

LECTURE 6 - DYNAMICAL SYSTEMS

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Linear diff systems with ∞ (cont.)

Diagonalizable matrix

Def: We say that a matrix $A \in \mathbb{M}_{n,n}(\mathbb{R})$ is diagonalizable over \mathbb{R} when there is a diagonal matrix $B \in \mathbb{M}_{n,n}(\mathbb{R})$ s.t A is similar to B .

A matrix that is not diagonalizable is said to be defective.

Property: Let $A \in \mathbb{M}_n(\mathbb{R})$. We have that A is diagonalizable over \mathbb{R} if and only if any eigenvalue of A is real and there exist n linearly independent eigenvectors of A .

Recall: $\lambda \in \mathbb{C}$ is an eigenvalue of A ($\Rightarrow \exists \underset{\text{def}}{u} \in \mathbb{R}^n, u \neq 0$ s.t. $Au = \lambda u$ (u is an eigenvector corresponding to the eigenvalue λ of A)) $\Leftrightarrow \det(A - \lambda I_n) = 0$ (this is a polynomial eq. in λ of degree n).

Assume that A is diagonalizable.

Let $\lambda_1, \lambda_2, \dots, \lambda_n \in \mathbb{R}$ be the eigenvalues of A , not necessarily distinct, and let $u_1, u_2, \dots, u_n \in \mathbb{R}^n$ be n linearly indep. eigenvectors of A .

Then $D = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$

Property: If $P \in \mathbb{C}^{n \times n}$ s.t. its k^{th} column is $\neq 0$. Then $A = PDP^{-1}$ and P is invertible.

Remark: $A^k = P D^k P^{-1} = P \text{diag}(\lambda_1^k, \lambda_2^k, \dots, \lambda_n^k) P^{-1}$

$$e^{tA} = P \text{diag}(e^{t\lambda_1}, e^{t\lambda_2}, \dots, e^{t\lambda_n}) P^{-1}$$

Procedure to find the general sol. of $x' = Ax$ when $A \in \mathbb{M}_{n \times n}(\mathbb{R})$ is diagonalizable.

Step 1: Find the eigenvalues and the eigenvectors of A . Decide whether A is diagonalizable or not. If it is, continue.

Step 2: Find $D = \text{diag}(\lambda_1, \dots, \lambda_n)$ $P = (u_1, u_2, \dots, u_n)$

Step 3: Find $e^{At} = P \cdot \text{diag}(e^{\lambda_1 t}, \dots, e^{\lambda_n t}) P^{-1}$

Step 4: Write the gen. sol. $x = e^{ta} \cdot C$, $C \in \mathbb{R}^n$

Property: Let $A \in \mathbb{C}^{n \times n}$, λ - an eigenvalue of A and u a correspond. eigenvector. We have that

$\varphi: \mathbb{R} \rightarrow \mathbb{R}^n$, $\varphi(t) = e^{At} u$, $\forall t \in \mathbb{R}$ is a sol. of $x' = Ax$.

φ : φ is a sol of $x' = Ax \Leftrightarrow \varphi'(t) = A \cdot \varphi(t), \forall t \in \mathbb{R} \Leftrightarrow \lambda e^{\lambda t} u = A \cdot e^{\lambda t} u, \forall t \in \mathbb{R}$

$\Leftrightarrow \lambda u = Au$, $\forall t \in \mathbb{R}$, true $\Leftrightarrow \lambda$ - eigenvalue of A \Rightarrow u - eigenvector of A \square

Consequence: Assume that A is diagonalizable. Then $e^{\lambda_1 t} u_1, e^{\lambda_2 t} u_2, \dots, e^{\lambda_n t} u_n$ are n lin. indep. sol. of $\dot{v}' = Ax$

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2. characteristic eq. method to find the gen sol of $\dot{x} = Ax$ when A is diagonalizable.

