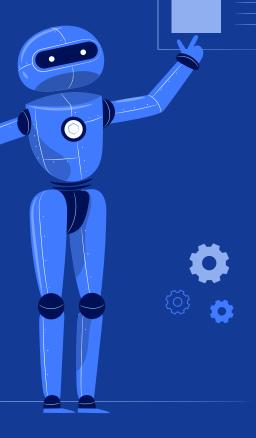


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Operating Systems Lab - 4

Group - 6



Members



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Question Statement

Using the concepts of shared-memory based programming, design and implement a client-server based project.

Components:

```
1. service1.c find LCM of 4 given numbers
```

2. service2.c find GCD of 2 numbers

3. service3.c find LCM and GCD of 2 numbers

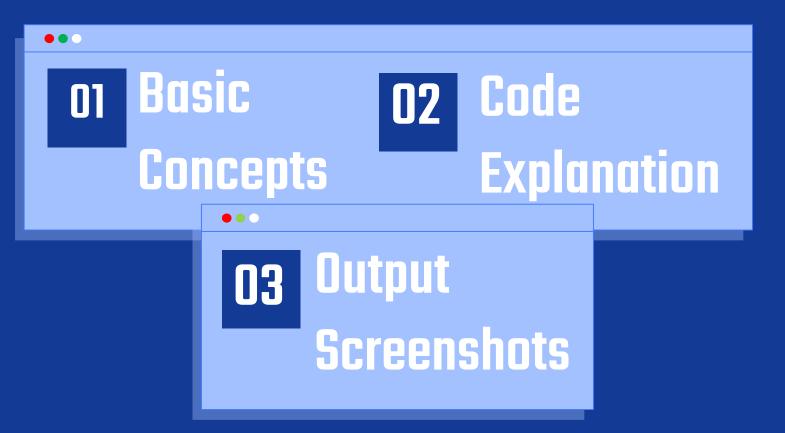
4. client.c to create particular request to server

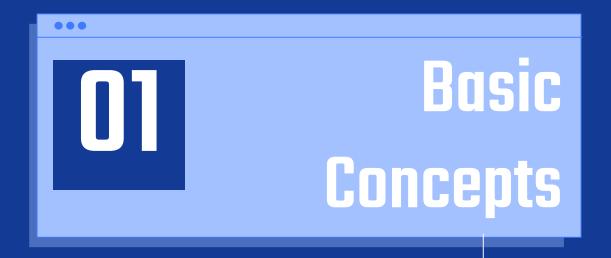
5. server.c to manage all client requests





Table of Contents







Basic Concepts



exec syscalls

The exec family of system calls replaces the program executed by a process. When a process calls exec, all code (text) and data in the process is lost and replaced with the executable of the new program.

The exec() functions return only if an error has occurred. The return value is -1, and error is set to indicate the error.

execl execle execlp execv execve execvp are some syscalls in exec family.

- **e**: It is an array of pointers that points to environment variables and is passed explicitly to the newly loaded process.
- I: I is for the command line arguments passed a list to the function
- **p**: p is the path environment variable which helps to find the file passed as an argument to be loaded into process.
- **v**: v is for the command line arguments. These are passed as an array of pointers to the function.



Shared memory IPC

Inter Process Communication through shared memory is a concept where two or more process can access the common memory. And communication is done via this shared memory where changes made by one process can be viewed by another process.

Shared memory provides a way by letting two or more processes share a memory segment. With Shared Memory the data is only copied twice - from input file into shared memory and from shared memory to the output file.

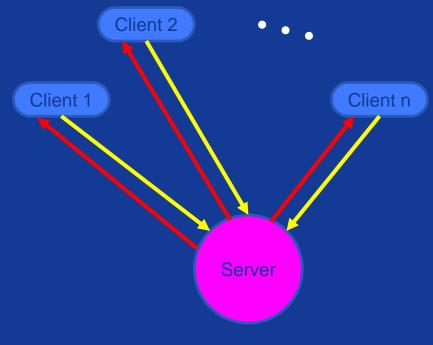
Syscalls for Shm-IPC

- ftok(),
- shmget(),
- shmat(),
- shmdt(),
- shmctl()



Client-Server system

- Client-server relationship is a relation in which one program (client) requests a service or resource from another program (server).
- Advantage of the client-server model is that its centralized architecture helps make it easier to protect data with access controls that are enforced by security policies.



