



## Introduction to Optimization Homework (week 4)

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### Problem IV.1: Minimization and the Armijo Step Size Rule

Let  $f(x) = \frac{1}{2}x^T Cx + c^T x$  with a symmetric and positive definite matrix  $C \in \mathbb{R}^{n \times n}$  and  $c \in \mathbb{R}^n$ . Moreover, let  $s \in \mathbb{R}^n$  be a descent direction of  $f$  at a point  $x \in \mathbb{R}^n$  and  $\sigma^* \geq 0$  be the exact line search step size, i.e.  $f(x + \sigma^*) = \min_{\sigma \geq 0} f(x + \sigma s)$ .

- a) Show that  $f$  is strictly convex.
- b) Show that  $\sigma^* > 0$  holds.
- c) What form (linear, quadratic, ...) does the function  $\phi(\sigma) = f(x + \sigma s)$  have? Use Taylor expansion of  $\phi$  about  $\sigma = 0$  and deduct that  $\sigma^*$  is well defined and uniquely determined.
- d) Show that for all  $\gamma \in (0, \frac{1}{2}]$  the choice  $\sigma = \sigma^*$  satisfies the sufficient decrease condition

$$f(x + \sigma s) - f(x) \leq \gamma \sigma \nabla f(x)^T s,$$

though, that this is not the case for  $\gamma > \frac{1}{2}$ .

- e) Sketch the graph of  $\phi$  and use it to illustrate the statement discussed in d)

### Solution

- a) The hessian of  $f$  is  $H_f(x) = C$  which is given to be symmetric positive definite implying that the function  $f$  is strictly convex.
- b) Since  $s$  is a descent direction of  $f$  we know that  $\nabla f(x)^T s < 0$ . By continuity of  $f$ , we know that there exists  $\varepsilon > 0$  such that  $f(x + \varepsilon s) < f(x)$  therefore the exact line search would have found that  $\varepsilon$ , i.e  $\sigma^* \geq \varepsilon > 0$ .
- c) The taylor expansion follows

$$\begin{aligned} \phi(\sigma) &= f(x) + \sigma \nabla f(x)^T s + \frac{1}{2} \sigma^2 s^T H_f(x) s \\ &= f(x) + \sigma (x^T C + c^T)^T s + \frac{1}{2} \sigma^2 s^T C s \end{aligned}$$

which is a quadratic equation in terms of  $\sigma$ . We have to show that

$$\frac{\overbrace{-\nabla f(x)^T s}^{>0 \text{ (descent direction)}}}{\underbrace{s^T H_f(x) s}_{>0 \text{ (positive definite)}}} > 0.$$

- d) We first express

$$\phi'(\sigma) = \sigma s^T C s + \nabla f(x)^T s$$

and now we can rewrite the condition to be

$$\phi(\sigma) - \phi(0) \leq \gamma \sigma \phi'(0) \implies \frac{\phi(\sigma) - \phi(0)}{\sigma} \leq \gamma \phi'(0)$$

Let  $g(\sigma) = \phi(\sigma^* - \sigma)$  allowing us to write

$$\frac{g(0) - g(\sigma^*)}{\sigma^*} \leq \gamma \phi'(0) \implies \frac{g(\sigma^*) - g(0)}{\sigma^*} \geq \gamma g'(\sigma^*)$$

Now let  $g(\sigma) = a\sigma^2 + c$  (with  $g'(\sigma) = 2a\sigma$ ) since we know that  $g(x)$  is a quadratic function and the minimum is at  $\sigma = 0$  the coefficient of the linear term will be 0. So

$$a\sigma^* = \frac{a(\sigma^*)^2 + c - c}{\sigma^*} = \frac{g(\sigma^*) - g(0)}{\sigma^*} \geq \gamma g'(\sigma^*) = \gamma(2a\sigma^*)$$

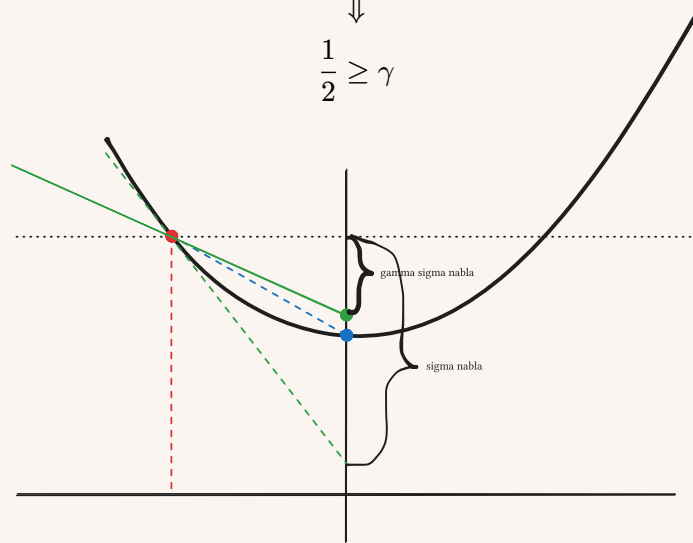
$\Downarrow$

$$a\sigma^* \geq 2\gamma a\sigma^*$$

$\Downarrow$

$$\frac{1}{2} \geq \gamma$$

e)



