

# Spacecraft and Aircraft Dynamics

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Lecture 2: Invariants

# Conclusion

In this Lecture, you learned:

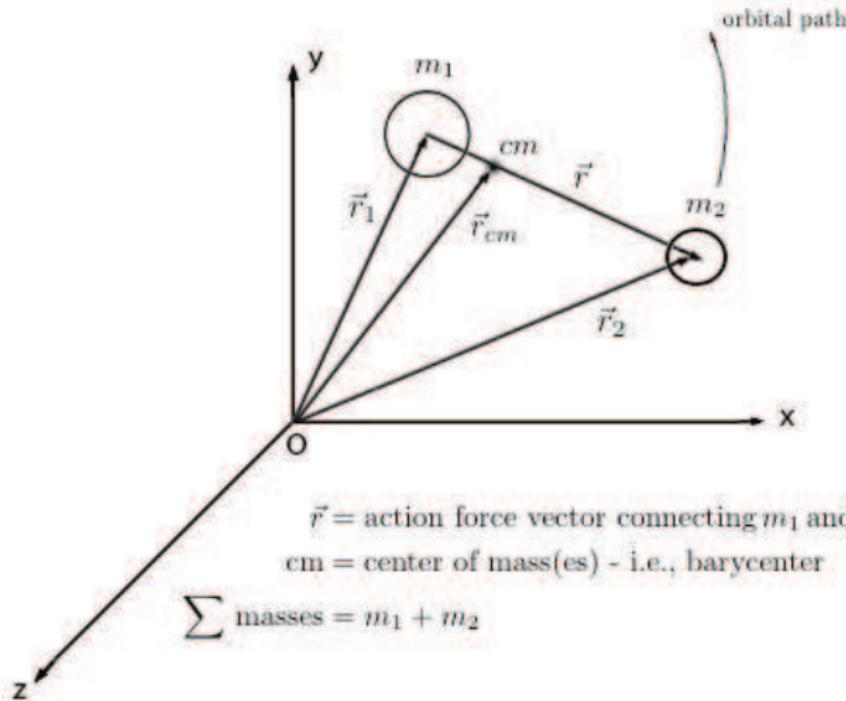
## N-body Problem

- Introduction
- Invariants
  - ▶ Linear Momentum
  - ▶ Angular Momentum
  - ▶ Energy

## Two-Body Problem

- How to calculate velocity given position
- How to calculate escape velocity

# Universal Gravitation



$\vec{r}$  = action force vector connecting  $m_1$  and  $m_2$  centers

$cm$  = center of mass(es) - i.e., barycenter

$$\sum \text{masses} = m_1 + m_2$$

$$\vec{F}_1 = G \frac{m_1 m_2}{\|\vec{r}_{12}\|^3} \vec{r}_{12}$$

# Relative motion

Recall the force on mass 1 due to mass 2 is

$$m_1 \ddot{\vec{r}}_1 = \vec{F}_1 = G \frac{m_1 m_2}{\|\vec{r}_{12}\|^3} \vec{r}_{12}$$

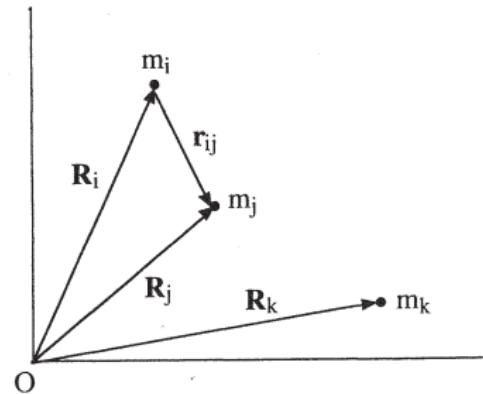
where we denote  $\vec{r}_{12} = \vec{r}_2 - \vec{r}_1$ . Clearly  $\vec{r}_{12} = \vec{r}_{21}$ . The motion of mass 2 due to mass 1 is

$$m_2 \ddot{\vec{r}}_2 = \vec{F}_2 = G \frac{m_2 m_1}{\|\vec{r}_{21}\|^3} \vec{r}_{21}$$

The problem is nonlinear coupled ODE with 6 degrees of freedom.

