

# **Spacecraft and Aircraft Dynamics**

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Lecture 3: Airfoils, and Static Stability

# Aircraft Dynamics

## Lecture 3

In this lecture, we will discuss

Airfoils:

- Nomenclature
  - ▶ Chords, Camber, Aerodynamic Center, etc.
- Forces and Moments produced by lifting surfaces
  - ▶ Lift and Moment coefficients and how to interpret them.

Static Stability:

- Definition
- How to determine static longitudinal stability

# Next Subject: Lifting Surfaces

How do they work???

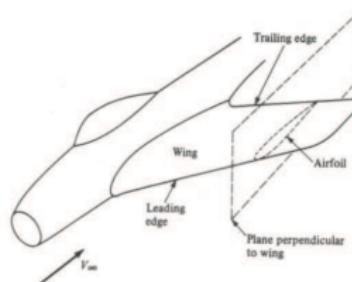


Figure: Airfoil as Cross-Section

Many of the Forces on an aircraft are produced by *Lifting Surfaces*.

- Major exception is propulsion.

Lifting surfaces are characterized by

**Planform Shape:** The shape of the wing when viewed from above.

- Surface area, tapering, etc.
- determines magnitude of forces.

**Airfoil:** The cross-section of the wing.

- Determines type of forces and moment.
  - ▶ Positivity, location, etc.

# Lifting Surfaces

## Planform Shapes

**Planform Shape:** The planform shape of the wing will affect

- Lift
- Drag
- Moment

**Surface Area:** As mentioned earlier, forces and moments are proportional to.

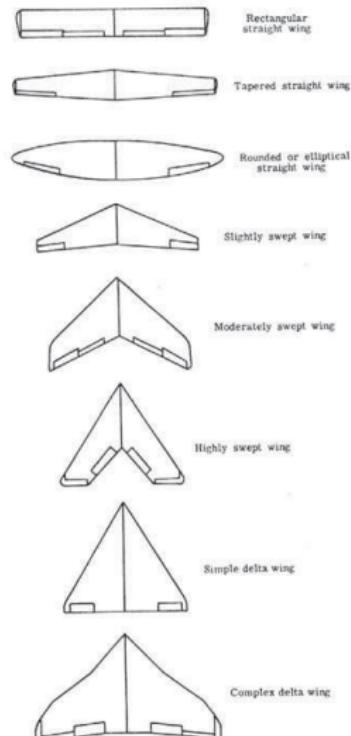
$$F \cong C_L Q S$$

and

$$M \cong C_M Q S l$$

Thus

- Larger wings produce more lift and drag
- Larger wings produce more Moment
- More on chord length,  $l$ , shortly

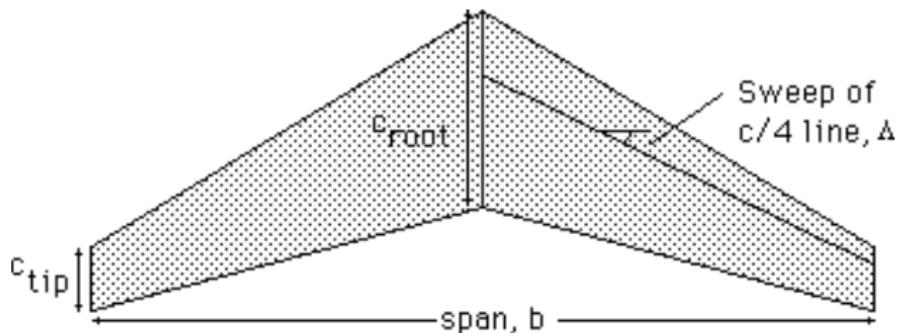


# Lifting Surfaces

## Planform Definitions

In this course, we will assume a rectangular wing planform.

Correction factors can be used for rounded or swept-wing configurations.



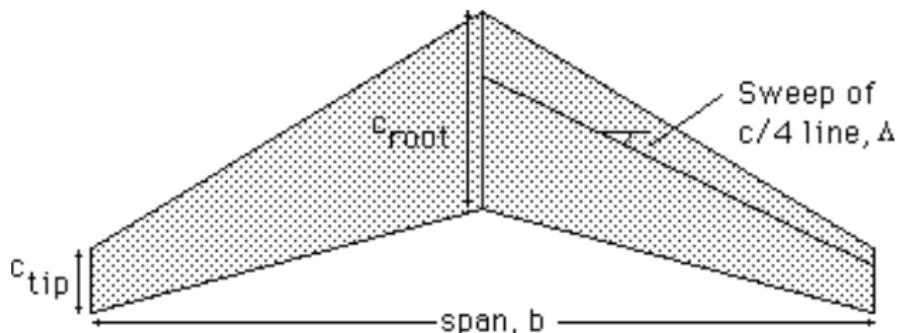
**Chord,  $c$ :** The width of the surface at some point. This determines the size of the airfoil.

