# 神经网络中的「内省」 ("introspection" in neural networks)

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**Abstract.** 在本文中「内省」是指智能系统直接读/写知识的能力,此能力在经典 logic-based AI 是免费做到的,但神经网络内的「知识」素来有「黑盒」的问题。解决办法是让神经网络直接作用在它自身的 weights 上。

#### 0 Introduction

这篇文章说的「内省」的意思是指智能系统有能力读/写它内部的知识。例如说,一个比较蠢的智能系统可以用 sequence-to-sequence 的方式将中文翻译成英文:

"中文句子" 
$$\xrightarrow{F}$$
 "英文句子" (1)

F 代表系统的函数。但系统并不真的明白句子的意义,句子只是「水过鸭背」地流过系统。一个更聪明的系统是:句子可以进入到 F 里。我所说的「内省」就是这意思。

「内省」亦有 meta-reasoning 的意思,亦即除了**外在**的知识,系统还拥有关於系统**自身状态**的知识。但本文中「内省」是指存取「普通知识」的能力。

### 1 Applications

Introspection (in the present paper's sense) is useful in:

- learning by instructions, or "learn by being told"
  (a technique crucial to accelerating the learning of human knowledge)
- belief revision / truth maintenance (the most challenging and highest-level task in logic-based AI)

举例来说,小孩子的行为是由他内部的知识决定的,「知识决定行为」。

• 当小孩子看到一个成人做的动作,他会模仿那动作。



• 或者小孩子听到一句说话:「不要吃污糟食物」,他明白了那句说话的意思而改变行为。

这两个例子都涉及到将「感觉资料」放进 F 里面:

$$sensory data \hookrightarrow \mathbf{F}$$
 (3)

#### 2 Cartesian closure

Introspection requires the functional closure  $\mathbb{X} \simeq \mathbb{X}^{\mathbb{X}}$  which yields a **Cartesian-closed category** (CCC).

$$\boldsymbol{x}_{n+1} = \boldsymbol{F}(\boldsymbol{x}_n) \tag{4}$$

where

$$F = \mathbf{KB} = \mathbf{X} \mathbf{X}$$
  
 $\mathbf{x} = \text{state}$ 

An individual logic rule is a <u>restriction</u> of F to a specific input; Perhaps I could call such elements "micro-functions".

 $F \equiv \mathbb{R}$  is the "union" of micro-functions:

$$\mathbf{KB} = \bigcup \mathbf{f}_i \tag{5}$$

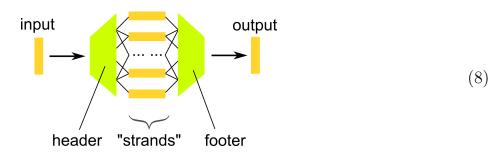
Or, in a vague sense, F is the sum total of objects like x:

$$F = \bigcup x_i \tag{6}$$

但 F 是一个神经网络,它的一般形式是:

$$\boxed{\text{output}} \quad \boldsymbol{x}_{n+1} = \boldsymbol{F}(\boldsymbol{x}_n) = \bigcirc W \quad \bigcirc W \quad \square \quad W \quad \boldsymbol{x}_n$$
 (7)

L = total number of layers. 由於各层的非线性「纠缠在一起」,表面上无法将神经网络「分解」。直到笔者受了 David Ha *et al* 提出的 PathNet [1] 理论所启发,PathNet 是由一些较小的神经网络 modules 组成,所以或许可以建构如下形式的「丝状神经网络」:



这些「丝条 」可以是简单的神经网络,例如每个的宽度或深度很小,因而可以用较短的 weights vector 描述。正是因为这原因,一个 — 本身可以作为神经网络的输入。但整个神经网络 F 无法输入自己,因为根据 Cantor's theorem, $\mathbb{X} = \mathbb{X}^{\mathbb{X}}$  是不可能的。

Let  $\overline{F} = \underline{\hspace{1cm}}$  header,  $\underline{F} = \underline{\hspace{1cm}}$  footer,  $f_i = \underline{\hspace{1cm}}$  strands, then:

$$\boldsymbol{F} = \overline{\boldsymbol{F}} \circ \bigcup \boldsymbol{f}_i \circ \underline{\boldsymbol{F}} \tag{9}$$

每个 \_\_\_ 大约对应於逻辑上的一个命题 (proposition, 可以是条件命题或普通命题)。

#### 3 Overall architecture

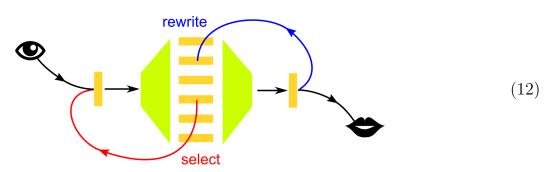
For reference, the architecture for **visual recognition** is:

Our basic AGI architecture is:

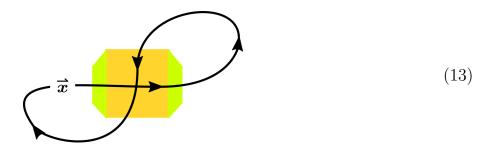
$$\begin{array}{cccc}
RNN \\
 & \times \\$$

 $\gg = [deep]$  neural network, trained via **reinforcement learning** 

The overall **recurrent** setup operates like this:



Viewing the "information flow" in a simplified way, we notice a "second" pass through the network's internal weights:



This mode of operation has always been standard in logic-based systems. The is the Landard pass represents reading/writing information to/from Landard pass represents using the landard in logical inference (thinking), ie:

$$x_n \cup \mathbb{R} \vdash x_{n+1}$$
 (14)

#### 4 Structure of memories

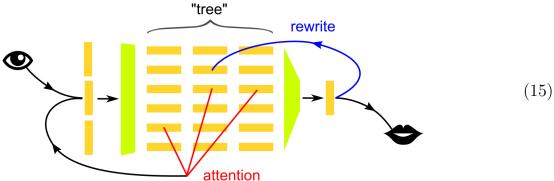
The "main memory" F can take the form of a tree  $(\bigwedge)$ , graph  $(\bigwedge)$ , or hyper-graph  $(\bigwedge)$ , with increasing complexity.

The **mental state** x, or "working memory", can also assume the above-mentioned forms.

Currently I am not sure whether to place **episodic memory** inside F or as a separate module outside F.

We need to organize the ---'s in the form of  $\bigwedge$ ,  $\swarrow$  or  $\swarrow$ , in such a way that the resulting structure is also a neural network, or more generally a mathematical **function** in Hilbert space.

But there is one simple way: Basically, a deep network is automatically "tree-like" because of its many layers (**levels**) of weights organized hierarchically. Thus we can build a network like this:



The attention mechanism selects a number of  $\blacksquare$ 's to be the **current state** or "working memory". Notice that the input size is bigger than the output size, which reflects the structure of the logical **consequece operator**  $\vdash$ .

## Acknowledgements

Thanks to David Ha for his PathNet idea.

## **Bibliography**

[1] Chrisantha Fernando, Dylan Banarse, Charles Blundell, Yori Zwols, David Ha, Andrei A. Rusu, Alexander Pritzel, and Daan Wierstra. Pathnet: Evolution channels gradient descent in super neural networks. CoRR, abs/1701.08734, 2017. URL http://arxiv.org/abs/1701.08734.