

Modern Control Systems

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Lecture 17: Operators on Signal Space

Signal Spaces

L_2 and \hat{L}_2 space

Now we are ready to define the Laplace transform.

Recall: $L_2(-\infty, \infty)$ is the space of functions with inner product given by

$$\langle u, y \rangle_{L_2} = \int_{-\infty}^{\infty} u(t)^* y(t) dt$$

Now, we propose a new signal space in the frequency domain: \hat{L}_2

Definition 1.

\hat{L}_2 is the inner-product space of functions $\hat{f} : \mathbb{R} \rightarrow \mathbb{C}^n$ with form $\hat{f}(j\omega)$ and inner product

$$\langle \hat{u}, \hat{y} \rangle_{\hat{L}_2} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{u}(j\omega)^* \hat{y}(j\omega) d\omega$$

\hat{L}_2 inherits the norm

$$\|\hat{u}\|_{\hat{L}_2}^2 = \frac{1}{2\pi} \int_{-\infty}^{\infty} \|\hat{u}(j\omega)\|^2 d\omega$$

Note: The use of “ $\hat{\cdot}$ ” notation will refer to frequency-domain spaces, signals and operators.

The Fourier Transform

Definition 2.

For any function $u : \mathbb{R} \rightarrow \mathbb{R}^n$, we define the **Fourier Transform** of u : ϕu by

$$\hat{u} = (\phi u)(\omega) = \int_{-\infty}^{\infty} u(t) e^{-i\omega t} dt$$

- Note that we neglected the signal space
- On L_2 , we have $\phi u(\omega) = \langle u, e^{-i\omega t} \rangle_{L_2}$

Theorem 3.

- If $u \in L_1$, the $(\phi u)(\omega)$ is well defined for all $\omega \in \mathbb{R}$
- If $u \in L_2$, then

$$\lim_{T \rightarrow \infty} \int_{-T}^T u(t) e^{-i\omega t} dt$$

exists for almost all ω .

- ▶ When limit does not exist, define $(\phi u)(\omega) = 0$

The “Inverse Fourier Transform”

Note: We have not shown that ϕ has an inverse (or any other properties).

Definition 4.

Given a function $\hat{u} : \mathbb{R} \rightarrow \mathbb{C}^n$, we propose the operator ϕ^{-1}

$$(\phi^{-1}\hat{u})(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{u}(i\omega) e^{i\omega t} d\omega$$

- In this case $(\phi^{-1}\hat{u})(t) = \langle \hat{u}, e^{i\omega t} \rangle_{\hat{L}_2}$
- If $\hat{u} \in \hat{L}_2(i\mathbb{R})$, then $(\phi^{-1}\hat{u})(t)$ exists for almost all t .

Invertible?

- If $(\phi u)(i\omega)$ exists for almost all ω , then

$$(\phi^{-1}\phi u)(t) = u(t)$$

for almost all t .

- If $(\phi^{-1}\hat{u})(t)$ exists for almost all t , then

$$(\phi\phi^{-1}\hat{u})(i\omega) = \hat{u}(i\omega)$$

for almost all ω .

The Plancherel Theorem

The Fourier Transform and its inverse are Unitary.

Theorem 5.

1. $\phi : L_2(-\infty, \infty) \rightarrow \hat{L}_2(i\mathbb{R})$ and

$$\langle u, v \rangle_{L_2} = \langle \phi u, \phi v \rangle_{\hat{L}_2} \quad \text{for all } u, v \in L_2.$$

2. $\phi^{-1} : \hat{L}_2(i\mathbb{R}) \rightarrow L_2(-\infty, \infty)$ and

$$\langle \hat{u}, \hat{v} \rangle_{\hat{L}_2} = \langle \phi^{-1} \hat{u}, \phi^{-1} \hat{v} \rangle_{L_2} \quad \text{for all } \hat{u}, \hat{v} \in \hat{L}_2.$$

Unitary because

$$\langle u, \phi^* \phi v \rangle = \langle \phi u, \phi v \rangle = \langle u, v \rangle$$

for all u, v , which implies $\phi^* \phi = I$.

