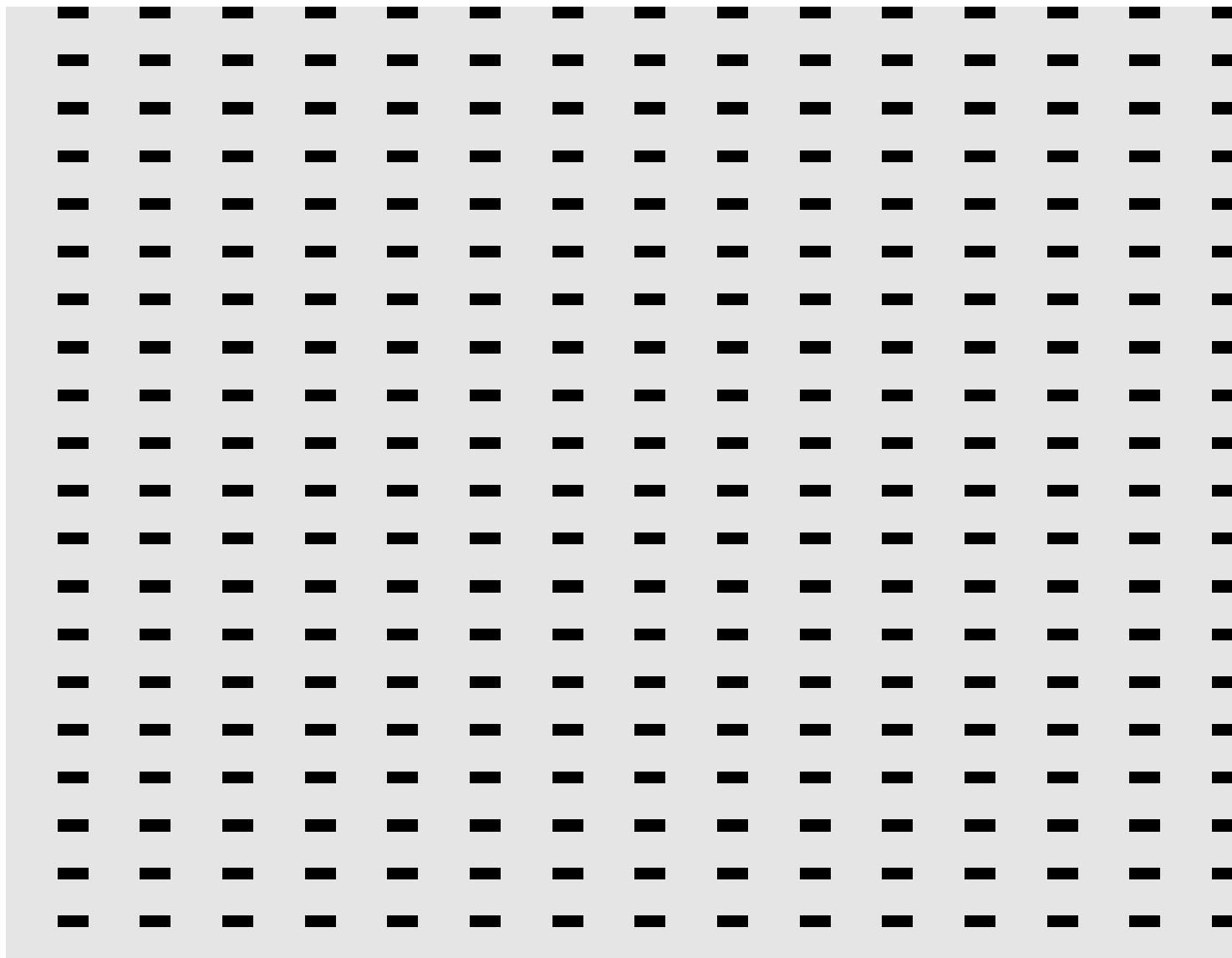
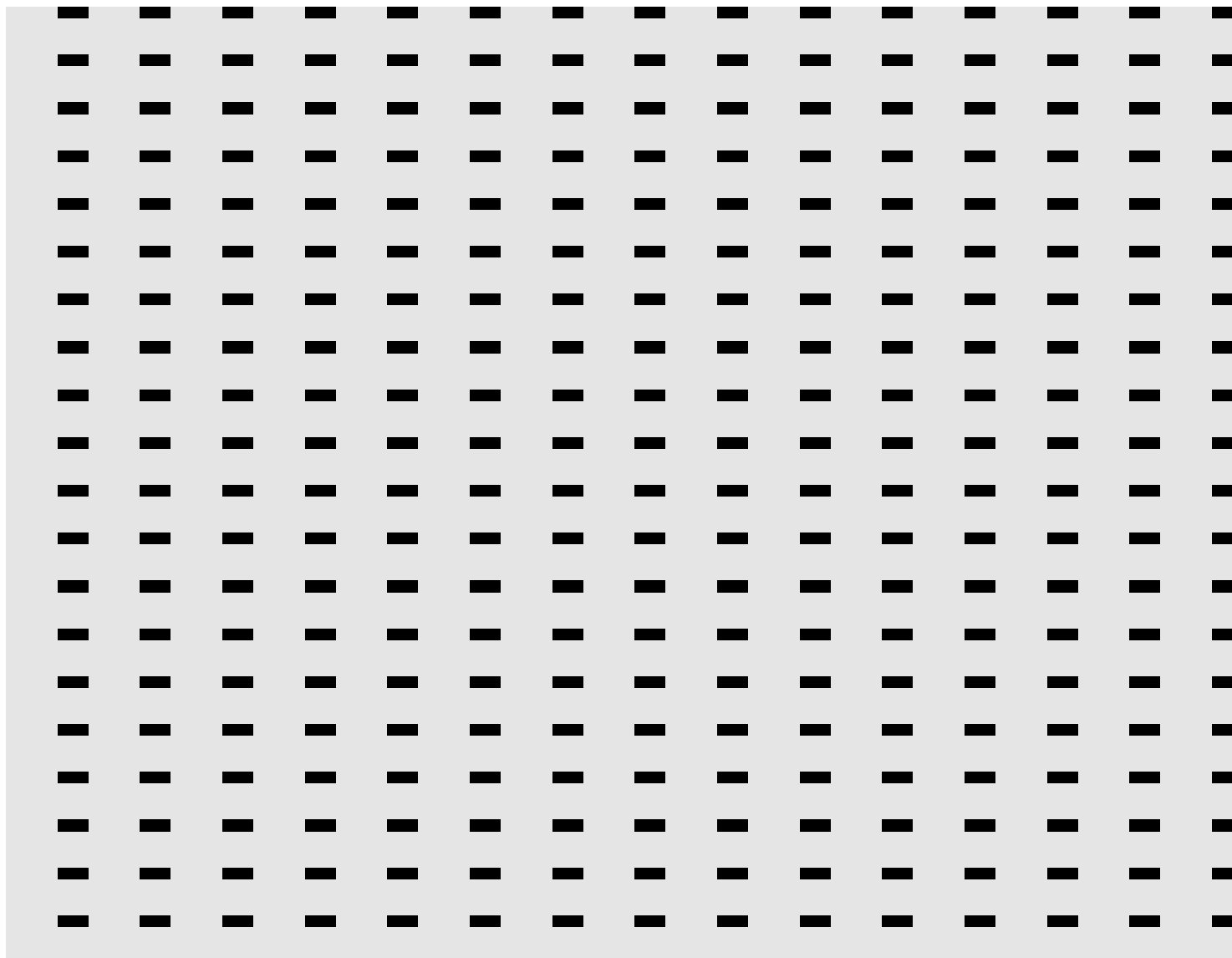


Tile 0, Coordinate: (4, 4)



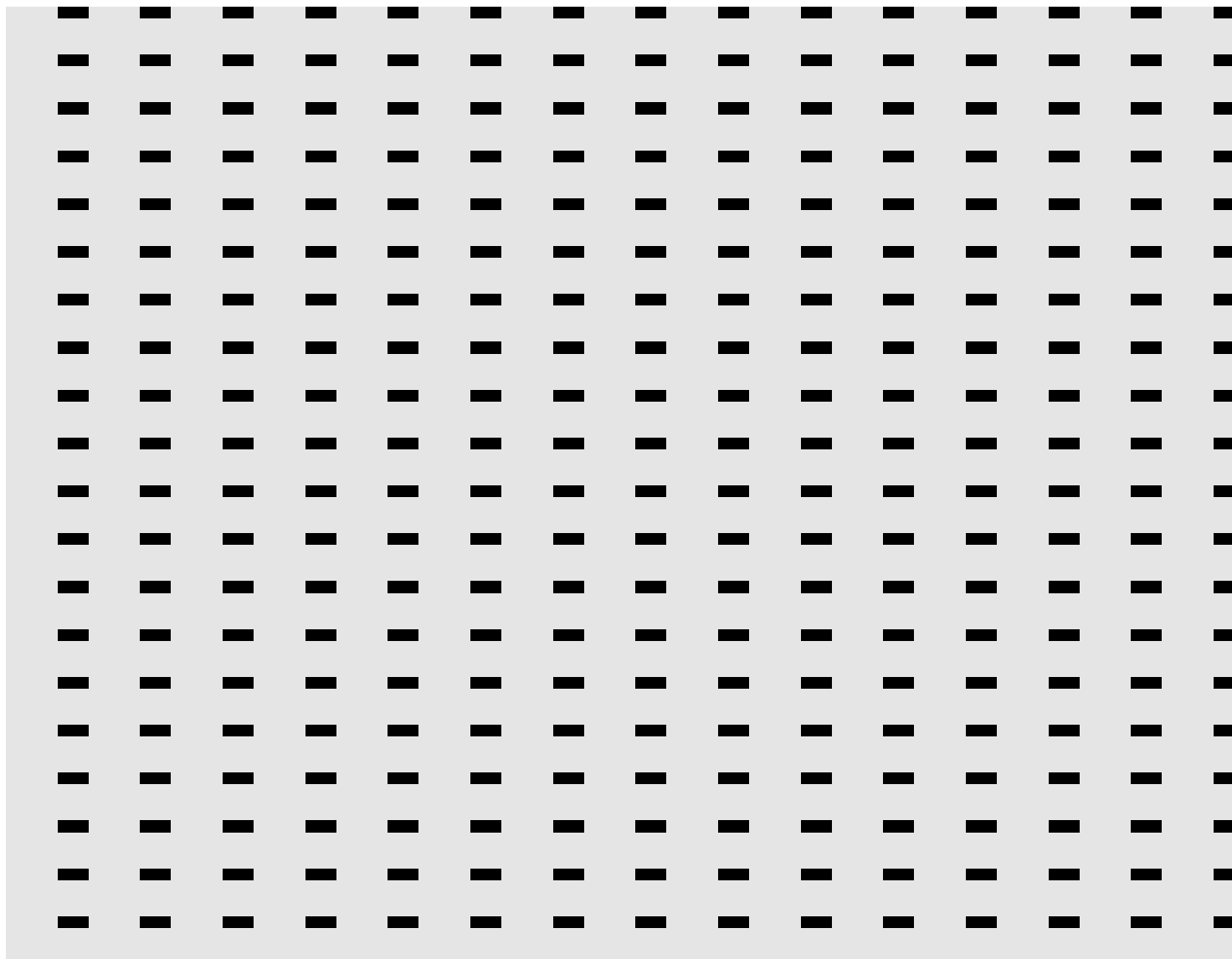
This side towards robot body

Tile 1, Coordinate: (4, 3)