■

## Problem IV.2: Application of the Wolfe-Powell Rule

- a) The first Wolfe-Powell condition (sufficient decrease condition) requires

$$f(x^k + \sigma_k s^k) - f(x^k) \leq \gamma \sigma_k \nabla f(x^k)^T s^k.$$

What is the maximum step length  $\sigma_k$  that satisfies the condition, given that  $f(x) = 5 + x_1^2 + x_2^2$ ,  $x^k = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$ ,  $s^k = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ , and  $\gamma = 10^{-4}$ .

- b) Given a general descent algorithm with the Wolfe-Powell step size rule, provide an example to show that the set

$$\left\{ t \in \mathbb{R} : \begin{array}{l} \nabla f(x + \sigma s)^T s \geq \eta \nabla f(x)^T s \text{ and} \\ f(x + \sigma s) - f(x) \leq \gamma \sigma \nabla f(x)^T s \end{array} \right\}$$

may be empty if  $0 < \gamma < \eta < 1$ . I.e., that under these conditions no step size can be found.

Hint: Think of a one-dimensional example.

## Solution

a)

$$f(x^k + \sigma_k s^k) - f(x^k) \leq \gamma \sigma_k \nabla f(x^k)^T s^k$$

$\Downarrow$

$$f\left(\begin{pmatrix} -1 \\ -1 \end{pmatrix} + \sigma_k \begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) - f\left(\begin{pmatrix} -1 \\ -1 \end{pmatrix}\right) \leq 10^{-4} \sigma_k \nabla f\left(\begin{pmatrix} -1 \\ -1 \end{pmatrix}\right)^T \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{aligned}
& \Downarrow \\
& f(\sigma_k - 1, -1) - f(-1, -1) \leq \sigma_k 10^{-4} \cdot \nabla f(-1, -1)^T \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\
& \Downarrow \\
& \cancel{\sigma_k} + \sigma_k^2 - 2\sigma_k + \cancel{1} - \cancel{1} - \cancel{\sigma_k} - \cancel{1} - \cancel{1} \leq \sigma_k (-2 \cdot 10^{-4}) \\
& \Downarrow \\
& \sigma_k (2 - 2 \cdot 10^{-4}) - \sigma_k^2 \geq 0 \\
& \Downarrow \\
& \sigma_k ((2 - 2 \cdot 10^{-4}) - \sigma_k) \geq 0 \\
& \Downarrow \\
& (2 - 2 \cdot 10^{-4}) \geq \sigma_k \geq 0
\end{aligned}$$

b) Consider the example  $f(x) = x$ , then  $\nabla f(x)^T s = -1$ . Take  $x = 1, s = -1$ . We these into the conditions to get

$$\begin{cases} 1 \cdot (-1) \geq \eta \cdot (-1) \\ 1 - \sigma - 1 \leq -\gamma \sigma \end{cases} \Rightarrow \begin{cases} 1 \leq \eta \\ 1 \geq \gamma \end{cases}$$

and since  $\eta < 1$  this is a counter example. ■

### Problem IV.3:

Let  $f(x) = \frac{1}{2}x^T Cx + c^T x + \gamma$  with a symmetric positive definite matrix  $C \in \mathbb{R}^{n \times n}$ ,  $c \in \mathbb{R}^n$ , and  $\gamma \in \mathbb{R}$ . Show that Gradient Descent Method with exact line search step size reaches the global minimum  $\bar{x} = -C^{-1}c$  in exactly one step if the initial point  $x^0$  is chosen such that  $\nabla f(x^0)$  is an eigenvector of  $C$ . What does this imply for a strategy to choose the initial point in a diagonally scaled Gradient Descent Method?

### Solution

We find

$$\nabla f(x) = Cx + c$$

and from past exercises we know that

$$\sigma^* = \frac{\|\nabla f(x^0)\|^2}{\nabla f(x^0)^T C \nabla f(x^0)} = \frac{1}{\lambda}$$

now we can write

$$\begin{aligned}
x^1 &= x^0 - \frac{1}{\lambda} \nabla f(x) \\
&= x^0 - \frac{1}{\lambda} C^{-1} C \nabla f(x) \\
&= x^0 - C^{-1} \nabla f(x) \\
&= x^0 - C^{-1} (Cx^0 + c) \\
&= x^0 - x^0 - C^{-1} c \\
&= C^{-1} c.
\end{aligned}$$

This result means that when using diagonal scaling it's probably best to chose initial points which are the eigenvectors of the scaling matrix. ■