Client requesting a service from server

Server granting service to client







```
int service no;
msg buffer structure is used here to store information
                                                                    int PID;
related to a request made by client, while creating a request,
                                                                    int shmid;
client process provides process id(PID), service no,
                                                                    int service input[4];
sharedmemory id(shmid), and inputs needed
                                                                  message;
(service input) for invoking particular service.
                                                                typedef struct{
                                                                     struct msg buffer arr[100000];
Array arr is implemented as a circular queue of type
msg buffer, which basically stores client's request
                                                                    int front;
information. front, end represent start and end index of
                                                                    int end;
circular queue respectively. Lock is used to create mutual
                                                                    pthread mutex t lock;
exclusion between other clients and server.
                                                                }queue;
                                                                queue *q;
queue *q; declares a variable of type queue
                                                                int shmid queue;
shmid queue stores the shared memory id for queue.
void my handler(){
                                                             This handler is called when ctrl+c is
    pthread mutex destroy(&q->lock);
                                                             pressed in server process, it destroys the
    shmctl(shmid queue, IPC RMID, NULL);
                                                             mutex lock from queue, clears shared memory
    printf("Server ended\n");
                                                             allotted to request queue, and quits server
    exit(1);
                                                             program.
```

server.c

struct msg_buffer{

```
Initiate interrupt handler
Initially queue is empty so, set front
and end to 0
Initiate mutex lock.
argv_... store the parameters to be
passed to exec sys call.
```

- Implementing circular queue using array
 - Using mutex locking to ensure that no other process changes, data in queue. Last line is used here to wait for client
- Last line is used here to wait for clien process to request a service when, there are no processes pending in request queue.

```
signal(SIGINT, my_handler);
    q->front=0;
    q->end=0;
    pthread_mutex_init(&q->lock,NULL);
    char argv_1[50], argv_2[50], argv_3[50],
argv_4[50], argv_5[50], argv_6[50];
```

```
while (1){
    if(q->end==99999 || q->front==99999) {
        while(pthread_mutex_trylock(&q->lock)!=0);
        if(q->end==99999)
            q->end=0;
        if(q->front==99999)
            q->front=0;
        pthread_mutex_unlock(&q->lock);
    }
    while(q->front==q->end);
```



```
Get the oldest request from queue
                                                   sprintf(argv 5, "%d", q->arr[front].PID);
                                                   sprintf(argv_6, "%d", q->arr[front].shmid);
   And other info like PID, shmid, etc.
                                                   int service number=q->arr[front].service no;
                                                   if(service number==1){
   And at last unlocks the mutex on
                                                        sprintf(argv 3, "%d", q->arr[front].service input[2]);
   queue.
                                                        sprintf(argv 4, "%d", q->arr[front].service input[3]);
                                               pthread mutex unlock(&q->lock);
int pid = fork();
                                                  Once all the details of client process, and its service request
        if (pid < 0){
                                                  are gathered, using fork() we create a new process.
            perror("Fork Error.");
                                                  If new process is not created, then result is shown.
            exit(1);
                                                  If child process is created, then particular program is
```

while(pthread_mutex_trylock(&q->lock)!=0);
 int front=q->front;

sprintf(argv_1, "%d", q->arr[front].service_input[0]);
sprintf(argv 2, "%d", q->arr[front].service input[1]);

invoked using exec1() syscall, within child process.

q->front++;

Tries to lock the mutex

else if (pid == 0){



client.c

scan_buffer is used
here to take input of
certain no. of items
in buffer array.

print_result is used here to print the result, after response is received from server for particular service

```
void scan buffer(int n){
    printf("Enter %d integers: ",n);
    for(int i=0;i< n;i++){
        scanf("%d",&buffer[i]);
        message.service input[i]=buffer[i];
void print result(int type, int lcm, int qcd){
    if(type==1)
        printf("LCM of %d, %d, %d and %d is: %d\n",buffer[0],buffer[1],buf
fer[2], buffer[3], Lcm);
    else if(type==2)
        printf("GCD of %d and %d is: %d\n",buffer[0],buffer[1],qcd);
    else if(type==3){
        printf("LCM of %d and %d is: %d\n",buffer[0],buffer[1],lcm);
        printf("GCD of %d and %d is: %d\n",buffer[0],buffer[1],qcd);
```



```
PID of client process is printed on
screen
Initiate service type with 0.
Keep taking service type until a
correct service type is provided by
user i.e. 1, 2 or 3.
service type is saved as service no in
message variable of type msg buffer.
```

```
Then according to service_type, number of inputs are taken, from user using scan buffer().
```

```
int service type=0;
while(service type<1 | service type>3){
  printf("Enter service type: \n");
  printf("1-> LCM of 4 integers\n");
  printf("2-> GCD of 2 integers\n");
  printf("3-> LCM and GCD of 2 integers\n");
  scanf("%d",&service type);
message.service no=service type;
switch(service type){
    case 1:
        scan buffer(4);
        break;
    case 2:
    case 3:
        scan_buffer(2);
        break;
    default:
        printf("Invalid choice\n");
        exit(-1);
```

printf("PID of this client process is: %d\n",getpid());

printf("Client Process started\n");



