



# Introduction to Optimization Homework (2)

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## Homework Assignment Not graded

### Problem 2.1:

(a) First calculate the gradient

$$f(x_1, x_2) = (4x_1^2 - x_2)^2 = 16x_1^4 - 8x_1^2x_2 + x_2^2 \Rightarrow \nabla f(x_1, x_2) = \langle 64x_1^3 - 16x_1x_2, -8x_1^2 + 2x_2 \rangle.$$

At stationary points,  $\nabla f(x) = 0$

$$\nabla f(x_1, x_2) = \langle 64x_1^3 - 16x_1x_2, -8x_1^2 + 2x_2 \rangle = 0 \Rightarrow \begin{cases} 64x_1^3 - 16x_1x_2 = 0 \\ -8x_1^2 + 2x_2 = 0 \end{cases} \Rightarrow 4x_1^2 = x_2.$$

At such points,  $f(u, 4u^2) = 0$  This means that all points  $\{(u, 4u^2) : u \in \mathbb{R}\}$  are stationary points.

$$H_{f(x_1, x_2)} = \begin{pmatrix} 192x_1^2 - 16x_2 & -16x_1 \\ -16x_1 & 2 \end{pmatrix} \Rightarrow H_{f(u, 4u^2)} = 2 \begin{pmatrix} 64u^2 & -8u \\ -8u & 1 \end{pmatrix}, \det(H_{f(u, 4u^2)}) = 0$$

so second derivative test is not suitable for this example. If we let  $d \in \mathbb{R}^2$  be an arbitrary non-zero vector we can write

$$\begin{aligned} f(x+d) &= (4(x_1+d_1)^2 - (x_2+d_2))^2 \\ &= (4x_1^2 - x_2 + 8x_1d_1 + 4d_1^2 - d_2)^2 \\ &= (4x_1^2 - x_2)^2 + 2(4x_1^2 - x_2)(8x_1d_1 + 4d_1^2 - 2x_2d_2 - d_2^2) + (8x_1d_1 + 4d_1^2 - 2x_2d_2 - d_2^2)^2 \end{aligned}$$

and in the case where  $4x_1^2 = x_2$  we get that

$$\begin{aligned} f(x+d) &= (4x_1^2 - x_2)^2 + 2(4x_1^2 - x_2)(8x_1d_1 + 4d_1^2 - 2x_2d_2 - d_2^2) + (8x_1d_1 + 4d_1^2 - 2x_2d_2 - d_2^2)^2 \\ &= 0 + 0 + (8x_1d_1 + 4d_1^2 - 2x_2d_2 - d_2^2)^2 \\ &\geq 0. \end{aligned}$$

Therefore the minimum of  $f$  is 0 and is attained at points  $\{(u, 4u^2) : u \in \mathbb{R}\}$ .

### Problem 2.2:

*Proof:* Let  $S = \{x \in \mathbb{R}^n : f(x) \leq f(y)\}$  be a sub-level set for some  $y$  and  $a, b \in S$  such that  $f(a) = f(b)$ . Since  $f$  is convex, i.e.  $(1-\lambda)f(a) + \lambda f(b) \geq f((1-\lambda)a + \lambda b)$  if some  $c$  is on the line between  $a$  and  $b$ ,  $f(c) \leq f(a) = f(b)$  meaning that if  $S$  contains  $a$  and  $b$  it will also contain  $c$ .  $\square$

### Problem 2.3:

(a) *Proof:*

$$\begin{aligned} f(g((1-\lambda)a + \lambda b)) &\leq f((1-\lambda)g(a) + \lambda g(b)) \quad (\text{by convexity and monotonousity}) \\ &\leq (1-\lambda)f(g(a)) + \lambda f(g(b)) \end{aligned}$$

$\square$

(b) *Proof:* Let  $f(x) = e^{-x}$ ,  $g(x) = x^2$ ,  $f(g(x)) = e^{-x^2}$ . At points  $-1$  and  $1$  value of the function is  $f(g(-1)) = f(g(1)) = e^{-1}$  which is evidently less than the value at  $0$  which is  $f(g(0)) = e^0$  thereby contradicting the convexity.  $\square$

### Problem 2.4:

Let  $\bar{x}$  and  $\bar{y}$  be the optimizers of the problem and  $\lambda \in (0, 1)$ . Then, by convexity of  $f(x)$ , we know that any point  $c = (1 - \lambda)x + \lambda y$  gives us

$$f(c) \leq (1 - \lambda)f(x) + \lambda f(y) = f(x) = f(y)$$

and since  $f(x) \leq f(a) \forall a \in K$  we get that  $f(c) = f(x) = f(y) \implies c \in \{x \in K : f(x) \leq f(y) \forall y \in K\}$ .

## Graded Homework Assignment

### Problem 2.1:

$$f(x_1, x_2) = x_1^2 - 5x_1x_2^2 + 5x_2^4$$

(a) To determine all stationary points of  $f$ , first we find

$$\nabla f(x_1, x_2) = \langle 2x_1 - 5x_2^2, -10x_1x_2 + 20x_2^3 \rangle$$

then we find such  $(x_1, x_2)$  that  $\nabla f(x_1, x_2) = 0$

$$\begin{cases} 2x_1 - 5x_2^2 = 0 \\ -10x_1x_2 + 20x_2^3 = 0 \end{cases} \implies \begin{cases} 2x_1 - 5x_2^2 = 0 \\ -x_1 + 2x_2^2 = 0 \end{cases} \implies \begin{cases} x_1 = 0 \\ x_2 = 0 \end{cases}$$

(b) •  $f(x_1, 0) = x_1^2$ .  $\bar{x}_1 = 0$  is a global minimizer since  $0^2 \leq x_1^2$  for all  $x_1$ .

•  $f(0, x_2) = 5x_2^4$ .  $\bar{x}_2 = 0$  is a global minimizer since  $5 \cdot 0^4 \leq 5 \cdot x_2^4$  for all  $x_2$ .

(c) We know that  $\bar{x} = 0$  is a stationary point. We need to find the Hessian of  $f$

$$H_{f(x_1, x_2)} = \begin{pmatrix} 2 & -10x_2 \\ -10x_2 & -10x_1 + 50x_2^2 \end{pmatrix}$$

Now we just plug in  $\bar{x} = 0$  and obtain

$$H_{f(0,0)} = \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$$

then we find the eigenvalues

$$\det(H_f - \lambda I) = \lambda(2 - \lambda) = 0 \implies \lambda = 0, 2.$$

This means that  $H_{f(0,0)}$  is positive semi-definite and that doesn't tell us anything about the class of the stationary point.

Consider the curves

$$\bullet A = \{(2u^2, u) : u \in \mathbb{R}\}$$

$$f(2u^2, u) = 4u^4 - 10u^4 + 5u^4 = -u^4$$

$$\bullet B = \{(u, 0) : u \in \mathbb{R}\}$$

$$f(B) = \{u^2 - 5u \cdot 0 + 5 \cdot 0^4 : u \in \mathbb{R}\} = \{u^2 : u \in \mathbb{R}\}$$

It's clear that  $\bar{x}$  has values both greater and lower than  $f(\bar{x}) = 0$ . This means that the point  $\bar{x}$  is a saddle point. Figure 1 also illustrates that quite well.

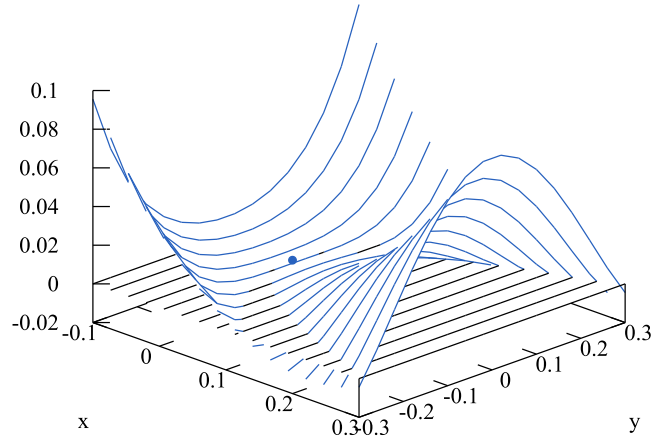


Figure 1: plot of  $f$  near  $(0, 0)$

### Problem 2.2:

- $f$  is bounded below  $\iff b \in \{Ay : y \in \mathbb{R}^n\}$

*Proof:* let  $b = Ay$

$$\begin{aligned}
 f(x) &= x^T A x + 2b^T x + c \\
 &= x^T A x + 2y^T A x + c \\
 &= \langle A^{\frac{1}{2}}(x+y), A^{\frac{1}{2}}(x+y) \rangle - y^T A y + c \\
 &= \underbrace{(x+y)^T A (x+y)}_{\geq 0 \text{ (PTSD)}} - \underbrace{y^T A y + c}_{\text{constant}} \\
 &\geq -y^T A y + c
 \end{aligned}$$

□

- $f$  is bounded below  $\implies b \in \{Ay : y \in \mathbb{R}^n\}$

*Proof:* Since  $A$  is positive semi-definite and not positive definite, assume  $\det(A) = 0$  and  $\ker(A) \neq \{0\}$ . If we let  $x \in \ker(A)$  we get

$$\begin{aligned}
 f(x) &= x^T A x + 2b^T x + c \\
 &= 0 + 2b^T x + c.
 \end{aligned}$$

From here we observe that if  $b$  were to be of the form  $Ay$  we would have

$$\begin{aligned}
 f(x) &= 2b^T x + c \\
 &= 2y^T \underbrace{A x}_{=0} + c \\
 &= c
 \end{aligned}$$

but otherwise,  $f(x)$  would be a linear function in respect to  $x$  which is not bounded from below. □

### Problem 2.3:

1. Let  $a = (1, 0)$  and  $b = (-1, 0)$ ,  $\|a\|^2 = \|b\|^2 = 1$  therefore  $a, b \in A$ . The midpoint is  $c = (0, 0)$  has  $\|c\|^2 = 0 \neq 1 \implies c \notin A$ .  $A$  is not convex.
2. *Proof:* Let  $a, b \in \mathbb{R}^n$  and  $a_{\max}, b_{\max} \leq 1 \iff a, b \in B$ . Now take the midpoint  $c$  of  $a$  and  $b$ ,

$$c = \left( \frac{a_1 + b_1}{2}, \frac{a_2 + b_2}{2}, \dots, \frac{a_n + b_n}{2} \right).$$

We can safely assume that  $a_i = a_{\max} \forall i$  and  $b_i = b_{\max} \forall i$  giving us

$$c = \left( \frac{a_{\max} + b_{\max}}{2}, \frac{a_{\max} + b_{\max}}{2}, \dots, \frac{a_{\max} + b_{\max}}{2} \right)$$

from which it's clear that  $c_{\max} = (a_{\max} + b_{\max})/2$ . We now prove that  $\frac{a_{\max} + b_{\max}}{2} \leq \max\{a_{\max}, b_{\max}\}$ . Assume  $a_{\max} \geq b_{\max}$ , we get

$$\begin{aligned} \frac{a_{\max} + b_{\max}}{2} &\leq a_{\max} \\ a_{\max} + b_{\max} &\leq 2a_{\max} \\ b_{\max} &\leq a_{\max} \end{aligned}$$

□

3. Let  $a = (10, 0)$  and  $b = (0, 10)$ ,  $\min a = \min b = 0 \leq 1$  therefore  $a, b \in C$ . The midpoint is  $c = (5, 5)$  has  $\min c = 5 \not\leq 1 \Rightarrow c \notin C$ .  $C$  is not convex.

## Problem 2.4:

*Proof:*

- $f$  is convex  $\Rightarrow g_{x,d}$  is convex.

$$\begin{aligned} g_{x,d}((1-\lambda)a + \lambda b) &= f(x + ((1-\lambda)a + \lambda b)d) \\ &= f((1-\lambda)(x + ad) + \lambda(x + bd)) \\ &\leq (1-\lambda)f(x + ad) + \lambda f(x + bd) \\ &= (1-\lambda)g_{x,d}(a) + \lambda g_{x,d}(b) \end{aligned}$$

- $f$  is convex  $\Leftarrow g_{x,d}$  is convex.

$$\begin{aligned} f((1-\lambda)a + \lambda b) &= g_{a,b-a}((1-\lambda) \cdot 0 + \lambda \cdot 1) \\ &\leq (1-\lambda)g_{a,b-a}(0) + \lambda g_{a,b-a}(1) \\ &= (1-\lambda)f(a) + \lambda f(b) \end{aligned}$$

□