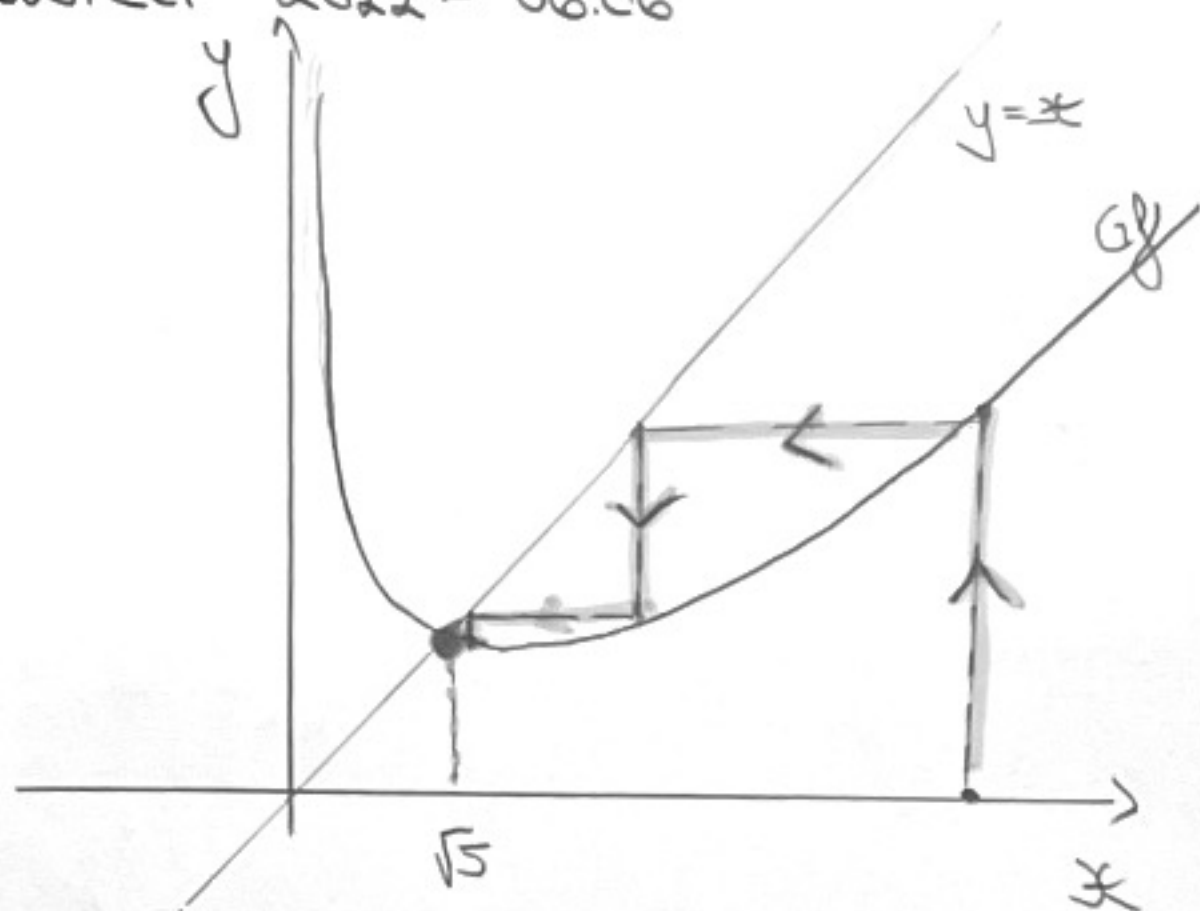
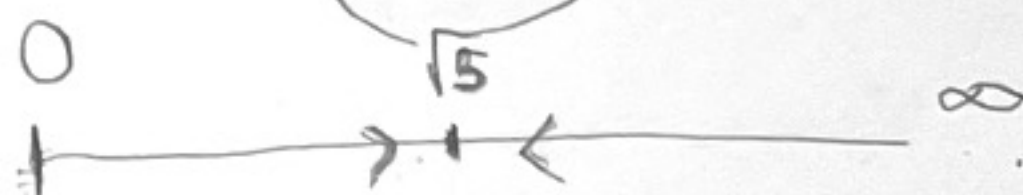


