

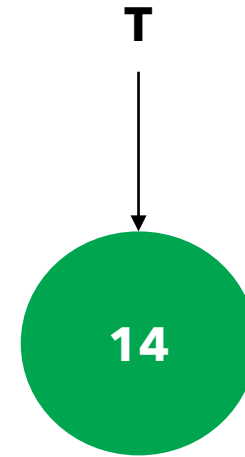
# Alberi binari

**Liceo G.B. Brocchi - Bassano del Grappa (VI)**  
**Liceo Scientifico - opzione scienze applicate**  
Giovanni Mazzocchin

# BST – inserimento ricorsivo

```
T = nil  
bst_insert(T, 14)
```

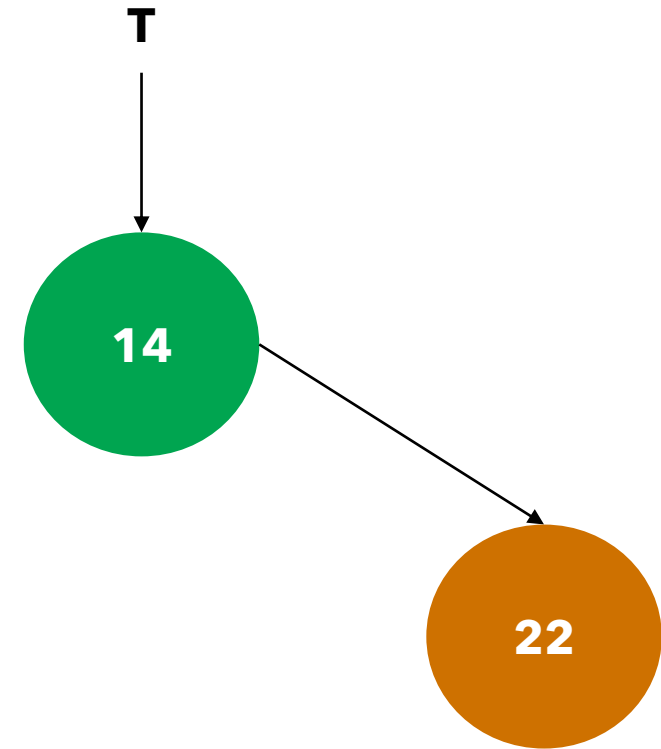
**caso base:** si crea un nuovo  
nodo e lo si fa puntare da T



# BST – inserimento ricorsivo

```
bst_insert(T, 22)
```

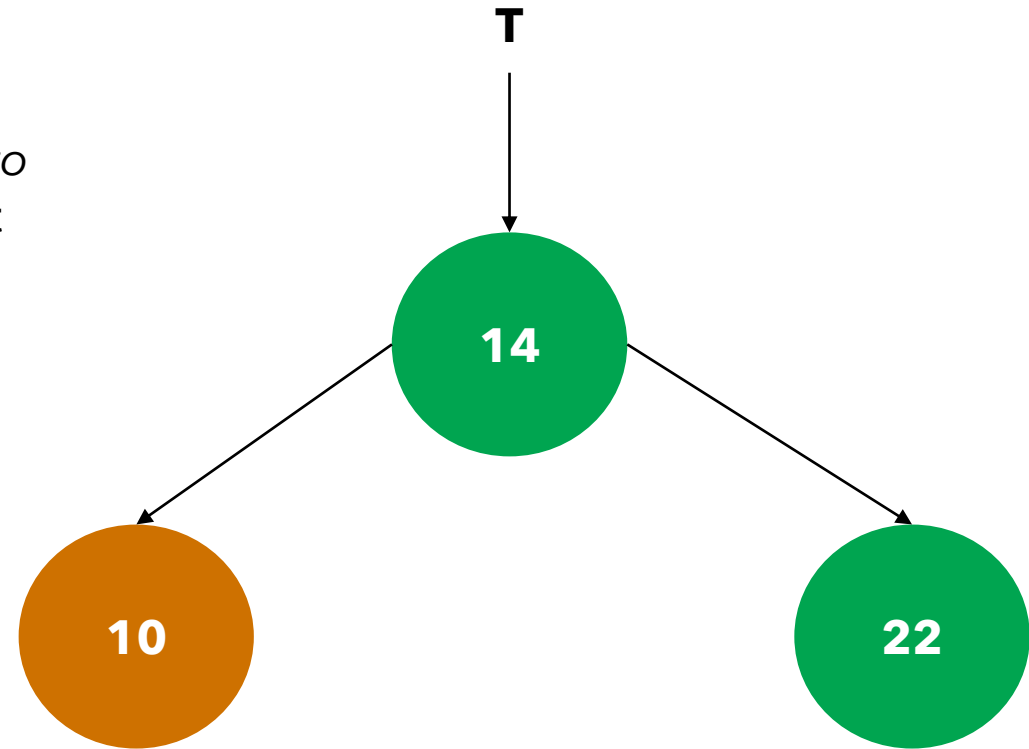
**caso ricorsivo:** si inserisce un nuovo nodo *al posto giusto* (come foglia) all'interno del sottoalbero `T.right`



# BST – inserimento ricorsivo

`bst_insert(T, 10)`

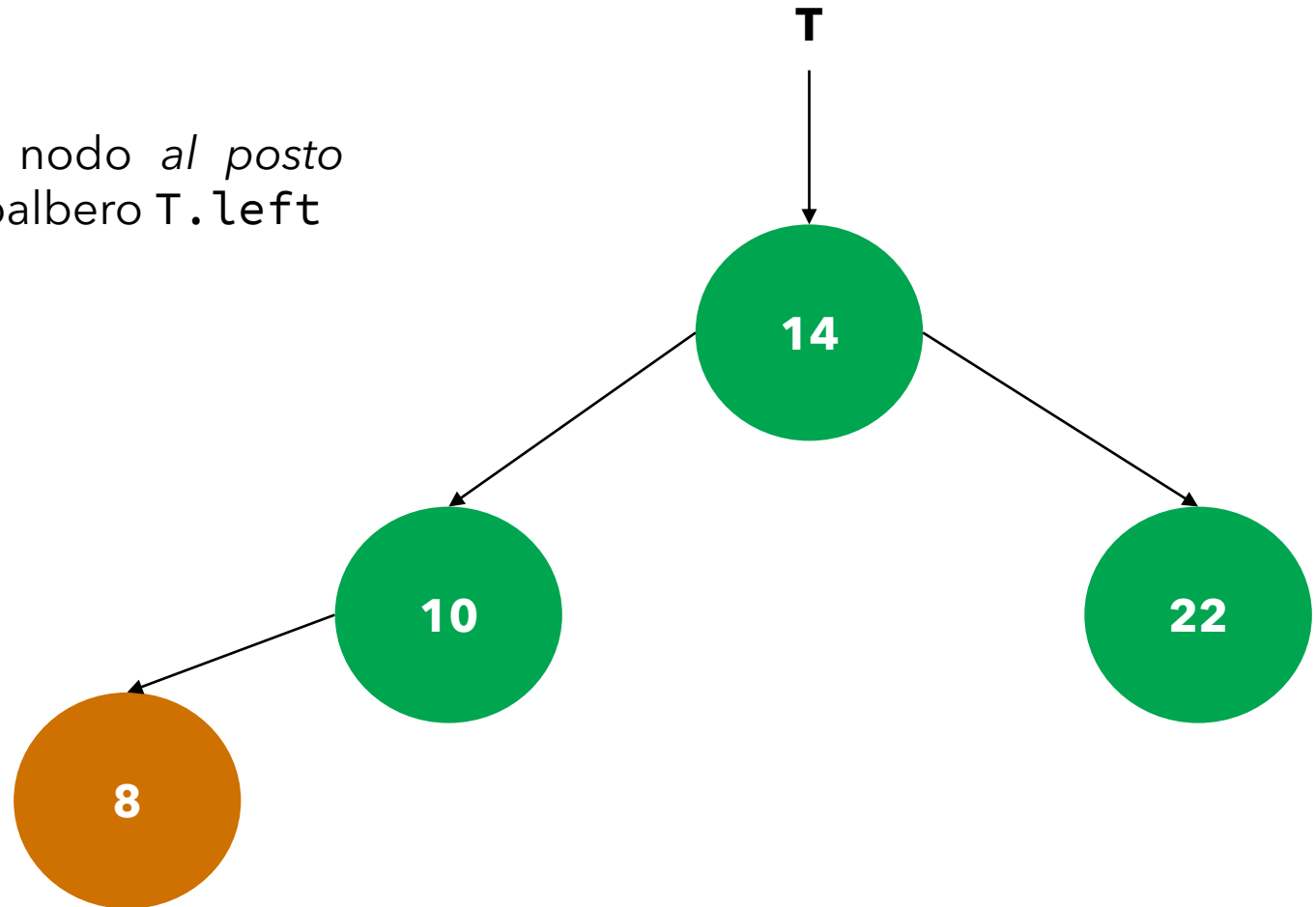
**caso ricorsivo:** si inserisce un nuovo nodo *al posto giusto* (come foglia) all'interno del sottoalbero `T.left`



