

LSGAN & ACGAN

GAN: N-STEP FURTHER

REMARK

- ▶ Binary Cross-Entropy Loss

$$BCE(x) = -\frac{1}{N} \sum_{i=1}^N y_i \log(h(x_i; \theta)) + (1 - y_i) \log(1 - h(x_i; \theta))$$

- ▶ 확률적 분류 모델의 학습
- ▶ 입력에 대한 확률적 예측이 ground-truth 확률과 최대한 유사하도록

REMARK: DCGAN

```
# Discriminator
inputs = Input(shape=img_shape, name='discriminator_input')
discriminator = build_discriminator(inputs)
optimizer = RMSprop(lr=lr, decay=decay)
discriminator.compile(loss='binary_crossentropy', optimizer=optimizer, metrics=['accuracy'])
discriminator.summary()

# Adversarial
discriminator.trainable = False # Fix weights # Boolean flag at compiling

inputs = Input(shape=z_shape, name='generator_input')
adversarial = Model(inputs, discriminator(generator(inputs)), name=model_name)
optimizer = RMSprop(lr=lr * 0.5, decay=decay * 0.5)
adversarial.compile(loss='binary_crossentropy', optimizer=optimizer, metrics=['accuracy'])
adversarial.summary()
```

LOGAN

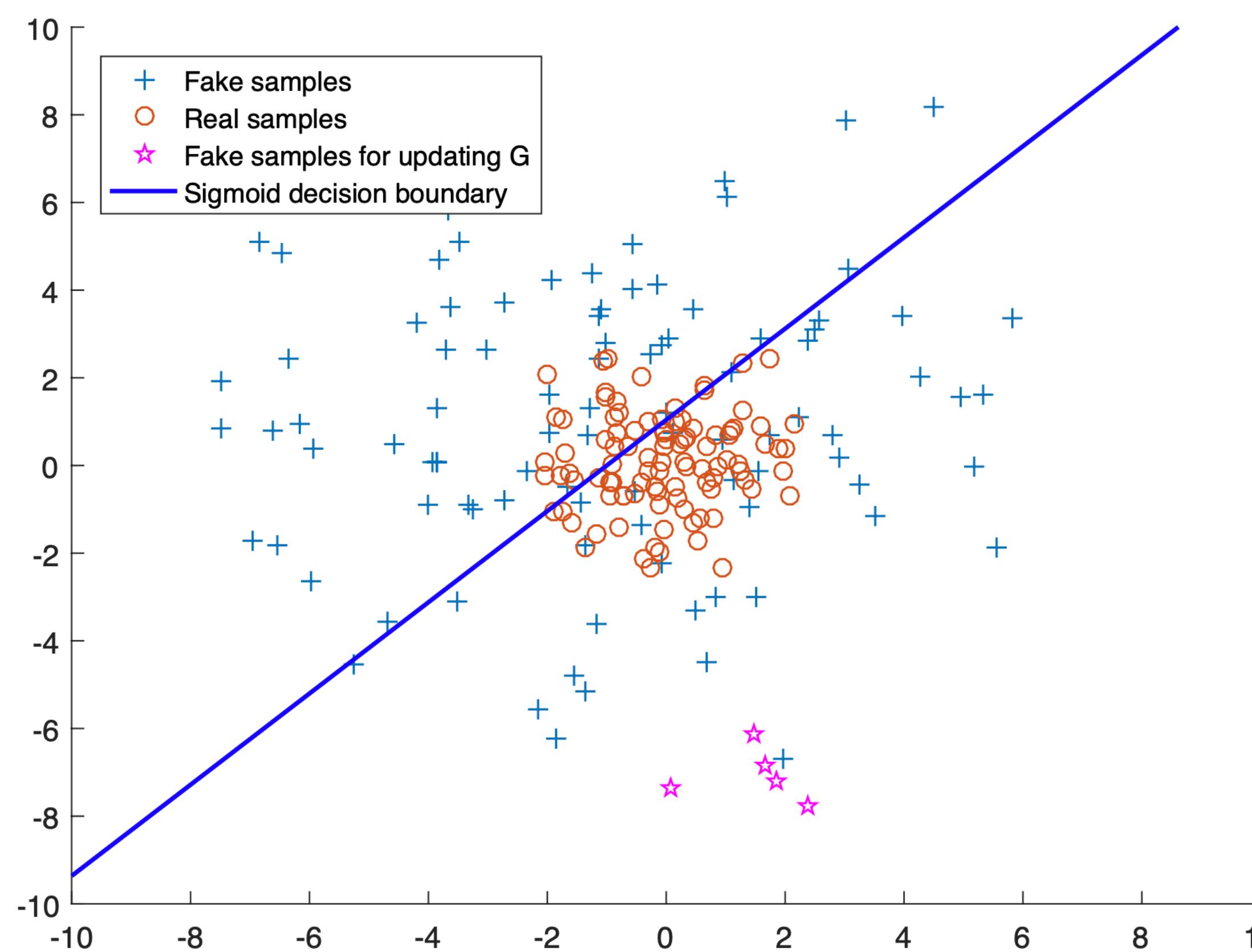
LSGAN

- ▶ Least Squares Generative Adversarial Networks
- ▶ Ref: Mao, Xudong, et al. "Least squares generative adversarial networks." Proceedings of the IEEE International Conference on Computer Vision. 2017.

GAN

- ▶ 기존 GAN에서의 sigmoid cross entropy loss
(=binary cross entropy loss)
- ▶ Gradient vanishing 문제를 야기함

