

Monte Carlo Tree Search with Adaptive Simulation

a Case Study on Weighted Vertex Coloring Problem

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Introduction

WVCP - Weighted Vertex Coloring Problem

Given a graph $G = (V, E)$, V the vertices, E the edges of the graph and $w(v)$ the weight of v for $v \in V$

The objective is to find a legal coloring s (two connected vertices can't share the same color) that minimizes the sum of the heaviest vertices of each k colors.

$$\text{score} = F(s) = \sum_{i=1}^k \max_{v \in V_i} w(v)$$

Applications :

- Scheduling on a Batch Machine with Job Compatibilities
- Traffic assignment in communication satellites
- Matrix Decomposition Problem

NP-hard problem

demo

Exemple of application

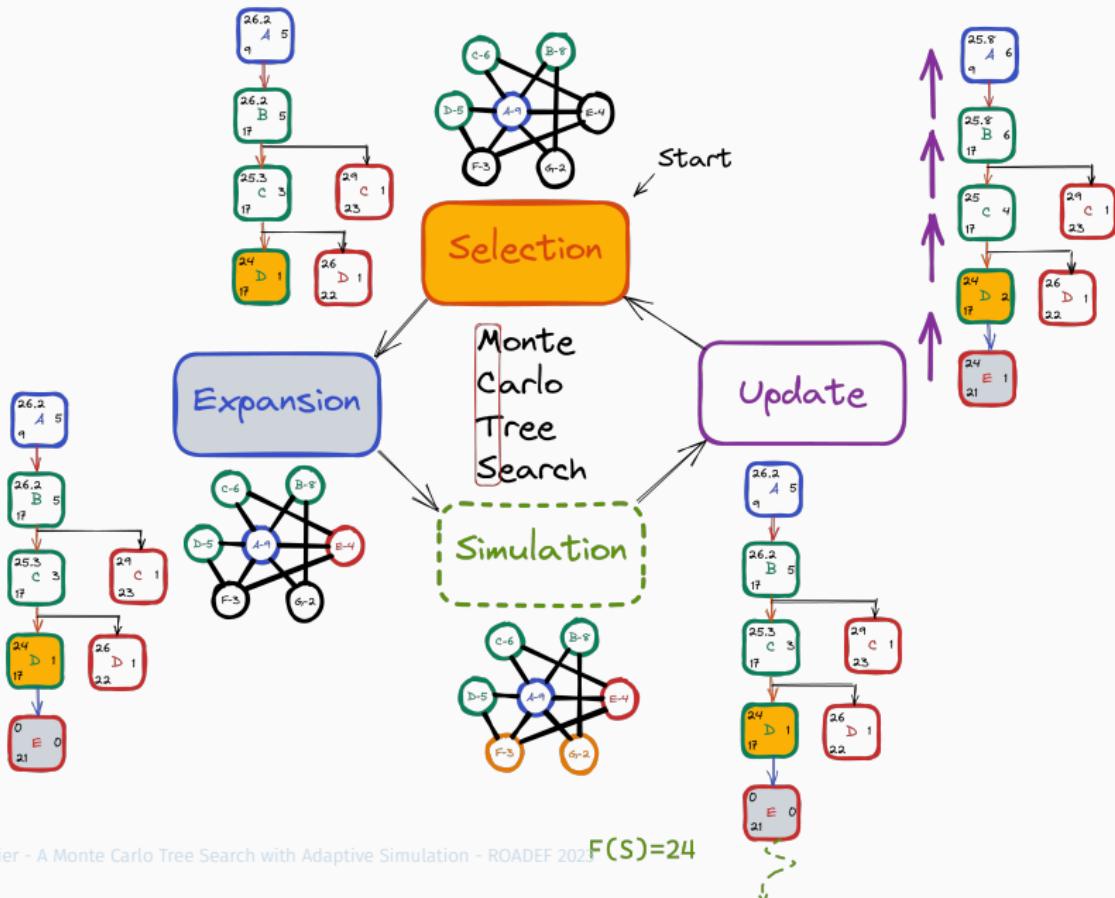
<p>8 Jobs</p> <p>J1 - 9s J2 - 8s J3 - 8s J4 - 6s J5 - 5s J6 - 5s J7 - 4s J8 - 2s</p> <p>3 Resources</p> <p>1 - Prepare the jobs in a bipartite graph (jobs - resources)</p>	<p>2 - Projection of the bipartite graph onto the resources to obtain a common needs graph</p>	<p>3 - Use the time of each task as a weight for each vertex</p>															
<p>optimal score = $9 + 8 + 6 + 2 = 25$</p> <p>4 - Solve the problem by minimizing the sum of the maximum weights of each color</p>	<p>4 Batches</p> <table border="1"> <tr> <td>B1 - 9s</td> <td>B2 - 8s</td> <td>B3 - 6s</td> <td>B4 - 2s</td> <td>Total : 25s</td> </tr> <tr> <td>J1 - 9s J3 - 8s J5 - 5s</td> <td>J2 - 8s</td> <td>J4 - 6s J6 - 5s J7 - 4s</td> <td>J8 - 2s</td> <td></td> </tr> <tr> <td>R1 R2 R3</td> <td>R1 R2 R3</td> <td>R1 R2 R3</td> <td>R1</td> <td></td> </tr> </table> <p>8 Jobs</p> <p>3 Resources</p>	B1 - 9s	B2 - 8s	B3 - 6s	B4 - 2s	Total : 25s	J1 - 9s J3 - 8s J5 - 5s	J2 - 8s	J4 - 6s J6 - 5s J7 - 4s	J8 - 2s		R1 R2 R3	R1 R2 R3	R1 R2 R3	R1		<p>5 - Prepare the batches according to the color of each job</p>
B1 - 9s	B2 - 8s	B3 - 6s	B4 - 2s	Total : 25s													
J1 - 9s J3 - 8s J5 - 5s	J2 - 8s	J4 - 6s J6 - 5s J7 - 4s	J8 - 2s														
R1 R2 R3	R1 R2 R3	R1 R2 R3	R1														

