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# Aim: Design a simple linear neural network model.

```
#include<iostream.h>
#include<conio.h>
void main()
{
clrscr();
float x,b,w,net;
float out;
cout<<"\n Enter the input X:";
cout<<"\n Enter the bias b:";
cout<<"\n Enter the weight W:";</pre>
cin>>w;
net=(w*x+b);
cout<<"\n______0UTPUT______";
cout<<"\n net+ "<<net<<endl;</pre>
if(net<0)
{ out=0;
}
else
if((net>=0)&&(net<=1))
{
out=net;
}
else
out=1;
cout<<"OUTPUT:"<<out<<endl;
getch();
}
```

```
Enter the input X:1

Enter the bias b:1

Enter the weight W:3

OUTPUT

net+ 4

OUTPUT:1
```

Aim: Calculate the output of the neural net using both binary and sigmoidal function.

```
#include<iostream.h>
#include<conio.h>
void main()
{
clrscr();
int i;
float inp[3] = {0.3,0.5,0.6};
float wght[3] ={0.2,0.1,-0.3};
float yin=0;
cout<<"The inputs are: \n";
for(i=0;i<3;i++)
{
cout<<inp[i];
cout<<"\n";
}
cout<<"The weights are: \n";</pre>
for(i=0;i<3;i++)
cout<<wght[i];
cout<<"\n";
  cout<<"***************************** \n";
  cout<<"\n the net input can be calculated as Yin= x1w1+.....+XnWn. \n";
  for(i=0;i<3;i++)
  yin= yin+inp[i]*wght[i];
  cout<<yin;
getch();
```

# Aim: Generate AND/NOT function using McCulloch-Pitts neural net.

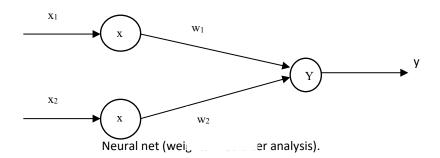
#### Solution:

In the case of ANDNOT function, the response is true if the first input is true and the second input is false. For all the other variations, the response is false. The truth table for ANDNOT function is given in Table below.

#### Truth Table:

<b>X</b> <sub>1</sub>	X <sub>2</sub>	у
0	0	0
0	1	0
1	0	1
1	1	0

The given function gives an output only when  $x_1 = 1$  and  $x_2 = 0$ . The weights have to be decided only after the analysis. The net can be represent as shown in figure below:



Case 1: Assume that both weights w<sub>1</sub> and w<sub>2</sub>. are excitatory, i.e.,

$$w_1 = w_2 = 1$$

Then for the four inputs calculate the net input using

$$y_{ij} = x_1 w_1 + x_2 w_2$$

#### For inputs

$$(1, 1), y_{ij} = 1 \times 1 + 1 \times 1 = 2$$

$$(1, 0), y_{ij} = 1 \times 1 + 0 \times 1 = 1$$

$$(0, 1), y_{ij} = 0 \times 1 + 1 \times 1 = 1$$

(0, 0), 
$$y_{ij} = 0 \times 1 + 0 \times 1 = 0$$

From the calculated net inputs, it is not possible to fire the neuron form input (1, 0) only. Hence, J-. weights are not suitable.

Assume one weight as excitatory and the other as inhibitory, i.e.,

$$w_1 = 1$$
,  $w_2 = -1$ 

Now calculate the net input. For the inputs

```
(1,1), y_{in} = 1 \times 1 + 1 \times -1 = 0
```

$$(1,0)$$
,  $y_{in} = 1 \times 1 + 0 \times -1 = 1$ 

$$(0,1)$$
,  $y_{in} = 0 \times 1 + 1 \times -1 = -1$ 

$$(0, 0), y_{in} = 0 \times 1 + 0 \times -1 = 0$$

From the calculated net inputs, now it is possible to fire the neuron for input (1, 0) only by fixing a threshold of 1, i.e.,  $\vartheta \ge 1$  for Y unit. Thus,

$$w_1 = 1, w_2 = -1; \vartheta \ge 1$$

Note: The value is calculated using the following:

 $\vartheta \ge nw - p$ 

 $\vartheta \ge 2 \times 1 - 1$ 

 $\vartheta \ge 1$ 

Thus, the output of neuron Y can be written as

y = f (y\_{in}) = { 
$$0 \ if \ y_{in} \geq 1 \\ 1 \ if \ y_{in} \leq 1$$

```
Code:
```

