

LECTURE 2 - DYNAMICAL SYSTEMS

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Scalar linear differential equations

$$(1) \quad x^{(n)} + a_1(t) \cdot x^{(n-1)} + \dots + a_{n-1}(t) \cdot x' + a_n(t) \cdot x = f(t), \quad t \in J \subset \mathbb{R},$$

Open interval, $a_1, \dots, a_n, f \in C(J)$

The unknown $x : \mathbb{R} \rightarrow \mathbb{R}$ - the set of scalars

$$\mathfrak{L} : C^n(\mathfrak{g}) \rightarrow C(\mathfrak{g})$$

$$L(x)(t) = x^{(n)} + a_1(t) \cdot x^{(n-1)} + \dots + a_n(t) \cdot x \quad , \forall t \in \mathbb{Y}, \forall x \in C^n(\mathbb{Y})$$

We proved that \mathcal{L} is a linear map.

(1) $\Leftrightarrow \alpha(x) = f$

$f(x) = 0$ ist eine L^HD^E

$\text{ker } L$ - the set of all solutions of the LODE;

- vector space .

Th.1 (The fundamental th. for LHDDEs)

Ker L has dimension n.

Pf: \mathbb{R}^n is a vector space of dim n. Fix $t_0 \in \mathbb{J}$
 Let $T: \text{Ker } \delta \rightarrow \mathbb{R}^n$ be defined by $T(\varphi) = \begin{pmatrix} \varphi(t_0) \\ \varphi'(t_0) \\ \vdots \\ \varphi^{(n-1)}(t_0) \end{pmatrix}$, it's clear

Трансформация ψ в \mathbb{R}^n есть $\varphi \in K_{\mathbb{R}}$ с $\Lambda \subset T(\varphi) = \varphi(\Gamma)$.

$$c_{\alpha} \cdot \varphi \eta = \begin{pmatrix} \eta_1 \\ \vdots \\ \eta_n \end{pmatrix} \in \mathbb{R}^n \exists ! \varphi \in C^n(\gamma) \text{ s.t. } \left\{ \begin{array}{l} L(\varphi) = 0 \\ \varphi(t_0) = \eta_1 \\ \varphi'(t_0) = \eta_2 \\ \vdots \\ \varphi^{(n-1)}(t_0) = \eta_n \end{array} \right.$$

This is true by the 3! Theorem from Lecture 1.

T linear $\Leftrightarrow T(\alpha_1 y_1 + \alpha_2 y_2) = \alpha_1 T(y_1) + \alpha_2 T(y_2), \forall \alpha_1, \alpha_2 \in \mathbb{R}$
 $\forall y_1, y_2 \in \text{ker } f$

$$T(\alpha_1\varphi_1 + \alpha_2\varphi_2) = \begin{pmatrix} (\alpha_1\varphi_1 + \alpha_2\varphi_2)(t_0) \\ (\alpha_1\varphi_1 + \alpha_2\varphi_2)'(t_0) \\ \vdots \\ (\alpha_1\varphi_1 + \alpha_2\varphi_2)^{(n-1)}(t_0) \end{pmatrix} = \alpha_1 T(\varphi_1) + \alpha_2 T(\varphi_2). \quad \text{qed}$$

T bijective and T linear $\Rightarrow T$ is an isomorphism between $\ker L$ and $\mathbb{R}^n \Rightarrow \dim(\ker L) = n$

The fundamental th. for Ln-HDE

Let $f \neq 0$. The set of sol. of $L(x) = f$ is $\text{ker } L + \{x_p\}$, where x_p -particular sol. of $L(x) = f$.

In other words, the gen. sol. of eq. (1) is:

$x = x_h + x_p$, x_h -general sol. of $L(x)$, which is called the LODE ans.

$$\text{To } L(x) = f$$

Example:

Find the general sol. of $x'' + x = -3$.

This is a second order Ln-HDE. $x = x_h + x_p$

$$x_h = ? \quad x'' + x = 0$$

$$x = \cos(t), z' = -\sin(t), z'' = -\cos(t) \Rightarrow x'' + x = 0, \forall t \in \mathbb{R}$$

$x = \sin(t)$ is also a sol.