# BST – inserimento ricorsivo

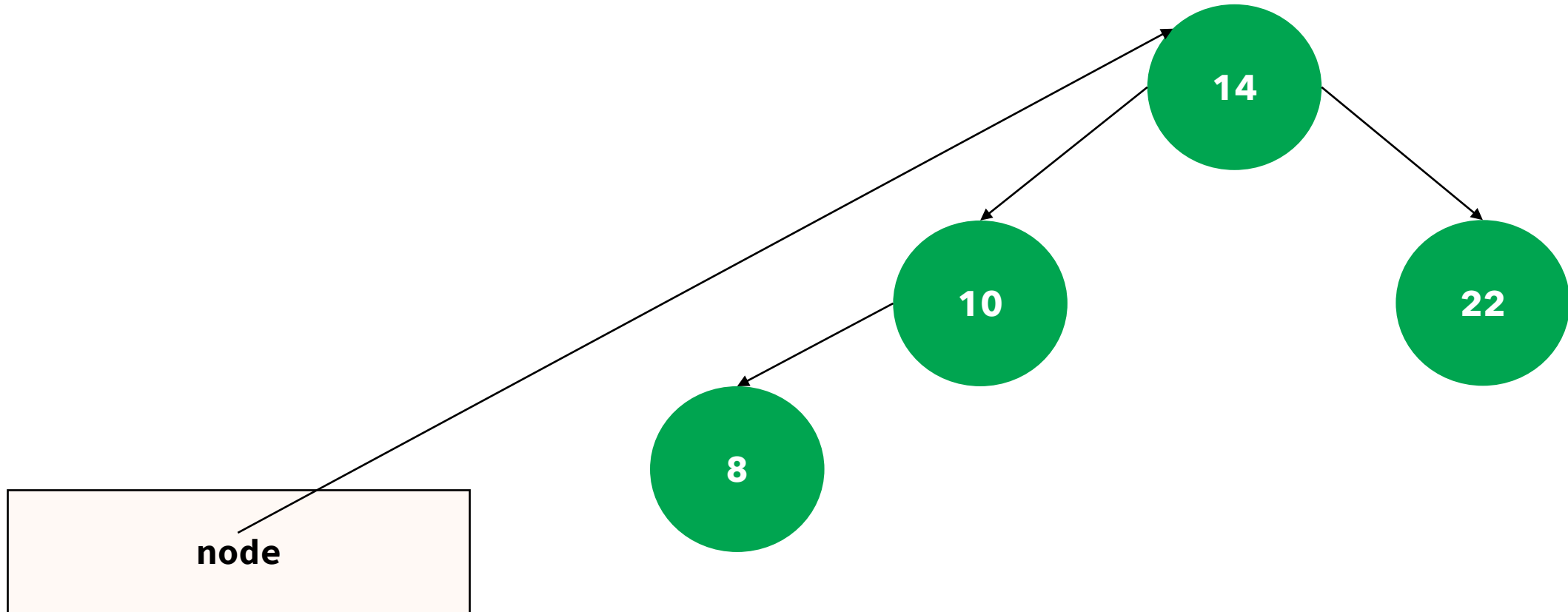
`bst_insert(T, 8)`

**caso ricorsivo:** si inserisce un nuovo nodo *al posto giusto* (come foglia) all'interno del sottoalbero `T.left`



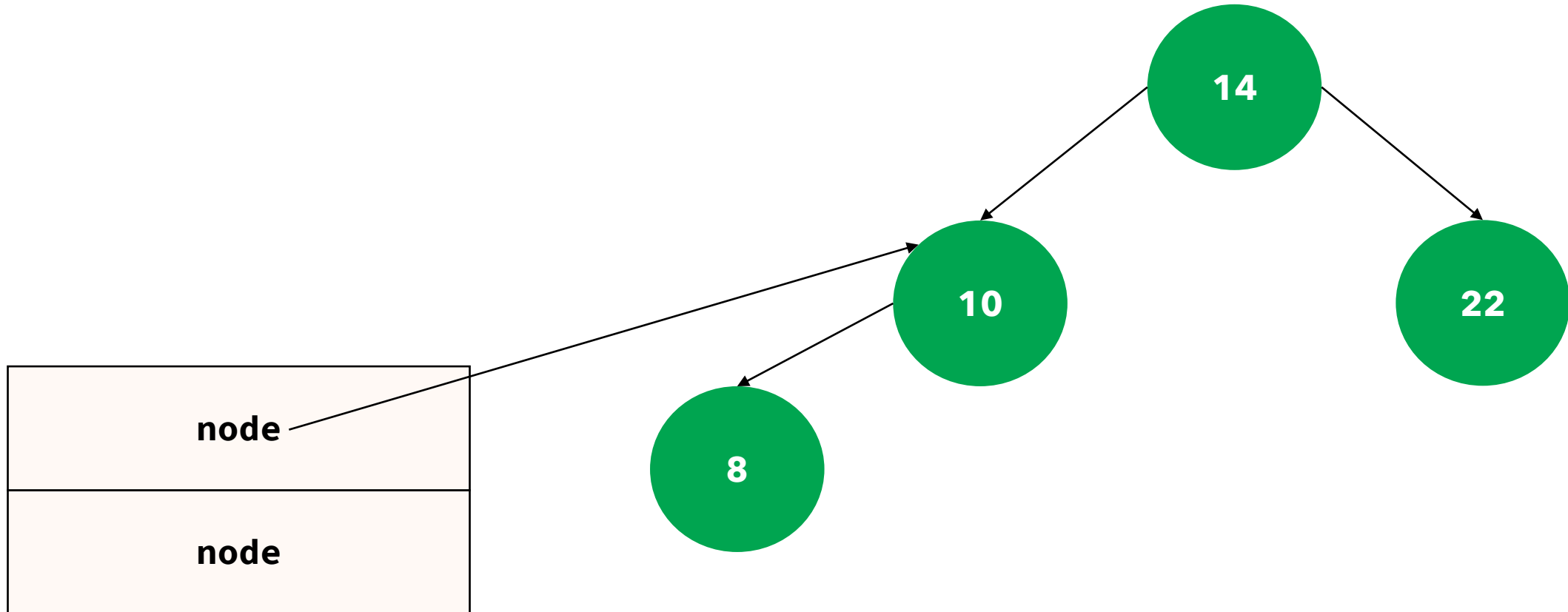
# BST – inserimento ricorsivo

`bst_insert(node, 6)`



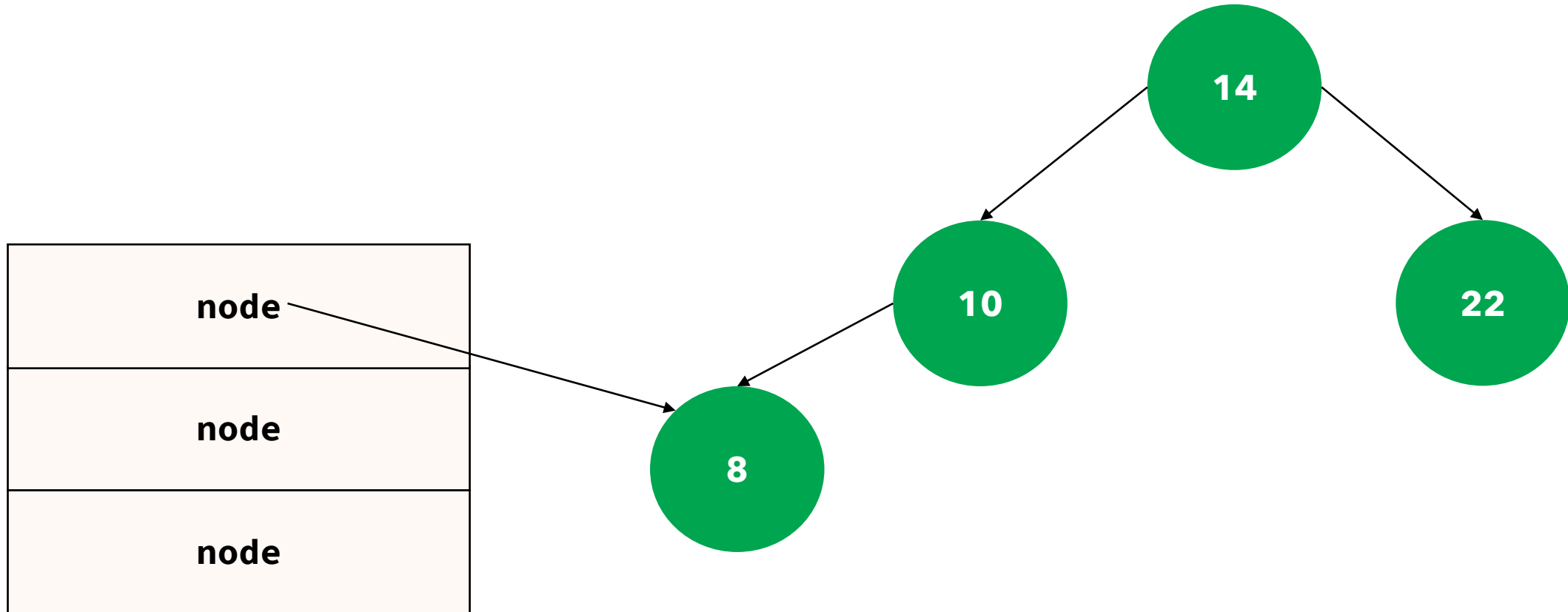
# BST – inserimento ricorsivo

`bst_insert(node, 6)`



# BST – inserimento ricorsivo

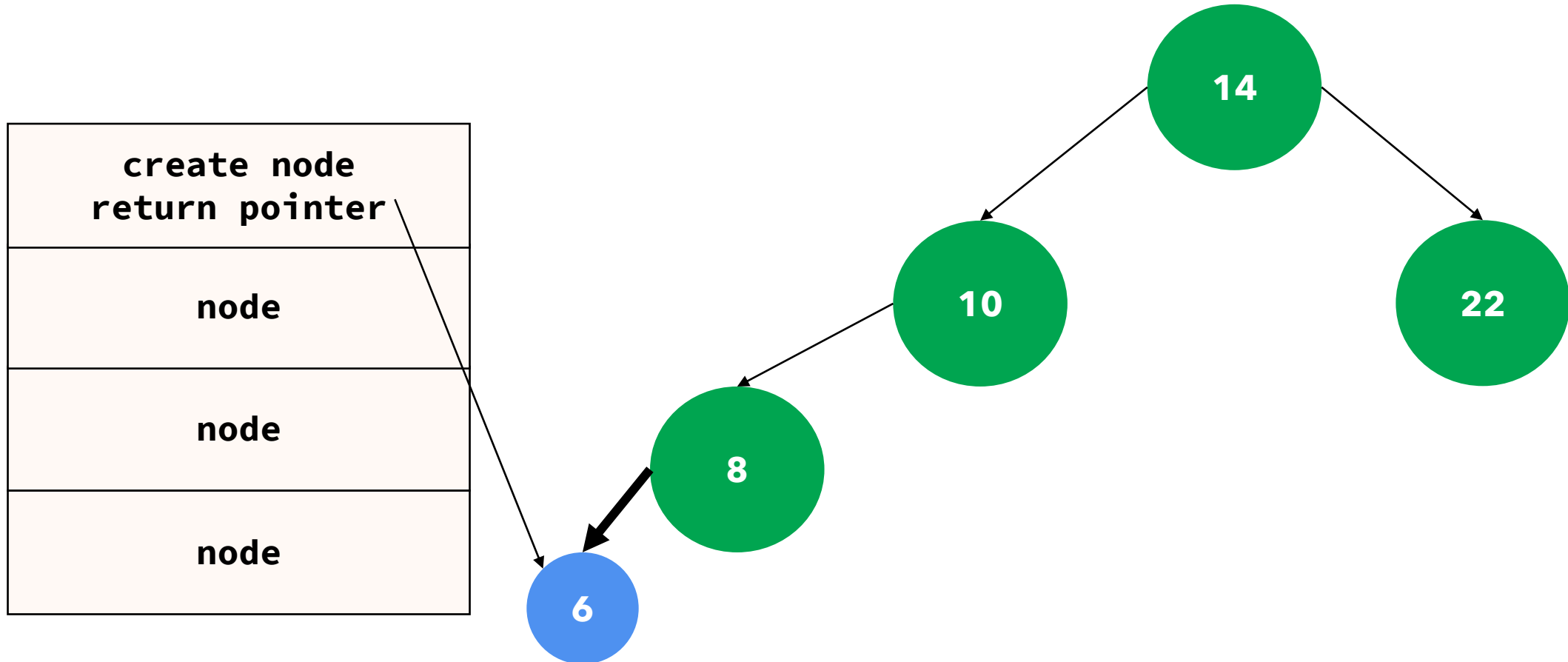
`bst_insert(node, 6)`





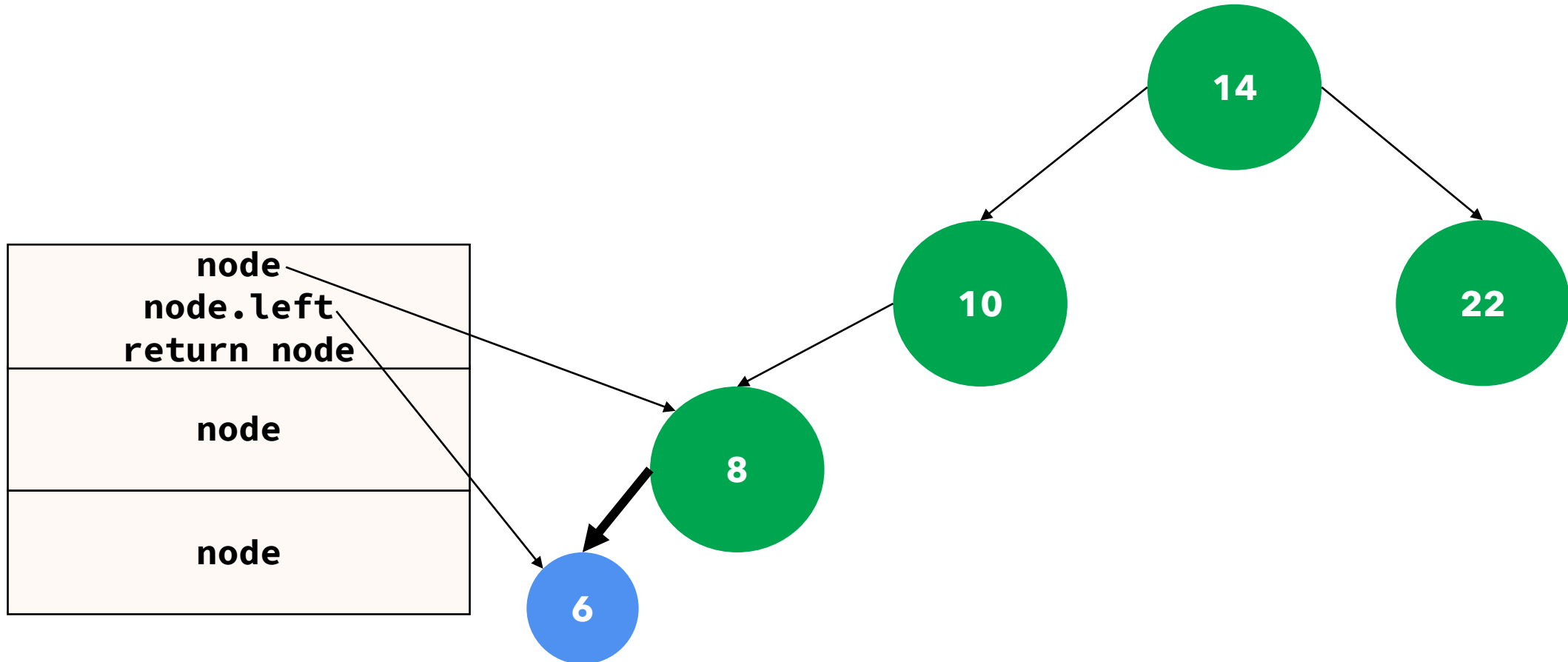
# BST – inserimento ricorsivo

`bst_insert(node, 6)`



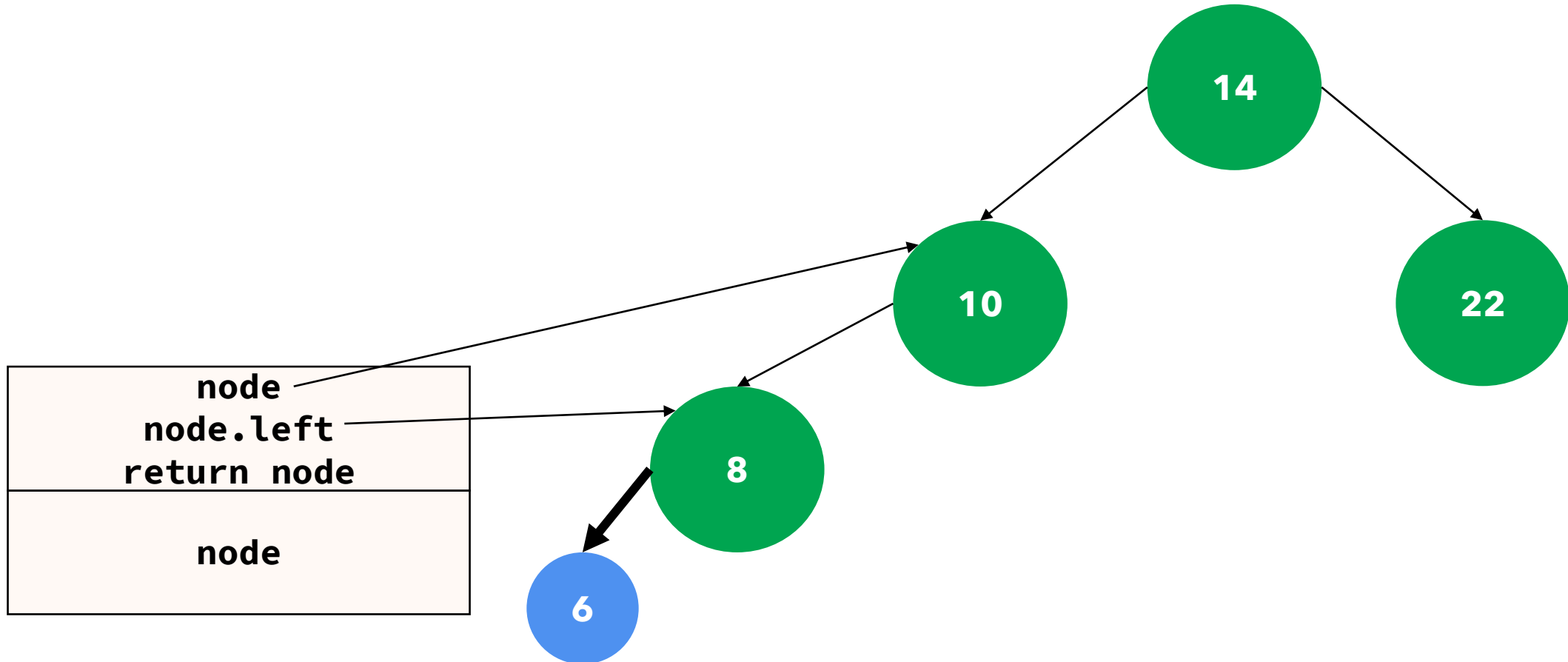
# BST – inserimento ricorsivo

`bst_insert(node, 6)`



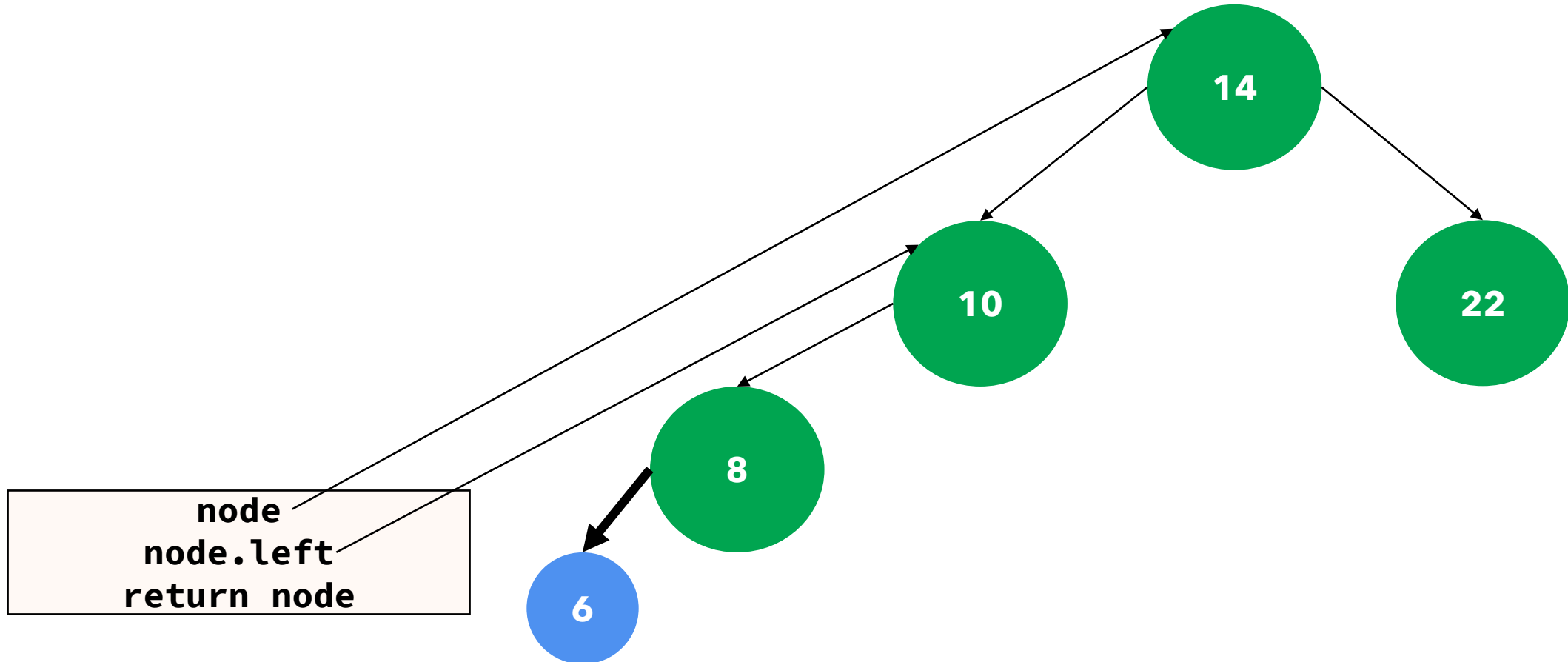
# BST – inserimento ricorsivo

`bst_insert(node, 6)`



# BST – inserimento ricorsivo

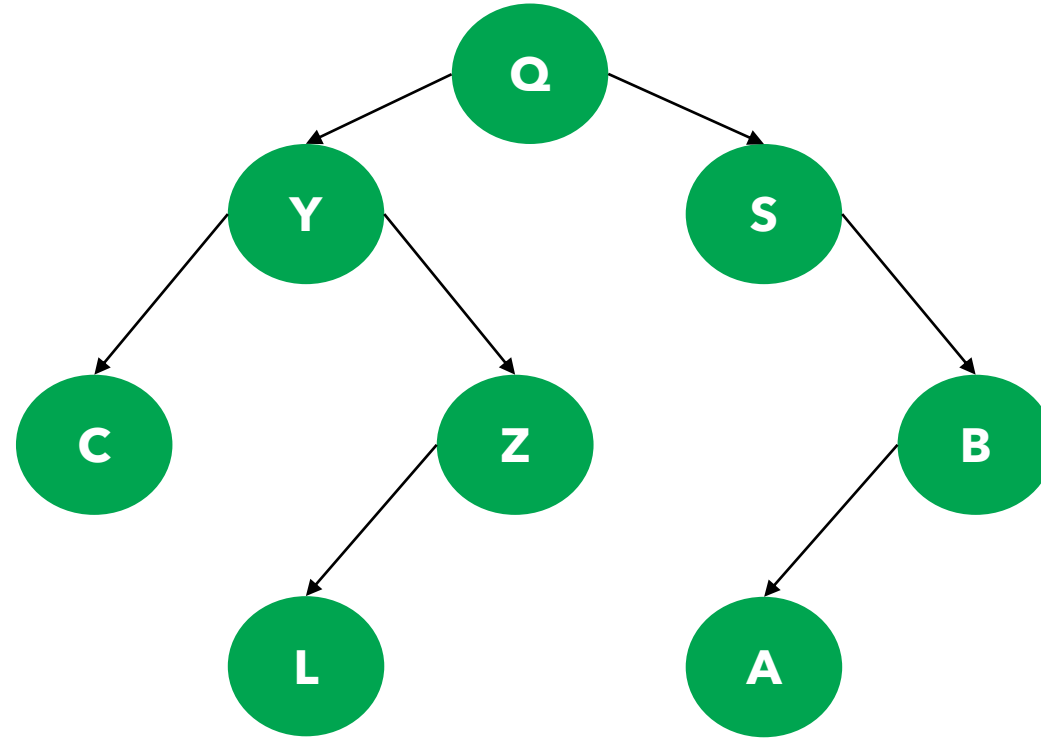
`bst_insert(node, 6)`



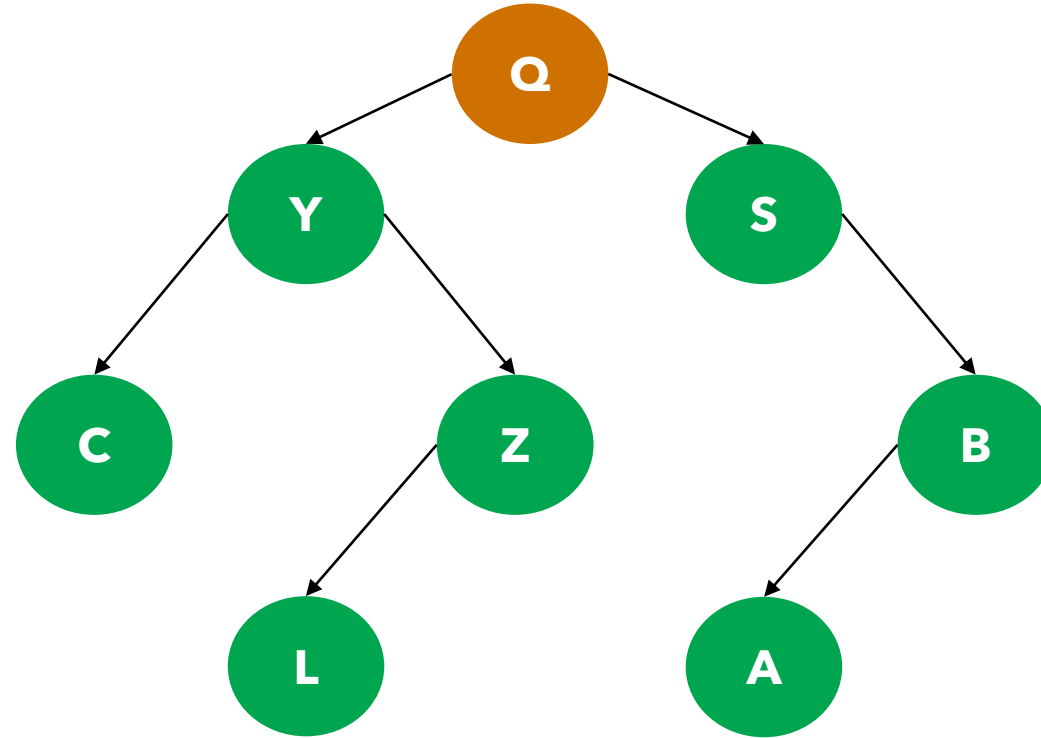
# Depth-first search (DFS)

- Nella ricerca in profondità (**depth-first**), per ogni nodo vengono visitati ricorsivamente in profondità prima il sottoalbero sinistro e poi il sottoalbero destro
- Questo significa che prima di *tornare indietro* ad un nodo T, uno dei due sottoalberi di T deve essere visitato completamente
- Per tornare indietro fino al punto giusto e non ripetere gli stessi percorsi serve uno **stack**. Ovviamente, la ricorsione ci aiuta molto, perché si basa sul call stack del programma
- Esistono diverse versioni della ricerca in profondità:
  - visita **preorder**
  - visita **inorder**
  - visita **postorder**

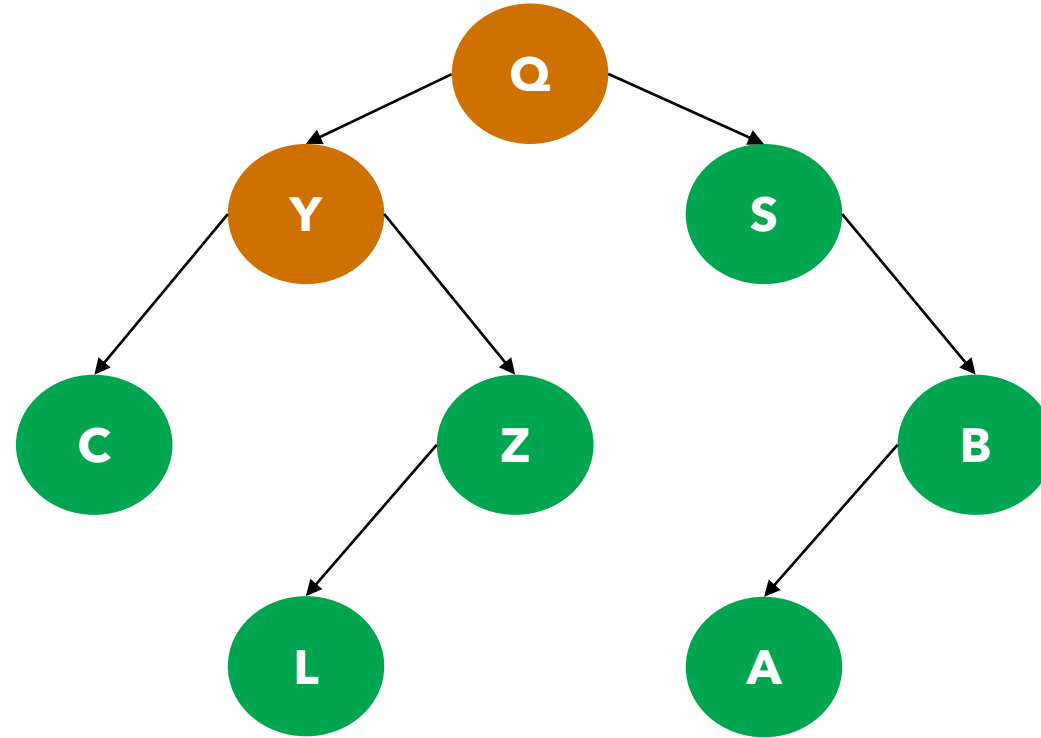
# Depth-first search (DFS)



# Depth-first search (DFS)

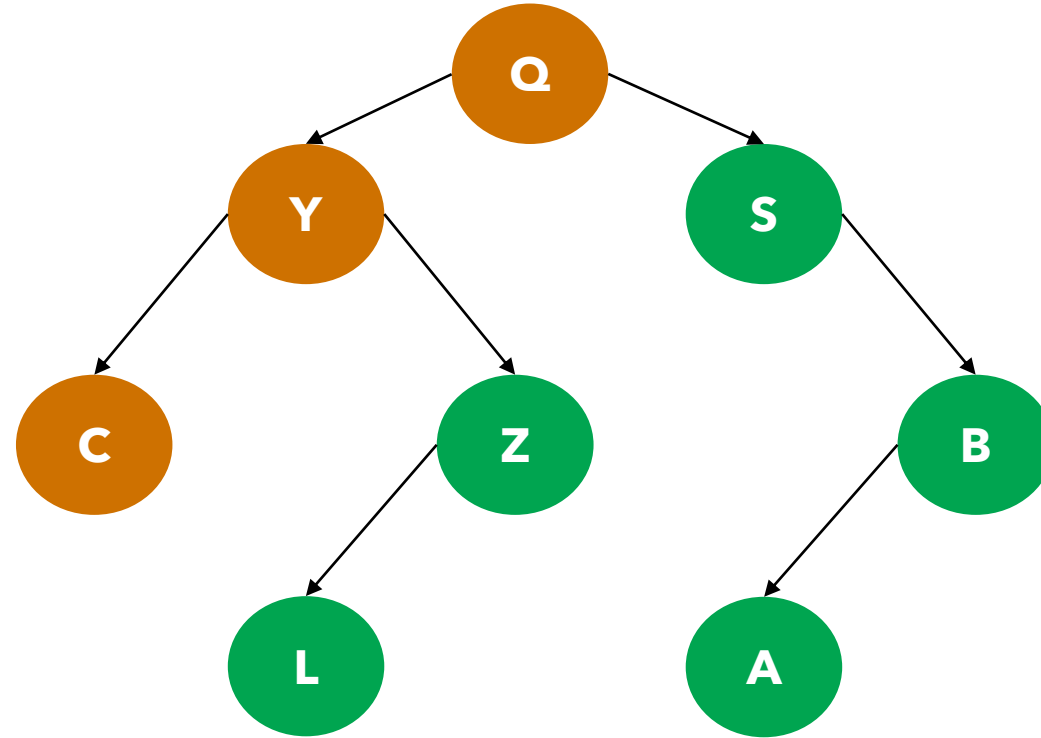


# Depth-first search (DFS)

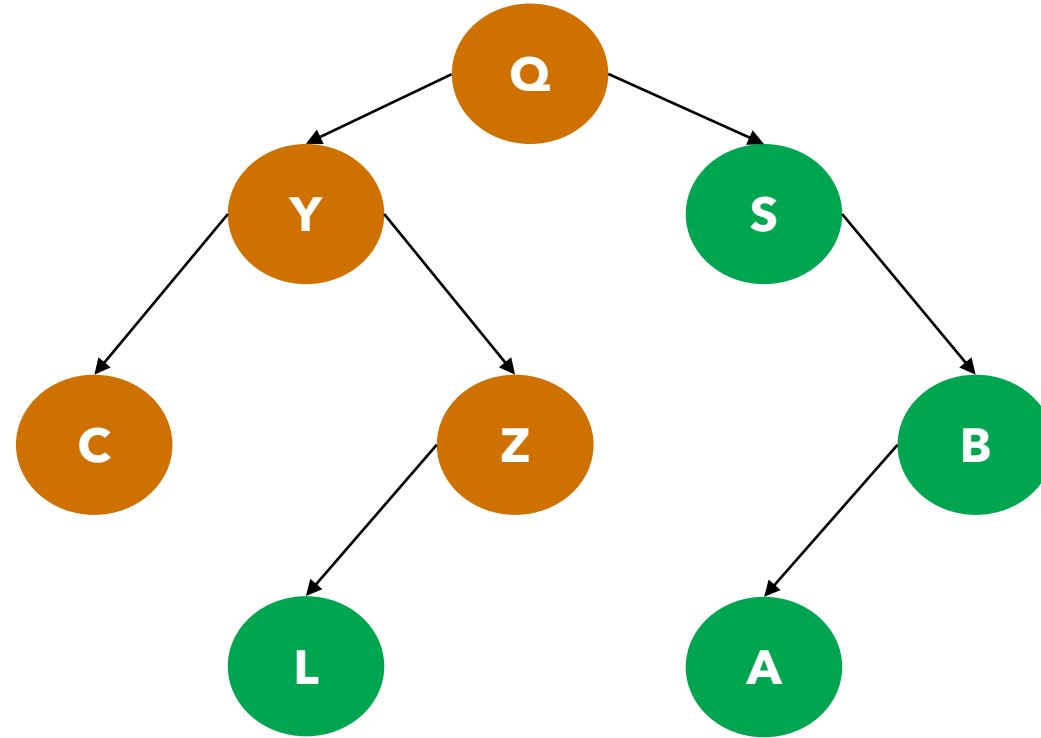




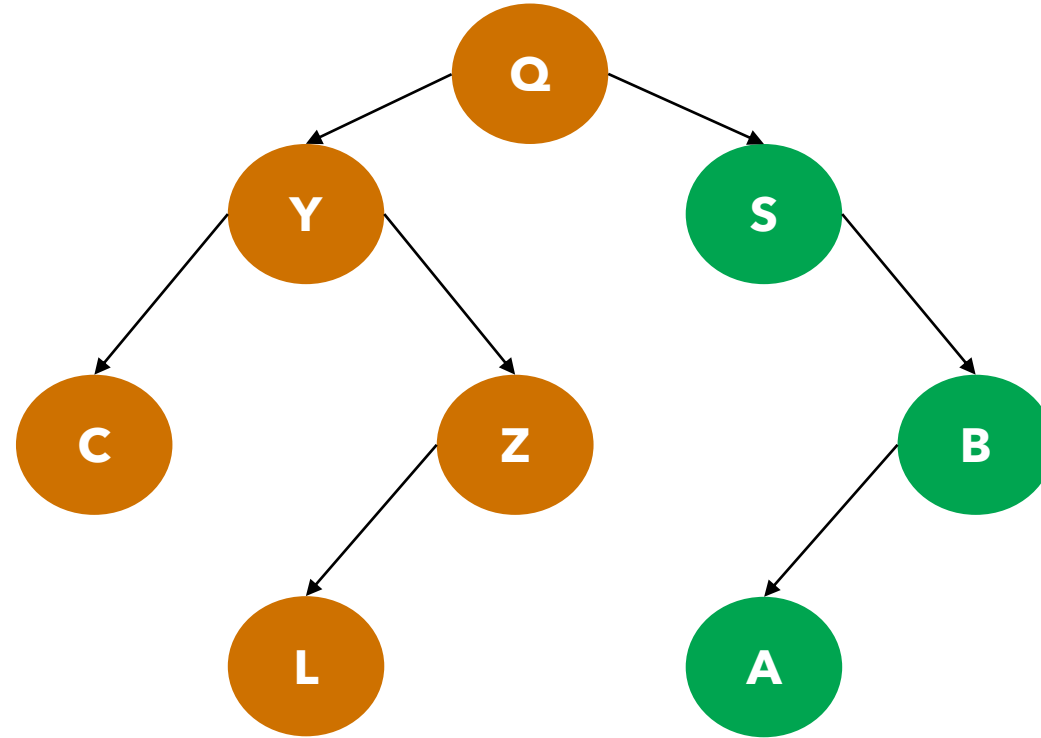
# Depth-first search (DFS)



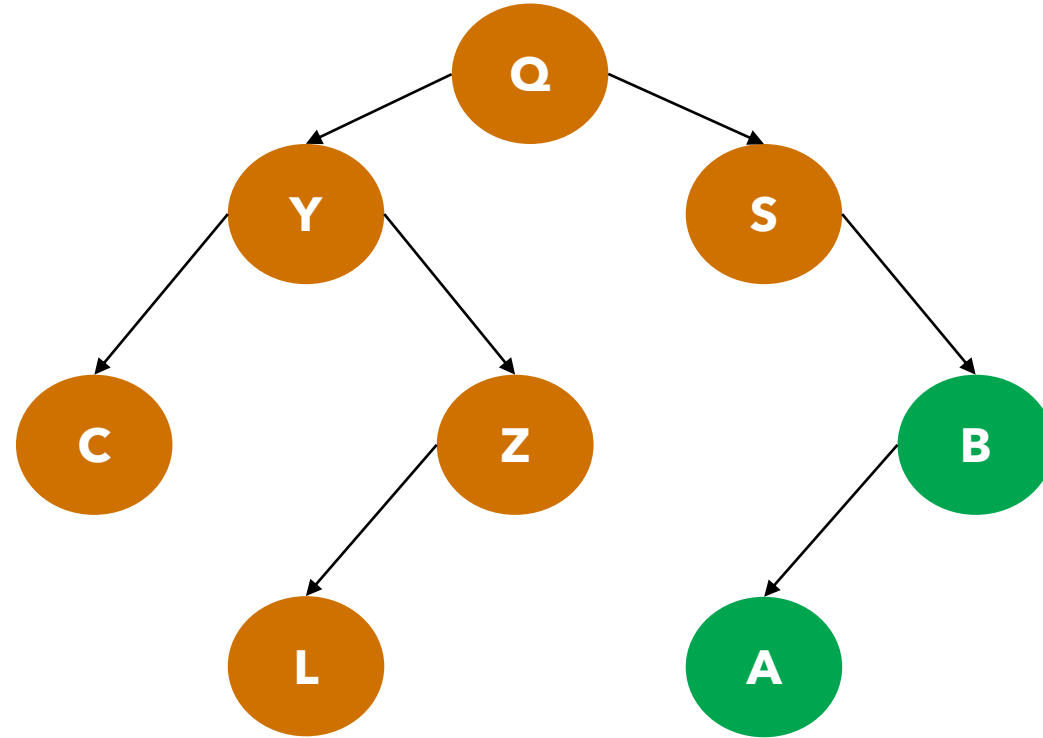
# Depth-first search (DFS)



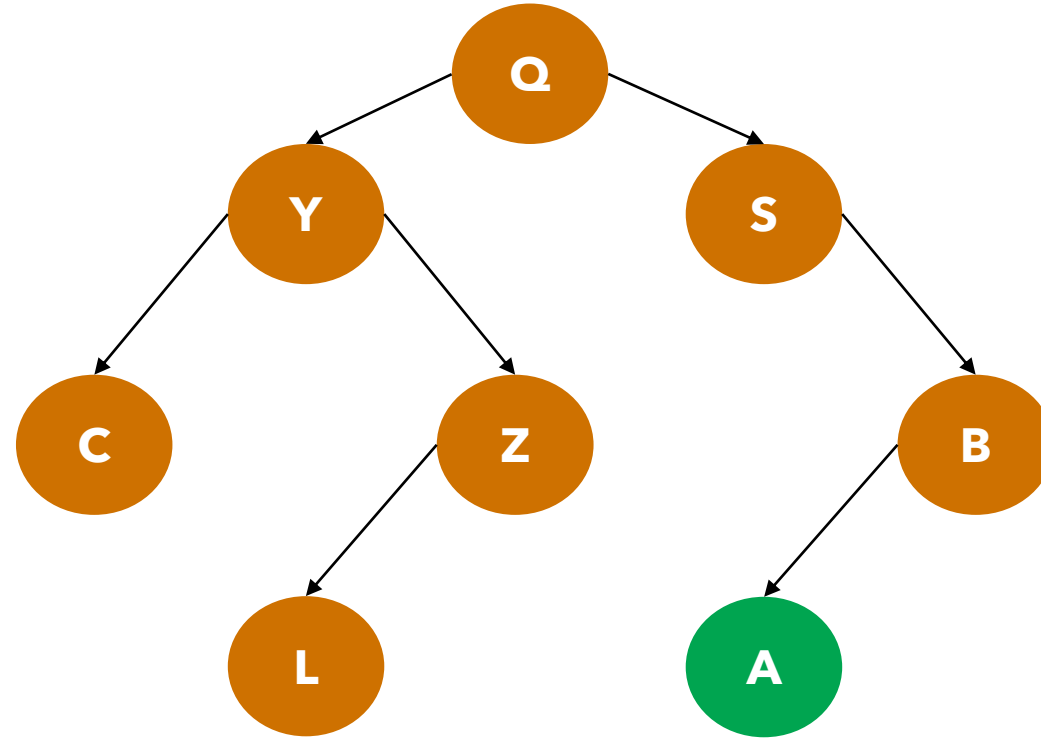
# Depth-first search (DFS)



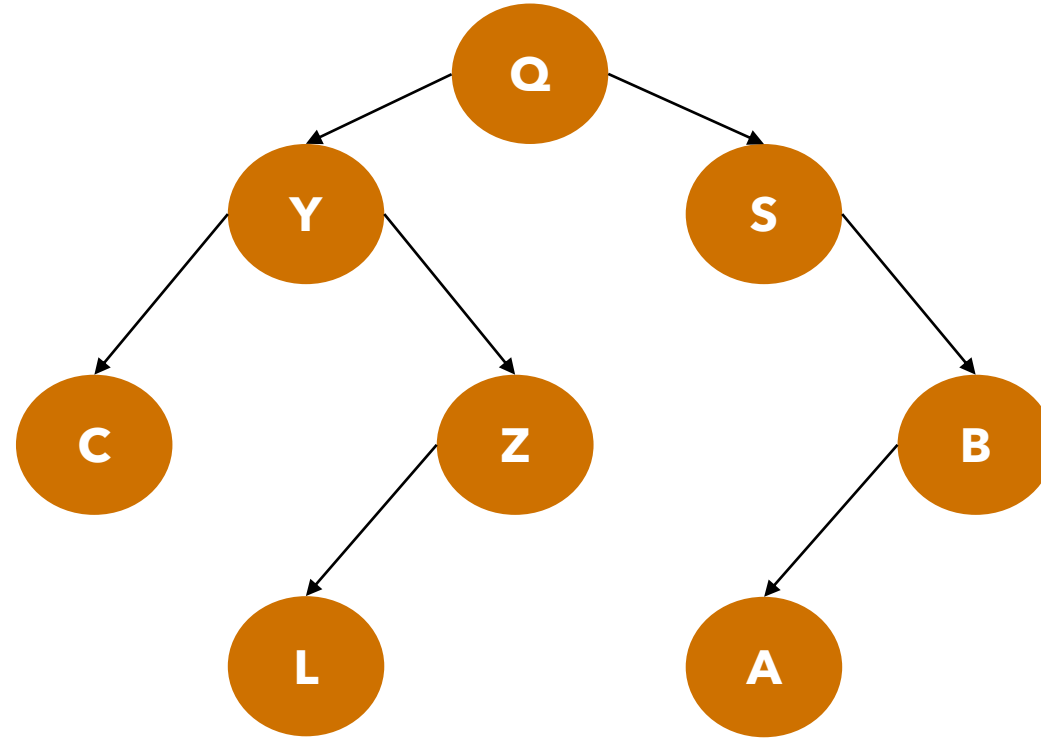
# Depth-first search (DFS)



# Depth-first search (DFS)



# Depth-first search (DFS)

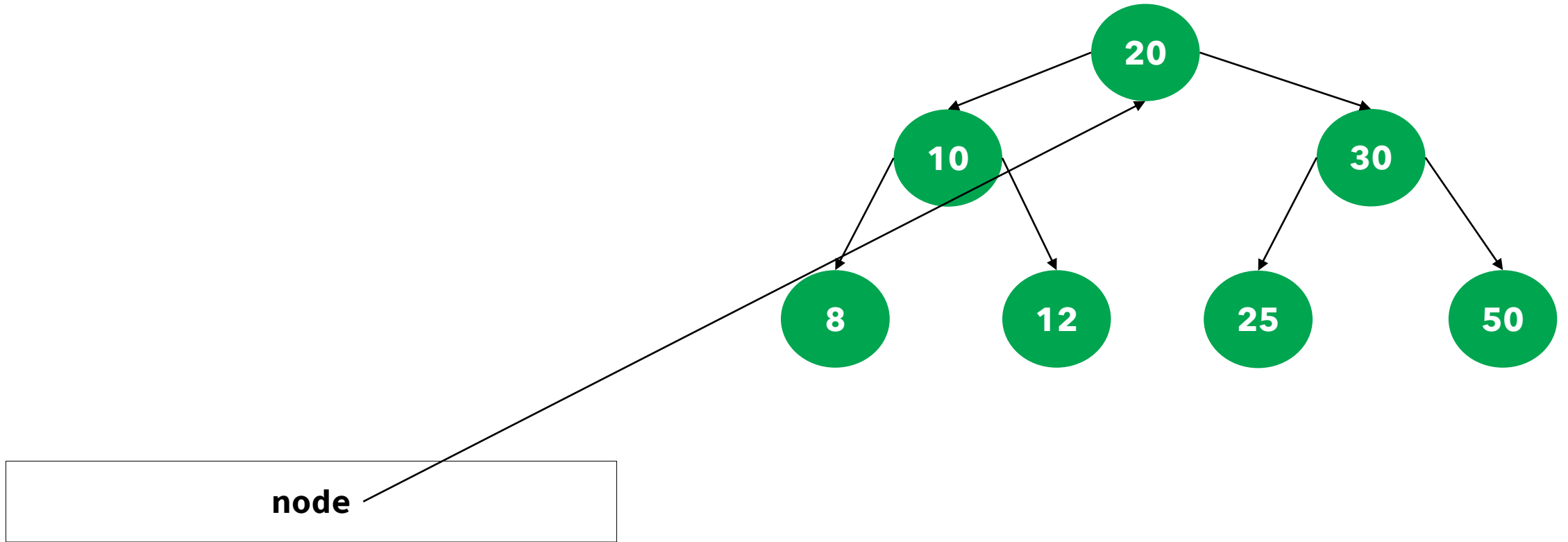


# Depth-first search (DFS): inorder

`inorder_tree_walk(T):`

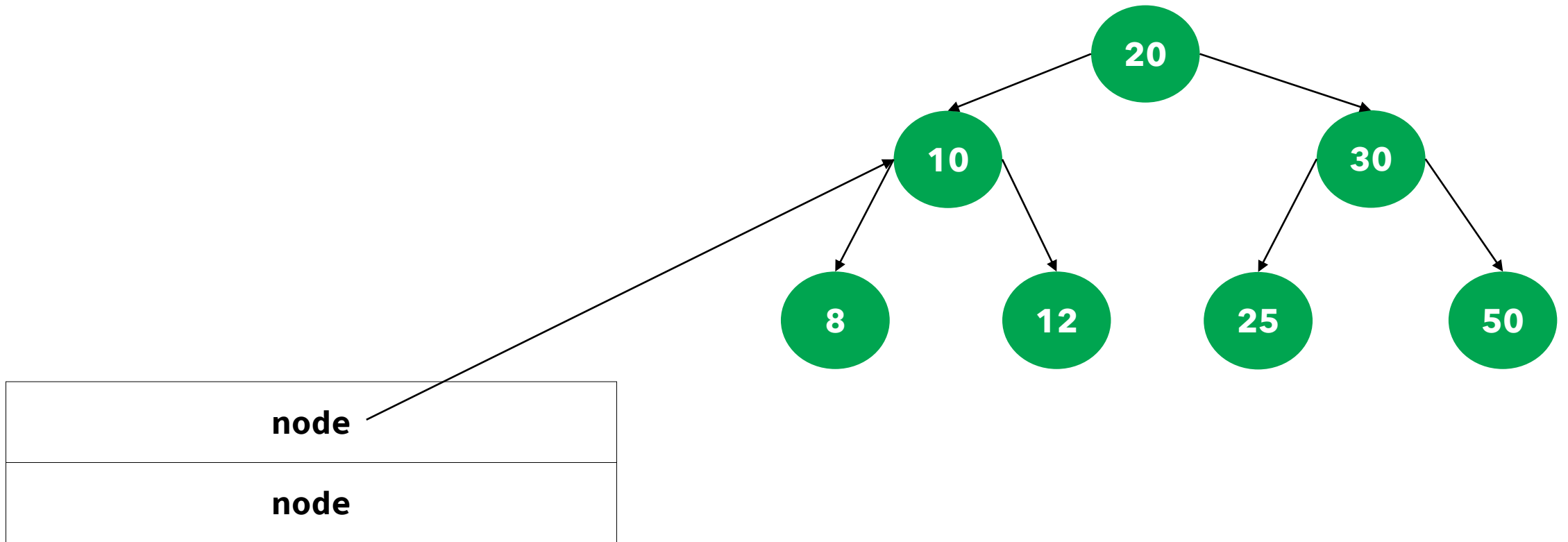
- if `T` is empty, do nothing
- otherwise:
  - call `inorder_tree_walk` on `T.left`
  - *open* `T` (e.g.: `print T.key`)
  - call `inorder_tree_walk` on `T.right`
- **NB:** su un BST stampa le chiavi in ordine ascendente

# Depth-first search (DFS): inorder

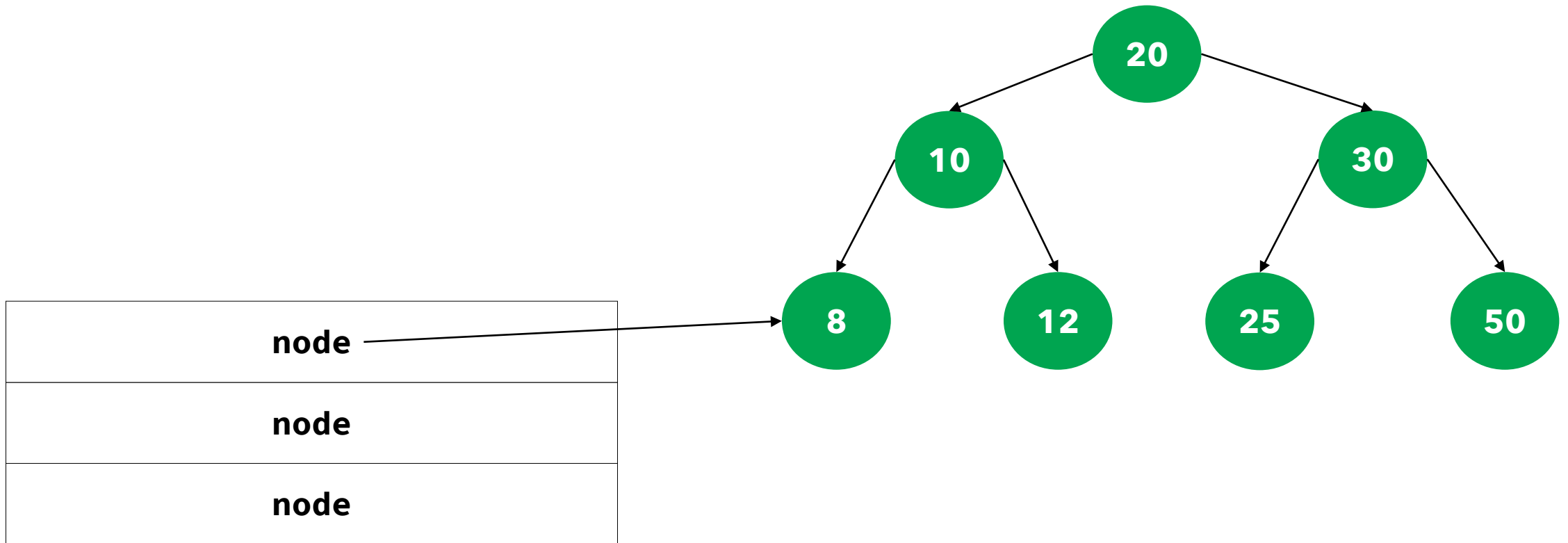




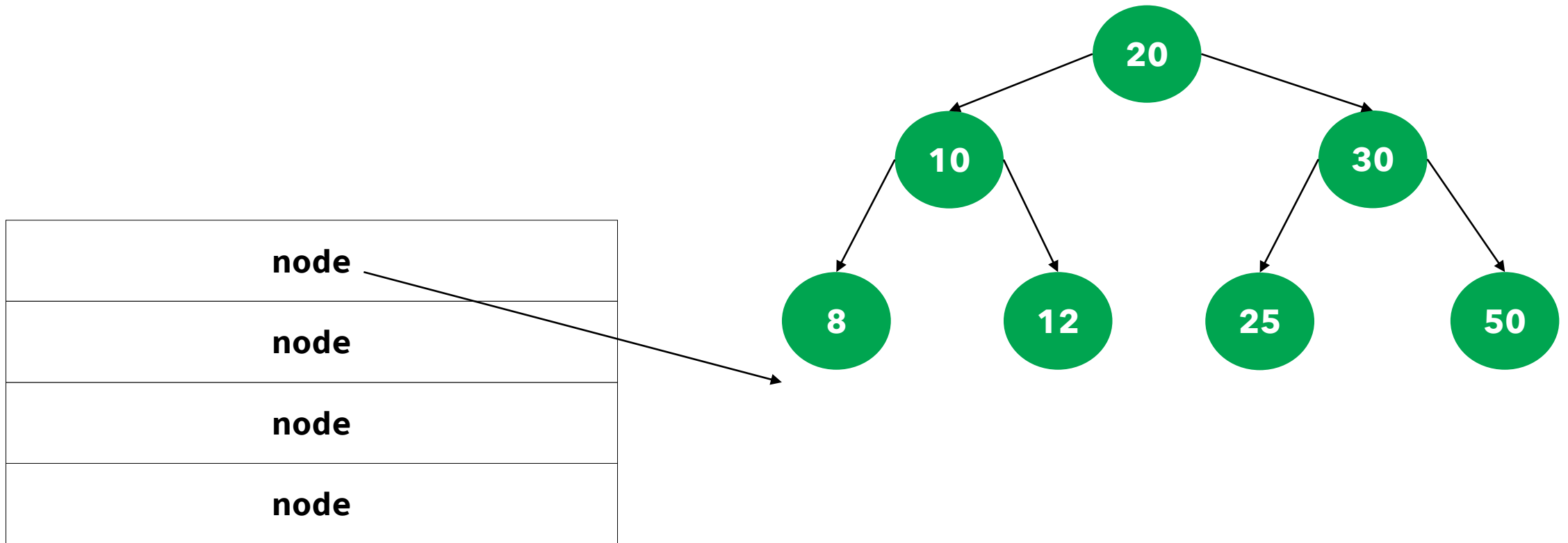
# Depth-first search (DFS): inorder



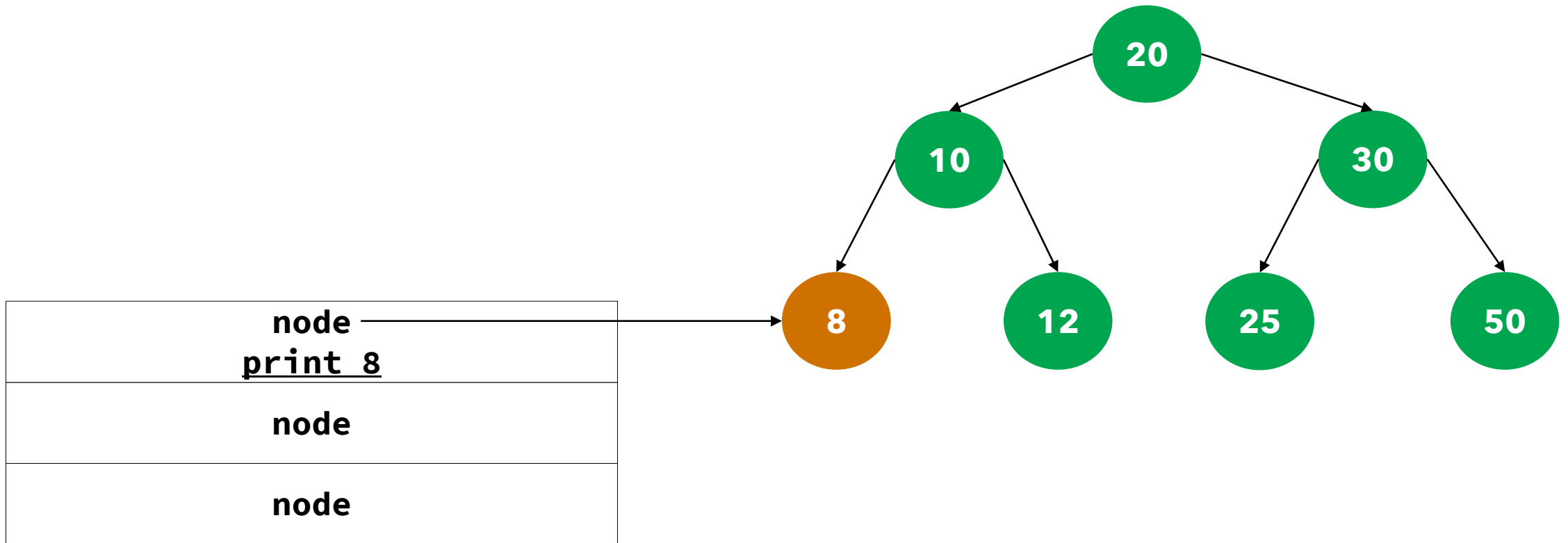
# Depth-first search (DFS): inorder



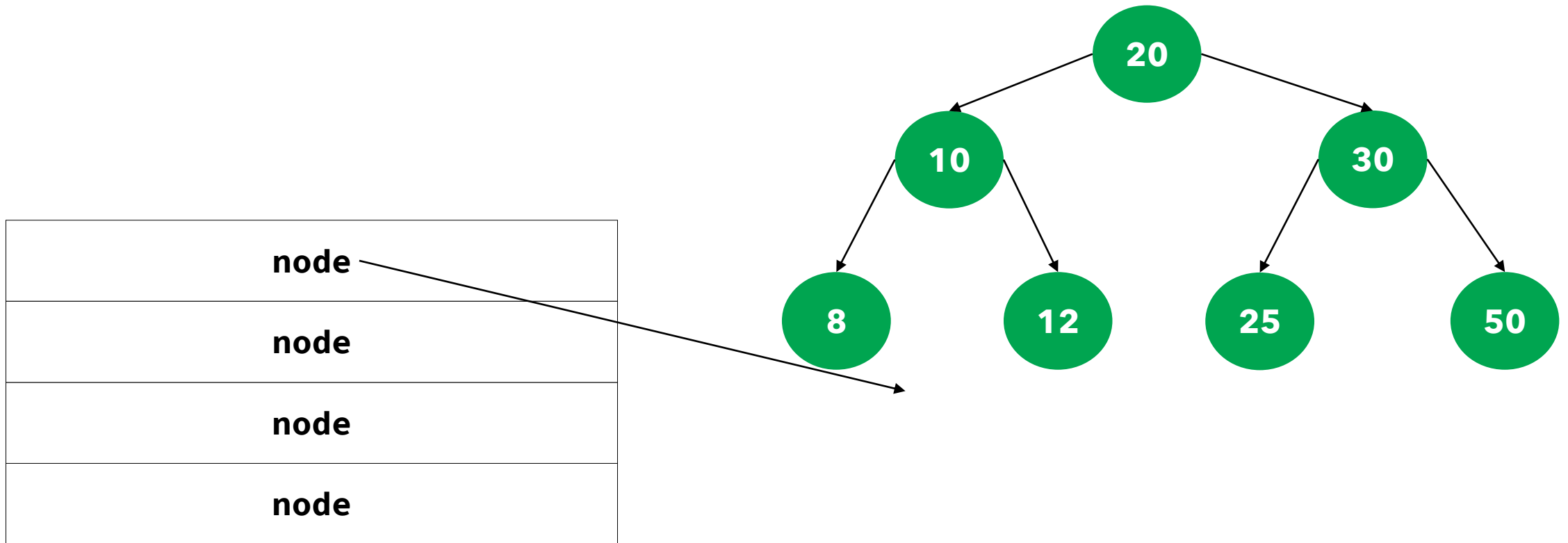
# Depth-first search (DFS): inorder



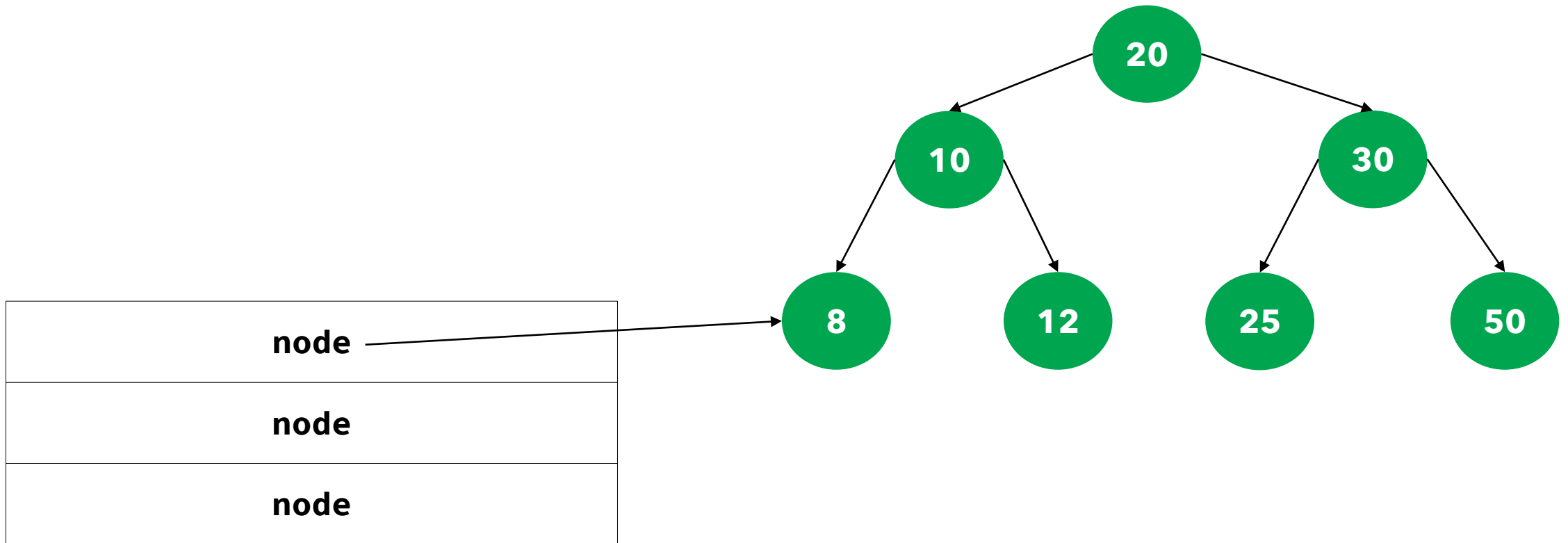
# Depth-first search (DFS): inorder



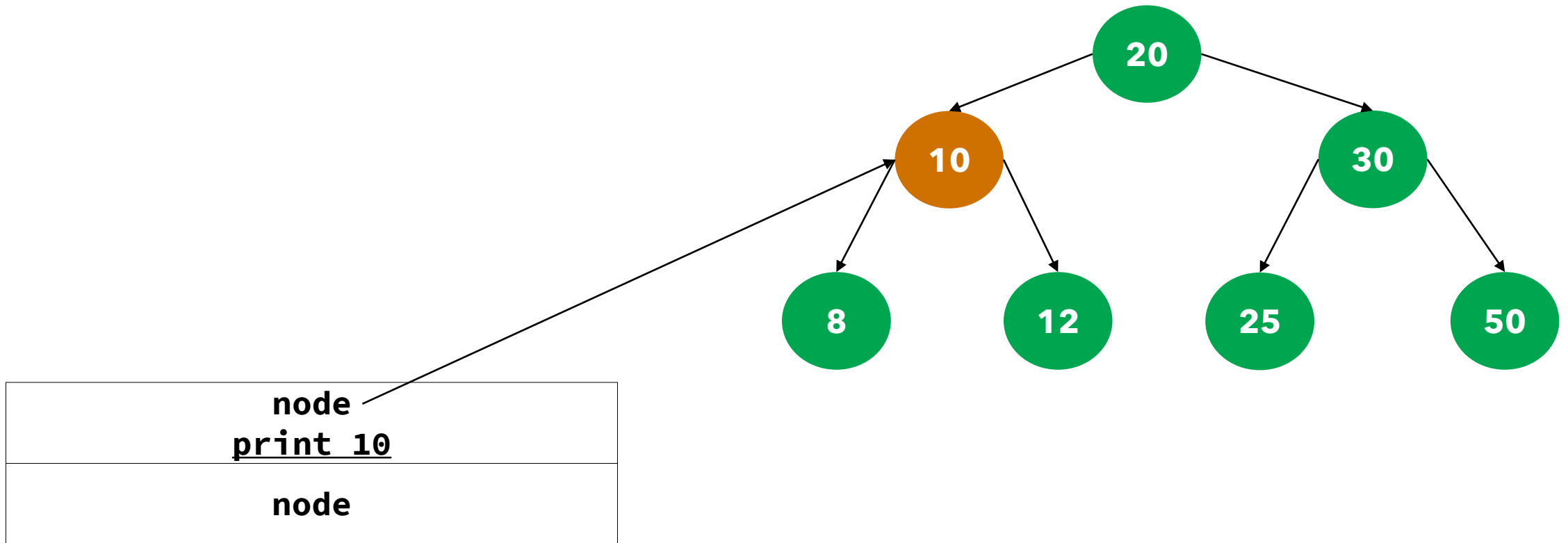
# Depth-first search (DFS): inorder



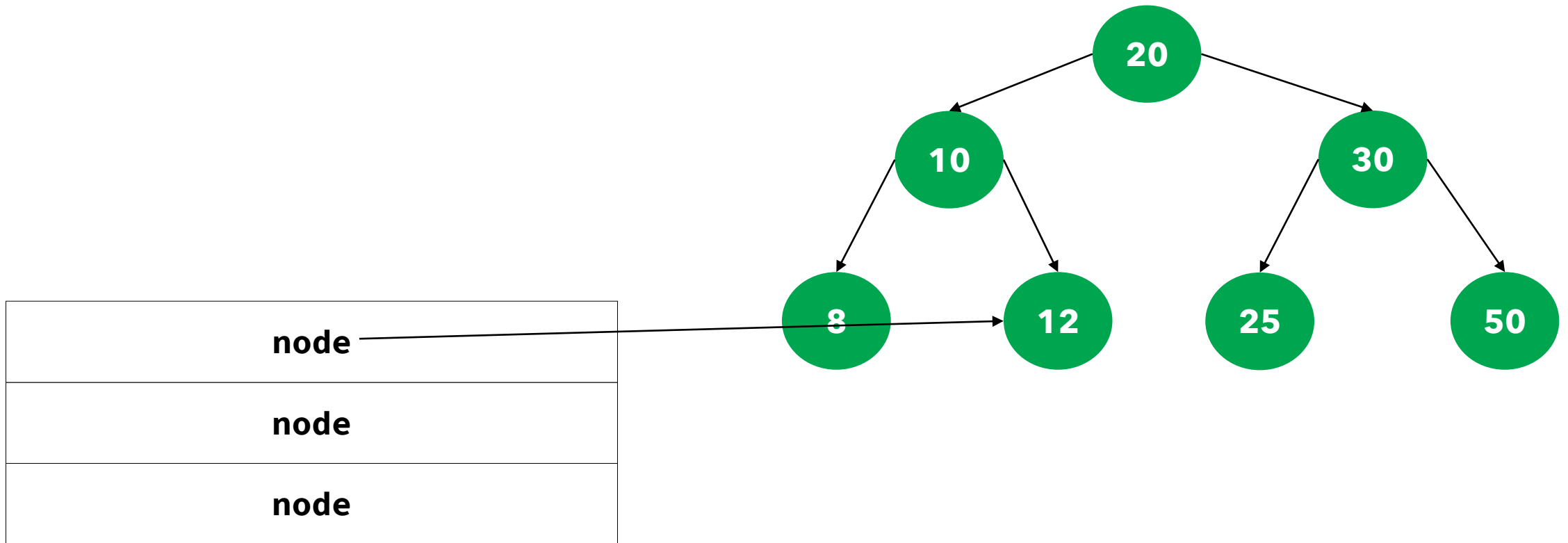
# Depth-first search (DFS): inorder



# Depth-first search (DFS): inorder

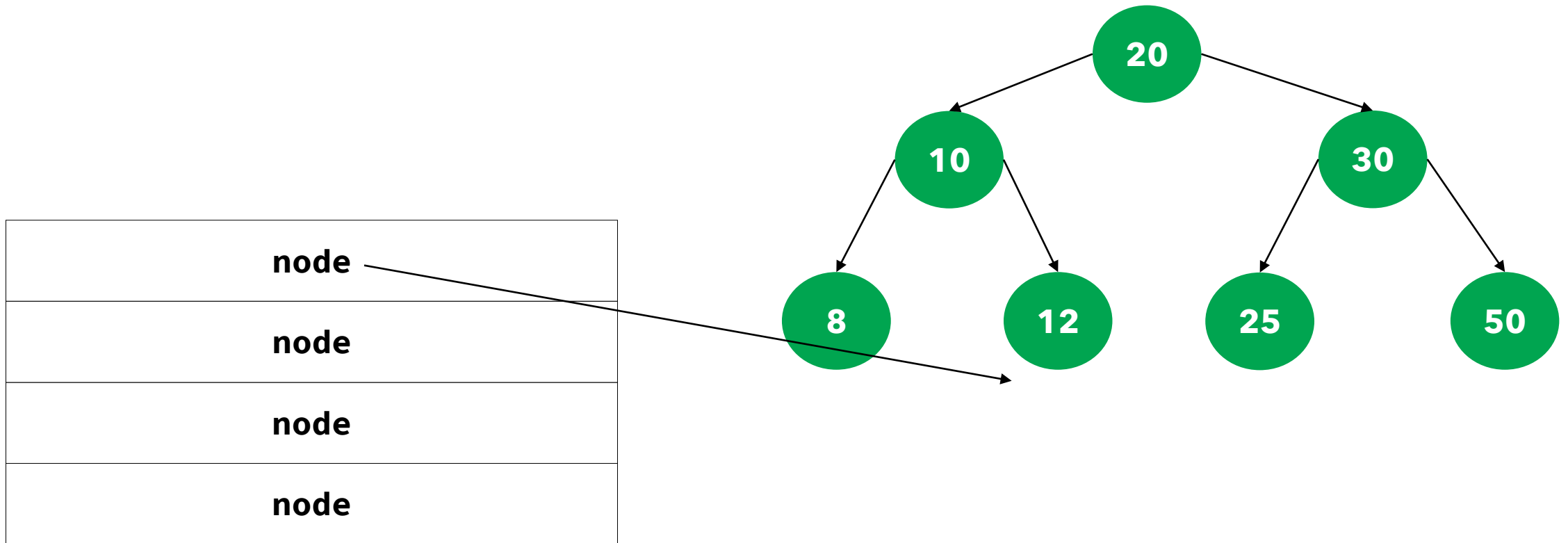


# Depth-first search (DFS): inorder

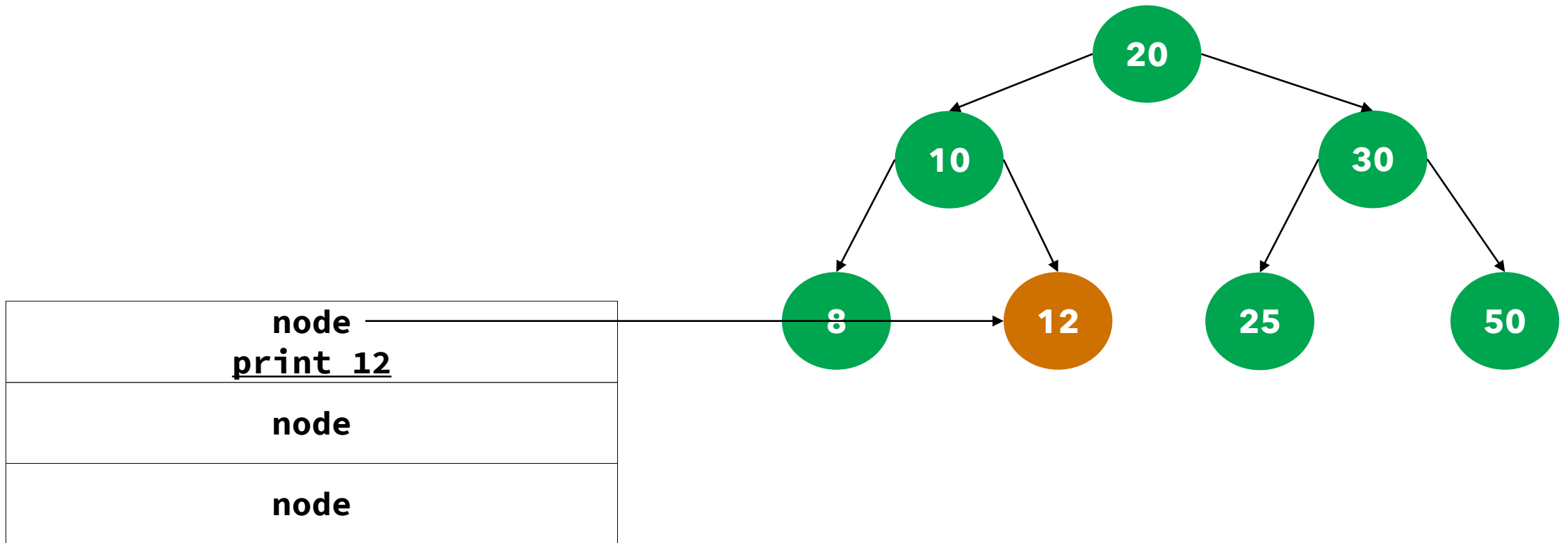




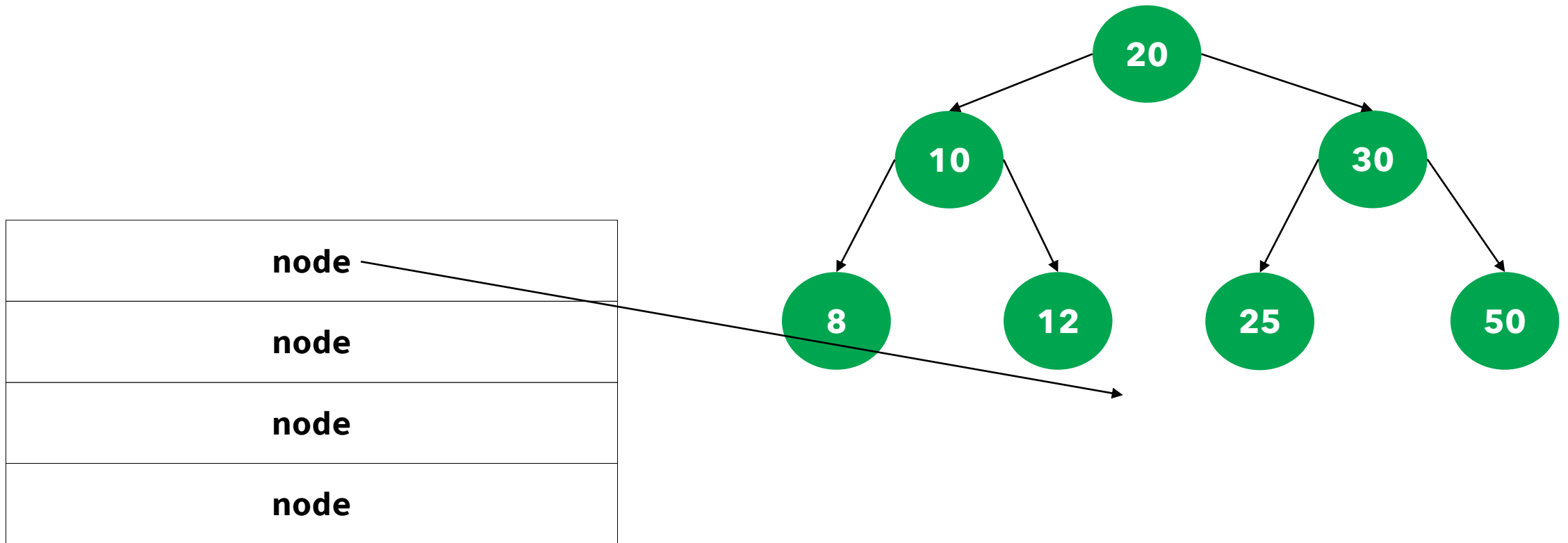
# Depth-first search (DFS): inorder



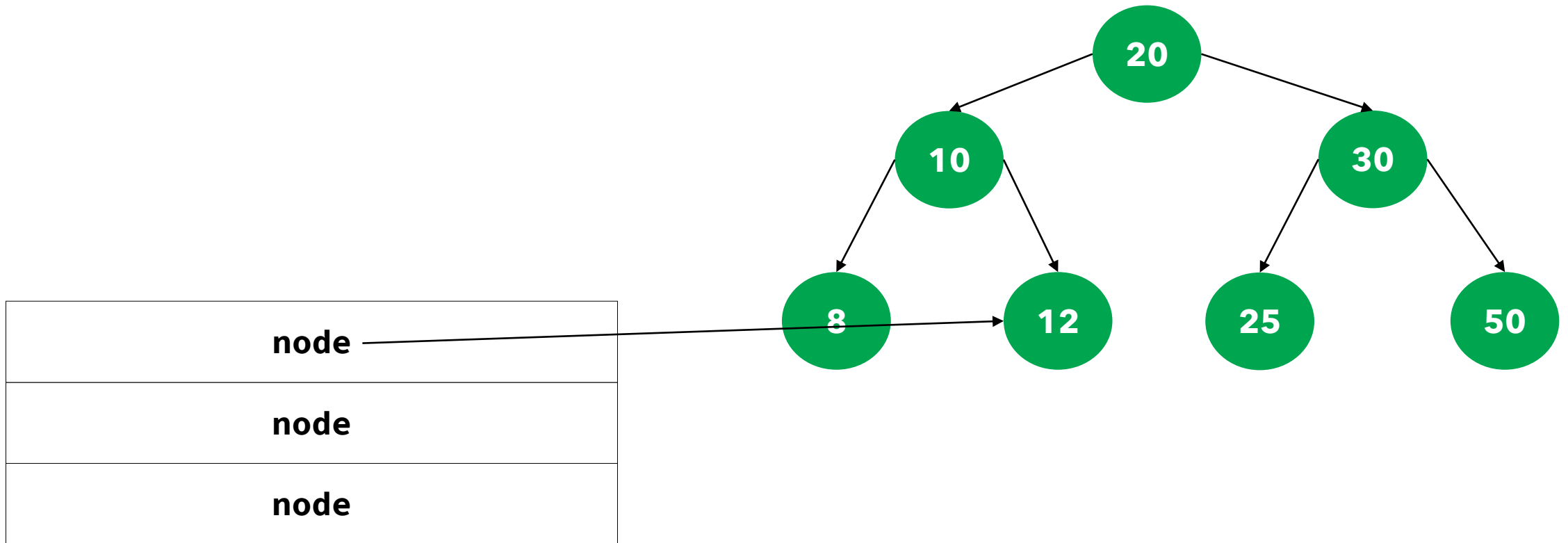
# Depth-first search (DFS): inorder



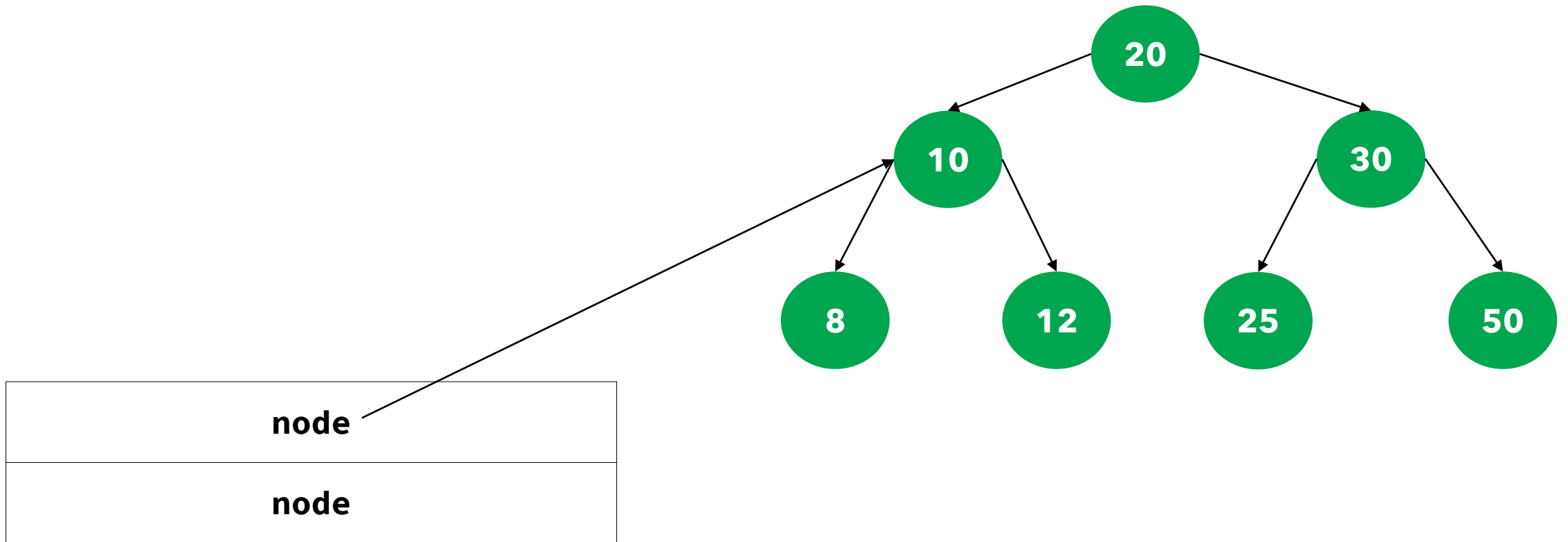
# Depth-first search (DFS): inorder



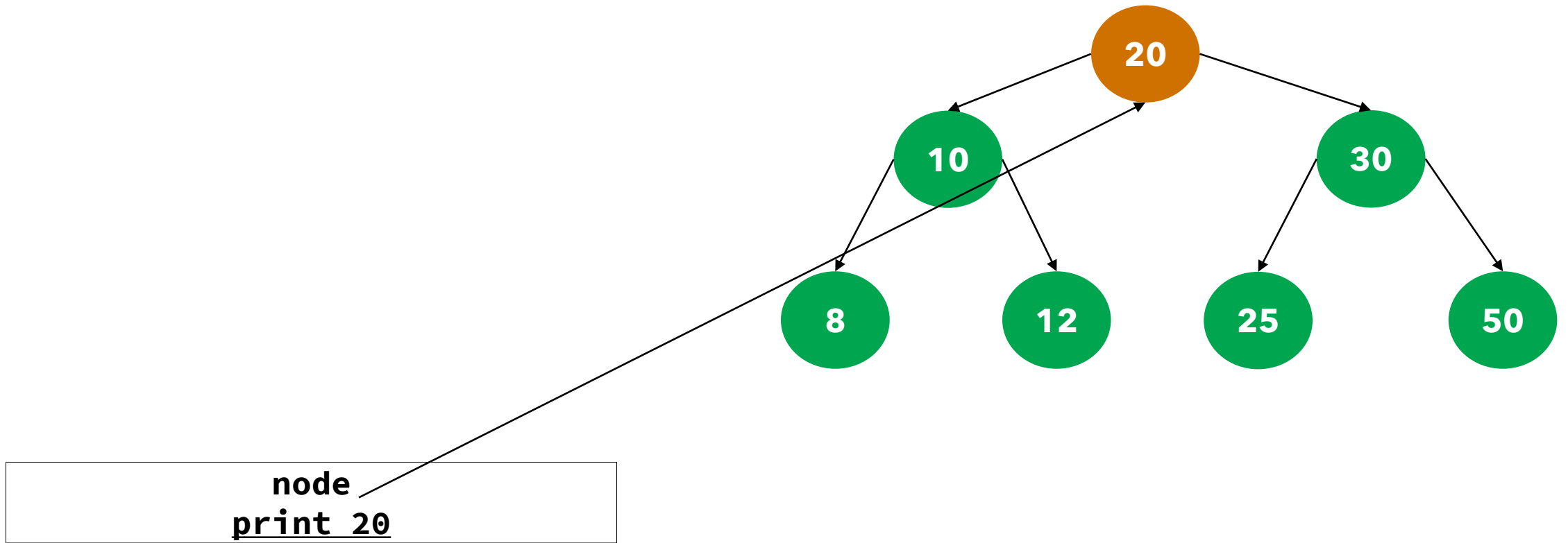
# Depth-first search (DFS): inorder



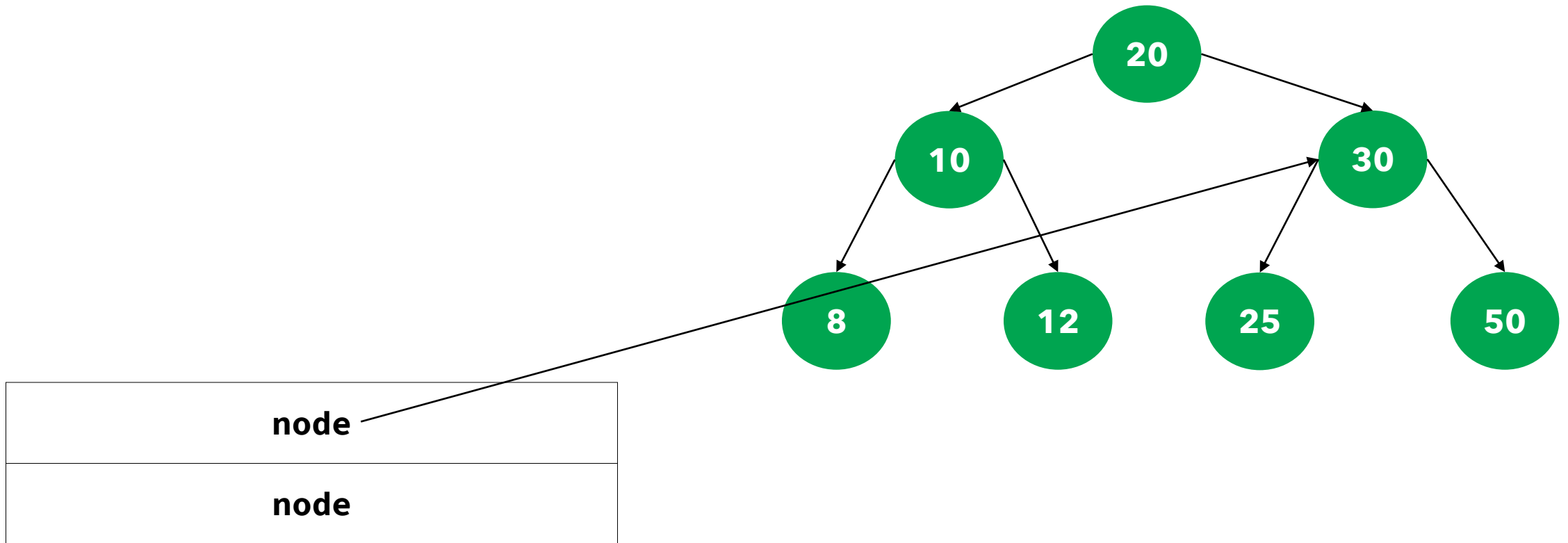
# Depth-first search (DFS): inorder



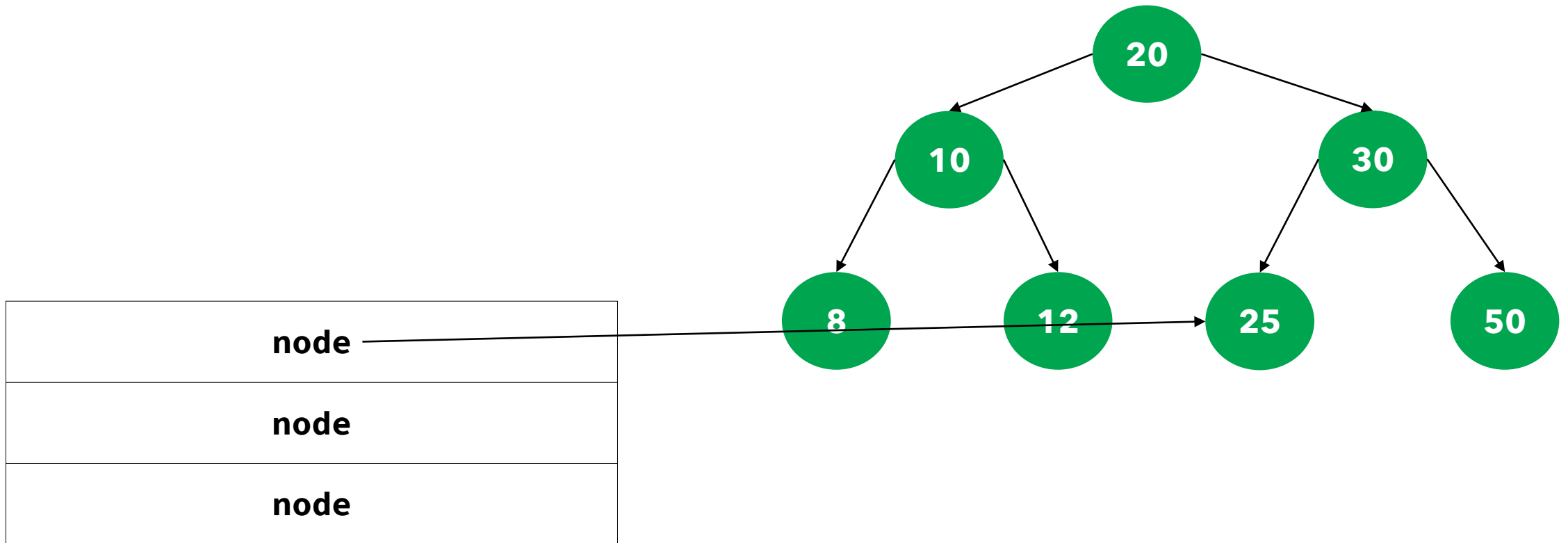
# Depth-first search (DFS): inorder



# Depth-first search (DFS): inorder

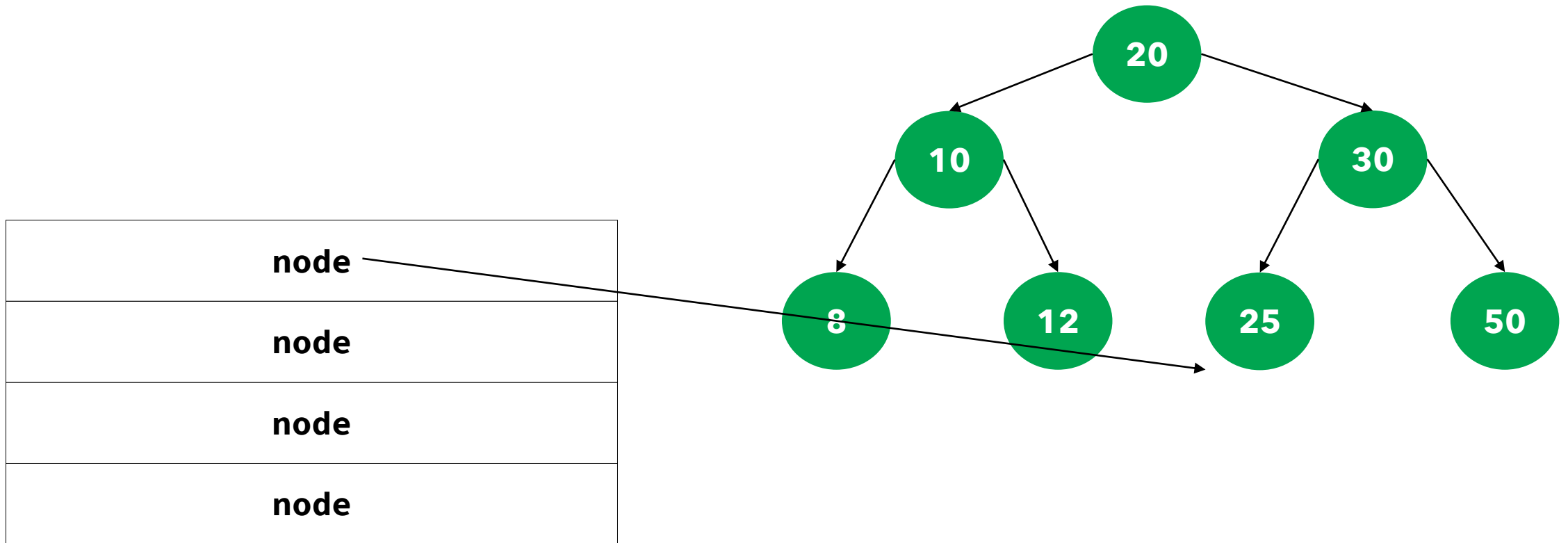


# Depth-first search (DFS): inorder

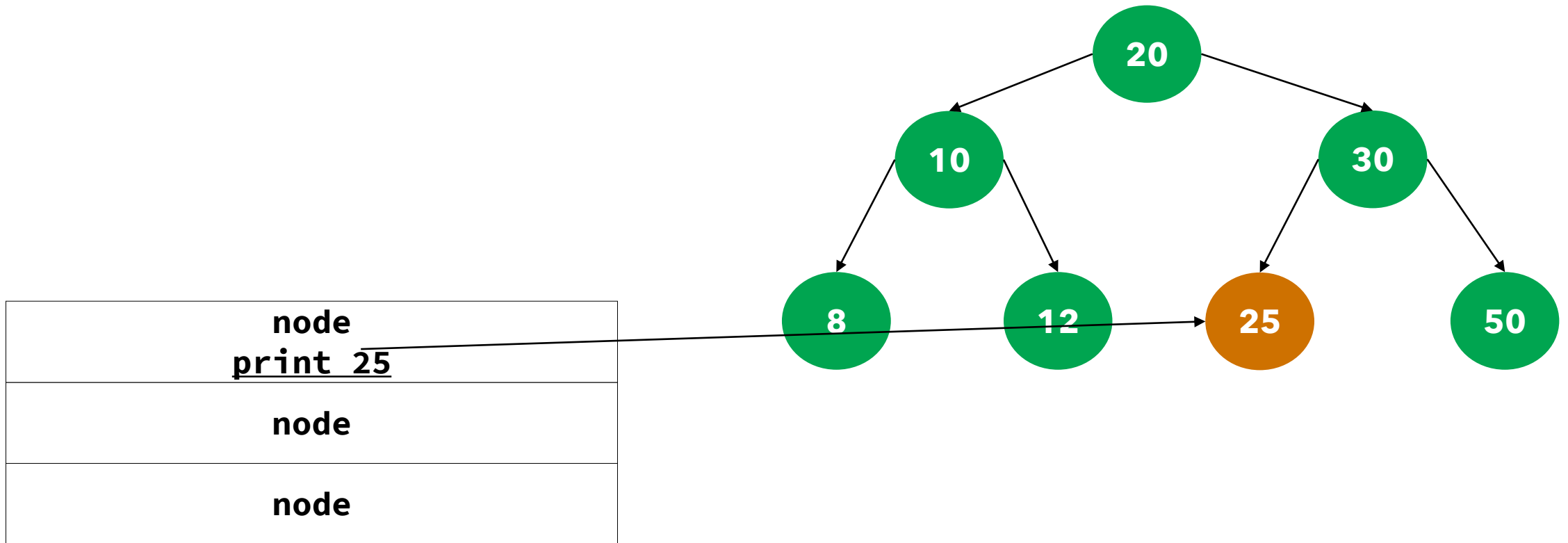




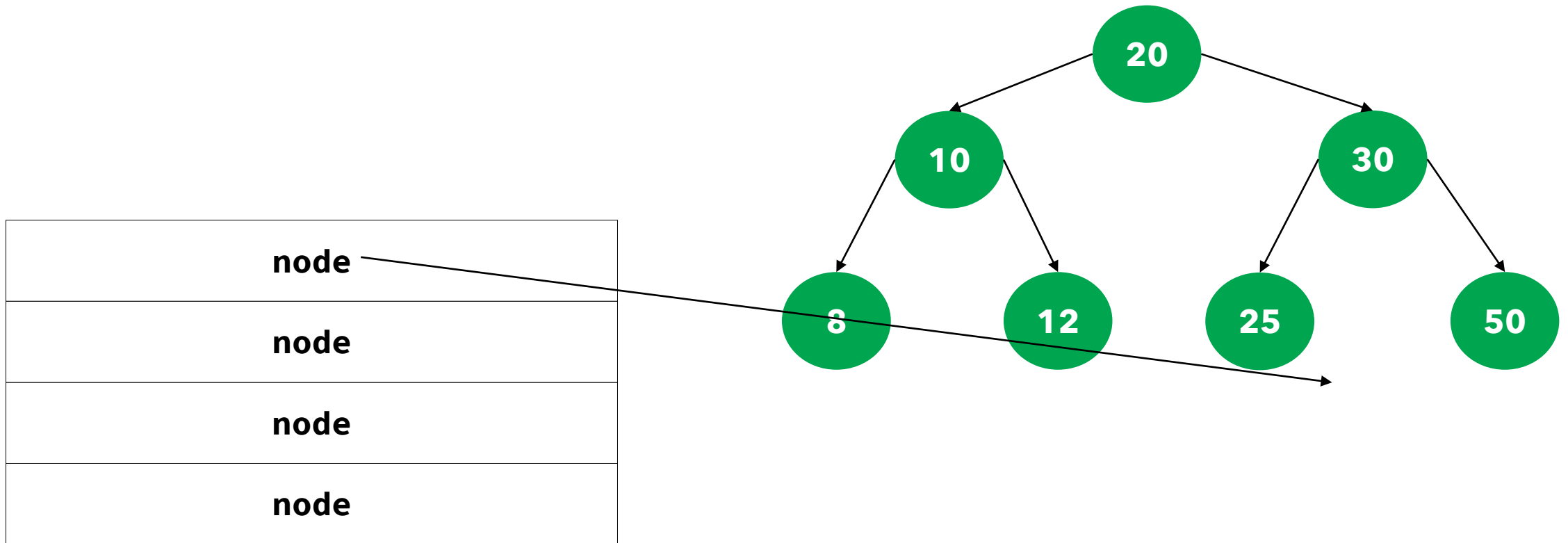
# Depth-first search (DFS): inorder



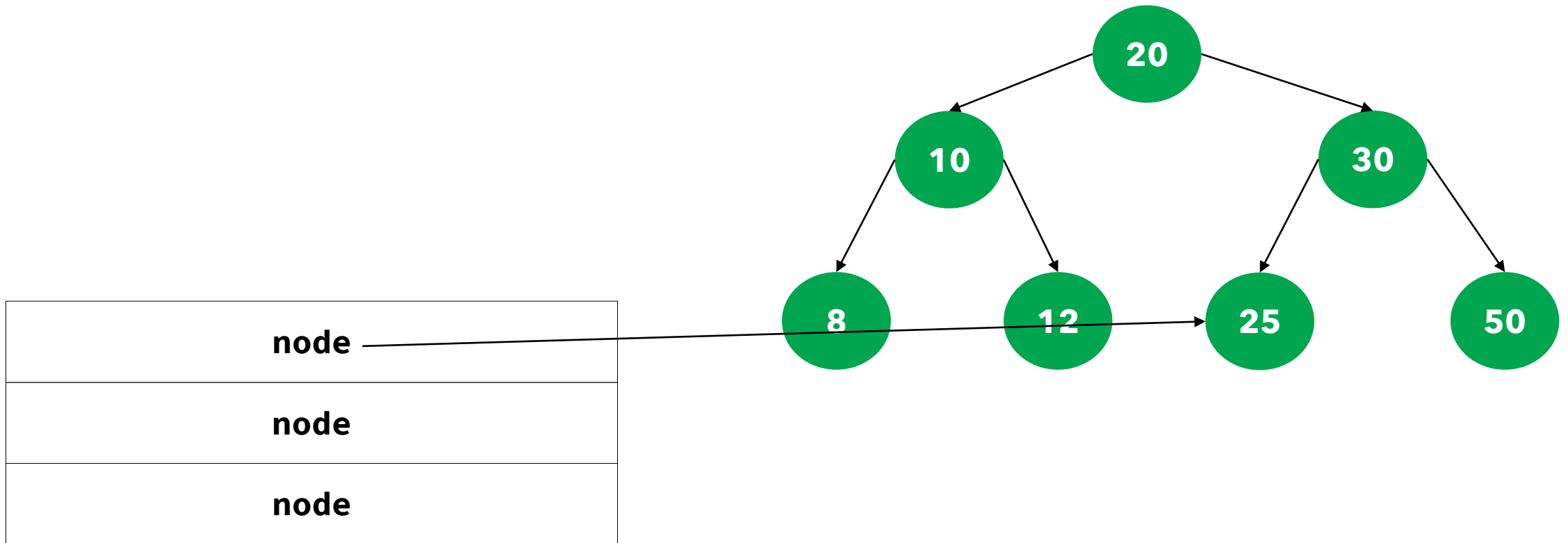
# Depth-first search (DFS): inorder



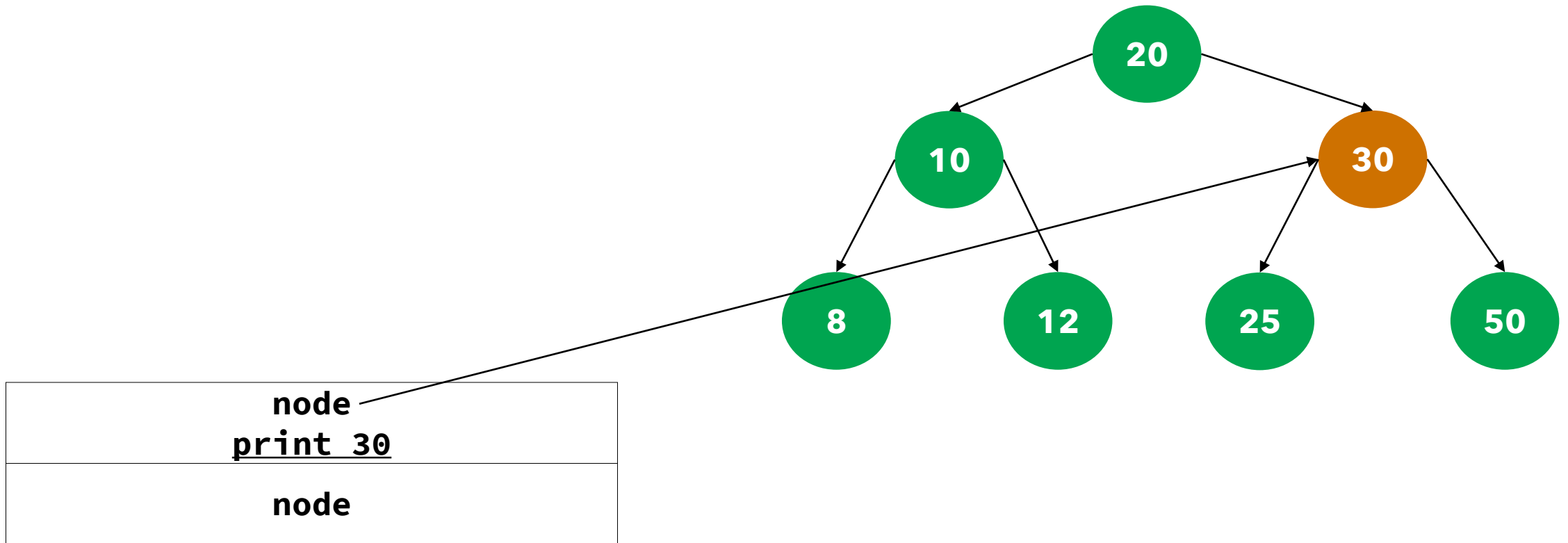
# Depth-first search (DFS): inorder



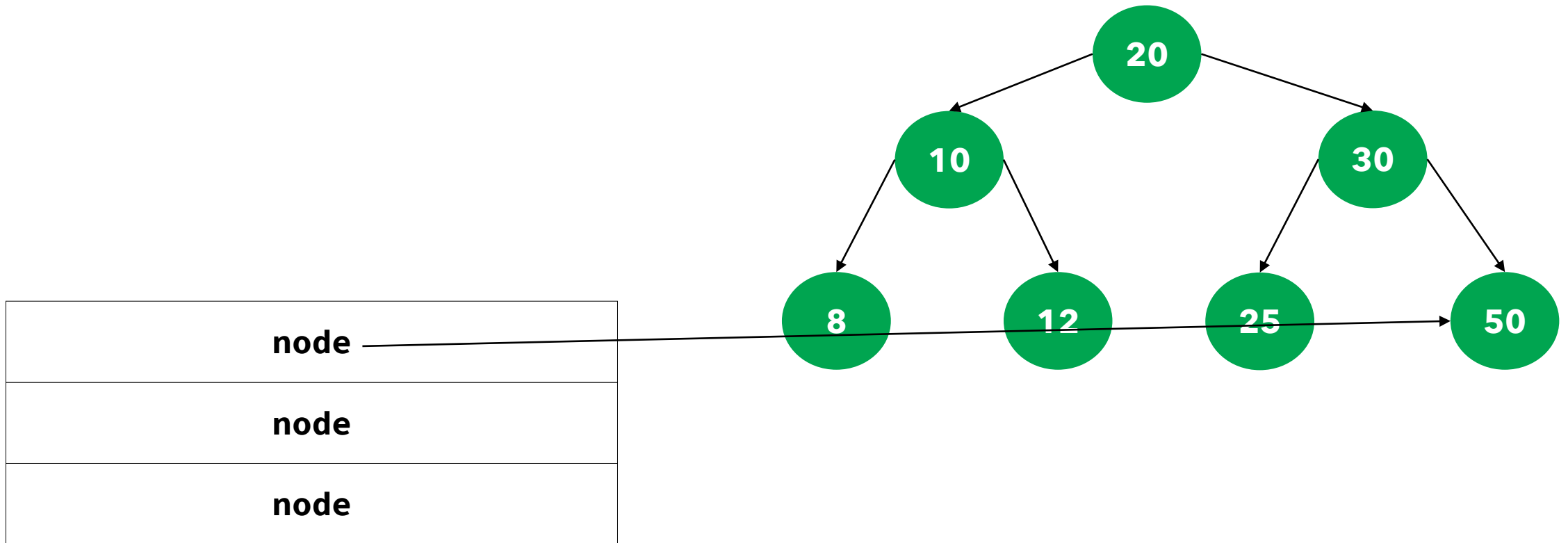
# Depth-first search (DFS): inorder



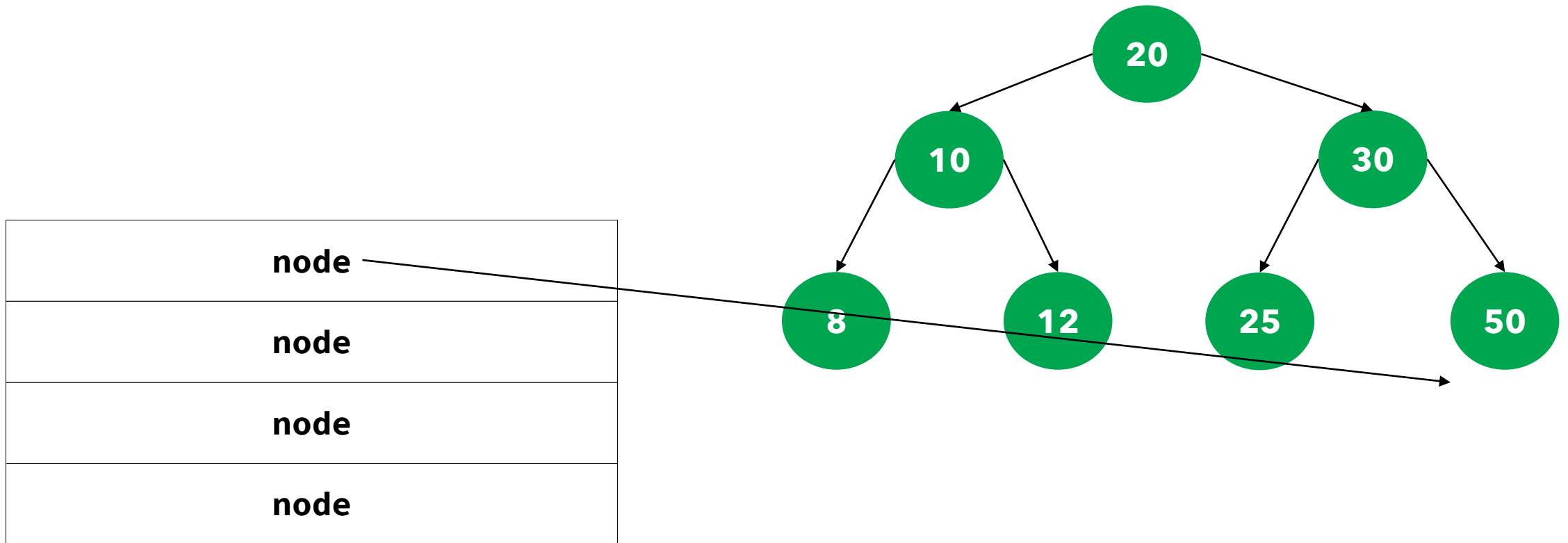
# Depth-first search (DFS): inorder



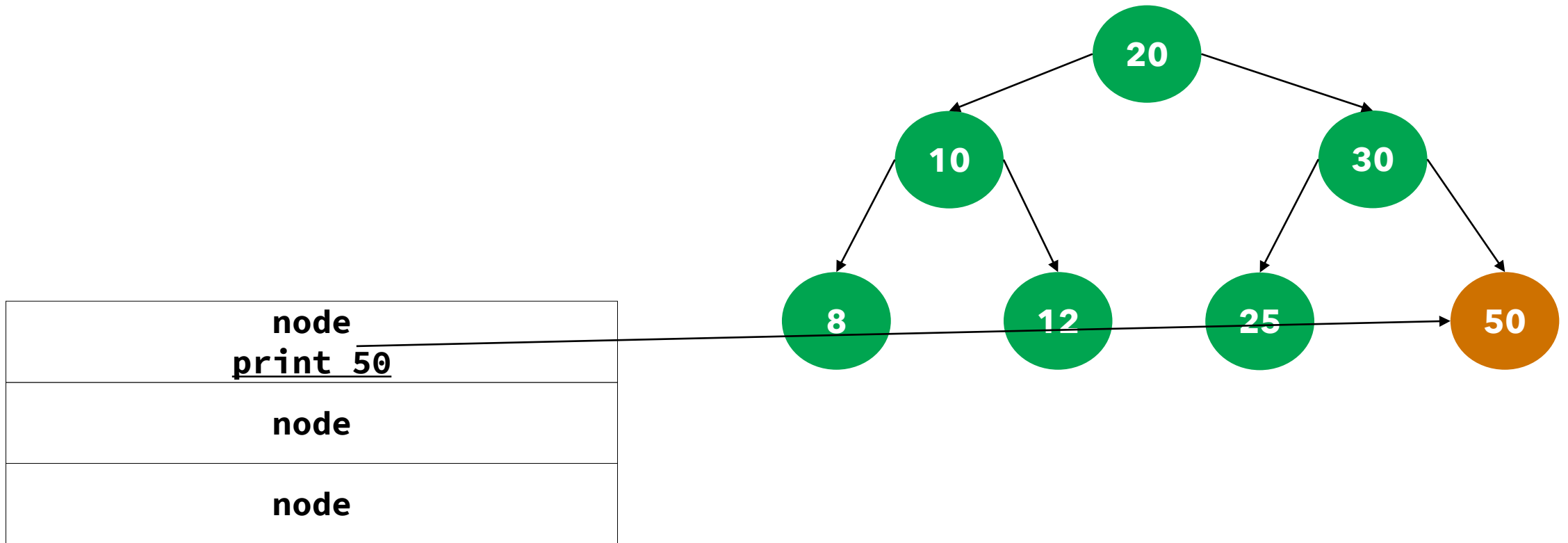
# Depth-first search (DFS): inorder



# Depth-first search (DFS): inorder

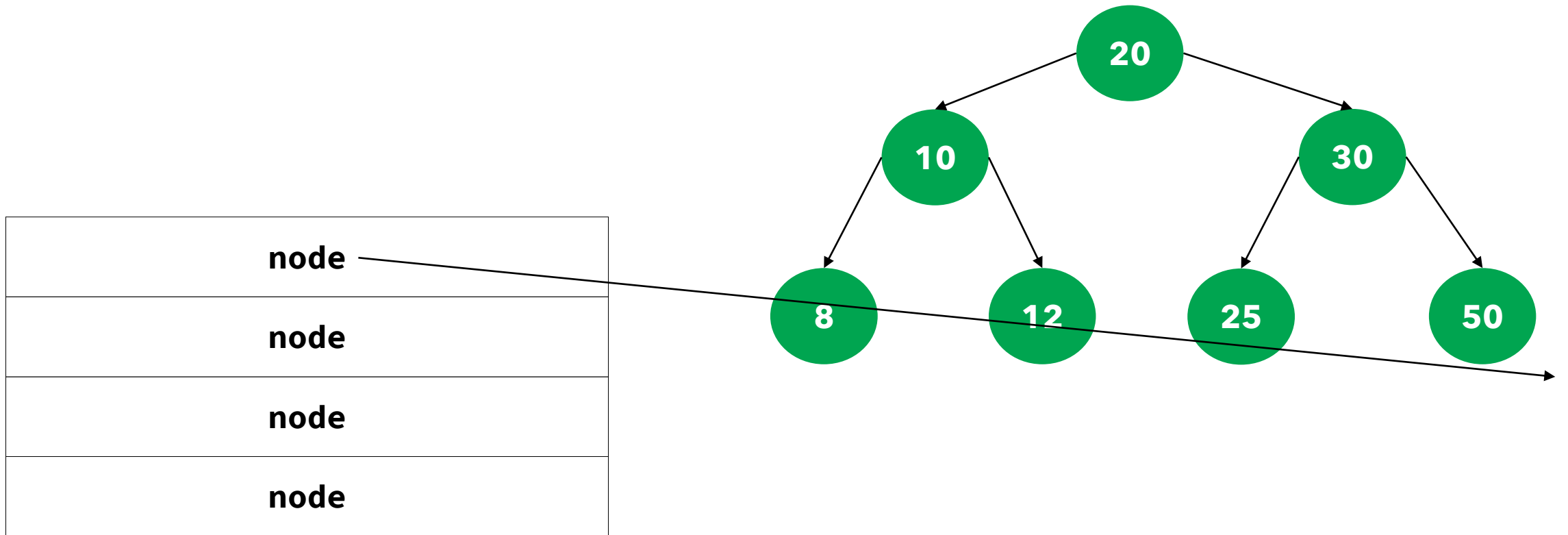


# Depth-first search (DFS): inorder

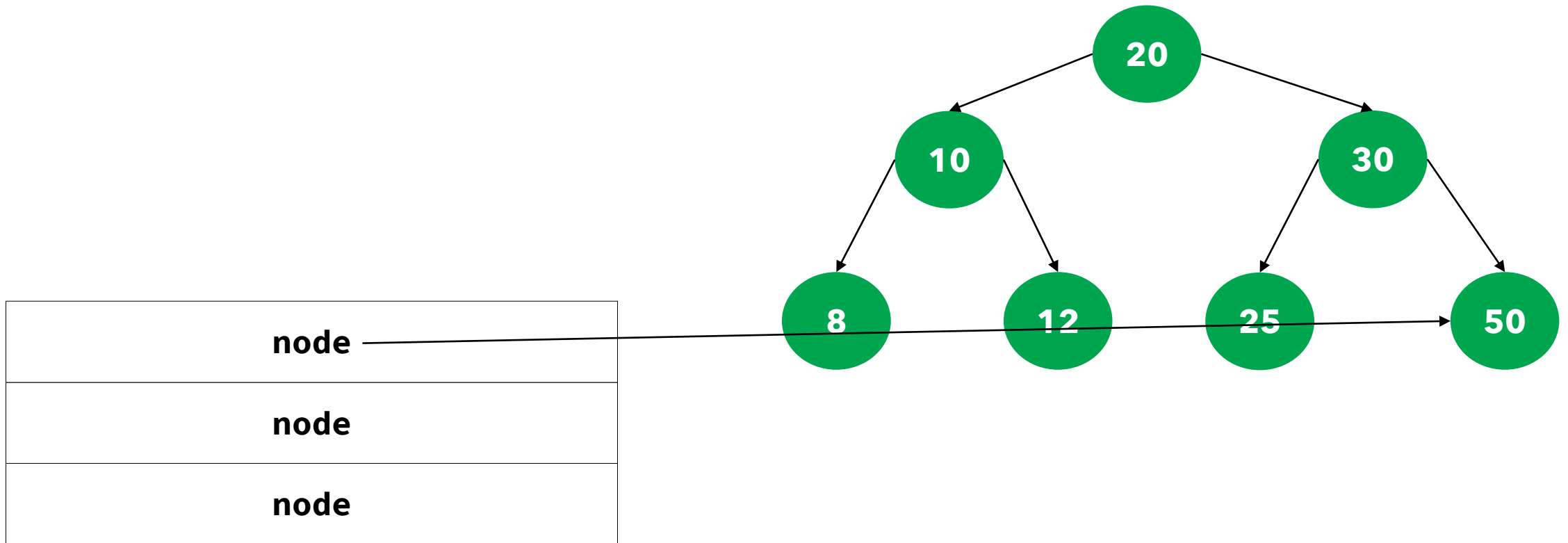




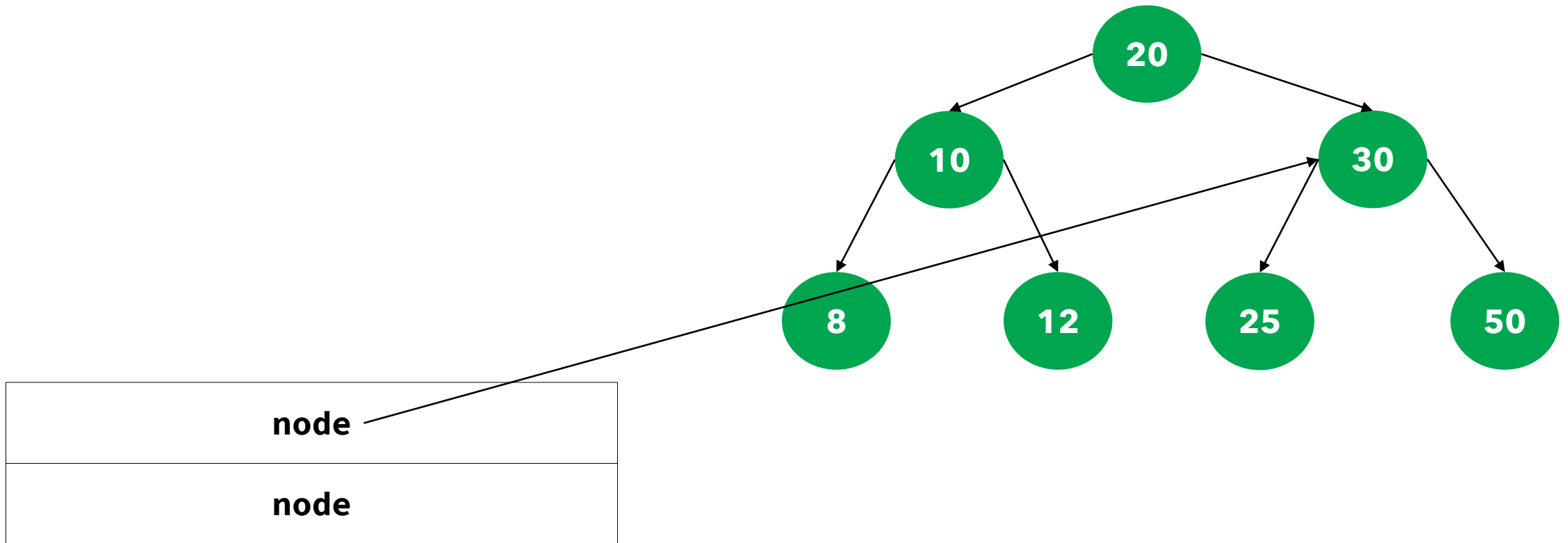
# Depth-first search (DFS): inorder



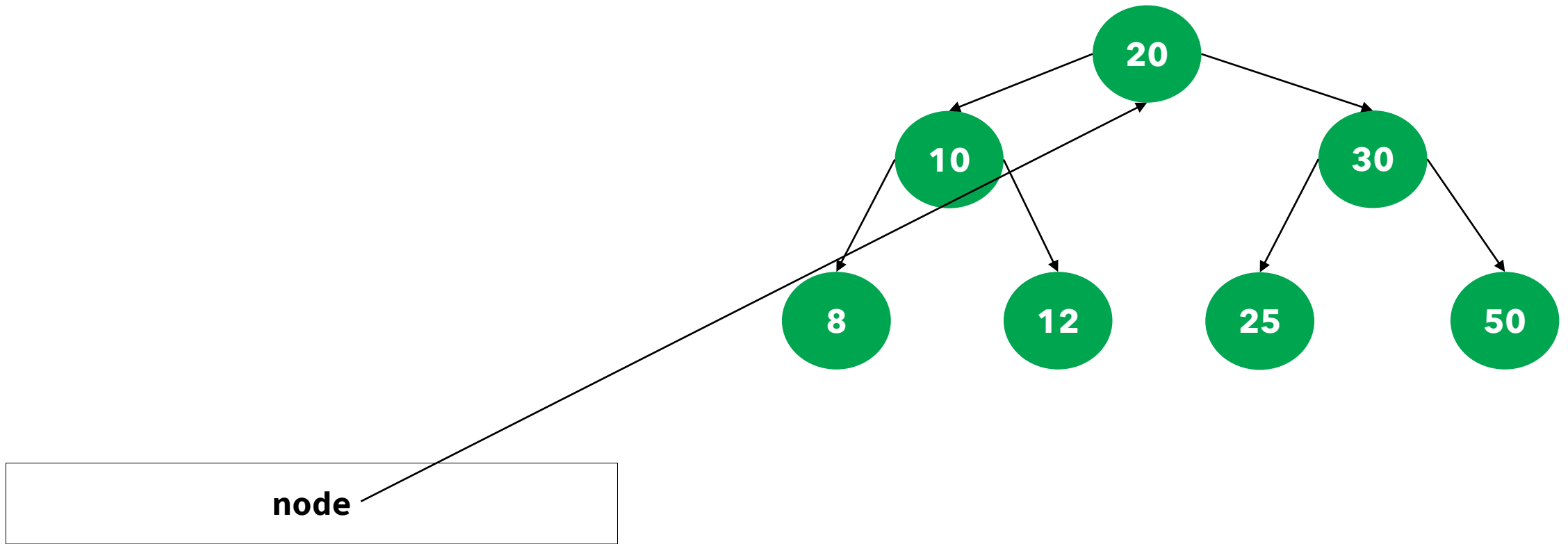
# Depth-first search (DFS): inorder



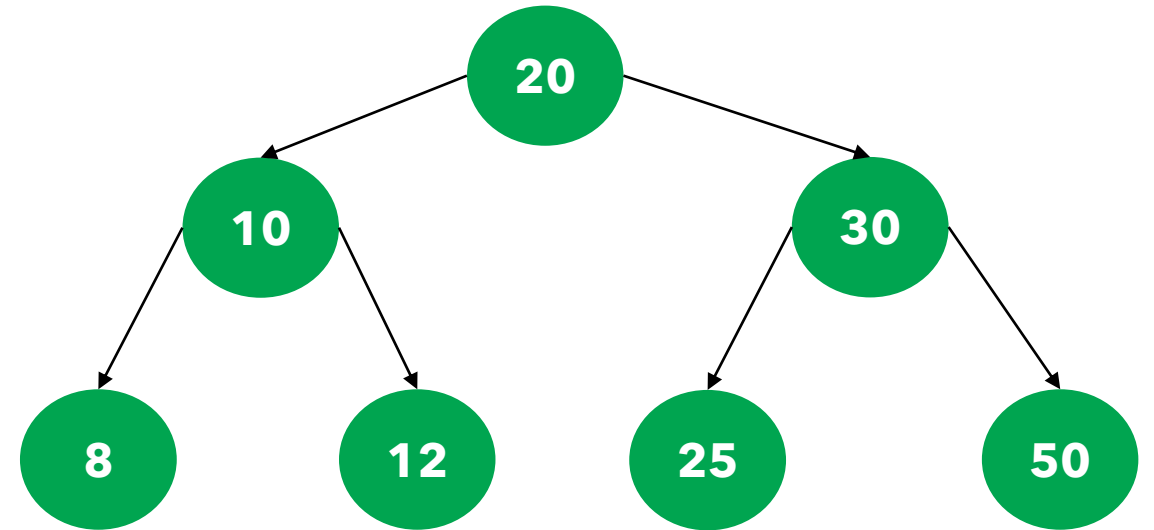
# Depth-first search (DFS): inorder



# Depth-first search (DFS): inorder



# Depth-first search (DFS): inorder



# Depth-first search (DFS): preorder

`preorder_tree_walk(T):`

- if `T` is empty, do nothing
- otherwise:
  - *open* `T` (e.g.: `print T.key`)
  - call `preorder_tree_walk` on `T.left`
  - call `preorder_tree_walk` on `T.right`

# Depth-first search (DFS): postorder

`postorder_tree_walk(T):`

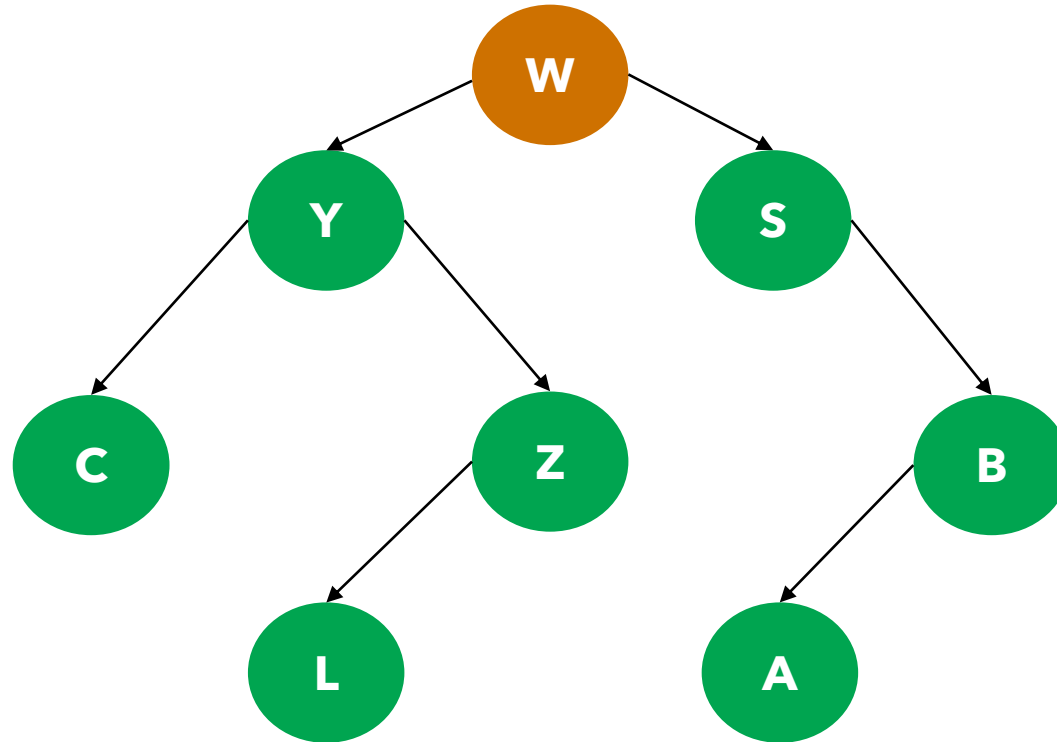
- if `T` is empty, do nothing
- otherwise:
  - call `postorder_tree_walk` on `T.left`
  - call `postorder_tree_walk` on `T.right`
  - *open* `T` (e.g.: `print T.key`)

# Breadth-first search (BFS)

- La ricerca in ampiezza è una ricerca per livelli
- Prima si visitano tutti i nodi al livello 0, poi tutti quelli al livello 1, poi tutti quelli al livello 2 etc...
- Visiteremo ciascun livello da sinistra a destra
- Per tenere traccia dei livelli nell'ordine corretto serve una **queue**



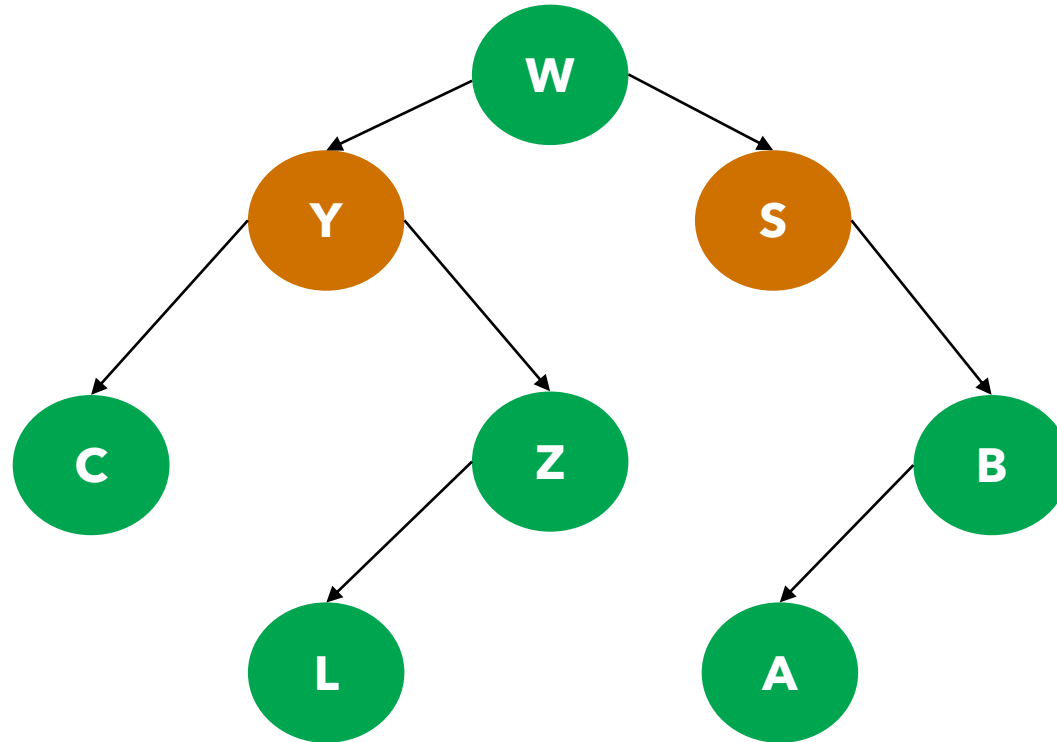
# Breadth-first search (BFS)



Q: []  
enqueue(W);

Q: [W]

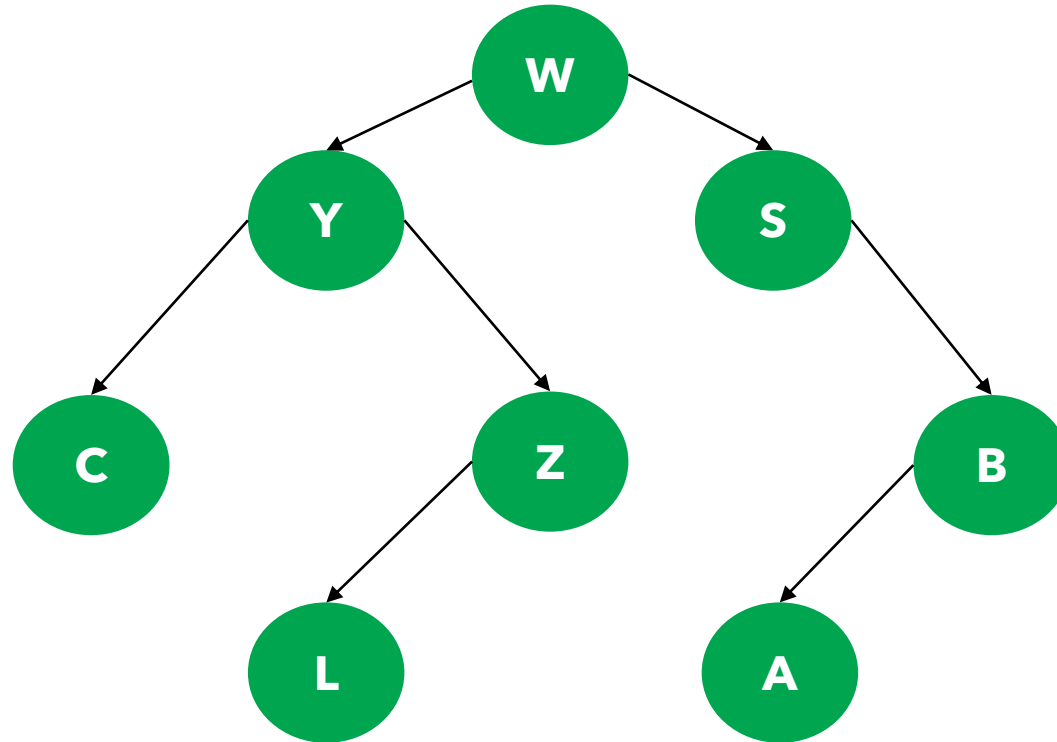
# Breadth-first search (BFS)



`enqueue(W.left);`  
`enqueue(W.right);`

`Q: [W, Y, S]`

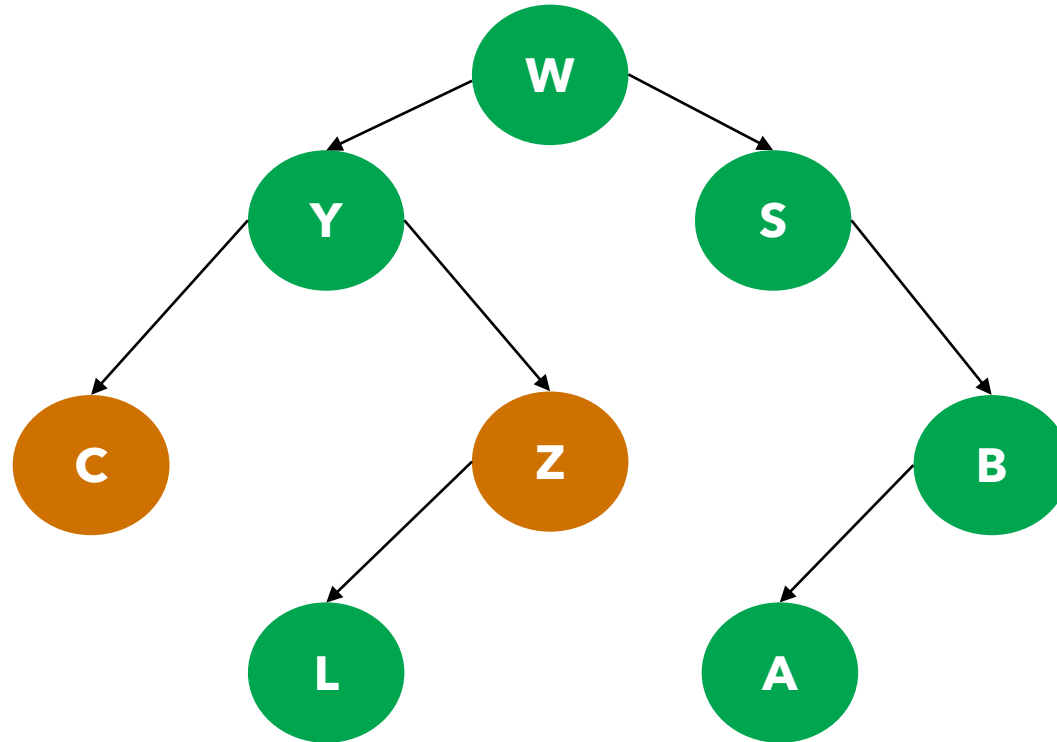
# Breadth-first search (BFS)



**dequeue();**

**Q: [Y, S]**

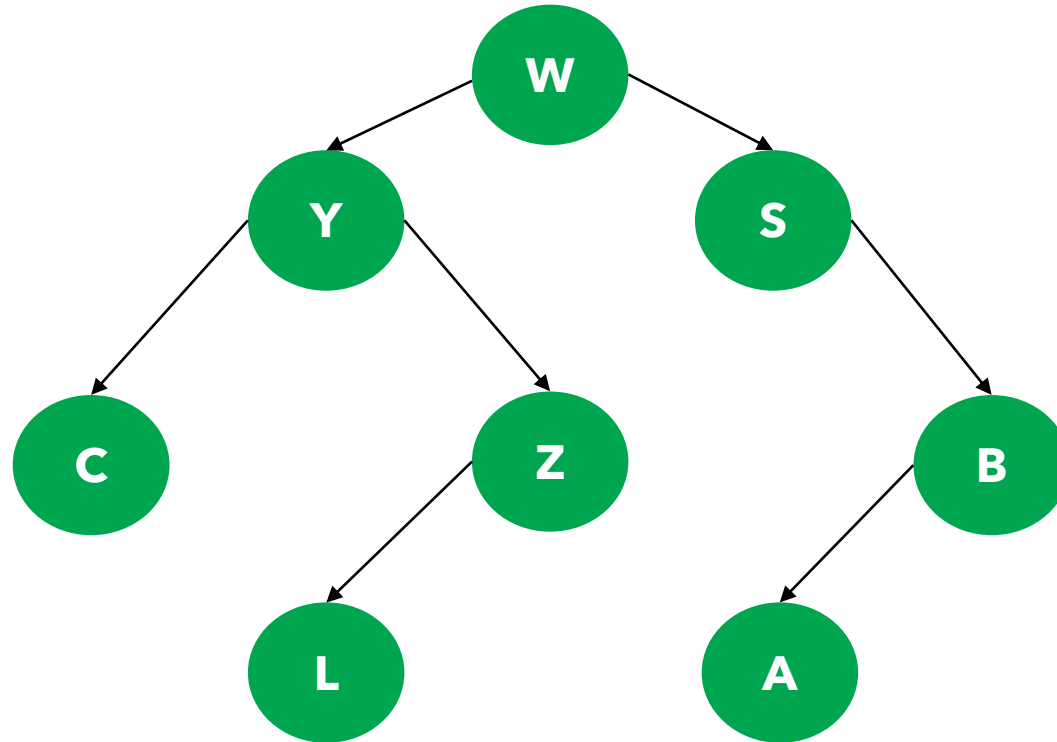
# Breadth-first search (BFS)



```
enqueue(Y.left);  
enqueue(Y.right);
```

Q: [Y, S, C, Z]

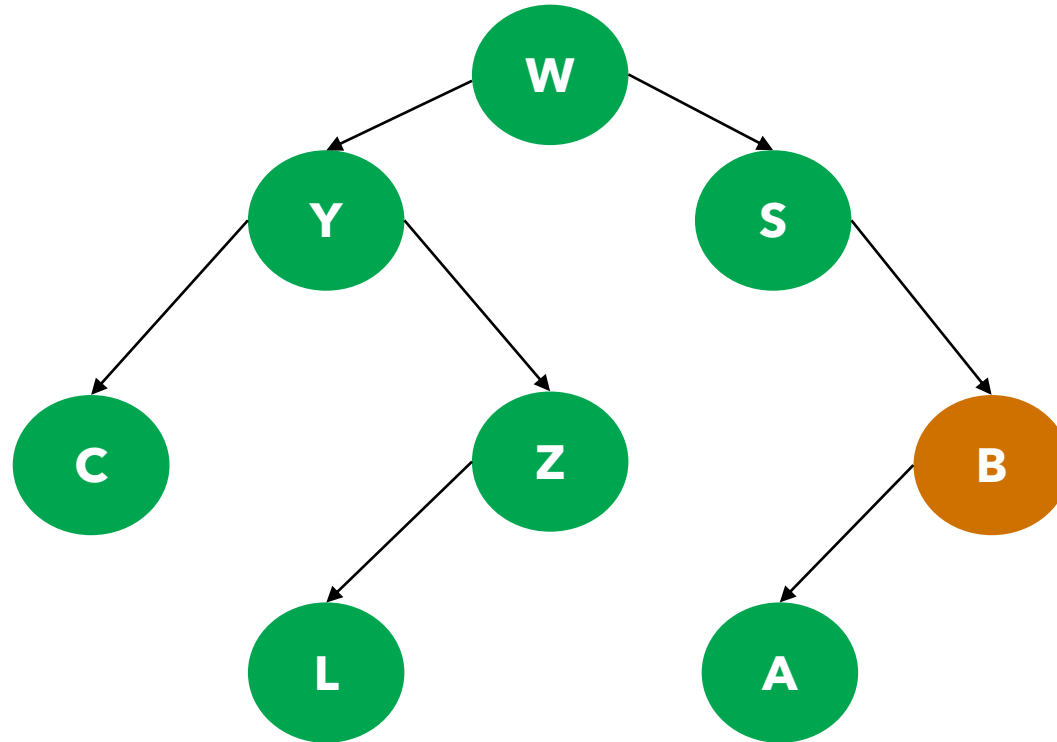
# Breadth-first search (BFS)