**Root Chord,  $c_r$ :** The width of the surface where joined to the airplane.

**Tip Chord,  $c_t$ :** The width of the surface at free-stream.

# Lifting Surfaces

## Planform Definitions continued



**Span,  $b$ :** The total length of the surface.

**Quarter-Chord Line:** The line connecting the points of 1/4 chord along the span of the surface. The 1/4 chord point is approximately the aerodynamic center of an airfoil - to be discussed

**Sweep:** The angle the 1/4-chord line makes with the horizontal.

# Lifting Surfaces

## Examples

### Piper PA-31 Navajo USA

Type: light sports aircraft

Accommodation: two pilots, four passengers



#### Dimensions:

Length: 32 ft 7 in (9.9 m)

Wingspan: 40 ft 8 in (12.4 m)

Height: 13 ft (3.9 m)

#### Weights:

Empty: 3991 lb (1810 kg)

Max T/O: 6500 lb (2948 kg)

Payload: 350 lb (159 kg)

Thrust: 620 hp (231 kW)

#### Performance:

Max speed: 261 mph  
(420 kmh)

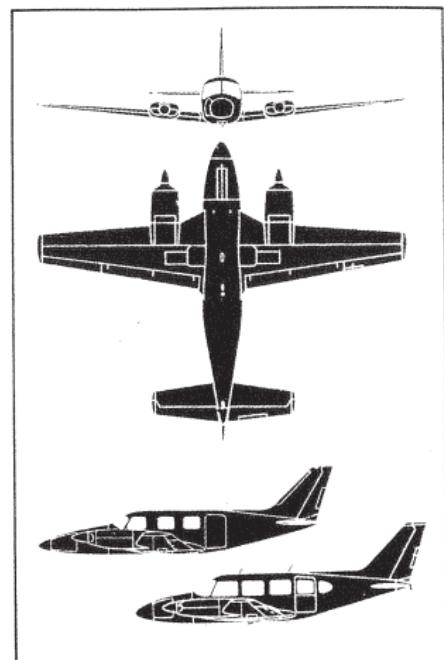
Range: 1065 nm (1973 km)

Power plant: two Lycoming  
TIO-540-A2C piston engines

#### Variants:

Navajo C/R; Pressurized  
Navajo; Navajo Chieftain  
stretched version

Notes: First flown in 1964, the Navajo has gone through a number of modifications, the Navajo Chieftain being the most recognizable.



# Lifting Surfaces

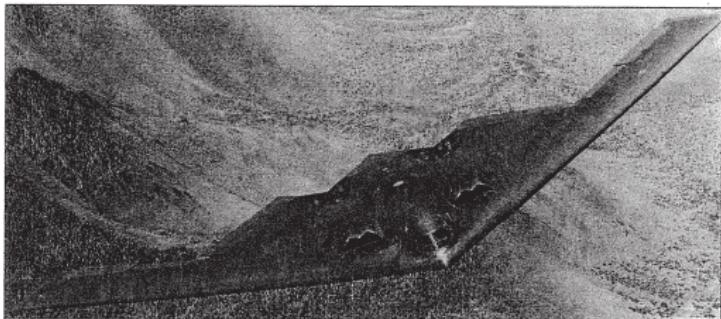
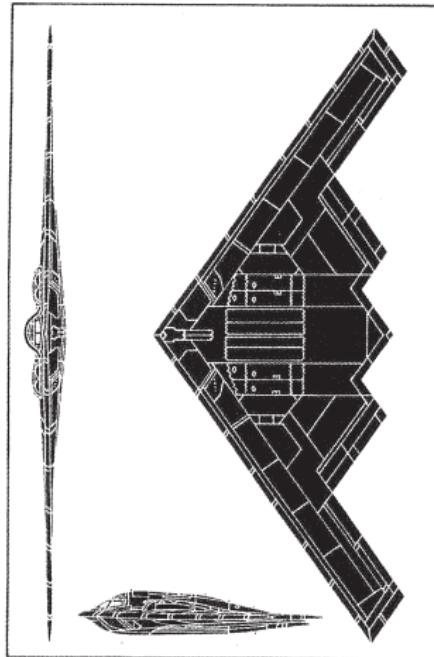
## Examples



### Northrop B-2 Spirit USA

Type: stealth bomber

Accommodation: one pilot one mission commander side-by-side



#### Dimensions:

Length: 69ft (21.03m)  
Wingspan: 172ft (52.43m)  
Height: 17ft (5.18m)

#### Weights:

Empty: 110 000lb (49 900kg)  
Max T/O: 376 000lb  
(170 550kg)

#### Performance:

Max Speed: n/a  
Range: 6600nm (12 223km),  
4500nm (8 334km) low level  
Powerplant: four General  
Electric F118-GE-110 turbofans  
Thrust: 76 000lb (169kN)

#### Armament:

internal bomb bay with rotary

launchers carrying 16 nuclear  
weapons or bomb racks  
carrying conventional  
weapons; 50 000lb (22 680kg)  
warload; AGM-131 SRAM II  
stand-off nuclear weapon,  
AGM-129 nuclear cruise  
missile; B61, B83 free fall  
nuclear weapons; conventional  
bombs and mines

**Notes:** The most expensive aircraft ever running at \$865 million per aircraft. The USAF originally wanted 133 B-2s, but only 20 had been funded by 1995. There is provision for a third crew member behind the commander.

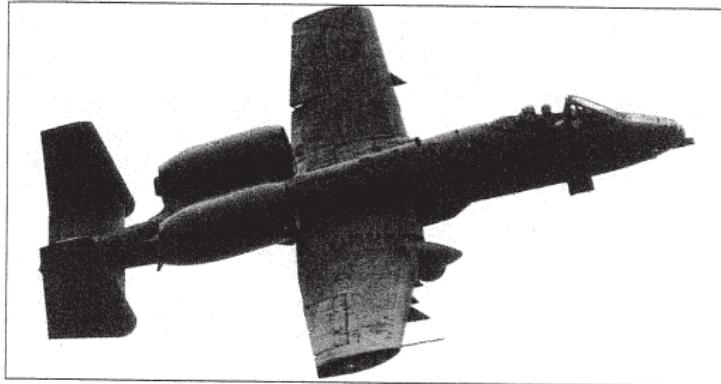
# Lifting Surfaces

## Examples

### Fairchild A-10A Thunderbolt USA

Type: close support aircraft

Accommodation: one pilot



#### Dimensions:

Length: 53 ft 4 in (16.26 m)  
Wingspan: 57 ft 6 in (17.53 m)  
Height: 14 ft 8 in (4.47 m)

