Hiding Computations in Projection

Pascal Leroy (pleroy)

2017-08-13

Notation: A and B are the extremities of the segment; C is the centre of the sphere; R is the radius of the sphere; K is the location of the camera.

We start our analysis by eliminating a case that would cause anomalies in the computations below. If

$$\overrightarrow{KC} \cdot \overrightarrow{KC} < R^2$$

then the camera is inside the sphere and the segment is hidden irrespective of its position.

Next, consider the plane that contains K and is orthogonal to $\overrightarrow{KC}$; it separates the entire space into two half-spaces. If the segment $\overline{AB}$ is entirely within the half-space that does not contain C then the segment is not hidden. This is the case if the following inequalities are both true

$$\overrightarrow{KA} \cdot \overrightarrow{KC} < 0$$
$$\overrightarrow{KB} \cdot \overrightarrow{KC} < 0.$$

For simplicity we will do the rest of our analysis in the plane KAB. We will use $(\overrightarrow{KA}, \overrightarrow{KB})$ as a basis of that plane. Let H be the orthogonal projection of C on KAB. Define α, β to be its coordinates in KAB

$$\overrightarrow{KH} = \alpha \overrightarrow{KA} + \beta \overrightarrow{KB}.$$

Note that $\overrightarrow{KH} = \overrightarrow{KC} + \overrightarrow{CH}$. By its definition, $\overrightarrow{CH}$ is orthogonal to both $\overrightarrow{KA}$ and $\overrightarrow{KB}$

$$\overrightarrow{KA} \cdot \overrightarrow{CH} = 0$$
$$\overrightarrow{KB} \cdot \overrightarrow{CH} = 0,$$

or

$$\overrightarrow{KA} \cdot \overrightarrow{KH} = \overrightarrow{KA} \cdot \overrightarrow{KC}$$
$$\overrightarrow{KB} \cdot \overrightarrow{KH} = \overrightarrow{KB} \cdot \overrightarrow{KC}.$$

Expanding $\overrightarrow{KH}$ gives a linear system of two equations with two unknowns

$$\alpha \overrightarrow{KA} \cdot \overrightarrow{KA} + \beta \overrightarrow{KA} \cdot \overrightarrow{KB} = \overrightarrow{KA} \cdot \overrightarrow{KC}$$
$$\alpha \overrightarrow{KA} \cdot \overrightarrow{KB} + \alpha \overrightarrow{KB} \cdot \overrightarrow{KB} = \overrightarrow{KB} \cdot \overrightarrow{KC}.$$

The determinant of this system is

$$D = (\overrightarrow{KA} \cdot \overrightarrow{KA})(\overrightarrow{KB} \cdot \overrightarrow{KB}) - (\overrightarrow{KA} \cdot \overrightarrow{KB})^2,$$

which is non-zero if and only if A ≠ B. The solutions are thus

$$\alpha = \frac{(\overrightarrow{KB} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KC}) - (\overrightarrow{KA} \cdot \overrightarrow{KB})(\overrightarrow{KB} \cdot \overrightarrow{KC})}{D}$$

$$\beta = \frac{(\overrightarrow{KA} \cdot \overrightarrow{KA})(\overrightarrow{KB} \cdot \overrightarrow{KC}) - (\overrightarrow{KA} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KC})}{D}.$$

Now that $\overrightarrow{KH}$ is determined we can compute $\overrightarrow{CH} = \overrightarrow{KH} - \overrightarrow{KC}$. If $\overrightarrow{CH} \cdot \overrightarrow{CH} \geq R^2$, the sphere is either tangent to the plane KAB or doesn't intersect it. Thus, there is no hiding.

Let's look at a figure in the plane KAB when the sphere intersects that plane. Let r be the radius of the intersection circle; it is such that $r^2 = R^2 - \overrightarrow{CH} \cdot \overrightarrow{CH}$.

