

Support Vector Machines

Classification with SVM, kernel trick

Machine Learning and Data Mining, 2020

Artem Maevskiy

National Research University Higher School of Economics



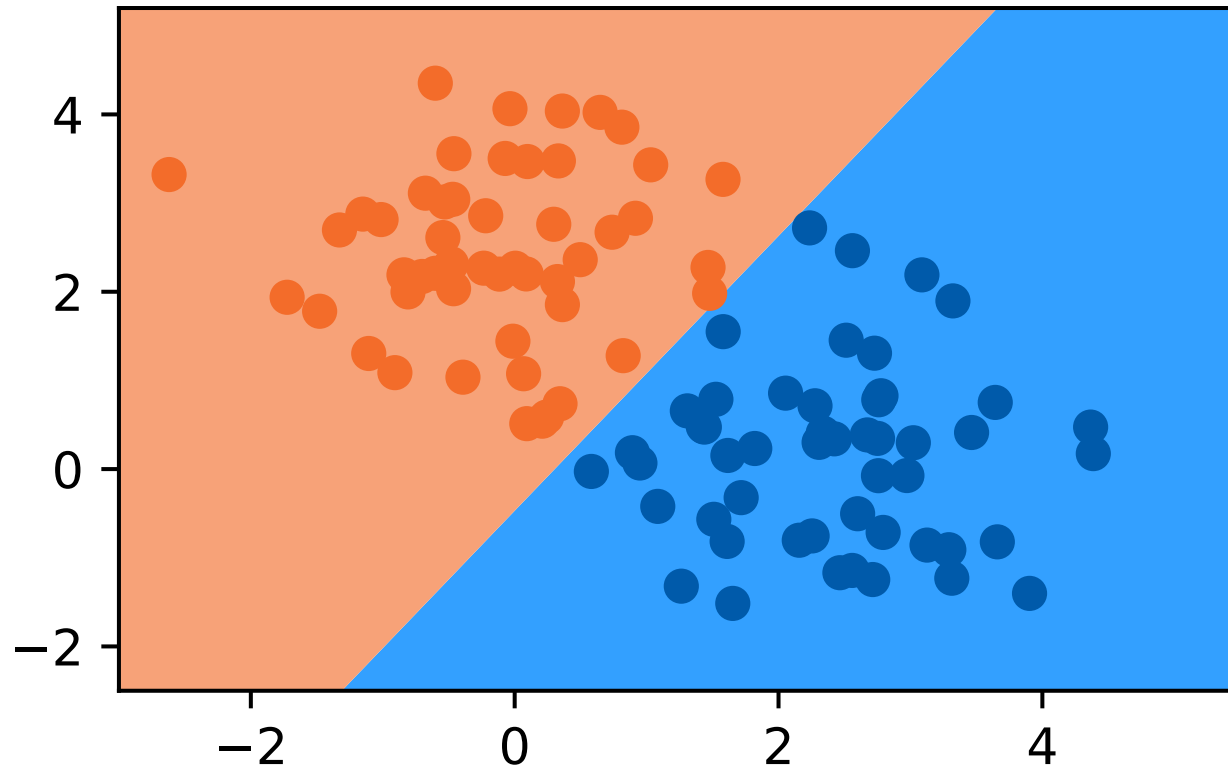
LAMBA • HSE

October 02, 2020

General Idea (linearly separable case)



