

# Lecture Note 3

- Lag Operators
- Autoregressive of order 2, AR(2)
- Autoregressive of order  $p$ , AR(p)

## Lag Operators

**Definition 1.** If  $x_t = x(t)$  is a function of time, the lag operator,  $L$ , is defined by

$$Lx_t = x_{t-1}.$$

**Definition 2.** Powers of the lag operator are defined as successive application of  $L$ , that is

$$L^2x_t = L(Lx_t) = Lx_{t-1} = x_{t-2},$$

and, in general, for any integer  $k$ ,

$$L^kx_t = x_{t-k}.$$

The lag operator satisfies,

- (i)  $L(a + bx_t) = a + bLx_t = a + bx_{t-1}$ .
- (ii)  $(a_1L^p + a_2L^q)x_t = a_1L^px_t + a_2L^qx_t = a_1x_{t-p} + a_2x_{t-q}$ .

**Definition 3.** A lag polynomial is defined by

$$a(L) = a_0 + a_1L + a_2L^2 + \dots$$

Lag polynomials satisfy the following properties,

(i)

$$\begin{aligned} a(L)b(L) &= (a_0 + a_1L + a_2L^2 + \dots)(b_0 + b_1L + b_2L^2 + \dots) \\ &= a_0b_0 + (a_1b_0 + a_0b_1)L + (a_2b_0 + a_1b_1 + a_0b_2)L^2 + \dots \end{aligned}$$

(ii)  $a(L)b(L) = b(L)a(L)$ .

(iii)  $(a(L))^2 = a(L)a(L)$ .

(iv) The lag polynomial  $a(L)$  can be factorized as follows:

$$a(L) = (1 - \lambda_1L)(1 - \lambda_2L)(1 - \lambda_3L)\dots,$$

where  $\lambda_1, \lambda_2, \lambda_3, \dots$  are coefficients.

(v) The inverse of the Lag polynomial  $a(L)$  is

$$a(L)^{-1} = (1 - \lambda_1 L)^{-1} (1 - \lambda_2 L)^{-1} (1 - \lambda_3 L)^{-1} \dots$$

**Example 1.** Suppose  $x_t$  follows the following AR(1) process:

$$x_t = \phi_0 + \phi_1 x_{t-1} + \varepsilon_t,$$

where  $\varepsilon_t \sim iid(0, \sigma^2)$ . We can write

$$x_t = \phi_0 + \phi_1 L x_t + \varepsilon_t \Rightarrow (1 - \phi_1 L) x_t = \phi_0 + \varepsilon_t \Rightarrow \phi(L) x_t = \phi_0 + \varepsilon_t.$$

To investigate whether the inverse of  $\phi(L)$ ,  $\phi(L)^{-1}$ , exists, allow  $\phi(L)^{-1} = a_0 + a_1 L + a_2 L^2 + \dots$ . Since  $\phi(L)^{-1} \phi(L) = 1$ , we can right

$$(a_0 + a_1 L + a_2 L^2 + \dots)(1 - \phi_1 L) = 1 \Rightarrow$$

$$a_0 = 1,$$

$$a_1 - a_0 \phi_1 = 0 \Rightarrow a_1 = \phi_1,$$

$$a_2 - a_1 \phi_1 = 0 \Rightarrow a_2 = \phi_1^2,$$

$$\vdots$$

$$a_i = \phi_1^i \text{ for } i = 0, 1, 2, \dots$$

So for the inverse to exist we need  $|\phi_1| < 1$ . Then

$$\begin{aligned} x_t &= \phi(L)^{-1} \phi_0 + \phi(L)^{-1} \varepsilon_t \\ &= (1 + \phi_1 + \phi_1^2 + \dots) \phi_0 + (1 + \phi_1 L + \phi_1^2 L^2 + \dots) \varepsilon_t \\ &= \frac{\phi_0}{1 - \phi_1} + \varepsilon_t + \phi_1 \varepsilon_{t-1} + \phi_1^2 \varepsilon_{t-2} + \dots \end{aligned}$$

Therefore,

$$x_t = \frac{\phi_0}{1 - \phi_1} + \sum_{i=0}^{\infty} \phi_1^i \varepsilon_{t-i}.$$

## Autoregressive of order two, AR(2)

**Definition 4.** A time series process  $x_t$  is said to be Autoregressive of order two,  $AR(2)$ , if it can be written as

$$x_t = \phi_0 + \phi_1 x_{t-1} + \phi_2 x_{t-2} + \varepsilon_t, \text{ where } \varepsilon_t \sim iid(0, \sigma^2). \quad (1)$$

• We can further write (1) as  $(1 - \phi_1 L - \phi_2 L^2)x_t = \phi_0 + \varepsilon_t$ .