If the circle doesn't intersect the wedge KAB then the segment AB is entirely visible. To find if this is the case, first observe that, if θ is the angle between $\overrightarrow{KA}$ and $\overrightarrow{KB}$, we have

$$\overrightarrow{KA} \cdot \overrightarrow{KB} = |\overrightarrow{KA}||\overrightarrow{KB}| \cos\theta$$

Assume that H is outside the wedge KAB and in a position where the circle is tangent to KB at point N. Let M be the point where H projects on $\overrightarrow{KB}$ parallel to $\overrightarrow{KA}$. We have

$$\overrightarrow{HM} = \alpha \overrightarrow{KA}$$

and

$$\overrightarrow{HM} \cdot \overrightarrow{HM} = \frac{r^2}{\sin^2\theta} = \frac{r^2}{1 - \cos^2\theta}$$

Eliminating $\overrightarrow{HM}$ we obtain the following conditions on α for H to be in the position indicated above

$$\alpha < 0$$

$$\alpha^2 > r^2 \frac{\overrightarrow{KB} \cdot \overrightarrow{KB}}{(\overrightarrow{KA} \cdot \overrightarrow{KA})(\overrightarrow{KB} \cdot \overrightarrow{KB}) - (\overrightarrow{KA} \cdot \overrightarrow{KB})^2}.$$

We have similar conditions on β for the circle to be outside the wedge KAB and tangent to $\overrightarrow{KA}$.

The next step is to find out the extension of the wedge formed by the circle when seen from K. Let P be a point where a line going through K is tangent to the circle, and let Q be the point where KP intersects AB; it may be between K and P or behind P.

We need to find P. It is defined by two equations

$$\overrightarrow{PH} \cdot \overrightarrow{PH} = r^2$$

$$\overrightarrow{PH} \cdot \overrightarrow{KP} = 0.$$

The second equation may be rewritten

$$\overrightarrow{PH} \cdot (\overrightarrow{KH} + \overrightarrow{HP}) = 0$$

from which we obtain

$$\overrightarrow{PH} \cdot \overrightarrow{KH} = r^2.$$

Let γ and δ be the coordinates of $\overrightarrow{PH}$ in KAB

$$\overrightarrow{PH} = \gamma \overrightarrow{KA} + \delta \overrightarrow{KB}.$$

The second equation is linear

$$\gamma \overrightarrow{KA} \cdot \overrightarrow{KH} + \delta \overrightarrow{KB} \cdot \overrightarrow{KH} = r^2,$$

thus

$$\gamma = \frac{r^2 - \delta \overrightarrow{KB} \cdot \overrightarrow{KH}}{\overrightarrow{KA} \cdot \overrightarrow{KH}}.$$

Note that $\overrightarrow{KA} \cdot \overrightarrow{KH}$ and $\overrightarrow{KB} \cdot \overrightarrow{KH}$ cannot both be 0 unless K is on AB. The first equation is quadratic

$$(\gamma \overrightarrow{KA} + \delta \overrightarrow{KB})^2 = r^2.$$

Pluging the value of γ above we get

$$\delta^2 ((\overrightarrow{KB} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KH})^2 + 2(\overrightarrow{KA} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KH})(\overrightarrow{KB} \cdot \overrightarrow{KH}) + \overrightarrow{KA} \cdot \overrightarrow{KA}(\overrightarrow{KB} \cdot \overrightarrow{KH})^2) +$$
$$2\delta r^2 ((\overrightarrow{KA} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KH}) - (\overrightarrow{KA} \cdot \overrightarrow{KA})(\overrightarrow{KB} \cdot \overrightarrow{KH})) +$$
$$r^2(r^2(\overrightarrow{KA} \cdot \overrightarrow{KA}) - (\overrightarrow{KA} \cdot \overrightarrow{KH})^2) = 0.$$
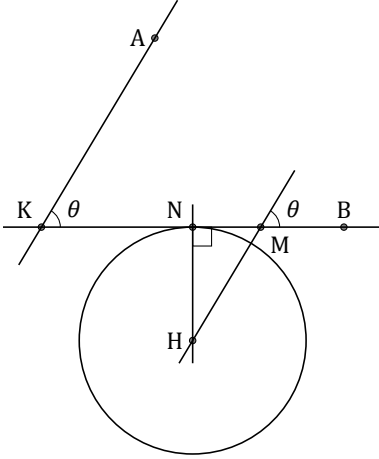

Figure 1. Circle outside of the wedge KAB.

This equation always has two solutions because the sphere intersects KAB. Having determined $\overrightarrow{PH}$, we can find Q. Q is on the line AB, thus

$$\overrightarrow{AQ} = \lambda\overrightarrow{AB},$$

which can be written

$$\overrightarrow{KQ} - \overrightarrow{KA} = \lambda\overrightarrow{AB}.$$

Noting that $\overrightarrow{KQ}$ is orthogonal to $\overrightarrow{PH}$ we have

$$-\overrightarrow{KA} \cdot \overrightarrow{PH} = \lambda\overrightarrow{AB} \cdot \overrightarrow{PH}, \text{ or, } \lambda = -\frac{\overrightarrow{KA} \cdot \overrightarrow{PH}}{\overrightarrow{AB} \cdot \overrightarrow{PH}}.$$