Classification with linear models



$$\hat{f}(x) = \text{sign}[w^T x + w_0]$$

$$y \in \{-1, 1\}$$

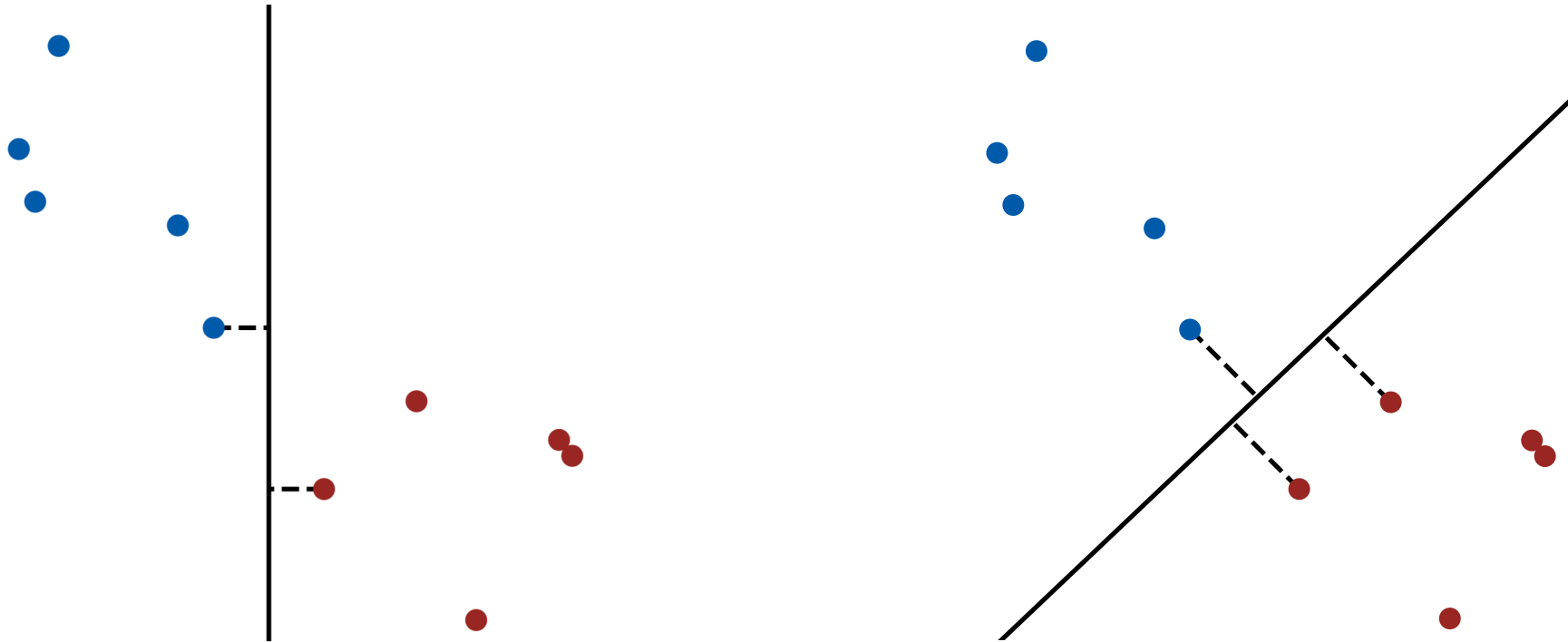
Separating hyperplane:

$$w^T x + w_0 = 0$$

Optimal hyperplane

Assume a separating hyperplane exists (task is linearly separable)

Idea: find the best hyperplane by maximizing the distance to the closest data points



Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$

Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$

defined up to a multiplicative constant

We can choose this constant s.t. for the

closest point: $y_{\text{closest}}(w^T x_{\text{closest}} + w_0) = 1$

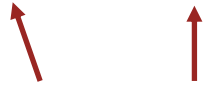
Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$



defined up to a multiplicative constant

We can choose this constant s.t. for the

closest point: $y_{\text{closest}}(w^T x_{\text{closest}} + w_0) = 1$

So for all points:

$$y(w^T x + w_0) \geq 1$$


Mathematical formulation

Correct classification if:

$$\begin{cases} w^T x + w_0 > 0, & y = +1 \\ w^T x + w_0 < 0, & y = -1 \end{cases}$$

or equivalently:

$$y(w^T x + w_0) > 0$$


defined up to a multiplicative constant
We can choose this constant s.t. for the
closest point: $y_{\text{closest}}(w^T x_{\text{closest}} + w_0) = 1$