- Show that $\phi^{-1} = \phi^*$ is the Inverse Fourier Transform

Now we know L_2 and \hat{L}_2 are isomorphic.

The Fourier System

Let $y = Gu$.

- Then $y = \phi^{-1}\phi G\phi^{-1}\phi u$
- OR $\hat{y} = (\phi G\phi^{-1})\hat{u}$
- We'll return to $\phi G\phi^{-1}$ shortly

Because L_2 and \hat{L}_2 are isomorphic, \hat{L}_2 are the coordinates of u in the Fourier basis.

- $\hat{L}_2(\omega)$ is the coordinate of basis $e^{-i\omega t}$.

The problem with operators on \hat{L}_2 is they are not always **Causal**.

Laplace Transform

Now consider the space $L_2[0, \infty)$.

Definition 6.

Given $u \in L_2[0, \infty)$, the Laplace Transform of u is $\hat{u} = \Lambda u$, where

$$\hat{u}(s) = (\Lambda u)(s) = \lim_{T \rightarrow \infty} \int_0^T u(t) e^{-st} dt$$

if this limit exists.

Note that for $u \in L_2[0, \infty)$, $\Lambda u = \phi u$.

- Laplace transform acts on a subspace of $L_2(-\infty, \infty)$
- Laplace and Fourier transforms coincide on the imaginary axis.
- Thus the image of the Laplace transform is “smaller” than the image of ϕ .
 - ▶ Speaking of which: What is the image?
 - ▶ Its a bit more complicated.....

Analytic Functions

Let $u \in L_2[0, \infty)$. Suppose $\operatorname{Re}(s) > 0$.

- Then $e^{-st} \in L_2$ - a basis function
- Then

$$\hat{u}(s) = (\Lambda u)(s) = \int_0^\infty e^{-st} u(t) dt = \langle e^{-st}, u \rangle_{L_2} < \infty$$

- $(\Lambda u)(s)$ is well-defined everywhere in the right-half-plane (RHP).

Definition 7.

In complex analysis, a function is **analytic** if it is continuous and bounded.

- More generally, a function is analytic if the Taylor series converges everywhere in the domain.
- image Λ is a subset of analytic functions bounded on the right-half-plane.
 - ▶ Note we didn't prove continuous.

Definition 8.

A function $\hat{u} : \bar{\mathbb{C}}^+ \rightarrow \mathbb{C}^n$ is in H_2 if

1. $\hat{u}(s)$ is analytic on the **Open RHP** (denoted \mathbb{C}^+)
2. For almost every real ω ,

$$\lim_{\sigma \rightarrow 0^+} \hat{u}(\sigma + i\omega) = \hat{u}(i\omega)$$

- ▶ Which means continuous on the imaginary axis

3.

$$\sup_{\sigma \geq 0} \int_{-\infty}^{\infty} \|\hat{u}(\sigma + i\omega)\|_2^2 < \infty$$

- ▶ Which means bounded on every vertical line.

Maximum Modulus Principle

Theorem 9 (Maximum Modulus).

An analytic function cannot obtain its extrema in the interior of the domain.

Hence if \hat{u} satisfies 1) and 2), then

$$\begin{aligned}\sup_{\sigma \geq 0} \int_{-\infty}^{\infty} \|\hat{u}(\sigma + i\omega)\|_2^2 d\omega &= \int_{-\infty}^{\infty} \|\hat{u}(i\omega)\|_2^2 d\omega \\ &= \|\hat{u}\|_{\hat{L}_2} = \|\phi u\|_{\hat{L}_2} \\ &= \|u\|_{L_2}\end{aligned}$$

Thus we equip H_2 with the \hat{L}_2 norm and inner product

$$\|\hat{u}\|_{H_2} = \int_{-\infty}^{\infty} \|\hat{u}(i\omega)\|_2^2 d\omega, \quad \langle \hat{u}, \hat{v} \rangle_{H_2} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{u}(i\omega)^* \hat{v}(i\omega) d\omega$$

- This is a valid inner product because H_2 is isomorphic to the image $\phi L_2[0, \infty)$, which is a subspace of \hat{L}_2 .
- Paley-Wiener