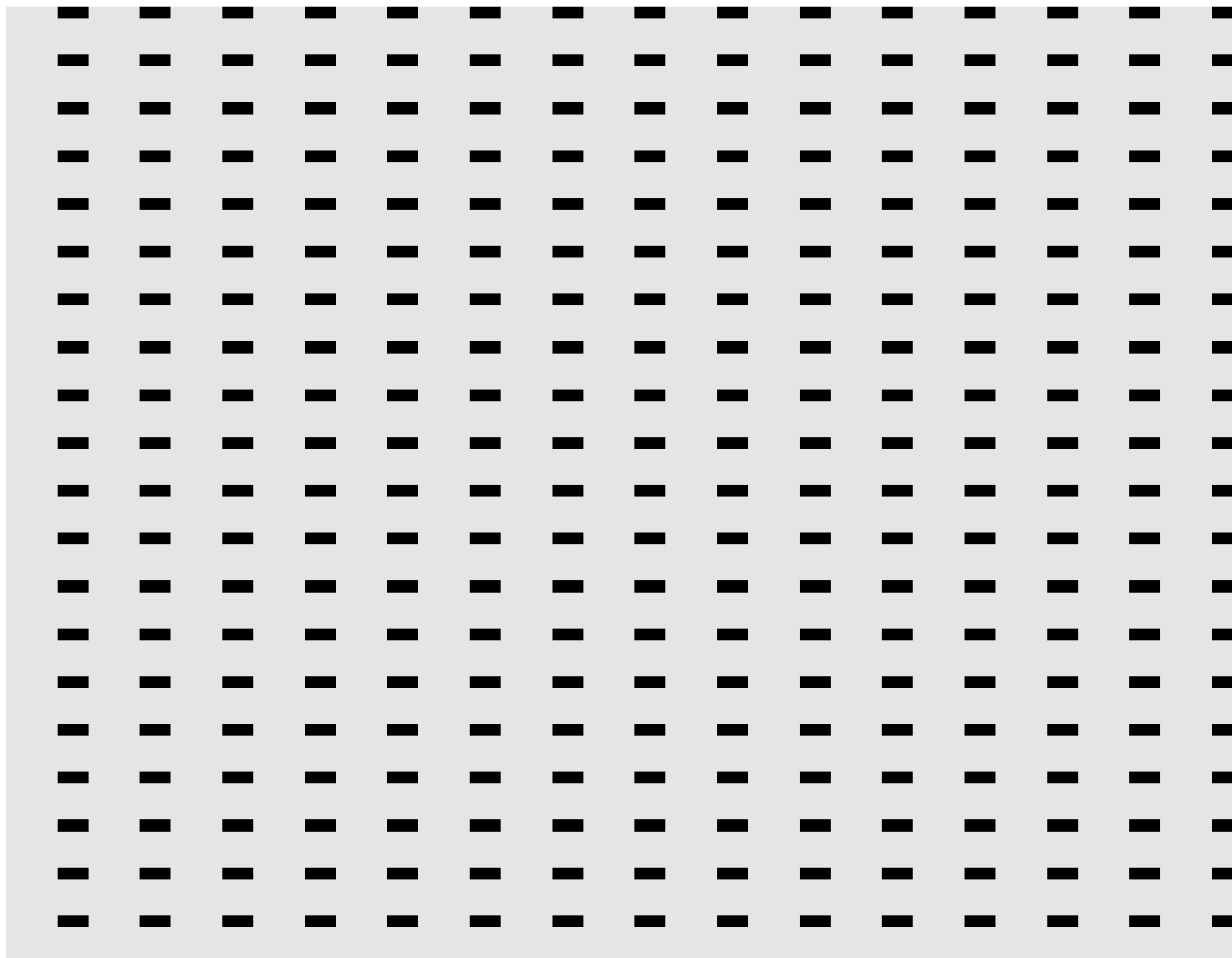
This side towards robot body

Tile 2, Coordinate: (4, 2)



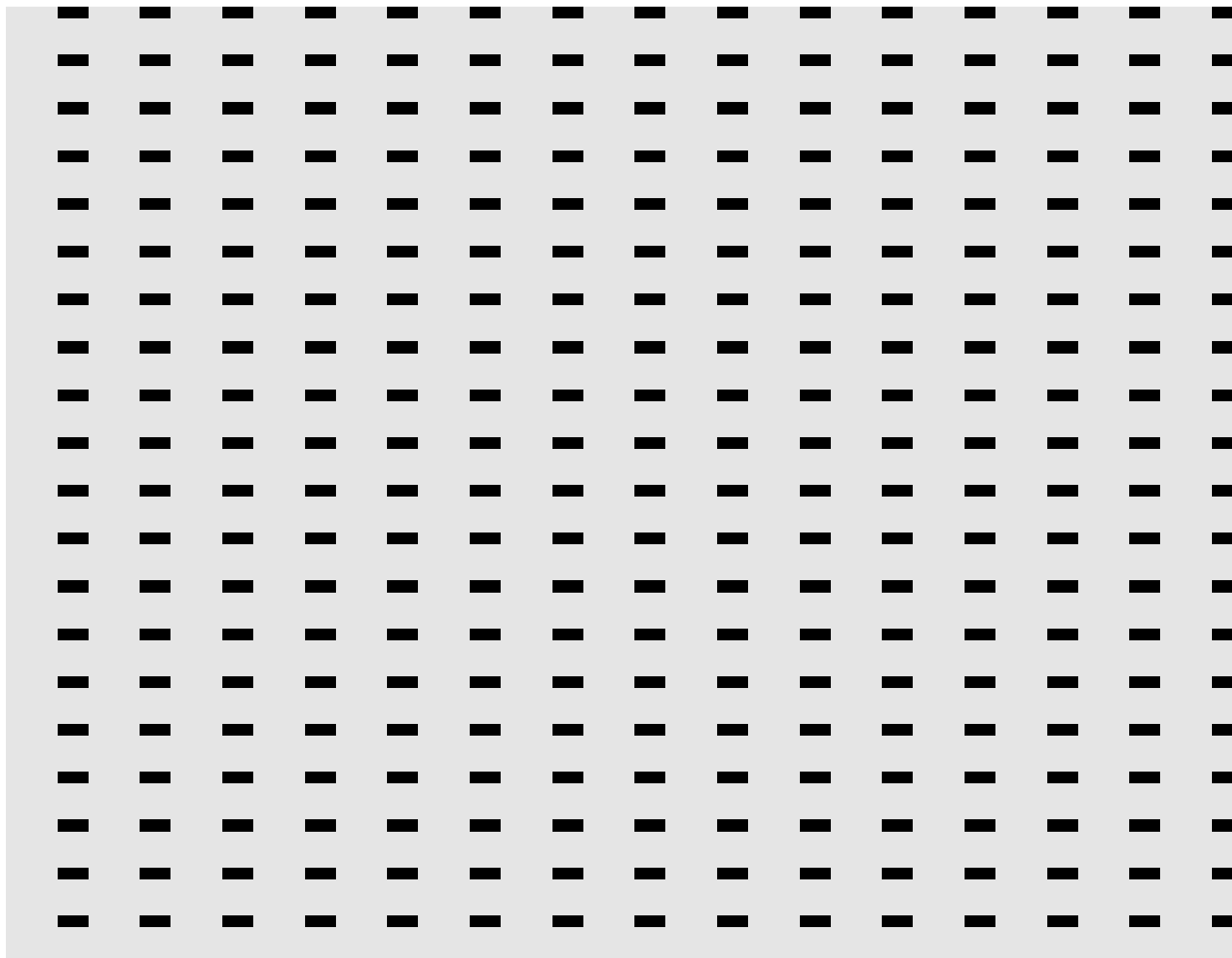
This side towards robot body

Tile 3, Coordinate: (4, 1)



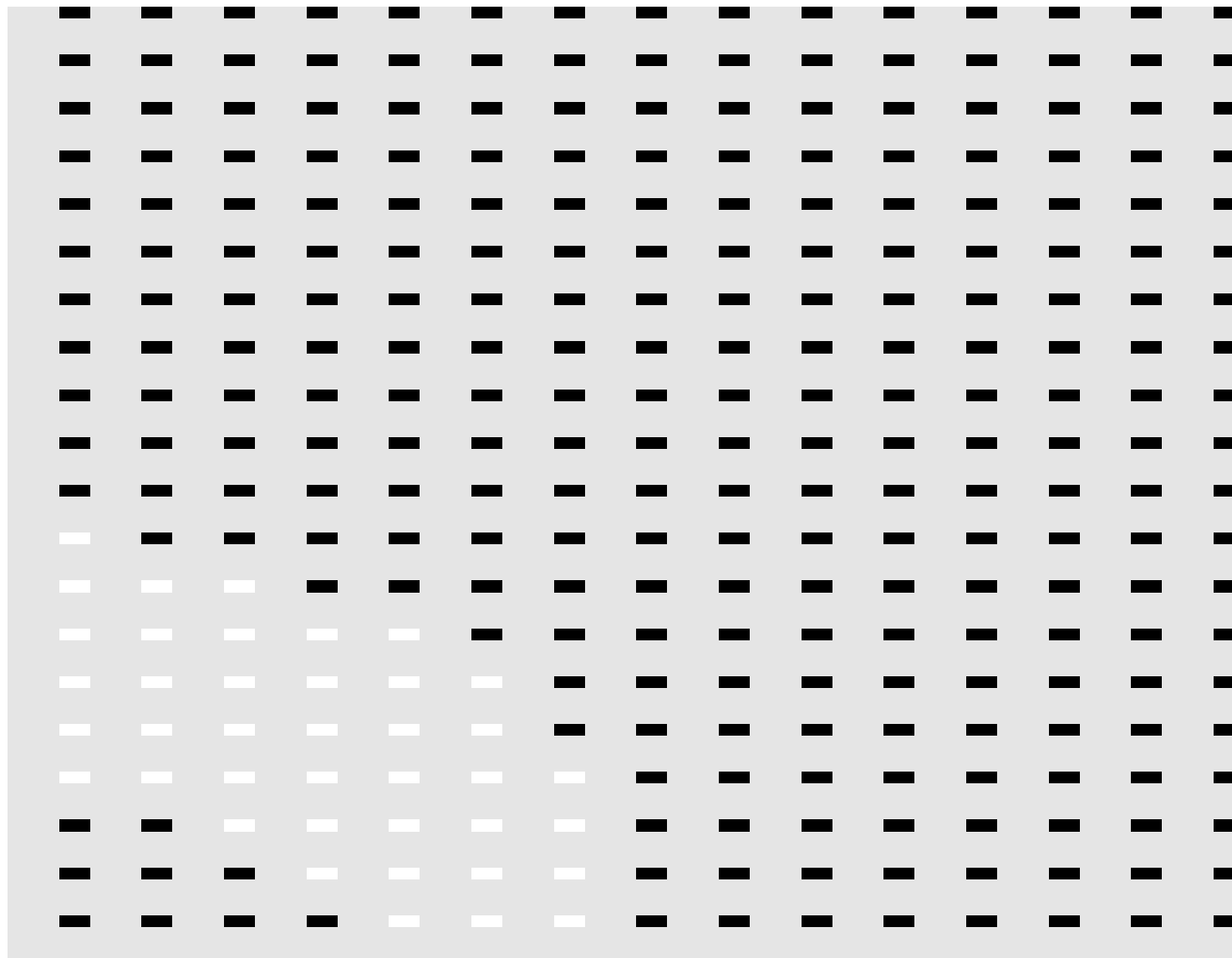
This side towards robot body

Tile 4, Coordinate: (4, 0)