State of the art - WVCP

- **R-GRASP** : reactive GRASP, iterated greedy algorithm with local search.
Prais, M., Ribeiro, C.C., 2000.
Reactive GRASP : An Application to a Matrix Decomposition Problem in TDMA Traffic Assignment.
- **2-Phase** : Phase 1 : generation of independent sets, phase 2 : optimization.
Malaguti, E., Monaci, M., Toth, P., 2009.
Models and heuristic algorithms for a weighted vertex coloring problem.
- **MWSS** : mixed integer linear programming.
Cornaz, D., Furini, F., Malaguti, E., 2017.
Solving vertex coloring problems as maximum weight stable set problems.
- **AFISA** : tabu search with coefficient to manage GCP and WVCP.
Sun, W., Hao, J.-K., Lai, X., Wu, Q., 2018.
Adaptive feasible and infeasible tabu search for weighted vertex coloring.
- **RedLS** : reduction and local search with weight management of the edges.
Wang, Y., Cai, S., Pan, S., Li, X., Yin, M., 2020.
Reduction and Local Search for Weighted Graph Coloring Problem.
- **ILS-TS** : reduction and iterated local search with grenade operator.
Nogueira, B., Tavares, E., Maciel, P., 2021.
Iterated local search with tabu search for the weighted vertex coloring problem.
- **DLMCOL** : memetic algorithm with deep learning for the crossover selection.
Goudet, O., Grelier, C., Hao, J.-K., 2021.
A deep learning guided memetic framework for graph coloring problems.
- **MCTS** : monte carlo tree search to find good initialisation for the local search.
Grelier, C., Goudet, O., Hao, J.-K., 2022.
On Monte Carlo Tree Search for Weighted Vertex Coloring.

