



CS215 DISCRETE MATH

Dr. QI WANG

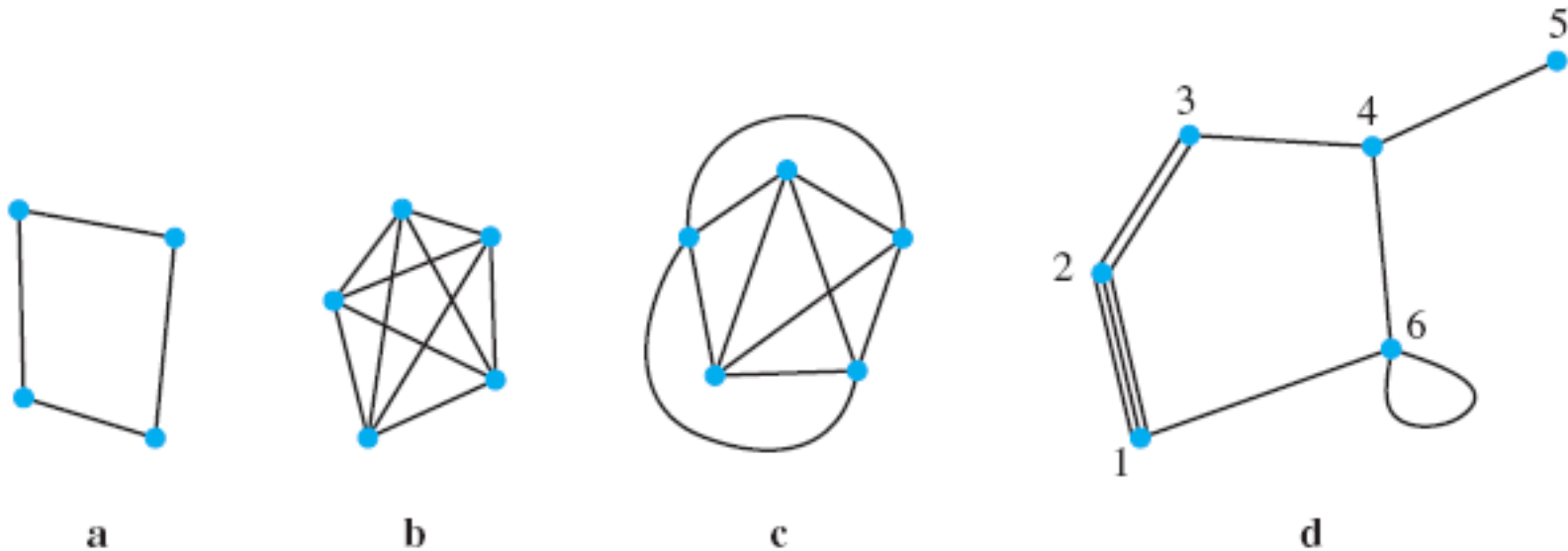
Department of Computer Science and Engineering

Office: Room413, CoE South Tower

Email: wangqi@sustech.edu.cn

Definition of a Graph

- **Definition.** A *graph* $G = (V, E)$ consists of a nonempty set V of *vertices* (or *nodes*) and a set E of *edges*. Each edge has either one or two vertices associated with it, called its *endpoints*. An edge is said to be *incident to* (or *connect* its endpoints).



Complete Graphs

- A *complete graph* on n vertices, denoted by K_n , is the simple graph that contains exactly one edge between **each pair** of distinct vertices.

Complete Graphs

- A *complete graph* on n vertices, denoted by K_n , is the simple graph that contains exactly one edge between **each pair** of distinct vertices.

K_1

K_2

K_3

K_4

K_5

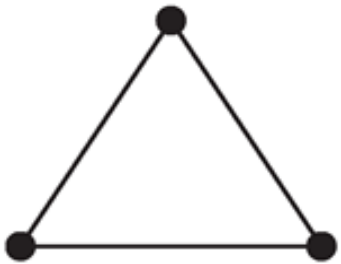
K_6

Cycles

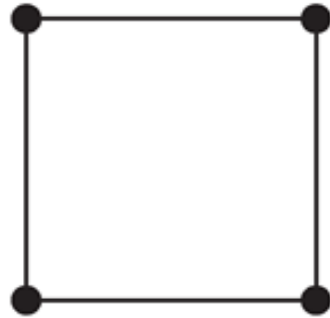
- A *cycle* C_n for $n \geq 3$ consists of n vertices v_1, v_2, \dots, v_n , and edges $\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}, \{v_n, v_1\}$.

Cycles

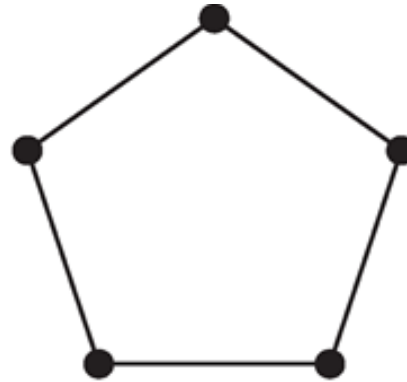
- A *cycle* C_n for $n \geq 3$ consists of n vertices v_1, v_2, \dots, v_n , and edges $\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}, \{v_n, v_1\}$.



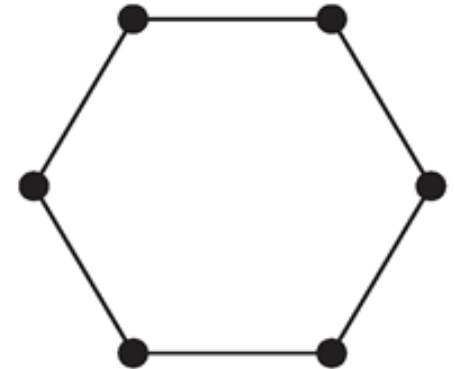
C_3



C_4



C_5



C_6

Wheels

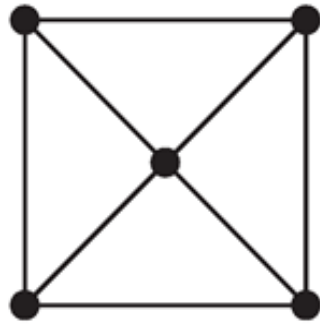
- A *wheel* W_n is obtained by adding an additional vertex to a cycle C_n .

Wheels

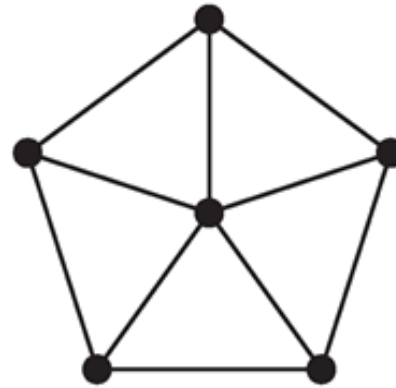
- A *wheel* W_n is obtained by adding an additional vertex to a cycle C_n .



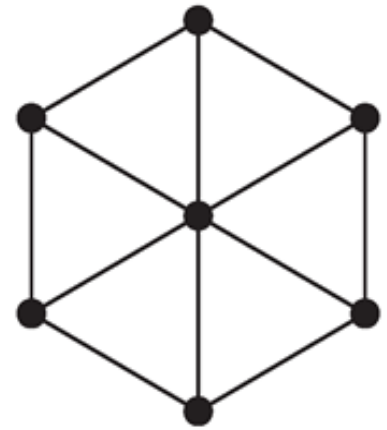
W_3



W_4



W_5



W_6

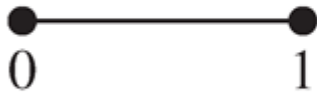
N -dimensional Hypercube

- An *n -dimensional hypercube*, or *n -cube*, Q_n is a graph with 2^n vertices representing all bit strings of length n , where there is an edge between two vertices that differ in exactly one bit position.

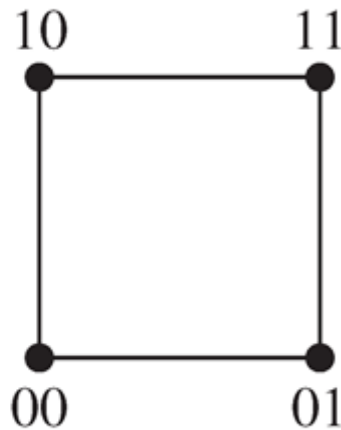


N -dimensional Hypercube

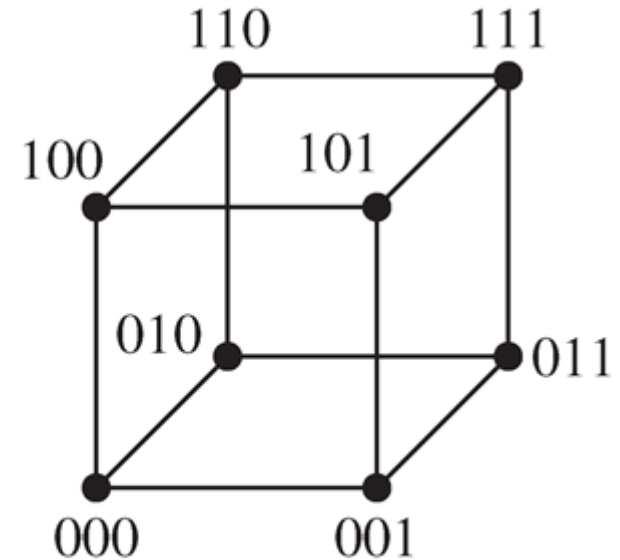
- An n -dimensional hypercube, or n -cube, Q_n is a graph with 2^n vertices representing all bit strings of length n , where there is an edge between two vertices that differ in exactly one bit position.



Q_1



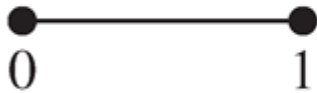
Q_2



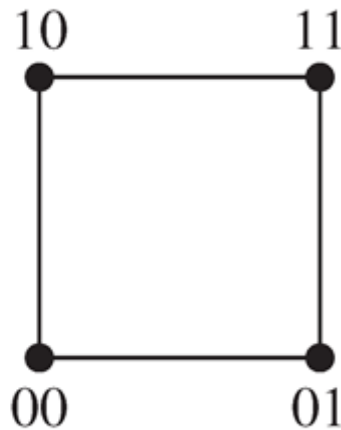
Q_3

N-dimensional Hypercube

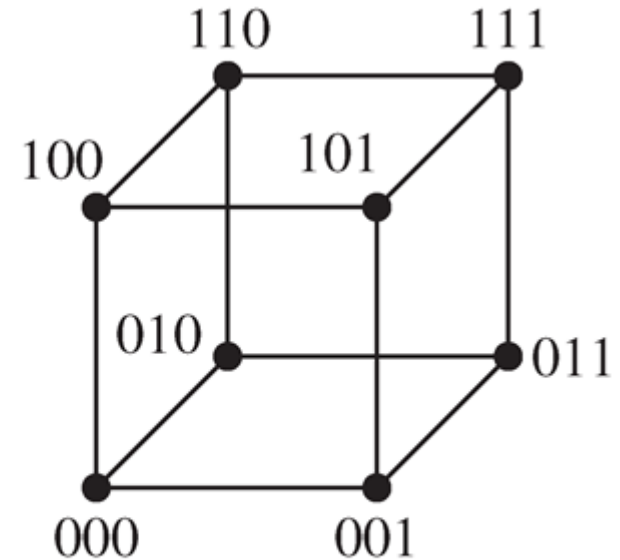
- An *n-dimensional hypercube*, or *n-cube*, Q_n is a graph with 2^n vertices representing all bit strings of length n , where there is an edge between two vertices that differ in exactly one bit position.



Q_1



Q_2



Q_3

How many vertices? How many edges?

Bipartite Graphs

- **Definition** A simple graph G is *bipartite* if V can be partitioned into two disjoint subsets V_1 and V_2 such that every edge connects a vertex in V_1 and a vertex in V_2 .



Bipartite Graphs

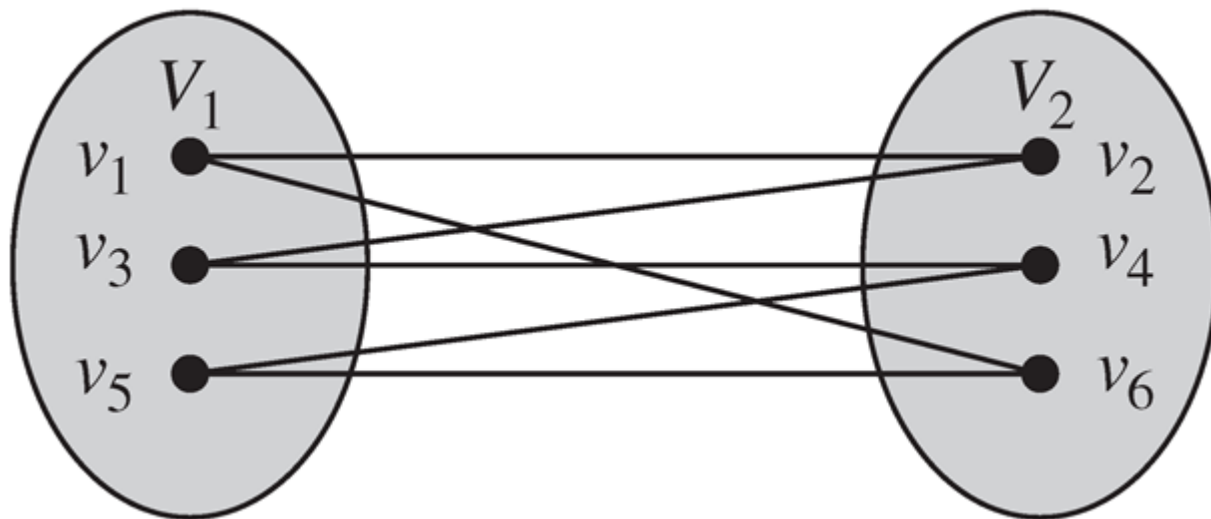
- **Definition** A simple graph G is *bipartite* if V can be partitioned into two disjoint subsets V_1 and V_2 such that every edge connects a vertex in V_1 and a vertex in V_2 .

An equivalent definition of a bipartite graph is a graph where it is possible to color the vertices red or blue so that no two adjacent vertices are of the same color.

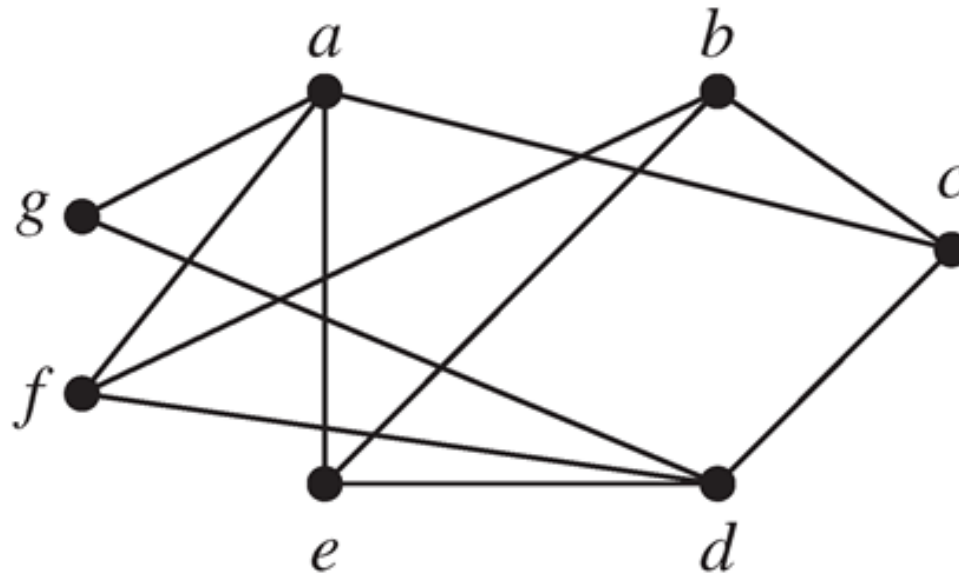
Bipartite Graphs

- **Definition** A simple graph G is *bipartite* if V can be partitioned into two disjoint subsets V_1 and V_2 such that every edge connects a vertex in V_1 and a vertex in V_2 .