#### Weights:

Empty: 23 370 lb (10 710 kg)  
Max T/O: 47 400 lb (21 500 kg)

#### Performance:

Max Speed: 449 mph (722 kmh)  
Range: 1080 nm (2000 km)  
Powerplant: two General Electric TF34-GE-100 high bypass ratio turbofans  
Thrust: 18 130 lb (80.6 kN)

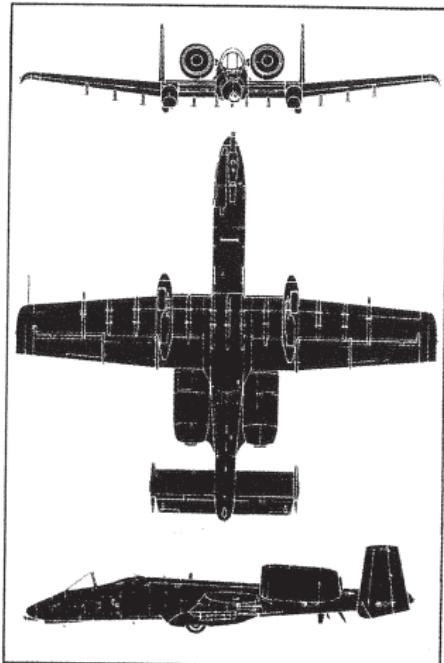
#### Armament:

one 30 mm GAU-8/A seven-barrelled cannon; 11 hardpoints; 16 000 lb (7257 kg) warload; AGM-65A Maverick; wide range of bombs

#### Variants:

OA-10A Fast FAC aircraft

**Notes:** The pilot is protected by a titanium 'bathtub' capable of withstanding 23 mm gun fire.



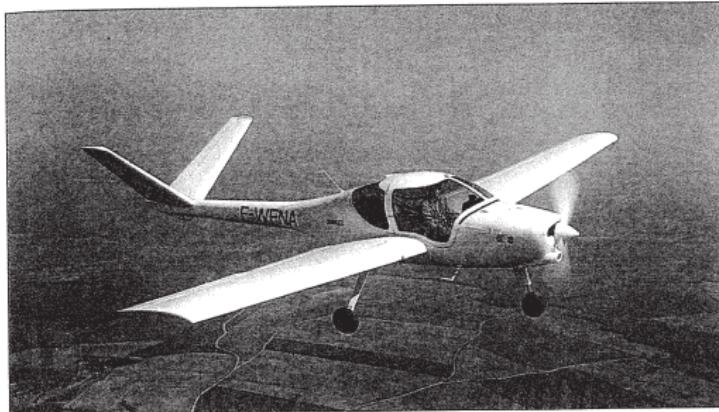
# Lifting Surfaces

## Examples

### Robin ATL Club France

Type: light sports aircraft

Accommodation: two pilots



#### Dimensions:

Length: 22 ft (6.7 m)

Wingspan: 33 ft 7 in (10.2 m)

Height: 6 ft-6 in (2 m)

Max T/O: 1278 lb (580 kg)

Payload: n/a

#### Performance:

Max speed: 124 mph  
(200 kmh)

Range: 539 nm (1000 km)

Power plant: one JPX 4T 60A piston engine

Thrust: 65 hp (48 kW)

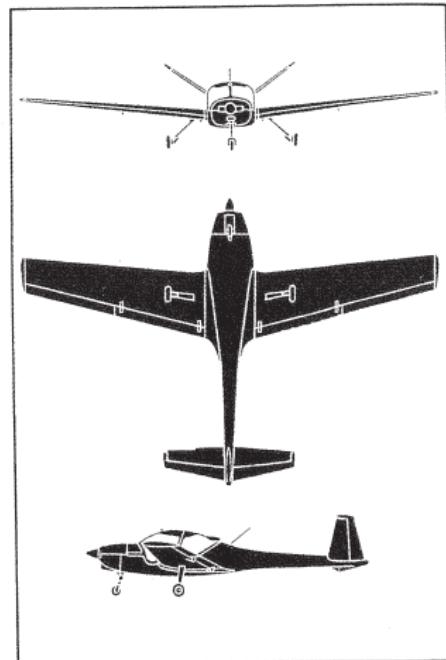
#### Variants:

Model 88 improved version;  
re-engined Model 89

#### Weights:

Empty: 794 lb (360 kg)

Notes: First flown in 1983, the ATL Club is powered by a converted Volkswagen car engine.



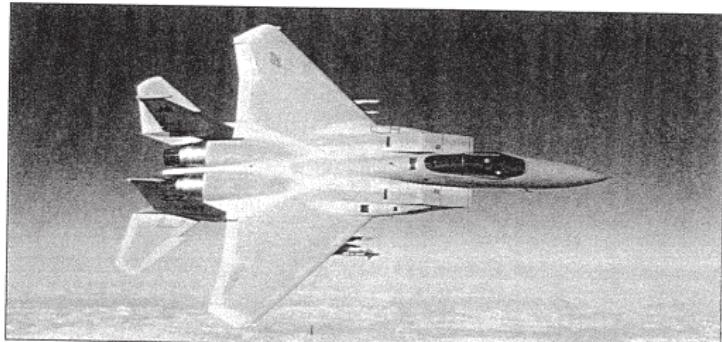
# Lifting Surfaces

## Examples

### McDonnell Douglas F-15C Eagle USA

Type: air superiority fighter

Accommodation: one pilot



#### Dimensions:

Length: 63 ft 9 in (19.43 m)