**Solution:** Consider relative motion (only  $\vec{r}_{12}$ )

$$\ddot{\vec{r}}_{12} = -\frac{G(m_1 + m_2)}{\|\vec{r}_{12}\|^3} \vec{r}_{12}$$



# The N-body problem

In some situations, there are more than two bodies.

- The solar system
- The Earth-Moon system

In this case, the force on mass  $i$  due to all other masses is

$$m_i \ddot{\vec{R}}_i = \vec{F}_i = G \sum_{\substack{j=1 \\ i \neq j}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \vec{r}_{ij}$$

## Definition 1.

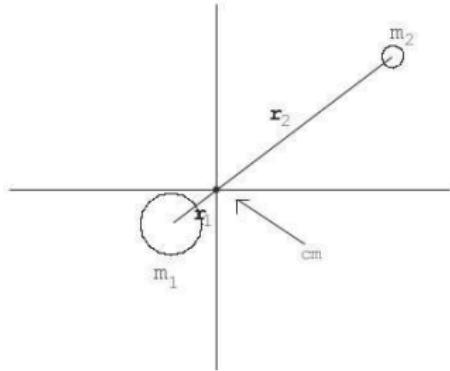
The center of mass of a collection of point masses  $m_i$  is

$$\vec{R}_{CM} = \frac{1}{\sum_i m_i} \sum_{i=1}^N m_i \vec{R}_i$$

# The N-body problem

The key thing to note is that since  $\vec{r}_{ij} = -\vec{r}_{ji}$ ,

$$\begin{aligned}\ddot{\vec{R}}_{CM} &= \frac{1}{\sum_i m_i} \sum_{i=1}^N m_i \ddot{\vec{R}}_i \\ &= \frac{G}{\sum_i m_i} \sum_{i=1}^N \sum_{\substack{j=1 \\ i \neq j}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \vec{r}_{ij} = 0\end{aligned}$$



Therefore, The center of mass is *not accelerating*.

$\vec{R}_{CM} = 0$  makes an excellent choice for the origin of a **coordinate system**.

**First Invariant Quantity:** Linear Momentum

$$\sum_i m_i R_i = C_1 t + C_2$$

Thus the motion of the center of mass doesn't change with time.  
We will return to this concept when we return to the 2-body problem.

# Invariants in the N-body problem

We now define the two key invariant quantities which will define the motion.

- Energy
- Angular Momentum

These hold for both the 2 and N body problems. Begin with the Angular momentum.

## Definition 2.

The angular momentum of a collection of particles is

$$\vec{H}(t) = \sum_{i=1}^N m_i \vec{R}_i(t) \times \dot{\vec{R}}_i(t)$$

We will show next that

$$\begin{aligned}\frac{d}{dt} \vec{H}(t) &= \sum_{i=1}^N m_i \left( \dot{\vec{R}}_i(t) \times \dot{\vec{R}}_i(t) + \vec{R}_i(t) \times \ddot{\vec{R}}_i(t) \right) \\ &= \sum_{i=1}^N m_i \vec{R}_i(t) \times \ddot{\vec{R}}_i(t) = 0\end{aligned}$$

# Conservation of Angular Momentum under Gravity

Begin with the relation

$$m_i \ddot{\vec{R}}_i = \vec{F}_i = G \sum_{\substack{j=1 \\ i \neq j}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \vec{r}_{ij}.$$

Then

$$\sum_{i=1}^N m_i (\vec{R}_i \times \ddot{\vec{R}}_i) = G \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \vec{R}_i \times \vec{r}_{ij}.$$

