### COM1031 - Group 1224 Coursework Report

# 1 - The problem:

The problem we faced was to implement a Morse code decoder and encoder, for all the letters of the alphabet, in AVR assembler - our implementation would be compiled to machine code and executed by an Arduino Uno's ATmega328p chip.

## 2 - Overview of implementation:

## A. Morse Code Decoder:

Our Morse code decoder can decode all the letters in the alphabet (A-Z). A high-level overview of our implementation is best explained by the flowchart below:

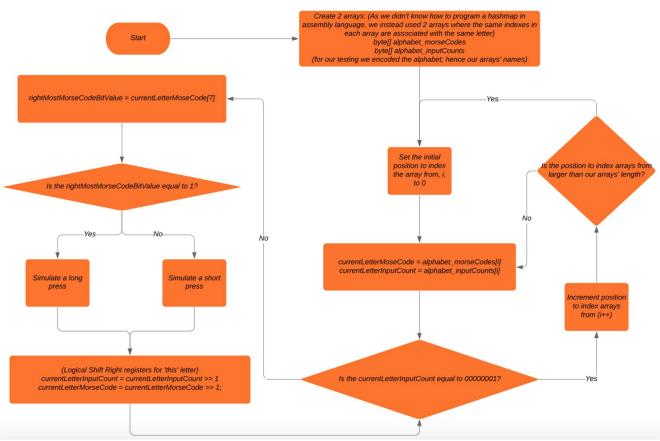
#### Morse Code Decoder Flowchart James Bigwood | December 13, 2019 Interrupt: More Start Interrupt: Button than 0.4 seconds interaction since a button interaction Setup (set indexer to 1, and morse code to 0) Are we waiting for byte indexer = 0x01 Is it a debounce: a button press or byte morse = 0x00Waiting for press release? No Match morse code to Infinite Loop an element in the array (Waiting for Was the button that contains the morse interrupt) pressed or Releasedcode's 7-segment released? representation Pressed Yes Nas it a long of Display matched short press? Long 7-segment representation on 7-segment LED Begin a timer to track the duration Short of 'this' press (set index in morse code to 1) OR morse, indexer Waiting for release byte indexer = 0x01byte morse = 0x00(increment indexer) ADD indexer, indexer Return Return

### B. Morse Code Encoder:

Our Morse code encoder can encode any sequence of any letters in the alphabet. A high-level overview of our implementation is best explained by the flowchart below:

#### Morse Code Encoder Flowchart

James Bigwood | December 14, 2019



# 3 - The main challenge we faced

- The problem Within our Morse code decoder solution, if we released the button more than 7 times then our 'indexer' register (labelled in the flowchart) would overflow. As a result, the output to signify an invalid input wasn't displayed.
- The solution We setup a register that would act as a boolean variable. This register would be initialised as 0, and if the user had released the button more than 7 times, the register would be set to 1. We could then test to see if this register had been set to 1 before reading out the Morse code and, if it was, we output a display to signify an invalid input.

### 4 - Work-load distribution

- Daniel Jezeph Implemented Morse code decoder. Focused on the implementation of the button interaction interrupt and assisted with other areas.
- James Bigwood Implemented Morse code decoder. Team lead primarily working on the interrupt for more than 0.4 seconds and assisting with other tasks and encoder.
- Athanasia Hadjichristou Implemented Morse code decoder. Focused on much of the main start-up of the program and assisted with other areas.
- Hrithik Udae Lacximicant Implemented Morse code encoder. Deputy lead, assisted with much of the decoder as well. Focused on the set up and implementation and interaction of the arrays.
- Liam Errington Implemented Morse code encoder. Error checking and solution to overflow problem and assisted with decoder.
- Isayah Wedderburn Implemented Morse code encoder. Implemented the simulation of short and long presses on the encoder and assisted with decoder.