**Q:** Suppose that  $x_t$  given by (1) is a weakly stationary process. Compute its mean, variance and autocovariance function.

$$\mathbf{A:} \mathbb{E}(x_t) = \phi_0 + \phi_1 \mathbb{E}(x_{t-1}) + \phi_2 \mathbb{E}(x_{t-2}) = \phi_0 + (\phi_1 + \phi_2) \mathbb{E}(x_t) \Rightarrow \mathbb{E}(x_t) = \frac{\phi_0}{1 - \phi_1 - \phi_2}.$$

$$\begin{aligned} \text{var}(x_t) &= \text{cov}(x_t, x_t) = \phi_1 \text{cov}(x_{t-1}, x_t) + \phi_2 \text{cov}(x_{t-2}, x_t) + \text{cov}(\varepsilon_t, x_t) \\ &= \phi_1 \text{cov}(x_{t-1}, x_t) + \phi_2 \text{cov}(x_{t-2}, x_t) + \text{var}(\varepsilon_t) \Rightarrow \end{aligned}$$

or

$$\gamma(0) = \phi_1 \gamma(1) + \phi_2 \gamma(2) + \sigma^2. \quad (2)$$

$$\begin{aligned} \text{cov}(x_t, x_{t-\ell}) &= \text{cov}(\phi_0 + \phi_1 x_{t-1} + \phi_2 x_{t-2} + \varepsilon_t, x_{t-\ell}) \\ &= \phi_1 \text{cov}(x_{t-1}, x_{t-\ell}) + \phi_2 \text{cov}(x_{t-2}, x_{t-\ell}) \end{aligned}$$

for all  $\ell = 1, 2, \dots$  or

$$\gamma(\ell) = \phi_1 \gamma(\ell - 1) + \phi_2 \gamma(\ell - 2) \text{ for all } \ell = 1, 2, \dots$$

By substituting,  $\ell = 1$  and  $\ell = 2$ , we get,

$$\gamma(1) = \phi_1 \gamma(0) + \phi_2 \gamma(1), \quad (3)$$

and

$$\gamma(2) = \phi_1 \gamma(1) + \phi_2 \gamma(0). \quad (4)$$

From equations (2), (3) and (4), we can find the values of  $\gamma(0)$ ,  $\gamma(1)$ , and  $\gamma(2)$  in terms of variance of  $\varepsilon_t$ ,  $\sigma^2$ , and the parameters  $\phi_1$  and  $\phi_2$ . Given the value of  $\gamma(0)$ ,  $\gamma(1)$ , and  $\gamma(2)$ , we can compute  $\gamma(\ell)$  for  $\ell = 3, 4, \dots$  in terms of variance of  $\varepsilon_t$ ,  $\sigma^2$ , and the parameters  $\phi_1$  and  $\phi_2$  by

$$\gamma(\ell) = \phi_1\gamma(\ell - 1) + \phi_2\gamma(\ell - 2).$$

**Theorem 1.** *An Autoregressive of order two,  $AR(2)$ , process*

$$x_t = \phi_0 + \phi_1x_{t-1} + \phi_2x_{t-2} + \varepsilon_t, \text{ where } \varepsilon_t \sim iid(0, \sigma^2),$$

*is weakly stationary if all the roots of*

$$\lambda^2 - \phi_1\lambda - \phi_2 = 0,$$

*are inside the unit circle, or all the roots of*

$$1 - \phi_1L - \phi_2L^2 = 0$$

*are outside of unit circle.*

*Proof.* By using Lag operator, we have,

$$(1 - \phi_1L - \phi_2L^2)x_t = \phi_0 + \varepsilon_t.$$

Let  $\phi(L) = 1 - \phi_1L - \phi_2L^2$  and suppose  $\phi(L)^{-1} = a_0 + a_1L + a_2L^2 + \dots$  is the inverse of  $\phi(L)$ . So,  $a_i$  for  $i = 1, 2, \dots$  should take values such  $\phi(L)^{-1}\phi(L) = 1$ . Therefore,

$$(a_0 + a_1L + a_2L^2 + \dots)(1 - \phi_1L - \phi_2L^2) = 1.$$

Hence,

$$\begin{aligned} a_0 &= 1, \\ a_1 - a_0\phi_1 &= 0 \Rightarrow a_1 = \phi_1, \\ a_2 - a_1\phi_1 - a_0\phi_2 &= 0, \\ \vdots \\ a_i - a_{i-1}\phi_1 - a_{i-2}\phi_2 &= 0 \text{ for } i = 2, 3, \dots \end{aligned}$$

