

# Solutions for Exercise Sheet 12

Handout: December 5th — Deadline: December 12th, 4pm

## Question 12.1 (0.5 marks)

Suppose that you modify GREEDY-ACTIVITY-SELECTOR to use the following greedy strategies. State whether each strategy would yield an optimal solution or not. If they do, then provide a proof of optimality. If they don't, then provide an example instance where the strategy fails.

1. Always select the activity of least duration amongst those that are compatible with all previously selected activities
2. Always select the compatible activity that overlaps with the fewest remaining activities
3. Always select the last activity to start that is compatible with all previously selected activities
4. Always select the compatible activity with the earliest start time

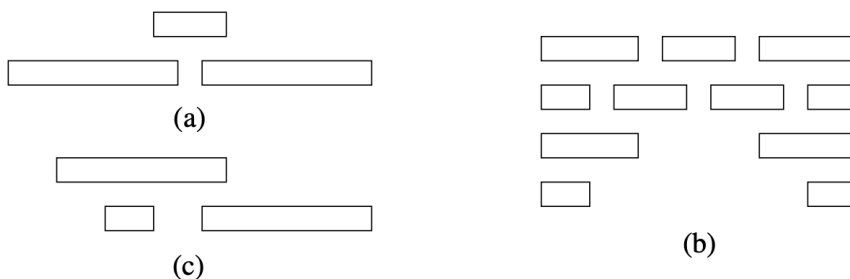


Figure 1: Examples

## Solution.

1. The strategy fails for example on this instance:  $s_1 = 1, f_1 = 5, s_2 = 4, f_2 = 6, s_3 = 5, f_3 = 10$ . (See Fig. 1 (a)).
2. The strategy fails for example with the activities in Fig. 1 (b). The activity that overlaps least is the second one on the first row. Selecting this activity first forces a solution with only 3 activities while the optimal solution has 4 activities.
3. This strategy is symmetric to the one used at lecture and works for the same reason, and you can prove that the greedy choice is *safe*.

Consider any nonempty subproblem  $S_k$ , and let  $a_m$  be an activity in  $S_k$  with the latest start time. Then  $a_m$  is included in some maximum-size subset of mutually compatible activities of  $S_k$ . Consider an optimal solution  $A_k$ . If it contains  $a_m$ , you're done. Otherwise swap  $a_m$  in with  $a_j$  out, where  $a_j$  is the activity in the solution with latest start time. Since  $a_m$  cannot start earlier than  $a_j$ , it must also be compatible with all the other activities or  $a_j$  wouldn't be compatible either. CVD.

4. The strategy fails for example if the first activity to start is also the last one to finish. Then all the other activities are force out of the solution. Another example is provided in Fig. 1 (c).

**Question 12.2** (0.25 marks)

Prove that the fractional knapsack problem has the greedy choice property, hence always finds an optimal solution.

**Solution.**

The Greedy algorithm sorts the items according to value per gram: let the greedy solution be  $a_1, a_2, \dots, a_m/i$ , of decreasing value per gram and where  $a_m/i$  may be some fraction of  $a_m$  if it doesn't all fit or exactly  $a_m$  if it fits (i.e. then  $i = 1$ ). Let's assume there is a different optimal solution using some  $a_{m+i}$  object(s) with lower value per gram instead of one (or more) of the  $a_i$  objects in the greedy solution. Then we could just swap them in and out and achieve the same solution value.

**Question 12.3** (0.5 marks)

Eddy takes part in a cycle race from start  $s_1$  to finish  $s_n$  with feed stations  $s_2, \dots, s_{n-1}$  along the way and distances  $d_i$  between  $s_i$  and  $s_{i+1}$ . To save time, Eddy plans to stop at the smallest possible number of stations. He knows that he can cycle distance  $\ell$  without stopping for supplies, where  $\ell > d_i$  for all  $1 \leq i \leq n - 1$ .

- Design a greedy algorithm that computes the minimal number of stops for Eddy.
- Argue why your greedy strategy yields an optimal solution.

**Solution.**

- The greedy strategy is to choose at any feed station where Eddy stops the most distant feed station he can reach. Thus from any  $s_k$  he should stop at  $s_{k'}$  where  $k < k'$  and

$$\sum_{i=k}^{k'} d_i \leq \ell < \sum_{i=k}^{k'+1} d_i.$$

An informal description like the above is sufficient. In pseudocode, the algorithm could look like this. In this code, we count the number of stops in a variable  $s\text{-}nr$ . We sum up distances from the last stop in a variable  $loc\text{-}sum$ , and when distances exceed  $\ell$ , and  $i$  is the current loop counter, we count a stop at feed station  $s_{i-1}$  (the one just before Eddy exceeds his maximum distance of  $\ell$ ). The algorithm then continues with  $loc\text{-}sum = d_i$  as that is the distance Eddy has travelled since stopping at  $s_{i-1}$ .

FEED-STATION( $d_1, \dots, d_{n-1}, \ell$ )

```

1   $s\text{-}nr = 0$ 
2   $loc\text{-}sum = 0$ 
3  for  $i = 1$  to  $n - 1$ 
4       $loc\text{-}sum = loc\text{-}sum + d_i$ 
5      if  $loc\text{-}sum > \ell$ 
6           $s\text{-}nr = s\text{-}nr + 1$ 
7           $loc\text{-}sum = d_i$ 
8  return  $s\text{-}nr$ 
```

NB: the algorithm can easily be extended to print out the actual feed stations by adding a line that prints  $s_{i-1}$  inside the *if* statement.

- (b) Let  $S = (s_{o_1}, \dots, s_{o_m})$  be an optimal sequence of feed stations. We show that the greedy choice  $s_{g_1}$  for the first feed station is always safe. Formally, similar to Theorem 16.1 for activity selection, we show that there is a solution with a minimum number of stops that includes  $s_{g_1}$  as first stop.

If  $s_{o_1} = s_{g_1}$  the claim is true and there is nothing to prove. Otherwise, we must have  $s_{o_1} < s_{g_1}$  as  $s_{g_1}$  is the furthest reachable feed station. If we replace  $s_{o_1}$  with  $s_{g_1}$ , we get a new solution  $S' = S \setminus \{s_{o_1}\} \cup \{s_{g_1}\}$ . This solution is feasible as  $d(s_1, s_{g_1}) \leq \ell$  and the distance to the second feed station has not increased:  $d(s_{o_1}, s_{o_2}) \leq \ell$  and  $s_{o_1} < s_{g_1}$  imply  $d(s_{g_1}, s_{o_2}) \leq \ell$ . Since we only replaced a feed station, both solutions have the same number of stops,  $|S'| = |S|$ . Hence we have shown that there is solution,  $S'$ , with a minimum number of stops that makes a greedy choice for the first feed station.

We can now consider the subproblem given by all stops from  $s_{g_1}$ . Iterating the above argument shows that the greedy algorithm will compute an optimal solution.

**Question 12.4** (0.25 marks)

Implement both `RECURSIVE-ACTIVITY-SELECTOR( $s, f, k, n$ )` and `GREEDY-ACTIVITY-SELECTOR( $s, f, n$ )`. The algorithms take in input the array  $s$  of starting times, the array  $f$  of ending times and the number of activities  $n$ . The elements are already sorted according to finish times.