GAN

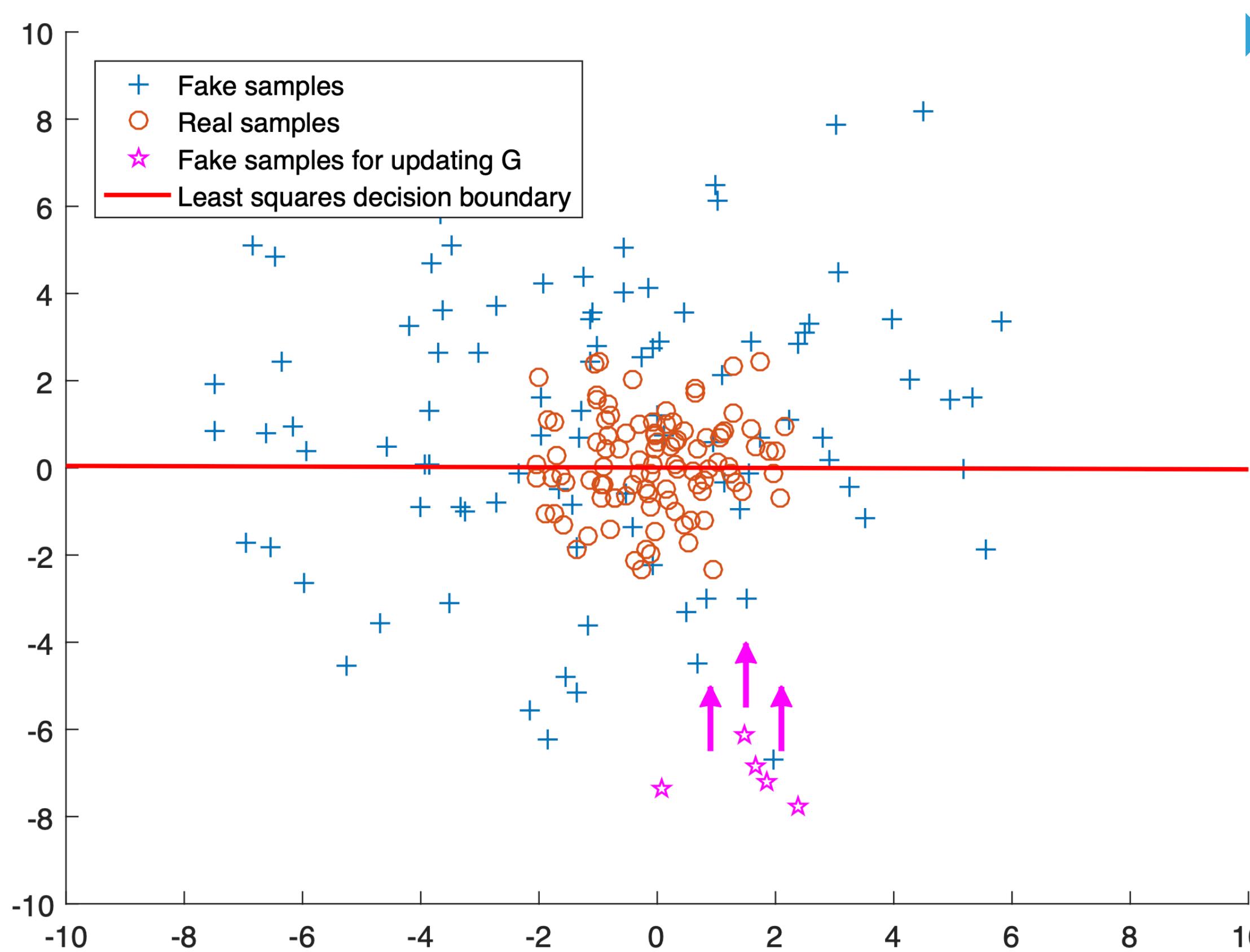


- ▶ 결정 경계 아래: 진짜로 구별
- ▶ 별(마젠타): 가짜이지만 진짜로 판단 중
- ▶ 생성기 업데이트에 도움을 주지 않음
- ▶ Gradient vanishing

LSGAN

- ▶ LSGAN의 least square
 - ▶ 가짜 데이터를 decision boundary에 가깝게 이동
 - ▶ 문제를 해결할 수 있음

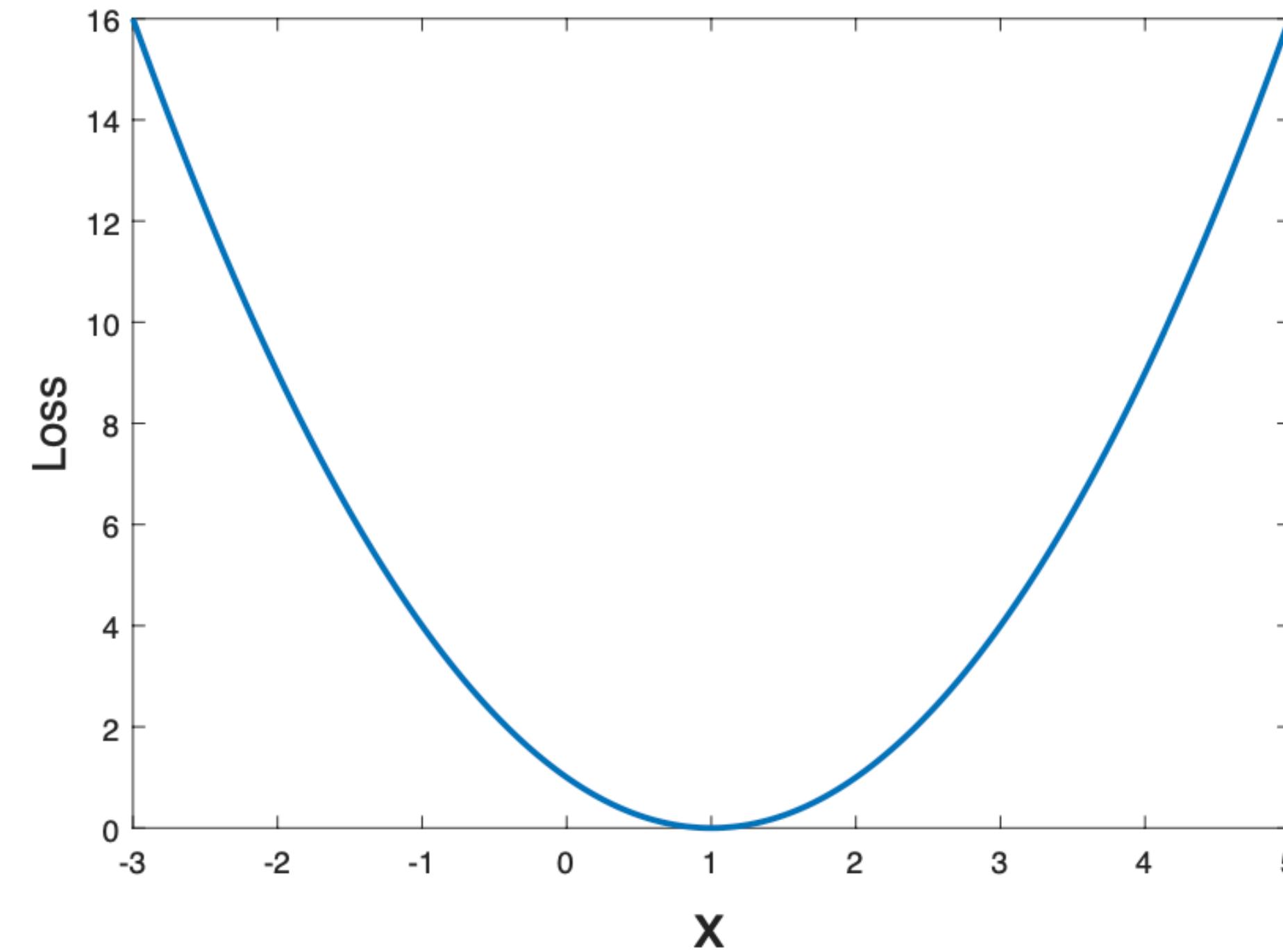
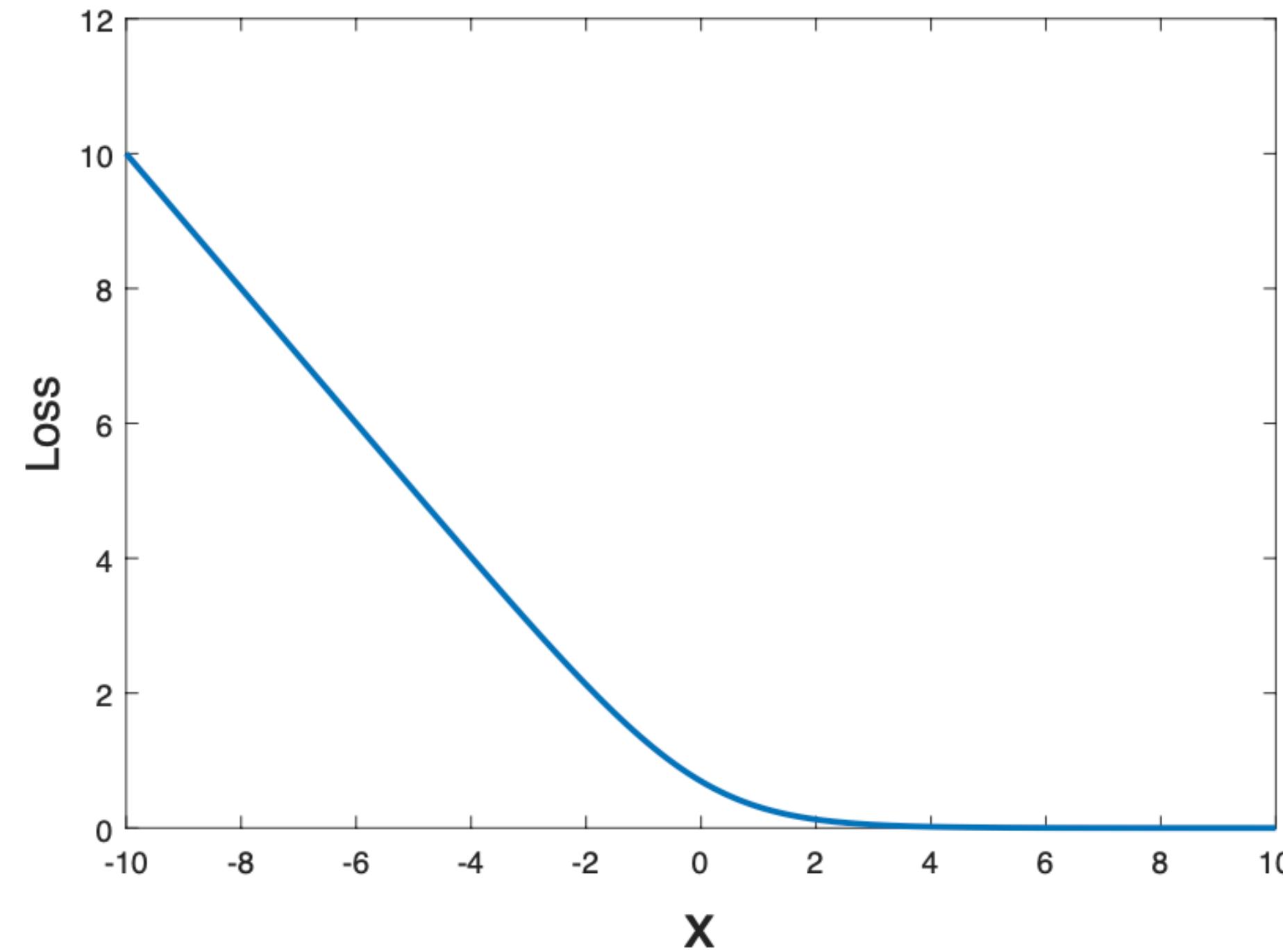
LSGAN