Wingspan: 42 ft 9 in (13.05 m)

Height: 18 ft 5 in (5.63 m)

#### Weights:

Empty: 28 600 lb (12 973 kg)

Max T/O: 68 000 lb (30 845 kg)

#### Performance:

Max Speed: Mach 2.5+

Range: 2500 nm (4631 km)

Powerplant: two Pratt & Whitney F100-PW-220 turbofans

Thrust: 47 540 lb (211.4 kN) with afterburner

#### Armament:

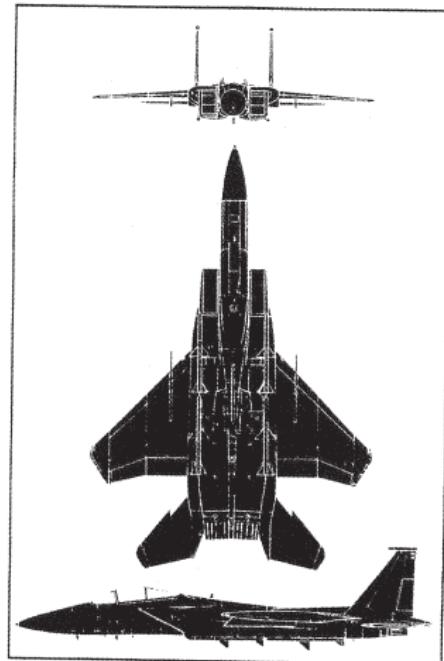
one 20 mm M61A1 Vulcan cannon; 11 hardpoints; four AIM-7 Sparrow or AIM-120

AMRAAM; four AIM-9 Sidewinder

#### Variants:

F-15D twin-seat operational trainer  
F-15J version for Japan  
F-15DJ two-seater for Japan

Notes: Can be configured to carry conformal fuel tanks and extra ECM kit



# Lifting Surfaces

## Examples

### Beechcraft Skipper USA

Type: light training aircraft

Accommodation: two pilots, one passenger



#### Dimensions:

Length: 23 ft 10 in (7.3 m)

Wingspan: 30 ft (9.1 m)

Height: 7 ft 6 in (2.3 m)

Max T/O: 1650 lb (748 kg)

Payload: n/a

piston engine

Thrust: 115 hp (85 kw)

#### Weights:

Empty: 1103 lb (500 kg)

#### Performance:

Max speed: 120 mph (196 kmh)

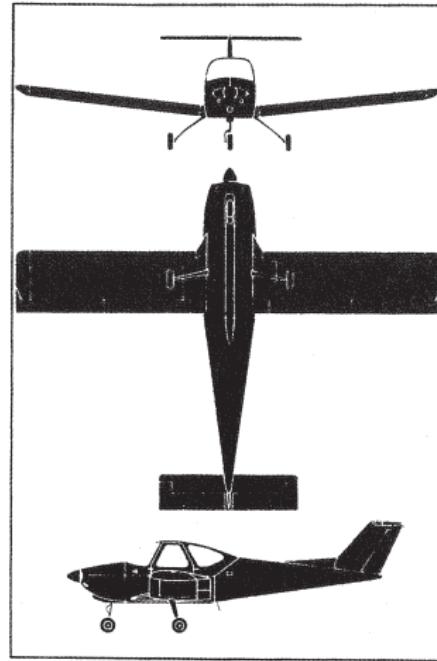
Range: 413 nm (764 km)

Power plant: one O-235

#### Variants:

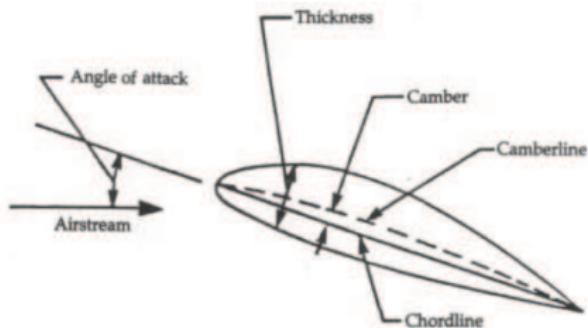
none

Notes: Built in small numbers, the Skipper is mainly used for training purposes.



# Lifting Surfaces

## Airfoils



**Figure:** Airfoil with positive camber

**Chord Line:** A line connecting the leading edge to the trailing edge.

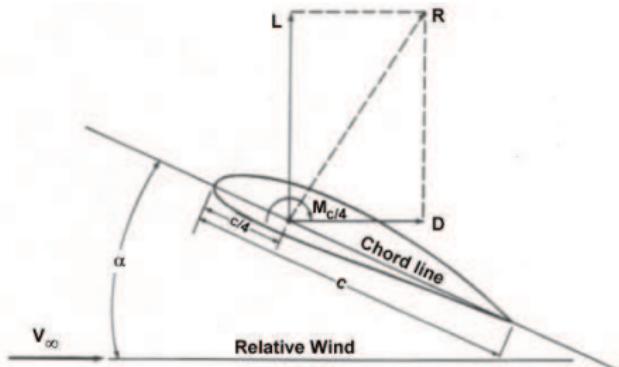
**Camber Line:** A line connecting the points halfway between the top and bottom surfaces.

**Camber:** Camber refers to the difference between the chord line and the camber line. Camber determines the moment produced by a wing. Most wings have positive camber.

# Airfoils: Aerodynamic Center

**Aerodynamic Center:** The point at which the pitching moment does not vary with angle of attack.

- Convenient since  $C_M$  is now static.
- Typically located at the 1/4-chord line.