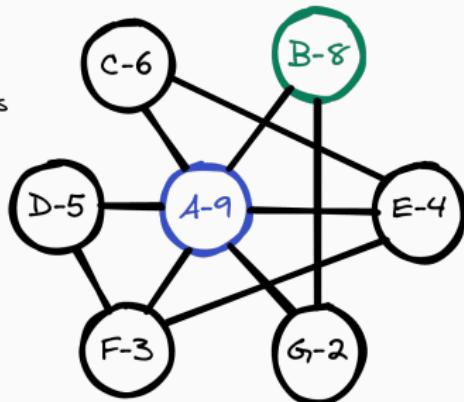
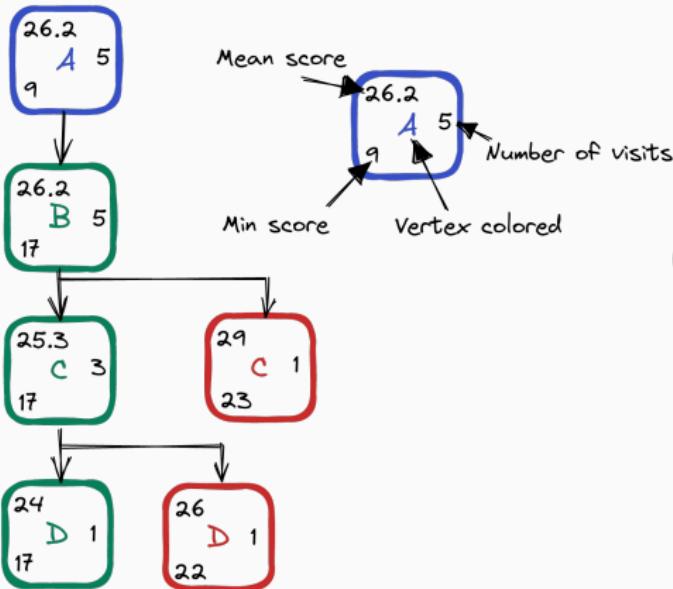
Proposed algorithm