- ▶ 결정 경계에서 멀리 떨어져 있을 수록 패널티
- ▶ 별(마젠타) 데이터를 진짜 데이터 근처로
- ▶ Least square loss 사용

BENEFITS

- ▶ Sigmoid cross entropy loss function (vs.) Least squares loss function



LSGAN

▶ 기존의 GAN:

$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_{data}(x)} [\log D(x)] + \mathbb{E}_{z \sim p_z(z)} [\log(1 - D(G(z)))]$$

▶ LSGAN

$$\min_D V_{LSGAN}(D) = \frac{1}{2} \mathbb{E}_{x \sim p_{data}(x)} [(D(x) - b)^2] + \frac{1}{2} \mathbb{E}_{z \sim p_x(z)} [(D(G(z)) - a)^2]$$

$$\min_G V_{LSGAN}(G) = \frac{1}{2} \mathbb{E}_{z \sim p_z(z)} [(D(G(z)) - c)^2]$$

LSGAN

▶ LSGAN

$$\begin{aligned} \min_D V_{LSGAN}(D) &= \frac{1}{2} \mathbb{E}_{x \sim p_{data}(x)} [(D(x) - b)^2] + \frac{1}{2} \mathbb{E}_{z \sim p_x(z)} [(D(G(z)) - a)^2] \\ \min_G V_{LSGAN}(G) &= \frac{1}{2} \mathbb{E}_{z \sim p_z(z)} [(D(G(z)) - c)^2] \end{aligned}$$

- ▶ a: fake label
- ▶ b: real label
- ▶ c: G 입장에서 D가 진짜라 믿게 하고픈 fakes

LSGAN

▶ LSGAN

$$\begin{aligned} \min_D V_{LSGAN}(D) &= \frac{1}{2} \mathbb{E}_{x \sim p_{data}(x)} [(D(x) - b)^2] + \frac{1}{2} \mathbb{E}_{z \sim p_x(z)} [(D(G(z)) - a)^2] \\ \min_G V_{LSGAN}(G) &= \frac{1}{2} \mathbb{E}_{z \sim p_z(z)} [(D(G(z)) - c)^2] \end{aligned}$$

▶ 최소가 되기 위해:

▶ $D(x) \rightarrow \text{reals}$

▶ $D(G(z)) \rightarrow \text{fakes}$

LSGAN

▶ LSGAN

$$\min_D V_{LSGAN}(D) = \frac{1}{2} \mathbb{E}_{x \sim p_{data}(x)} [(D(x) - b)^2] + \frac{1}{2} \mathbb{E}_{z \sim p_x(z)} [(D(G(z)) - a)^2]$$