Step 1: Find the eigenvalues and the eigenvectors of A . Decide whether A is diagonalizable or not. If it is diagonalizable, find the matrix P and D .

Step 2: Write the λ 's, $e^{\lambda_1 t} u_1, \dots, e^{\lambda_n t} u_n$

Step 3: Write the general of $x^1 = Ax$

$$x = c_1 e^{\lambda_1 t} u_1 + \dots + c_n e^{\lambda_n t} u_n, c_1, \dots, c_n \in \mathbb{R}$$

Example :

Example: 1) Prove that $A = \begin{pmatrix} 1 & 3 \\ 0 & 2 \end{pmatrix}$ is diagonalizable over \mathbb{R} .

Given $\sin \theta = -\frac{1}{2}$ and $\cos \theta < 0$, find the exact value of $\tan \theta$.

1) Prove that $A = \begin{pmatrix} 1 & 3 \\ -1 & 1 \end{pmatrix}$ is diagonalizable over \mathbb{R} .

2) Using the charact. eq. method find the gen. sol. of $x' = Ax$.

1) the charact. eq. is $\det(A - \lambda I_2) = 0 \Leftrightarrow \begin{vmatrix} 1-\lambda & 3 \\ -1 & 1-\lambda \end{vmatrix} = 0 \Leftrightarrow -(1-\lambda)(1+\lambda) - 3 = 0 \Leftrightarrow -1 + \lambda^2 - 3 = 0 \Leftrightarrow \lambda^2 - 4 = 0 \Leftrightarrow$

$$\therefore \lambda_1 = -2, \lambda_2 = 2$$

$u_1 = ?$ an eigenvector corr. to $\lambda_1 = -2 \Leftrightarrow u_1 \in \mathbb{R}^2, u_1 \neq \begin{pmatrix} 0 \\ 0 \end{pmatrix}, A u_1 = -2u_1, u_1 = \begin{pmatrix} a \\ b \end{pmatrix}$
 $Au_1 = -2u_1 \Leftrightarrow \begin{pmatrix} 1 & 3 \\ -1 & 1 \end{pmatrix} \cdot \begin{pmatrix} a \\ b \end{pmatrix} = -2 \begin{pmatrix} a \\ b \end{pmatrix} \Leftrightarrow \begin{cases} a+3b = -2a \\ a-b = -2b \end{cases} \begin{cases} 3a+3b=0 \\ a+b=0 \end{cases} \therefore a+b=0$

$$\therefore a+b=0. \text{ Check } a=b=-1 \Leftrightarrow u_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$u_2 = ?$ an eigenvector corr. to $\lambda_2 = 2 \Leftrightarrow u_2 \in \mathbb{R}^2, u_2 \neq \begin{pmatrix} 0 \\ 0 \end{pmatrix}, u_2 = \begin{pmatrix} a \\ b \end{pmatrix}$

$$Au_2 = 2u_2 \Leftrightarrow (4 \cdot 2u_2)u_2 = 0 \Leftrightarrow \begin{pmatrix} -1 & 3 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 0 \Leftrightarrow \begin{cases} -a+3b=0 \\ a-3b=0 \end{cases}$$

Choose $a = 3, b = 1 \Rightarrow u_2 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$

So A has the eigenvalues $\lambda_1 = -2, \lambda_2 = 2$, both real, $n = 2$ and we found 2 eigenvectors $u_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $u_2 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$

Since $\begin{pmatrix} 1 & 3 \\ -1 & 1 \end{pmatrix} = 4 + 0 \rightarrow u_1$, and u_2 are lin. indep

Thus, A is diagonalizable.