- Once we have gathered all information required to invoke a service using, server, we try to lock the mutex.
- Once the mutex is locked, we add all relate details like PID, service_no, service_input etc. to queue.
- Now after successful write operation, we release the lock.
- Now the processed is paused, after putting its request to server When server encounters a request of this
- client, it invokes a relevant service.

 Service after successful completion,

sends a signal to client(this) process,

with result in result_buffer.Now, we print the result using

print result().

And then we free result_buffer from memory, using shmctl()

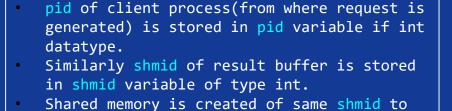
```
pause();
    switch(service type){
        case 1:
            print_result(1,result_buffer[0],0);
            break:
        case 2:
            print result(2,0,result buffer[0]);
            break:
        case 3:
            print result(3,result buffer[0],result buffer[1])
            break:
        default:
            printf("Invalid choice\n");
            exit(-1);
    shmctl(shmid, IPC RMID, NULL);
```



Required argv elements are copied to buffer array.

service1.c

Particular calculation is performed, in this case we have to find lcm of 4 number so, we perform that operation, and store result in lcm variable.



client. Using kill(), we signal the client process with pid to continue its execution.

Same applies for other services also.

create same result buffer which is at

for(int i=1;i<5;i++){ buffer[i-1]=atoi(arqv[i]); int lcm=buffer[0]; for(int i=1;i<4;i++){ lcm=((buffer[i]*lcm)/gcd(buffer[i],lcm));

signal(SIGUSR1, my_handler);

int buffer[4];

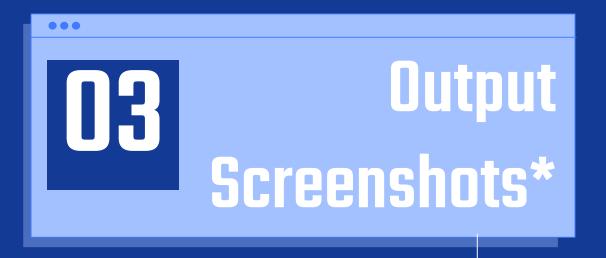
printf("Service 1 started...\n");

int pid = atoi(arqv[arqc - 2]);

```
int shmid = atoi(argv[argc - 1]);
int *result_buffer = (int *)shmat(shmid, NULL, 0);
if(result buffer == (void *) -1){
    perror("error2:");
    exit(1);
```

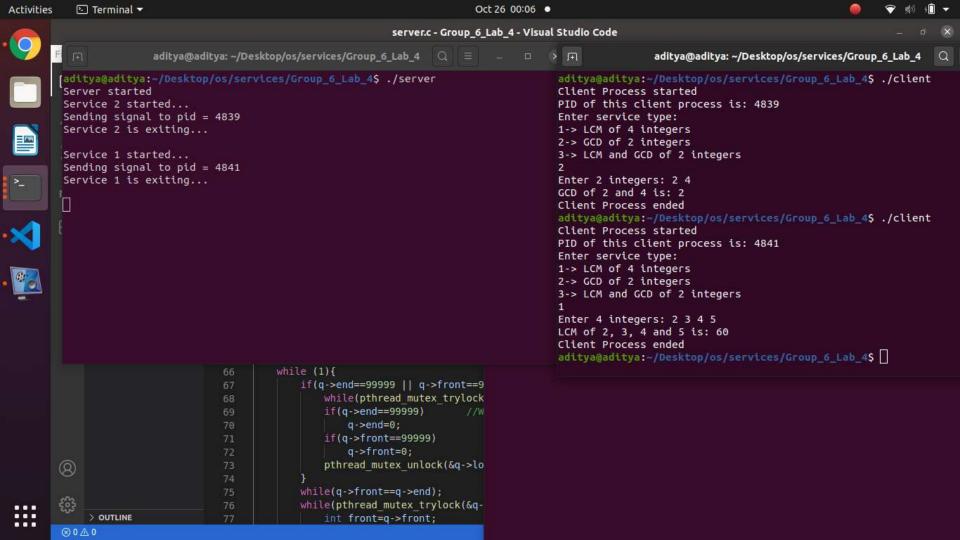
printf("Service 1 is exiting...\n\n");