Now, suppose that  $a_i = c\lambda^i$  is the solution for  $a_i - a_{i-1}\phi_1 - a_{i-2}\phi_2 = 0$ . Then,

$$c\lambda^i - \phi_1 c\lambda^{i-1} - \phi_2 c\lambda^{i-2} = 0 \Rightarrow \lambda^2 - \phi_1\lambda - \phi_2 = 0.$$

The roots of the above equation are

$$\lambda_1 = \frac{\phi_1 + \sqrt{\phi_1^2 + 4\phi_2}}{2} \text{ and } \lambda_2 = \frac{\phi_1 - \sqrt{\phi_1^2 + 4\phi_2}}{2}$$

So,  $a_i = c_1\lambda_1^i$  is one root of  $a_i - a_{i-1}\phi_1 - a_{i-2}\phi_2 = 0$  and  $a_i = c_2\lambda_2^i$  is the other one. So, in general all  $a_i$  such that

$$a_i = c_1\lambda_1^i + c_2\lambda_2^i \tag{5}$$

is the solution for  $a_i - a_{i-1}\phi_1 - a_{i-2}\phi_2 = 0$  for all  $i = 2, 3, \dots$ . We can determine the value of  $c_1$  and  $c_2$  such that  $a_i = c_1\lambda_1^i + c_2\lambda_2^i$  to be also the solution for  $i = 0, 1$ . For  $i = 0$ , we have  $a_1 = c_1 + c_2 = 1$  so  $c_2 = 1 - c_1$ . Also for  $i = 1$ , we have  $a_2 = c_1\lambda_1 + c_2\lambda_2 = \phi_1$ . Setting  $c_2 = 1 - c_1$ , we can further write

$$c_1(\lambda_1 - \lambda_2) + \lambda_2 = \phi_1 \Rightarrow c_1 = \frac{\phi_1 - \lambda_2}{\lambda_1 - \lambda_2}.$$

From (5), we can conclude that the inverse exists if the roots  $\lambda_1$  and  $\lambda_2$  are inside the unit circle,  $|\lambda_j| < 1$  for  $j = 1, 2$ .

$$x_t = \phi(L)^{-1}\phi_0 + \phi(L)^{-1}\varepsilon_t \Rightarrow x_t = \phi_0 \sum_{j=0}^{\infty} a_j + \sum_{j=0}^{\infty} a_j \varepsilon_{t-j},$$

where  $a_i = c_1\lambda_1^i + c_2\lambda_2^i$ . Since  $\lambda_1$  and  $\lambda_2$  are inside the unit circle, we can show that  $\sum_{j=0}^{\infty} a_j < \infty$  and  $\sum_{j=0}^{\infty} a_j^2 < \infty$ . Hence the process is weakly stationary.

Note that since  $\lambda^2 - \phi_1\lambda - \phi_2 = 0$ , we have  $1 - \phi_1\frac{1}{\lambda} - \phi_2\frac{1}{\lambda^2} = 0$ . Setting  $L = \frac{1}{\lambda}$ , we get  $1 - \phi_1L - \phi_2L^2 = 0$ . Since the roots  $\lambda_1$  and  $\lambda_2$  should be inside the unit circle, so that the process be weakly stationary and  $L = \frac{1}{\lambda}$ , we need the roots of  $1 - \phi_1L - \phi_2L^2 = 0$ ,  $L_1$  and  $L_2$ , to be outside unit circle.  $\square$

## Autoregressive of order $p$ , AR( $p$ )

**Definition 5.** A time series process  $x_t$  is said to be Autoregressive of order  $p$ , AR( $p$ ), if it can be written as

$$x_t = \phi_0 + \phi_1x_{t-1} + \phi_2x_{t-2} + \cdots + \phi_px_{t-p} + \varepsilon_t, \text{ where } \varepsilon_t \sim iid(0, \sigma^2). \quad (6)$$

- We can further write (6) as  $(1 - \phi_1L - \phi_2L^2 - \cdots - \phi_pL^p)x_t = \phi_0 + \varepsilon_t$ .

**Theorem 2.** An Autoregressive of order  $p$ , AR( $p$ ), process

$$x_t = \phi_0 + \phi_1x_{t-1} + \phi_2x_{t-2} + \cdots + \phi_px_{t-p} + \varepsilon_t, \text{ where } \varepsilon_t \sim iid(0, \sigma^2).$$

is weakly stationary if all the roots of

$$\lambda^p - \phi_{p-1}\lambda^{p-1} - \phi_{p-2}\lambda^{p-2} - \cdots - \phi_p = 0,$$

are inside the unit circle, or all the roots of

$$1 - \phi_1L - \phi_2L^2 - \cdots - \phi_pL^p = 0$$

are outside of the unit circle.