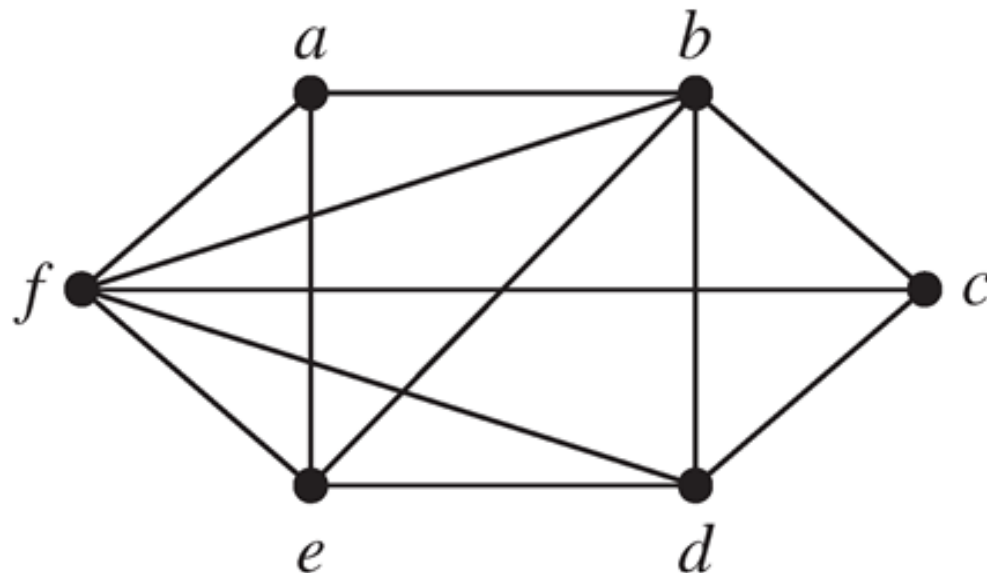
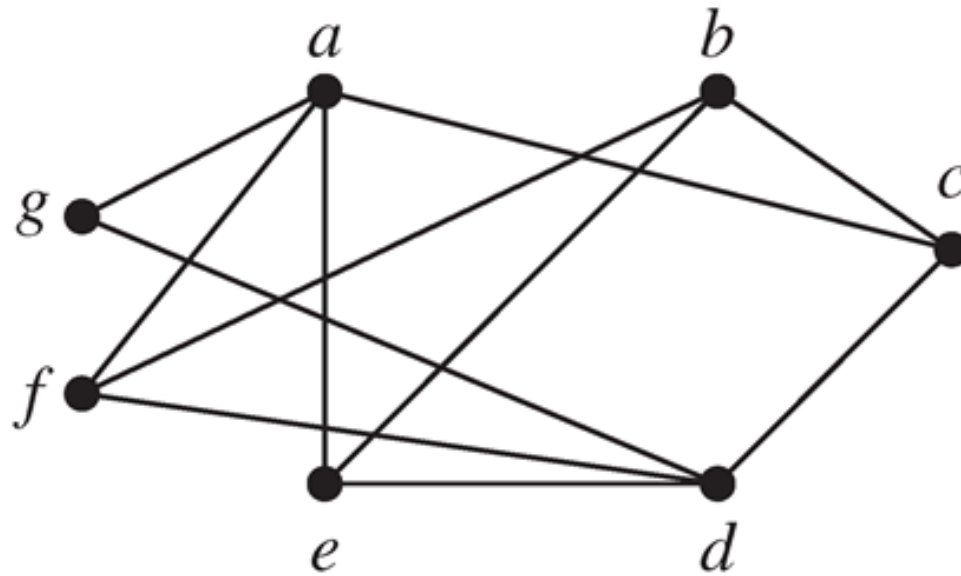
An equivalent definition of a bipartite graph is a graph where it is possible to color the vertices red or blue so that no two adjacent vertices are of the same color.



Bipartite Graphs

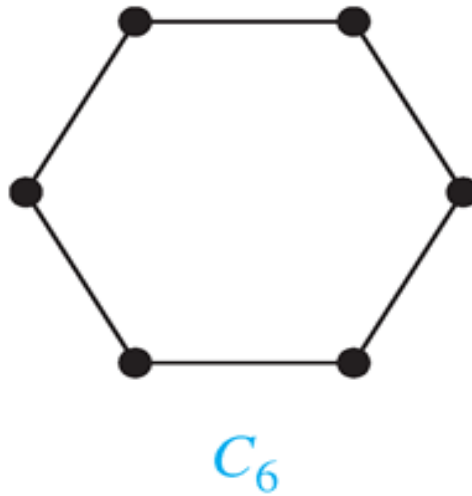


Bipartite Graphs



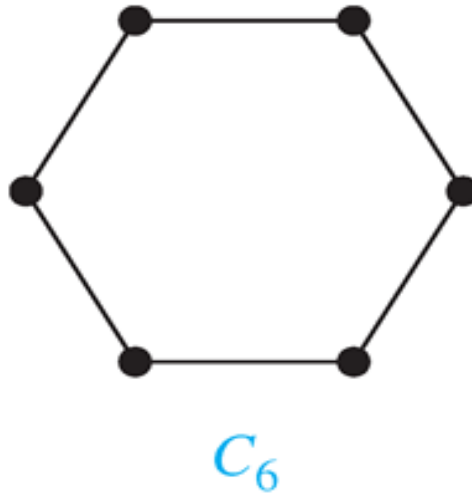
Bipartite Graphs

- **Example** Show that C_6 is bipartite.

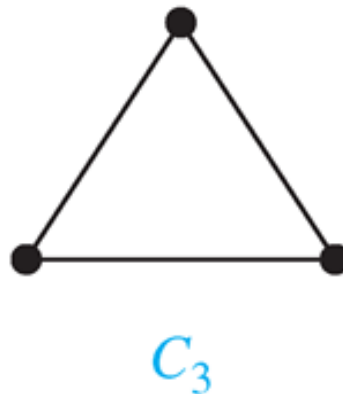


Bipartite Graphs

- **Example** Show that C_6 is bipartite.



Example Show that C_3 is not bipartite.



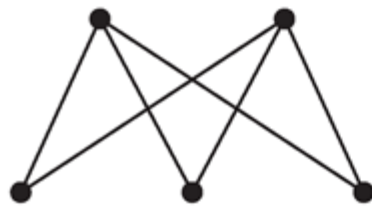
Complete Bipartite Graphs

- **Definition** A *complete bipartite graph* $K_{m,n}$ is a graph that has its vertex set partitioned into two subsets V_1 of size m and V_2 of size n such that there is an edge from every vertex in V_1 to every vertex in V_2 .

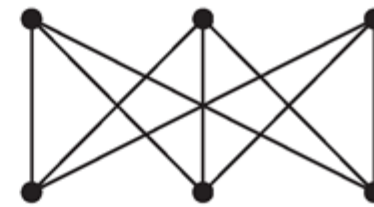


Complete Bipartite Graphs

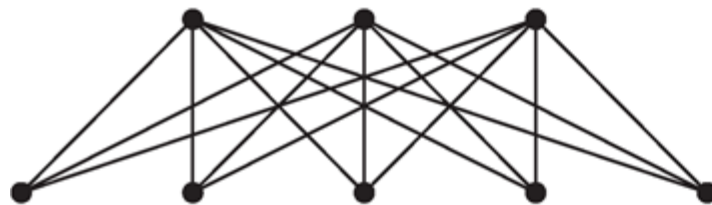
- **Definition** A *complete bipartite graph* $K_{m,n}$ is a graph that has its vertex set partitioned into two subsets V_1 of size m and V_2 of size n such that there is an edge from every vertex in V_1 to every vertex in V_2 .



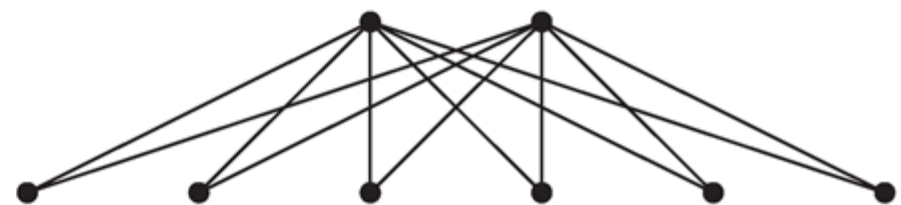
$K_{2,3}$



$K_{3,3}$



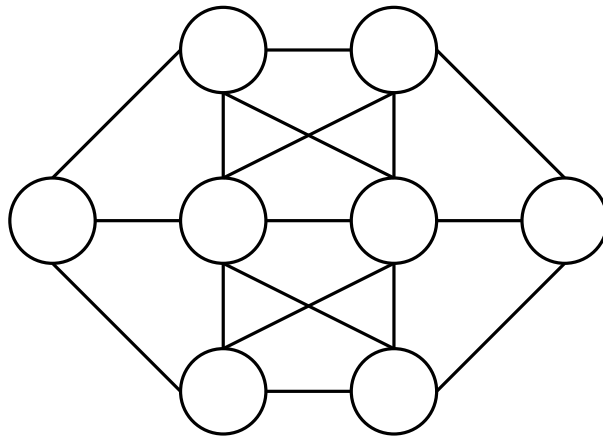
$K_{3,5}$



$K_{2,6}$

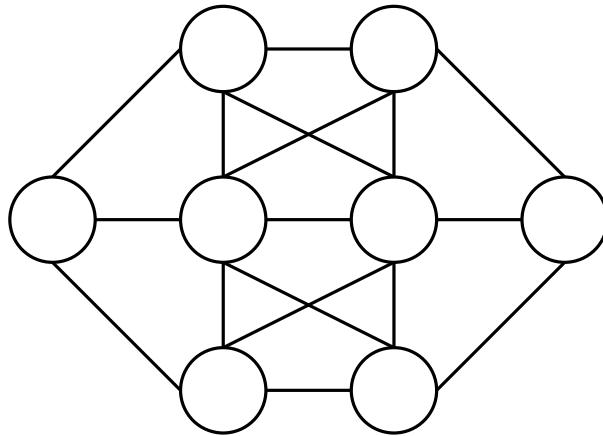
Puzzles using Graphs

- **The eight-circles problem** Place the letters A, B, C, D, E, F, G, H into the eight circles in the figure, in such a way that **no** letter is adjacent to a letter that is next to it in the alphabet.



Puzzles using Graphs

- **The eight-circles problem** Place the letters A, B, C, D, E, F, G, H into the eight circles in the figure, in such a way that **no** letter is adjacent to a letter that is next to it in the alphabet.



- **Six people at a party** Show that, in any gathering of six people, there are either three people who all know each other, or three people none of which knows either of the other two.

Bipartite Graphs and Matchings

- *Matching* the elements of one set to elements in another. A *matching* is a subset of E s.t. **no two edges are incident with the same vertex.**



Bipartite Graphs and Matchings

- *Matching* the elements of one set to elements in another. A *matching* is a subset of E s.t. **no two edges are incident with the same vertex.**

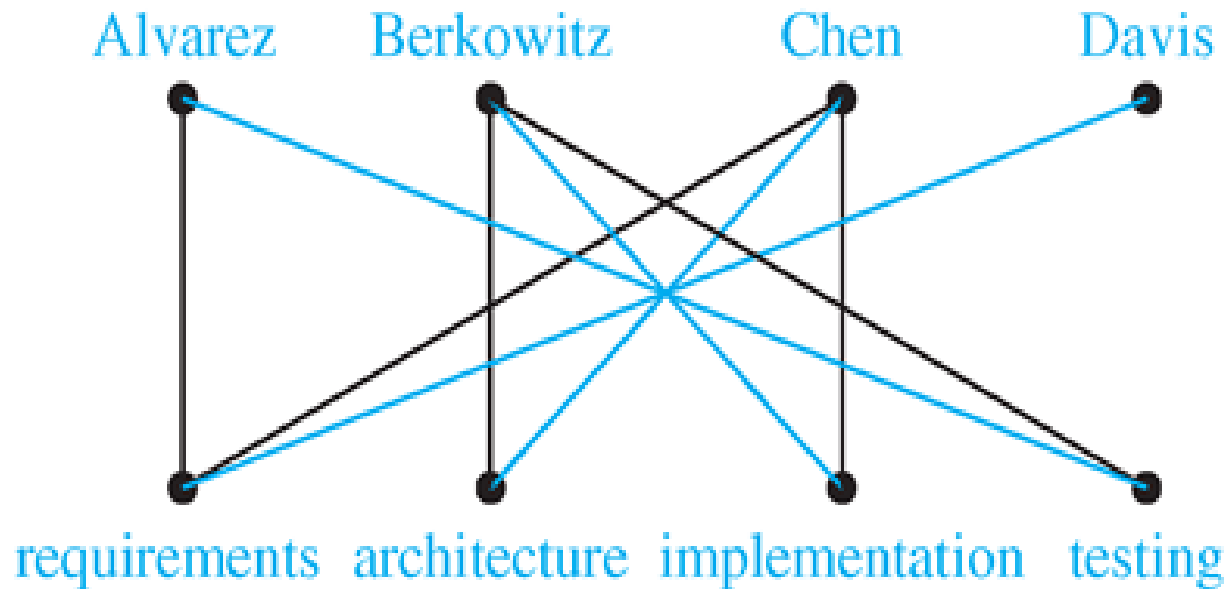
Job assignments: vertices represent the jobs and the employees, edges link employees with those jobs they have been trained to do. A **common goal** is to **match jobs to employees** so that the most jobs are done.



Bipartite Graphs and Matchings

- *Matching* the elements of one set to elements in another. A *matching* is a subset of E s.t. **no two edges are incident with the same vertex**.

Job assignments: vertices represent the jobs and the employees, edges link employees with those jobs they have been trained to do. A **common goal** is to **match jobs to employees** so that the most jobs are done.



Bipartite Graphs and Matchings

- **Definition** A simple graph G is *bipartite* if V can be partitioned into two disjoint subsets V_1 and V_2 such that every edge connects a vertex in V_1 and a vertex in V_2 .

An equivalent definition of a bipartite graph is a graph where it is possible to color the vertices red or blue so that no two adjacent vertices are of the same color.



Bipartite Graphs and Matchings

- **Definition** A simple graph G is *bipartite* if V can be partitioned into two disjoint subsets V_1 and V_2 such that every edge connects a vertex in V_1 and a vertex in V_2 .

An equivalent definition of a *bipartite graph* is a graph where it is possible to color the vertices red or blue so that no two adjacent vertices are of the same color.

Matching the elements of one set to elements in another. A *matching* is a subset of E s.t. no two edges are incident with the same vertex.



Bipartite Graphs and Matchings

- A *maximum matching* is a matching with the largest number of edges.



Bipartite Graphs and Matchings

- A *maximum matching* is a matching with the **largest number of edges**.
A matching M in a bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) is a *complete matching from V_1 to V_2* if **every vertex in V_1 is the endpoint of an edge in the matching**, or equivalently, if $|M| = |V_1|$.

Bipartite Graphs and Matchings

- A *maximum matching* is a matching with the **largest number of edges**.
A matching M in a bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) is a *complete matching from V_1 to V_2* if **every vertex in V_1 is the endpoint of an edge in the matching**, or equivalently, if $|M| = |V_1|$.

Theorem (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a *complete matching from V_1 to V_2* if and only if $|N(A)| \geq |A|$ for **all subsets A of V_1** .