So for all points:

$$y(w^T x + w_0) \geq 1$$

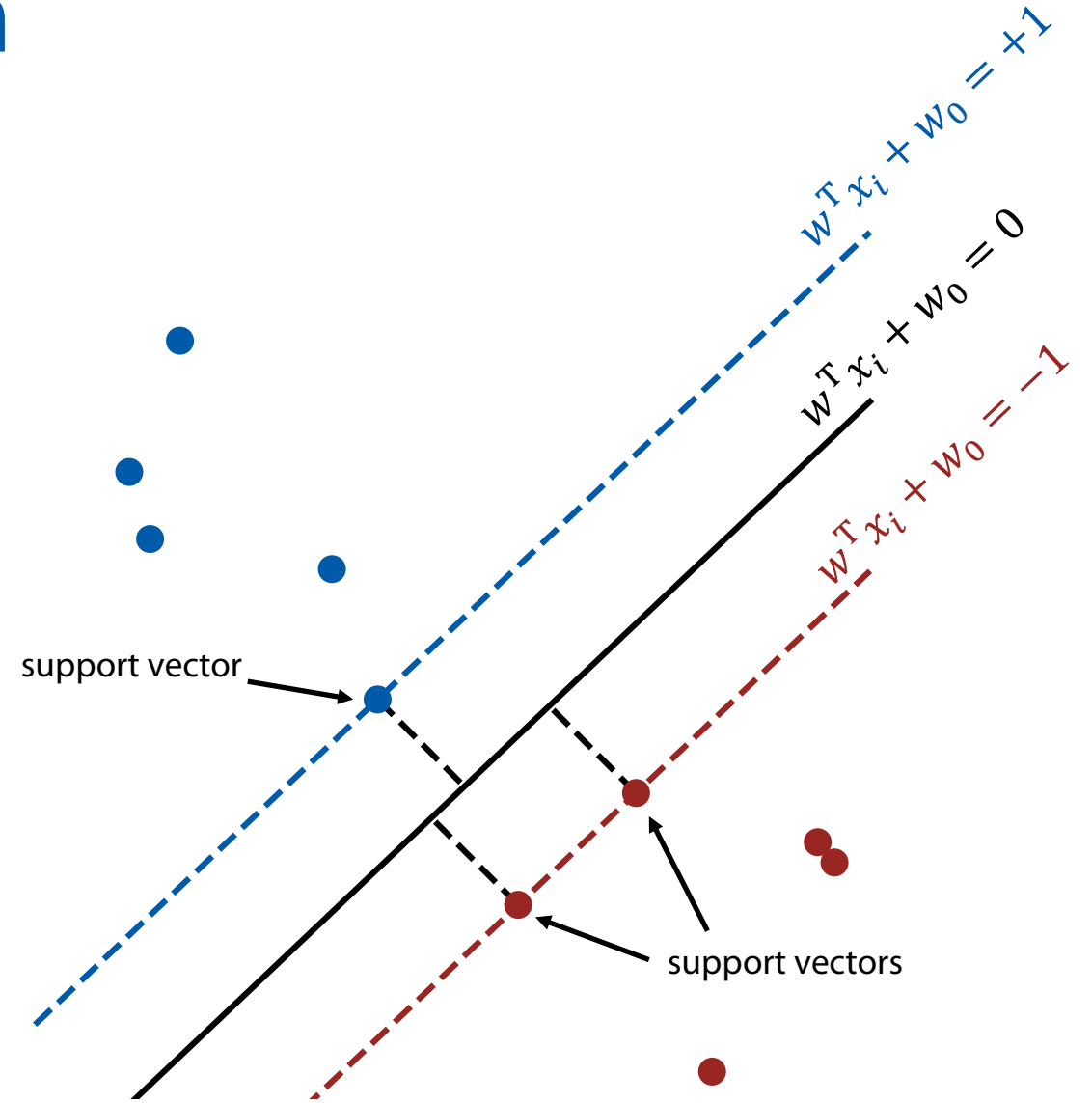
Distance to the closest point is:

$$h = y_{\text{closest}} \frac{(w^T x_{\text{closest}} + w_0)}{\|w\|} = \frac{1}{\|w\|}$$

Mathematical formulation

So the problem can be defined as:

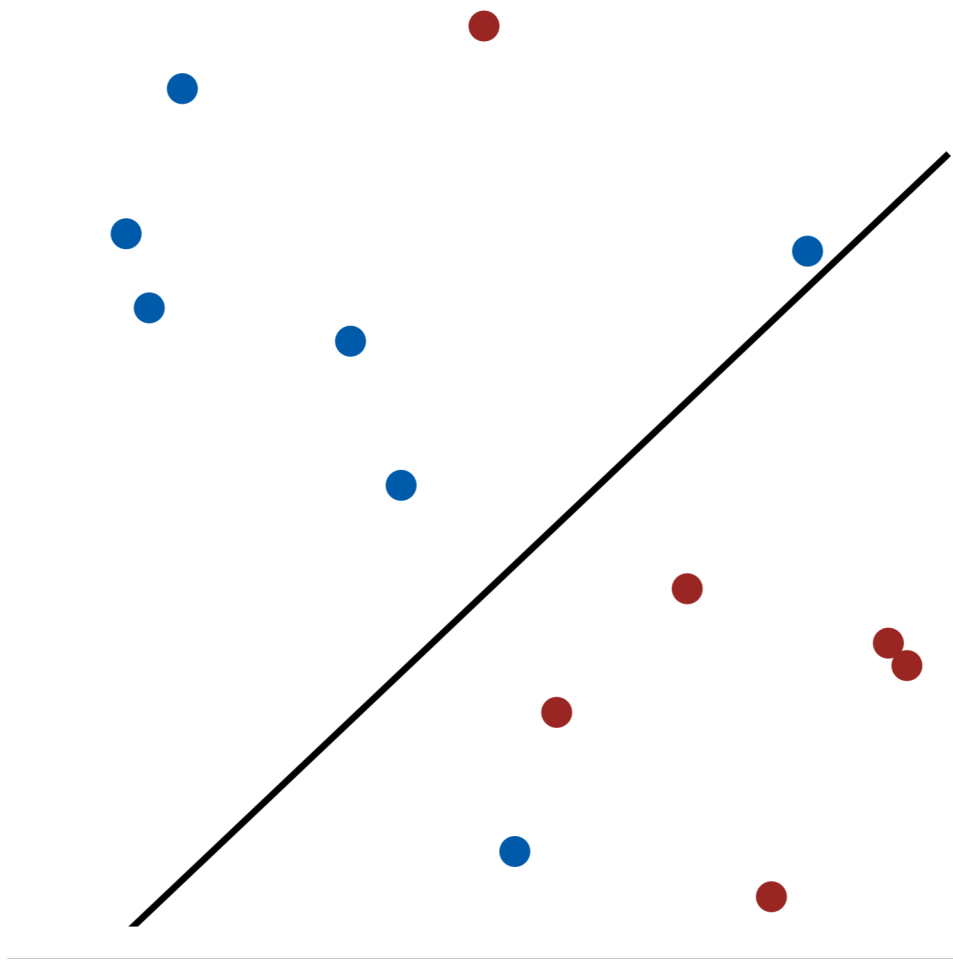
$$\begin{cases} \frac{1}{2} \|w\|^2 \rightarrow \min_{w, w_0} \\ y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N \end{cases}$$



