

Evolutionarily Stable Strategies and Replicator Dynamics

Evolutionarily Stable Strategies

Task 1. Consider the following

$$A = \begin{pmatrix} -6 & 2 & 1 \\ 2 & -11 & 3 \\ 1 & 3 & -22 \end{pmatrix}.$$

Find the ESS (mixed version) and provide the appropriate proof.

Definition 1 (Hawks–Dove–Retaliator). For Hawk and Dove consider its extension, by adding an extra strategy Retaliator strategy R . Retaliator plays Dove unless the opponent escalates; against Hawk it retaliates (so the outcome is like H vs H), while against Dove (and against another Retaliator) it behaves like Dove. This yields the payoff matrix

$$A = \begin{pmatrix} \frac{V-C}{2} & V & \frac{V-C}{2} \\ 0 & \frac{V}{2} & \frac{V}{2} \\ \frac{V-C}{2} & \frac{V}{2} & \frac{V}{2} \end{pmatrix}, \quad (\text{rows/cols ordered as } (H, D, R)).$$

Task 2. Find all ESS for Hawks–Dove–Retaliator game. Consider two cases $V < C$ and $V \geq C$.

Task 3 (*). Can you propose and implement the algorithm that finds ESS (mixed version) for a given symmetric game? Prove its correctness.

Replicator Dynamics

Definition 2. For a symmetric game with payoff matrix $n \times n$ A , the replicator dynamics is the ODE system:

$$\dot{x}_i = x_i((Ax)_i - x^\top Ax), \quad i = 1, 2, \dots, n \quad (1)$$

Task 4. Show that if $\sum_i x_i(0) = 1$ then for all $t \geq 0$ we have $\sum_i x_i(t) = 1$.

Task 5. Show that if for some t_0 and i $x_i(t_0) = 0$ then for all $t \geq t_0$ we have $x_i(t) = 0$. Conclude that if $\forall i$ $x_i(0) \geq 0$, then $\forall i, t$ $x_i(t) \geq 0$

Task 6. What happens if $x(0) = x^*$, where x^* is the Nash Equilibrium.

Task 7. Investigate the replicator dynamics for Hawkss and Doves game for different initial conditions and different values of V and C . What is the limit $\lim_{t \rightarrow \infty} x(t)$? Illustrate your answer with appropriate graphs.

Task 8. Investigate the replicator dynamics for games from Task 1 and Task 2 for different parameters and initial conditions. Illustrate your answers with appropriate graph and formulate conclusions and hypothesis (Hint: use barycentric coordinates to draw appropriate 2D graphs).

Task 9. Check the behaviour of replicator dynamics for the games having pure version ESS but not having mixed version ESS.

Task 10 (* if proven). Is it true that if a symmetric game has ESS x^* (mixed version), then for every initial conditions that are sufficiently close to x^* we have $\lim_{t \rightarrow \infty} x(t) = x^*$?

Task 11. Consider classical Rock–Paper–Scissors (RPS) with payoff matrix

$$A = \begin{pmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ -1 & 1 & 0 \end{pmatrix}.$$

Find all NE and check if there is ESS. Analyse the replicator dynamics for different initial values.

Task 12. Consider a modification of a classical Rock–Paper–Scissors (RPS), where the price for winning is v , with payoff matrix

$$A = \begin{pmatrix} 0 & -1 & v \\ v & 0 & -1 \\ -1 & v & 0 \end{pmatrix}.$$

Find all NE and check if there is ESS if $v > 0$. Analyse the replicator dynamics for different initial values.

Task 13. Consider the following

$$A = \alpha \begin{pmatrix} -6 & 2 & 1 \\ 2 & -11 & 3 \\ 1 & 3 & -22 \end{pmatrix} + \beta \begin{pmatrix} 0 & -1 & v \\ v & 0 & -1 \\ -1 & v & 0 \end{pmatrix}.$$

Investigate the replicator dynamics model for different α , β and $v > 0$. If some patterns and examples are present some of them. If you can formulate some hypothesis/observations - do it.

Task 14. Let us add a small mutation term $\mu > 0$ to the replicator dynamics:

$$\dot{x}_i = x_i((Ax)_i - x^\top Ax) + \mu \left(\frac{1}{n} - x_i \right), \quad i = 1, \dots, n.$$

For RPS, simulate the replicator dynamics with small μ and different initial values. How would you interpret the results in biological terms? Can you slightly generalize the model?

Task 15. Is it possible for a game that its replicator dynamics has cycles as well as attractors? Check the problem for different values of x^* , like all coordinates greater than zero (all pure strategies play) or similar. Propose some hypothesis.