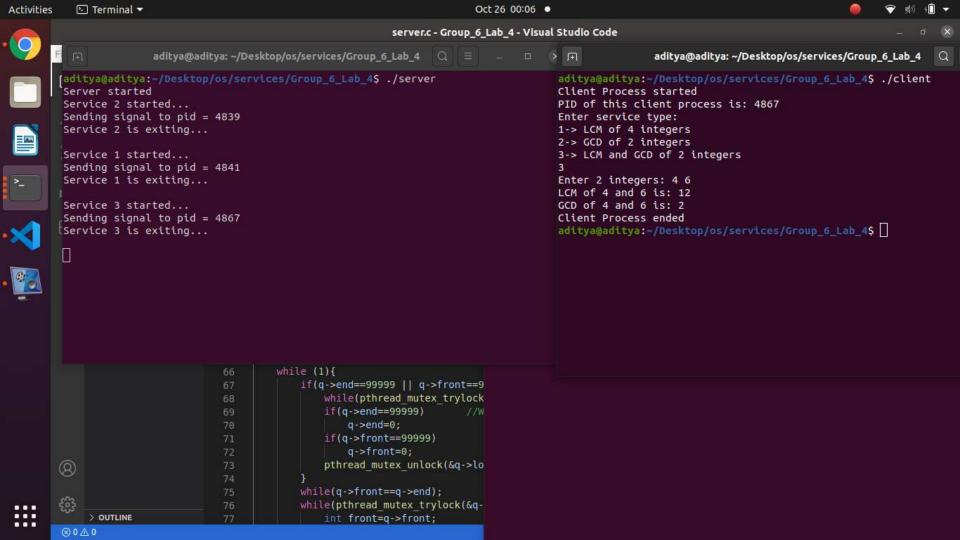
result buffer[0] = lcm; printf("Sending signal to pid = %d\n",pid); kill(pid, SIGUSR1);