2) we have that $e^{-2t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $e^{2t} \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ are linearly indep. sol. of $x' = Ax$.

$$\Rightarrow \text{gen. sol.: } X = c_1 e^{-2t} \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 e^{2t} \begin{pmatrix} 3 \\ 1 \end{pmatrix}, c_1, c_2 \in \mathbb{R}$$

Remark: Write by components the system $x' = Ax$ and its gen. sol., using the not. $X = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$ or $X = \begin{pmatrix} x \\ y \end{pmatrix}$.

$$x' = Ax \Leftrightarrow \begin{cases} x'_1 = x_1 + 3x_2 \\ x'_2 = x_1 - x_2 \end{cases} \text{ and its gen. sol. is } \begin{cases} x_1 = c_1 e^{-2t} + 3c_2 e^{2t} \\ x_2 = -c_1 e^{-2t} + c_2 e^{2t}, c_1, c_2 \in \mathbb{R} \end{cases}$$

Ex. 3) Find e^{tA}

$$A = \begin{pmatrix} -2 & 0 \\ 0 & 2 \end{pmatrix}, P = \begin{pmatrix} 1 & 3 \\ -1 & 1 \end{pmatrix}, P^{-1} = ? \quad \det P = 4 \Rightarrow P^{-1} = \begin{pmatrix} \frac{1}{4} & -\frac{3}{4} \\ \frac{-1}{4} & \frac{1}{4} \end{pmatrix} \Rightarrow e^{tA} = \begin{pmatrix} 1 & 3 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} e^{-2t} & 0 \\ 0 & e^{2t} \end{pmatrix} \begin{pmatrix} \frac{1}{4} & \frac{3}{4} \\ \frac{-1}{4} & \frac{1}{4} \end{pmatrix} =$$

$$= \begin{pmatrix} 1 & 3 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{4} e^{-2t} & -\frac{3}{4} e^{-2t} \\ \frac{1}{4} e^{2t} & \frac{1}{4} e^{2t} \end{pmatrix} = \frac{1}{4} \begin{pmatrix} e^{-2t} + 3e^{2t} & -3e^{-2t} + 3e^{2t} \\ -e^{-2t} + e^{2t} & 3e^{-2t} + e^{2t} \end{pmatrix} \text{ it was quite easy to compute in this way since we already computed the eigenvalues and the eigenvectors}$$

Another method to find the gen. sol. of LHS with \mathbf{cc} in dimension $n=2$.

$$(1) \begin{cases} x' = a_{11}x + a_{12}y \\ y' = a_{21}x + a_{22}y \end{cases} \text{ where } A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in \mathcal{M}_2(\mathbb{R})$$

Case 1: Uncoupled systems (A is diagonal or $a_{12} = a_{21} = 0$)

$$\begin{cases} x' = a_{11}x \\ y' = a_{22}y \end{cases} \Rightarrow \begin{cases} x = c_1 e^{a_{11}t} \\ y = c_2 e^{a_{22}t} \end{cases}, c_1, c_2 \in \mathbb{R}$$

Case 2: Coupled systems (either $a_{12} \neq 0$ or $a_{21} \neq 0$)

$$(1) \begin{cases} x' = a_{11}x + a_{12}y \\ y' = a_{21}x + a_{22}y \end{cases} \text{ consider the case } a_{12} \neq 0$$

Reduction to a second order diff. eq.

$a_{12} \neq 0 \Rightarrow$ the second order DE will be in x . Thus, we want to obtain from (1) a rel. between x' , x''

and x , without y .

$$y = \frac{1}{a_{42}} (x' - a_{41}x)$$

$$\begin{aligned} x'' &= a_{11}x' + a_{12}y' \stackrel{(2)}{=} a_{11}x' + a_{12}(a_{41}x + a_{42}y) = \\ &= a_{11}x' + a_{12}a_{41}x + a_{11}a_{42} \cdot \frac{1}{a_{42}}(x' - a_{41}x) = \\ &= a_{11}x' + a_{12}a_{41}x + a_{22}x' - a_{11}a_{22}x = \end{aligned}$$

$$= x'' - (a_{11}a_{22})x' + (a_{11}a_{22} - a_{12}a_{41})x = 0 \quad (4) \text{ Second order LDE with CC.}$$

Remark: The charact. polynomial of eq. (4) is $p(k) = k^2 - (a_{11} + a_{22})k + (a_{11}a_{22} - a_{12}a_{41}) = k^2 - \text{tr}(A)k + \det(A)$, which also is the charact. polynomial of A .

