



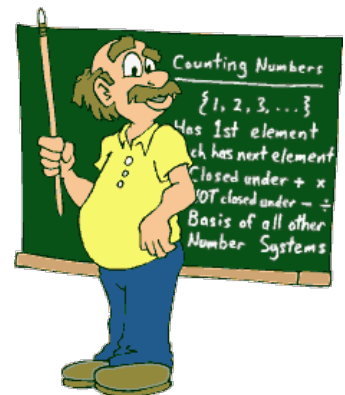
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# MSYS

## Microcontroller Systems

### Lektion 11

## AVR hardware konfiguration



# Mega32 pins

PDIP

(XCK/T0) PB0	1	40	PA0 (ADC0)
(T1) PB1	2	39	PA1 (ADC1)
(INT2/AIN0) PB2	3	38	PA2 (ADC2)
(OC0/AIN1) PB3	4	37	PA3 (ADC3)
( $\overline{SS}$ ) PB4	5	36	PA4 (ADC4)
(MOSI) PB5	6	35	PA5 (ADC5)
(MISO) PB6	7	34	PA6 (ADC6)
(SCK) PB7	8	33	PA7 (ADC7)
RESET	9	32	AREF
VCC	10	31	GND
GND	11	30	AVCC
XTAL2	12	29	PC7 (TOSC2)
XTAL1	13	28	PC6 (TOSC1)
(RXD) PD0	14	27	PC5 (TDI)
(TXD) PD1	15	26	PC4 (TDO)
(INT0) PD2	16	25	PC3 (TMS)
(INT1) PD3	17	24	PC2 (TCK)
(OC1B) PD4	18	23	PC1 (SDA)
(OC1A) PD5	19	22	PC0 (SCL)
(ICP) PD6	20	21	PD7 (OC2)

Provides supply

These pins are used to connect external crystal or RC oscillator

Reference voltage

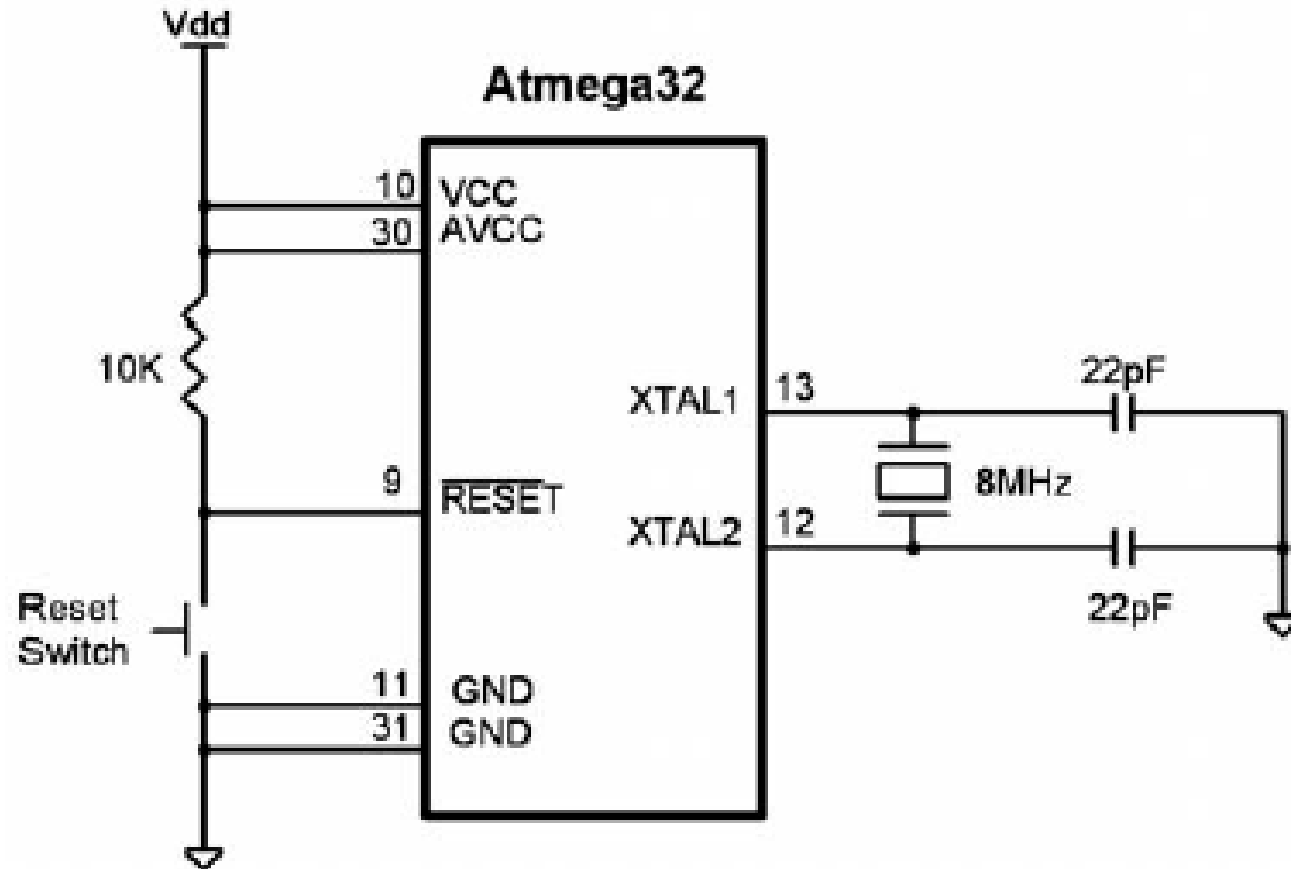
Supply voltage for ADC and portA. Connect it to VCC



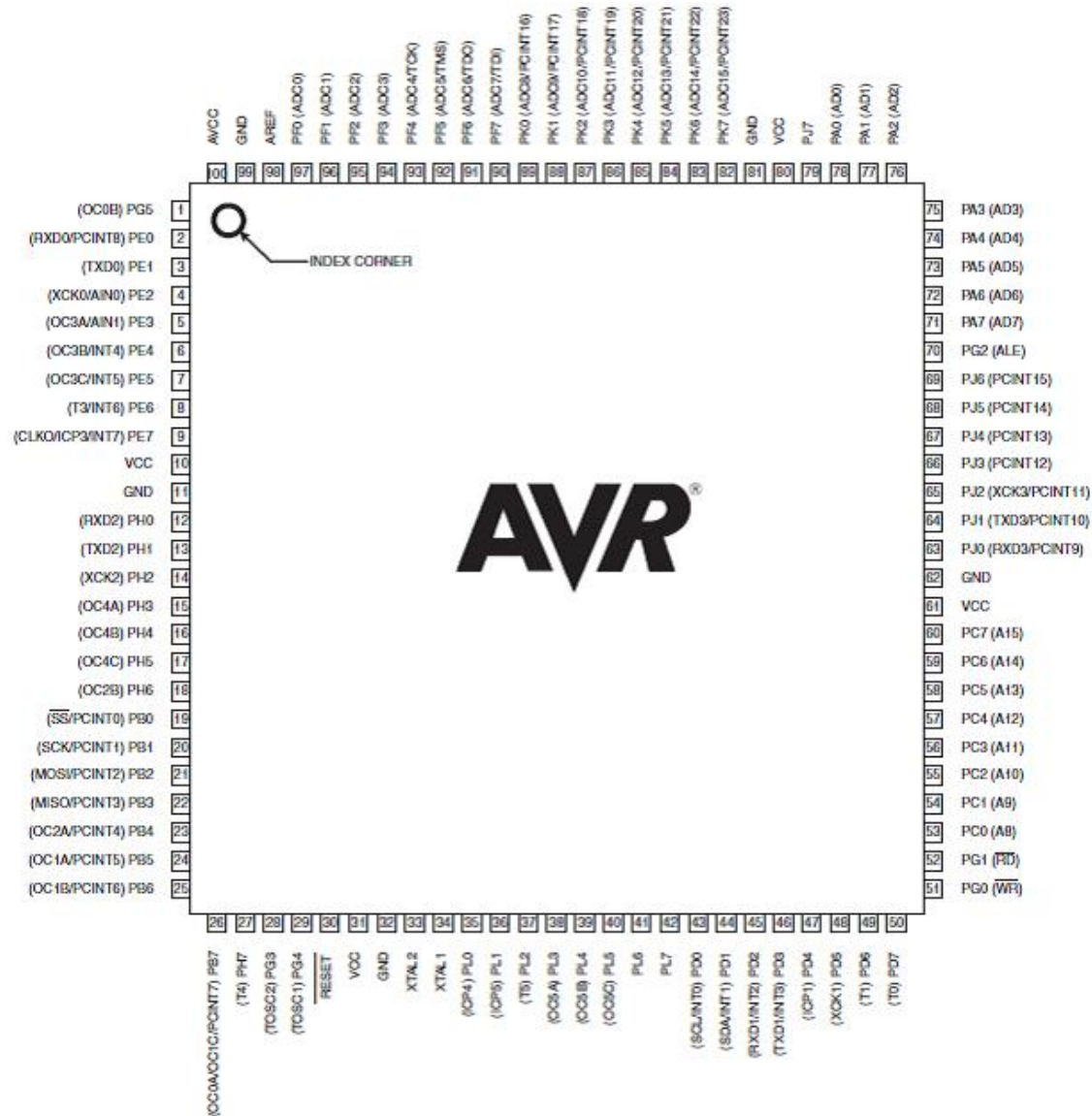
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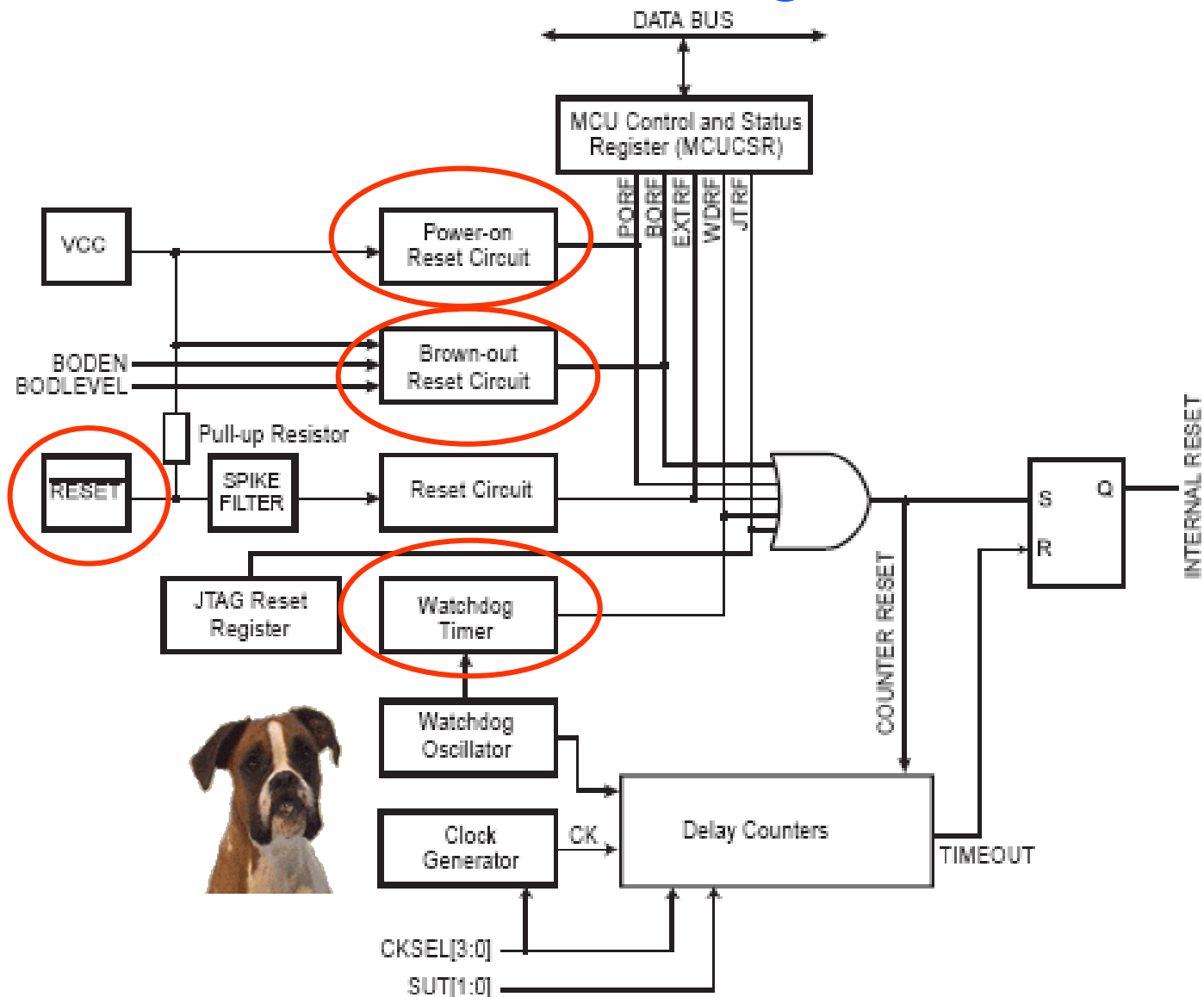
# Simple HW configuration



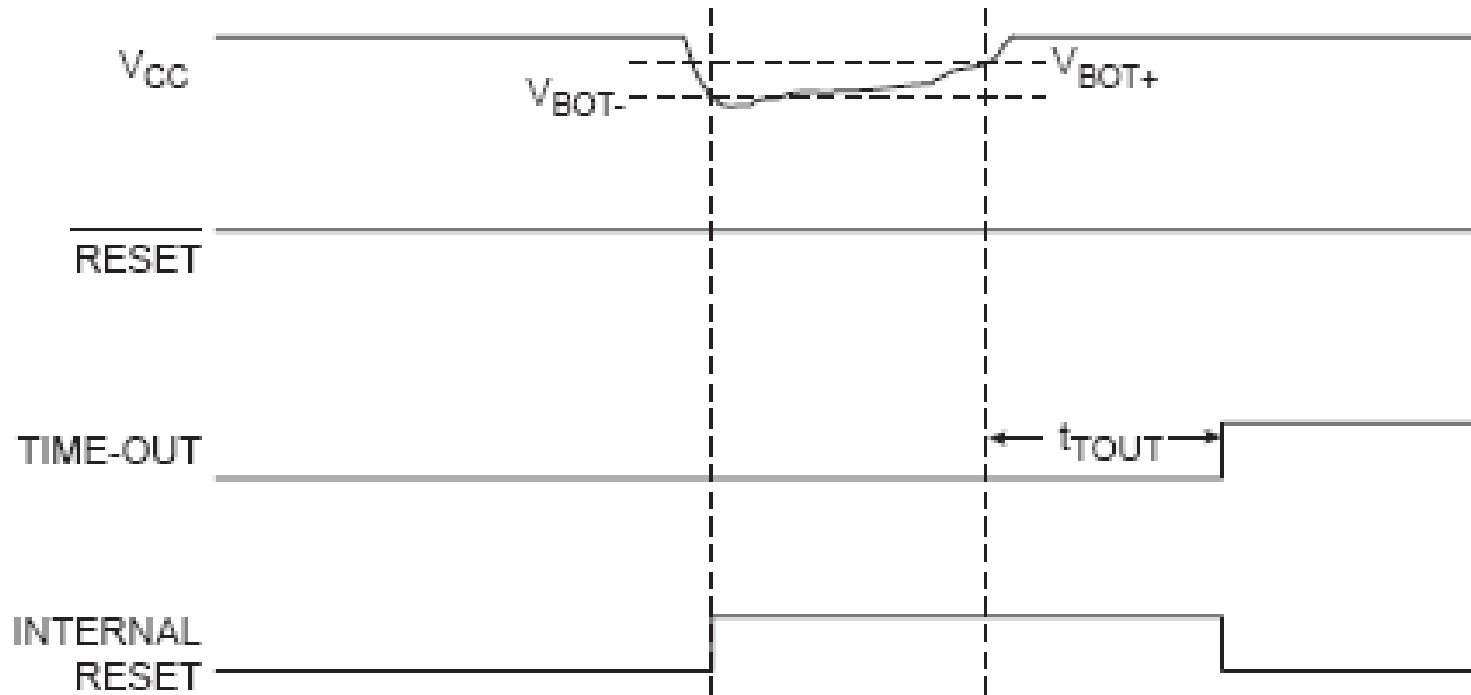
# Mega2560 pins



# RESET logik



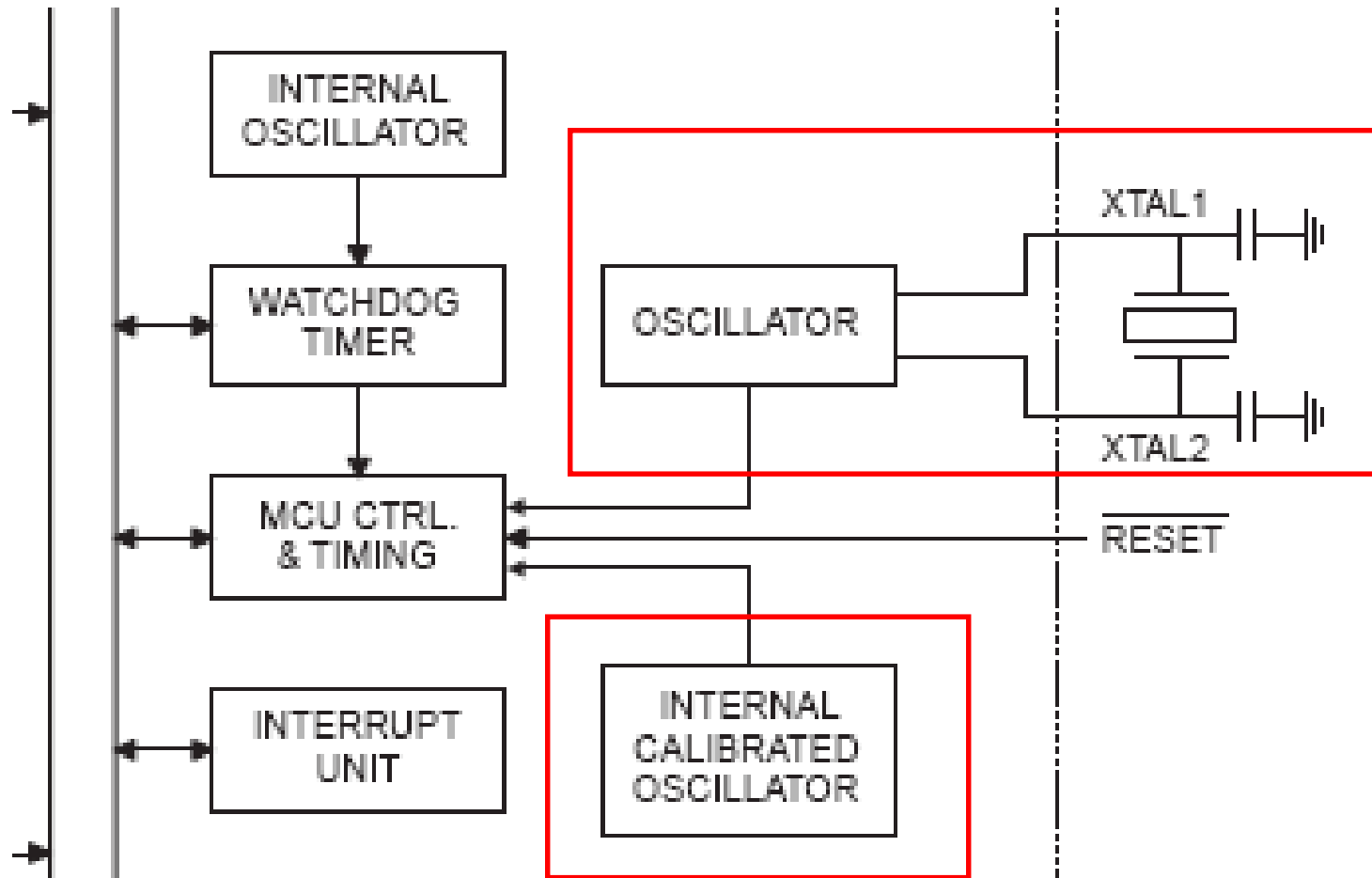
# Brown Out RESET



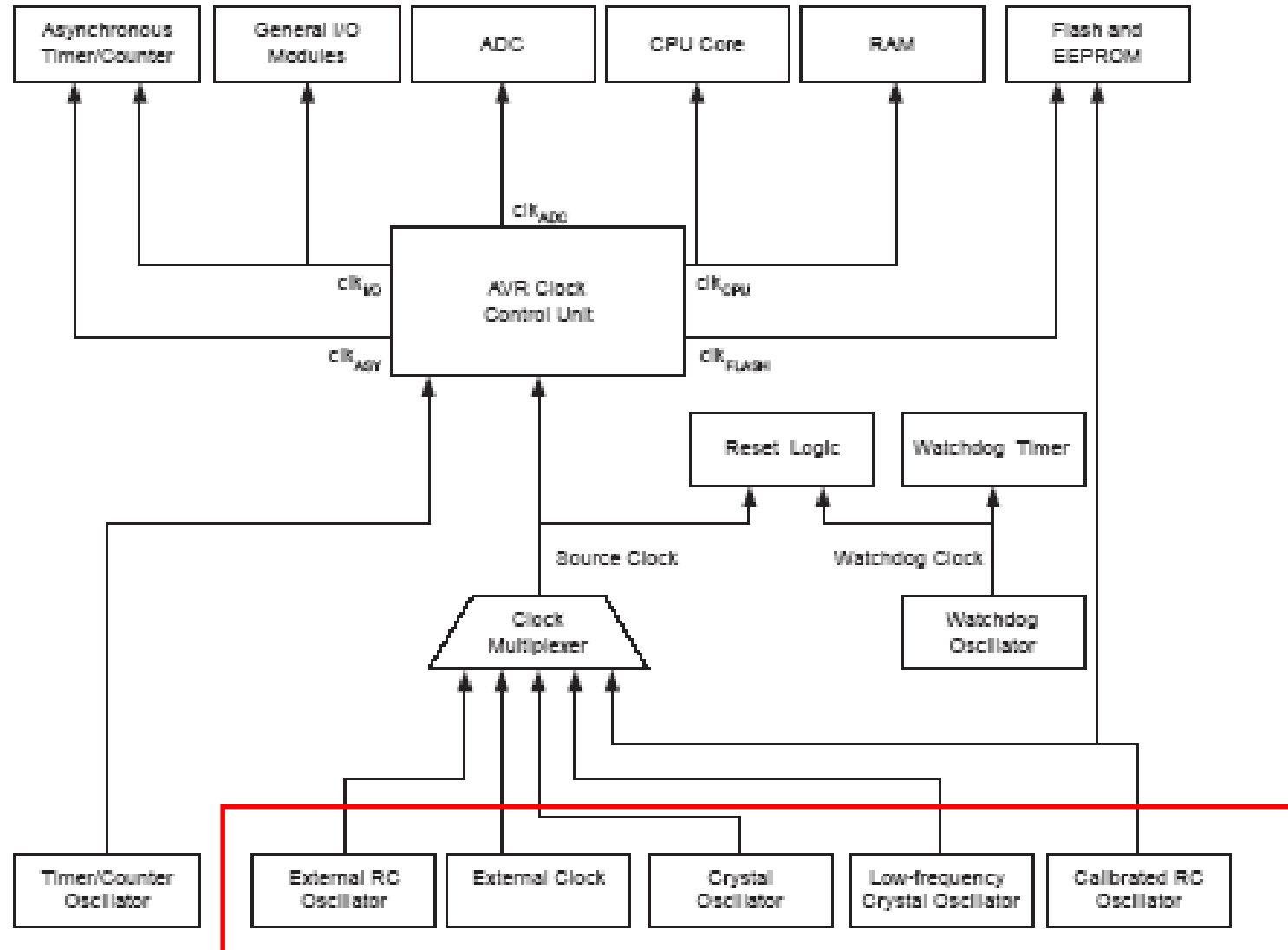
OBS:

Brown out RESET kun aktiv, hvis enabled af programmøren

# Clock options

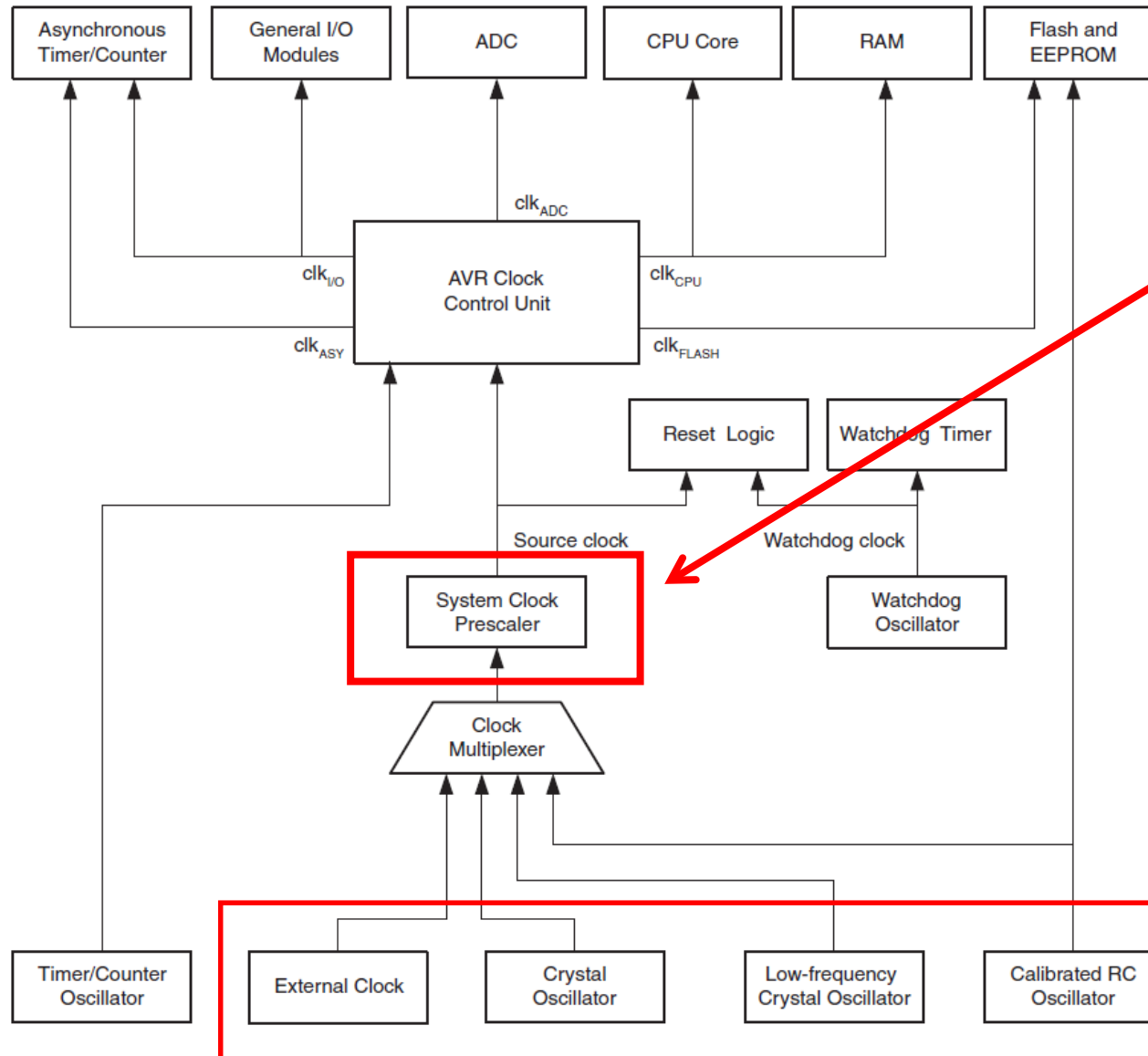


# Mega32: Intern clock distribution



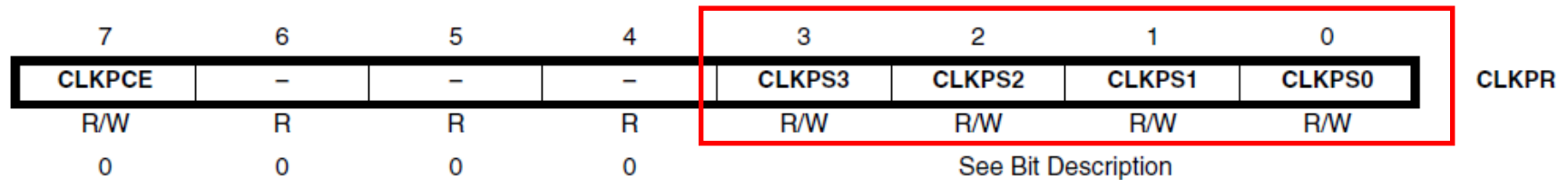


# Mega2560: Intern clock distribution



"System clock prescaler"  
Findes ikke i Mega32

# CLKPR = System Clock Prescale Register



CLKPS3	CLKPS2	CLKPS1	CLKPS0	Clock Division Factor
0	0	0	0	1
0	0	0	1	2
0	0	1	0	4
0	0	1	1	8
0	1	0	0	16
0	1	0	1	32
0	1	1	0	64
0	1	1	1	128
1	0	0	0	256

Metode (sæt prescaler til 32):

CLKPR = 0b10000000; //Skal være først

CLKPR = 0b00000101; //Straks derefter

# Clock "fuses"

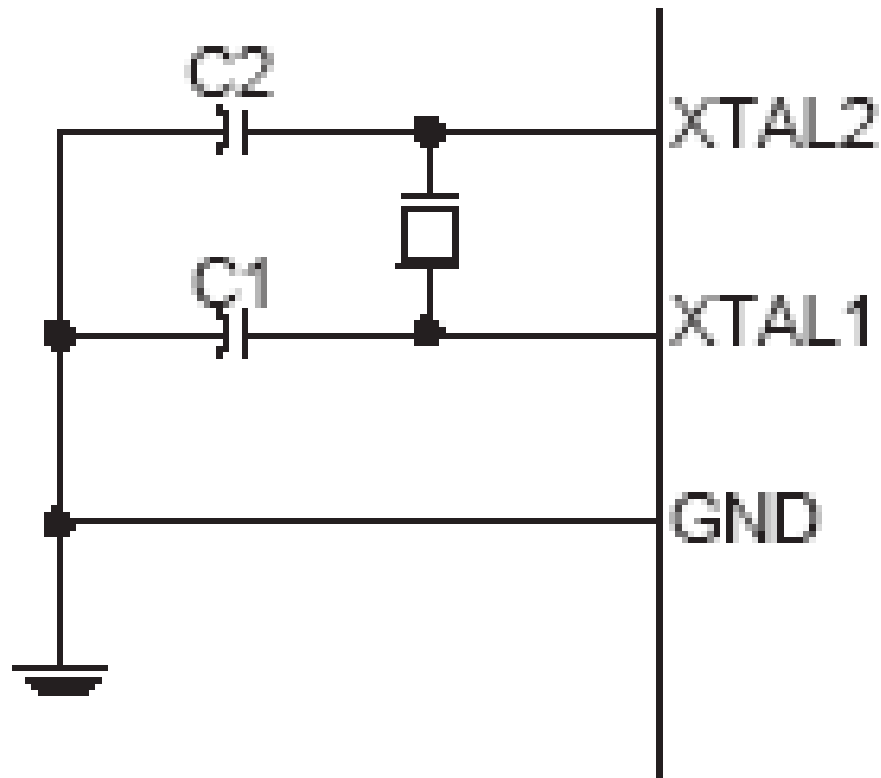
**Table 2.** Device Clocking Options Select<sup>(1)</sup>

Device Clocking Option	CKSEL3..0
External Crystal/Ceramic Resonator	1111 - 1010
External Low-frequency Crystal	1001
External RC Oscillator	1000 - 0101
Calibrated Internal RC Oscillator	0100 - 0001
External Clock	0000

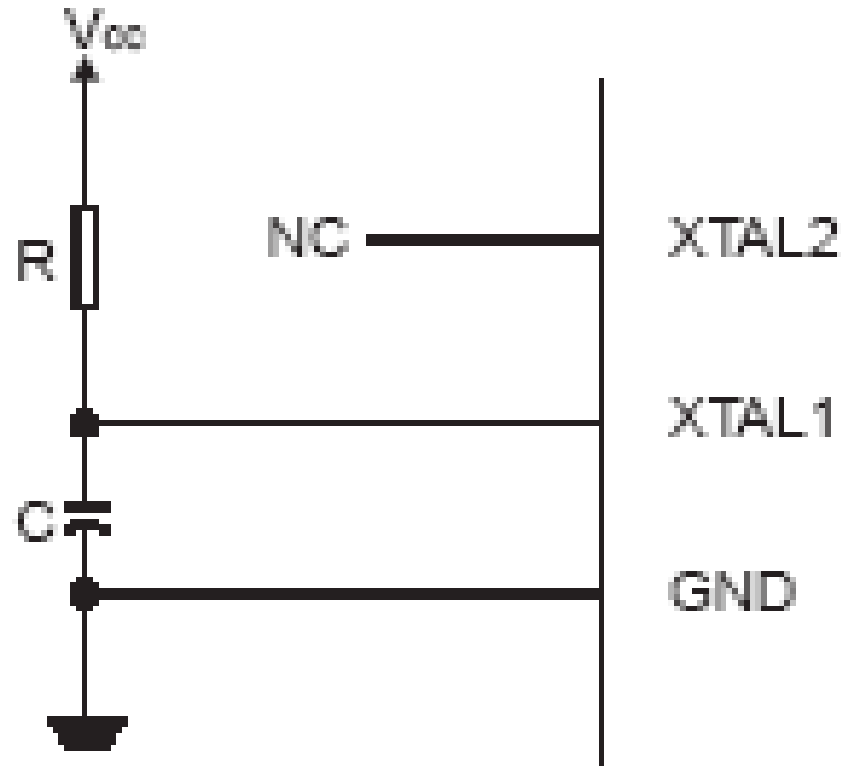
Note: 1. For all fuses "1" means unprogrammed while "0" means programmed.

- Valg af clock source sker med et programmeringsværktøj (f.eks. "AVRdude").
- Vores "Arduino Mega2560" board er sat op til at anvende et eksternt krystal - men det kan vi ændre (anbefales ikke).

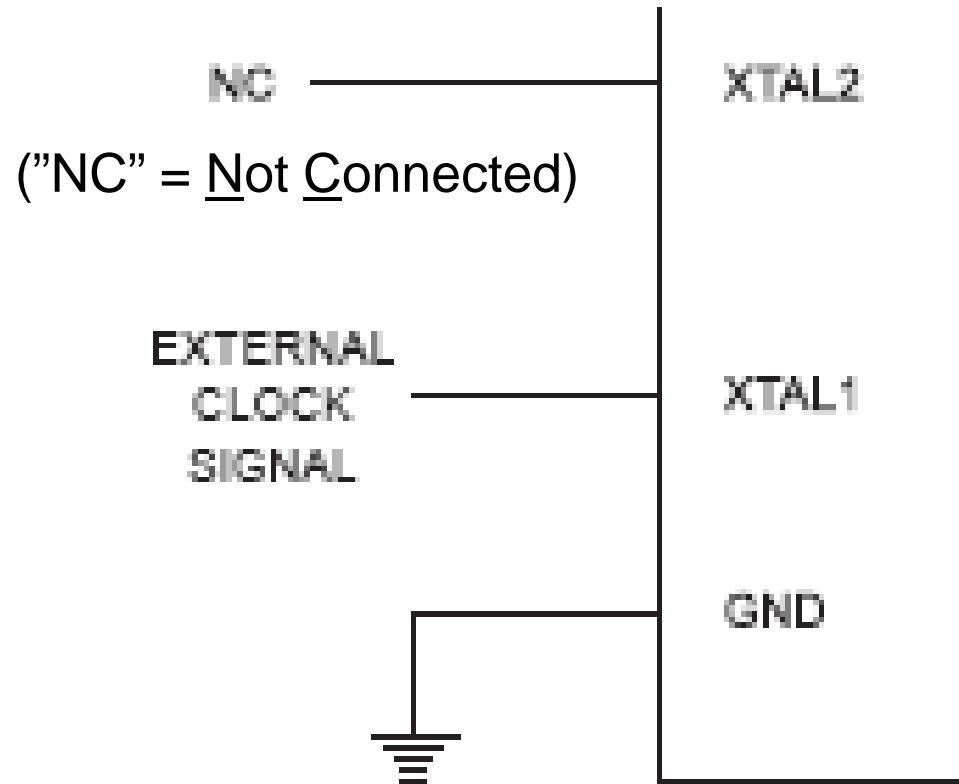
# Hvis krystal oscillator vælges:



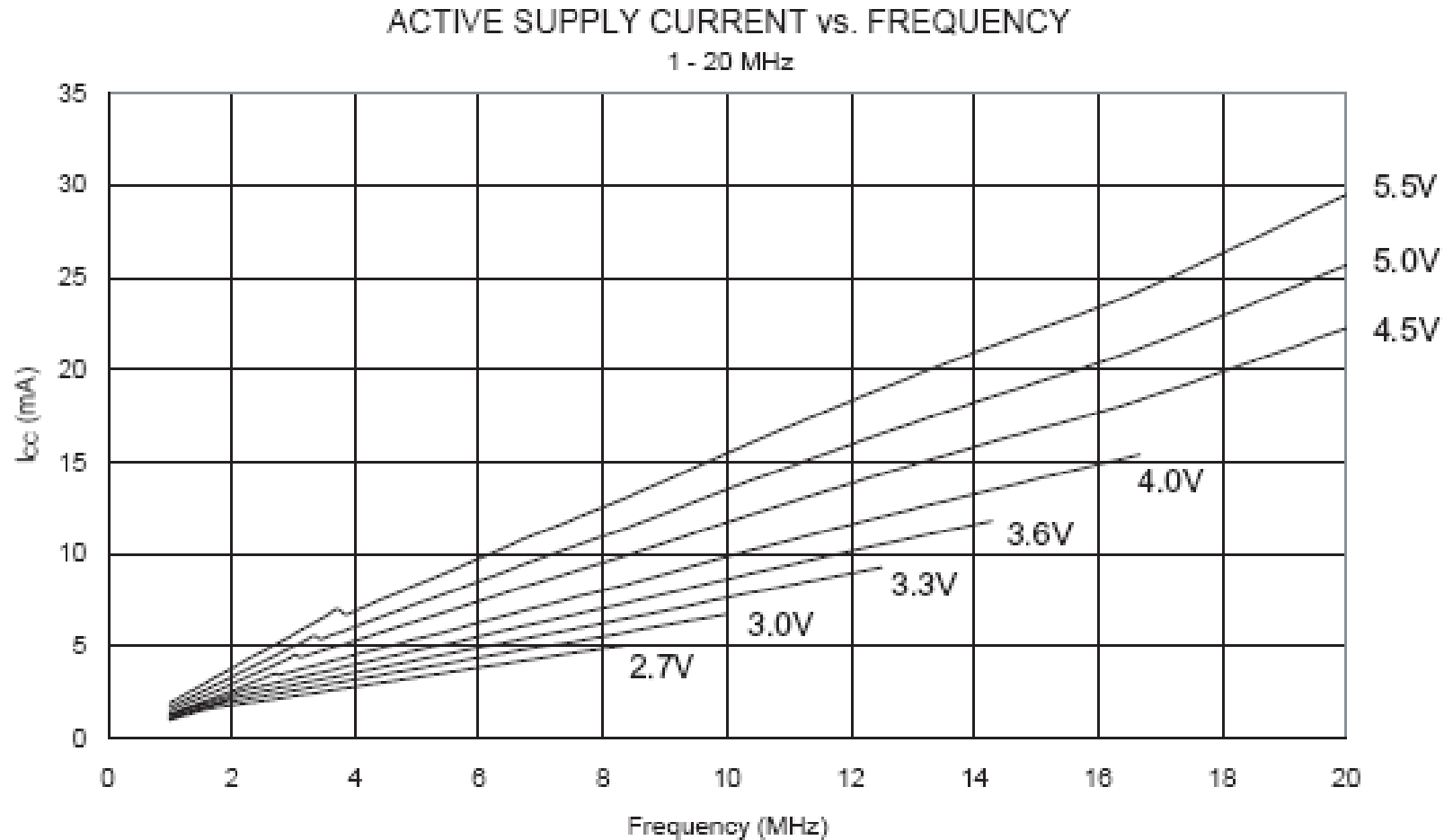
# Hvis ekstern RC-oscillator vælges:



# Hvis eksternt clocksignal vælges:



# Strømforbrug vs. frekvens



# Test ("socrative.com": Room = MSYS)

- Vi har valgt clock fuses til "external crystal" og anvender et krystal på 1 MHz.

Hvad bliver CPU clockfrekvensen efter :

CLKPR = 0b10000000;

CLKPR = 0b00001000;

A: 1 MHz

B: 3,9 kHz

C: 62,5 kHz

D: 256 kHz



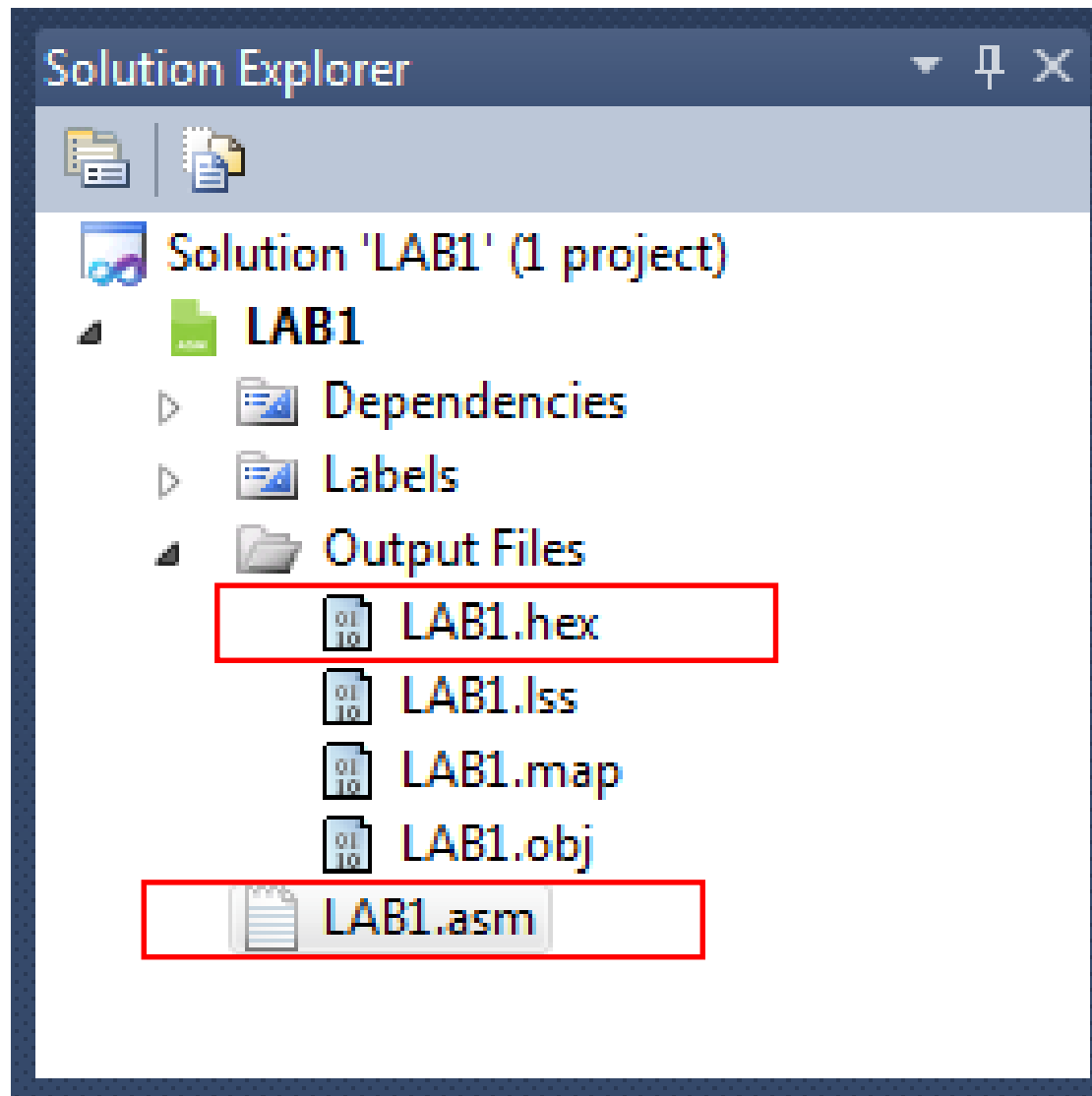


# Uddrag af en .hex - fil

```
:0C000000C942B000C9400000C940000E9
:10000C000C9400000C9400000C9400000C94000064
:10001C000C9400000C9400000C94DA000C9400007A
:10002C000C941B010C9400000C9400000C94000028
:10003C000C9400000C9400000C9400000C94000034
:10004C000C9400000C9400000000F894EE27ECBB1C
:10005C00F1E0FBBFEBBFE5BFF8E1F1BDE1BD8DE029
:10006C00A2E0BB27ED938A95E9F780E094E0A0E647
:10007C00ED930197E9F7E4E5F0E085919591009710
:10008C0061F0A591B59105901590BF01F001059017
:10009C000D920197E1F7FB01F0CFEFE5EDBFE4E046
:1000AC00EEBFC0E6D1E00C943F01E5E0E3BF08955C
:1000BC00E0E0EFBDE9E0EEBD8D9A0895E881E3360E
:1000CC0051F421FE03C0E8EFF9E102C0E2E8FBE1E4
:1000DC00FBBDEABD45C0E43651F421FE03C0E4E2A9
:1000EC00F7E102C0E3E8F8E1FBBDEABD39C0E53653
:1000FC0019F4E6EDF5E132C0E63651F421FE03C009
:10010C00E5E7F3E102C0EDE9F4E1FBBDEABD28C08F
:10011C00E73651F421FE03C0E5E5F1E102C0EDE55F
```