1.c



$$A_{\sqrt{5}} = (0, \infty)$$



1.a $f(m^*) = m^*$

$$\frac{m^{*2} + 5}{2m^*} = m^* \Rightarrow m^{*2} + 5 = 2m^{*2} \Rightarrow m^{*2} = 5 \Rightarrow m^* = \pm\sqrt{5}$$

but $m^* \in (0, \infty)$ $\Rightarrow m^* = \sqrt{5}$ the unique fixed point

1.b. $f'(x) = \frac{x^2 - 5}{2x}$

$$f'(\sqrt{5}) = \left| \frac{(\sqrt{5})^2 - 5}{2 \cdot (\sqrt{5})^2} \right| = 0 < 1 \Rightarrow m^* \text{ is an attractor}$$

2. $\begin{cases} \dot{x} = -y(x^2 + y^2) \\ \dot{y} = x(x^2 + y^2) \end{cases}$

a) $f(x, y) = \begin{pmatrix} -y(x^2 + y^2) \\ x(x^2 + y^2) \end{pmatrix}$

Equilibria $\Leftrightarrow f(x, y) = 0 \Leftrightarrow \begin{cases} -y(x^2 + y^2) = 0 \\ x(x^2 + y^2) = 0 \end{cases} \Rightarrow x = y = 0 \Rightarrow$

\Rightarrow the only equil point is $(0, 0)$

b) $Jf(x) = \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix} = \begin{pmatrix} (-y x^2 - y^3)'_x & (-y x^2 - y^3)'_y \\ (x^3 + x y^2)'_x & (x^3 + x y^2)'_y \end{pmatrix}$

$$= \begin{pmatrix} -y \cdot 2x & -x^2 - 3y^2 \\ 3x^2 + y^2 & 2xy \end{pmatrix}$$

c) $f(f(m^*)) = f(f(0, 0)) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\det(J(f(0,0)) - \lambda J_2) = \begin{vmatrix} -\lambda & 0 \\ 0 & -\lambda \end{vmatrix} = \lambda^2$$

$\Rightarrow \lambda^2 = 0 \Rightarrow \lambda_1 = \lambda_2 = 0 \Rightarrow \operatorname{Re}(\lambda_1) = \operatorname{Re}(\lambda_2) = 0 \Rightarrow (0,0)$ the point is not hyperbolic

$$\begin{aligned} 2c) \frac{\dot{\theta}}{\cos^2 \theta} &= \frac{\dot{y} \cdot x - y \dot{x}}{x^2} = \frac{x^2(x^2+y^2) + y^2(x^2+y^2)}{x^2} = \frac{(x^2+y^2)(x^2+y^2)}{x^2} = \\ &= \frac{(x^2+y^2)^2}{x^2} = \frac{\rho^4}{\rho^2 \cos^2 \theta} \end{aligned}$$

Obs: $x^2 + y^2 = \rho^2$
 $x^2 = \rho^2 \cos^2 \theta$

$$\Rightarrow \dot{\theta} = \rho^2 / dt \Rightarrow \theta(t) = \rho^2 \cdot t$$

• $\varphi(t, 1, 0)$ $\rho = \sqrt{1^2 + 0^2} = 1$
 $x=1$ $\theta(t) = \rho^2 \cdot t = t \Rightarrow x = \rho \cos \theta = \cos t$
 $y=0$ $y = \rho \sin \theta = \sin t$

• $\varphi(t, 2, 0)$ $\rho = \sqrt{2^2 + 0^2} = \sqrt{4} = 2$
 $x=2$ $\theta(t) = \rho^2 \cdot t = 4t \Rightarrow x = \rho \cos \theta = 2 \cos 4t$
 $y=0$ $y = \rho \sin \theta = 2 \sin 4t$

• $\varphi(t, 3, 0)$ $\rho = \sqrt{3^2 + 0^2} = 3$
 $x=3$ $\theta(t) = \rho^2 \cdot t = 9t \Rightarrow x = 3 \cos 9t$
 $y=0$ $y = 3 \sin 9t$

$$d) \begin{cases} x' = -y(x^2+y^2) \\ y' = x(x^2+y^2) \end{cases} \Rightarrow \begin{cases} \frac{dx}{dt} = -y(x^2+y^2) \\ \frac{dy}{dt} = x(x^2+y^2) \end{cases}$$

$$\frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{x(x^2+y^2)}{-y(x^2+y^2)} \Rightarrow \frac{dy}{dx} = \frac{x}{-y} \Rightarrow -y dy = x dx / \rho \Rightarrow -\int y dy = \int x dx \Rightarrow$$

$$\Rightarrow -\frac{y^2}{2} = \frac{x^2}{2} + C / \cdot 2 \Rightarrow -y^2 = x^2 + C \Rightarrow C = -x^2 - y^2 = H(x, y) \text{ first integral}$$

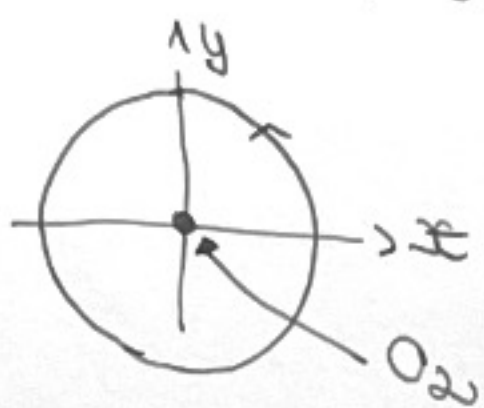
$$\frac{\partial H}{\partial x} f_1 + \frac{\partial H}{\partial y} f_2 = 0 = (-x^2 - y^2)' \cdot (-y(x^2+y^2)) + (-x^2 - y^2)' \cdot x(x^2+y^2) =$$

$$\Rightarrow +2xy(x^2+y^2) - 2yx(x^2+y^2) = 0 \quad \text{TRUE}$$

$$e) \quad f\dot{f} = x \cdot \dot{x} + y\dot{y} = x(-y(x^2+y^2)) + y(x(x^2+y^2)) = \\ = -xy(x^2+y^2) + xy(x^2+y^2) = 0$$

$\Rightarrow \dot{f} = 0 \Rightarrow f$ is constant along the orbit \Rightarrow the orbit is a circle centered in O_2

$\Rightarrow \dot{\theta} = f^2 \Rightarrow > 0 \Rightarrow \theta' > 0 \Rightarrow$ counter clockwise rotation



XAM 6 JUNIE 2022

Teorema de existență și unicitate

$$a^2 + b^2 + c = 0$$

$$1) \begin{cases} x' = ax - 5y \\ y' = x - 2y \end{cases} \Rightarrow A = \begin{pmatrix} a & -5 \\ 1 & -2 \end{pmatrix}$$

$$\text{CENTRE} \Rightarrow \lambda_1, \lambda_2 = \pm i\beta$$

$$\begin{cases} \Delta < 0 \\ b = 0 \end{cases}$$

$$\det(A - \lambda I) = \begin{vmatrix} a - \lambda & -5 \\ 1 & -2 - \lambda \end{vmatrix} = (a - \lambda)(-2 - \lambda) + 5$$

$$= -2a - a\lambda + 2\lambda + \lambda^2 + 5$$

$$= \lambda^2 + \lambda(2 - a) - 2a + 5$$

$$\lambda^2 + \lambda(2 - a) - 2a + 5$$

$$\Rightarrow 2 - a = 0 \Rightarrow a = 2$$

$$\text{vg: } \begin{cases} \lambda^2 - 4 + 5 = 0 \\ \lambda^2 + 1 = 0 \end{cases}$$

$$\Delta = -4 = (2i)^2$$

$$\lambda_1 = \frac{2i}{2} = i$$

$$\lambda_2 = -\frac{2i}{2} = -i$$

$$b) a = 0$$

$$\begin{cases} x' = -5y \\ y' = x - 2y \end{cases} \Rightarrow y = \frac{x'}{-5}$$

$$x'' = -5y' = -5(x - 2y) = -5x + 10y = -5x + \frac{2}{-5}x' = -5x - 2x'$$

$$x'' + 2x' + 5x = 0$$

$$\lambda^2 - 2\lambda + 5 = 0$$

$$\Delta = 4 - 4 \cdot 5$$

$$= -16 = (4i)^2$$

FOCUS, GLOBAL ATTRACTOR

$$\lambda_1 = \frac{-2 + 4i}{2} = -1 + 2i$$

$$\lambda_2 = \frac{-2 - 4i}{2} = -1 - 2i$$

$$\omega = -1$$

$$\beta = 2$$

$$x(t) = c_1 e^{-t} \cos 2t + c_2 e^{-t} \sin 2t$$

$$x'(t) = c_1 (e^{-t} \cos 2t - 2e^{-t} \sin 2t) + c_2 (e^{-t} \sin 2t + 2e^{-t} \cos 2t)$$

the general solution

$$\Rightarrow \begin{cases} x(t) = c_1 e^{-t} \cos 2t + c_2 e^{-t} \sin 2t \\ y(t) = \frac{c_1}{-5} (e^{-t} \cos 2t - 2e^{-t} \sin 2t) - \frac{c_2}{5} (e^{-t} \sin 2t + 2e^{-t} \cos 2t) \end{cases}$$