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “only if” \rightarrow

Suppose that there is a complete matching M from V_1 to V_2 .
Consider an arbitrary subset $A \subseteq V_1$.

Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “only if” \rightarrow

Suppose that there is a complete matching M from V_1 to V_2 .

Consider an arbitrary subset $A \subseteq V_1$.

Then, for every vertex $v \in A$, there is an edge in M connecting v to a vertex in V_2 . Thus, there are at least as many vertices in V_2 that are neighbors of vertices in V_1 as there are vertices in V_1 .



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “only if” \rightarrow

Suppose that there is a complete matching M from V_1 to V_2 .

Consider an arbitrary subset $A \subseteq V_1$.

Then, for every vertex $v \in A$, there is an edge in M connecting v to a vertex in V_2 . Thus, there are at least as many vertices in V_2 that are neighbors of vertices in V_1 as there are vertices in V_1 .

Hence, $|N(A)| \geq |A|$.



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Use **strong induction** to prove it.



Proof of Hall's Theorem

- **Theorem** ([Hall's Marriage Theorem](#)) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a [complete matching from \$V_1\$ to \$V_2\$](#) if and only if $|N(A)| \geq |A|$ for [all subsets \$A\$ of \$V_1\$](#) .

Proof. “if” \leftarrow

Use [strong induction](#) to prove it.

Basic step: $|V_1| = 1$

Proof of Hall's Theorem

- **Theorem** ([Hall's Marriage Theorem](#)) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a [complete matching](#) from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for [all subsets](#) A of V_1 .

Proof. “if” \leftarrow

Use **strong induction** to prove it.

Basic step: $|V_1| = 1$

Inductive hypothesis: Let k be a positive integer. If $G = (V, E)$ is a bipartite graph with bipartition (V_1, V_2) , and $|V_1| = j \leq k$, then [there is a complete matching](#) M from V_1 to V_2 whenever the condition that $|N(A)| \geq |A|$ for [all](#) $A \subseteq V_1$ is met.



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Use **strong induction** to prove it.

Basic step: $|V_1| = 1$

Inductive hypothesis: Let k be a positive integer. If $G = (V, E)$ is a bipartite graph with bipartition (V_1, V_2) , and $|V_1| = j \leq k$, then there is a complete matching M from V_1 to V_2 whenever the condition that $|N(A)| \geq |A|$ for all $A \subseteq V_1$ is met.

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.



Proof of Hall's Theorem

- **Theorem** ([Hall's Marriage Theorem](#)) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a [complete matching from \$V_1\$ to \$V_2\$](#) if and only if $|N(A)| \geq |A|$ for [all subsets \$A\$ of \$V_1\$](#) .

Proof. “if” \leftarrow

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.

Case (i): For all integers j with $1 \leq j \leq k$, the vertices in every set of j elements from W_1 are adjacent to at least $j + 1$ elements of W_2

Case (ii): For some integer j with $1 \leq j \leq k$, there is a subset W'_1 of j vertices such that there are exactly j neighbors of these vertices in W_2



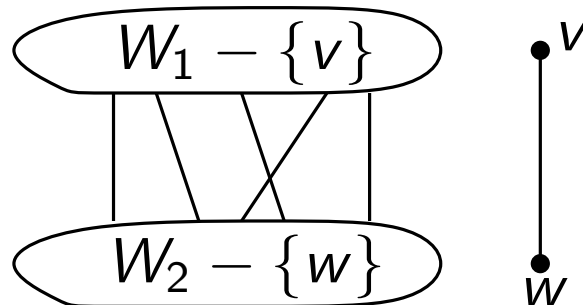
Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.

Case (i):



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.

Case (ii): For some integer j with $1 \leq j \leq k$, there is a subset W'_1 of j vertices such that there are exactly j neighbors of these vertices in W_2



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.

Case (ii): For some integer j with $1 \leq j \leq k$, there is a subset W'_1 of j vertices such that there are exactly j neighbors of these vertices in W_2

Let W'_2 be the set of these neighbors. Then by i.h., there is a complete matching from W'_1 to W'_2 . Now consider the graph $K = (W_1 - W'_1, W_2 - W'_2)$. We will show that the condition $|N(A)| \geq |A|$ is met for all subsets A of $W_1 - W'_1$.



Proof of Hall's Theorem

- **Theorem** (Hall's Marriage Theorem) The bipartite graph $G = (V, E)$ with bipartition (V_1, V_2) has a complete matching from V_1 to V_2 if and only if $|N(A)| \geq |A|$ for all subsets A of V_1 .

Proof. “if” \leftarrow

Inductive step: suppose that $H = (W, F)$ is a bipartite graph with bipartition (W_1, W_2) and $|W_1| = k + 1$.

Case (ii): For some integer j with $1 \leq j \leq k$, there is a subset W'_1 of j vertices such that there are exactly j neighbors of these vertices in W_2 .

Let W'_2 be the set of these neighbors. Then by i.h., there is a complete matching from W'_1 to W'_2 . Now consider the graph $K = (W_1 - W'_1, W_2 - W'_2)$. We will show that the condition $|N(A)| \geq |A|$ is met for all subsets A of $W_1 - W'_1$.

If not, there is a subset B of t vertices with $1 \leq t \leq k + 1 - j$ s.t. $|N(B)| < t$.



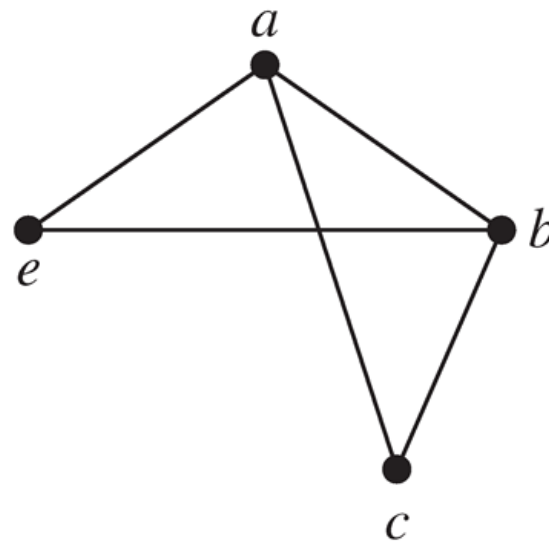
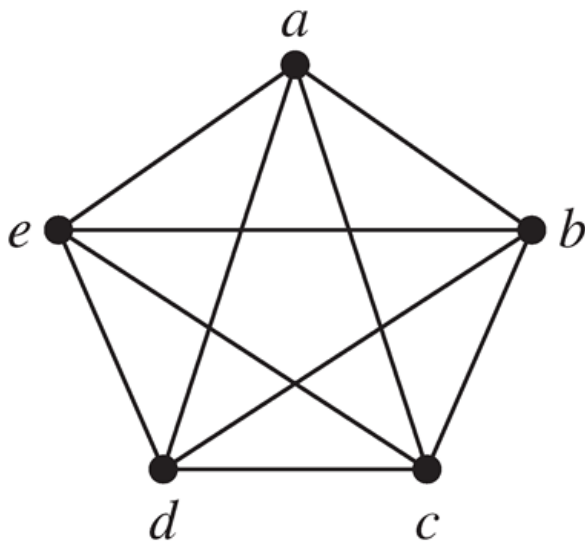
Subgraphs

- **Definition** A *subgraph of a graph* $G = (V, E)$ is a graph (W, F) , where $W \subseteq V$ and $F \subseteq E$. A subgraph H of G is a *proper subgraph* of G if $H \neq G$.



Subgraphs

- **Definition** A *subgraph of a graph* $G = (V, E)$ is a graph (W, F) , where $W \subseteq V$ and $F \subseteq E$. A subgraph H of G is a *proper subgraph* of G if $H \neq G$.



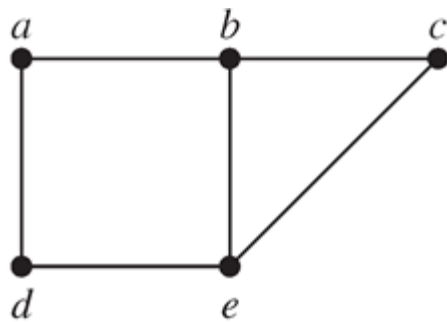
Union of Graphs

- **Definition** The *union of two simple graphs* $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ is the simple graph with vertex set $V_1 \cup V_2$ and edge set $E_1 \cup E_2$, denoted by $G_1 \cup G_2$.

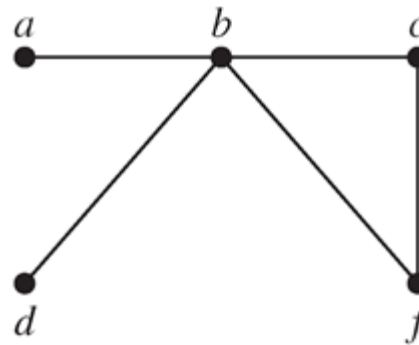


Union of Graphs

- **Definition** The *union of two simple graphs* $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ is the simple graph with vertex set $V_1 \cup V_2$ and edge set $E_1 \cup E_2$, denoted by $G_1 \cup G_2$.



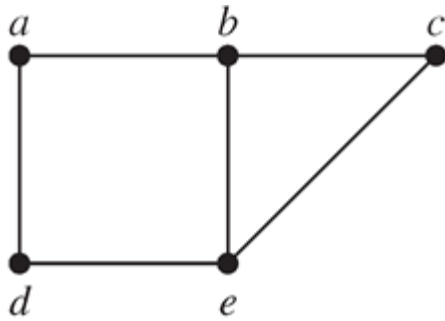
G_1



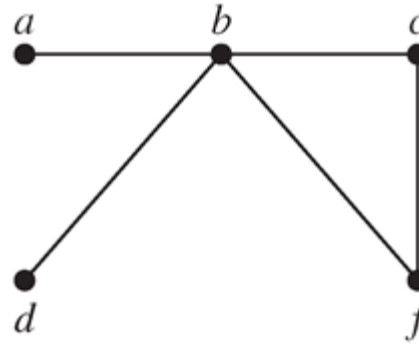
G_2

Union of Graphs

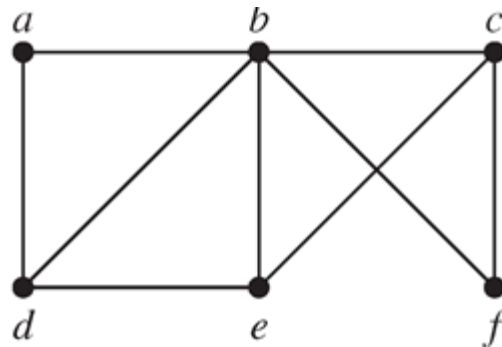
- **Definition** The *union of two simple graphs* $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ is the simple graph with vertex set $V_1 \cup V_2$ and edge set $E_1 \cup E_2$, denoted by $G_1 \cup G_2$.



G_1



G_2



$G_1 \cup G_2$

Representation of Graphs

- To represent a graph, we may use *adjacency lists*, *adjacency matrices*, and *incidence matrices*.



Representation of Graphs

- To represent a graph, we may use *adjacency lists*, *adjacency matrices*, and *incidence matrices*.

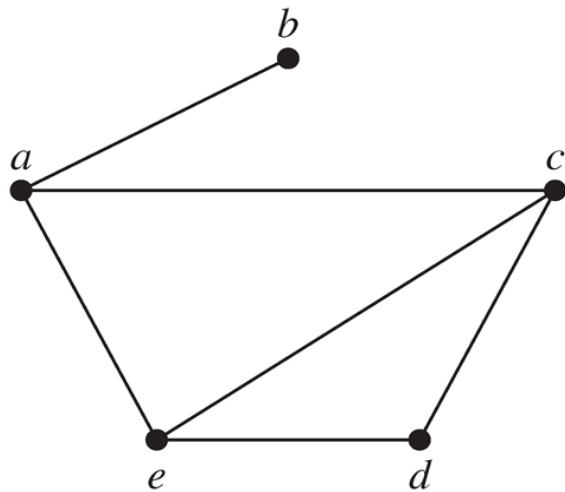
Definition An *adjacency list* can be used to represent a graph with **no multiple edges** by specifying the vertices that are adjacent to each vertex of the graph.



Representation of Graphs

- To represent a graph, we may use *adjacency lists*, *adjacency matrices*, and *incidence matrices*.

Definition An *adjacency list* can be used to represent a graph with **no multiple edges** by specifying the vertices that are adjacent to each vertex of the graph.



Representation of Graphs

- To represent a graph, we may use *adjacency lists*, *adjacency matrices*, and *incidence matrices*.

Definition An *adjacency list* can be used to represent a graph with **no multiple edges** by specifying the vertices that are adjacent to each vertex of the graph.

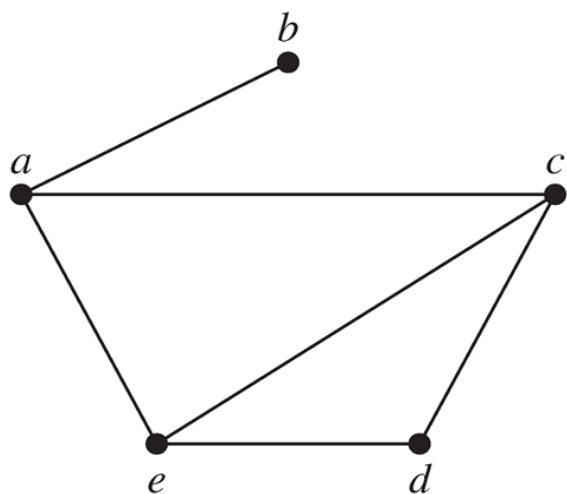
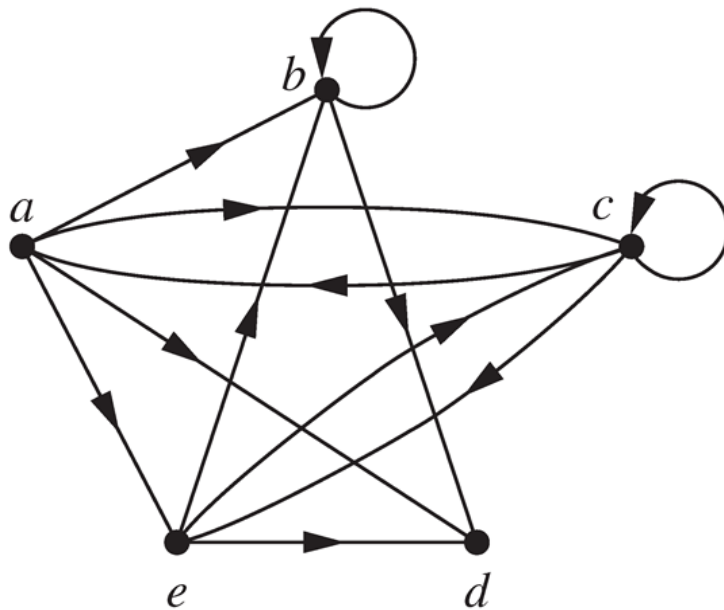


TABLE 1 An Adjacency List for a Simple Graph.

Vertex	Adjacent Vertices
<i>a</i>	<i>b, c, e</i>
<i>b</i>	<i>a</i>
<i>c</i>	<i>a, d, e</i>
<i>d</i>	<i>c, e</i>
<i>e</i>	<i>a, c, d</i>

Representation of Graphs

- **Definition** An *adjacency list* can be used to represent a graph with **no multiple edges** by specifying the vertices that are adjacent to each vertex of the graph.



Representation of Graphs

- **Definition** An *adjacency list* can be used to represent a graph with **no multiple edges** by specifying the vertices that are adjacent to each vertex of the graph.

