# **Modern Control Systems**

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Lecture 11: Linear Operators

## Hilbert Spaces

Operator Theory

An operator is simply any map between normed spaces.  $P: X \to Y$ 

• This includes the implicit assumption that ||Px|| is bounded.

### Definition 1.

An operator P is uniformly bounded if there exists some K such that

$$||Px|| \le K||x||$$

A **Linear Operator** is uniformly bounded if and only if it is bounded.

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# Operator Theory

**Linear Operators** 

### Definition 2.

Let X,Y be Banach spaces. The operator  $P:X\to Y$  is a bounded linear operator if

1. It is linear. i.e.

$$F(\alpha x + \beta z) = \alpha F(x) + \beta F(z)$$

for all  $x, z \in X$  and  $\alpha, \beta \in \mathbb{R}$ .

2. It is uniformly bounded. i.e. there exists a K such that

$$||Px||_Y \le K||x||_X$$

for all  $x \in X$ 

# Operator Theory

**Linear Operators** 

### Definition 3.

The normed space of bounded linear operators from X to Y is **denoted**  $\mathcal{L}(X,Y)$  with norm

$$||P||_{\mathcal{L}(X,Y)} := \sup_{\substack{x \in X \\ x \neq 0}} \frac{||Px||_Y}{||x||_X} = K$$

- The norm is the bound (an induced norm)
- Notation:  $\mathcal{L}(X) := \mathcal{L}(X, X)$
- If X is a Banach space, then  $\mathcal{L}(X,Y)$  is a Banach space

### **Properties:**Suppose $G_1 \in \mathcal{L}(X,Y)$ and $G_1 \in \mathcal{L}(Y,Z)$

Define

$$G_{12}(x) = G_2(G_1(x))$$

- Then  $G_{12} \in \mathcal{L}(X,Z)$ .
- $||G_{12}||_{\mathcal{L}(X,Z)} \le ||G_2||_{\mathcal{L}(Y,Z)} ||G_1||_{\mathcal{L}(X,Y)}$ .
- Not Cauchy Schwartz
- Composition forms an algebra.

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# **Linear Operators**

Linear Systems

Any linear system defines an operator

$$y = Gu$$

#### Add Feedback:

- y = G(u Ky)
- $Y = (I + GK)^{-1}Gu$

#### Question:

- Is  $(I + GK)^{-1}G$  a bounded linear operator?
- If so, the feedback is stable

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# **Linear Operators**

Example

The space  $\mathcal{L}(\mathbb{R}^n,\mathbb{R}^m)$  using the  $\|\cdot\|_2$  on  $\mathbb{R}^n$  and  $\mathbb{R}^m$ .

- $\mathcal{L}(\mathbb{R}^n, \mathbb{R}^m) = \mathbb{R}^{m \times n}$
- For  $A \in \mathbb{R}^{m \times n}$ ,

$$||A|| = \sup_{x \neq 0} \frac{||Ax||}{||x||} = \bar{\sigma}(A)$$

## **Linear Operators**

#### Example

Like matrices, the set of convolution operators is equivalent to the subspace of causal linear time-invariant operators  $\mathcal{L}(L_2)$ .

### Definition 4.

For a given f, define y = Fu by

$$y(t) = (Fu)(t) := \int_0^t f(t-s)u(s)ds$$

- Clearly, F is linear
- If  $f \in L_1$ , then  $F \in \mathcal{L}(L_n)$  for any p > 0.
- Young's Inequality:  $||y||_{L_r} \leq ||f||_{L_p} ||u||_{L_q}$  for any p,q,r with

$$\frac{1}{p} + \frac{1}{q} = \frac{1}{r} + 1$$

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$$(Fu)(t) := \int_0^t f(t-s)u(s)ds$$

Lets consider the case where  $f \in L_1$ .