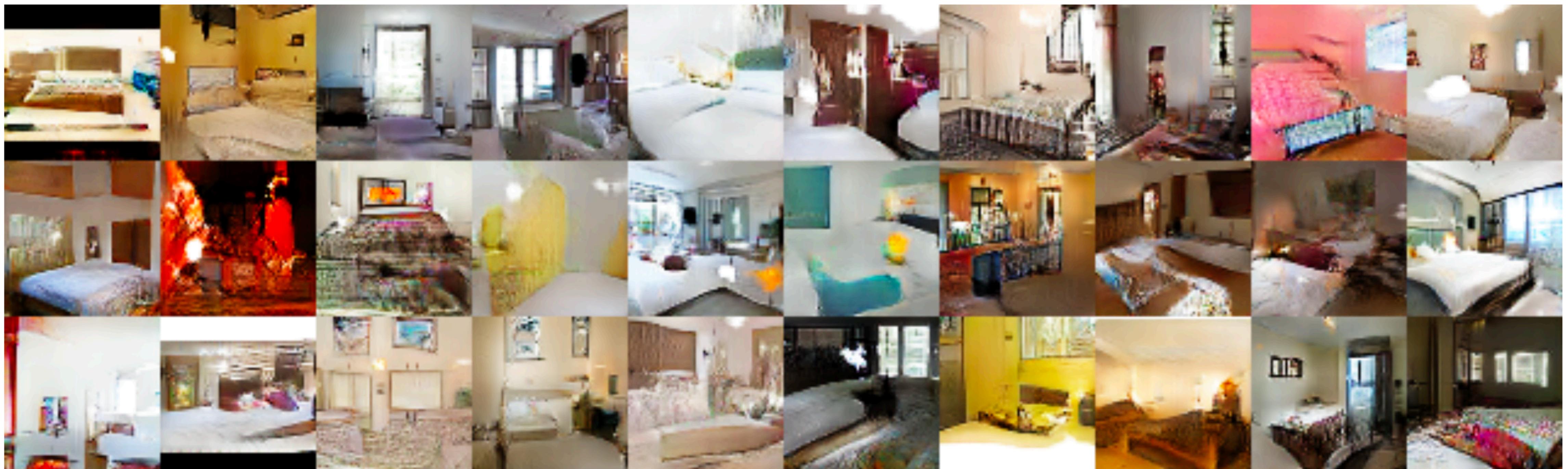
$$\min_G V_{LSGAN}(G) = \frac{1}{2} \mathbb{E}_{z \sim p_z(z)} [(\boxed{D(G(z)) - c})^2]$$

▶ 최소가 되기 위해:

▶ $D(G(z)) \rightarrow fakes imitating reals$

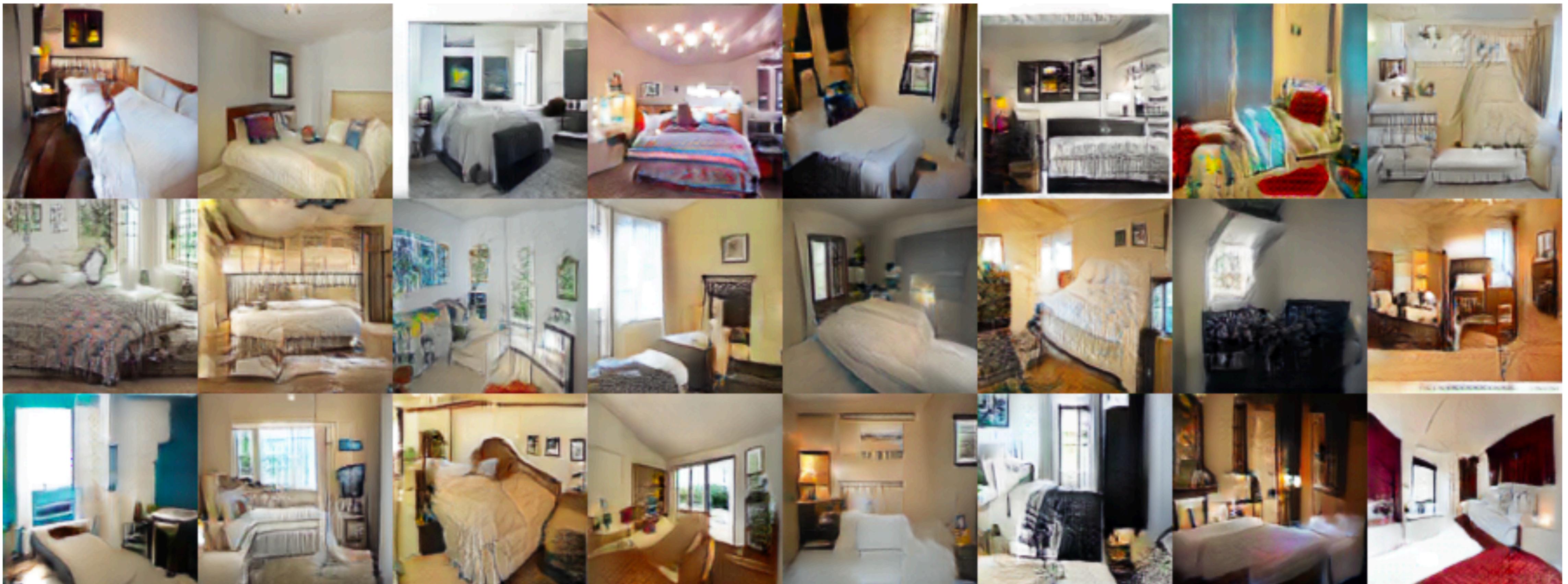
EXPERIMENTS

► DCGANs:



EXPERIMENTS

▶ LSGANs:



EXPERIMENTS

- ▶ 안정성

- ▶ Mode collapse의 유무 (NO가 좋음)

Optimizer	BN _G	BN _G	BN _{GD}	BN _{GD}
Regular GANs	Adam	RMSProp	Adam	RMSProp
LSGANs	YES	NO	YES	YES
	NO	NO	YES	NO