**Forces and Moments:** The motion of air creates forces and moments.

- Lift and Drag are measured at the *aerodynamic center*.
- Moment is measured as the moment about the *aerodynamic center*.
- Usually take standard form

$$L = C_L Q S, \quad D = C_D Q S, \quad \text{and} \quad M = C_M Q S l$$

- $C_L$  and  $C_D$  will depend on angle of attack and airfoil geometry.
- $C_M$  will (hopefully) depend only on airfoil geometry, especially camber.

# Airfoils: Lift Coefficient

Lift is given by

$$L = C_L Q S$$

**General Form:**

$$C_L = C_{L0} + C_{L\alpha}\alpha$$

where

- $C_{L0}$  is the lift produced at steady-level flight. We define  $C_{L0} = 0$  for an airfoil. However, for the aircraft overall, we want  $C_{L0} > 0$ .
  - ▶ Don't want to fly nose-up all the time.
- $C_{L\alpha} > 0$  is determined by the airfoil type and other factors.
  - ▶ Sweep, planform shape, winglets, Mach number, etc.

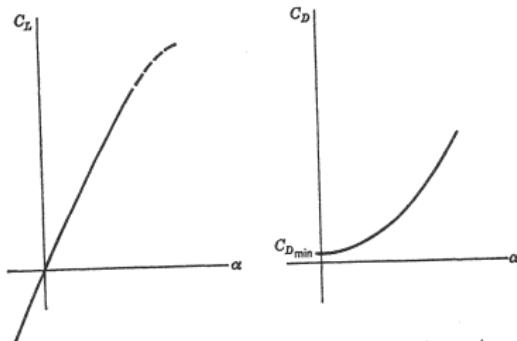


Figure 2.2 Lift and drag for subsonic and supersonic speeds.

# Airfoils: Drag Coefficient

$$D = C_D Q S$$

The drag coefficient,  $C_D$ , of an airfoil is related to the lift coefficient,  $C_L$ . It can be approximated as

$$C_D = C_{D0} + K C_L^2$$

where

- $C_{D0}$  and  $K$  are determined by airfoil type and other factors
  - ▶ Mach number, thrust coefficient, etc.

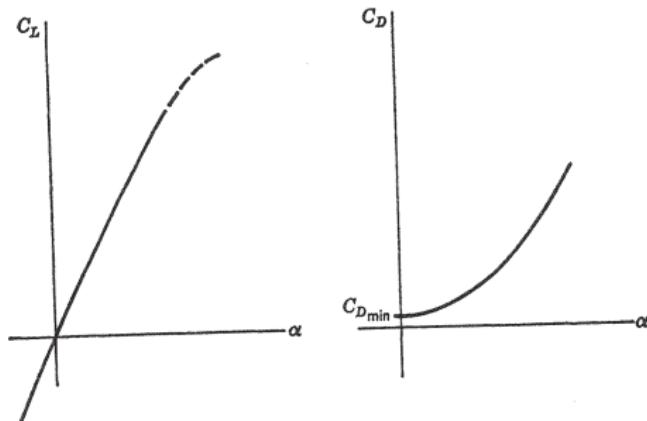


Figure 2.2 Lift and drag for subsonic and supersonic speeds.

# Airfoils: Moment Coefficient

Positive pitching moment is given by

$$M = C_M Q S l$$

## General Form:

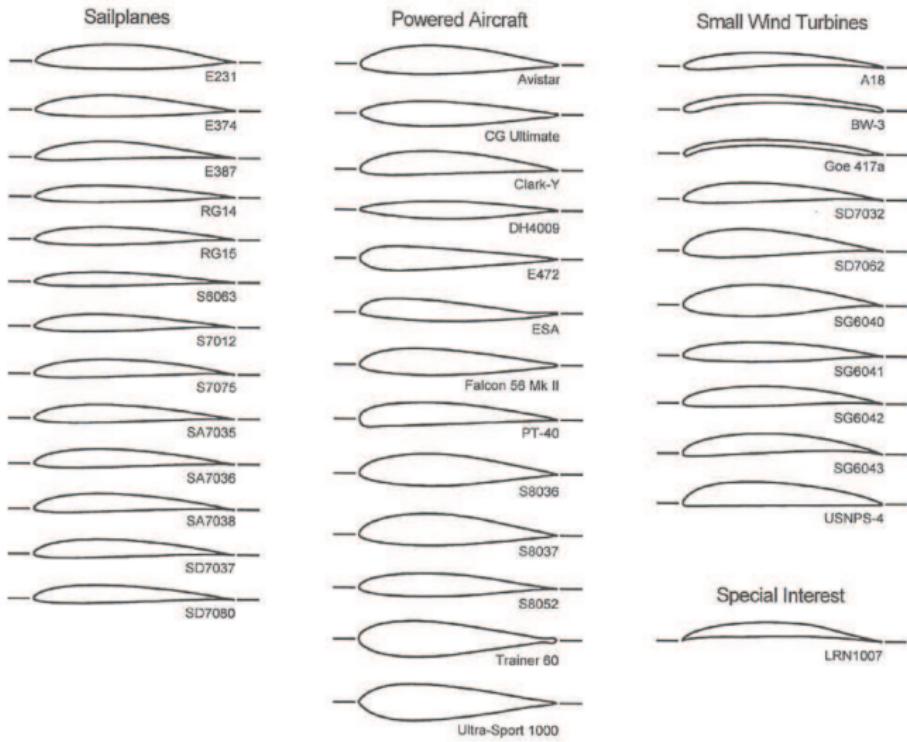
$$C_M = C_{M0} + C_{M\alpha} \alpha$$

where

- $C_{M0}$  is the moment produced at steady-level flight. For an airfoil we have the confusing terminology:
  - ▶  $C_{M0} < 0$  for if the airfoil has **positive camber**.
  - ▶  $C_{M0} > 0$  for if the airfoil has **negative camber**.
- For the aircraft overall, we typically want  $C_{M0} > 0$  (negative camber), but most airfoils have positive camber.
- By definition  $C_{M\alpha} = 0$  for an airfoil if we are considering moment about the aerodynamic center. We will next discuss the effect of  $C_{M\alpha}$  on the overall airplane.