# -\*- coding: utf-8 -\*-

x1.append(ele1) x2.append(ele2)

```
Spyder Editor

This is a temporary script file.
"""

import numpy
# enter the no of inputs
num_ip = int(input("Enter the number of inputs : "))

#Set the weights with value 1
w1 = 1
w2 = 1

print("For the ", num_ip , " inputs calculate the net input using yin = x1w1 + x2w2 ")

x1 = []
x2 = []
for j in range(0, num_ip):
    ele1 = int(input("x1 = "))
    ele2 = int(input("x2 = "))
```

```
print("x1 = ",x1)
print("x2 = ",x2)
n = x1 * w1
m = x2 * w2
Yin = []
for i in range(0, num ip):
         Yin.append(n[i] + m[i])
print("Yin = ",Yin)
#Assume one weight as excitatory and the other as inhibitory, i.e.,
Yin = []
for i in range(0, num_ip):
         Yin.append(n1[i] - m1[i])
print("After assuming one weight as excitatory and the other as inhibitory Yin = ",Yin)
#From the calculated net inputs, now it is possible to fire the neuron for input (1, 0)
#only by fixing a threshold of 1, i.e., \theta \ge 1 for Y unit.
#Thus, w1 = 1, w2 = -1; \theta \ge 1
Y=[]
for i in range(0, num_ip):
  if(Yin[i]>=1):
    ele = 1
    Y.append(ele)
  if(Yin[i]<1):
    ele = 0
    Y.append(ele)
print("Y = ",Y)
```

```
Enter the number of inputs: 4
For the 4 inputs calculate the net input using yin = x1w1 + x2w2

x1 = 0

x2 = 0

x1 = 0

x2 = 1

x1 = 1

x2 = 0

x1 = 1

x2 = 1

x1 = [0, 0, 1, 1]

x2 = [0, 1, 0, 1]

y1 = [0, 1, 1, 2]

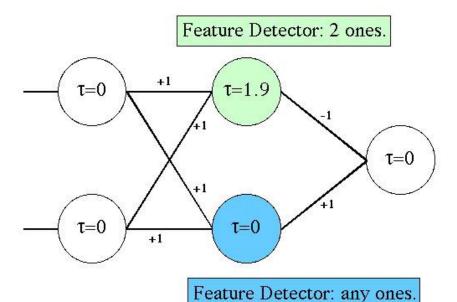
After assuming one weight as excitatory and the other as inhibitory Yin = [0, 1, -1, 0]

Y = [0, 1, 0, 0]

In [14]: |
```