- ▶ BN: Batch Normalization (G, D) 제외
 - ▶ Adam (vs.) RMSProp

ACGAN

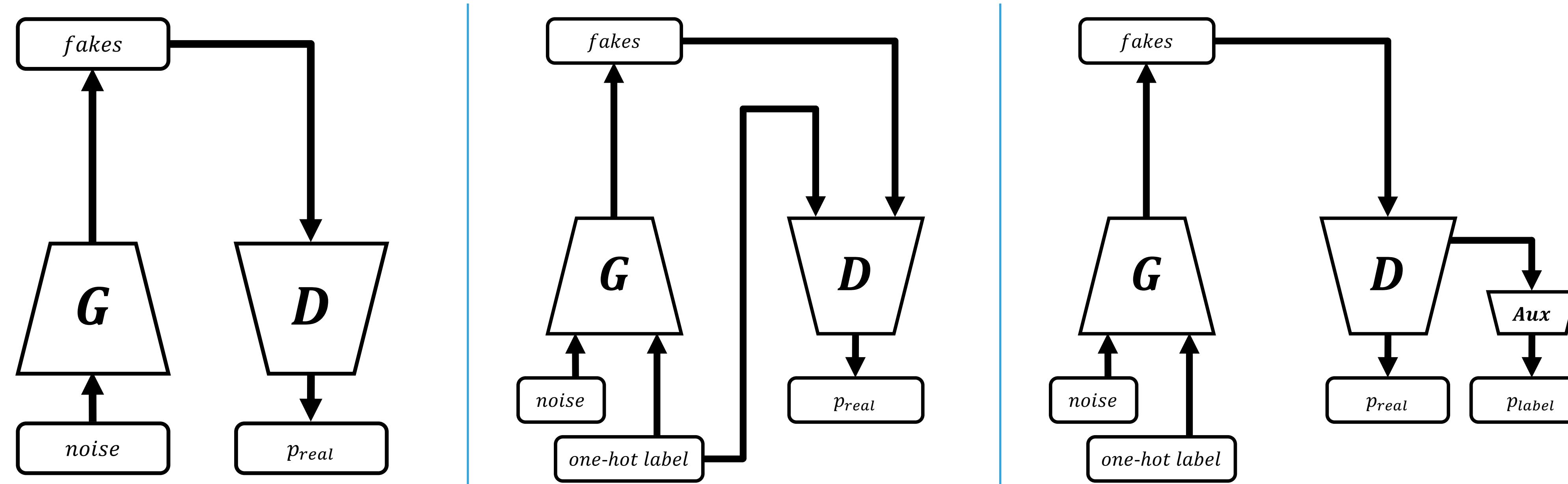
ACGAN

- ▶ Ref: Odena, Augustus, Christopher Olah, and Jonathon Shlens. "Conditional image synthesis with auxiliary classifier gans." Proceedings of the 34th International Conference on Machine Learning-Volume 70. JMLR. org, 2017.

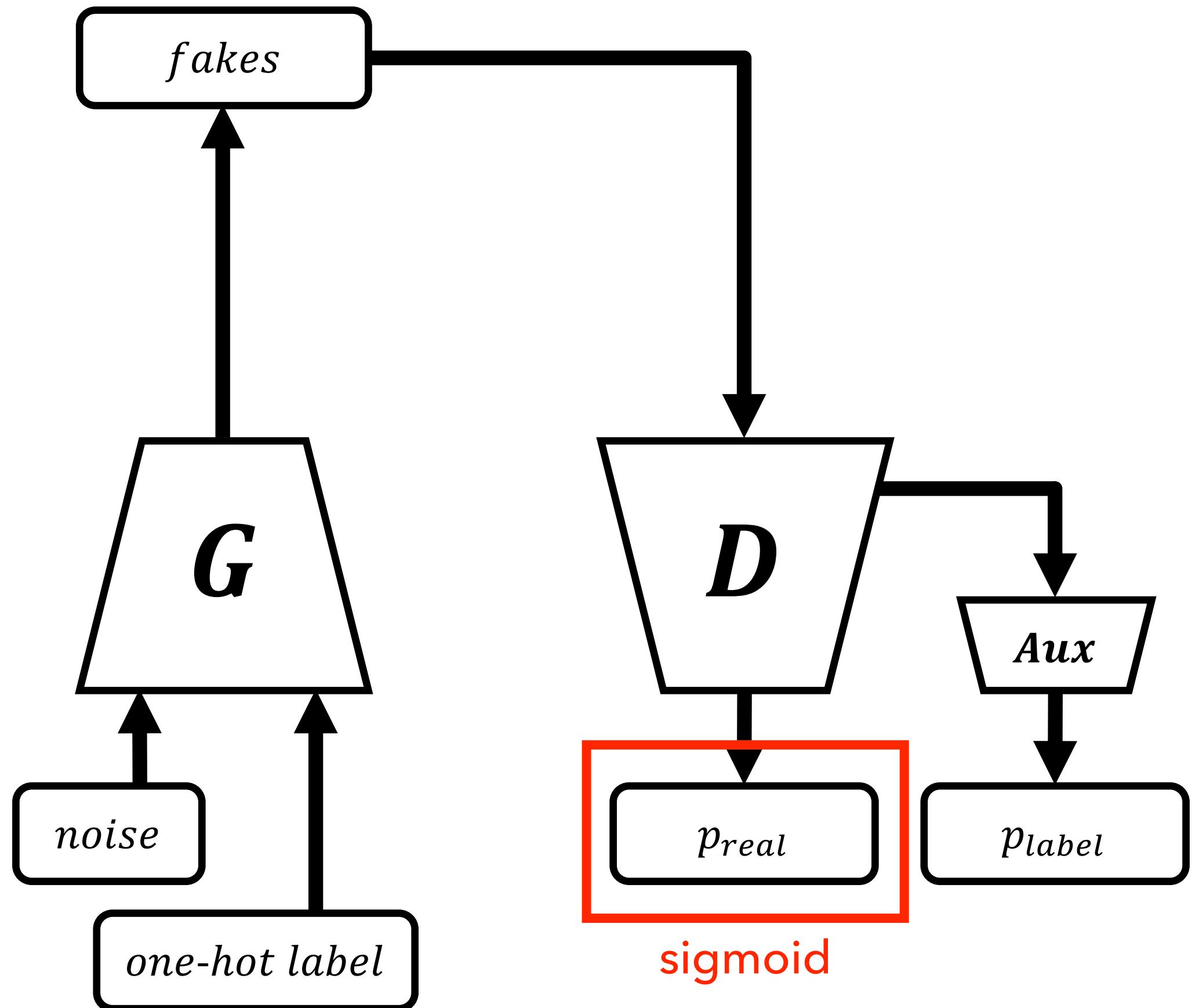
ACGAN

- ▶ 보조 분류기(Auxiliary Classifier) GANs
- ▶ CGAN 판별기
 - ▶ 입력: 이미지와 레이블
 - ▶ 출력: 이미지가 진짜일 확률
- ▶ ACGAN 판별기
 - ▶ 입력: 이미지
 - ▶ 출력: 이미지가 진짜이면서 **클래스 레이블일 확률**