We have $\{\cos t, \sin t\}$ two linearly indep. sol. of $x'' + x = 0 \Rightarrow$

$$\{x_h = c_1 \cdot \cos t + c_2 \cdot \sin t, c_1, c_2 \in \mathbb{R}\} \cup x = c_1 \cos t + c_2 \sin t - 3, c_1, c_2 \in \mathbb{R}.$$

$$x_p = -3 \Rightarrow (-3)'' + (-3) = -3, \text{ true}$$

Scalar first order LDE

$$(2) x' + a(t)x = f(t), t \in \mathbb{Y} \text{ where } a, f \in C(\mathbb{Y}). \text{ Let } t_0 \in \mathbb{Y}$$

$$\text{Let } A(t) = - \int_{t_0}^t a(s) ds. \text{ Then } A'(t) = -a(t), A(t_0) = 0$$

I. The integrating factor method to find the gen. sol. of (2).

We have that $\mu(t) = e^{-A(t)}$ is an integrating factor

We multiply (2) with $\mu(t)$ and obtain:

$$x' \cdot e^{-A(t)} + a(t) \cdot x \cdot e^{-A(t)} = f(t) e^{-A(t)} \Leftrightarrow \\ \left(x \cdot e^{-A(t)} \right)' = f(t) \cdot e^{-A(t)} \Leftrightarrow x \cdot e^{-A(t)} = \int_{t_0}^t f(s) e^{-A(s)} ds + C / e^{A(t)}$$

$$x = C \cdot e^{A(t)} + e^{A(t)} \cdot \int_{t_0}^t f(s) e^{-A(s)} ds, C \in \mathbb{R}$$

ii. The separation of var. method to find the gen. sol. $x' + a(t)x = 0$

We already know that its gen. sol. is $x = C \cdot e^{A(t)}, C \in \mathbb{R}$

$$x' = -a(t)x.$$

Remark: any eq. $x' = \underline{a(t) \cdot g(x)}$ is said to be a separable eq.
t and x are separated

then. why x . $a = \frac{dx}{dt}$ gives us an expression for x .
 t and x are separated

$x=0$ is a solution

$x(t) \neq 0, \forall t \in \mathbb{R}$

$$\begin{aligned} \text{i)} \quad \frac{x'(t)}{x(t)} = -a(t) &\Rightarrow (\ln |x(t)|)' = -a(t) \Leftrightarrow \\ (\ln |x(t)|)' &\stackrel{(\text{int})}{\Rightarrow} \ln |x(t)| = - \int_0^t a(s) ds + C, \Leftrightarrow \\ \ln |x(t)| &= A(t) + C \Leftrightarrow |x(t)| = e^{A(t) + C} \Leftrightarrow \\ \therefore x(t) &= \pm e^{A(t)} \cdot e^C, \quad \left\{ \begin{array}{l} x(t) = \pm e^C \cdot e^{A(t)}, C \in \mathbb{R} \\ x = 0 \end{array} \right. \end{aligned}$$

Remark: $\{e^C, -e^C, 0; C \in \mathbb{R}\} \subseteq \mathbb{R} \Rightarrow x \in C_1 \cdot e^{A(t)}, C_1 \in \mathbb{R}$

iii. The Lagrange method (the variation of the constant method)

- to find a particular sol. to a first order LDE $x' + a(t)x = f$.

The general sol. of the LDE $x' + a(t)x = 0$ is $x_p = C \cdot e^{A(t)}$, $C \in \mathbb{R}$

The idea of Lagrange was to look for x_p sol. of (2).