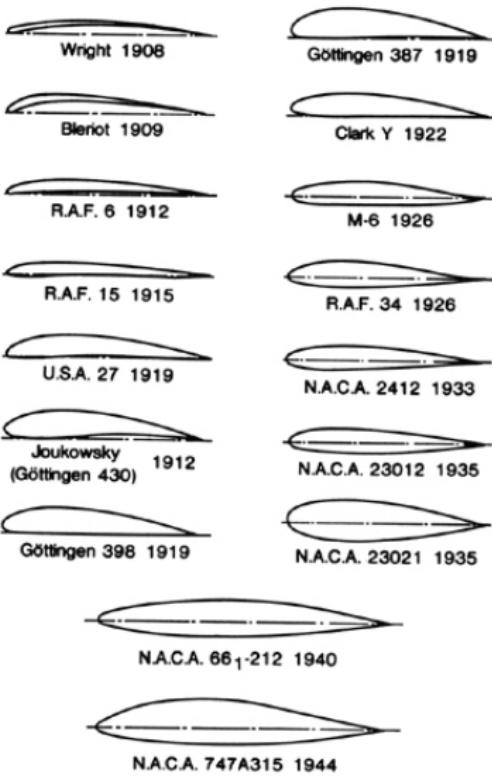
# Airfoils: Examples

## Low-Speed Airfoils



# Airfoils: Examples

## Early Airfoil Evolution



## Airfoils: Examples

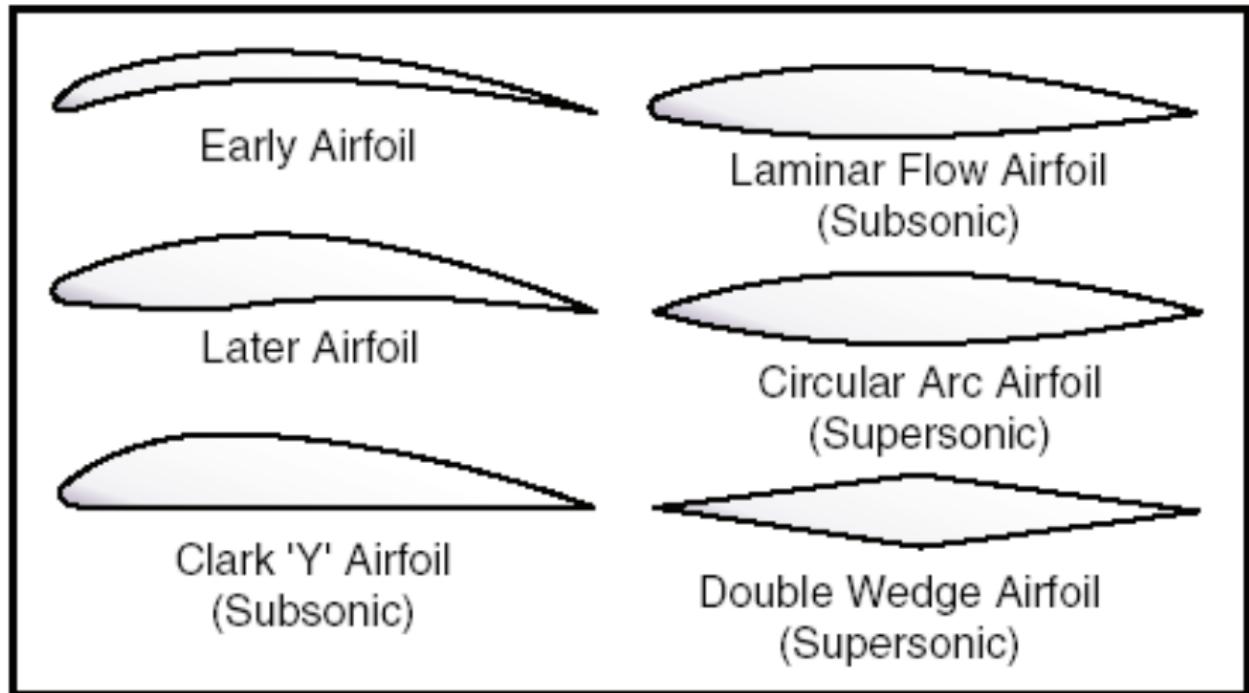


Figure: Later Airfoils

# Big Idea: Static Stability

We now introduce the poorly-defined notion of static stability.

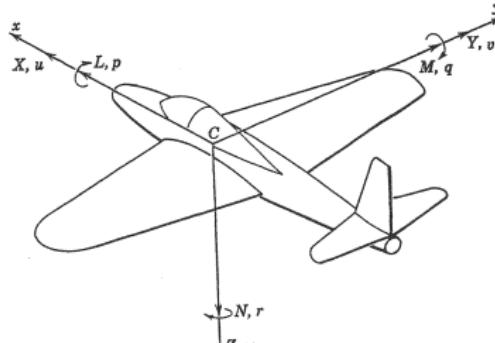
**Static Stability** is stability of the equations of motion for if we only consider 2 dimensions and consider the body-fixed frame to be inertial.