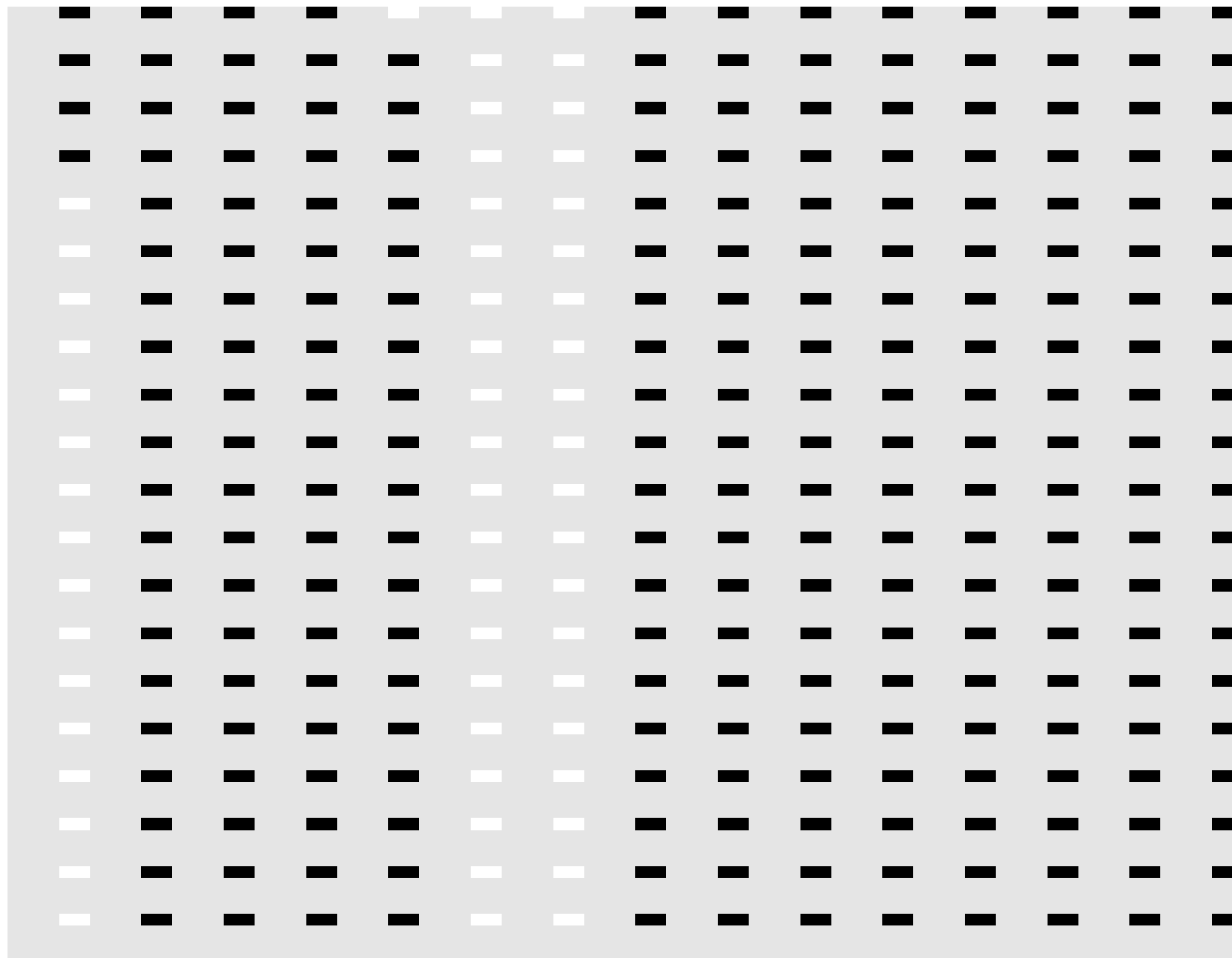
This side towards robot body

Tile 5, Coordinate: (3, 4)



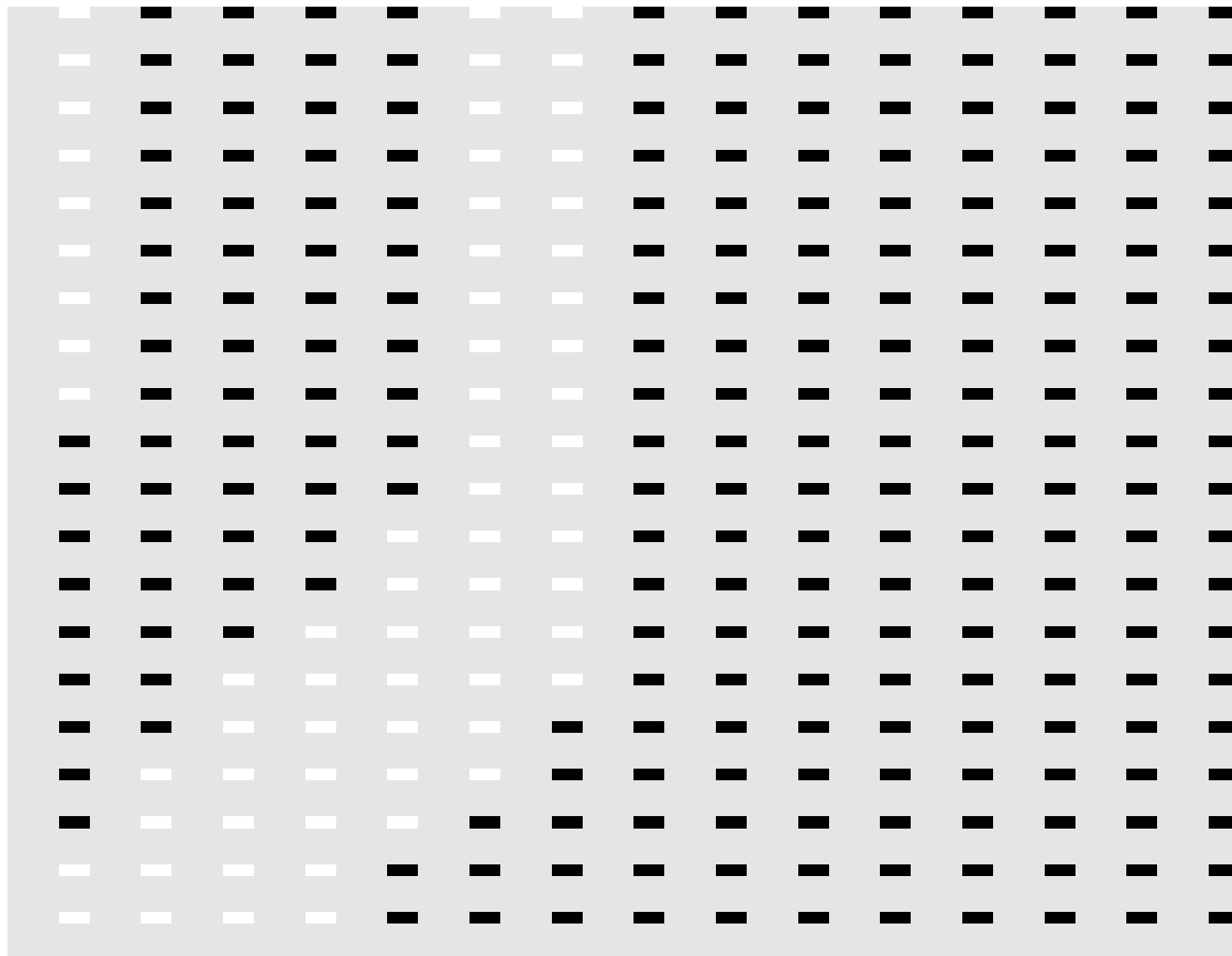
This side towards robot body

Tile 6, Coordinate: (3, 3)



This side towards robot body

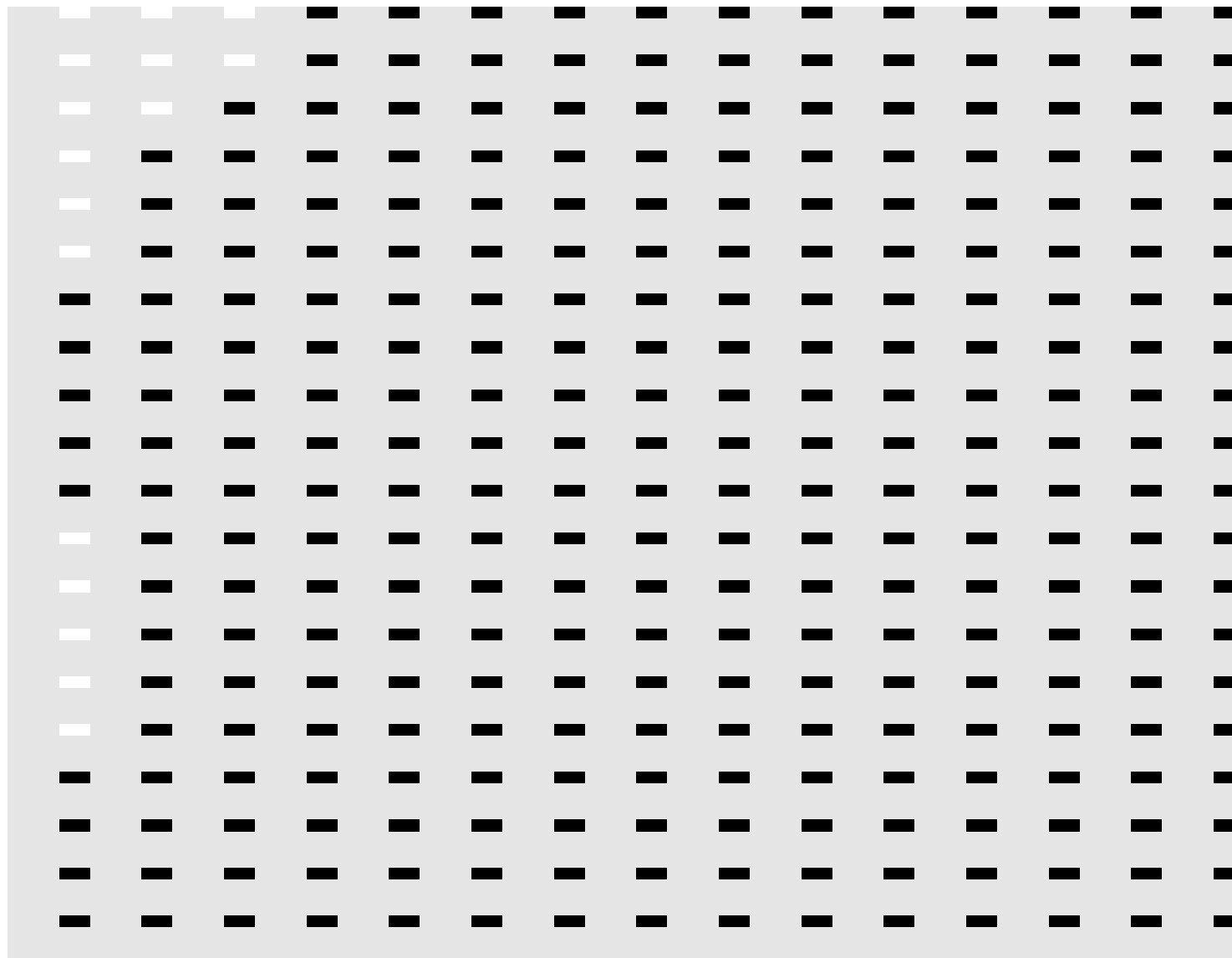
Tile 7, Coordinate: (3, 2)