Monte Carlo Tree Search



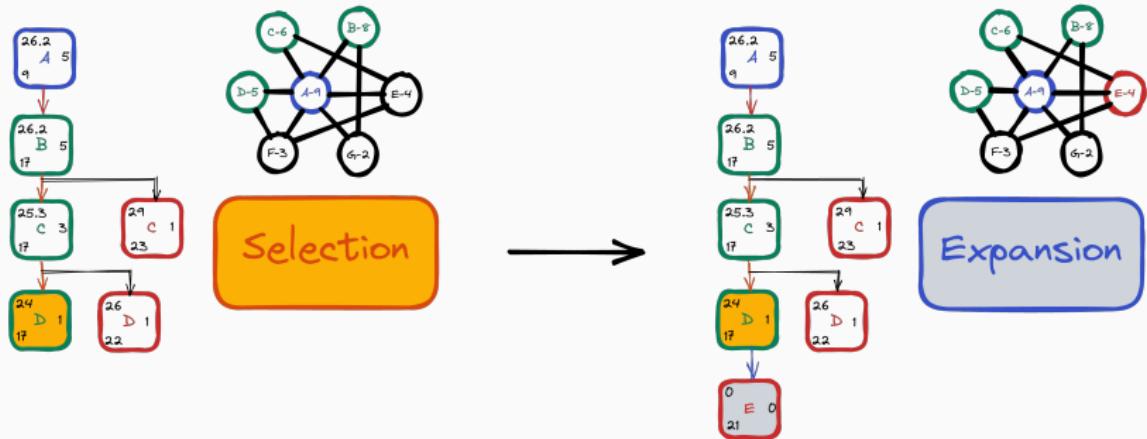
Monte Carlo Tree Search

Tree



Graph

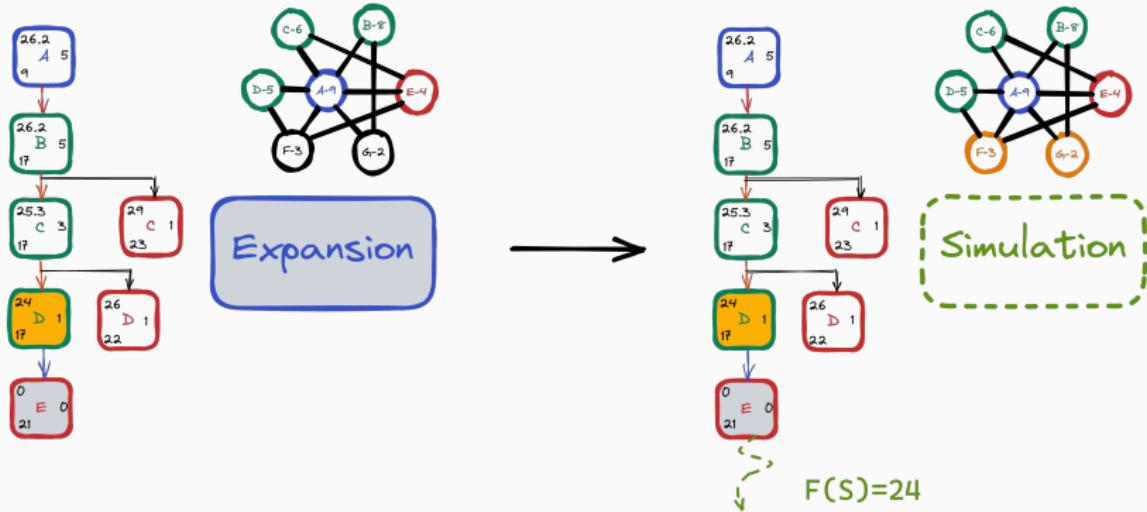
Monte Carlo Tree Search



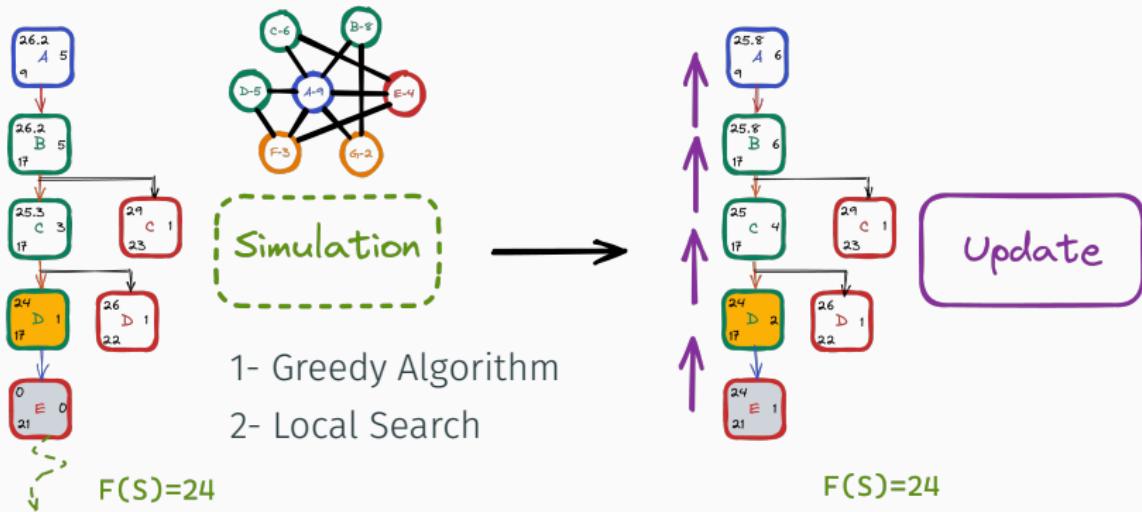
$$(\text{UCB}) \text{ normalized_score}(C_{t+1}^i) = \frac{\text{rank}(C_{t+1}^i)}{\sum_{i=1}^l \text{rank}(C_{t+1}^i)}$$

$$\text{normalized_score}(C_{t+1}^i) + c \times \sqrt{\frac{2 * \ln(\text{nb_visits}(C_t))}{\text{nb_visits}(C_{t+1}^i)}}$$