However, we can use the identities

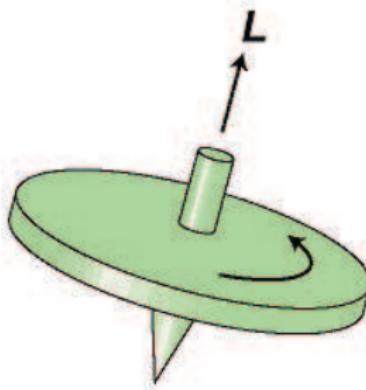
$$\vec{R}_i \times \vec{r}_{ij} = \vec{R}_i \times (\vec{R}_j - \vec{R}_i) = \vec{R}_i \times \vec{R}_j$$

$$\vec{R}_j \times \vec{r}_{ji} = \vec{R}_j \times (\vec{R}_i - \vec{R}_j) = -\vec{R}_i \times \vec{R}_j$$

Thus

$$\sum_{i=1}^N \vec{R}_i \times \ddot{\vec{R}}_i = G \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \vec{R}_i \times \vec{R}_j = 0.$$

# Conservation of Angular Momentum under Gravity



Thus we conclude that

$$\dot{\vec{H}} = 0$$

from whence we have that

$$\vec{H} = \sum_{i=1}^N m_i \vec{R}_i \times \dot{\vec{R}}_i = C_3$$

The concept of an invariant plane defined as normal to the vector  $\vec{H}$ .

# Illustration of Conservation of Angular Momentum under Gravity

Milky Way + Andromeda

# Conservation of Energy

## Definition 3.

The Kinetic Energy of a particle is

$$T_i = \frac{1}{2}m_i \dot{\vec{R}}_i^T \dot{\vec{R}}_i$$

Thus the total kinetic energy for a system of particles is

$$T = \sum_{i=1}^N \frac{1}{2}m_i \dot{\vec{R}}_i^T \dot{\vec{R}}_i$$

## Definition 4.

The Gravitational Potential Energy of a collection of particles is

$$V = -\frac{G}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|}$$

# Conservation of Energy

We show that the fourth invariant is

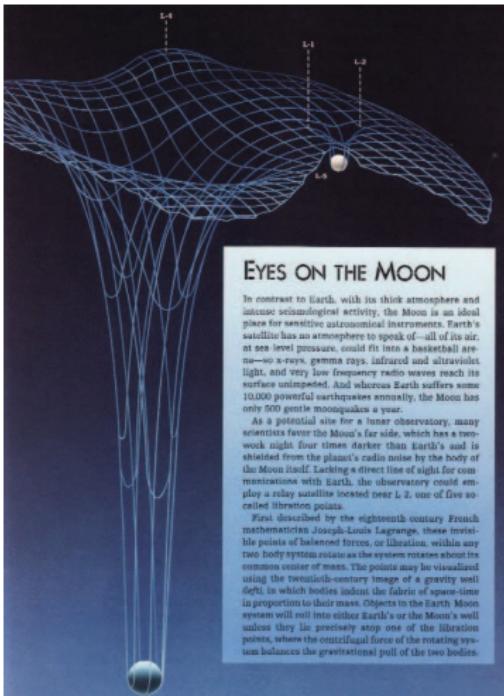
$$E = T + V = C_4$$

by showing  $\dot{T} + \dot{V} = 0$ .

$$\begin{aligned}\dot{T} &= \sum_{i=1}^N m_i \dot{\vec{R}}_i^T \ddot{\vec{R}}_i \\ &= G \sum_{i=1}^N \sum_{\substack{j=1 \\ i \neq j}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \dot{\vec{R}}_i^T \vec{r}_{ij}\end{aligned}$$

Which is complicated.