This side towards robot body

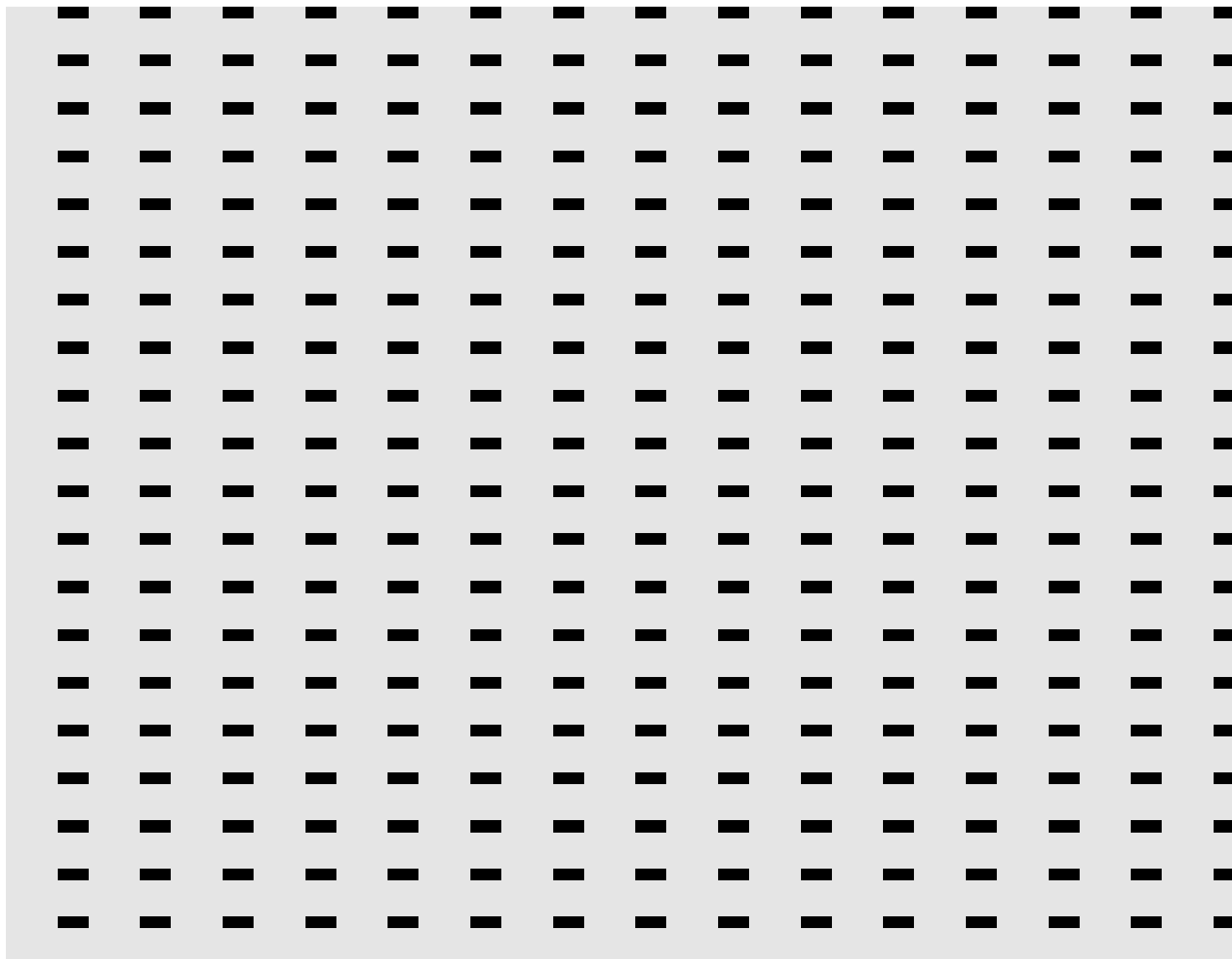


Tile 8, Coordinate: (3, 1)



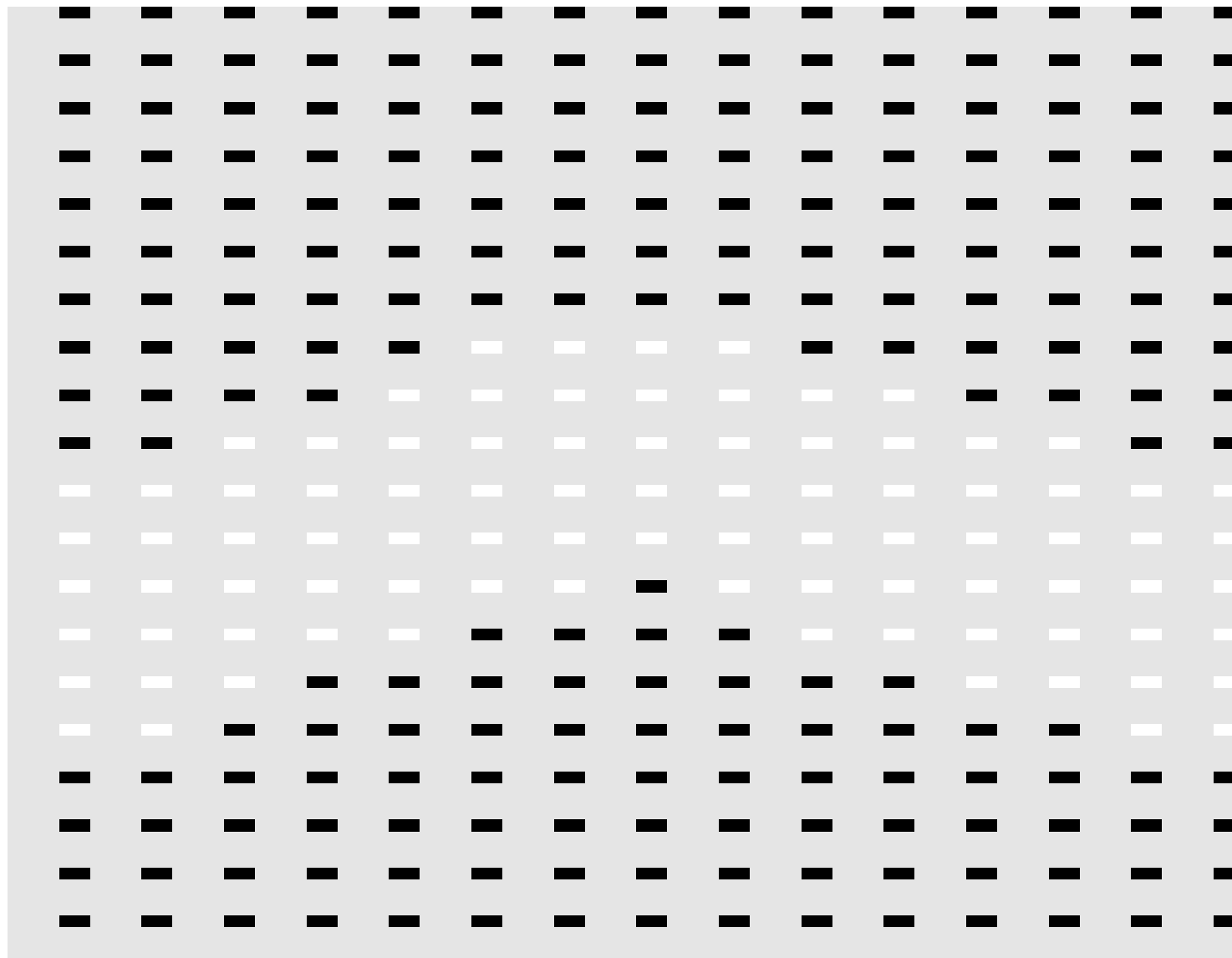
This side towards robot body

Tile 9, Coordinate: (3, 0)



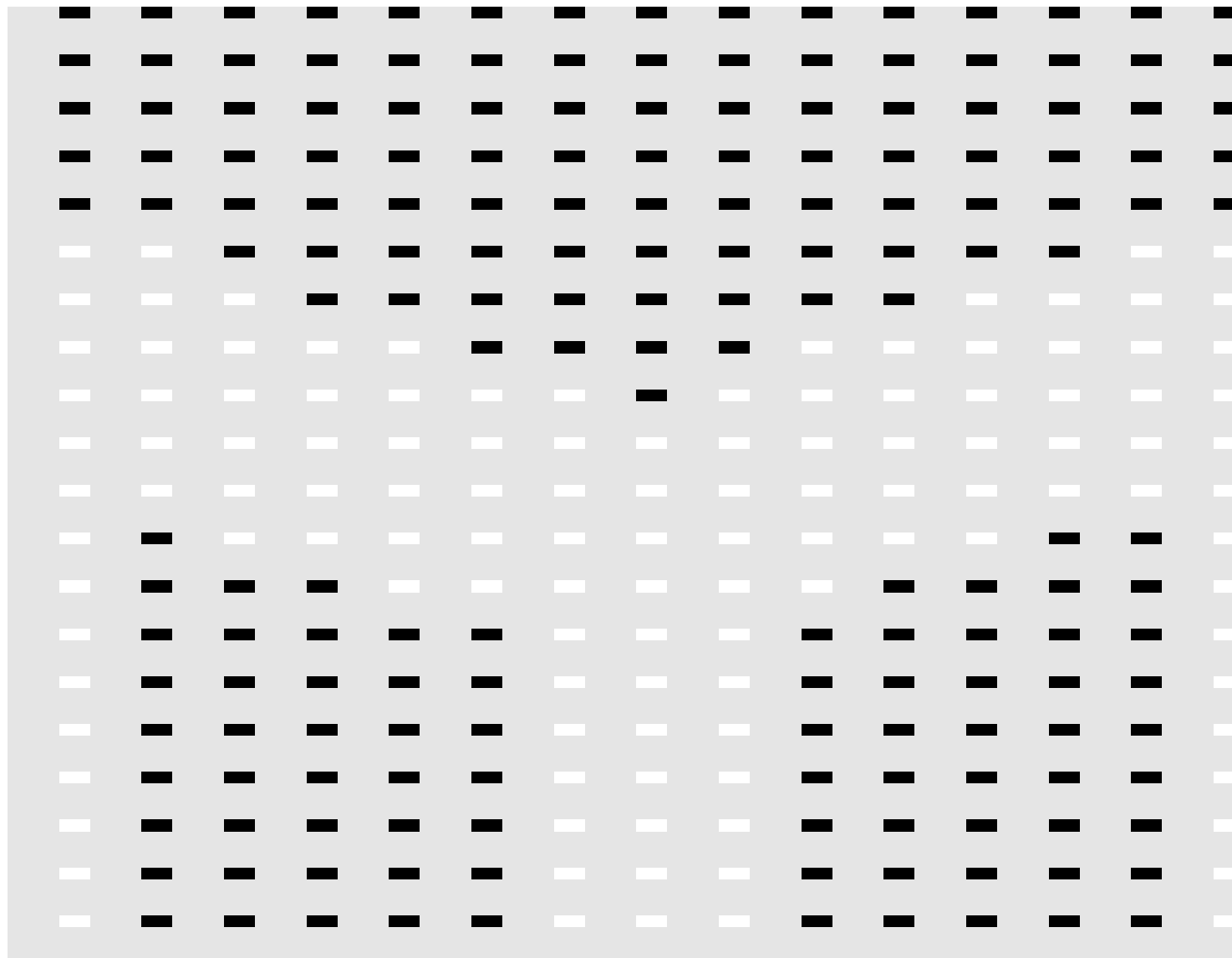
This side towards robot body

Tile 10, Coordinate: (2, 4)