Nonseparable case



Slack variables

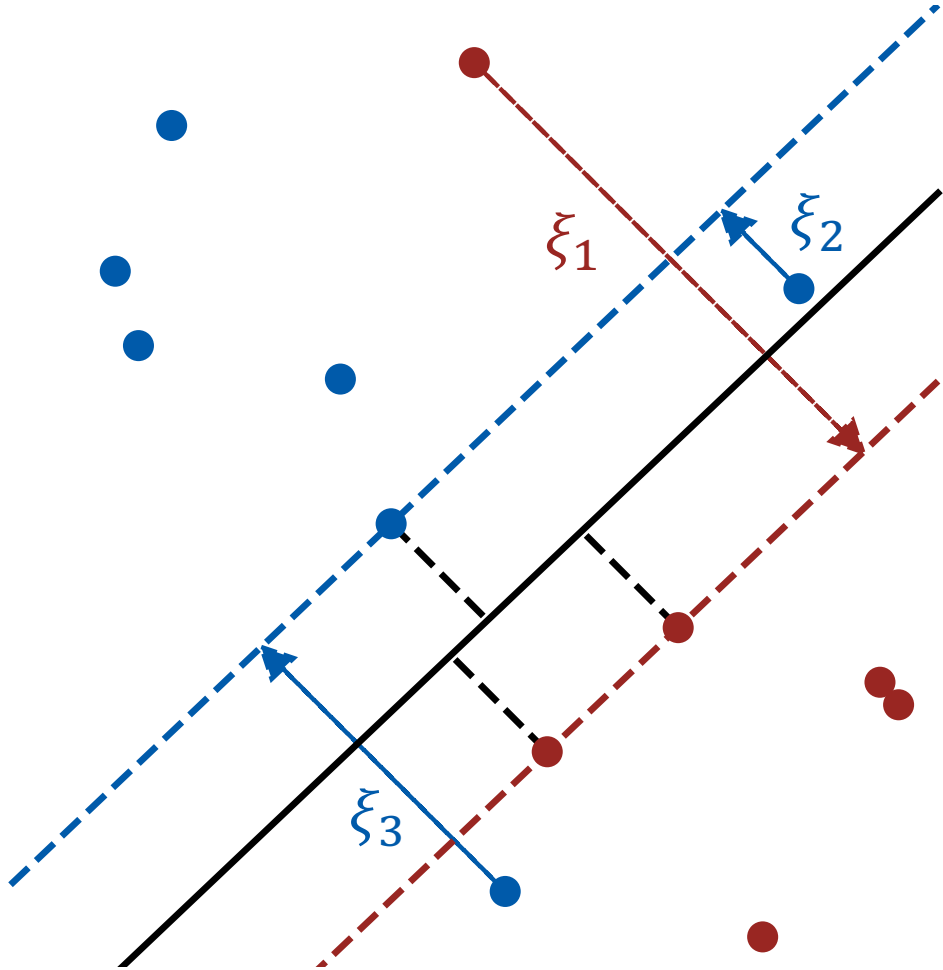


For nonseparable case, these conditions:

$$y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

cannot be satisfied simultaneously.

Slack variables



For nonseparable case, these conditions:

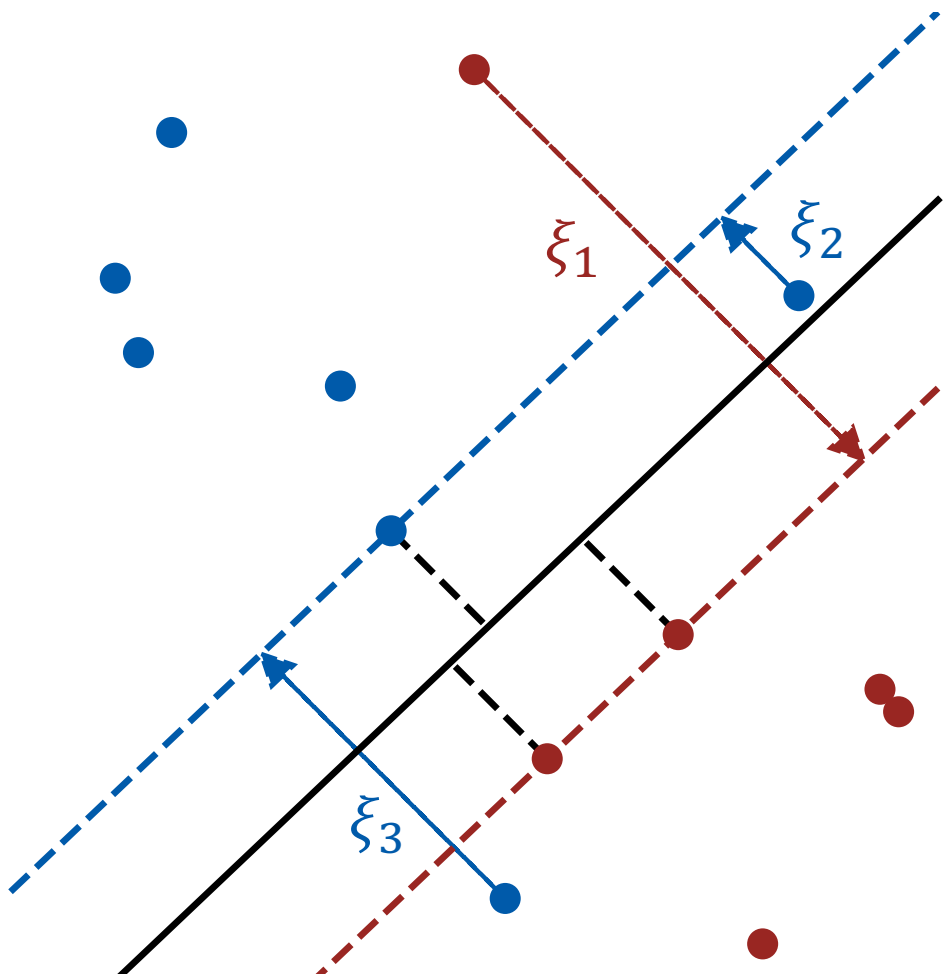
$$y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

