Symmetric neural networks

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1 General case for y = Ax

$$\boxed{\text{original}} \quad y_j = \sum_i a_{ij} x_i \tag{1}$$

Equivariance implies:

where \square denotes "the rest of the elements".

This gives us a set of equations:

$$a_{kj}x_j + a_{jj}x_k = a_{jk}x_j + a_{kk}x_k \qquad \forall x_j, x_k \tag{3}$$

for $(j \ k) \in \mathfrak{S}_n$.

By setting x_j and x_k to zero, this yields:

$$a_{kj} = a_{jk} \qquad \forall j, k$$

$$a_{jj} = a_{kk} \qquad \forall j, k.$$

$$(4)$$

In other words, the matrix A is:

$$A = \alpha I + \beta 11^T \tag{5}$$

2 Case for $y_k = A_k x x$

The general form of a "quadratic" vector function is:

$$y = (Ax) \cdot x + Bx + C \tag{6}$$

We just focus on the quadratic term $(Ax) \cdot x$:

Equivariance implies: