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1
2 from micropython import const
3 import framebuf
4 import time
5
6 # Register definitions
7 SET_CONTRAST = const(0x81)
8 SET_ENTIRE_ON = const(0xA4)
9 SET_NORM_INV = const(0xA6)
10 SET_DISP = const(0xAE)
11 SET_MEM_ADDR = const(0x20)
12 SET_COL_ADDR = const(0x21)
13 SET_PAGE_ADDR = const(0x22)
14 SET_DISP_START_LINE = const(0x40)
15 SET_SEG_REMAP = const(0xA0)
16 SET_MUX_RATIO = const(0xA8)
17 SET_IREF_SELECT = const(0xAD)
18 SET_COM_OUT_DIR = const(0xC0)
19 SET_DISP_OFFSET = const(0xD3)
20 SET_COM_PIN_CFG = const(0xDA)
21 SET_DISP_CLK_DIV = const(0xD5)
22 SET_PRECHARGE = const(0xD9)
23 SET_VCOM_DESEL = const(0xDB)
24 SET_CHARGE_PUMP = const(0x8D)
25
26 class SSD1306_DualSPI(framebuf.FrameBuffer):
27     def __init__(self, width, height, spi, dc, res, cs1, cs2, external_vcc=False):
28         self.width = width
29         self.height = height
30         self.external_vcc = external_vcc
31         self.pages = self.height // 8
32         self.buffer = bytearray(self.pages * self.width)
33         super().__init__(self.buffer, self.width, self.height, framebuf.MONO_VLSB)
34
35         self.spi = spi
36         self.dc = dc
37         self.res = res
38         self.cs1 = cs1
39         self.cs2 = cs2
40         self.rate = 10 * 1024 * 1024
41
42         for pin in (dc, res, cs1, cs2):
43             pin.init(pin.OUT, value=0)
44
45         self.reset()
46         self.init_display()
47
48     def reset(self):
49         self.res(1)
50         time.sleep_ms(1)
51         self.res(0)
52         time.sleep_ms(10)
53         self.res(1)
54
55     def write_cmd(self, cmd, cs):
56         self.spi.init(baudrate=self.rate, polarity=0, phase=0)
57         cs(1)
58         self.dc(0)
59         cs(0)
60         self.spi.write(bytearray([cmd]))
61         cs(1)
62
63     def write_data(self, buf, cs):
64         self.spi.init(baudrate=self.rate, polarity=0, phase=0)

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65         cs(1)
66         self.dc(1)
67         cs(0)
68         self.spi.write(buf)
69         cs(1)
70
71     def init_display(self):
72         for cs in (self.cs1, self.cs2):
73             for cmd in (
74                 SET_DISP,
75                 SET_MEM_ADDR, 0x00,
76                 SET_DISP_START_LINE,
77                 SET_SEG_REMAP | 0x01,
78                 SET_MUX_RATIO, self.height - 1,
79                 SET_COM_OUT_DIR | 0x08,
80                 SET_DISP_OFFSET, 0x00,
81                 SET_COM_PIN_CFG, 0x02 if self.width > 2 * self.height else 0x12,
82                 SET_DISP_CLK_DIV, 0x80,
83                 SET_PRECHARGE, 0x22 if self.external_vcc else 0xF1,
84                 SET_VCOM_DESEL, 0x30,
85                 SET_CONTRAST, 0xFF,
86                 SET_ENTIRE_ON,
87                 SET_NORM_INV,
88                 SET_IREF_SELECT, 0x30,
89                 SET_CHARGE_PUMP, 0x10 if self.external_vcc else 0x14,
90                 SET_DISP | 0x01,
91             ):
92                 self.write_cmd(cmd, cs)
93         self.fill(0)
94         self.show()
95
96     def show(self):
97         for page in range(0, self.pages):
98             left_start = page * 256
99             right_start = left_start + 128
100
101             self.write_cmd(0xB0 | page, self.cs1)
102             self.write_cmd(0x00, self.cs1)
103             self.write_cmd(0x10, self.cs1)
104             self.write_data(self.buffer[left_start:left_start + 128], self.cs1)
105
106             self.write_cmd(0xB0 | page, self.cs2)
107             self.write_cmd(0x00, self.cs2)
108             self.write_cmd(0x10, self.cs2)
109             self.write_data(self.buffer[right_start:right_start + 128], self.cs2)
110
111     def poweroff(self):
112         for cs in (self.cs1, self.cs2):
113             self.write_cmd(SET_DISP, cs)
114
115     def poweron(self):
116         for cs in (self.cs1, self.cs2):
117             self.write_cmd(SET_DISP | 0x01, cs)
118
119     def contrast(self, contrast):
120         for cs in (self.cs1, self.cs2):
121             self.write_cmd(SET_CONTRAST, cs)
122             self.write_cmd(contrast, cs)
123
124     def invert(self, invert):
125         for cs in (self.cs1, self.cs2):
126             self.write_cmd(SET_NORM_INV | (invert & 1), cs)
127
128     def rotate(self, rotate):
129         for cs in (self.cs1, self.cs2):

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130 | self.write_cmd(SET_COM_OUT_DIR | ((rotate & 1) << 3), cs)  
131 | self.write_cmd(SET_SEG_REMAP | (rotate & 1), cs)  
132 |
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