We have the following three varieties, in order of interest:

**Static Longitudinal Stability:** “Pseudo-stability” of the pitching dynamics.  
Only motion in the  $q$ -direction.

**Static Directional Stability:** “Pseudo-stability” of the yawing dynamics. Only motion in the  $r$ -direction.

**Static Roll Stability:** “Pseudo-stability” of the roll dynamics. Only motion in the  $p$ -direction.



# Static Longitudinal Stability: Conceptual Description

## Equilibrium

Longitudinal or pitching stability is the most common question we consider. The dynamics are very simple

$$M = I\dot{q} = I\ddot{\alpha} = (C_{M0} + C_{M\alpha}\alpha)QSl$$

where

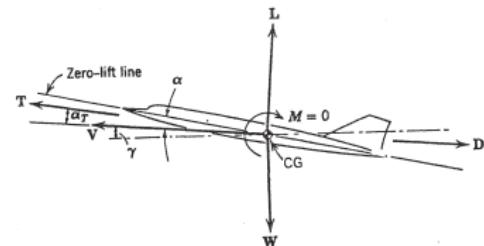
- $I$  is a moment of inertia term.
- Recall  $q = \dot{\alpha}$

*Equilibrium* occurs when

$$\dot{q} = \ddot{\alpha} = (C_{M0} + C_{M\alpha}\alpha)\frac{QSl}{I} = 0.$$

Thus the equilibrium point is

$$\alpha = -\frac{C_{M0}}{C_{M\alpha}}.$$



# Static Longitudinal Stability: Conceptual Description

## Nose-Up Configuration

Regarding the equilibrium point

$$\alpha_E = -\frac{C_{M0}}{C_{M\alpha}}.$$

- Typically, we prefer an aircraft with *nose-up* in steady-level flight.
  - ▶ An aircraft is “nose-up” when  $\alpha > 0$ .
- Steady-level flight means an aircraft in equilibrium.

Thus, when designing an aircraft, we want  $\alpha_E > 0$ . This is achieved when

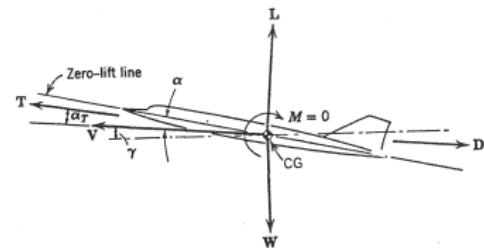
### Case 1:

- $C_{M0} \geq 0$
- $C_{M\alpha} \leq 0$

### Case 2:

- $C_{M0} \leq 0$
- $C_{M\alpha} \geq 0$

In the next slide we will show that for stability, only Case 1 is possible.



# Static Longitudinal Stability: Conceptual Description

## Stability of the Equilibrium

For a given equilibrium, the aircraft is

- Stable if a positive displacement results in negative restoring force.
- Unstable if a positive displacement results in a positive force.

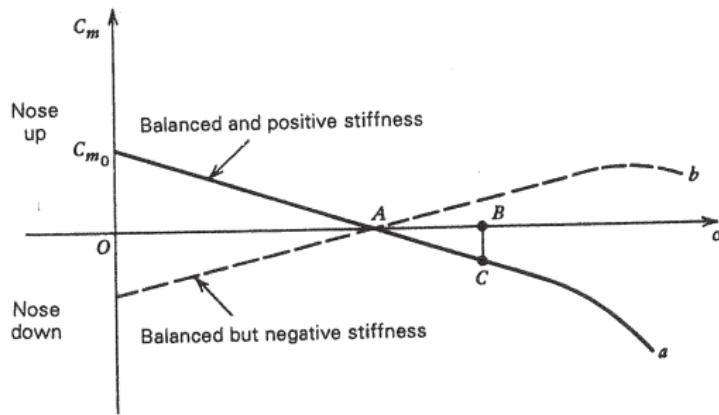


Figure 2.3 Pitching moment of an airplane about the CG.

# Static Longitudinal Stability

Dynamics about the Equilibrium

Stability is about displacement from equilibrium:

$$\Delta\alpha(t) = \alpha(t) - \alpha_E$$

**Stability Question:** Does  $\lim_{t \rightarrow \infty} \Delta\alpha(t) \rightarrow 0???$

The dynamics of the displacement,  $\Delta\alpha$  are

$$\begin{aligned}\frac{d^2}{dt^2}\Delta\alpha(t) &= \frac{d^2}{dt^2}\alpha(t) - \frac{d^2}{dt^2}\alpha_E = \ddot{\alpha}(t) \\ &= (C_{M0} + C_{M\alpha}\alpha(t))\frac{QSl}{I} \\ &= (C_{M0} + C_{M\alpha}(\Delta\alpha(t) + \alpha_E))\frac{QSl}{I} \\ &= (C_{M0} - C_{M\alpha}\frac{C_{M0}}{C_{M\alpha}} + C_{M\alpha}\Delta\alpha(t))\frac{QSl}{I} \\ &= C_{M\alpha}\frac{QSl}{I}\Delta\alpha(t).\end{aligned}$$

Stability *always* considers displacement from equilibrium!!!

# Static Longitudinal Stability

## Characteristic Equation

The displacement dynamics are

$$\frac{d^2}{dt^2} \Delta\alpha(t) = C_{M\alpha} \frac{QSl}{I} \Delta\alpha(t)$$

Thus the characteristic equation is  $s^2 - \frac{C_{M\alpha} QSl}{I}$ , which has roots at

$$s_{1,2} = \pm \frac{1}{2} \sqrt{\frac{C_{M\alpha} QSl}{I}}$$

- We want to know if any roots have positive real part.

Since  $Q$ ,  $S$ ,  $l$  and  $I$  are all positive, there are two cases.