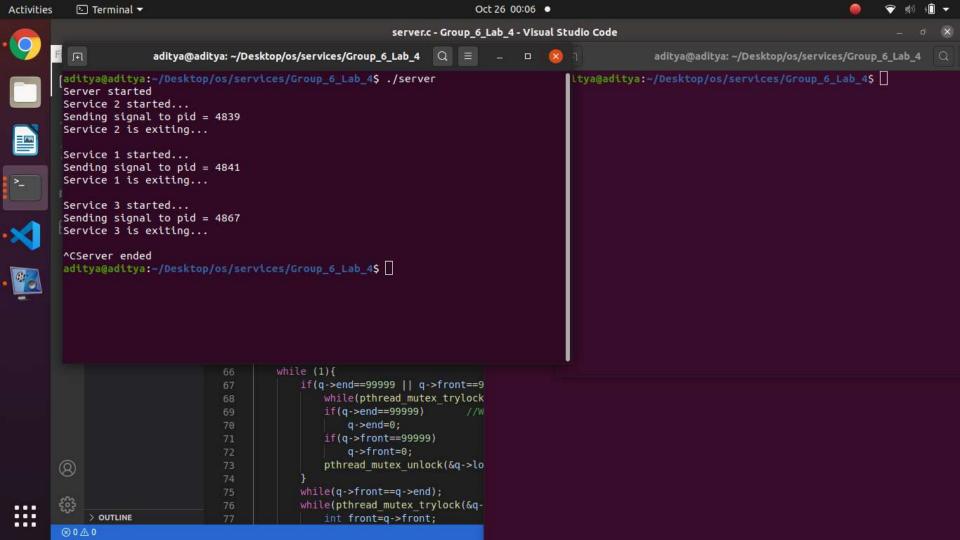


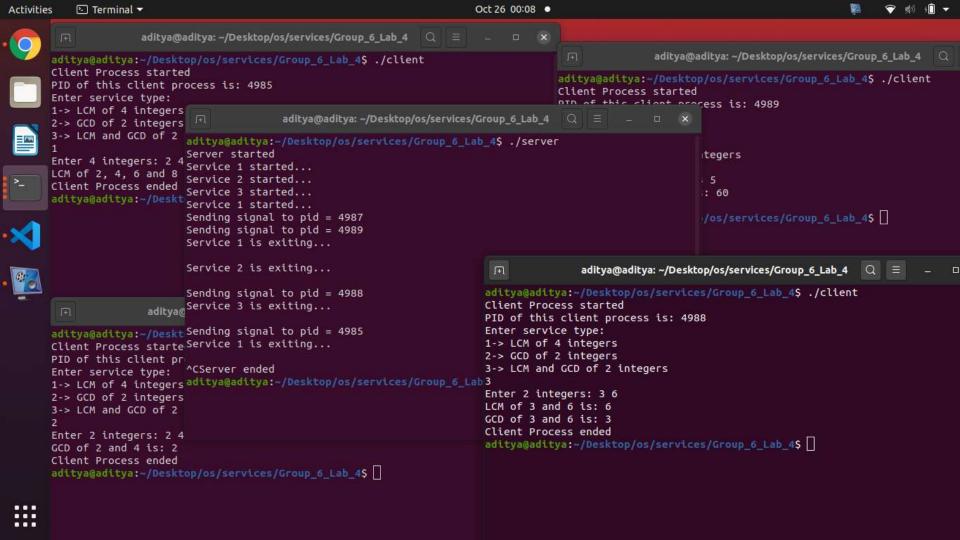


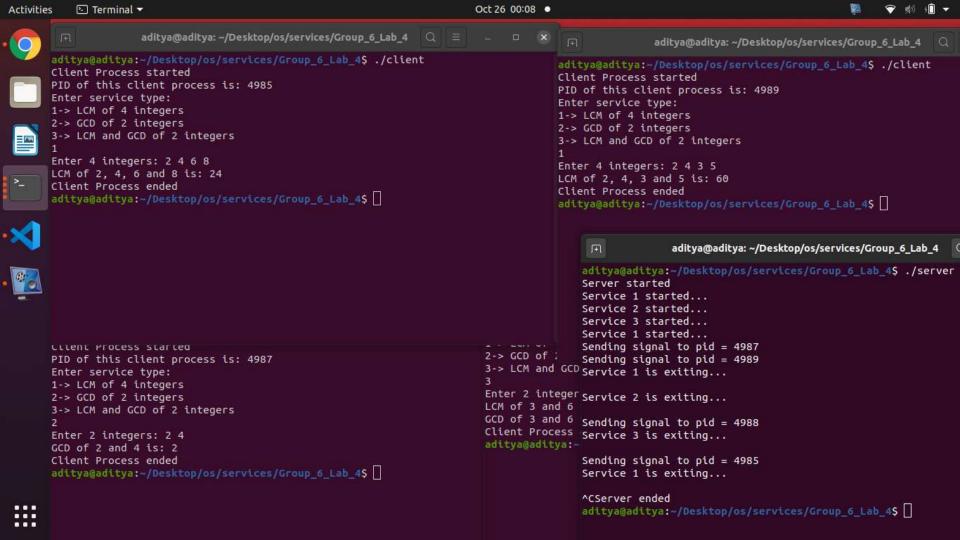
* In ppt we are showing few screenshots of output, we have also attached a video demonstrating the complete work.

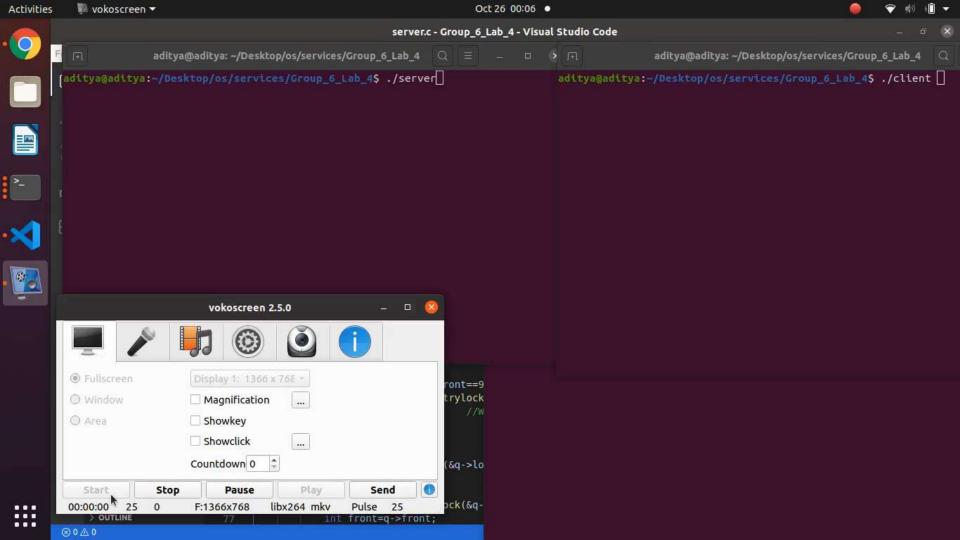












THANK YOU