$x_p = \varphi(t) \cdot e^{A(t)}$, and to find the function $\varphi(t)$.

$$\begin{aligned} x_p \text{ sol. of (2)} \Leftrightarrow x_p' + a(t) \cdot x_p &= f \Leftrightarrow \underbrace{\varphi' \cdot e^{A(t)}}_{x_p'} + \underbrace{\varphi \cdot A'(t) \cdot e^{A(t)}}_{a(t) \cdot x_p} + \underbrace{a(t) \cdot \varphi \cdot e^{A(t)}}_{a(t) \cdot x_p} = f \\ \therefore \varphi' \cdot e^{A(t)} &= f(t) / e^{-A(t)} \end{aligned}$$

$$\therefore \varphi'(t) = f(t) \cdot e^{-A(t)} \Leftrightarrow \varphi(t) = \int_0^t f(s) \cdot e^{-A(s)} ds. \text{ Then } x_p = e^{A(t)} \cdot \int_0^t f(s) \cdot e^{-A(s)} ds$$

iv. Another method to find the gen. sol. of $x' + a(t)x = 0$

Step 1: Check that $e^{A(t)}$ is a solution.

$$(e^{A(t)})' = A'(t) \cdot e^{A(t)} = -a(t) \cdot e^{A(t)} \Rightarrow$$

$$\therefore (e^{A(t)})' + a(t) \cdot e^{A(t)} = 0, \forall t \in \mathbb{R}$$

Step 2: we use the fundamental th. for LDE \Rightarrow

$$\therefore x = C \cdot e^{A(t)}, C \in \mathbb{R}$$

Example:

$$x' = 2t \cdot x + t \quad \text{and} \quad x|_{t=0} = 2$$

Examples:

$$x' - 2tx = t \text{ and } x' - 2tx = \frac{2}{\sqrt{\pi}}$$

These are first order LDEs with the same homogeneous part
 → find the gen sol. of $x' - 2tx = 0$

$$x' = 2tx \quad x' \rightarrow \frac{dx}{dt}$$

$$\frac{dx}{dt} = 2tx \text{ separating } x \text{ and } t \rightarrow \int \frac{dx}{x} = \int 2t dt \Rightarrow$$

$$\Rightarrow \ln|x| = t^2 + C, C \in \mathbb{R} \Rightarrow |x| = e^C \cdot e^{t^2}, C \in \mathbb{R} \Rightarrow$$

$$\Rightarrow x = \pm e^C \cdot e^{t^2}, C \in \mathbb{R} \Rightarrow \begin{cases} x = \pm e^C \cdot e^{t^2} \\ x = 0 \end{cases} \Rightarrow x = C_1 \cdot e^{t^2}, C_1 \in \mathbb{R}$$

$$x' - 2tx = t$$

$$x_p = ? \text{ we see that } x_p = -\frac{1}{2} \text{ the gen sol is } x = C \cdot e^{t^2} - \frac{1}{2}, C \in \mathbb{R}$$

$$x' - 2tx = \frac{2}{\sqrt{\pi}}, \text{ apply Lagrange}$$

$$x_p = C \cdot e^{t^2}, C \in \mathbb{R}, x_p = \varphi(t) \cdot e^{t^2}, \varphi = ?$$

$$x_p' - 2tx_p = \frac{2}{\sqrt{\pi}} \Leftrightarrow \varphi'(t) \cdot e^{t^2} + \cancel{\varphi(t) \cdot 2te^{t^2}} - 2t \cancel{\varphi \cdot e^{t^2}} = \frac{2}{\sqrt{\pi}}, t \in \mathbb{R}$$

$$\therefore \varphi'(t) \cdot e^{t^2} = \frac{2}{\sqrt{\pi}} /, t \in \mathbb{R} \Rightarrow \varphi'(t) = \frac{2}{\sqrt{\pi}} \cdot \tilde{e}^{t^2}, \therefore$$

$$\therefore \varphi(t) = \frac{2}{\sqrt{\pi}} \cdot \int_0^t \tilde{e}^{s^2} ds = \operatorname{erf}(t), \text{ the error function}$$

$$\text{So, } x_p = \varphi(t) \cdot e^{t^2} \Rightarrow x_p = \operatorname{erf}(t) \cdot e^{t^2}$$

$$\therefore \text{the gen sol is } x = e^{t^2} (C + \operatorname{erf}(t)), C \in \mathbb{R}$$