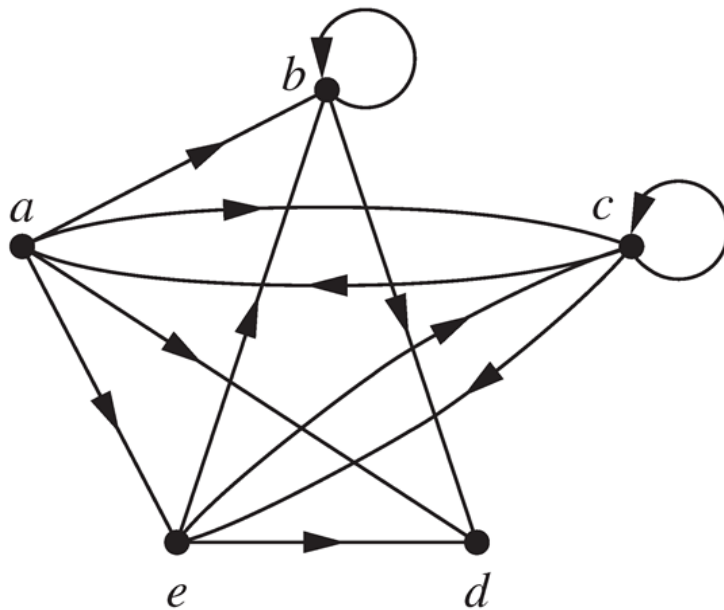


TABLE 2 An Adjacency List for a Directed Graph.

<i>Initial Vertex</i>	<i>Terminal Vertices</i>
<i>a</i>	<i>b, c, d, e</i>
<i>b</i>	<i>b, d</i>
<i>c</i>	<i>a, c, e</i>
<i>d</i>	
<i>e</i>	<i>b, c, d</i>

Adjacency Matrices

- **Definition** Suppose that $G = (V, E)$ is a simple graph with $|V| = n$. Arbitrarily list the vertices of G as v_1, v_2, \dots, v_n . The *adjacency matrix* \mathbf{A}_G of G , is the $n \times n$ zero-one matrix with 1 as its (i, j) -th entry when v_i and v_j are adjacent, and 0 as its (i, j) -th entry when they are not adjacent.



Adjacency Matrices

- **Definition** Suppose that $G = (V, E)$ is a simple graph with $|V| = n$. Arbitrarily list the vertices of G as v_1, v_2, \dots, v_n . The *adjacency matrix* \mathbf{A}_G of G , is the $n \times n$ zero-one matrix with 1 as its (i, j) -th entry when v_i and v_j are adjacent, and 0 as its (i, j) -th entry when they are not adjacent.

$$\mathbf{A}_G = [a_{ij}]_{n \times n}, \text{ where}$$

$$a_{ij} = \begin{cases} 1 & \text{if } \{v_i, v_j\} \text{ is an edge of } G, \\ 0 & \text{otherwise.} \end{cases}$$

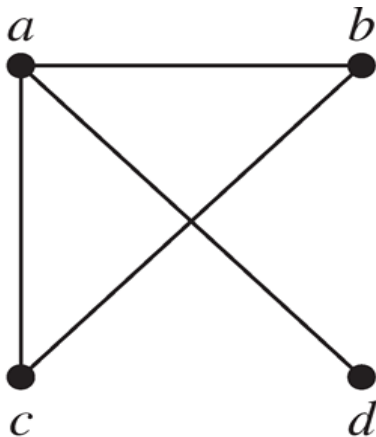


Adjacency Matrices

- **Definition** Suppose that $G = (V, E)$ is a simple graph with $|V| = n$. Arbitrarily list the vertices of G as v_1, v_2, \dots, v_n . The *adjacency matrix* \mathbf{A}_G of G , is the $n \times n$ zero-one matrix with 1 as its (i, j) -th entry when v_i and v_j are adjacent, and 0 as its (i, j) -th entry when they are not adjacent.

$$\mathbf{A}_G = [a_{ij}]_{n \times n}, \text{ where}$$

$$a_{ij} = \begin{cases} 1 & \text{if } \{v_i, v_j\} \text{ is an edge of } G, \\ 0 & \text{otherwise.} \end{cases}$$

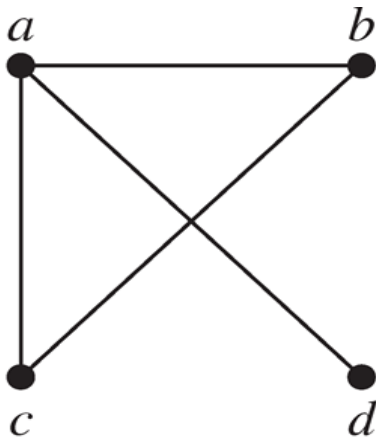


Adjacency Matrices

- **Definition** Suppose that $G = (V, E)$ is a simple graph with $|V| = n$. Arbitrarily list the vertices of G as v_1, v_2, \dots, v_n . The *adjacency matrix* \mathbf{A}_G of G , is the $n \times n$ zero-one matrix with 1 as its (i, j) -th entry when v_i and v_j are adjacent, and 0 as its (i, j) -th entry when they are not adjacent.

$$\mathbf{A}_G = [a_{ij}]_{n \times n}, \text{ where}$$

$$a_{ij} = \begin{cases} 1 & \text{if } \{v_i, v_j\} \text{ is an edge of } G, \\ 0 & \text{otherwise.} \end{cases}$$



$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

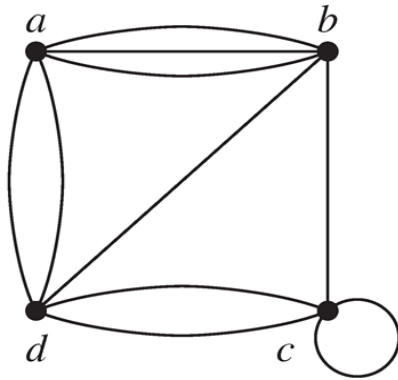
Adjacency Matrices

- Adjacency matrices can also be used to represent graphs with loops and multiple edges. The matrix is no longer a zero-one matrix.



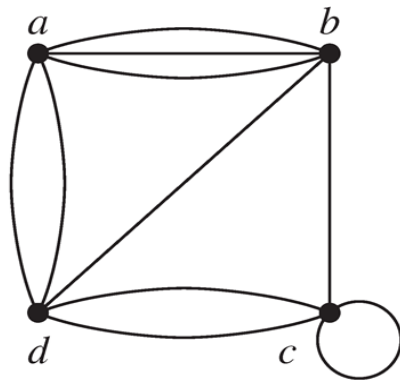
Adjacency Matrices

- Adjacency matrices can also be used to represent graphs with loops and multiple edges. The matrix is no longer a zero-one matrix.



Adjacency Matrices

- Adjacency matrices can also be used to represent graphs with loops and multiple edges. The matrix is no longer a zero-one matrix.



$$\begin{bmatrix} 0 & 3 & 0 & 2 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 1 & 2 \\ 2 & 1 & 2 & 0 \end{bmatrix}$$

Incidence Matrices

- **Definition** Let $G = (V, E)$ be an undirected graph with vertices v_1, v_2, \dots, v_n and edges e_1, e_2, \dots, e_m . The *incidence matrix* with respect to the ordering of V and E is the $n \times m$ matrix $\mathbf{M} = [m_{ij}]_{n \times m}$, where

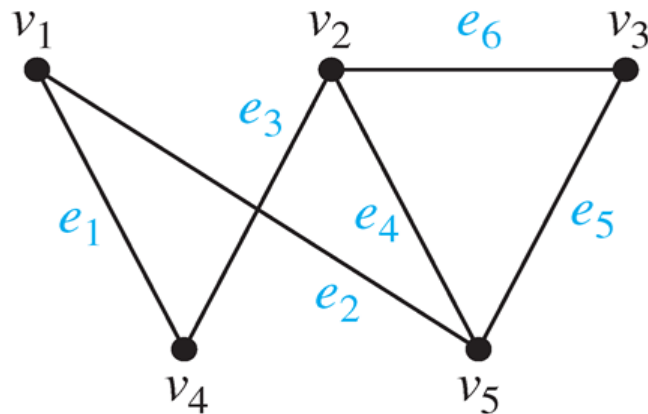
$$m_{ij} = \begin{cases} 1 & \text{if edge } e_j \text{ is incident with } v_i, \\ 0 & \text{otherwise.} \end{cases}$$



Incidence Matrices

- **Definition** Let $G = (V, E)$ be an undirected graph with vertices v_1, v_2, \dots, v_n and edges e_1, e_2, \dots, e_m . The *incidence matrix* with respect to the ordering of V and E is the $n \times m$ matrix $\mathbf{M} = [m_{ij}]_{n \times m}$, where

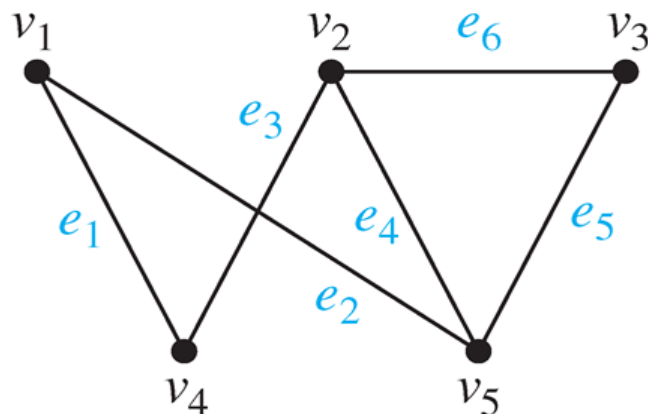
$$m_{ij} = \begin{cases} 1 & \text{if edge } e_j \text{ is incident with } v_i, \\ 0 & \text{otherwise.} \end{cases}$$



Incidence Matrices

- **Definition** Let $G = (V, E)$ be an undirected graph with vertices v_1, v_2, \dots, v_n and edges e_1, e_2, \dots, e_m . The *incidence matrix* with respect to the ordering of V and E is the $n \times m$ matrix $\mathbf{M} = [m_{ij}]_{n \times m}$, where

$$m_{ij} = \begin{cases} 1 & \text{if edge } e_j \text{ is incident with } v_i, \\ 0 & \text{otherwise.} \end{cases}$$

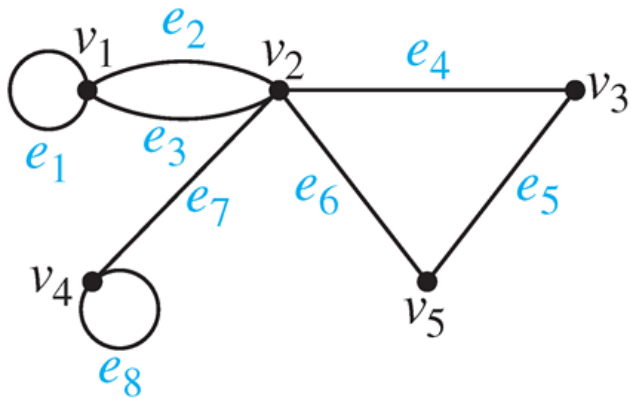


$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 1 & 0 \end{bmatrix}$$

Incidence Matrices

- **Definition** Let $G = (V, E)$ be an undirected graph with vertices v_1, v_2, \dots, v_n and edges e_1, e_2, \dots, e_m . The *incidence matrix* with respect to the ordering of V and E is the $n \times m$ matrix $\mathbf{M} = [m_{ij}]_{n \times m}$, where

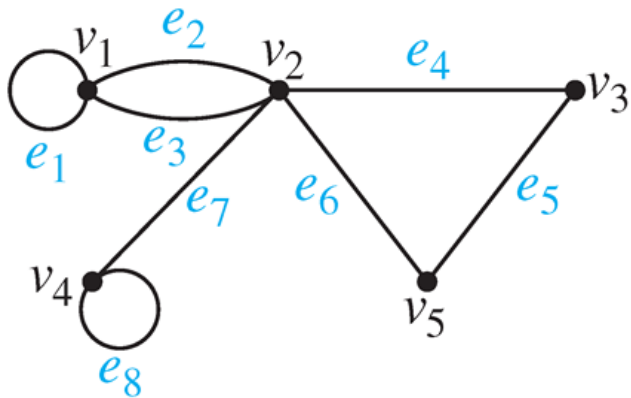
$$m_{ij} = \begin{cases} 1 & \text{if edge } e_j \text{ is incident with } v_i, \\ 0 & \text{otherwise.} \end{cases}$$



Incidence Matrices

- **Definition** Let $G = (V, E)$ be an undirected graph with vertices v_1, v_2, \dots, v_n and edges e_1, e_2, \dots, e_m . The *incidence matrix* with respect to the ordering of V and E is the $n \times m$ matrix $\mathbf{M} = [m_{ij}]_{n \times m}$, where

$$m_{ij} = \begin{cases} 1 & \text{if edge } e_j \text{ is incident with } v_i, \\ 0 & \text{otherwise.} \end{cases}$$



$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}$$

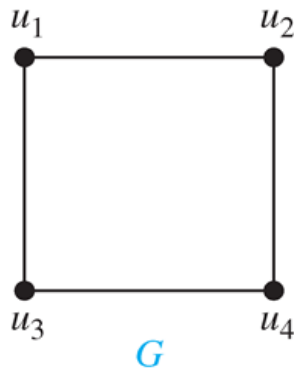
Isomorphism of Graphs

- **Definition** The simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are *isomorphic* if there is a **one-to-one** and **onto** function from V_1 to V_2 with the property that **a and b are adjacent in G_1 if and only if $f(a)$ and $f(b)$ are adjacent in G_2** , for all a and b in V_1 . Such a function is called an *isomorphism*.

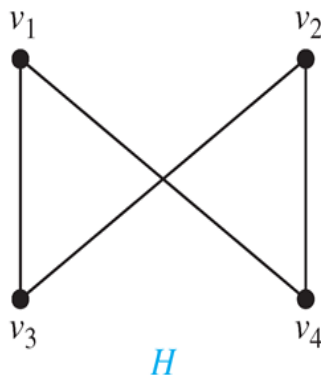


Isomorphism of Graphs

- **Definition** The simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are *isomorphic* if there is a **one-to-one** and **onto** function from V_1 to V_2 with the property that **a and b are adjacent in G_1 if and only if $f(a)$ and $f(b)$ are adjacent in G_2** , for all a and b in V_1 . Such a function is called an *isomorphism*.

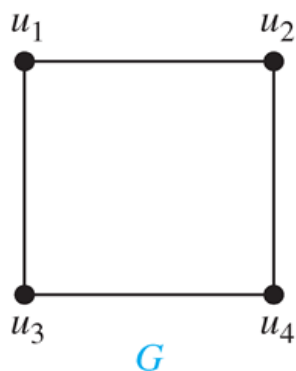


Are the two graphs **isomorphic**?



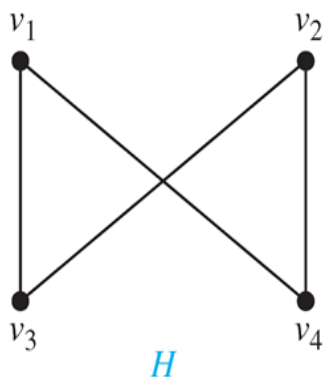
Isomorphism of Graphs

- **Definition** The simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are *isomorphic* if there is a **one-to-one** and **onto** function from V_1 to V_2 with the property that **a and b are adjacent in G_1 if and only if $f(a)$ and $f(b)$ are adjacent in G_2** , for all a and b in V_1 . Such a function is called an *isomorphism*.



Are the two graphs **isomorphic**?

Define a **one-to-one correspondence**:
 $f(u_1) = v_1, f(u_2) = v_4, f(u_3) = v_3,$ and
 $f(u_4) = v_2$



Isomorphism of Graphs

- It is usually **difficult** to determine whether two simple graphs are isomorphic **using brute force** since there are $n!$ possible **one-to-one correspondences**.