DCGAN VS CGAN VS ACGAN

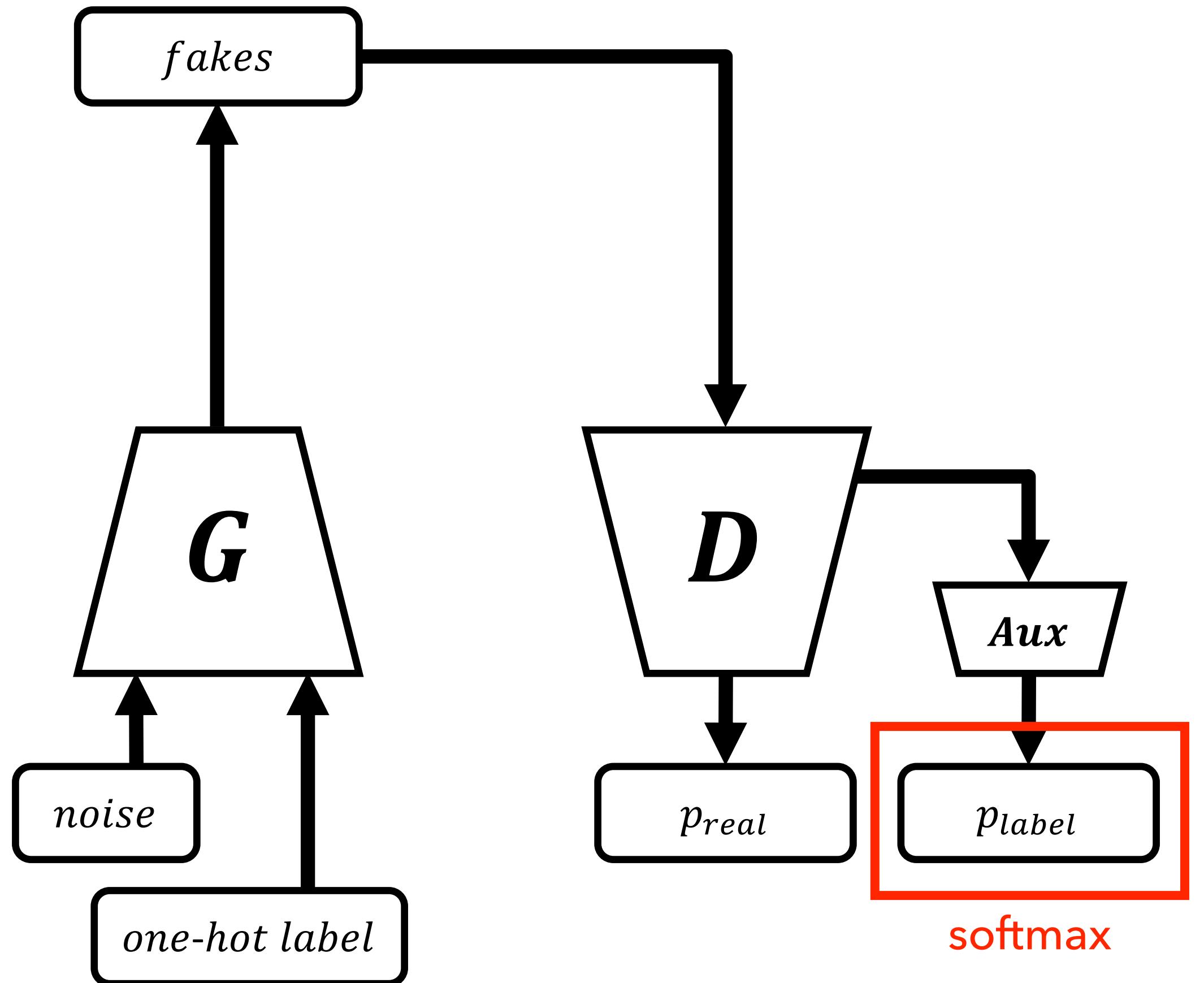


ACGAN



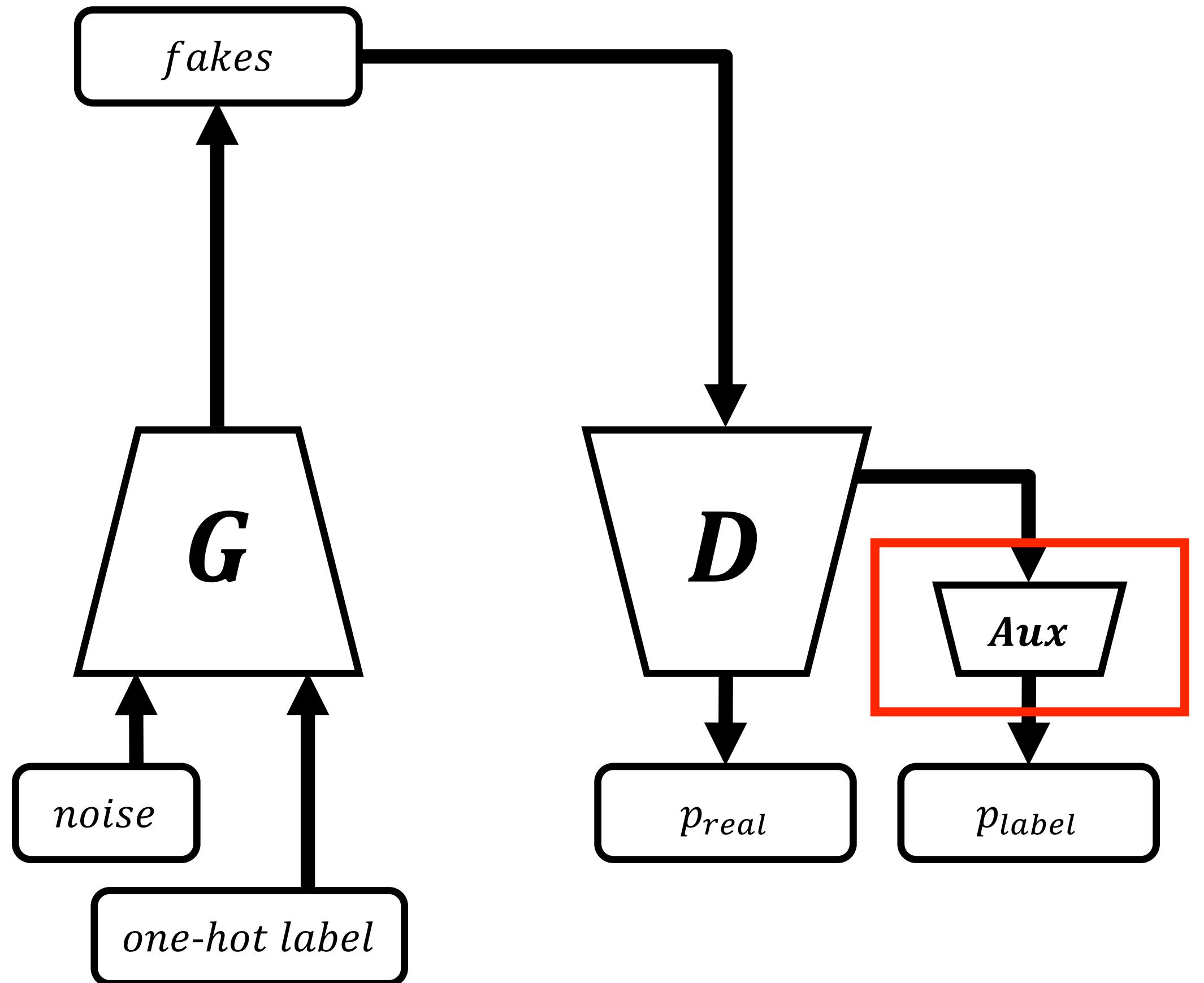
► p_{real} : Binary Cross-Entropy Loss

ACGAN



- ▶ p_{label} : Categorical Cross-Entropy Loss

ACGAN



▶ *Aux* : Auxiliary class decoder network

AUX

- ▶ 보조 클래스 디코더 네트워크(Auxiliary class decoder network)
 - ▶ 부가 정보인 레이블 정보를 재구성
 - ▶ 네트워크에 **부가 작업**을 시킴으로써 **본래 작업**의 성능을 향상
 - ▶ 본래 작업인 가짜 이미지 생성