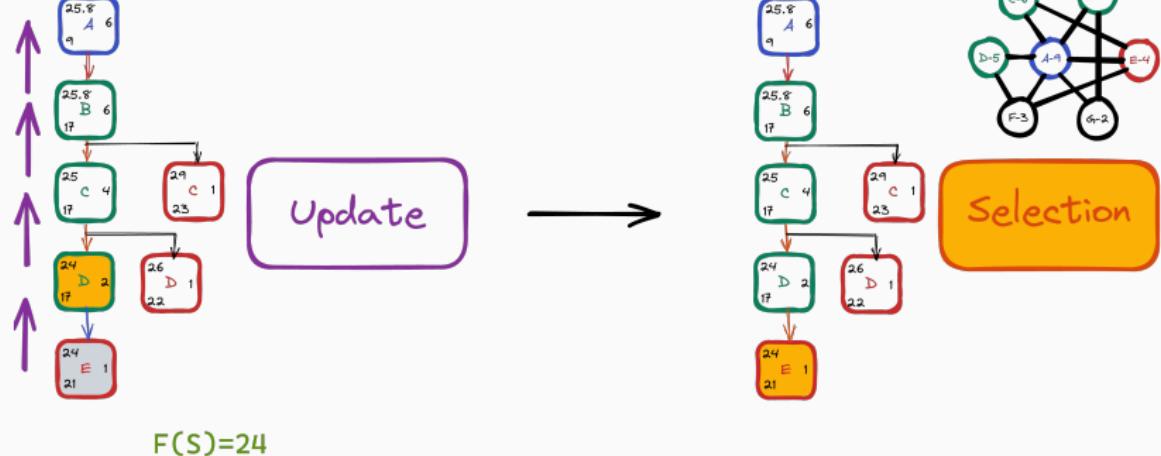
Monte Carlo Tree Search



Monte Carlo Tree Search



Monte Carlo Tree Search



Monte Carlo Tree Search with adaptive simulation

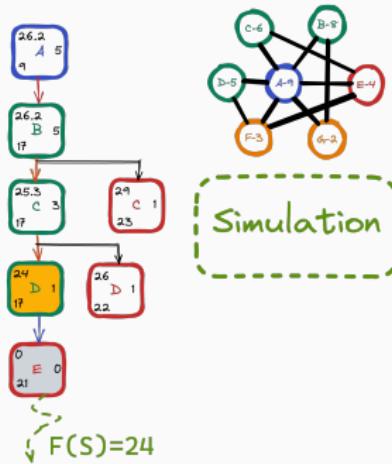
Why?

- **No Free Lunch Theorem** : No Local Search dominates the others
- **Adapt** : Choose the right operator without previous knowledge

How?

- **Selection criteria** : train a criterion to choose operators
- **Reward** : use the score of the solution after local search
- **Sliding window** : use a normalization of the scores during the ws last iterations

Monte Carlo Tree Search with adaptive simulation



Before :

- 1 - Greedy algorithm to complete the solution
- 2 - Apply a Local Search

Now :

- 1 - Greedy algorithm to complete the solution
- 2 - Criteria to choose the LS operator
- 3 - Apply the LS
- 4 - Update criteria with $F(\text{solution after LS})$

Monte Carlo Tree Search with adaptive simulation

What are the possible Local Search operators?

- **AFISA** : illegal search space, one move operator, coefficient varies to come back to a legal solution
- **RedLS** : illegal search space, one move operator, weights on conflicting edges to come back to a legal solution and force heaviest vertices of color to move
- **ILSTS** : partial legal search space, one move and grenade operator, force heaviest vertices of multiple colors to move
- **TabuWeight (TW)** : legal search space, one move operator, inspired from TabuCol

Monte Carlo Tree Search with adaptive simulation

Which selection criteria ?

- **Random** : Random selection
- **Roulette Wheel**¹ : Fair selection depending on the results

$$proba[o] = p_{min} + (1 - n_o * p_{min}) * \frac{r[o]}{\sum r}$$

- **Pursuit** : Unfair selection in favor of the best operator (b)

$$\begin{cases} proba[b] = proba[b] + \beta(p_{max} - proba[b]) \\ proba[o] = proba[o] + \beta(p_{min} - proba[o]) \end{cases}$$

