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**Proposition 3.1.** Every line in  $\mathbb{E}^2$  can be described with a linear equation in two variables

$$ax + by + c = 0 \quad (3.4)$$

relative to a fixed coordinate system and any linear equation in two variables describes a line relative to a fixed coordinate system.

- We showed that a line satisfies a linear eq. (see for example symmetric eq.)
- Consider the set  $S$  of points  $P(x, y)$  such that  $ax + by + c = 0$   
for some  $a, b, c \in \mathbb{R}$   
with  $a, b$  not both 0
- $a, b$  not both zero  $\Rightarrow$  without loss of generality we may assume  $a \neq 0$

$$\text{then } \begin{cases} x = -\frac{b}{a}y - \frac{c}{a} \\ y = y \end{cases} \text{ so } S = \left\{ P(x, y) \in \mathbb{E}^2 : \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -\frac{b}{a} \\ 0 \end{bmatrix} + y \begin{bmatrix} -\frac{b}{a} \\ 1 \end{bmatrix} \right\} \text{ for any } y \in \mathbb{R}$$

$$\text{the point } A = \begin{bmatrix} -\frac{b}{a} \\ 0 \end{bmatrix} \in S$$

$$\Rightarrow S = \left\{ P(x, y) \in \mathbb{E}^2 : \begin{bmatrix} x - \frac{c}{a} \\ y \end{bmatrix} = t \begin{bmatrix} -\frac{b}{a} \\ 1 \end{bmatrix} \quad \forall t \in \mathbb{R} \right\}$$

$\stackrel{\text{AP}}{\parallel}$

$$\text{denote } \begin{bmatrix} -\frac{b}{a} \\ 1 \end{bmatrix} \text{ by } v,$$

$$\Rightarrow S = \left\{ P(x, y) \in \mathbb{E}^2 : \overrightarrow{AP} = t v \right\}$$

$$\Rightarrow \phi_A(S) \text{ is the 1-dimensional vector subspace of } V^2 \text{ generated by } v$$

$$\Rightarrow S \text{ is a line}$$

**Proposition 3.2.** Suppose you have a line  $\ell : ax + by + c = 0$  and a point  $P(x_P, y_P)$  in  $\mathbb{E}^2$ . The distance from  $P$  to  $\ell$  is

$$d(P, \ell) = \frac{|ax_P + by_P + c|}{\sqrt{a^2 + b^2}}.$$

• Identify  $\mathbb{E}^2$  with the  $Oxy$ -plane of  $\mathbb{E}^3$  relative to a right oriented orthonormal coordinate system of  $\mathbb{E}^3$

• Let  $A(x_A, y_A)$  and  $B(x_B, y_B)$  be two points in  $\ell$

• For any point  $Q(x_Q, y_Q) \in \mathbb{E}^2 = Oxy$  we have

$Q \in \ell \Leftrightarrow A, B, Q$  collinear

$$\Leftrightarrow \begin{vmatrix} x_Q & y_Q & 1 \\ x_A & y_A & 1 \\ x_B & y_B & 1 \end{vmatrix} = 0 \quad (\text{see chapter 2})$$

$$\Leftrightarrow \underbrace{x_Q(y_A - y_B)}_{a'} + \underbrace{y_Q(-x_A + x_B)}_{b'} + \underbrace{(x_A y_B - y_A x_B)}_{c'} = 0 \quad \text{a linear eq. in } x_Q \text{ and } y_Q$$

So  $\ell : a'x + b'y + c' = 0$

$$\left\{ \Rightarrow \frac{a}{a'} = \frac{b}{b'} = \frac{c}{c'} = \lambda \right.$$

but we also have  $\ell : ax + by + c = 0$

$$\text{then } \frac{|ax_P + by_P + c|}{\sqrt{a^2 + b^2}} = \frac{|\lambda a'x_P + \lambda b'y_P + \lambda c'|}{\sqrt{(\lambda a')^2 + (\lambda b')^2}} = \frac{|a'x_P + b'y_P + c'|}{\sqrt{(a')^2 + (b')^2}}$$

$$\text{Moreover } \frac{|a'x_P + b'y_P + c'|}{\sqrt{(a')^2 + (b')^2}} = \frac{\begin{vmatrix} x_P & y_P & 1 \\ x_A & y_A & 1 \\ x_B & y_B & 1 \end{vmatrix}}{\sqrt{(x_A - x_B)^2 + (y_A - y_B)^2}}$$

$$= \frac{\text{area of } \triangle ABP}{\|\vec{BA}\|} = h = d(P, \ell)$$