Isomorphism of Graphs

- It is usually **difficult** to determine whether two simple graphs are isomorphic **using brute force** since there are $n!$ possible **one-to-one correspondences**.
- Sometimes it is **not difficult** to show that **two graphs are not isomorphic**. We can achieve this by checking some *graph invariants*.



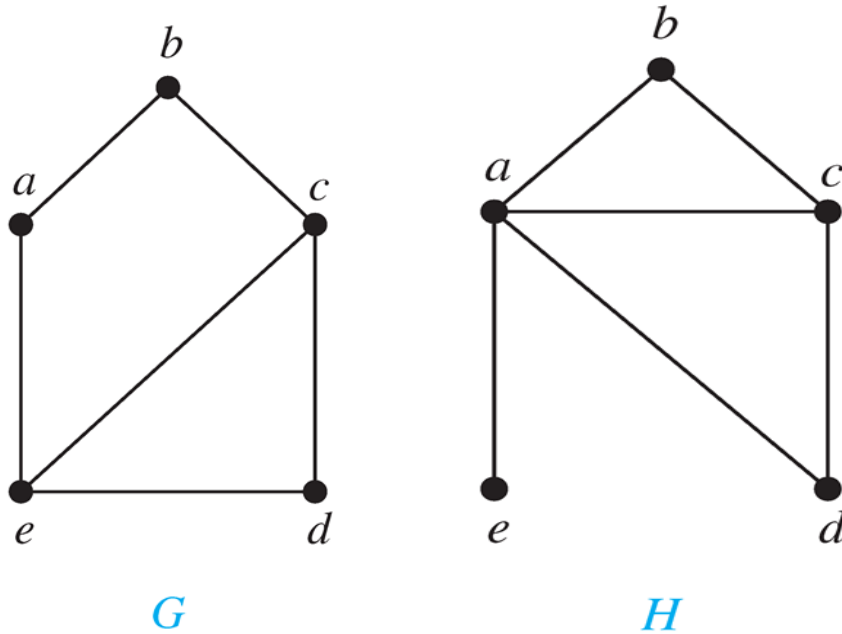
Isomorphism of Graphs

- It is usually **difficult** to determine whether two simple graphs are isomorphic **using brute force** since there are $n!$ possible **one-to-one correspondences**.
- Sometimes it is **not difficult** to show that **two graphs are not isomorphic**. We can achieve this by checking some *graph invariants*.
- Useful **graph invariants** include **the number of vertices**, **number of edges**, **degree sequence**, etc.



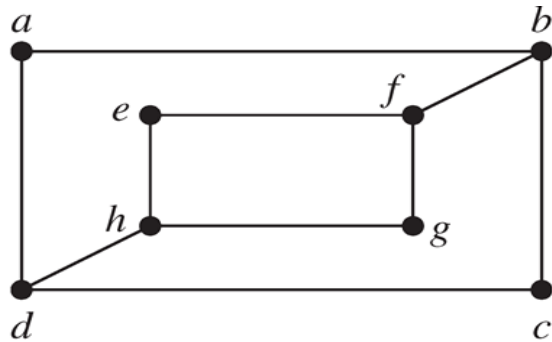
Isomorphism of Graphs

- **Example** Determine whether these two graphs are **isomorphic**.

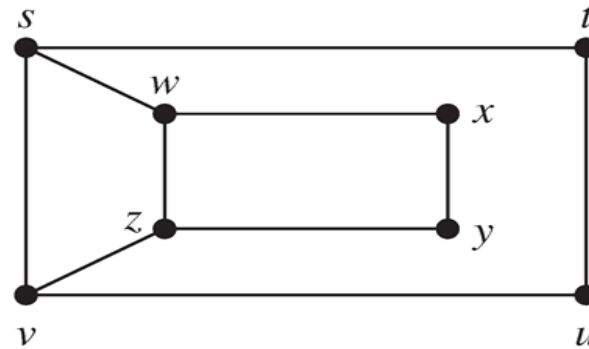


Isomorphism of Graphs

- **Example** Determine whether these two graphs are **isomorphic**.



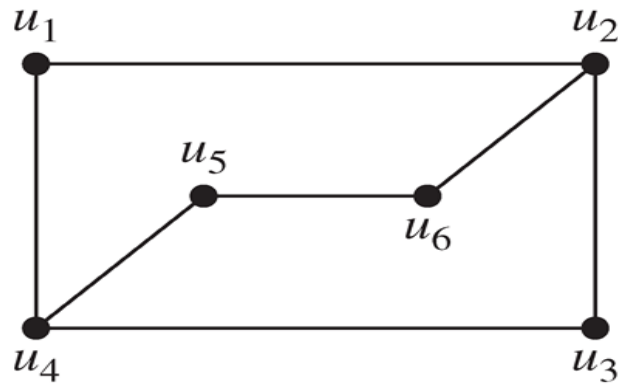
G



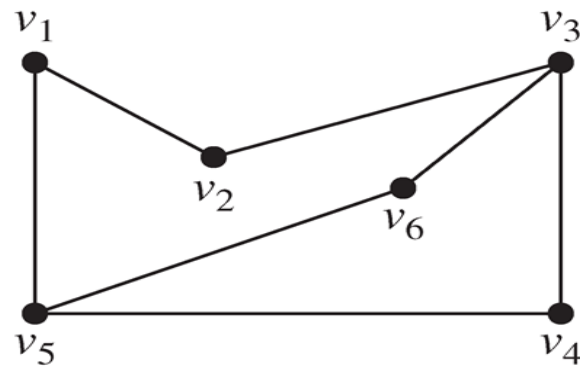
H

Isomorphism of Graphs

- **Example** Determine whether these two graphs are **isomorphic**.



G



H

Path

- **Definition** Let n be a nonnegative integer and G an undirected graph. A *path of length n* from u to v in G is a sequence of *n edges* e_1, e_2, \dots, e_n of G for which there exists a sequence $x_0 = u, x_1, \dots, x_{n-1}, x_n = v$ of vertices such that e_i has the endpoints x_{i-1} and x_i for $i = 1, \dots, n$. The path is a *circuit* if it *begins and ends at the same vertex*, i.e., if $u = v$ and has length greater than zero. A path or circuit is *simple* if it *does not* contain *the same edge* more than once.

Path

- **Definition** Let n be a nonnegative integer and G an undirected graph. A *path of length n* from u to v in G is a sequence of n edges e_1, e_2, \dots, e_n of G for which there exists a sequence $x_0 = u, x_1, \dots, x_{n-1}, x_n = v$ of vertices such that e_i has the endpoints x_{i-1} and x_i for $i = 1, \dots, n$. The path is a *circuit* if it *begins and ends at the same vertex*, i.e., if $u = v$ and has length greater than zero. A path or circuit is *simple* if it *does not* contain *the same edge* more than once.
 - ◇ it *starts and ends with a vertex*
 - ◇ each edge joins *the vertex before it* in the sequence to *the vertex after it* in the sequence
 - ◇ *no edge appears more than once* in the sequence



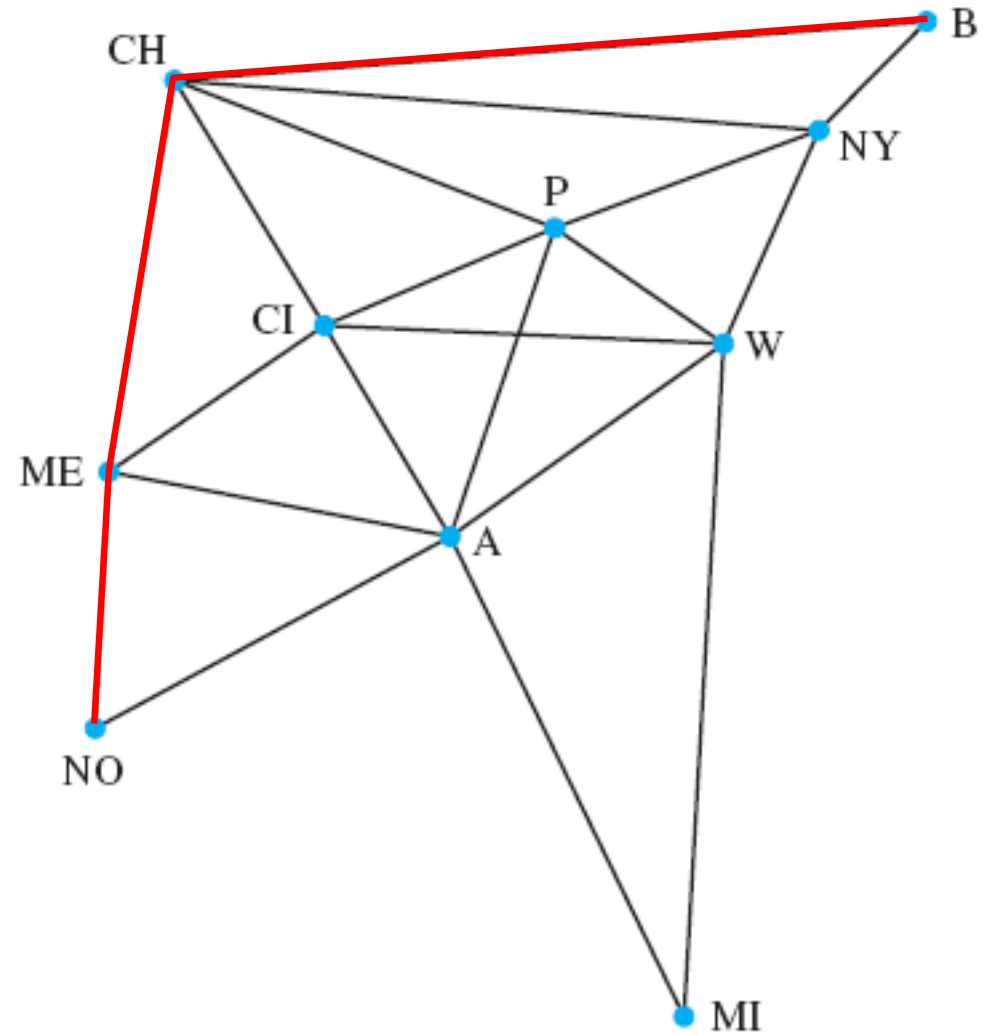
Path

- **Definition** Let n be a nonnegative integer and G an undirected graph. A *path of length n* from u to v in G is a sequence of n edges e_1, e_2, \dots, e_n of G for which there exists a sequence $x_0 = u, x_1, \dots, x_{n-1}, x_n = v$ of vertices such that e_i has the endpoints x_{i-1} and x_i for $i = 1, \dots, n$. The path is a *circuit* if it *begins and ends at the same vertex*, i.e., if $u = v$ and has length greater than zero. A path or circuit is *simple* if it *does not* contain *the same edge* more than once.
- ◇ it *starts and ends with a vertex*
 - ◇ each edge joins *the vertex before it* in the sequence to *the vertex after it* in the sequence
 - ◇ *no edge appears more than once* in the sequence

Length of a *path* = # of edges on path

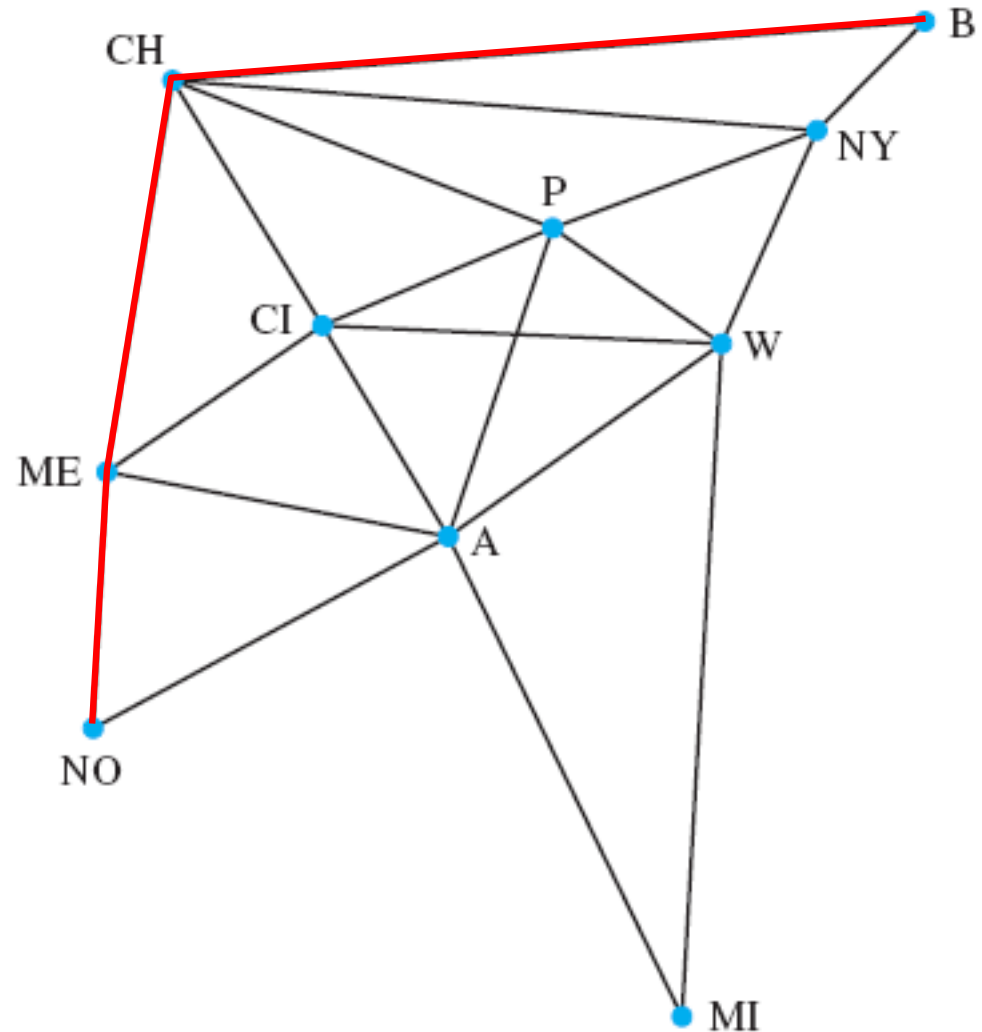


Path



Path

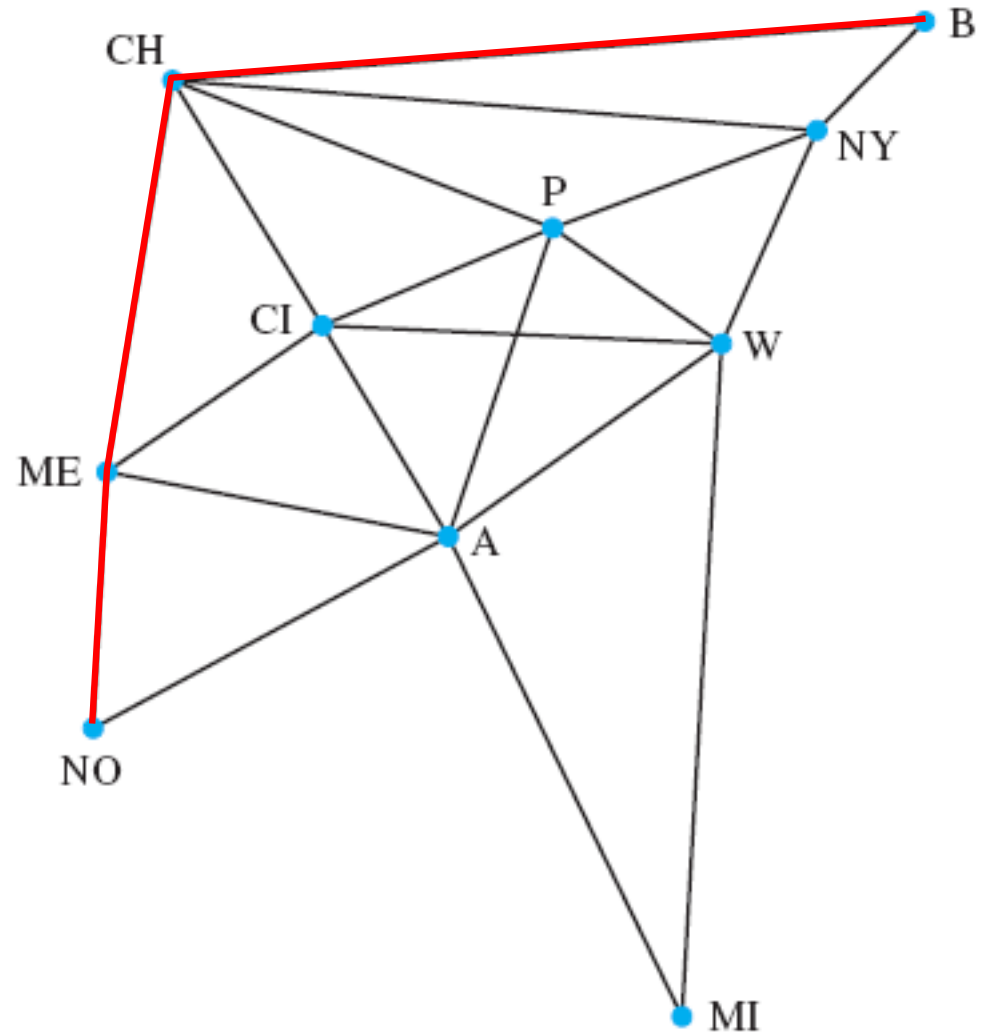
Path from Boston to New Orleans is B, CH, ME, NO