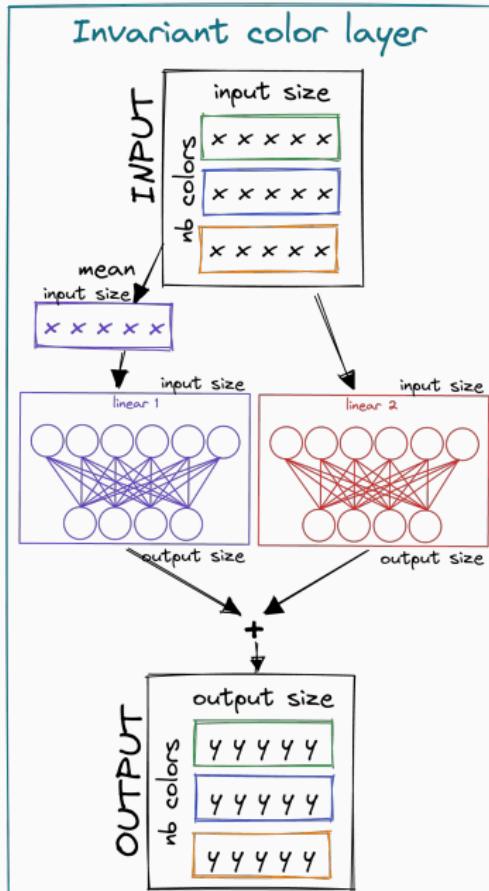
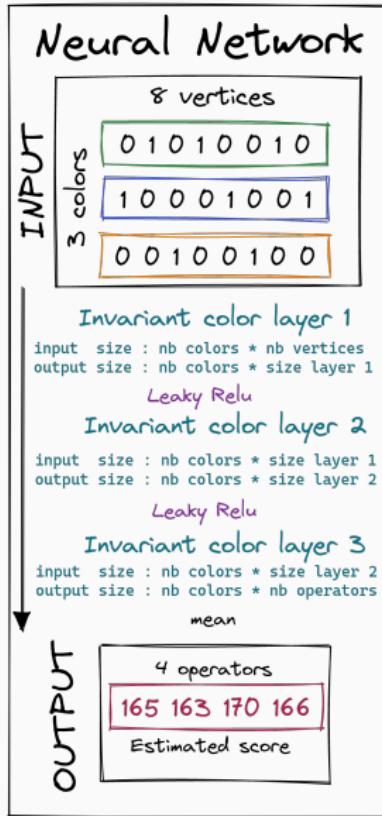
- **UCB** : Favouring the best operators while encouraging exploration

$$score[o] = r[o] + c * \sqrt{2 * \frac{\log(\sum visits)}{visits[o]}}$$

- **NN** : Recommendations of a Neural Network using deep sets² on a raw solution

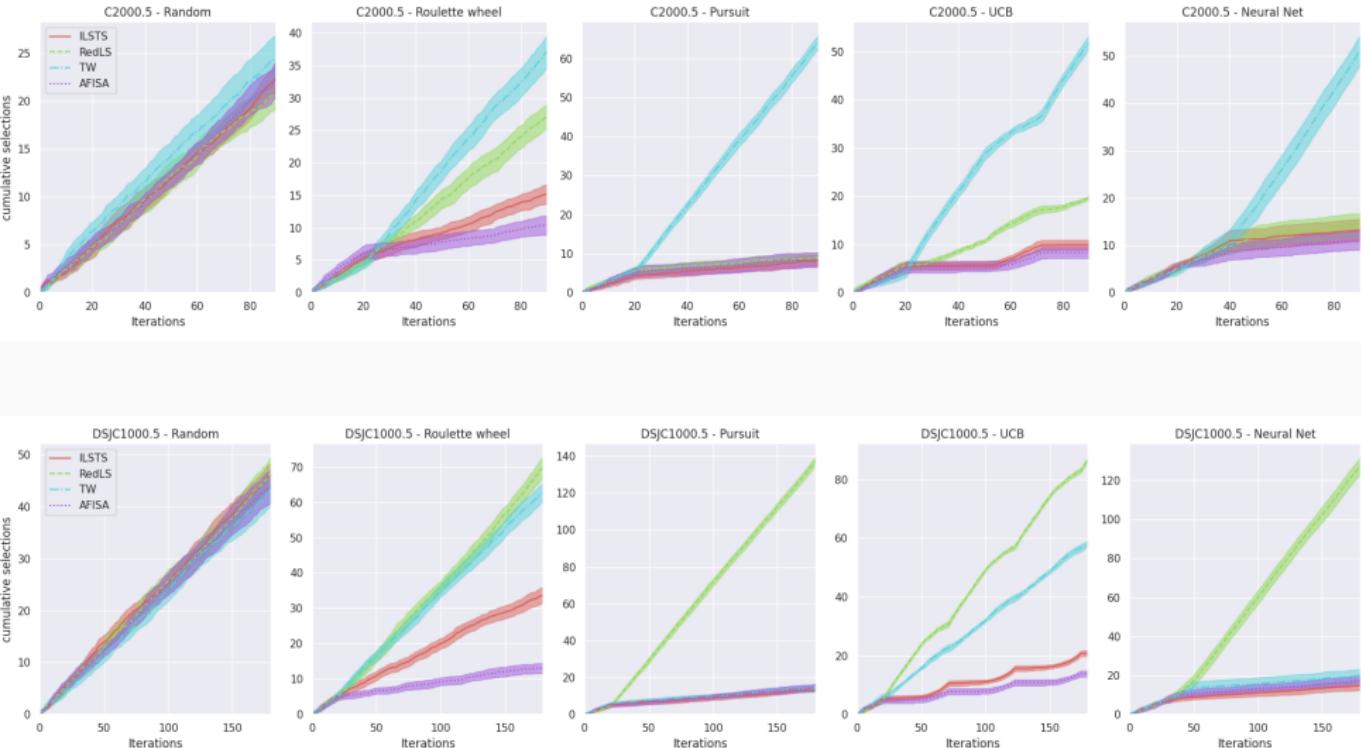
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1. A. Goëffon et al. Simulating non-stationary operators in search algorithms. 2016
 2. M. Zaheer et al. Deep Sets. 2018