## Aim: Generate XOR function using McCulloch-Pitts neural net.

# **XOR Network**



import numpy from matplotlib.colors import ListedColormap import matplotlib.pyplot as plt

```
def __init__(self, net_arch):
  numpy.random.seed(0)
  # Initialized the weights, making sure we also
  # initialize the weights for the biases that we will add later
  self.activity = tanh
  self.activity derivative = tanh derivative
  self.layers = len(net arch)
  self.steps per epoch = 1
  self.arch = net_arch
  self.weights = []
  # Random initialization with range of weight values (-1,1)
  for layer in range(self.layers - 1):
    w = 2*numpy.random.rand(net_arch[layer] + 1, net_arch[layer+1]) - 1
    self.weights.append(w)
def _forward_prop(self, x):
  y = x
  for i in range(len(self.weights)-1):
    activation = numpy.dot(y[i], self.weights[i])
    activity = self.activity(activation)
    # add the bias for the next layer
    activity = numpy.concatenate((numpy.ones(1), numpy.array(activity)))
    y.append(activity)
  # last laver
  activation = numpy.dot(y[-1], self.weights[-1])
  activity = self.activity(activation)
  y.append(activity)
  return y
def _back_prop(self, y, target, learning_rate):
  error = target - y[-1]
  delta vec = [error * self.activity derivative(y[-1])]
  # we need to begin from the back, from the next to last layer
  for i in range(self.layers-2, 0, -1):
    error = delta vec[-1].dot(self.weights[i][1:].T)
    error = error*self.activity derivative(y[i][1:])
    delta vec.append(error)
  # Now we need to set the values from back to front
  delta_vec.reverse()
  # Finally, we adjust the weights, using the backpropagation rules
  for i in range(len(self.weights)):
    layer = y[i].reshape(1, self.arch[i]+1)
```

```
delta = delta_vec[i].reshape(1, self.arch[i+1])
    self.weights[i] += learning_rate*layer.T.dot(delta)
#########
# parameters
# -----
# self: the class object itself
# data: the set of all possible pairs of booleans True or False indicated by the integers 1 or 0
# labels: the result of the logical operation 'xor' on each of those input pairs
########
def fit(self, data, labels, learning_rate=0.1, epochs=100):
  # Add bias units to the input layer -
  # add a "1" to the input data (the always-on bias neuron)
  ones = numpy.ones((1, data.shape[0]))
  Z = numpy.concatenate((ones.T, data), axis=1)
  for k in range(epochs):
    if (k+1) % 10000 == 0:
      print('epochs: {}'.format(k+1))
    sample = numpy.random.randint(X.shape[0])
    # We will now go ahead and set up our feed-forward propagation:
    x = [Z[sample]]
    y = self._forward_prop(x)
    # Now we do our back-propagation of the error to adjust the weights:
    target = labels[sample]
    self._back_prop(y, target, learning_rate)
#########
# the predict function is used to check the prediction result of
# this neural network.
#
# parameters
# -----
# self: the class object itself
# x:
      single input data
#########
def predict_single_data(self, x):
  val = numpy.concatenate((numpy.ones(1).T, numpy.array(x)))
  for i in range(0, len(self.weights)):
    val = self.activity(numpy.dot(val, self.weights[i]))
    val = numpy.concatenate((numpy.ones(1).T, numpy.array(val)))
  return val[1]
#########
# the predict function is used to check the prediction result of
# this neural network.
```

```
# parameters
  # -----
  # self: the class object itself
  # X:
         the input data array
  #########
  def predict(self, X):
    Y = numpy.array([]).reshape(0, self.arch[-1])
    for x in X:
      y = numpy.array([[self.predict_single_data(x)]])
      Y = numpy.vstack((Y,y))
    return Y
numpy.random.seed(0)
# Initialize the NeuralNetwork with
# 2 input neurons
#2 hidden neurons
#1 output neuron
nn = NeuralNetwork([2,2,1])
# Set the input data
X = numpy.array([[0, 0], [0, 1],
        [1, 0], [1, 1]])
# Set the labels, the correct results for the xor operation
y = numpy.array([0, 1,
         1, 0])
# Call the fit function and train the network for a chosen number of epochs
nn.fit(X, y, epochs=100000)
# Show the prediction results
print("Final prediction")
for s in X:
  print(s, nn.predict_single_data(s))
           epochs: 10000
           epochs: 20000
           epochs: 30000
           epochs: 40000
           epochs: 50000
           epochs: 60000
           epochs: 70000
           epochs: 80000
           epochs: 90000
           epochs: 100000
           Final prediction
           [0 0] 2.769390318381638e-05
           [0 1] 0.995154295769496
           [1 0] 0.9951532983339081
           [1 1] 2.7834280538588892e-05
```

Sign:\_\_\_

# Aim: Write a program to implement Hebb's rule.

```
#include<iostream>
using namespace std;
int main()
float wt,net,div,a,at,d,i,x,w,dw;
cout<<"consider a single neuron perceptron with a single i/p";</pre>
cin>>w;
cout<<"enter the learning coefficient";
for ( i=0;i<10;i++)
net = x+w;
if(wt<0)
a=0;
}
else
  a=1;
div=at+a+w;
w=w+div;
}
cout<<"i+1 in fraction are i"<<a<<"change in weight"<<dw<<"adjustment at="<<w;
}
 options | compilation | execution
 consider a single neuron perceptron with a single i/p2
 enter the learning coefficient12
 i+1 in fraction are i1change in weight0adjustment at=5i+1 in fraction are i1change in weight0adjustment at=11:
 Exit code: 0 (normal program termination)
```

## Aim: Write a program to implement delta rule

```
#include<iostream.h>
#include<conio.h>
void main()
clrscr( );
float input[3],d,weight[3],delta;
for(int i=0; i < 3; i++)
cout<<"\n initilize weight vector "<<i<<"\t";
cin>>input[i];
}
cout << ""\n enter the desired output\t";
cin>>d;
do {
del=d-a;
if(del < 0)
for(i=0; i<3; i++)
w[i]=w[i]-input[i];
else
if(del>0)
for(i=0;i<3;i++)
weight[i]=weight[i]+input[i];
for(i=0;i<3;i++)
{
val[i]=del*input[i];
weight[+1]=weight[i]+val[i];
cout<<"\value of delta is "<<del;
cout << "\n weight have been adjusted";
while (del \neq 0)
if(del=0)
cout << "\n output is correct";
```

# Aim: Write a program for linear separation.

You could imagine that you have two attributes describing am eddible object like a fruit for example: "sweetness" and "sourness"

We could describe this by points in a two-dimensional space. The x axis for the sweetness and the y axis for the sourness. Imagine now that we have two fruits as points in this space, i.e. an orange at position (3.5, 1.8) and a lemon at (1.1, 3.9).

