denominator²:
$$[\omega_1(1-u)^2 + 2 \cdot \omega_2 \cdot U(1-u) + \omega_3 u^2]^2$$

W,2(1-u)4

2w, wz u (1-u)3 N

 $\omega_1 \omega_3 u^2 (1-u)^2$ $2\omega_1 \omega_2 u (1-u)^3$ $4\omega_2^2 u^2 (1-u)^2$

2 wzw3 u3(1-u) K

7 wiws u2(1-u)2 }

2 w 2 w 3 (1- u) 9 w 3 2 (14

(Test wi=ws=vz) wz=1

$$(1-u)^{4} = \omega_{1}^{2}$$

$$u(1-u)^{3} = 4\omega_{1}\omega_{2}$$

$$u^{2}(1-u)^{2} = 4\omega_{2}^{2} + 2\omega_{1}\omega_{3}$$

$$u^{3}(1-u) = 4\omega_{2}\omega_{3}$$

$$u^{4} = \omega_{3}^{2}$$

Control Points & Weights

3:
$$\omega_2 = 1$$
; (cos 20, sin 28)

$$num(x) = (1-u^2) + 28\cos8w_2u(1-u) + u^2\cos29$$

$$nod y) = 2 ssin \partial \omega_1 + u^2 sin 20$$

$$(u(1-u)$$

denom:
$$(1-u)^2 + 2u(1-u)w_1 + u^2$$

$$U^{2}(1-u)^{2} = 4w_{1}^{2} + 2$$

$$0^{2}(1-u)^{2} = 4\omega_{1}^{2} + 2$$

$$0^{3}(1-u)^{2} = 4\omega_{1}$$

$$u^{4} = 1$$

$$x^{2} = [(-u)^{2} + 2s \cdot \cos\theta_{\omega_{1}} \ \upsilon(1-u) + \omega_{1}^{2}\cos2\theta]^{2}$$

$$(-u)^{4} = 1$$

$$\upsilon(1-u)^{3} = 4[s \cdot \cos\theta_{\omega_{1}}]^{2} + 2\cos2\theta$$

$$\upsilon^{2}(1-u)^{2} = 4[s \cdot \cos\theta_{\omega_{1}}]^{2} + 2\cos2\theta$$

$$\upsilon^{2}(1-u)^{2} = 4s^{2}\cos^{2}\theta_{\omega_{1}} + 2\cos2\theta$$

$$\upsilon^{3}(1-u) = 4[s\cos\theta_{\omega_{1}}][\cos2\theta]$$

$$\upsilon^{3}(1-u) = 4s\cos\theta\cos2\theta_{\omega_{1}}$$

$$u^{4} = \cos^{2}2\theta$$

$$\upsilon^{2} = [2s \cdot \sin\theta_{\omega_{1}} \cdot \upsilon(1-u) + u^{2} \cdot \sin\theta_{\omega_{1}}]$$

$$\upsilon^{2}(1-u)^{2} = 4s^{2}\sin^{2}\theta_{\omega_{1}}]$$

$$\upsilon^{2}(1-u)^{2} = 4s\sin\theta\sin2\theta_{\omega_{1}}$$

$$\upsilon^{4} = \sin^{2}2\theta$$

$$x^{2} + y^{2} \Rightarrow$$

$$(-u)^{4} = 1$$

$$\upsilon(1-u)^{3} = 4s\cos\theta_{\omega_{1}} + 2\cos2\theta + 4s^{2}\sin^{2}\theta_{\omega_{1}}$$

$$\upsilon^{2}(1-u)^{2} = 4s^{2}\cos^{2}\theta_{\omega_{1}} + 2\cos2\theta + 4s^{2}\sin^{2}\theta_{\omega_{1}}$$

$$\upsilon^{3}(1-u) = 4s\omega_{1}[\cos\theta_{\cos2}\theta + \sin\theta_{\sin2}\theta]$$

$$(1-u)^{3}: 4 \le \cos \theta \ \omega_{1} = 4 \omega_{1}$$

$$5 \cos \theta = 1$$

$$(1-u)^{2} 4 \sec^{2} \theta \omega_{1} + 4 \sec^{2} \sin^{2} \theta \omega_{1} + 2 \cos^{2} \theta = 4 \omega_{1}^{2} + 2$$

$$4 \sec^{2} \omega_{1}^{2} + 2 \cos^{2} \theta = 4 \omega_{1}^{2} + 2$$

$$\frac{4 \omega_{1}^{2}}{\cos^{2} \theta} + 2 \cos^{2} \theta = 4 \omega_{1}^{2} + 2$$

$$4 \cos^{4} \theta + 2 \cos^{2} \theta + 4 \omega_{1}^{2} = 0$$

$$4 \cos^{4} \theta + (4 \omega_{1}^{2} + 4) \cos^{2} \theta + 4 \omega_{1}^{2} = 0$$

$$6 \cos^{4} \theta + (-\omega_{1}^{2} - 1) \cos^{4} \omega_{1}^{2} = 0$$

$$6 \cos^{2} \theta = \omega_{1}^{2} + 1 \pm \sqrt{\omega_{1}^{4} + 2 \omega_{1}^{2} + 1 + 4 \omega_{1}^{2}}$$

$$= \omega_{1}^{2} + 1 \pm \sqrt{\omega_{1}^{4} + 2 \omega_{1}^{2} + 1 + 4 \omega_{1}^{2}}$$

$$\cos^{2} \theta = \omega_{1}^{2} + 1 \pm \sqrt{(\omega_{1}^{2} - 1)^{2}}$$

$$\cos^{2} \theta = \omega_{1}^{2} + 1 \pm \sqrt{(\omega_{1}^{2} - 1)^{2}}$$

$$\cos^{2} \theta = \omega_{1}^{2} + 1 \pm \sqrt{(\omega_{1}^{2} - 1)^{2}}$$

$$\cos^{2} \theta = \omega_{1}^{2} + 1 \pm \sqrt{(\omega_{1}^{2} - 1)^{2}}$$

$$\cos^{2} \theta = \omega_{1}^{2} + 1 \pm \sqrt{(\omega_{1}^{2} - 1)^{2}}$$

$$= \omega_1^2 \qquad \cos^2\theta = \omega_1^2 + |-\omega_1 + |$$

$$\cos\theta = \omega_1 \qquad OR$$

$$\cos^2\theta = \omega_1 \qquad \omega_2^2\theta = 1$$

$$\cos^2\theta = \omega_1 \qquad \omega_1 = \cos\theta$$

$$\sec^2\theta = 1$$