# LAB1 (assembly projekt)



# LAB1.asm

LAB1.asm X

```
;***** MSYS, LAB1 *****
;***** Henning Hargaard *****
;***** 14.august 2015 *****
;*****

;***** INITIERING *****
    LDI R16,HIGH(RAMEND) ;Initialize Stack Pointer
    OUT SPH,R16
    LDI R16,LOW(RAMEND)
    OUT SPL,R16
    SER R16              ;PORTB = Outputs
    OUT DDRB,R16

;***** PROGRAM-LOOP *****
    CLR R16
LOOP:
    LDI R17,9            ;R17 = 9
    ADD R16,R17          ;R16 = R16 + R17
    CALL DISP_AND_DELAY ;Display R16
    JMP LOOP             ;Jump to "LOOP"
```

# LAB1.hex

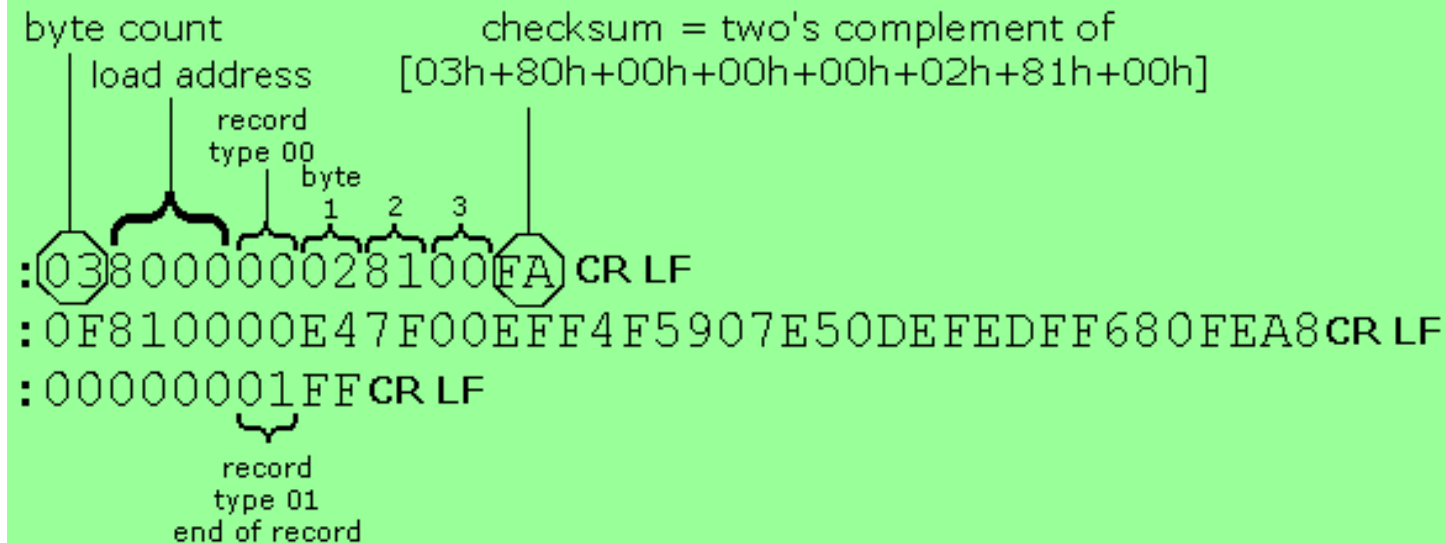
LAB1.hex X LAB1.asm

```
:0200000020000FC  
:1000000008E00EBF0FE50DBF0FEF07BB0DE00E942C  
:100010000E0019E0010F0E940E00F8CF102F10956E  
:1000200018BB112722273AE01A95F1F72A95E1F734  
:060030003A95D1F7089596  
:000000001FF
```

# Intel 8 Hex format

```
:10010000214601360121470136007EFE09D2190140
:100110002146017EB7C20001FF5F16002148011988
:10012000194E79234623965778239EDA3F01B2CAA7
:100130003F0156702B5E712B722B732146013421C7
:000000001FF
```

- Start code
- Byte count
- Address
- Record type
- Data
- Checksum



# LAB1.hex

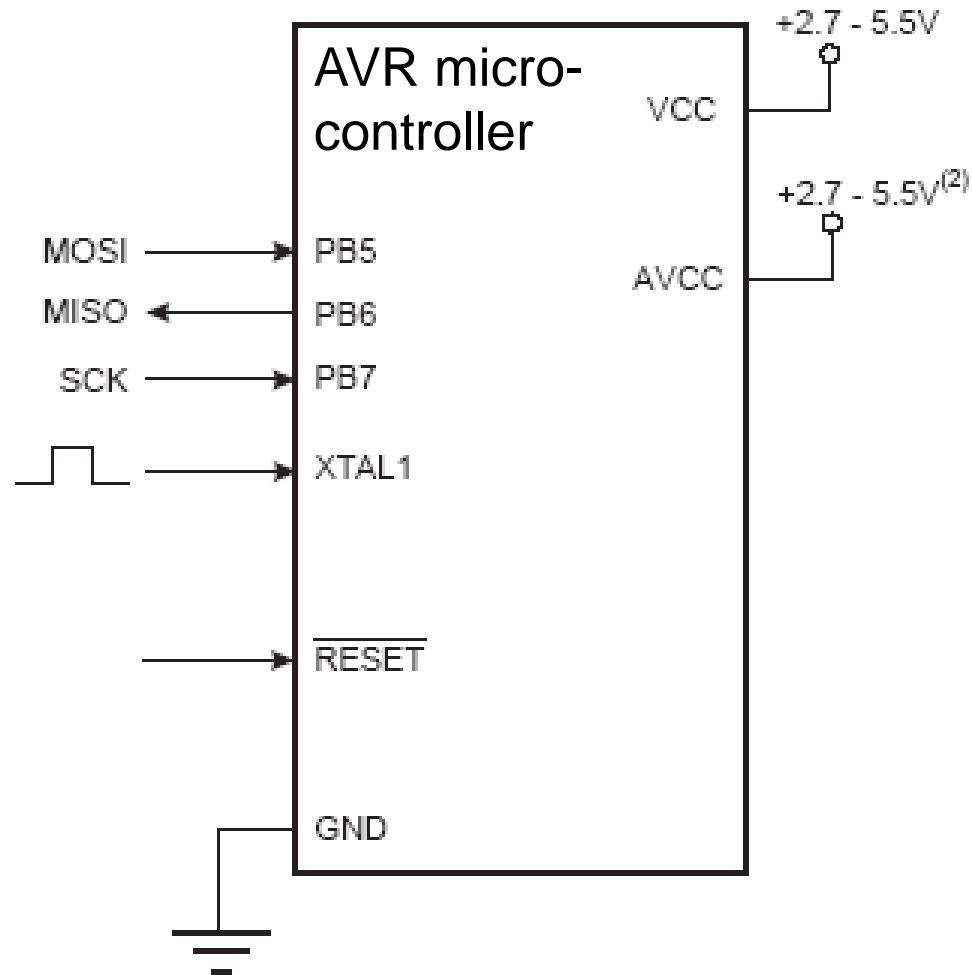
LAB1.hex X LAB1.asm

```
:0200000020000FC  
:1000000008E00EBF0FE50DBF0FEF07BB0DE00E942C  
:100010000E0019E0010F0E940E00F8CF102F10956E  
:1000200018BB112722273AE01A95F1F72A95E1F734  
:060030003A95D1F7089596  
:000000001FF
```