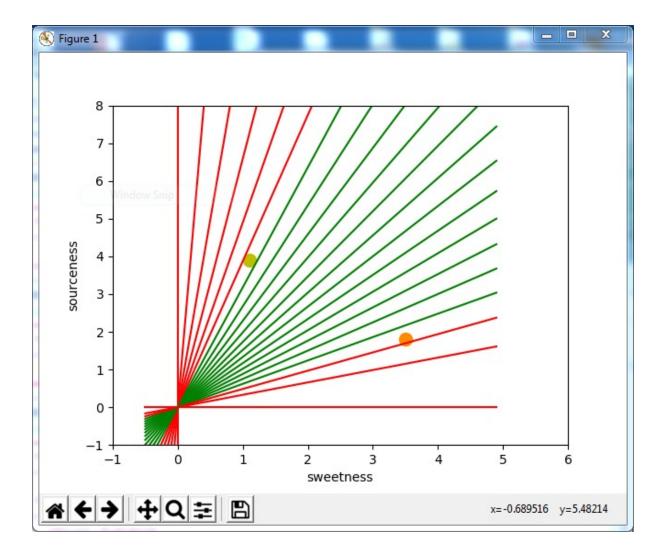
We could define dividing lines to define the points which are more lemon-like and which are more orange-like. The following program calculates and renders a bunch of lines. The red ones are completely unusable for this purpose, because they are not separating the classes. Yet, it is obvious that even the green ones are not all useful.

import numpy as np

```
import matplotlib.pyplot as plt
def create distance function(a, b, c):
  """ 0 = ax + by + c """
  def distance(x, y):
    """ returns tuple (d, pos)
       d is the distance
      If pos == -1 point is below the line,
      0 on the line and +1 if above the line
    .....
    nom = a * x + b * y + c
    if nom == 0:
       pos = 0
    elif (nom<0 and b<0) or (nom>0 and b>0):
       pos = -1
    else:
       pos = 1
    return (np.absolute(nom) / np.sqrt( a ** 2 + b ** 2), pos)
  return distance
points = [ (3.5, 1.8), (1.1, 3.9) ]
fig, ax = plt.subplots()
ax.set_xlabel("sweetness")
ax.set_ylabel("sourness")
ax.set_xlim([-1, 6])
```

```
Soft Computing Techniques
```

```
ax.set_ylim([-1, 8])
X = np.arange(-0.5, 5, 0.1)
colors = ["r", ""] # for the samples
size = 10
for (index, (x, y)) in enumerate(points):
  if index== 0:
    ax.plot(x, y, "o",
         color="darkorange",
         markersize=size)
  else:
    ax.plot(x, y, "oy",
         markersize=size)
step = 0.05
for x in np.arange(0, 1+step, step):
  slope = np.tan(np.arccos(x))
  dist4line1 = create_distance_function(slope, -1, 0)
  #print("x: ", x, "slope: ", slope)
  Y = slope * X
  results = []
  for point in points:
    results.append(dist4line1(*point))
  #print(slope, results)
  if (results[0][1] != results[1][1]):
    ax.plot(X, Y, "g-")
  else:
    ax.plot(X, Y, "r-")
plt.show()
```



# Aim: Write a program for Hopfield network model for associative memory.

The Hopfield model (226), consists of a network of N neurons, labeled by a lower index i, with  $1 \le i \le N$ . Similar to some earlier models (335; 304; 549), neurons in the Hopfield model have only two states. A neuron i is 'ON' if its state variable takes the value Si = +1 and 'OFF' (silent) if Si = -1. The dynamics evolves in discrete time with time steps  $\Delta t$ . There is no refractoriness and the duration of a time step is typically not specified. If we take  $\Delta t = 1$ ms, we can interpret Si(t) = +1 as an action potential of neuron i at time t. If we take  $\Delta t = 500$ ms, Si(t) = +1 should rather be interpreted as an episode of high firing rate.