Neural network – Deep sets

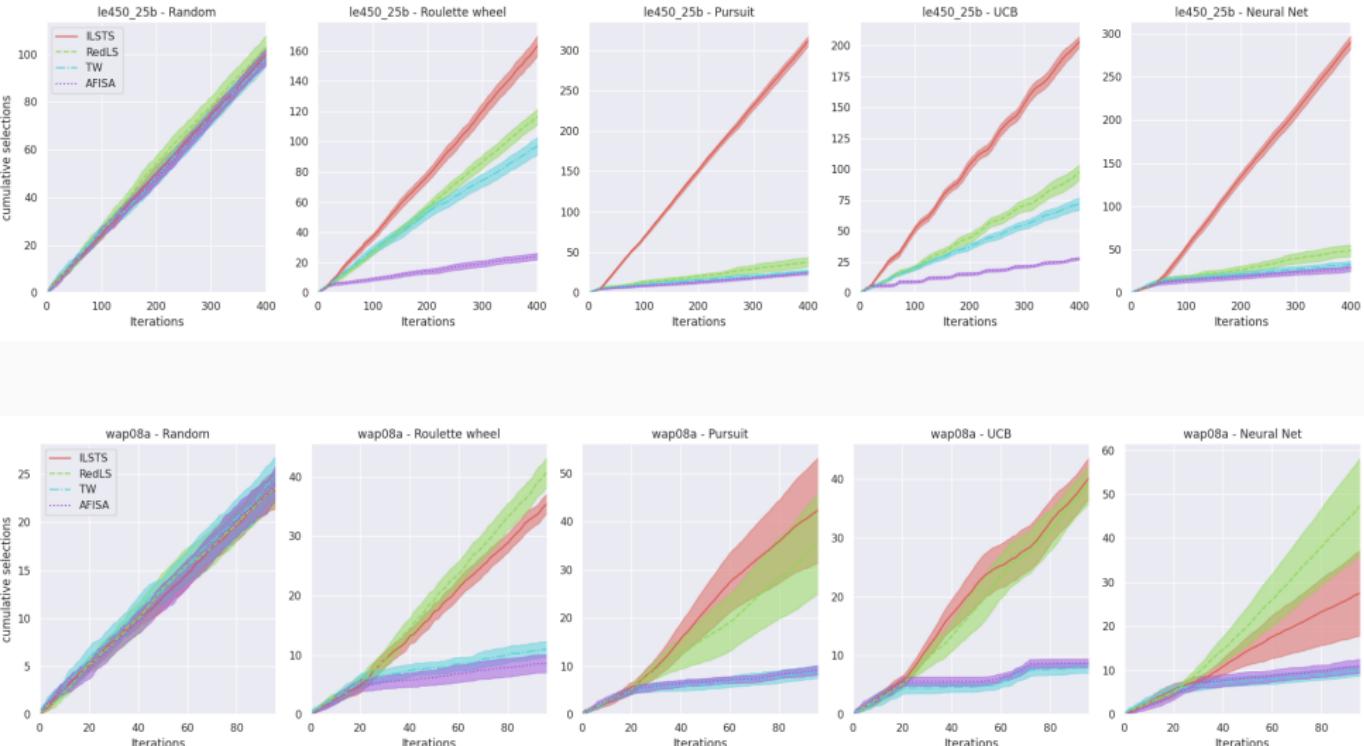


Experimentation

Operator selection



Operator selection



Results

1 point for the method on the row if the difference on the mean score on the 20 runs is significantly better (non-parametric Wilcoxon signed-rank test with a p-value ≤ 0.001)