cannot be satisfied simultaneously.

Need to introduce slack variables ξ_i :

$$\begin{aligned} y_i(w^T x_i + w_0) &\geq 1 - \xi_i, \\ \xi_i &\geq 0, \quad i = 1, \dots, N \end{aligned}$$

Slack variables



For nonseparable case, these conditions:

$$y_i(w^T x_i + w_0) \geq 1, \quad i = 1, \dots, N$$

cannot be satisfied simultaneously.

Need to introduce slack variables ξ_i :

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i, \\ \xi_i \geq 0, \quad i = 1, \dots, N$$

And the objective function becomes:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

Solution

To solve:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

subject to:

$$\begin{aligned} y_i (w^T x_i + w_0) &\geq 1 - \xi_i, \\ \xi_i &\geq 0, \quad i = 1, \dots, N \end{aligned}$$

Solution

To solve:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

subject to:

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i, \\ \xi_i \geq 0, \quad i = 1, \dots, N$$

define the Lagrangian:

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i(w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$

Solution

To solve:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i \rightarrow \min_{w, w_0, \xi}$$

subject to:

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i, \\ \xi_i \geq 0, \quad i = 1, \dots, N$$

define the Lagrangian:

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i(w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$

Solution determined by the Karush–Kuhn–Tucker conditions:

$$\frac{\partial L}{\partial (w, w_0, \xi_i)} = 0 \quad L \rightarrow \max_{\alpha, r}$$

$$\alpha_i \geq 0, \quad r_i \geq 0$$

$$y_i(w^T x_i + w_0) \geq 1 - \xi_i$$

$$\xi_i \geq 0,$$

$$\alpha_i (y_i(w^T x_i + w_0) - 1 + \xi_i) = 0$$

$$r_i \xi_i = 0 \quad i = 1, \dots, N$$

Solution

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$
$$\frac{\partial L}{\partial w} = 0 \quad \Rightarrow \quad w = \sum_{i=1}^N \alpha_i y_i x_i$$

i.e. the solution is a **linear combination** of the training objects.

Solution

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$
$$\frac{\partial L}{\partial w} = 0 \quad \Rightarrow \quad w = \sum_{i=1}^N \alpha_i y_i x_i$$

i.e. the solution is a **linear combination** of the training objects.

$$\frac{\partial L}{\partial w_0} = 0 \quad \Rightarrow \quad \sum_{i=1}^N \alpha_i y_i = 0$$

i.e. the combination coefficients need to be **balanced** between classes.

Solution

$$L(w, w_0, \xi, \alpha, r) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \alpha_i (y_i (w^T x_i + w_0) - 1 + \xi_i) - \sum_{i=1}^N r_i \xi_i$$
$$\frac{\partial L}{\partial w} = 0 \quad \Rightarrow \quad w = \sum_{i=1}^N \alpha_i y_i x_i$$

i.e. the solution is a **linear combination** of the training objects.

$$\frac{\partial L}{\partial w_0} = 0 \quad \Rightarrow \quad \sum_{i=1}^N \alpha_i y_i = 0$$

i.e. the combination coefficients need to be **balanced** between classes.

$$\frac{\partial L}{\partial \xi_i} = 0 \quad \Rightarrow \quad C - \alpha_i - r_i = 0$$

Dual problem

Substituting these into the Lagrangian:

$$w = \sum_{i=1}^N \alpha_i y_i x_i, \quad \sum_{i=1}^N \alpha_i y_i = 0, \quad C - \alpha_i - r_i = 0$$

we obtain the **dual problem**:

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \rightarrow \max_{\alpha}$$

subject to:

$$\sum_{i=1}^N \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C$$

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

$$y_i(w^T x_i + w_0) > 1 \Rightarrow \alpha_i = 0 \quad \textbf{(non-informative vector)}$$

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

$$y_i(w^T x_i + w_0) > 1 \Rightarrow \alpha_i = 0 \quad \textbf{(non-informative vector)}$$

$$y_i(w^T x_i + w_0) < 1 \Rightarrow \xi_i > 0, \quad r_i = 0, \quad \alpha_i = C \quad \textbf{(non-boundary support vector)}$$

Support vectors

Due to these KKT conditions:

$$\alpha_i(y_i(w^T x_i + w_0) - 1 + \xi_i) = 0, \quad r_i \xi_i = 0$$

there are the following options for the training objects:

$$y_i(w^T x_i + w_0) > 1 \Rightarrow \alpha_i = 0 \quad \textbf{(non-informative vector)}$$

$$y_i(w^T x_i + w_0) < 1 \Rightarrow \xi_i > 0, r_i = 0, \alpha_i = C \quad \textbf{(non-boundary support vector)}$$

$$y_i(w^T x_i + w_0) = 1 \Rightarrow \xi_i = 0, \alpha_i \in [0, C] \quad \textbf{(boundary support vector)}$$

Whole pipeline:


Solve the dual problem to find the optimal α^*

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j x_i^T x_j \rightarrow \max_{\alpha}$$
$$\sum_{i=1}^N \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C$$

Make predictions for new data:

$$\hat{y} = \text{sign} \left(\sum_{i \in \text{SV}} \alpha_i^* y_i x_i^T x + w_0 \right)$$

Can be obtained from e.g. boundary support vectors from: $y_i(w^T x_i + w_0) = 1$



Kernel trick



Whole pipeline:

Note that the dual problem and prediction depend on the data only through **scalar products**:

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j \rightarrow \max_{\alpha}$$

$$\sum_{i=1}^N \alpha_i y_i = 0, \quad 0 \leq \alpha_i \leq C$$

$$\hat{y} = \text{sign} \left(\sum_{i \in SV} \alpha_i^* y_i \mathbf{x}_i^T \mathbf{x} + w_0 \right)$$

Feature expansion

Suppose we want to expand our features:

$$x_i \rightarrow \phi(x_i)$$

Then, our solution would only depend on the scalar products: $\phi^T(x_i)\phi(x_j)$.

Feature expansion

Suppose we want to expand our features:

$$x_i \rightarrow \phi(x_i)$$

Then, our solution would only depend on the scalar products: $\phi^T(x_i)\phi(x_j)$.

E.g. for the following polynomial expansion: $(x_1, x_2)_i \rightarrow \left(\frac{1}{2}, x_1, x_2, x_1^2, \sqrt{2}x_1x_2, x_2^2\right)_i$,

the scalar product equals to:

$$\begin{aligned} \frac{1}{4} + x_{1i}x_{1j} + x_{2i}x_{2j} + (x_{1i}x_{1j})^2 + 2(x_{1i}x_{1j})(x_{2i}x_{2j}) + (x_{2i}x_{2j})^2 = \\ = \frac{1}{4} + x_i^T x_j + (x_i^T x_j)^2 = \left(x_i^T x_j + \frac{1}{2}\right)^2 \end{aligned}$$

Feature expansion

Suppose we want to expand our features:

$$x_i \rightarrow \phi(x_i)$$

Then, our solution would only depend on the scalar products: $\phi^T(x_i)\phi(x_j)$.