Neurons interact with each other with weights wij. The input potential of neuron i, influenced by the activity of other neurons is

 $hi(t)=\sum jwijSj(t)$ .

The input potential at time *t* influences the probabilistic update of the state variable *Si* in the next time step:

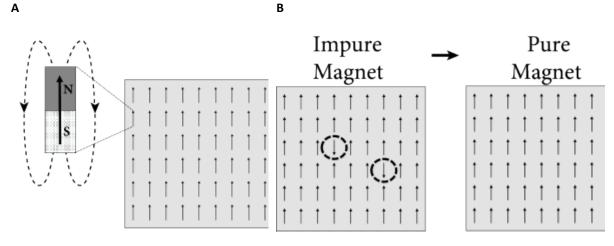
#### Prob{ $Si(t+\Delta t)=+1 \mid hi(t)$ }= $g(hi(t))=g(\sum jwijSj(t))$

where g is a monotonically increasing gain function with values between zero and one. A common choice is  $g(h)=0.5[1+\tanh(\beta h)]$  with a parameter  $\beta$ . For  $\beta\to\infty$ , we have g(h)=1 for h>0 and zero otherwise. The dynamics are therefore deterministic and summarized by the update rule

 $Si(t+\Delta t)=sgn[h(t)]$ 

For finite  $\theta$  the dynamics are stochastic. In the following we assume that in each time step all neurons are updated synchronously (parallel dynamics), but an update scheme where only one neuron is updated per time step is also possible.

The aim of this section is to show that, with a suitable choice of the coupling matrix *wij* memory items can be retrieved by the collective dynamics defined in Eq. (17.3), applied to all *N* neurons of the network. In order to illustrate how collective dynamics can lead to meaningful results, we start, in Section 17.2.1, with a detour through the physics of magnetic systems. In Section 17.2.2, the insights from magnetic systems are applied to the case at hand, i.e., memory recall.



**Fig.** 17.5: Physics of ferromagnets. **A**. Magnetic materials consists of atoms, each with a small magnetic moment, here visualized as an arrow, a symbol for a magnetic needle. At low temperature, all magnetic needles are aligned. Inset: Field lines around one of the magnetic needles. **B**. At high temperature, some of the needles are misaligned (dashed circles). Cooling the magnet leads to a spontaneous alignment and reforms a pure magnet; schematic figure.

#### %matplotlib inline

from neurodynex.hopfield\_network import network, pattern\_tools, plot\_tools

# **Soft Computing Techniques** pattern\_size = 5 # create an instance of the class HopfieldNetwork hopfield\_net = network.HopfieldNetwork(nr\_neurons= pattern\_size\*\*2) # instantiate a pattern factory factory = pattern\_tools.PatternFactory(pattern\_size, pattern\_size) # create a checkerboard pattern and add it to the pattern list checkerboard = factory.create\_checkerboard() pattern\_list = [checkerboard] # add random patterns to the list pattern\_list.extend(factory.create\_random\_pattern\_list(nr\_patterns=3, on\_probability=0.5)) plot\_tools.plot\_pattern\_list(pattern\_list) # how similar are the random patterns and the checkerboard? Check the overlaps overlap\_matrix = pattern\_tools.compute\_overlap\_matrix(pattern\_list) plot\_tools.plot\_overlap\_matrix(overlap\_matrix) # let the hopfield network "learn" the patterns. Note: they are not stored # explicitly but only network weights are updated! hopfield\_net.store\_patterns(pattern\_list) # create a noisy version of a pattern and use that to initialize the network noisy\_init\_state = pattern\_tools.flip\_n(checkerboard, nr\_of\_flips=4) hopfield\_net.set\_state\_from\_pattern(noisy\_init\_state) # from this initial state, let the network dynamics evolve. states = hopfield\_net.run\_with\_monitoring(nr\_steps=4) # each network state is a vector. reshape it to the same shape used to create the patterns.

states\_as\_patterns = factory.reshape\_patterns(states)