ACGAN

- ▶ 손실 함수
- ▶ $L_S = E[\log p(S = real | X_{real})] + E[\log p(S = fake | X_{fake})]$
- ▶ $L_C = E[\log p(C = c | X_{real})] + E[\log p(C = c | X_{fake})]$
- ▶ S는 Source (data)
- ▶ C는 Class (label)

ACGAN

- ▶ $L_S = E[\log p(S = \text{real} | X_{\text{real}})] + E[\log p(S = \text{fake} | X_{\text{fake}})]$
- ▶ $L_C = E[\log p(C = c | X_{\text{real}})] + E[\log p(C = c | X_{\text{fake}})]$
- ▶ 판별기
 - ▶ $L_S + L_C$ 를 최대화
 - ▶ 생성기
 - ▶ $-L_S + L_C$ 를 최대화

ACGAN

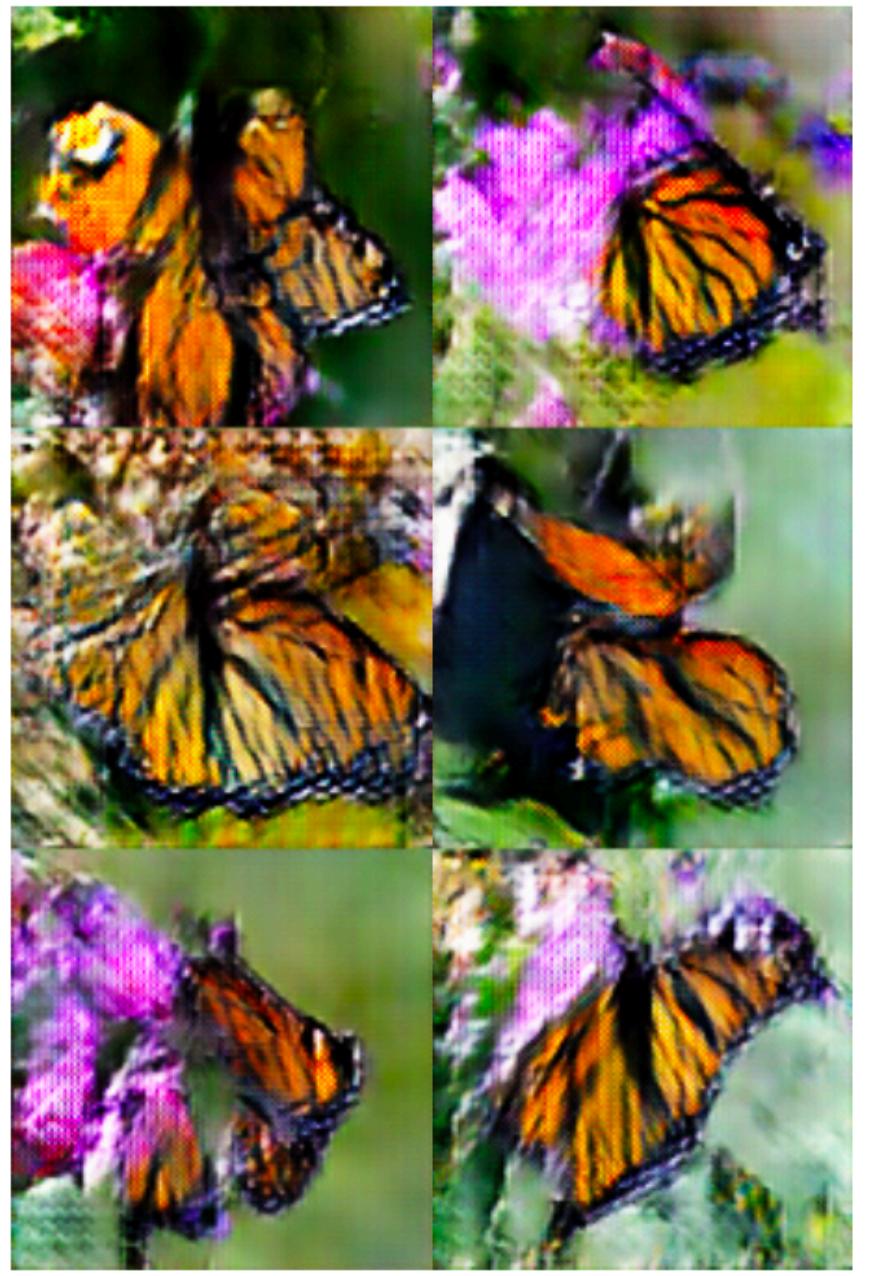
- ▶ 판별기
 - ▶ $L_S + L_C$ 를 최대화
 - ▶ $-L_S - L_C$ 를 최소화
 - ▶ $L^{(D)} = -\mathbb{E}_{x \sim P_{data}} \log D(x) - \mathbb{E}_z \log(1 - D(G(z|y)))$
 $\quad -\mathbb{E}_{x \sim P_{data}} \log p(c|x) - \mathbb{E}_z \log p(c|G(z|y))$

ACGAN

- ▶ 생성기
 - ▶ $-L_S + L_C$ 를 최대화
 - ▶ $L_S - L_C$ 를 최소화
 - ▶
$$L^{(G)} = -\mathbb{E}_z \log D(G(z | y)) - \mathbb{E}_z \log p(c | G(z | y))$$
 - ▶ 가짜를 진짜라 말해야 함: L_S 의 반대 = $-L_S$
 - ▶ Real data 상관 없음