**dequeue();**

**Q: [S, C, Z]**

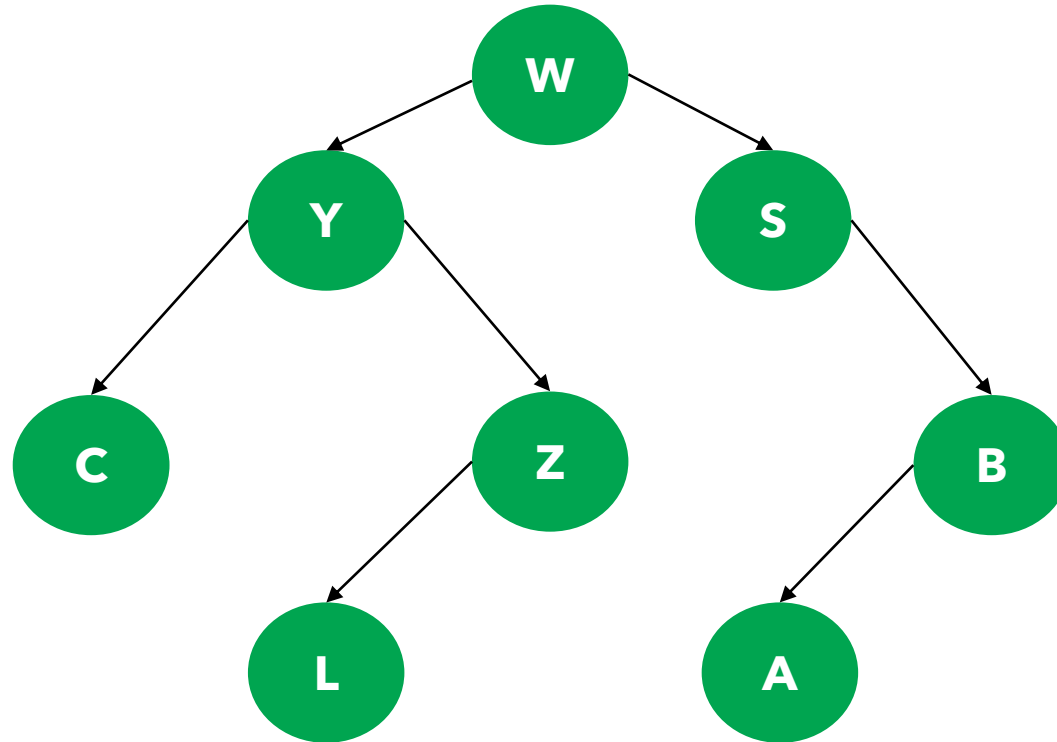
# Breadth-first search (BFS)



**enqueue(S.right);**

**Q: [S, C, Z, B]**

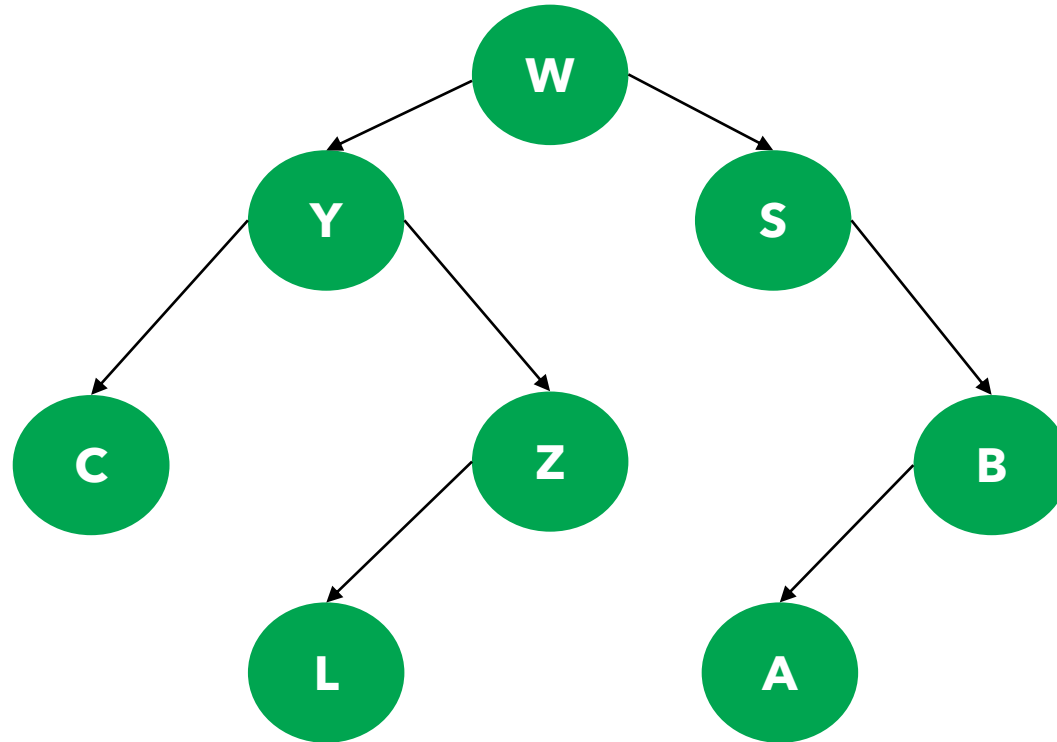
# Breadth-first search (BFS)



**dequeue();**

**Q: [C, Z, B]**

# Breadth-first search (BFS)

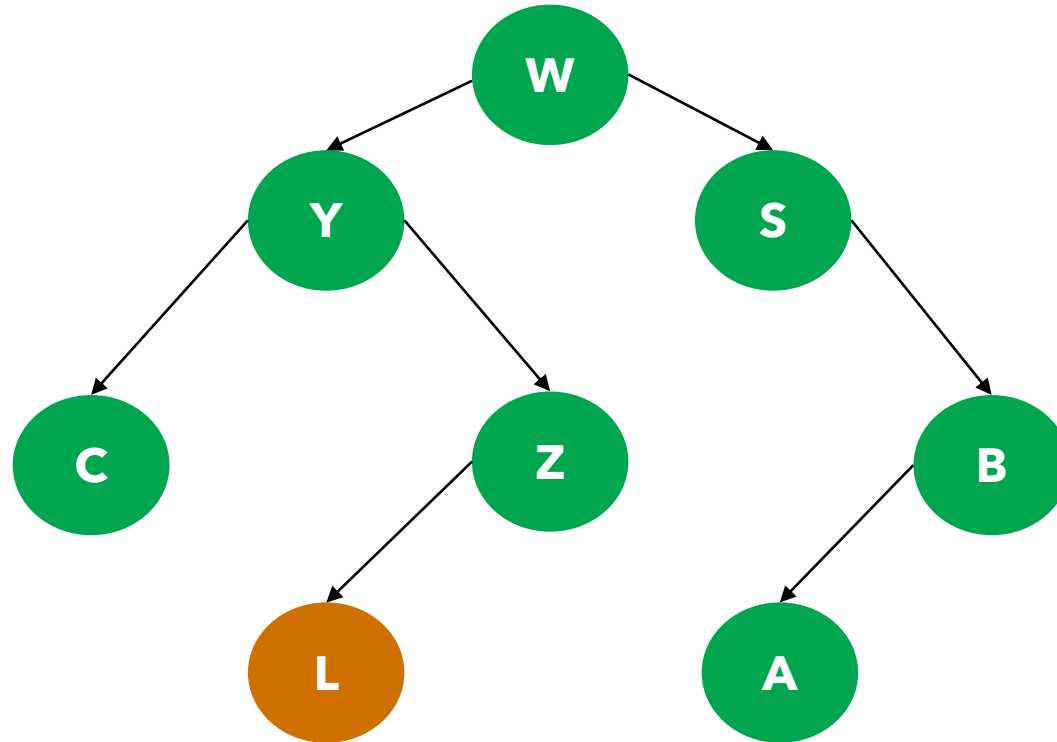


**dequeue();**

**Q: [Z, B]**



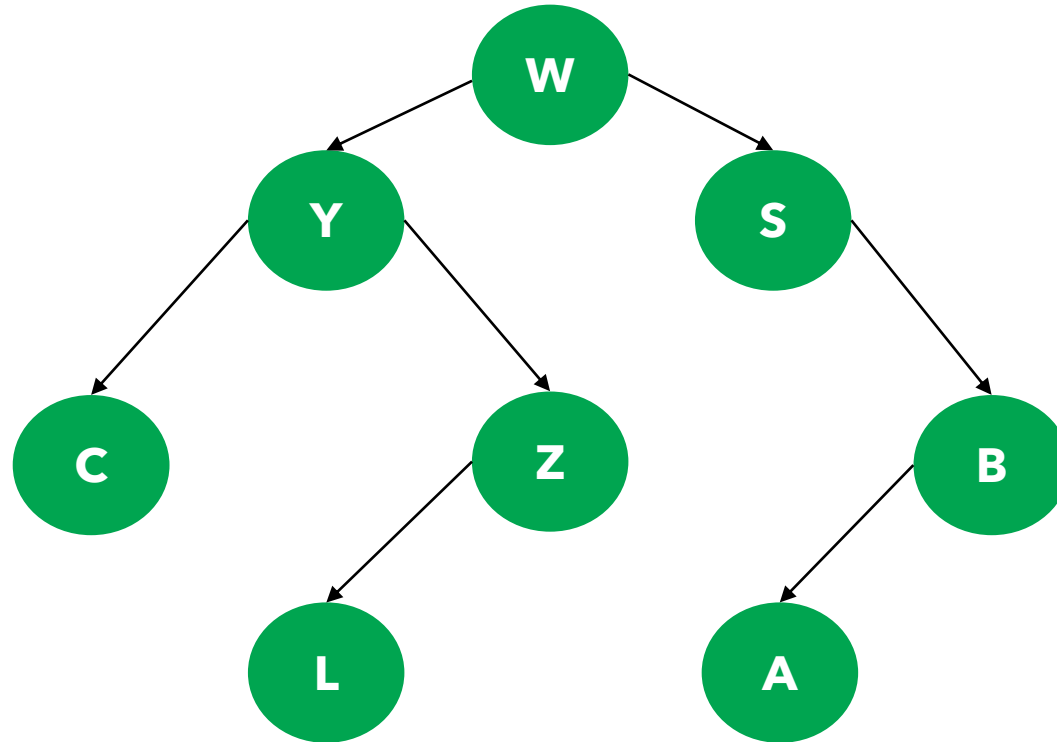
# Breadth-first search (BFS)



**enqueue(Z.left);**

**Q: [Z, B, L]**

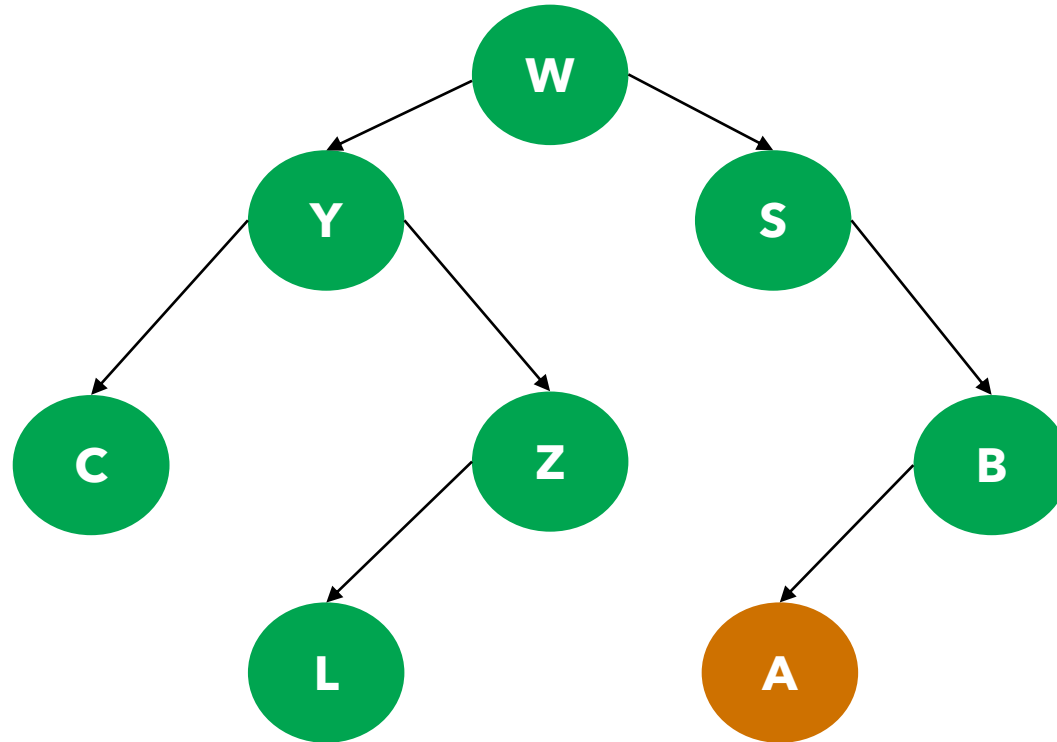
# Breadth-first search (BFS)



**dequeue();**

**Q: [B, L]**

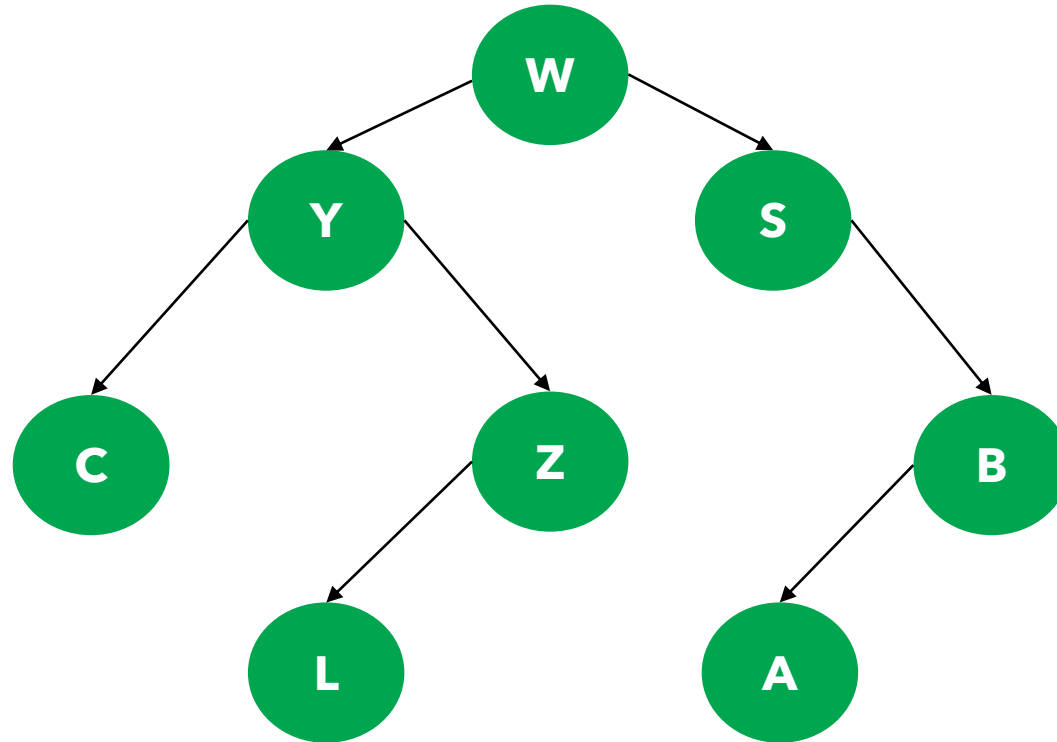
# Breadth-first search (BFS)



**`enqueue(B.left);`**

**`Q: [B, L, A]`**

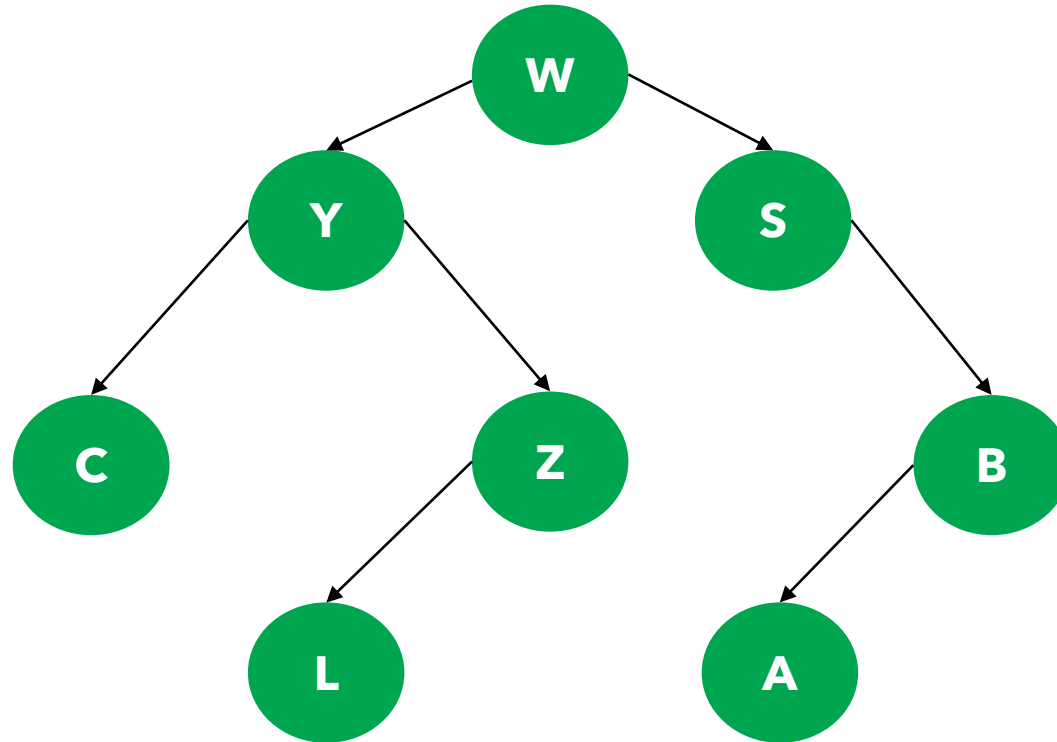
# Breadth-first search (BFS)



**dequeue();**

**Q: [L, A]**

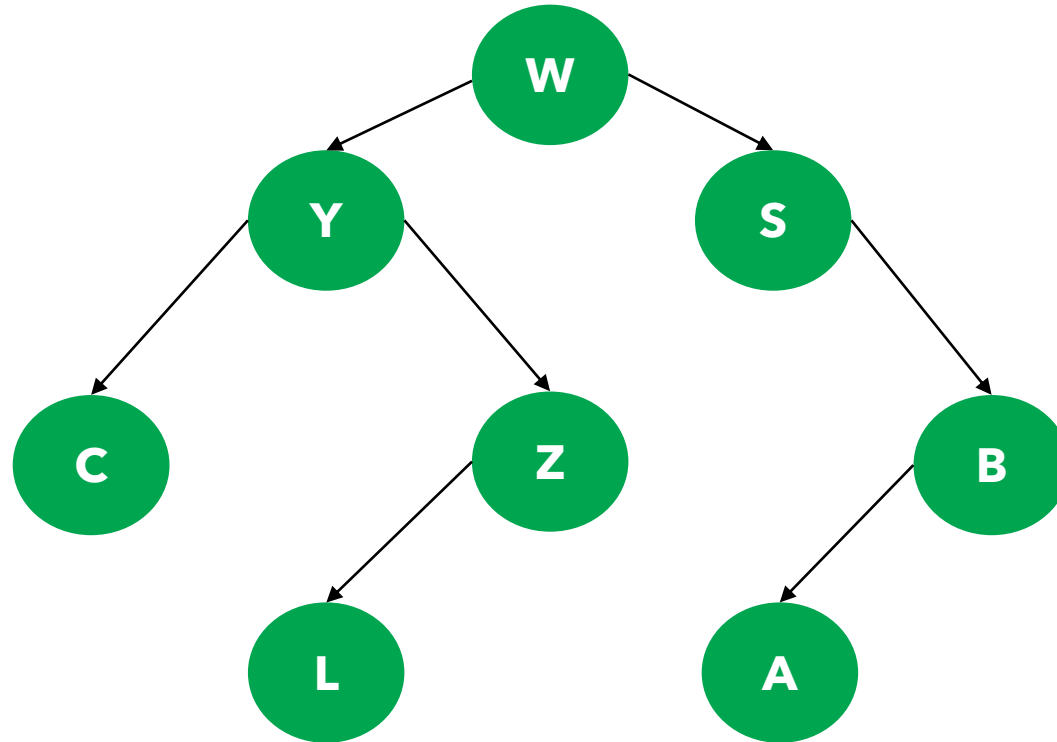
# Breadth-first search (BFS)



**dequeue();**

**Q: [A]**

# Breadth-first search (BFS)



**dequeue();**

**Q: []**