	AFISA	MCTS+AFISA	TW	MCTS+TW	RedLS	MCTS+RedLS	ILSTS	MCTS+ILSTS	Random	Roulette Wheel	Pursuit	UCB	Neural network
AFISA	-	35	48	16	56	0	9	13	0	0	0	0	0
MCTS+AFISA	40	-	72	10	86	0	1	1	0	0	0	0	0
TW	39	38	-	26	47	2	16	23	2	2	2	2	2
MCTS+TW	68	71	78	-	99	5	8	17	0	0	0	0	0
RedLS	44	38	47	29	-	13	23	25	15	15	15	15	14
MCTS+RedLS	102	79	105	68	102	-	42	43	21	7	6	4	4
ILSTS	87	80	86	56	83	13	-	25	8	5	1	2	4
MCTS+ILSTS	82	78	83	48	81	11	0	-	5	2	0	1	2
Random	103	81	103	72	98	12	34	39	-	0	0	0	1
Roulette Wheel	103	81	104	73	100	13	35	40	4	-	1	0	1
Pursuit	103	81	105	75	101	14	35	40	11	0	-	1	2
UCB	103	81	104	75	100	13	36	40	4	0	1	-	1
NN	103	81	104	75	101	13	35	41	9	2	0	0	-

Results

/188 instances	# Best Known Score	# Best Score	# Best Mean Score
AFISA	115	115	49
MCTS+AFISA	116	116	98
TabuWeight	98	98	52
MCTS+TabuWeight	129	129	98
RedLS	112	130	46
MCTS+RedLS	153	162	144
ILSTS	151	151	141
MCTS+ILSTS	148	148	141
Random	154	158	139
Roulette Wheel	155	160	142
Pursuit	156	163	155
UCB	156	160	146
NN	157	161	152

Complete results and source code :

https://github.com/Cyril-Grelier/gc_wvcp_adaptive_mcts

Conclusion

Conclusion

MCTS with adaptive simulation for the weighted vertex coloring problem :

- highest number of BKS, good rank among other methods, and provide regularity in the results
- No change of operator during the search
 - usually one(/two) dominant operator for one instance
 - no complementarity in using different operators

Thank you for your attention!

Questions?

Selection criteria - Criteria based on probabilities

Random selection with bias³

- **Fixed random** (with bias or not) :

Same probability during all the search

- **Adaptive roulette wheel** :

The more an operator o reaches good scores, the more it will be selected

$$proba[o] = p_{min} + (1 - n_o * p_{min}) * \frac{r[o]}{\sum r}$$

n_o : number of operators

r : vector of the normalization of the sum of the obtained rewards during the last ws generations for each operators

p_{min} : probability minimum (0.05)

- **Adaptive pursuit** :

The operator with the best results (b) get far more chances to be selected

$$\begin{cases} proba[b] = proba[b] + \beta(p_{max} - proba[b]) \\ proba[o] = proba[o] + \beta(p_{min} - proba[o]) \end{cases}$$

p_{max} : probability maximum ($= 1 - (n_o - 1) * p_{min}$)

-
3. A. Goëffon, F. Lardeux, and F. Saubion. Simulating non-stationary operators in search algorithms. 2016

Selection criteria - Criteria based on multi-armed bandit

Selection of the most profitable (best score)²

- UCB :

The better scores an operator gets, the more likely it is to be selected (exploitation) but the less an operator is selected, the more likely it is to be selected (exploration)

$$score[o] = r[o] + c * \sqrt{2 * \frac{\log(\sum \text{visits})}{\text{visits}[o]}}$$

r : vector of the normalization of the sum of the obtained rewards during the last ws generations for each operators

visits : number of time each operator have been selected during the last ws generations

2. A. Goëffon, F. Lardeux, and F. Saubion. Simulating non-stationary operators in search algorithms. 2016

Selection criteria - Criteria based on a neural network

Selection of the best according to a neural network

- **Neural network :**

- Use a raw solution as input and predict the reward for each operator

- 10% chance of random selection

- Use deep set⁴

4. M. Zaheer, S. Kottur, S. Ravanbakhsh, B. Poczos, R. Salakhutdinov, and A. Smola. Deep Sets. 2018