E.g. for the following polynomial expansion: $(x_1, x_2)_i \rightarrow \left(\frac{1}{2}, x_1, x_2, x_1^2, \sqrt{2}x_1x_2, x_2^2\right)_i$,
the scalar product equals to:

$$\begin{aligned} \frac{1}{4} + x_{1i}x_{1j} + x_{2i}x_{2j} + (x_{1i}x_{1j})^2 + 2(x_{1i}x_{1j})(x_{2i}x_{2j}) + (x_{2i}x_{2j})^2 = \\ = \frac{1}{4} + x_i^T x_j + (x_i^T x_j)^2 = \left(x_i^T x_j + \frac{1}{2}\right)^2 \end{aligned}$$

So instead of doing the expansion we can replace all scalar products with:

$$x_i^T x_j \rightarrow K(x_i, x_j) = \left(x_i^T x_j + \frac{1}{2}\right)^2$$

RBF kernel

This trick allows for expansions that would normally be infeasible to compute, e.g. expansions to infinite dimension spaces.

Example: **Radial Basis Function** (RBF) kernel:

$$K(x_i, x_j) = e^{-\gamma \|x_i - x_j\|^2}$$

This kernel has maximum of 1 for $x_i = x_j$, and decays to 0 as the vectors become further apart. Hence, the solution averages the labels for nearby support vectors:

$$\hat{y} = \text{sign} \left(\sum_{i \in SV} \alpha_i^* y_i K(x_i, x) + w_0 \right)$$

Can any function be a kernel?

Note that the quadratic form of the dual problem is defined by the symmetric, positive semi-definite matrix XX^T :

$$\sum_i \alpha_i - \frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j \rightarrow \max_{\alpha}$$

In fact, kernel functions should also have these properties (Mercer theorem):

Symmetry:

$$K(x_i, x_j) = K(x_j, x_i)$$

For every set x_1, \dots, x_M the Gram matrix is positive semi-definite:

$$K(x_i, x_j) \equiv K_{ij} \quad - \text{p.s.d.}$$

Summary

- ▶ SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary

Summary

- ▶ SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary
- ▶ For the inseparable case, it balances between:
 - minimizing $\|w\|^2$, i.e. pushing the $w^T x_i + w_0 = \pm 1$ lines further away from the decision boundary
 - maximizing the sum of margins for objects with $y_i(w^T x_i + w_0) < 1$ (through slack variables)
- ▶ The balance is controlled by the constant C

Summary

- ▶ SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary
- ▶ For the inseparable case, it balances between:
 - minimizing $\|w\|^2$, i.e. pushing the $w^T x_i + w_0 = \pm 1$ lines further away from the decision boundary
 - maximizing the sum of margins for objects with $y_i(w^T x_i + w_0) < 1$ (through slack variables)
- ▶ The balance is controlled by the constant C
- ▶ Solution only depends on the support vectors
 - Not robust to outliers as they always become support vectors

Summary

- ▶ SVM is a linear classification model. In the linearly separable case it maximizes the distance from the closest training points to the decision boundary
- ▶ For the inseparable case, it balances between:
 - minimizing $\|w\|^2$, i.e. pushing the $w^T x_i + w_0 = \pm 1$ lines further away from the decision boundary
 - maximizing the sum of margins for objects with $y_i(w^T x_i + w_0) < 1$ (through slack variables)
- ▶ The balance is controlled by the constant C
- ▶ Solution only depends on the support vectors
 - Not robust to outliers as they always become support vectors
- ▶ Kernel trick allows to expand features by just redefining the scalar product in the original feature space (i.e. almost no computational overhead)
 - This allows for infinite dimension representations
 - Can define kernels (similarity measures) for complex objects like strings, sets, graphs, etc.

Thank you!



amaevskij@hse.ru



SiLiKhon



hse_lambda

Artem Maevskiy