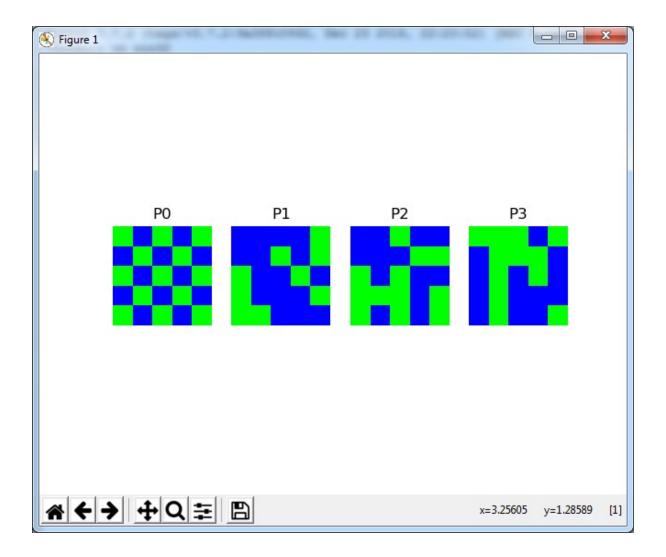
plot\_tools.plot\_state\_sequence\_and\_overlap(states\_as\_patterns,

# plot the states of the network

suptitle="Network dynamics")

reference\_idx=0,

pattern\_list,



# Aim: Write a program to implement membership and identity operators in, not in.

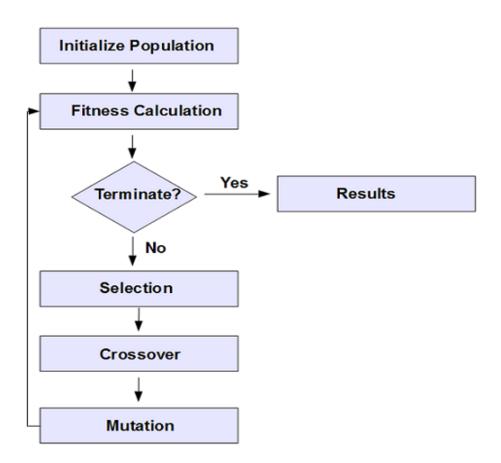
```
# Python program to illustrate
# Finding common member in list
# without using 'in' operator
# Define a function() that takes two lists
def overlapping(list1,list2):
        c=0
        d=0
        for i in list1:
                 c+=1
        for i in list2:
                 d+=1
        for i in range(0,c):
                 for j in range(0,d):
                         if(list1[i]==list2[j]):
                                  return 1
        return 0
list1=[1,2,3,4,5]
list2=[6,7,8,9]
if(overlapping(list1,list2)):
        print("overlapping")
else:
        print("not overlapping")
 === RESTART: C:/Users/yadne/AppData/Local/Programs/Python/Python38-32,
 not overlapping
 >>>
```

```
# Python program to illustrate
# Finding common member in list
# without using 'in' operator
# Define a function() that takes two lists
def overlapping(list1,list2):
        c=0
        d=0
        for i in list1:
                 c+=1
        for i in list2:
                 d+=1
        for i in range(0,c):
                 for j in range(0,d):
                          if(list1[i]==list2[j]):
                                   return 1
        return 0
list1=[1,2,3,4,5]
list2=[6,7,8,9]
if(overlapping(list1,list2)):
        print("overlapping")
else:
        print("not overlapping")
 === kE51Ak1: C:/Users/yaqne/AppData/Loc
 not overlapping
 >>>
```

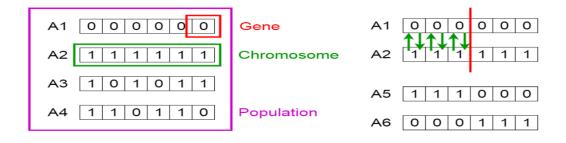
# Aim: Write a program to implement membership and identity operators is, is not.

```
# Python program to illustrate the use
# of 'is' identity operator
x = 5
if (type(x) is int):
       print ("true")
else:
       print ("false")
x = 5
if (type(x) is int):
         print ("true")
else:
          print ("false")
>>>
>>>
# Python program to illustrate the
# use of 'is not' identity operator
x = 5.2
if (type(x) is not int):
       print ("true")
else:
       print ("false")
x = 5.2
if (type(x) is not int):
         print ("true")
else:
          print ("false")
 true
>>>
```