### Case 1:

- $C_{M\alpha} \geq 0$

Aircraft is **Unstable!**

### Case 2:

- $C_{M\alpha} < 0$

Aircraft is **Stable**, but oscillates.

# Static Longitudinal Stability

Using the  $dC_M/dC_L$  Relationship

Sometimes,  $dC_M/dC_L$  data is used instead of  $C_{M\alpha} = dC_M/d\alpha$ . This can be done because

$$C_L = C_{L0} + C_{L\alpha}\alpha, \quad \text{so} \quad \frac{dC_L}{d\alpha} = C_{L\alpha}.$$

Therefore,

$$C_{M\alpha} = \frac{dC_M}{d\alpha} = \frac{dC_M}{dC_L} * \left( \frac{dC_L}{d\alpha} \right)^{-1} = \frac{dC_M}{dC_L} C_{L\alpha}$$

Since  $C_{L\alpha}$  is constant and positive, we have

- **Stability** if  $\frac{dC_M}{dC_L} < 0$
- **Instability** if  $\frac{dC_M}{dC_L} \geq 0$

This is useful if we also want to balance Lift and weight.

# Static Longitudinal Stability

## Example 1

An aircraft without a tail has the following moment characteristics:

$$C_{M0} = -0.4 \quad \text{and} \quad C_{M\alpha} = -0.2 \deg^{-1}.$$

Describe the steady-state motion.

- $C_{M\alpha} = -0.2 \deg^{-1}$ , so aircraft is stable.
- $C_{M0} = -0.4$ , so equilibrium is at

$$\alpha_E = -\frac{C_{M0}}{C_{M\alpha}} = -\frac{-0.4}{-0.2} \deg = -2 \deg$$

So Equilibrium is **Nose Down!** The plane will not produce enough lift.

**Question:** How do we fix the airplane???

**Answer:** Add a tail.

**Question:** Alternatives??? Flaps, inclined wings, etc.

# Aircraft Incidents: Failure Modes

## Short-Period Failure Mode in SAAB Gripen

# Aircraft Incidents: Failure Modes

Long-Period? Failure Mode in SAAB Gripen

# Aircraft Incidents: Failure Modes

F-22 Longitudinal Mode

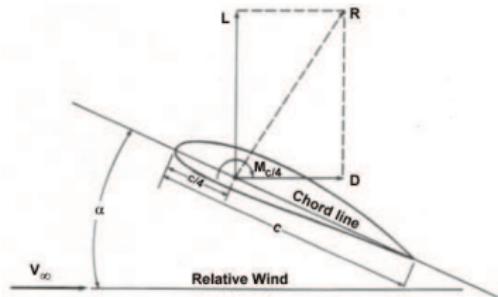
# Aircraft Incidents: Failure Modes

## F-8 Pilot-Induced Oscillation

# Aircraft Incidents: Failure Modes

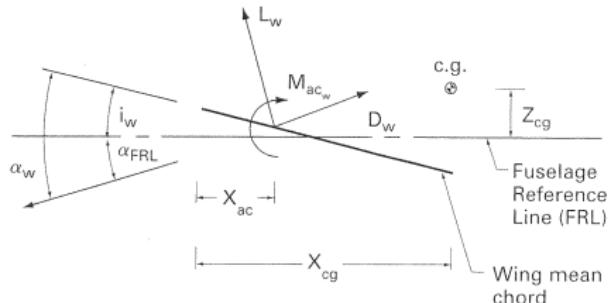
Space Shuttle Pilot-Induced Oscillation

# Two Confusing Figures



**Confusion:** For an airfoil, angle of attack is measured to the zero-lift-line.

- Thus  $C_{M0} = 0$  for an un-inclined airfoil.



**Confusion:** We assume that the aerodynamic center is on the FRL.

- Thus as measure from the CG,

$$\vec{r}_{ac} = \begin{bmatrix} X_{cg} - X_{ac} \\ 0 \\ Z_{cg} \end{bmatrix}.$$

- If there is any confusion on a problem, ask me to clarify.

# Static Longitudinal Stability

## Summary

To summarize these two results:

To have static longitudinal stability, we need

- $C_{M\alpha} \leq 0$

To have longitudinal stability **AND** nose-up in steady state, we need

- $C_{M0} \geq 0$

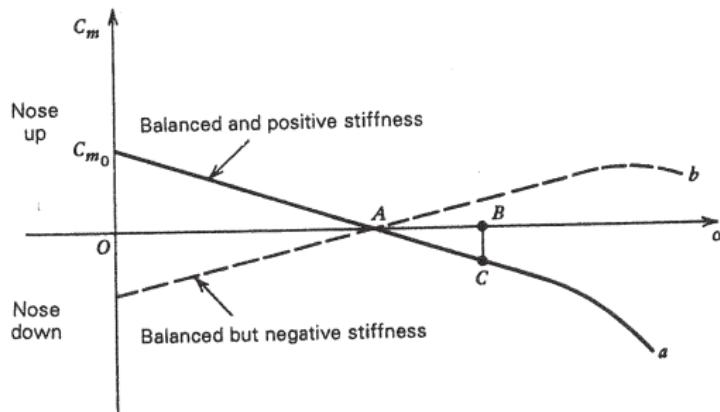


Figure 2.3 Pitching moment of an airplane about the CG.

## Next Lecture: Finding $C_{M0}$ and $C_{M\alpha}$

The  $C_{M0}$  and  $C_{M\alpha}$  of an airplane are determined by adding up the contributions of all factors.

In the next lecture, we will discuss the contributions of

- Rectangular Wing
- Horizontal Stabilizer
- Canards