#### Theorem 5.

Suppose  $f \in L_1$ , then  $F: L_{\infty}[0,\infty) \to L_{\infty}[0,\infty)$  with

$$||F||_{\mathcal{L}(L_{\infty})} = ||f||_{L_1}$$

### Proof.

To show that  $\|F\|_{\mathcal{L}(L_{\infty})} = \|f\|_{L_1}$ ,

- we will show  $\|F\|_{\mathcal{L}(L_{\infty})} \leq \|f\|_{L_1}$
- We will show  $||F||_{\mathcal{L}(L_{\infty})} \ge ||f||_{L_1}$

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### Proof.

To show that  $||F||_{\mathcal{L}(L_{\infty})} \leq ||f||_{L_1}$ , let y = Fu. then

$$|y(t)| = |(Fu)(t)| = \left| \int_0^t f(t-s)u(s)ds \right|$$

$$\leq \int_0^t |f(t-s)u(s)| ds$$

$$\leq \int_0^t |f(t-s)| |u(s)| ds$$

$$\leq \int_0^t |f(t-s)| ||u||_{L_{\infty}} ds$$

$$= ||u||_{L_{\infty}} \int_0^t |f(t-s)| ds$$

$$\leq ||u||_{L_{\infty}} ||f||_{L_1} ds$$

Thus  $F \in \mathcal{L}(L_{\infty})$  with  $||F||_{\mathcal{L}(L_{\infty})} \leq ||f||_{L_{1}}$ 

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### Proof.

To show  $\|F\|_{\mathcal{L}(L_{\infty})} = \|f\|_{L_1}$ , we need only show that  $\|F\|_{\mathcal{L}(L_{\infty})} \geq \|f\|_{L_1}$ .

- To show that  $\|F\|_{\mathcal{L}(L_\infty)} \ge \|f\|_{L_1}$ , we will show that for any  $\epsilon > 0$ ,  $\|F\|_{\mathcal{L}(L_\infty)} \ge \|f\|_{L_1} \epsilon$ . We proceed by construction.
- Since  $f \in L_1$ ,

$$||f||_{L_1} = \lim_{T \to \infty} \int_0^T |f(s)| \, ds$$

• Therefore, for any  $\epsilon > 0$ , there exists a  $T_{\epsilon} > 0$  such that

$$||f||_{L_1} - \int_0^{T_\epsilon} |f(s)| \, ds < \epsilon$$

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### Proof.

• Let  $u(t) = \frac{f(T_{\epsilon}-t)}{|f(T_{\epsilon}-t)|}$ . Then  $||u||_{L_{\infty}} = 1$  and

$$Fu(T_{\epsilon}) = \int_{0}^{T_{\epsilon}} f(T_{\epsilon} - s)u(s)ds$$
$$= \int_{0}^{T_{\epsilon}} \frac{f(T_{\epsilon} - s)^{2}}{|f(T_{\epsilon} - s)|} ds$$
$$= \int_{0}^{T_{\epsilon}} |f(T_{\epsilon} - s)| ds$$
$$> ||f||_{L_{\epsilon}} - \epsilon$$

- Thus  $||Fu||_{\infty} \geq ||f||_{L_1} \epsilon$
- Thus  $||F||_{\infty} = \sup_{\|u\|_{L_{\infty}}=1} ||Fu|| \ge ||f||_{L_{1}} \epsilon$
- Thus  $||F||_{\infty} \ge ||f||_{L_1}$  (Implicit Contradiction)

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## Convolution Operators

To conclude, if  $f \in L_1$ , then the convolution operator maps  $L_\infty \to L_\infty$ . Recall the input-output map for a linear system is

$$y(t) = \int_0^t Ce^{A(t-s)}Bu(s)ds + Du(t)$$

#### Conclusion:

• If  $Ce^{At}B \in L_1$ , then G is stable on  $L_{\infty}$ 

In fact, we usually don't work with systems  $G:L_\infty\to L_\infty$  Question: When is  $G\in\mathcal{L}(L_p)$ 

- Young's inequality:
  - ▶ When

$$\frac{1}{t} + \frac{1}{p} = \frac{1}{p} + 1$$

- Thus we need  $f \in L_1$  for any p.
- A Sufficient Condition

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