However, now look at  $\dot{V}$



# Conservation of Energy

Recall  $\dot{T} = G \sum_{i=1}^N \sum_{\substack{j=1 \\ i \neq j}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \dot{\vec{R}}_i^T \vec{r}_{ij}$  Now,

$$\begin{aligned}\dot{V} &= -\frac{d}{dt} \frac{G}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|} = -\frac{G}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{d}{dt} (\vec{r}_{ij}^T \vec{r}_{ij})^{-0.5} \\ &= \frac{G}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j (\vec{r}_{ij}^T \vec{r}_{ij})^{-1.5} \dot{\vec{r}}_{ij}^T \vec{r}_{ij} \\ &= \frac{G}{2} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} (\dot{\vec{R}}_j - \dot{\vec{R}}_i)^T \vec{r}_{ij} = -G \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{m_i m_j}{\|\vec{r}_{ij}\|^3} \dot{\vec{R}}_i^T \vec{r}_{ij}\end{aligned}$$

Which cancels  $\dot{T}$ . Therefore

$$\dot{E} = \dot{T} + \dot{V} = 0$$

and hence gravity is a conservative field with  $T(t) + V(t) = C_4$ .

# Potential Energy

We can see velocity increases as we descend into the well

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## Back to the Two-Body problem

Going back to the two-body problem.... Recall our equation of motion

$$\ddot{\vec{r}}_{12} = -\frac{G(m_1 + m_2)}{\|\vec{r}_{12}\|^3} \vec{r}_{12}$$

but this considers only relative motion. How to recover absolute position? Use a coordinate system centered at the center of mass so that

$$\vec{R}_{CM} = \frac{\vec{R}_1 m_1 + \vec{R}_2 m_2}{m_1 + m_2} = 0$$

Then we can recover from  $\vec{r}_{12}$

$$\vec{R}_1 = \frac{m_2}{m_1 + m_2} \vec{r}_{12}$$

and

$$\vec{R}_2 = \frac{m_1}{m_1 + m_2} \vec{r}_{12}$$

If  $m_1$  is a satellite and  $m_2$  is a planet, then  $\frac{m_1}{m_1+m_2} \cong 0$  and  $\frac{m_1}{m_1+m_2} \cong 1$  and so

$$\vec{R}_2 \cong 0 \quad \text{and} \quad \vec{R}_1 \cong \vec{r}_{12}.$$

# The Orbital Parameter, $\mu$

While we are considering **orbits**, we can make some simplifications. Our first simplification is to write

$$\mu = G(m_1 + m_2).$$

If  $m_2 \gg m_1$ , then

$$\mu \cong Gm_2$$

- Each central body has its own  $\mu$
- The size of the orbit varies with  $\mu$
- Needed to convert orbital elements to  $\vec{r}$  and  $\vec{v}$ .
- Values are tabulated

## The Sun

$$\text{Mass} = 1.989 \cdot 10^{30} \text{ kg}$$

$$\text{Radius} = 6.9599 \cdot 10^5 \text{ km}$$

$$\mu_{\text{sun}} = Gm_{\text{sun}} = 1.327 \cdot 10^{11} \text{ km}^3/\text{s}^2$$

## The Earth

$$\text{Mass} = 5.974 \cdot 10^{24} \text{ kg}$$

$$\text{Radius} = 6.37812 \cdot 10^3 \text{ km}$$

$$\mu_{\text{earth}} = Gm_{\text{earth}} = 3.986 \cdot 10^5 \text{ km}^3/\text{s}^2$$

$$\text{Mean distance from sun} = 1 \text{ au} = 1.495978 \cdot 10^8 \text{ km}$$

## The Moon

$$\text{Mass} = 7.3483 \cdot 10^{22} \text{ kg}$$

$$\text{Radius} = 1.738 \cdot 10^3 \text{ km}$$

$$\mu_{\text{moon}} = Gm_{\text{moon}} = 4.903 \cdot 10^3 \text{ km}^3/\text{s}^2$$

$$\text{Mean distance from earth} = 3.844 \cdot 10^5 \text{ km}$$

$$\text{Orbit eccentricity} = 0.0549$$

$$\text{Orbit inclination (to ecliptic)} = 5^\circ 09'$$

# A note on the Gravitational Constant, $G$

The calculation of  $G$  is non-trivial

- Given  $G$ , it is easy to calculate the mass of any planet.
- The search for  $G$  was another major scientific quest.