Exercise: Using the above method, find the gen. sol. of $x' = Ax$ with $A = \begin{pmatrix} 1 & 3 \\ 1 & -1 \end{pmatrix}$. Then find e^{tA} using the gen. sol. that we found and that $E(t) = e^{tA}$ satisfies $x' = Ax$.

$$x(0) = y_2$$

$\begin{cases} x' = x + 3y \\ y' = x - y \end{cases}$, this is a coupled system, here it is possible to find the second order eq. with respect to y .

$$\begin{aligned} y &= \frac{1}{3}(x' - x) & x'' = x' + 3y' &= x' + 3(x - y) = x' + 3x - 3 \cdot \frac{1}{3}(x' - x) = x' + 3x - x' + x = 4x \\ x'' - 4x &= 0 & x_1 = -2 \mapsto e^{-2t} & x = c_1 e^{-2t} + c_2 e^{2t} \\ x^2 - 4 = 0 & & x_2 = 2 \mapsto e^{2t} & y = \frac{1}{3}(-2c_1 e^{-2t} + 2c_2 e^{2t} - c_1 e^{-2t} - c_2 e^{2t}) \end{aligned}$$

$$\Rightarrow \begin{cases} x = c_1 e^{-2t} + c_2 e^{2t} \\ y = -c_1 e^{-2t} + \frac{1}{3}c_2 e^{2t}, c_1, c_2 \in \mathbb{C} \end{cases}$$

$e^{tA} = ?$ the first column of e^{tA} is the sol. of the IVP $\begin{cases} x' = Ax \\ x(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{cases} \quad (5)$

The second column of e^{tA} is the sol. of the IVP $\begin{cases} x' = Ax \\ x(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{cases} \quad (6)$

$$(5) : \begin{cases} x(0) = c_1 + c_2 = 1 \\ y(0) = -c_1 + \frac{1}{3}c_2 = 0 \end{cases} \Leftrightarrow \begin{cases} \frac{4}{3}c_2 = 1 \Rightarrow c_2 = \frac{3}{4} \Rightarrow c_1 = \frac{c_2}{3} \cdot \frac{1}{4} = \frac{1}{4} \end{cases} \Rightarrow \text{the sol. of (5) is } x_1 = \begin{pmatrix} \frac{1}{4}e^{-2t} + \frac{3}{4}e^{2t} \\ -\frac{1}{4}e^{-2t} + \frac{1}{4}e^{2t} \end{pmatrix}$$

$$(6) : \begin{cases} x(0) = c_1 + c_2 = 0 \\ y(0) = -c_1 + \frac{1}{3}c_2 = 1 \end{cases} \Leftrightarrow \begin{cases} c_2 = \frac{3}{4} \Rightarrow c_1 = -c_2 = -\frac{3}{4} = 1 \end{cases} \Rightarrow \text{the sol. of (6) is } x_2 = \begin{pmatrix} -\frac{3}{4}e^{-2t} + \frac{3}{4}e^{2t} \\ \frac{3}{4}e^{-2t} + \frac{1}{4}e^{2t} \end{pmatrix}$$

$$\text{So, } e^{tA} = (x_1 \ x_2) = \begin{pmatrix} \frac{1}{4}e^{-2t} + \frac{3}{4}e^{2t} & -\frac{3}{4}e^{-2t} + \frac{3}{4}e^{2t} \\ -\frac{1}{4}e^{-2t} + \frac{1}{4}e^{2t} & \frac{3}{4}e^{-2t} + \frac{1}{4}e^{2t} \end{pmatrix}.$$