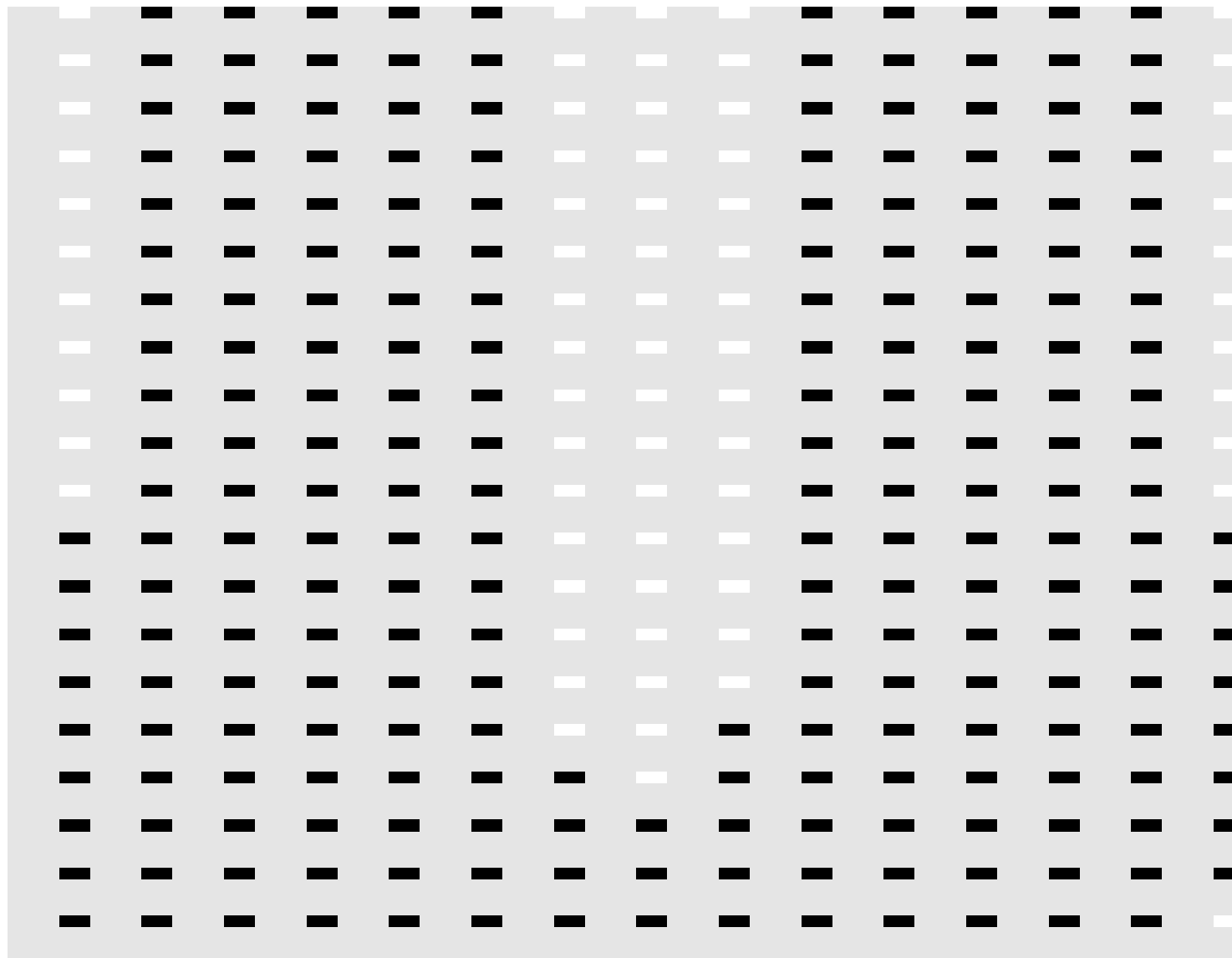
This side towards robot body

Tile 11, Coordinate: (2, 3)



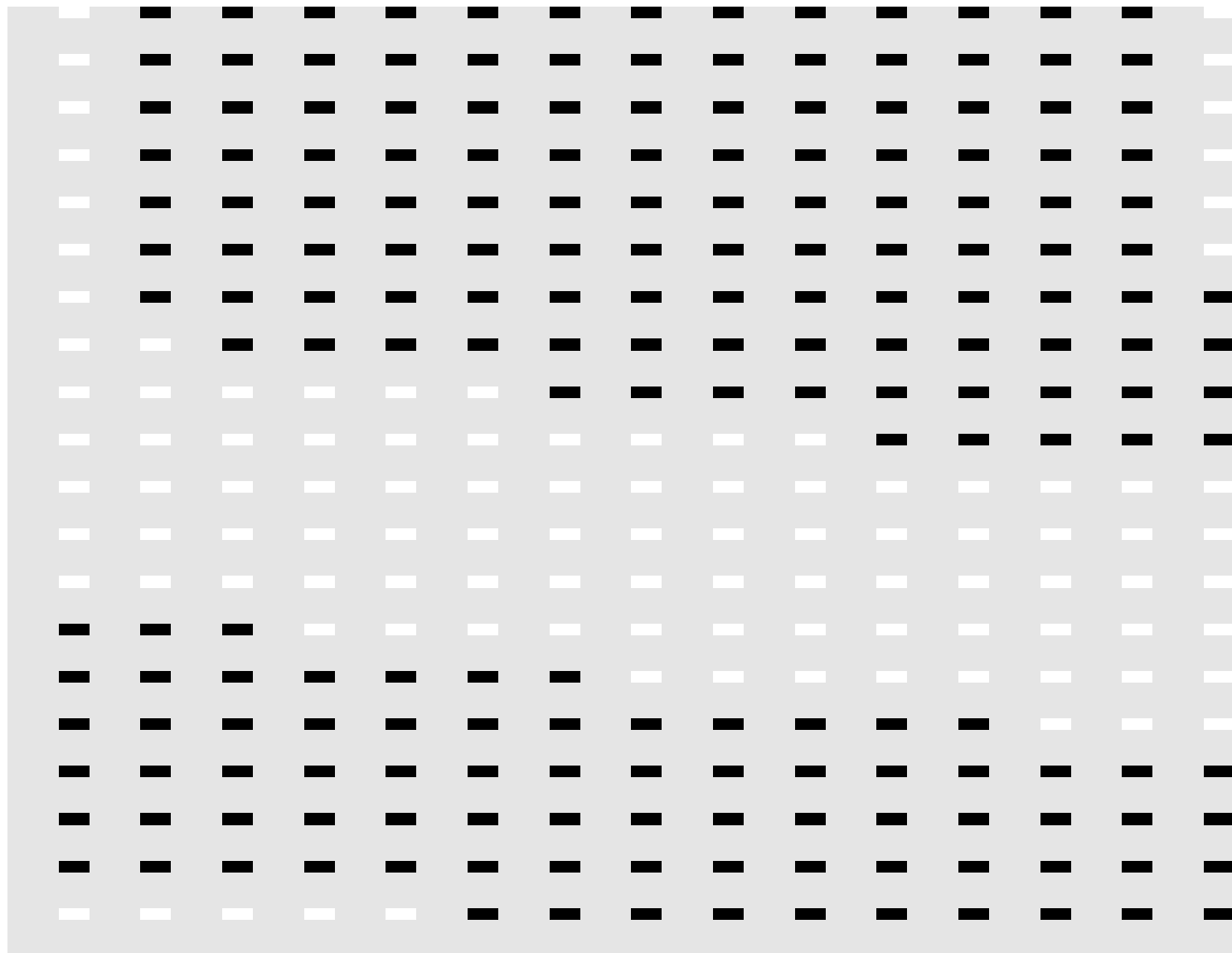
This side towards robot body

Tile 12, Coordinate: (2, 2)



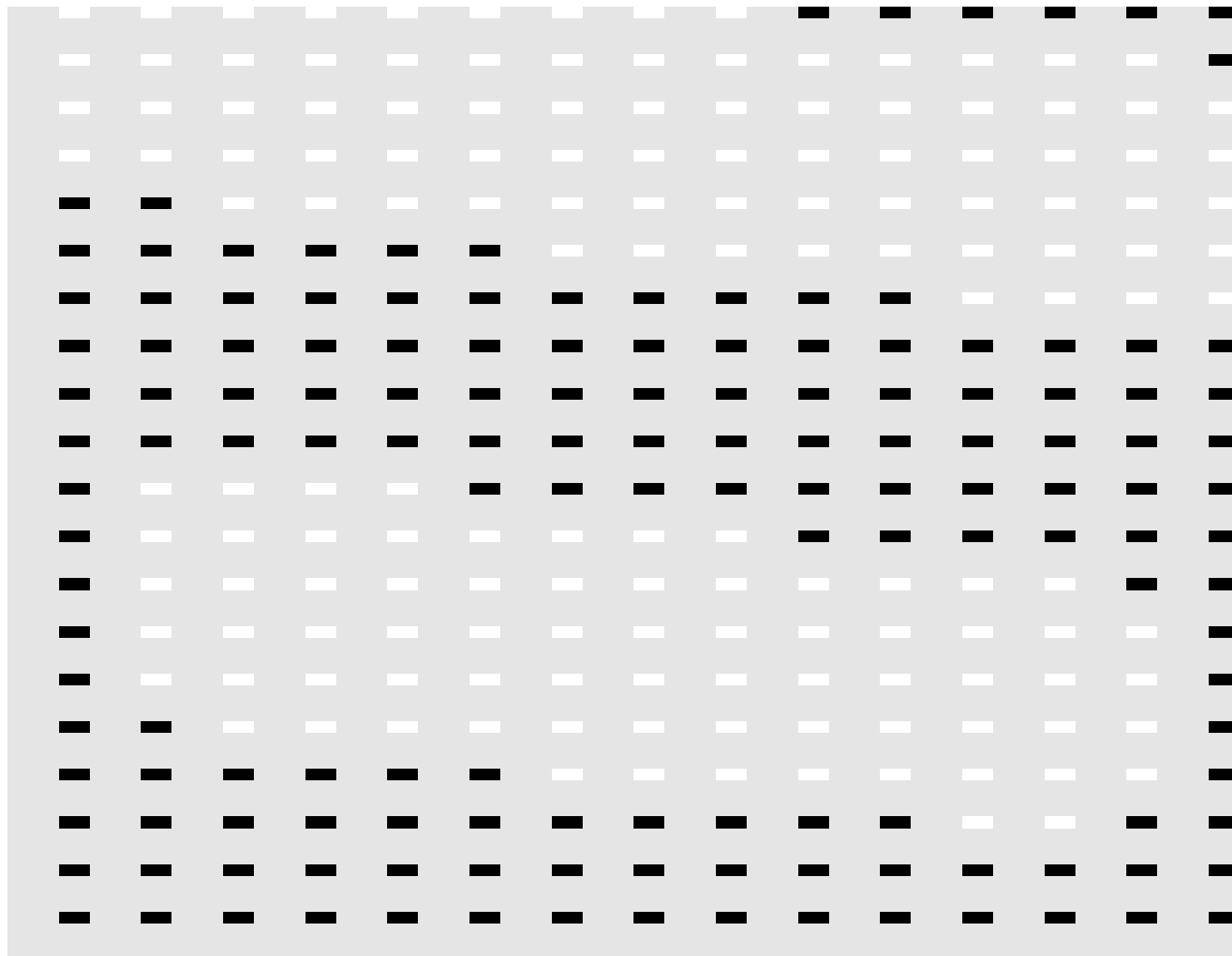
This side towards robot body

Tile 13, Coordinate: (2, 1)



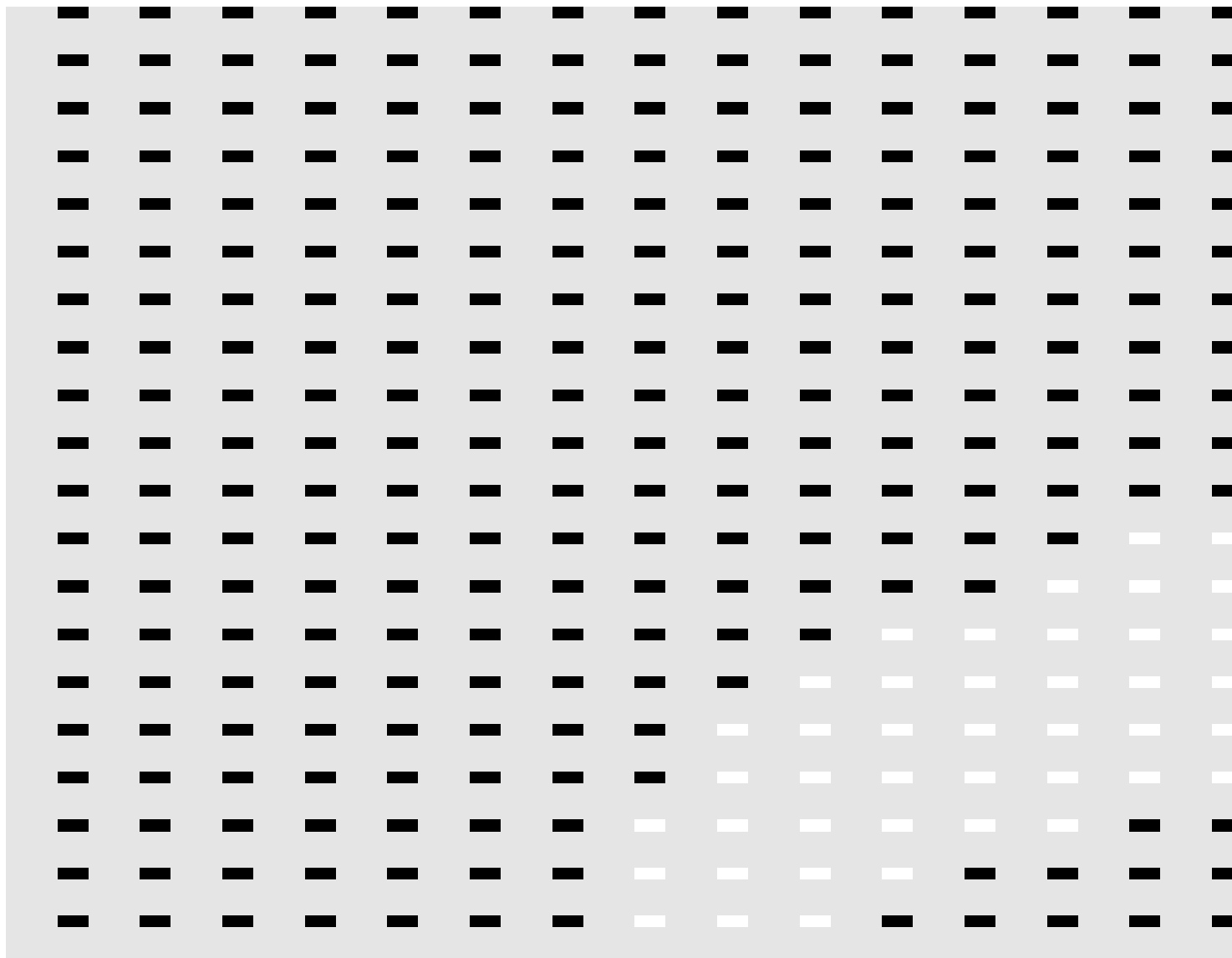
This side towards robot body

Tile 14, Coordinate: (2, 0)