In principle, it is easy to calculate:

- take two objects of known mass ( $m_1, m_2$ ) and measure the attraction,  $F$ .  
Then

$$G = \frac{Fr^2}{m_1 m_2}$$

Unfortunately, the force is infinitesimal for all but planet-size objects. So how to calculate  $G$ ?

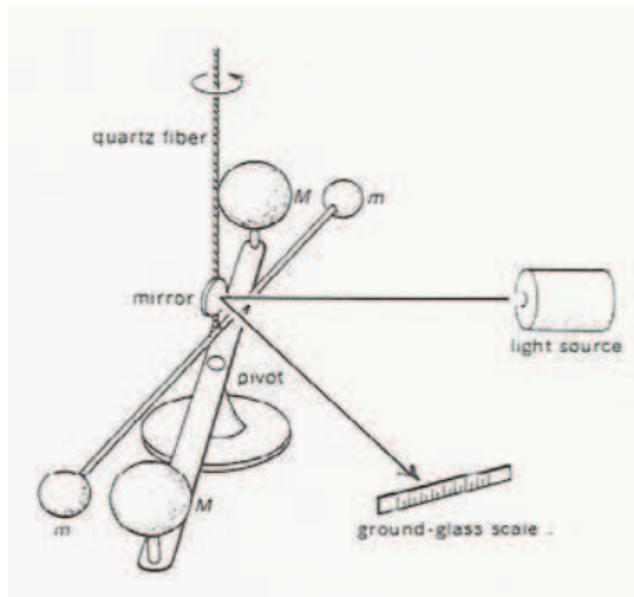
# The Cavendish Balance

The first accurate measurement of  $G$  was made by Cavendish in 1798.

1. Suspend two small spheres, separated by length,  $l$ , by a quartz filament.
2. Move two large spherical masses within known (small) distance of test masses.
3. Gravity will produce a moment on the quartz fiber, causing a deflection.
4. Deflection is measured by movement of a mirror on glass filament.
5. Rotation of mirror causes movement of reflected light.

Measurement revealed

$$G = 6.67428 \pm .00067 * 10^{-11} m^3 kg^{-1} s^{-2}$$



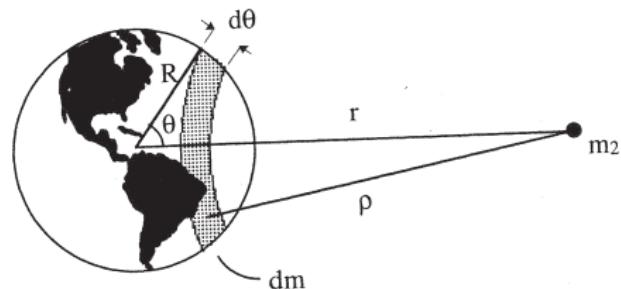
# A Problem with the Model?

## Non-point masses

- Our equation of motion assumes that the masses are concentrated at a point.
- Most masses are actually quite large (planet-sized)

**Question:** Is this a problem?

**Answer:** Not if there is symmetry about the line  $\vec{r}_{12}$ .



The *sphere* is symmetric about any line passing through the center.

- Most planets are spheres.
- Exception is the orbit perturbation effect due earth oblateness.
- See book for proof that the effect reduces to a point mass.

# Energy in Orbits

Now lets return to the question of potential fields and energy For an orbit, we will hence only consider motion of the satellite, which we denote

$$\vec{r}(t) = \vec{R}_1(t) \cong \vec{r}_{12}(t)$$

and  $m = m_1$ .  $\dot{r} = v$ . We will ignore motion of the larger body.

$$T = \frac{1}{2} \|\vec{v}\|^2$$

and

$$V = -\frac{\mu}{\|\vec{r}\|}$$

and  $T+V$  is conserved. This can already be used to solve problems

## Example: Velocity

**Question:** Suppose a satellite of earth is initially tracked at radius of  $r_1 = 20,000\text{km}$  at a velocity of  $1000\text{m/s}$ . The satellite is later spotted at a radius of  $10,000\text{km}$ . Determine the velocity of the satellite.