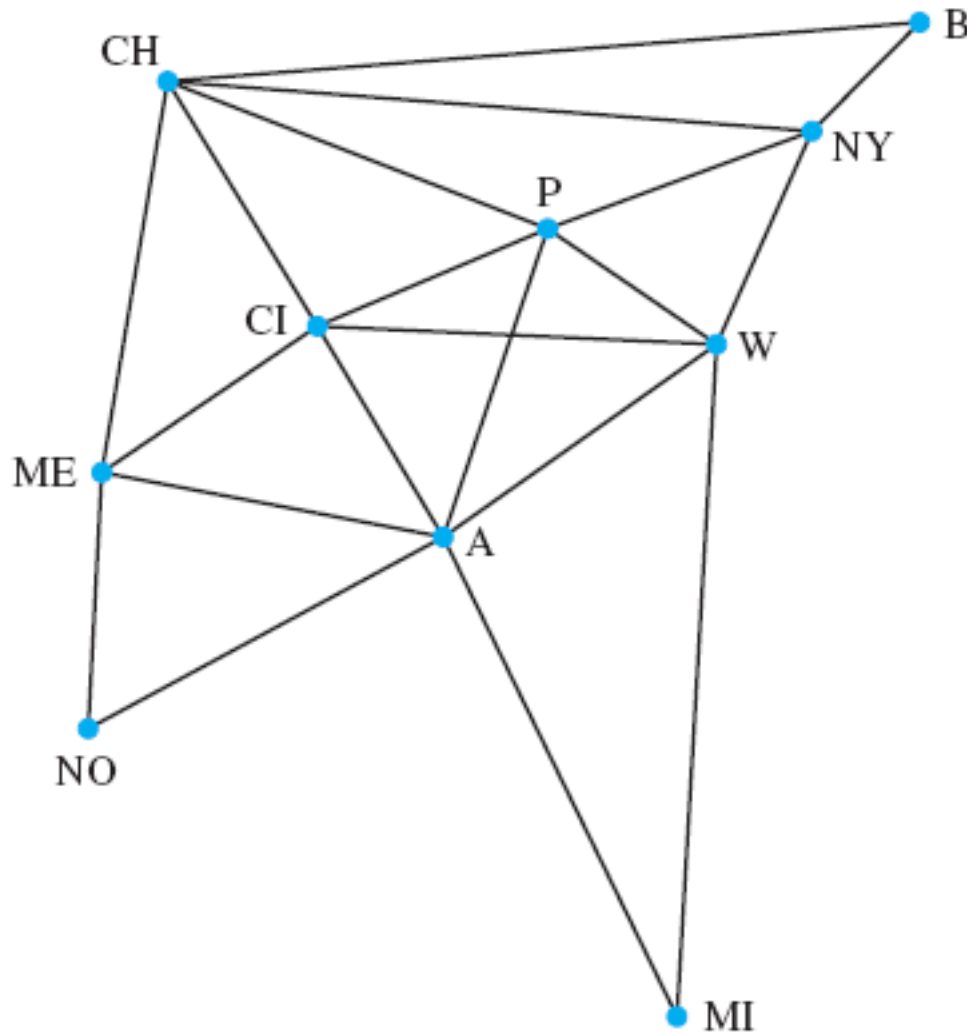
Path

Path from Boston to New Orleans is B, CH, ME, NO

This path has length 3.



Connectivity



Company decides to lease only **minimum number** of communication lines it needs to be able to send a message from any city to any other city by using any number of intermediate cities.

What is the **minimum** number of lines it needs to lease?

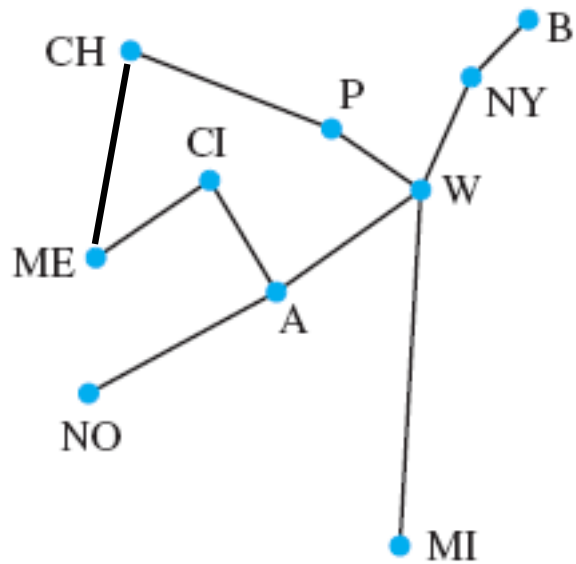
Connectivity

- Choosing 10 edges?



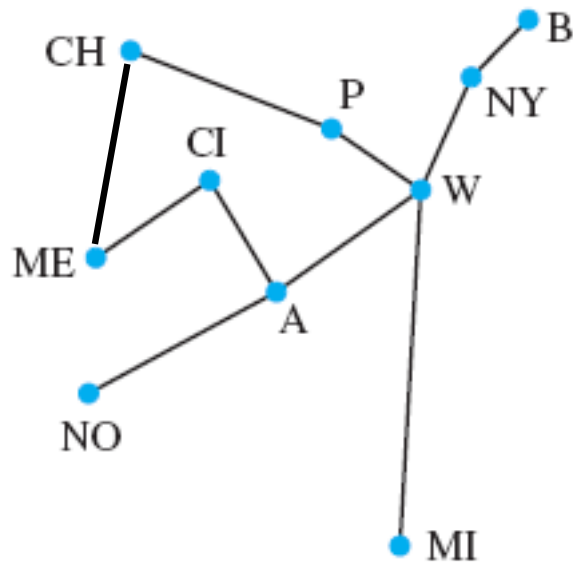
Connectivity

- Choosing 10 edges?



Connectivity

- Choosing 10 edges?

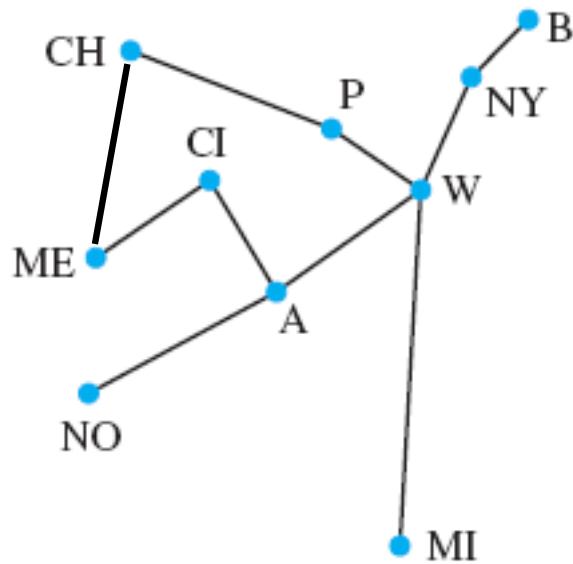


Too many.

Could throw away edge **CI**, **A**, and still have a solution.

Connectivity

- Choosing 10 edges?



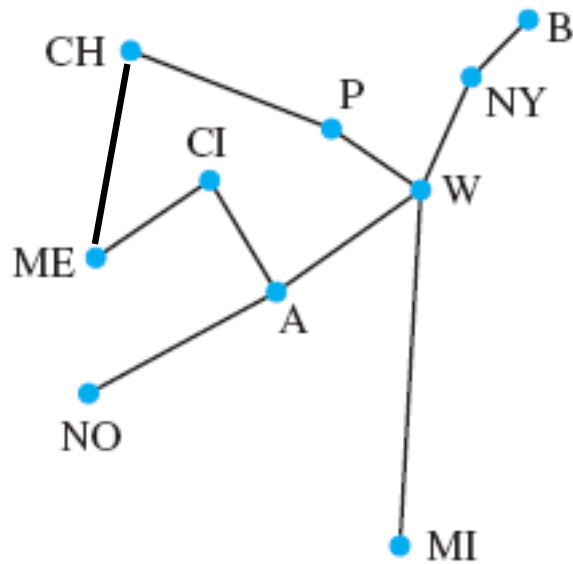
Too many.

Could throw away edge **CI**, **A**, and still have a solution.

Choosing 8 edges?

Connectivity

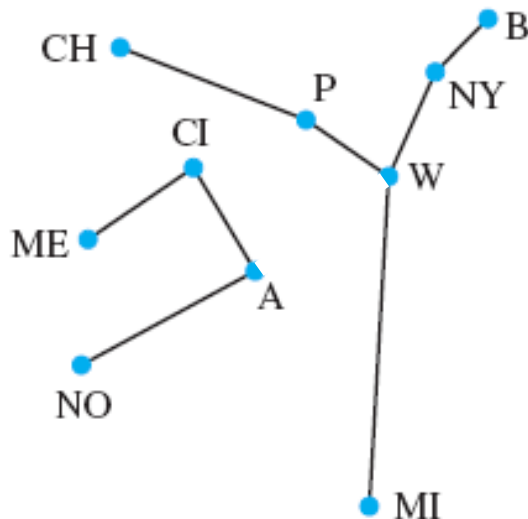
- Choosing 10 edges?



Too many.

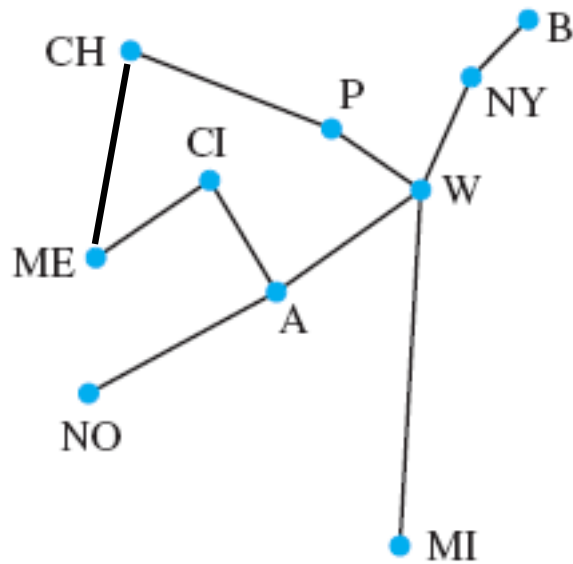
Could throw away edge **CI**, **A**, and still have a solution.

Choosing 8 edges?



Connectivity

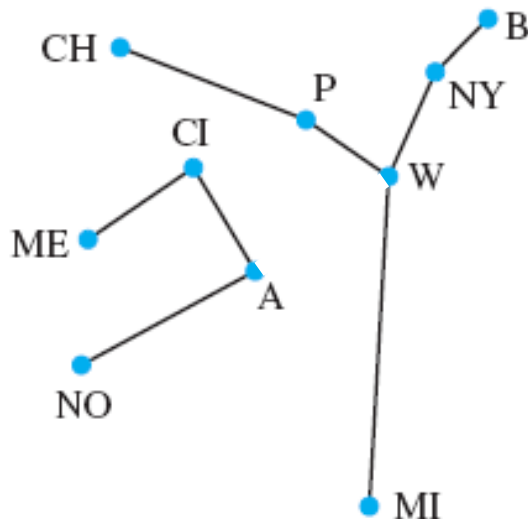
- Choosing 10 edges?



Too many.

Could throw away edge **CI**, **A**, and still have a solution.

Choosing 8 edges?



Not enough.

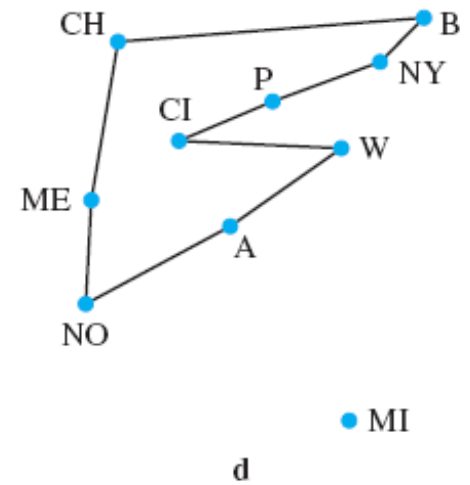
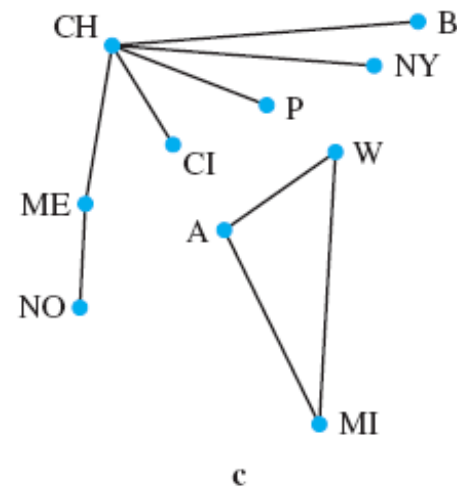
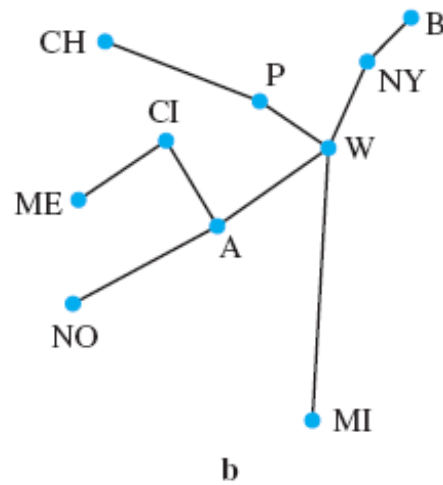
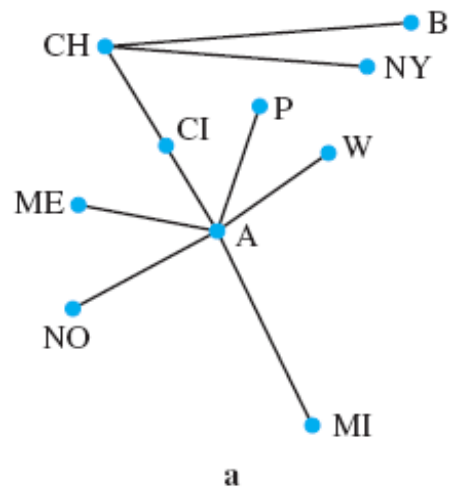
There is **no path** from, e.g., **NO** to **B**.