# AVR programmerings-metoder

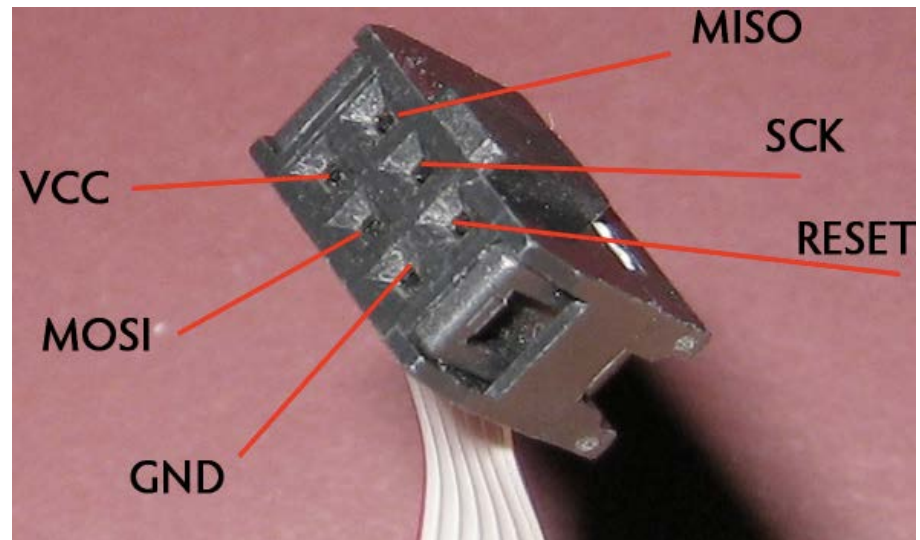
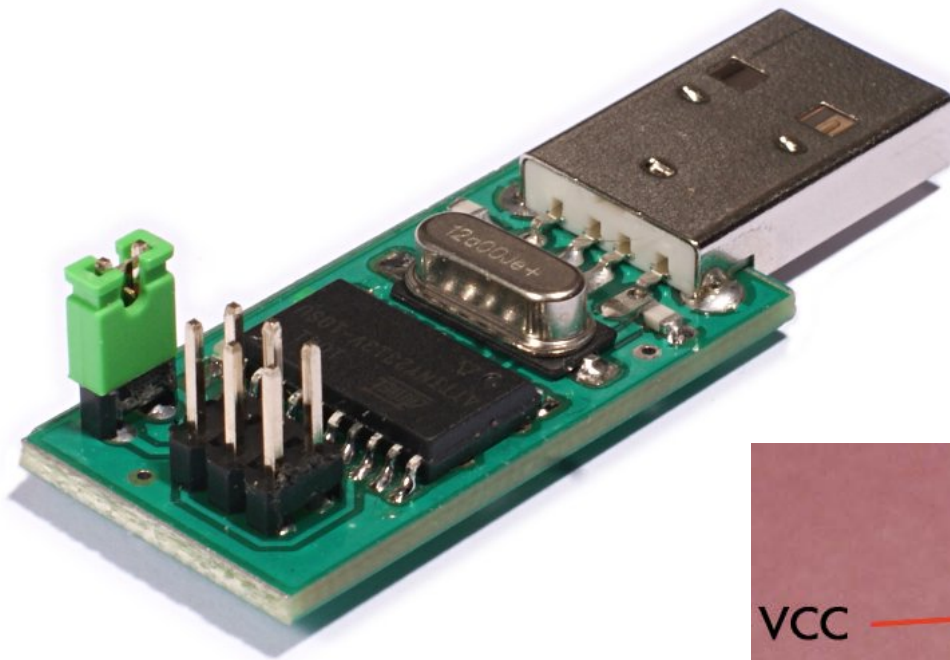
- Parallel programming (anvendes sjældent).
- **ISP** = **I**n **S**ystem **P**rogramming (anvendes meget ofte).
  - **SPI**
  - JTAG (kræver ekstra – ret dyrt – udstyr).
- **Bootloading** (speciel teknik, der kræver specialprogram på microcontrolleren).  
“Arduino Mega2560” boardet har en bootloader, der er programmeret fra fabrikken.

# ISP serial programming



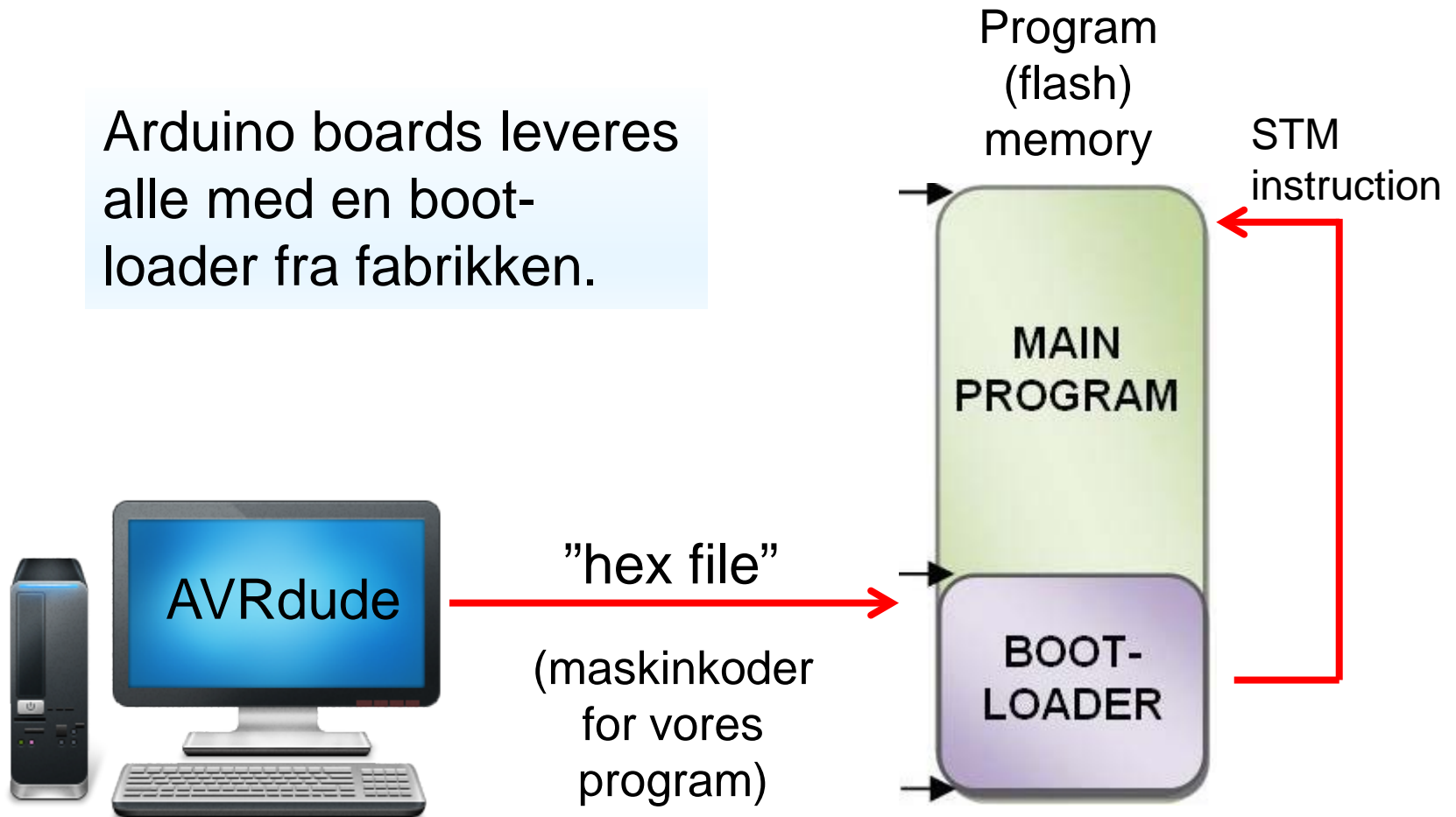


# ISP programmer



# Boot loading

Arduino boards leveres alle med en boot-loader fra fabrikken.



# Slut på lektion 11

