"Mental space continuation" of reinforcement learning

In conventional RL, the **environment** is physically observable. I propose to extend it to the **internal** mental space.

From the traditional RL perspective: one reaches out for an apple, the apple is the **reward**, moving the arm is an **action**. These are all observable:



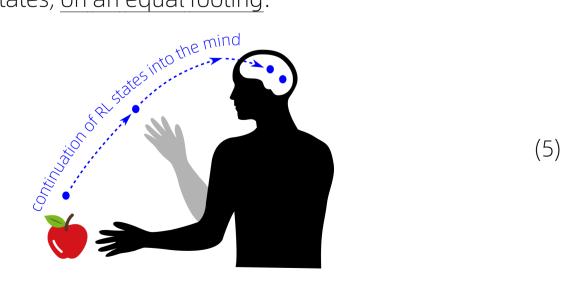
The foundation of RL is the **Bellman equation**. It can be viewed as a **recursive** formula:

Current state
$$V(x_0) = \max_a \{R + \gamma V(x_1)\}$$
 Next state (2)

In other words, the reward of getting an apple, back-propagates to the action of reaching out an arm for the apple. So far so good. And we continue this process back to the **chain of thoughts** that decided to reach for an apple:

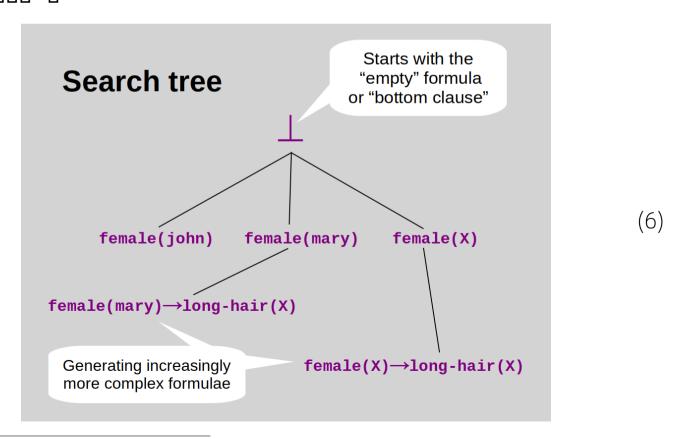
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In other words, we turn our **internal** mental states "inside-out", viewing them as **external** states, on an equal footing:



And this is <u>exactly analogous</u> to the propagation of rewards in a chess game. In other words, we can apply techniques of RL to learn the contents of mental space, thus providing a very rigorous foundation for AGI.

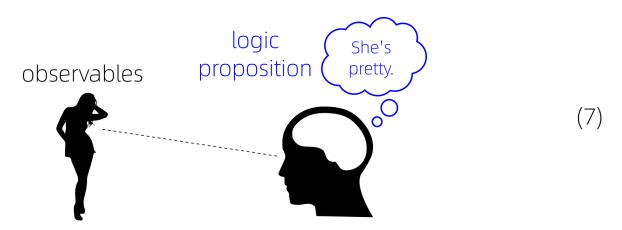
The above approach of unifying internal and external states is philosophically entirely sound, because our "brain states" are actually physical states; they are electrical activations of neuronal populations, and their transitions are governed by synaptic weights between neurons, which weights are updated through **Hebbian learning**, at least according to our current best understanding.

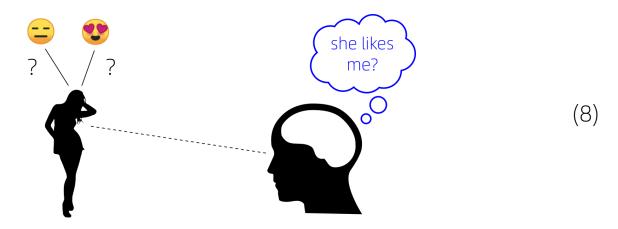


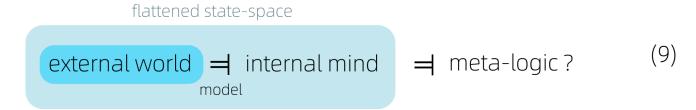
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In traditional RL, there are **model-based** methods, and in our brain we build **mental models** of the world. These are actually one and the same concept, there is no conflict between the two.







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Human figure from www.onlinewebfonts.com licensed by CC BY 3.0 Thought bubble created by Catherine Please from the Noun Project

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