This side towards robot body

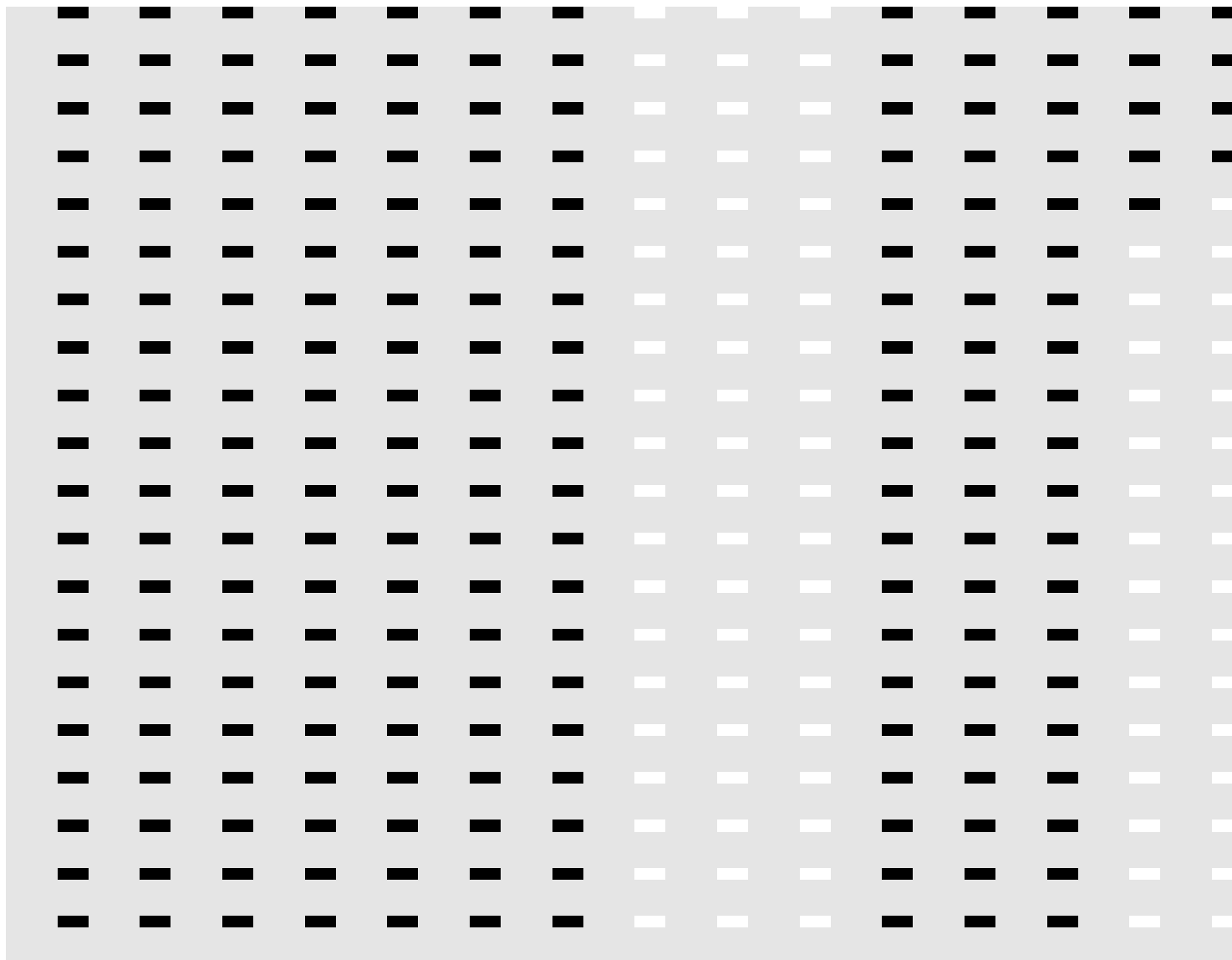
Tile 15, Coordinate: (1, 4)



This side towards robot body

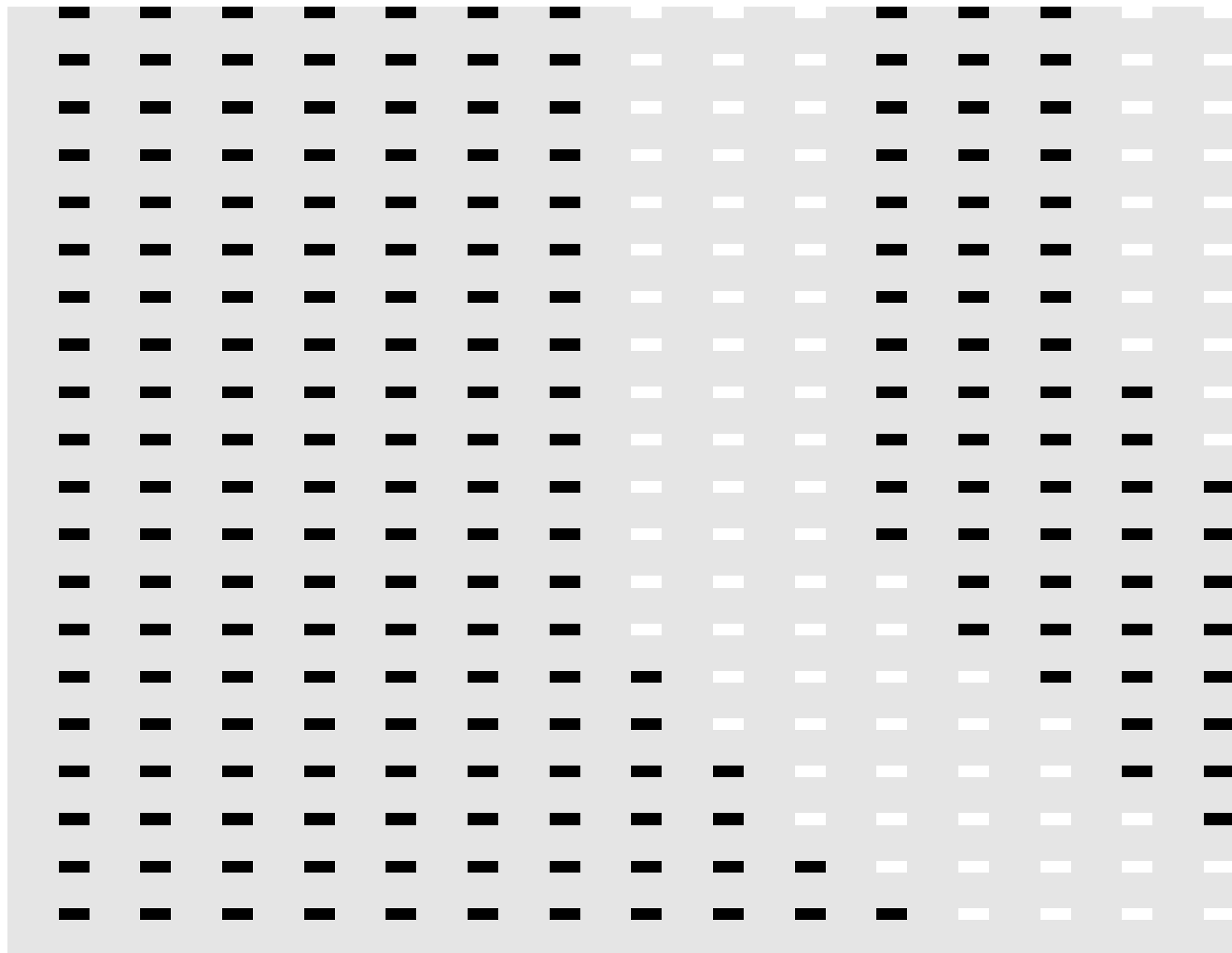


Tile 16, Coordinate: (1, 3)



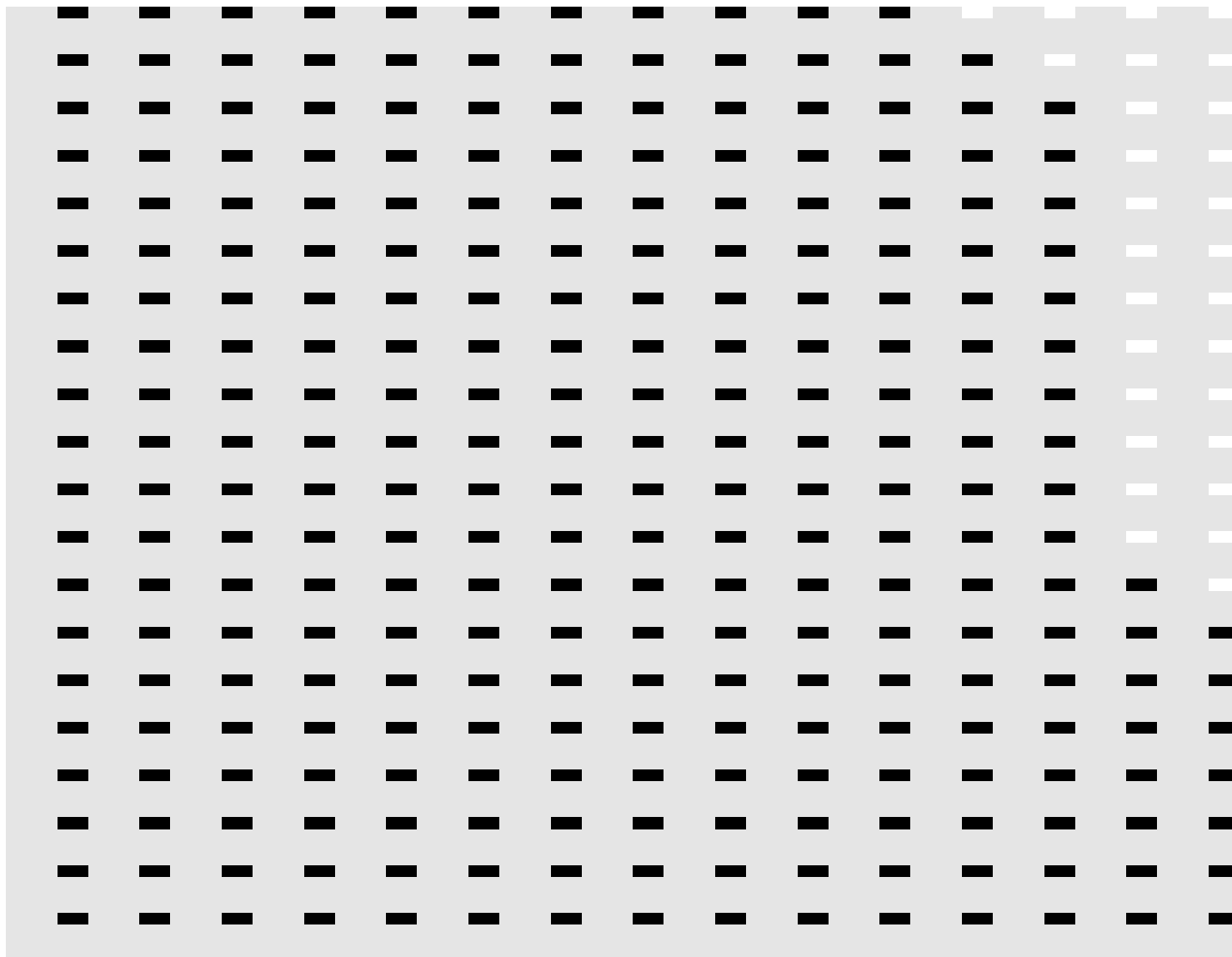
This side towards robot body

Tile 17, Coordinate: (1, 2)



