AFFIRM Quarterly Meeting

February 15, 2017

Year 3 Plans

- Build a prototype SAL/Sally backend for the ADSL:
 - translation of expression language and message passing semantics
 - configurable hybrid fault model
 - generation of framework specific lemmas (e.g. calendar lemmas)
 - specification of properties
 - generation of observers and abstract state machines
- Specify our case studies in terms of the prototype ADSL and translator
 - OM(1)
 - WBS
 - Multi-level system: BRAIN, TTE, ...

• ...

Configurable hybrid fault model:

Built-in options:

- no faults
- fixed fault mapping
- hybrid fault model with user specified maximum fault assumption

New Channel API:

```
    channel :: Name
        -> Type
        -> Atom (ChanInput, ChanOutput)
    writeChannel :: ChanInput -> E a -> Atom ()
    readChannel :: ChanOutput -> E a
    fullChannel :: ChanOutput -> E Bool
    consumeChannel :: ChanOutput -> Atom ()
```

These calls are now translated into calendar automata actions.

We added and/or improved synthesis of:

- clock module
- calendar entries
- fault model
- maximum fault assumption

We added a few user-facing features:

- Add simple debugging option to Sally models
- Arithmetic term rewriting to generate smaller models

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Modular Model-Checking of a Byzantine Fault-Tolerant Protocol

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Abstract. With proof techniques like ICS and &-induction, model-checking scales further than over before. Still, fault-telerant distributed systems are particularly challenging to model check given their large state spaces and non-determinism. The typical approach to controlling complexity is to construct ad hoe abstractions of faults, message passing, and behavions, However, these abstractions come at the price of divorting the model from its implementation and making refactoring difficult. In this work, we present a framework for facilitationest distributed system wellfication that combining ideas from the literature including calendar automata, symbolic fruit injection, and abstract transition systems, and then we apply the framework to model-checking vertors implementations. of the Hybrid Gral Messages algorithm that differ in the fault model, timing model, and local node behavior. We show that despite being implementation-lovel models, the verifications are scalable and modelar, insofar as isolated changes to an implementation require isolated changes to the model and proofs. This work is carried out in SAL model-chocker.

1 Introduction

Fault-telerant distributed systems are framously complex, yet are the backbone of life-critical systems, such as commercial axionies. Consequently, this class of systems demands high-assurance of correct design and implementation. Formal verification can help provide that assurance

The verification of this class of systems has usually been at the algorithmic level, chicing details about a concrete implementation, and historically, has relied on formal models verified by interactive theorem-proving [1–4]. If formal verification is to be introduced into the workflow of system designers, though, we need more automated methods that scale for implementation-level models. (Mostly) automated proof techniques are required to reduce the need for specialized verification expertise. We also need programmatic verification of implementations. System designers create software and hardware implementations to test, simulate, and deploy. Discrepancies between implementations and algorithmic models can arise if the latter is abstracted too much from the former [3], particularly if those abstractions are ad-look and system specific. Furthermore, as implementations are medified to explore the design space, it is easy for the formal model

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- generation of <u>framework lemmas</u> (e.g. calendar lemmas)
- generation of <u>synchronous observers</u> and <u>abstract state machines</u>
- refine our case studies in the ADSL:
 - WBS
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