**Solution:** Find the Energy at the initial time and use it to find the kinetic energy at the final time.

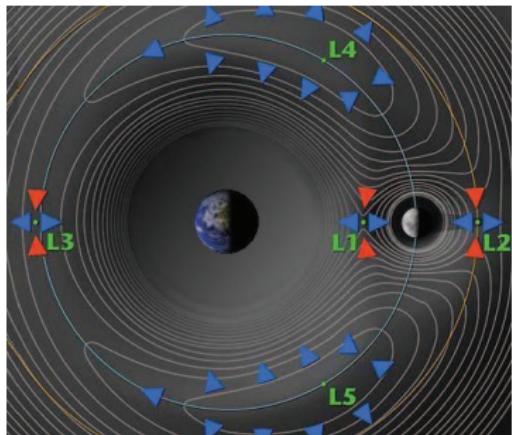
$$\begin{aligned}E &= T_1 + V_1 = \frac{1}{2}\|\vec{v}_1\|^2 - \frac{\mu}{\|\vec{r}_1\|} \\&= .5 - \frac{398601}{20,000} = -19.43\end{aligned}$$

$$V_2 = -\frac{\mu}{\|\vec{r}_2\|} = -\frac{398601}{10,000} = -39.86.$$

So  $T_1 + V_1 = T_2 + V_2$  implies

$$T_2 = E - V_2 = -19.43 + 39.86 = 20.43$$

$$\|\vec{v}_2\| = \sqrt{2T_2} = \sqrt{40.86} = 6.392\text{km/s}$$



## Example: Escape Velocity

Escape velocity is the kinetic energy needed to leave the sphere of influence of a planet. To achieve escape, net energy,  $E$  must be positive, so that as  $r \rightarrow \infty$ , we still have forward motion.

At  $r \rightarrow \infty$ ,  $V_\infty = \lim_{r \rightarrow \infty} \frac{\mu}{\|\vec{r}\|} = 0$ , so

$$E = T_\infty + V_\infty = T_\infty$$

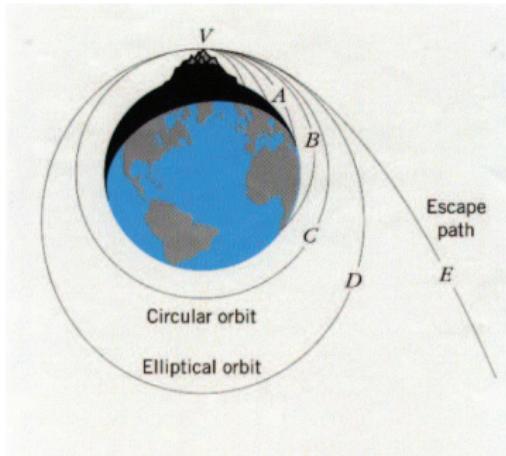
**Question:** Find the escape velocity at  $r = 20,000\text{km}$ .

**Solution:** As we know, at  $r = 20,000$ ,  $V = -19.93$ . So in order for  $E > 0$ , we need

$$E = T + V = T - 19.93 > 0$$

So we need  $T > 19.93$ . This yields a velocity of

$$\|v\| = \sqrt{2T} > 6.313$$



# Conclusion

In this Lecture, you learned:

## N-body Problem

- Introduction
- Invariants
  - ▶ Linear Momentum
  - ▶ Angular Momentum
  - ▶ Energy

## Two-Body Problem

- How to calculate velocity given position
- How to calculate escape velocity

# Next Lecture: The two-body problem continued

## Derivation of Kepler's First Law

- eccentricity vector
  - ▶ How to calculate
  - ▶ circular orbits
  - ▶ elliptic orbits
  - ▶ parabolic orbits
  - ▶ hyperbolic orbits
- Solution to the two-body problem