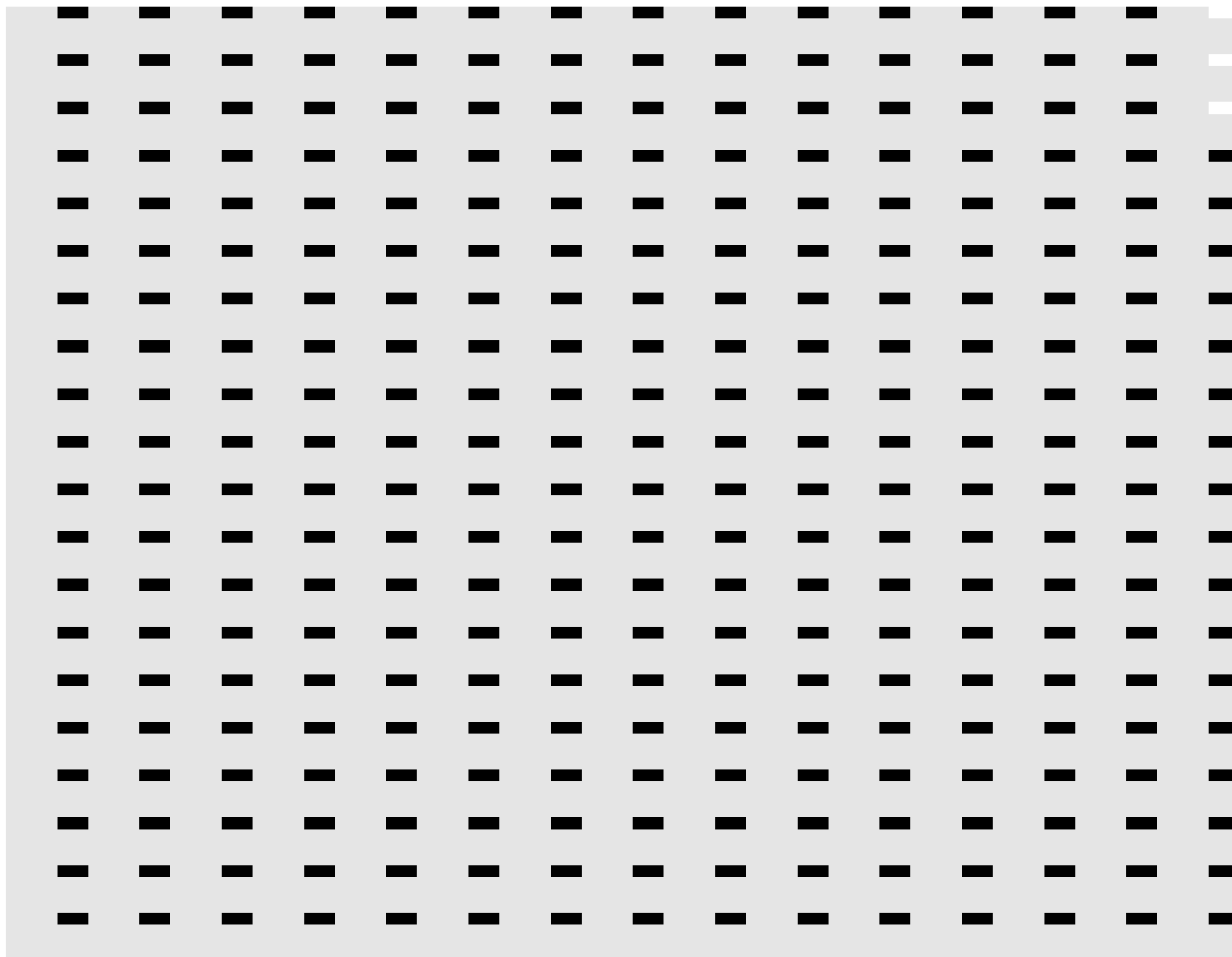
This side towards robot body

Tile 18, Coordinate: (1, 1)



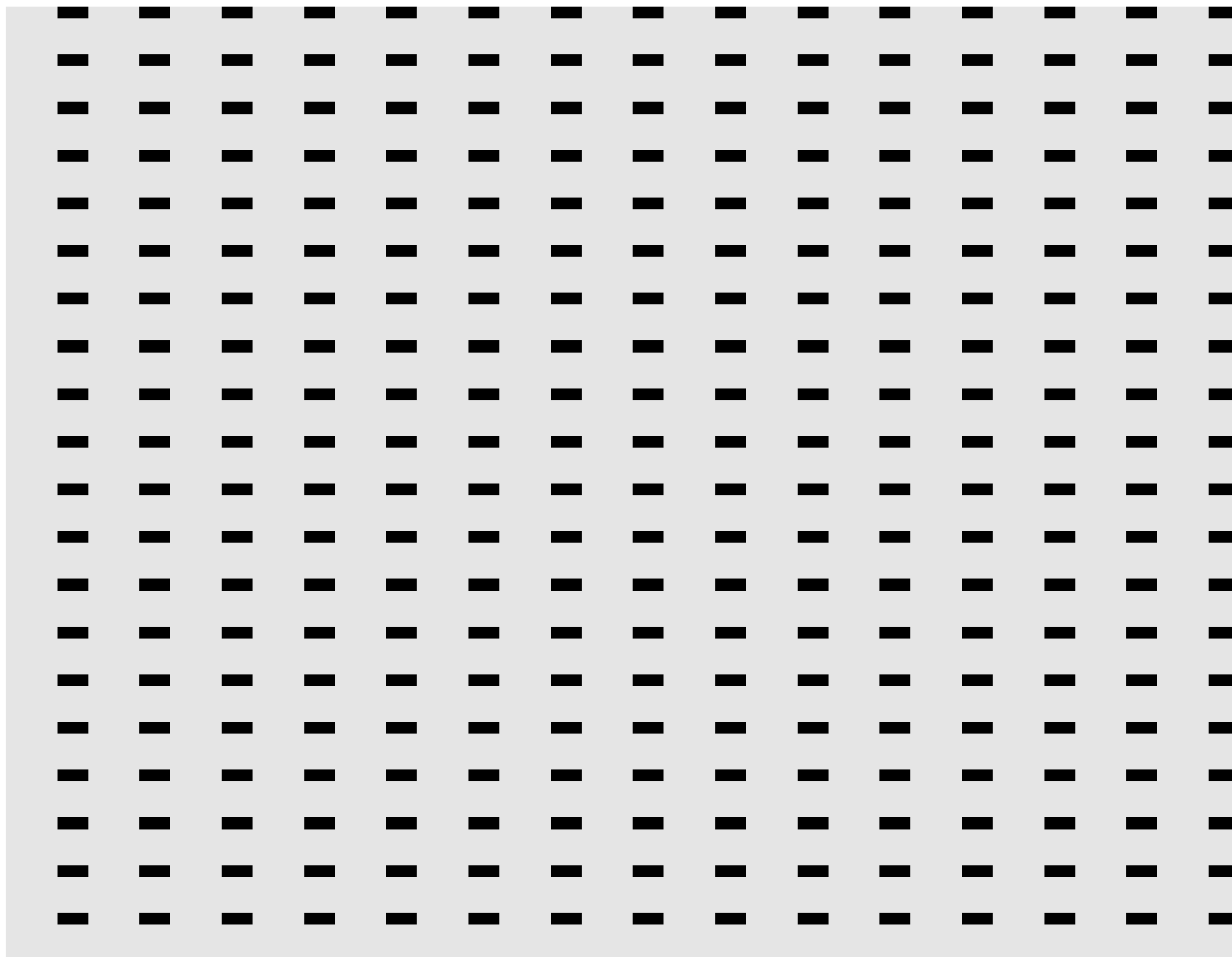
This side towards robot body

Tile 19, Coordinate: (1, 0)



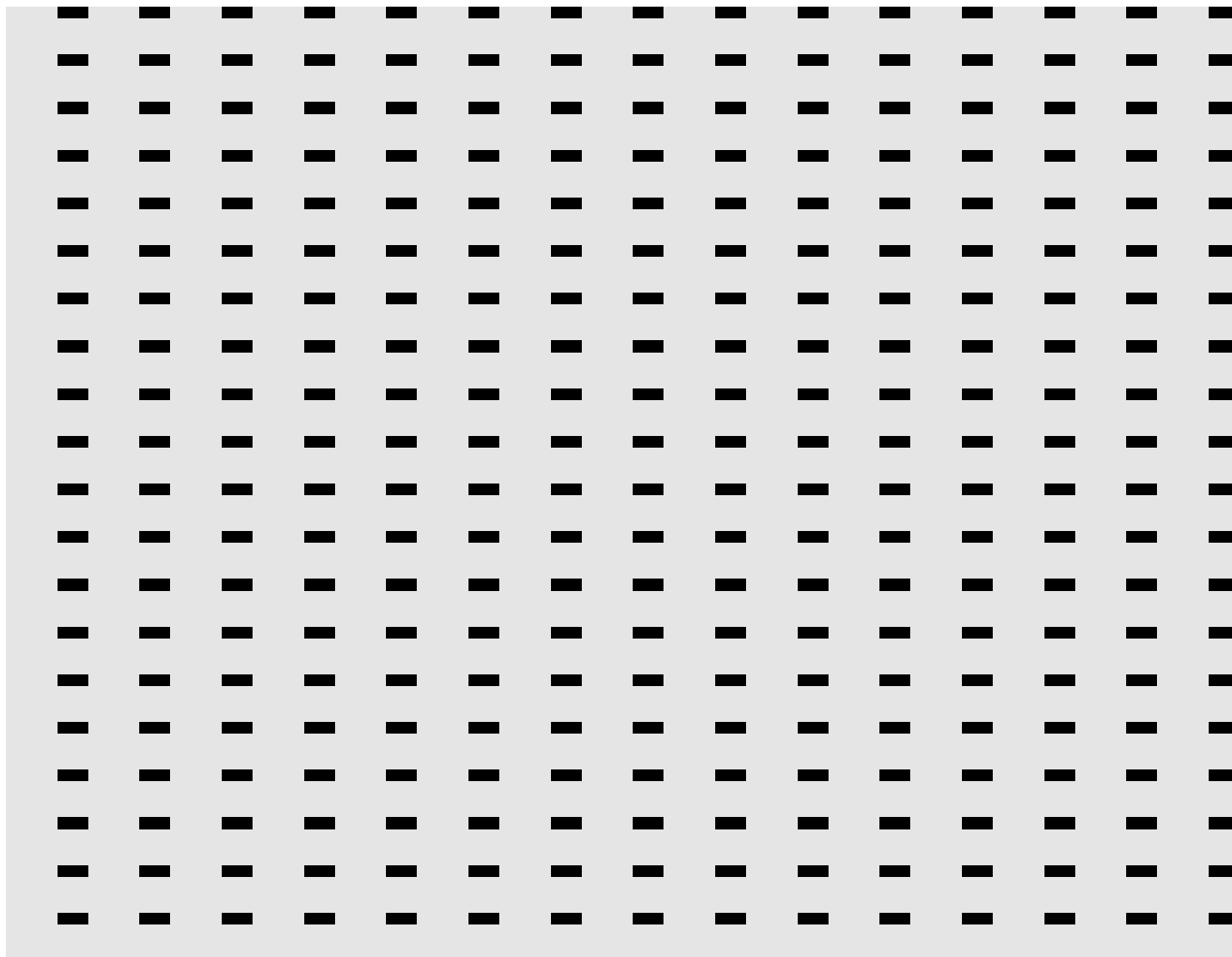
This side towards robot body

Tile 20, Coordinate: (0, 4)



