



## Introduction to Optimization Mock Quiz (1)

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### Problem 1.1:

- a) We need to calculate  $\nabla f(x)$  and show that it is 0 at  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$ . We write

$$\nabla f(x) = \begin{pmatrix} 2x_1 \\ 3x_2^2 \end{pmatrix}$$

which gives us  $\nabla f(0, 0) = \begin{pmatrix} 2 \cdot 0 \\ 3 \cdot 0^2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ .

- b) For  $f$  to be convex,  $H_f$  needs to be positive semi-definite everywhere. We can calculate the hessian:

$$H_f(x) = \begin{pmatrix} 2 & 0 \\ 0 & 6x_2 \end{pmatrix}$$

which has eigenvalues 2 and  $6x_2$  which is clearly not bounded by zero from below, therefore  $f$  is not convex. If  $f$  were to be convex, a local minimizer would also be a global minimizer, but that is not the case.

- c) For us to know that a point  $x$  is local minimizer  $\nabla f(x) = 0$  should hold and  $H_f(x)$  should be positive definite. We know that  $\nabla f(0, 0) = 0$  and we can easily calculate  $H_f(0)$  to be  $\begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$  which is positive semi-definite, not positive definite. This means that we have to show that there is no direction  $s$  and  $\varepsilon > 0$  such that  $f(0 + ts) < f(0) \forall t \in (0, \varepsilon)$ . By looking at  $f(x)$  it's easy to see that going in the direction  $\begin{pmatrix} 0 \\ -1 \end{pmatrix}$  will lead to a decrease in the value of the function. We can check to get

$$f\left(0 + \begin{pmatrix} 0 \\ -t \end{pmatrix}\right) = f(0, -t) = -3t^3 < 0 = f(0) \forall t \in (0, \varepsilon).$$

- d) For a function to be coercive  $f(x)$  should tend to infinity as  $\|x\|$  tends to infinity. We can show that that's not the case by picking  $x$  from the set  $\{(u, v) : u^2 = -v^3\}$ . This way, when  $\|x\| \rightarrow \infty$ ,  $f(x) = f(u, v) = u^2 + v^3 = 0$  stays 0, therefore  $f$  is not coercive.

### Problem 1.2:

a) •  $x^1 = x^0 + \frac{1}{2}(-\nabla f(x^0)) = \begin{pmatrix} 2 \\ 2 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

•  $x^2 = x^1 + \frac{1}{2}(-\nabla f(x^1)) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/2 \\ 0 \end{pmatrix}$

•  $x^3 = x^2 + \frac{1}{2}(-\nabla f(x^2)) = \begin{pmatrix} 1/2 \\ 0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1/2 \\ 0 \end{pmatrix} = \begin{pmatrix} 1/4 \\ 0 \end{pmatrix}$

- b) The global minimum of  $f$  is 0. The iterates seem to not have zig-zaged very much, however, it will take infinite iterations to converge to the solution.

### Problem 1.3:

- a) •  $\kappa(A) = \frac{4}{2} = 2$   
•  $\kappa(B) = \frac{40}{10} = 4$
- b) •  $A: \sqrt{2} \left( \frac{2-1}{2+1} \right) = \frac{\sqrt{2}}{3}$   
•  $B: \sqrt{4} \left( \frac{4-1}{4+1} \right) = \frac{6}{5}$
- c) Since both examples are diagonal matrices, using  $D_{i,i} = H_f(x^k)_{i,i}^{-1}$  would give  $D^{\frac{1}{2}}AD^{\frac{1}{2}} = I$  and also  $D^{\frac{1}{2}}BD^{\frac{1}{2}} = I$  so

$$\sqrt{\kappa(I)} \left( \frac{\kappa(I) - 1}{\kappa(I) + 1} \right) = \sqrt{1} \left( \frac{1 - 1}{1 + 1} \right) = 0.$$

meaning it would converge in one iteration.