5 CLASSES ON THE IMAGENET DATASET

- ▶ 128×128 해상도의 가짜 이미지들
- ▶ 당시(2016) 기준으로 고해상도



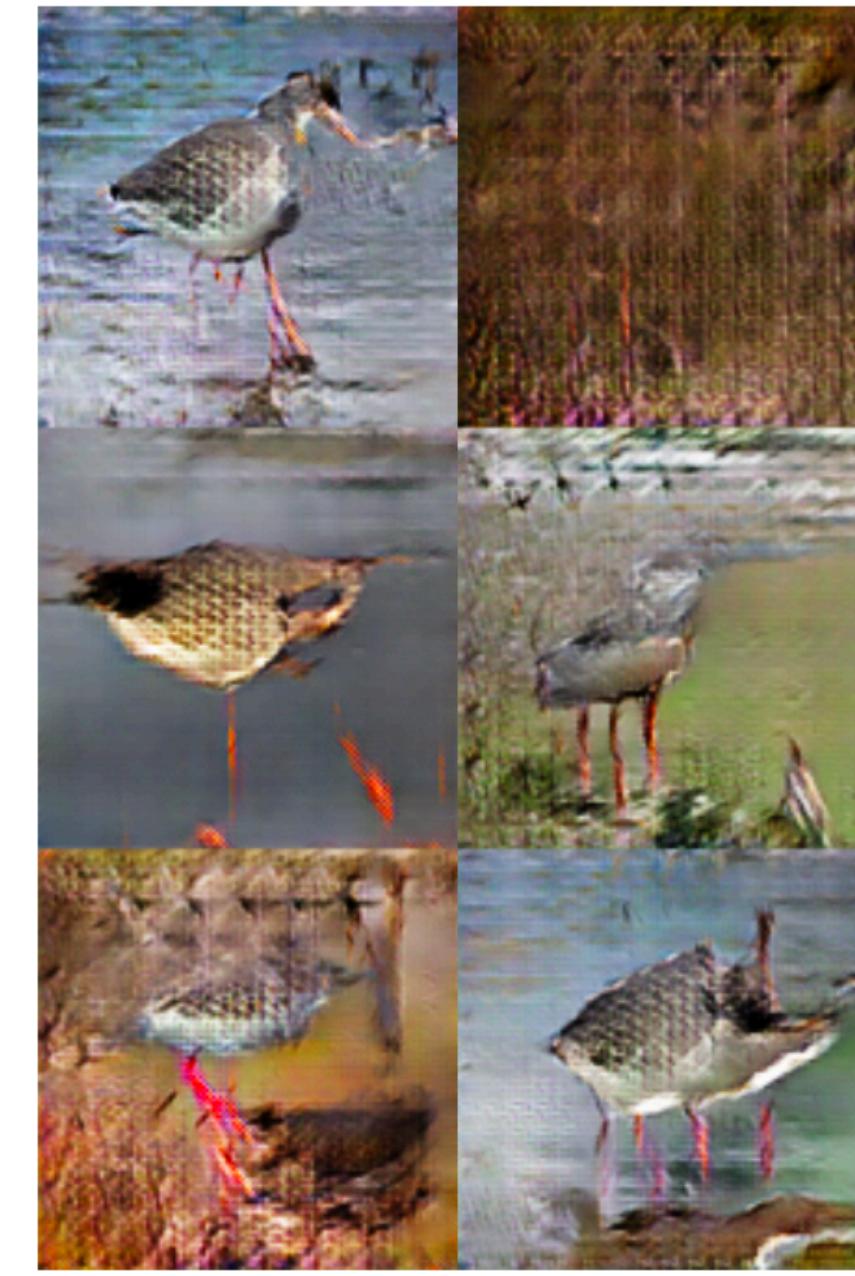
monarch butterfly



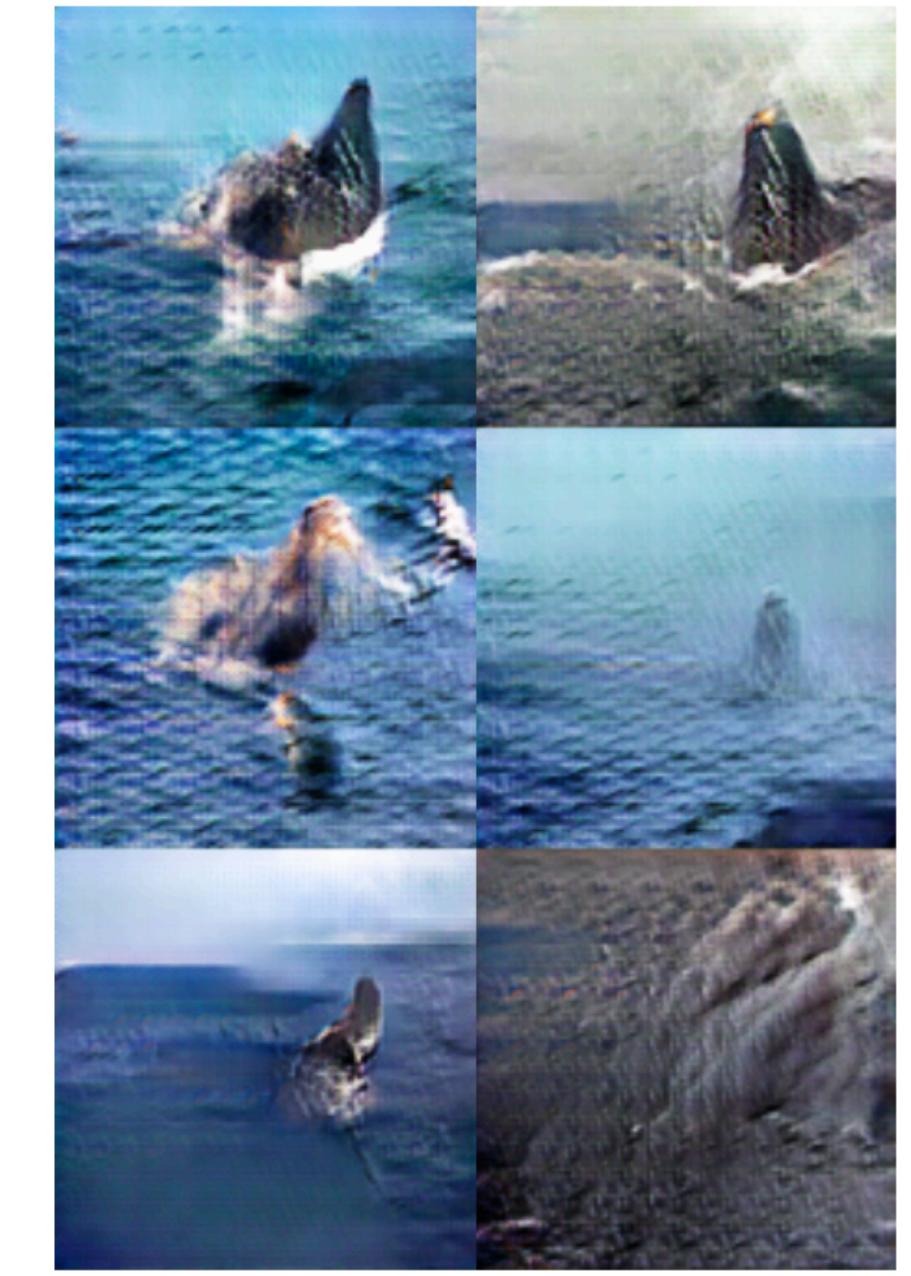
goldfinch



daisy



redshank



grey whale

LSGAN & ACGAN

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