Connectivity

- Choosing 9 edges:

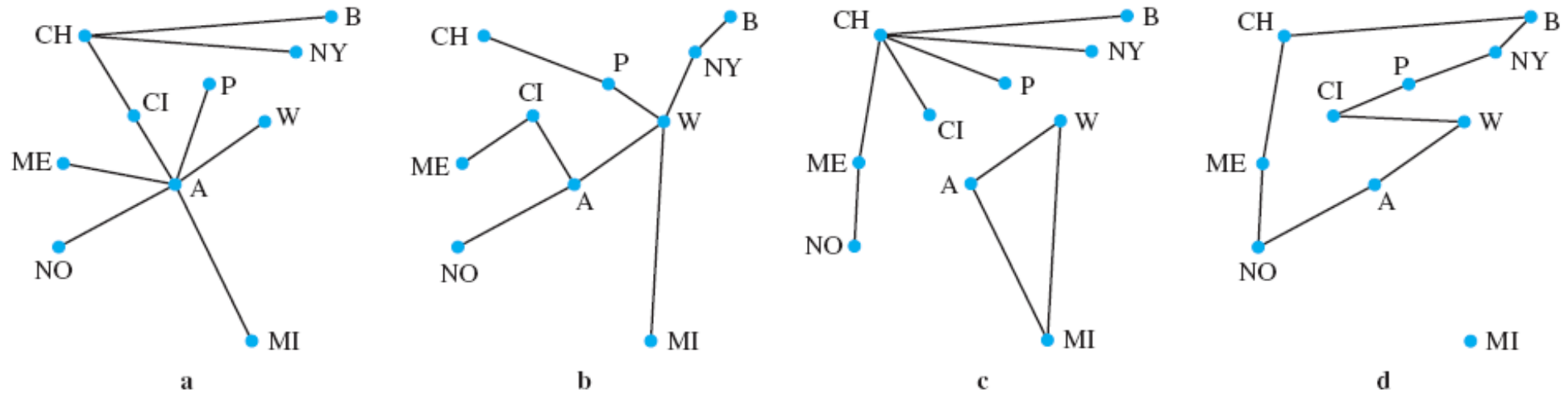
Connectivity

■ Choosing 9 edges:



Connectivity

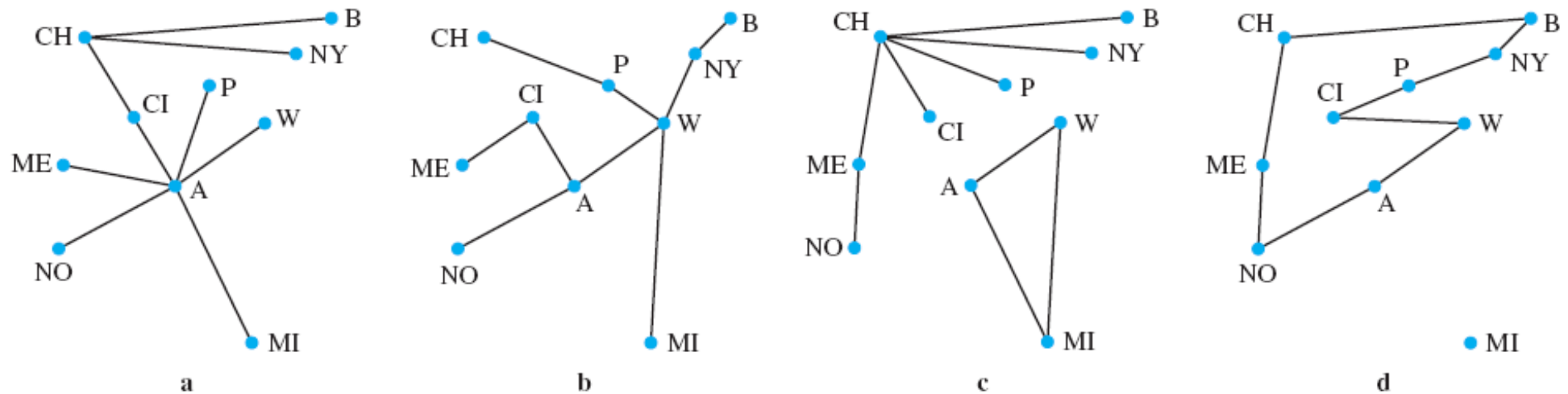
■ Choosing 9 edges:



Two vertices are *connected* if there is a path between them.

Connectivity

■ Choosing 9 edges:

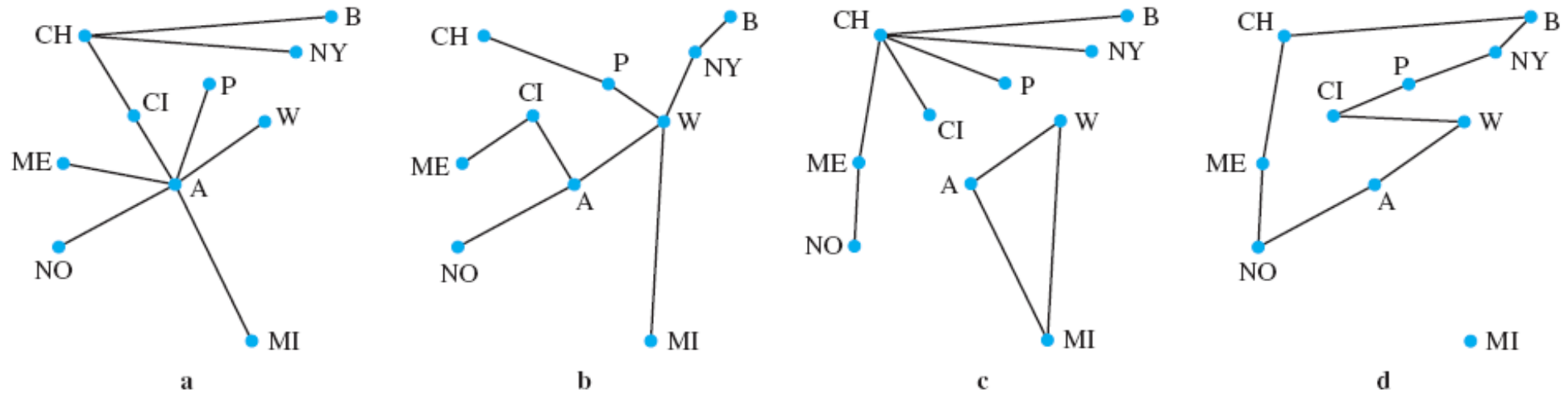


Two vertices are *connected* if there is a path between them.

Example: W, B are *connected* in (b), but are *disconnected* in (c).

Connectivity

■ Choosing 9 edges:



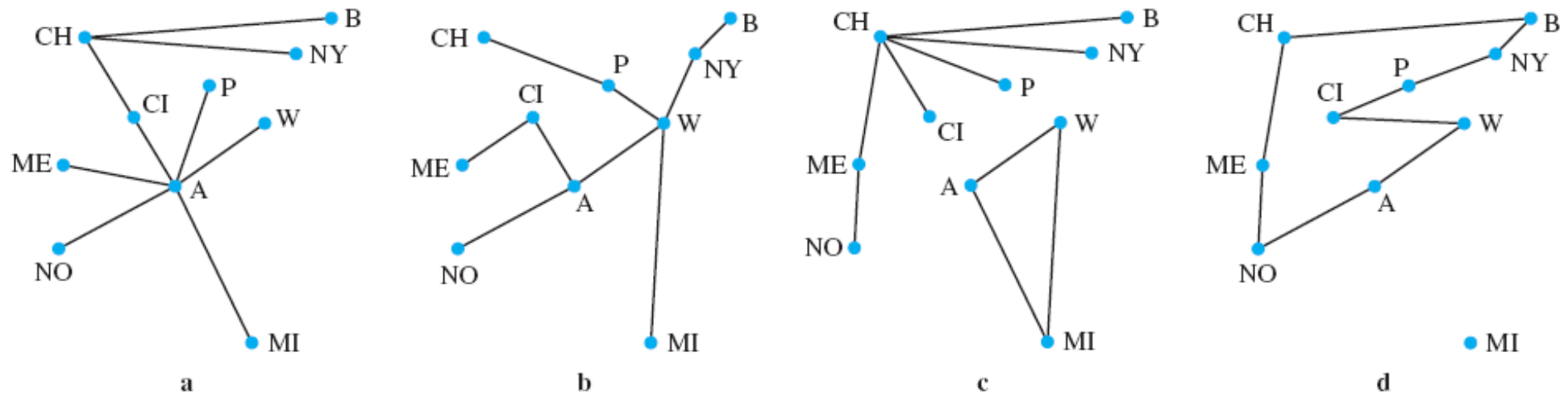
Two vertices are *connected* if there is a path between them.

Example: W, B are *connected* in (b), but are *disconnected* in (c).

Definition An undirected graph is called *connected* if there is a path between every pair of distinct vertices of the graph.

Connectivity

■ Choosing 9 edges:



Two vertices are *connected* if there is a path between them.

Example: W, B are *connected* in (b), but are *disconnected* in (c).

Definition An undirected graph is called *connected* if there is a path between every pair of distinct vertices of the graph.

Example: (a) and (b) are *connected*, (c) and (d) are *disconnected*.

Path

- **Lemma** If there is a path between two distinct vertices x and y of a graph G , then there is a simple path between x and y in G .



Path

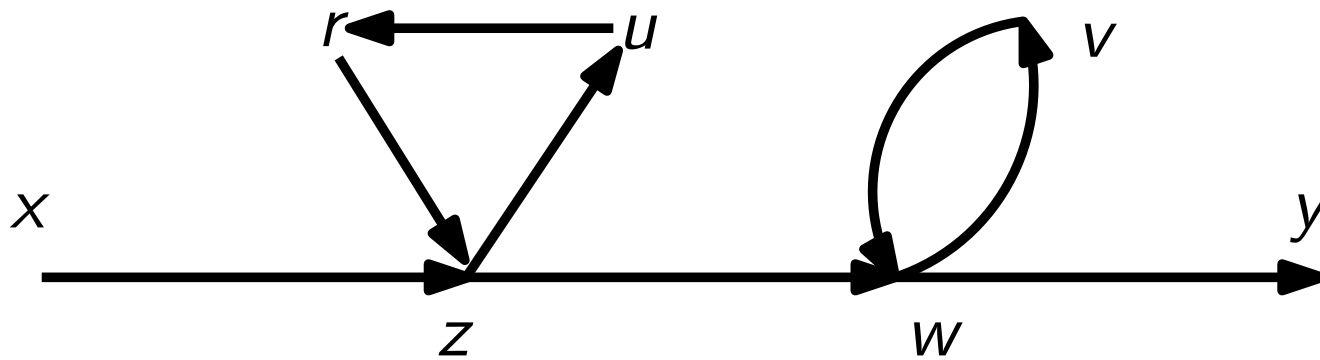
- **Lemma** If there is a path between two distinct vertices x and y of a graph G , then there is a simple path between x and y in G .

Proof Just delete cycles (loops).

Path

- **Lemma** If there is a path between two distinct vertices x and y of a graph G , then there is a simple path between x and y in G .

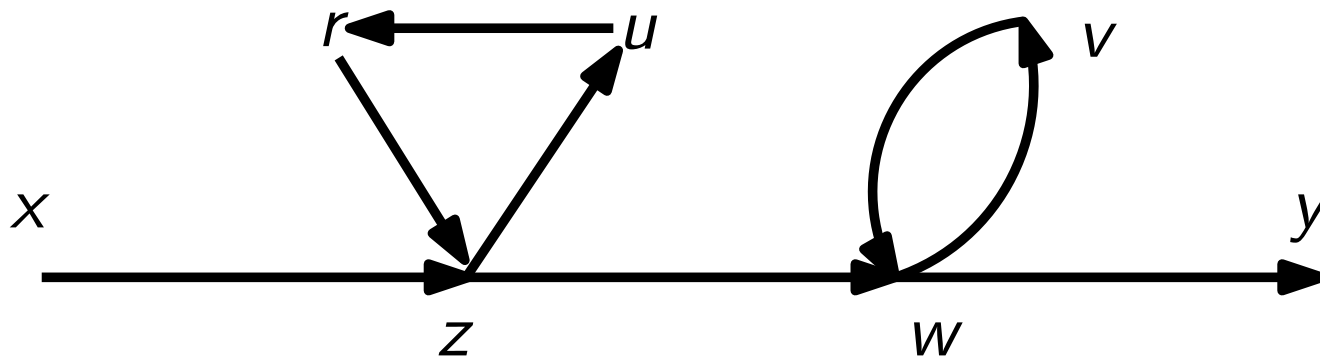
Proof Just delete cycles (loops).



Path

- **Lemma** If there is a path between two distinct vertices x and y of a graph G , then there is a simple path between x and y in G .

Proof Just delete cycles (loops).



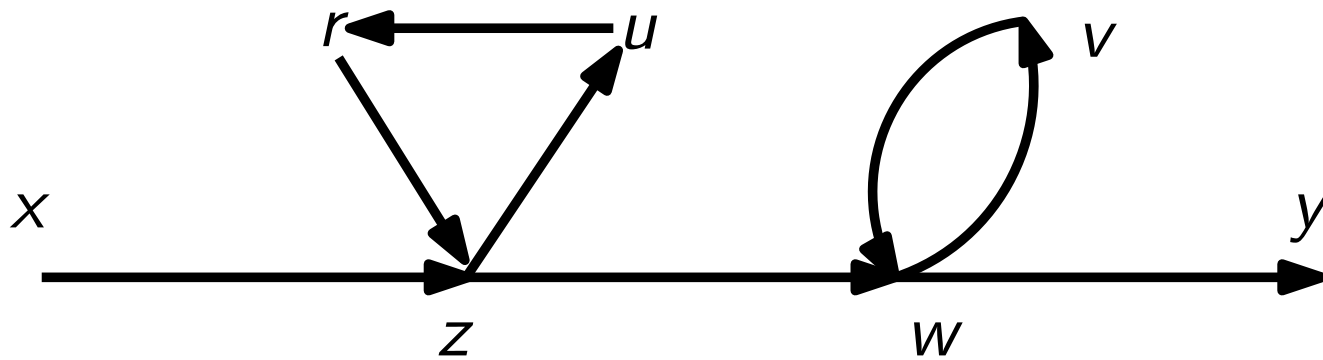
Path from x to y

$x, z, u, r, z, w, v, w, y$.

Path

- **Lemma** If there is a path between two distinct vertices x and y of a graph G , then there is a simple path between x and y in G .

Proof Just delete cycles (loops).



Path from x to y
 $x, z, u, r, z, w, v, w, y$.

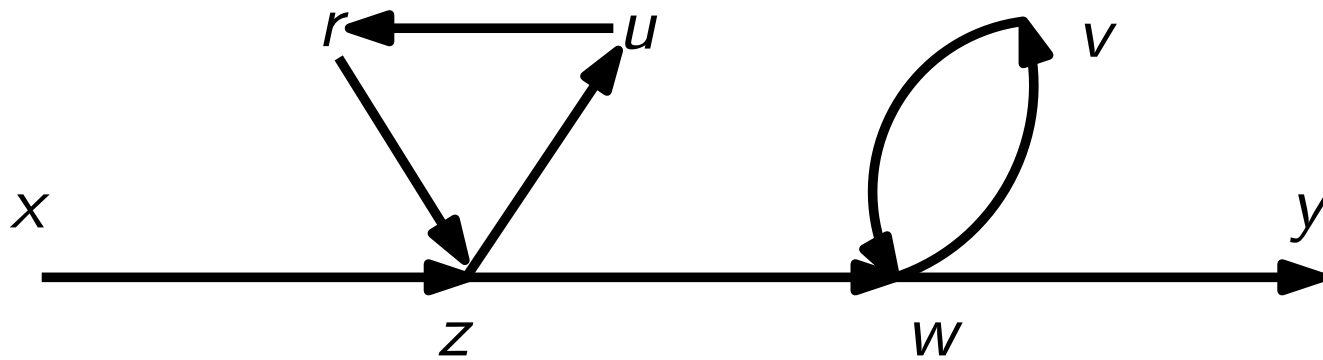


Path from x to y
 x, z, w, y .