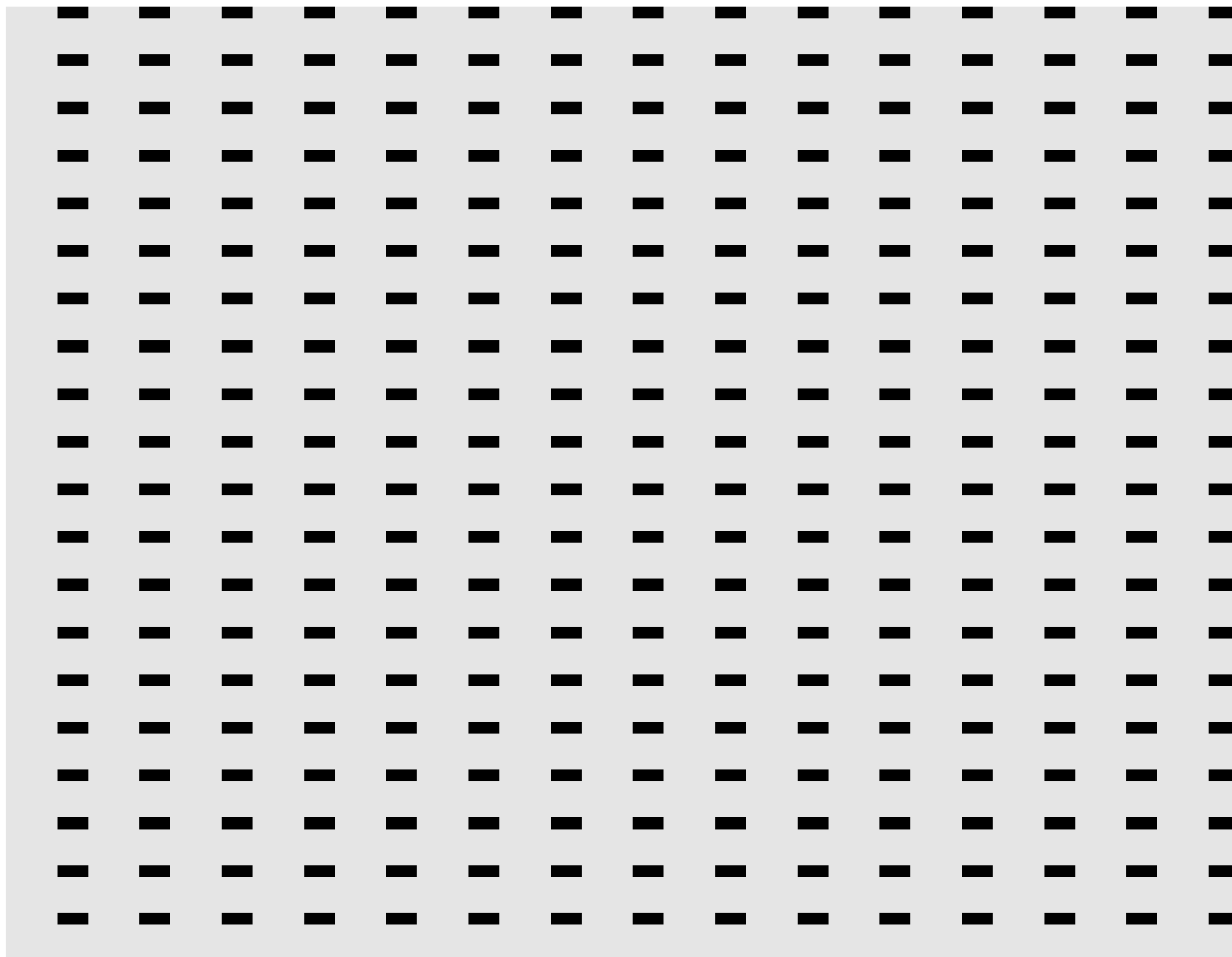
This side towards robot body

Tile 21, Coordinate: (0, 3)



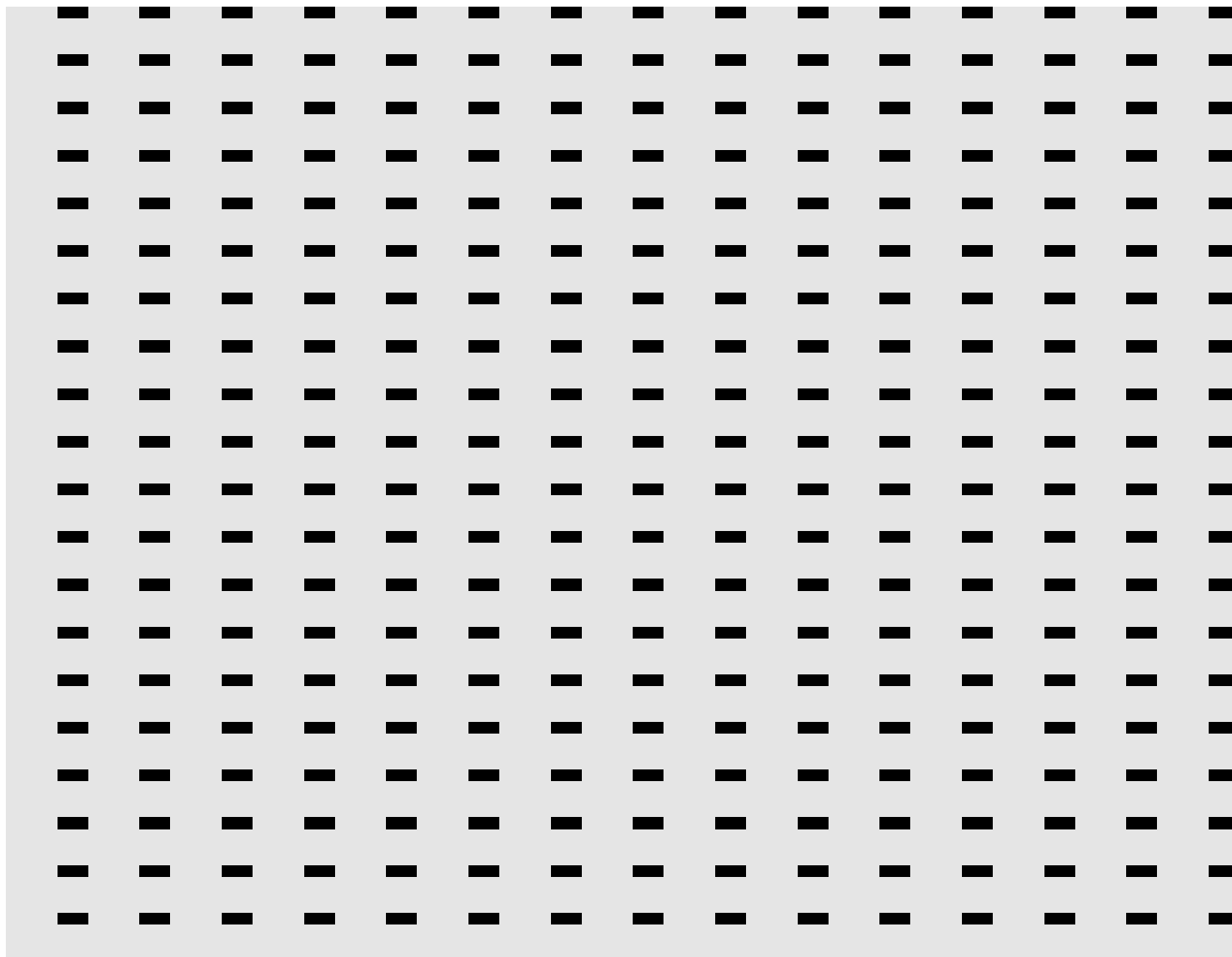
This side towards robot body

Tile 22, Coordinate: (0, 2)



This side towards robot body

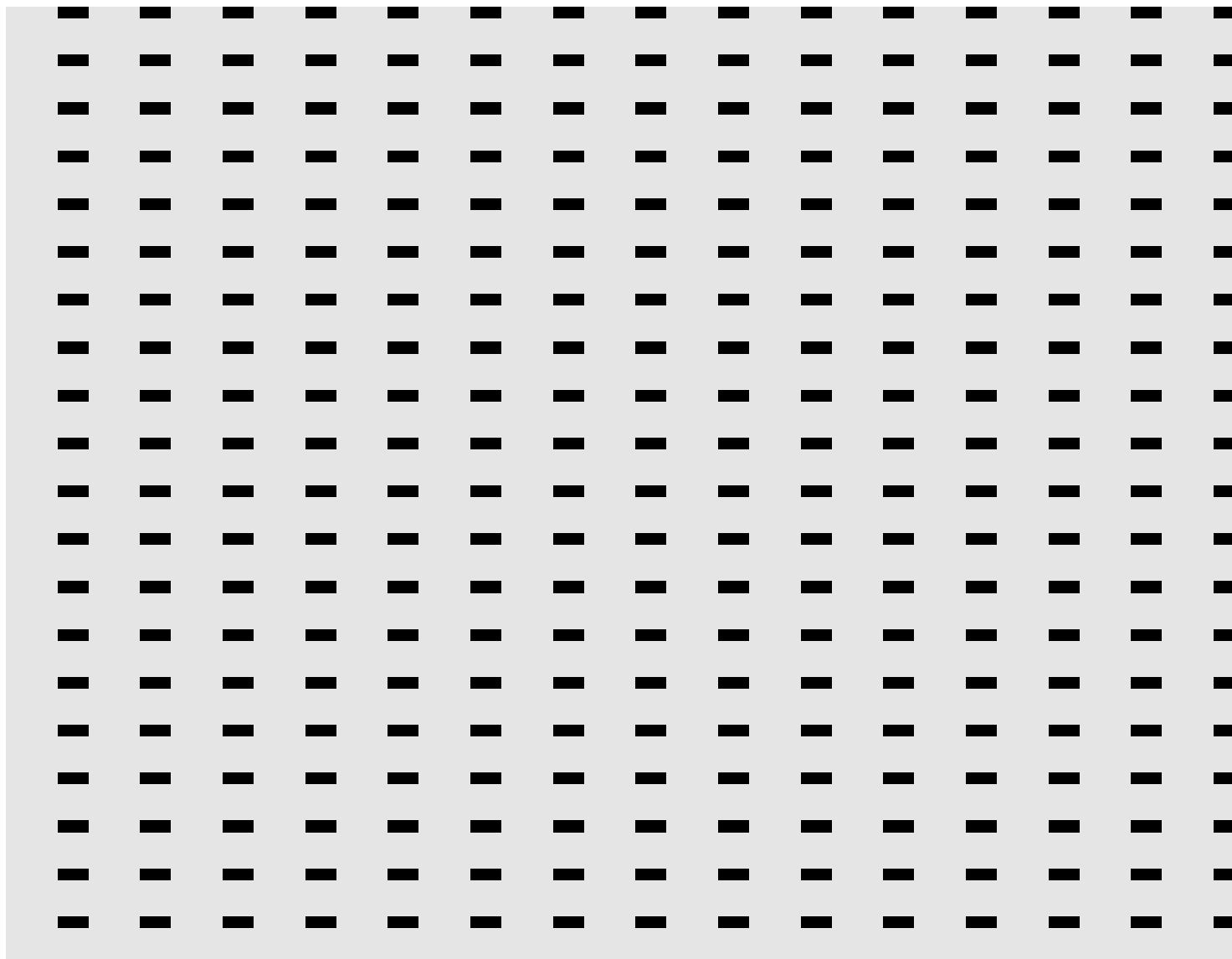
Tile 23, Coordinate: (0, 1)



This side towards robot body



Tile 24, Coordinate: (0, 0)



This side towards robot body