Having determined the values of λ we need to find out where Q is located with respect to the segment $\overrightarrow{AB}$. Let S be the intersection of AB with the line orthogonal to KH at K. We locate S on AB as follows

$$\overrightarrow{KS} = \overrightarrow{KA} + \sigma\overrightarrow{AB}.$$

Noting that $\overrightarrow{KS} \cdot \overrightarrow{KH} = 0$ we obtain

$$\sigma = -\frac{\overrightarrow{KA} \cdot \overrightarrow{KH}}{\overrightarrow{AB} \cdot \overrightarrow{KH}}$$

Now let T be the intersection of AB with the line orthogonal to KH at P. We locate T on AB similarly

$$\overrightarrow{KT} = \overrightarrow{KA} + \tau\overrightarrow{AB}.$$

We have

$$\overrightarrow{PT} = \overrightarrow{KA} + \tau\overrightarrow{AB} - \overrightarrow{KH} + \overrightarrow{PH}$$

Noting that $\overrightarrow{PT} \cdot \overrightarrow{KH} = 0$ we obtain

$$\tau = \frac{\overrightarrow{KH} \cdot \overrightarrow{KH} - \overrightarrow{PH} \cdot \overrightarrow{KH} - \overrightarrow{KA} \cdot \overrightarrow{KH}}{\overrightarrow{AB} \cdot \overrightarrow{KH}}$$

We can now determine if λ is an "interesting" intersection, i.e., one that intersects the cone behind the sphere when seen from the camera. First, assume that A and B are in the same order as S and T on AB. Then we have $\sigma \leq \tau$ and the intersection is farther than T (as seen from the camera) if and only if $\tau < \lambda$. Conversely, if A and B are in the reverse order as S and T on AB we have $\tau \leq \sigma$ and the intersection is farther than T if and only if $\lambda < \tau$

There is another special case to handle: if the line AB is in "hyperbolic" position, i.e. intersects both halves of the cone, then one value of λ is smaller than σ and one value is greater than σ. Exactly one of the values of λ will be retained by the preceding analysis, and we need to add an extra λ equal to an infinity with the sign of $\tau - \sigma$ to account for the fact that all the points farther than T are hidden by the cone.

To complete the analysis we need to compute the intersection Q of the sphere (not the cone) with the line AB. Q is on the sphere, thus

$$\overrightarrow{CQ} \cdot \overrightarrow{CQ} = R^2.$$

It is also on the line AB thus

$$\overrightarrow{KQ} = \overrightarrow{KA} + \mu\overrightarrow{AB}.$$

We have

$$\overrightarrow{CQ} = \overrightarrow{KQ} - \overrightarrow{KC} = \overrightarrow{KA} + \mu\overrightarrow{AB} - \overrightarrow{KC} = \overrightarrow{CA} + \mu\overrightarrow{AB},$$

and therefore

$$R^2 = (\overrightarrow{CA} + \mu\overrightarrow{AB})^2,$$

meaning that μ is a solution of

$$\mu\overrightarrow{AB} \cdot \overrightarrow{AB} + 2\mu\overrightarrow{CA} \cdot \overrightarrow{AB} + \overrightarrow{CA} \cdot \overrightarrow{CA} - R^2 = 0.$$

Depending on the location of the segment with respect to the sphere, there can be 0, 1, or 2 intersections.

If we take the union of the values of λ and μ and order them, it is straightforward to find the visible segments. Remember that $0 < \lambda, \mu < 1$ for points that are in the segment AB.
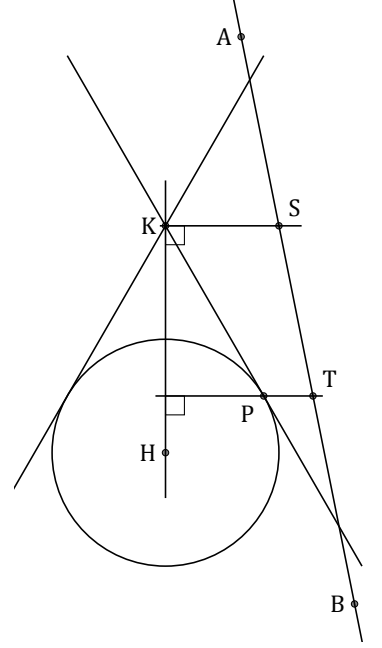

Figure 2. Definition of S and T.