Path

- **Lemma** If there is a path between two distinct vertices x and y of a graph G , then there is a simple path between x and y in G .

Proof Just delete cycles (loops).



Path from x to y

$x, z, u, r, z, w, v, w, y$.



Path from x to y

x, z, w, y .

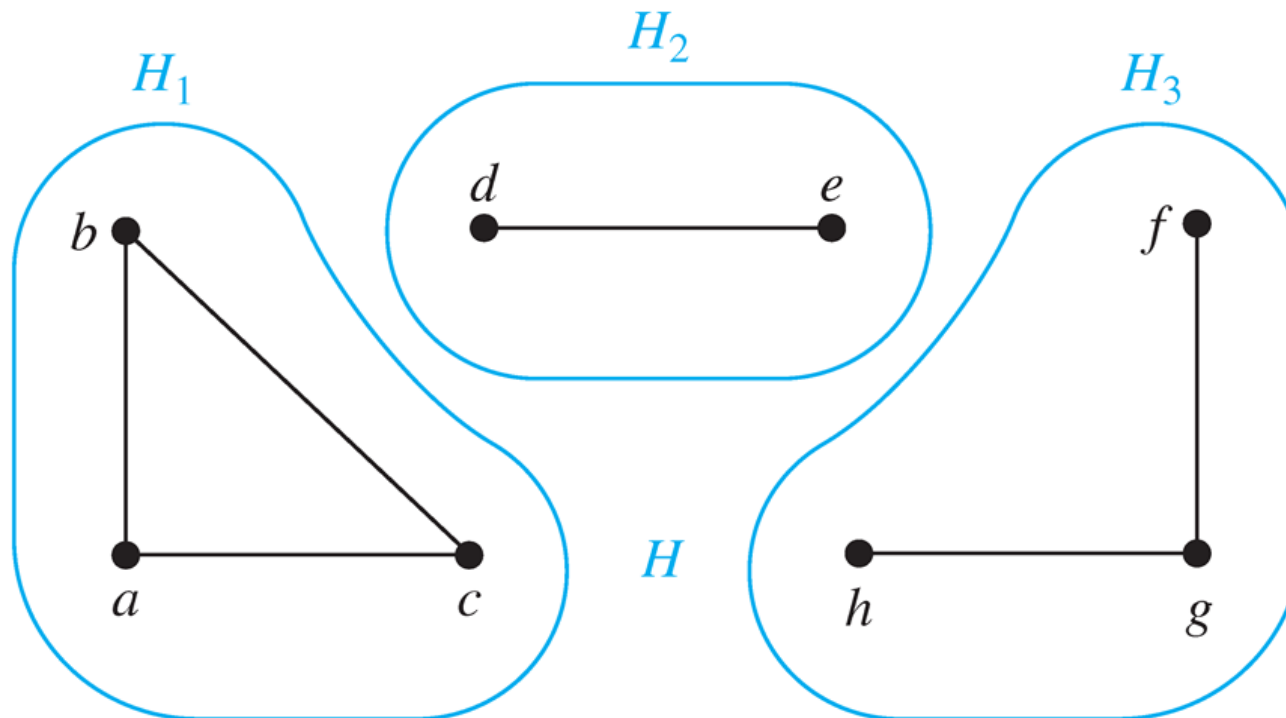
Theorem There is a simple path between every pair of distinct vertices of a connected undirected graph.

Connected Components

- **Definition** A *connected component* of a graph G is a connected *subgraph* of G that is *not a proper subgraph of another connected subgraph* of G .

Connected Components

- **Definition** A *connected component* of a graph G is a connected subgraph of G that is not a proper subgraph of another connected subgraph of G .



Connectedness in Directed Graphs

- **Definition** A directed graph is *strongly connected* if there is a path from a to b and a path from b to a whenever a and b are vertices in the graph.



Connectedness in Directed Graphs

- **Definition** A **directed graph** is *strongly connected* if there is a path **from a to b** and a path **from b to a** whenever a and b are vertices in the graph.

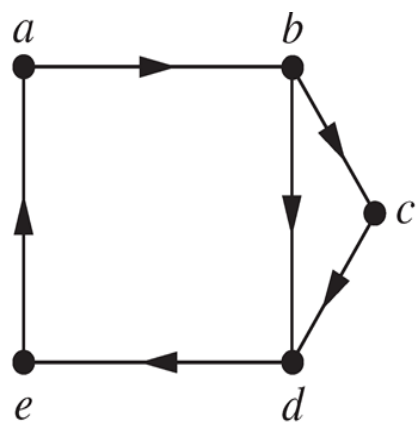
Definition A **directed graph** is *weakly connected* if there is a path between **every two vertices in the underlying undirected graph**, which is the undirected graph obtained by ignoring the directions of the edges in the directed graph.



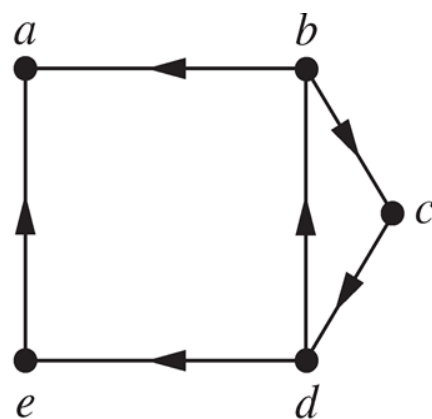
Connectedness in Directed Graphs

- **Definition** A directed graph is *strongly connected* if there is a path from a to b and a path from b to a whenever a and b are vertices in the graph.

Definition A directed graph is *weakly connected* if there is a path between every two vertices in the underlying undirected graph, which is the undirected graph obtained by ignoring the directions of the edges in the directed graph.



G



H

Cut Vertices and Cut Edges

- Sometimes the removal from a graph of a vertex and all incident edges **disconnect** the graph. Such vertices are called **cut vertices**. Similarly we may define **cut edges**.

Cut Vertices and Cut Edges

- Sometimes the removal from a graph of a vertex and all incident edges **disconnect** the graph. Such vertices are called **cut vertices**. Similarly we may define **cut edges**.

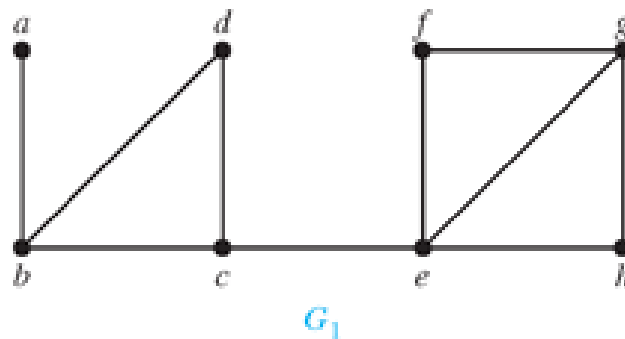
A set of edges E' is called an **edge cut** of G if the subgraph $G - E'$ is **disconnected**. The **edge connectivity** $\lambda(G)$ is the **minimum number** of edges in an edge cut of G .



Cut Vertices and Cut Edges

- Sometimes the removal from a graph of a vertex and all incident edges **disconnect** the graph. Such vertices are called **cut vertices**. Similarly we may define **cut edges**.

A set of edges E' is called an **edge cut** of G if the subgraph $G - E'$ is **disconnected**. The **edge connectivity** $\lambda(G)$ is the **minimum number** of edges in an edge cut of G .



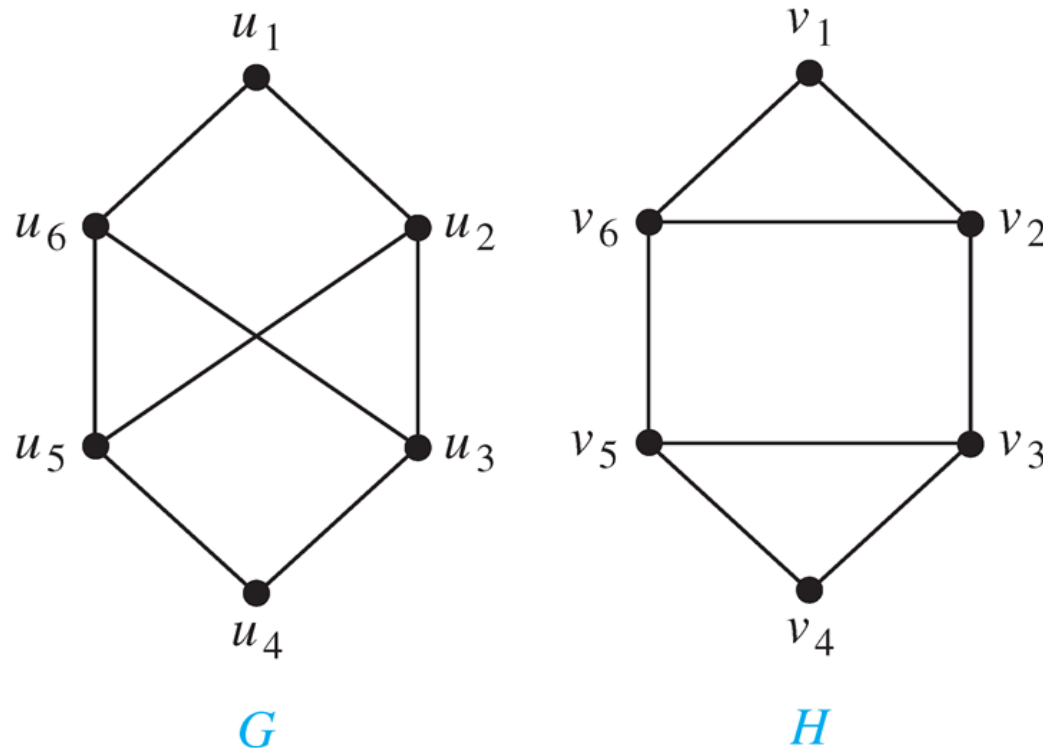
Paths and Isomorphism

- The existence of a simple circuit of length k is **isomorphic invariant**. In addition, **paths** can be used to construct mappings that may be **isomorphisms**.



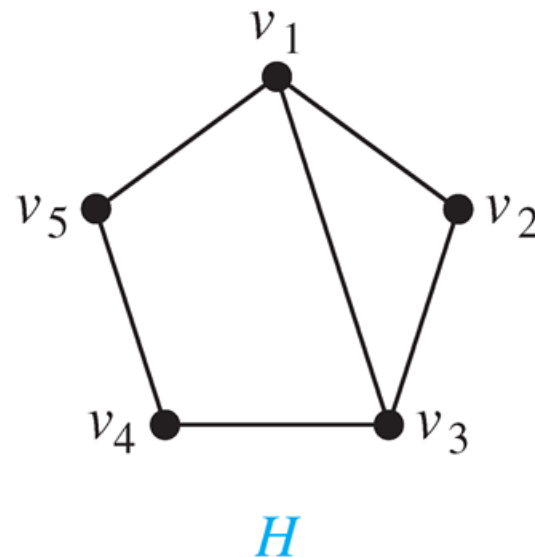
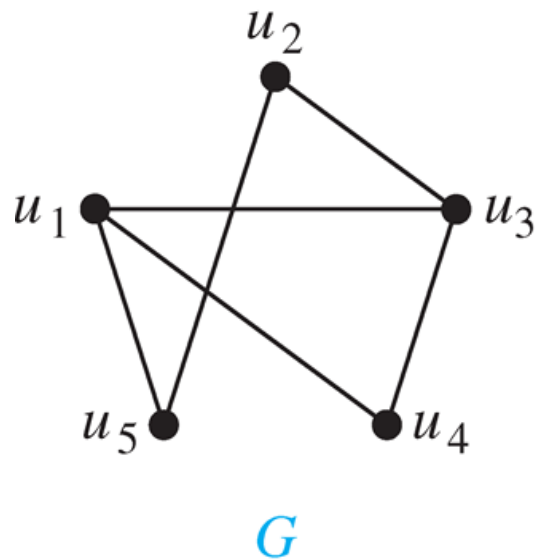
Paths and Isomorphism

- The existence of a simple circuit of length k is **isomorphic invariant**. In addition, **paths** can be used to construct mappings that may be **isomorphisms**.



Paths and Isomorphism

- The existence of a simple circuit of length k is **isomorphic invariant**. In addition, **paths** can be used to construct mappings that may be **isomorphisms**.



Counting Paths between Vertices

- **Theorem** Let G be a graph with adjacency matrix \mathbf{A} with respect to the ordering v_1, v_2, \dots, v_n of vertices. The number of different paths of length r from v_i to v_j , where $r > 0$ is positive, equals the (i, j) -th entry of \mathbf{A}^r .



Counting Paths between Vertices

- **Theorem** Let G be a graph with adjacency matrix \mathbf{A} with respect to the ordering v_1, v_2, \dots, v_n of vertices. The number of different paths of length r from v_i to v_j , where $r > 0$ is positive, equals the (i, j) -th entry of \mathbf{A}^r .

Proof (by **induction**)



Counting Paths between Vertices

- **Theorem** Let G be a graph with adjacency matrix \mathbf{A} with respect to the ordering v_1, v_2, \dots, v_n of vertices. The number of different paths of length r from v_i to v_j , where $r > 0$ is positive, equals the (i, j) -th entry of \mathbf{A}^r .

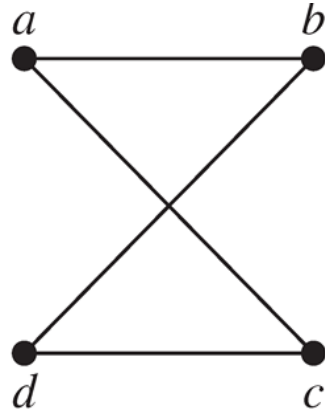
Proof (by **induction**)

$\mathbf{A}^{r+1} = \mathbf{A}^r \mathbf{A}$, the (i, j) -th entry of \mathbf{A}^{r+1} equals $b_{i1}a_{1j} + b_{i2}a_{2j} + \dots + b_{in}a_{nj}$, where b_{ik} is the (i, k) -th entry of \mathbf{A}^r .



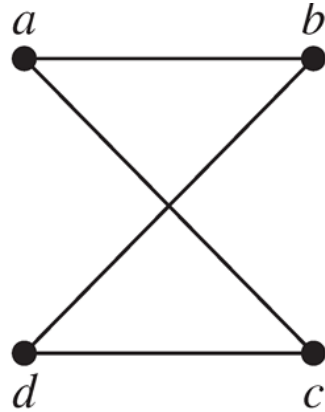
Counting Paths between Vertices

- **Example** How many paths of length 4 are there from a to d in the graph G ?



Counting Paths between Vertices

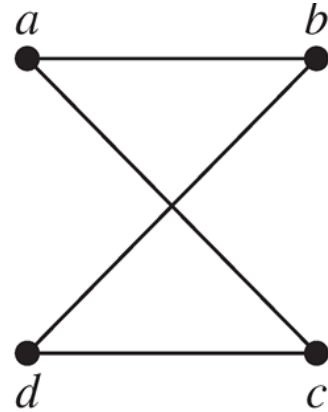
- **Example** How many paths of length 4 are there from a to d in the graph G ?



$$\begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

Counting Paths between Vertices

- **Example** How many paths of length 4 are there from a to d in the graph G ?



$$\begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 0 & 0 & 8 \\ 0 & 8 & 8 & 0 \\ 0 & 8 & 8 & 0 \\ 8 & 0 & 0 & 8 \end{bmatrix}$$

Next Lecture

- Graph theory II ...