# Aim: Write a program to implement Simple genetic Algorithm.



# Genetic Algorithms



import random

# Number of individuals in each generation POPULATION\_SIZE = 100

# Valid genes GENES = '''abcdefghijklmnopqrstuvwxyzABCDEFGHIJKLMNOP

```
QRSTUVWXYZ 1234567890, .-;:_!"#%&/()=?@${[]}'"
# Target string to be generated
TARGET = "I love GeeksforGeeks"
class Individual(object):
  Class representing individual in population
  def __init__(self, chromosome):
    self.chromosome = chromosome
    self.fitness = self.cal_fitness()
  @classmethod
  def mutated genes(self):
    create random genes for mutation
    global GENES
    gene = random.choice(GENES)
    return gene
  @classmethod
  def create gnome(self):
    create chromosome or string of genes
    global TARGET
    gnome_len = len(TARGET)
    return [self.mutated_genes() for _ in range(gnome_len)]
  def mate(self, par2):
    Perform mating and produce new offspring
    # chromosome for offspring
    child chromosome = []
    for gp1, gp2 in zip(self.chromosome, par2.chromosome):
      # random probability
      prob = random.random()
      # if prob is less than 0.45, insert gene
      # from parent 1
      if prob < 0.45:
        child_chromosome.append(gp1)
      # if prob is between 0.45 and 0.90, insert
      # gene from parent 2
      elif prob < 0.90:
        child_chromosome.append(gp2)
      # otherwise insert random gene(mutate),
      # for maintaining diversity
      else:
        child_chromosome.append(self.mutated_genes())
```

```
# create new Individual(offspring) using
    # generated chromosome for offspring
    return Individual(child_chromosome)
  def cal_fitness(self):
    Calculate fittness score, it is the number of
    characters in string which differ from target
    string.
    global TARGET
    fitness = 0
    for gs, gt in zip(self.chromosome, TARGET):
      if gs != gt: fitness+= 1
    return fitness
# Driver code
def main():
  global POPULATION_SIZE
  #current generation
  generation = 1
  found = False
  population = []
  # create initial population
  for _ in range(POPULATION_SIZE):
        gnome = Individual.create_gnome()
        population.append(Individual(gnome))
  while not found:
    # sort the population in increasing order of fitness score
    population = sorted(population, key = lambda x:x.fitness)
    # if the individual having lowest fitness score ie.
    # 0 then we know that we have reached to the target
    # and break the loop
    if population[0].fitness <= 0:
      found = True
      break
    # Otherwise generate new offsprings for new generation
    new_generation = []
    # Perform Elitism, that mean 10% of fittest population
    # goes to the next generation
    s = int((10*POPULATION SIZE)/100)
    new_generation.extend(population[:s])
    # From 50% of fittest population, Individuals
    # will mate to produce offspring
    s = int((90*POPULATION_SIZE)/100)
    for in range(s):
      parent1 = random.choice(population[:50])
```

```
parent2 = random.choice(population[:50])
    child = parent1.mate(parent2)
    new_generation.append(child)
   population = new generation
   print("Generation: {}\tString: {}\tFitness: {}".\
     format(generation,
     "".join(population[0].chromosome),
     population[0].fitness))
   generation += 1
 print("Generation: {}\tString: {}\tFitness: {}".\
    format(generation,
    "".join(population[0].chromosome),
    population[0].fitness))
if __name__ == '__main__':
 main()
                                                -- KESIAKI: C:/USEI:
Generation: 1 String: 5#idvR pnw-LF@i]q@Q. Fitness: 18
Generation: 2 String: 5 _tvR pwd-LFcNFGXQ.
Generation: 3 String: 2 JNv#1Fs/2s@sA&euRn
                                                   Fitness: 17
                                                   Fitness: 16
Generation: 4 String: 2 JNv#1Fs/2s@sA&euRn
                                                   Fitness: 16
               String: U LdvR /u/-sG@A4eliv
Generation: 5
                                                  Fitness: 15
                 String: 5 LXvz Mw8-sf,4,eXQ.
Generation: 6
                                                   Fitness: 14
               String: IXLn}n _e;ksC@iGeQ,(
Generation: 7
                                                   Fitness: 13
Generation: 8 String: I Lnvk _efks@@ileQ,v
                                                  Fitness: 12
                 String: I Lnvk _efks@@ileQ,v
Generation: 9
                                                   Fitness: 12
Generation: 10 String: I Lnvk
                                  efks@@ileQ,v
                                                   Fitness: 12
Generation: 11 String: C Pnvn MeK sfoFGe&,F
                                                   Fitness: 11
Generation: 12
                String: I ldv, Wz0?sfo Ge@k7
                                                  Fitness: 10
Generation: 13
                 String: I ldvn Ye0ksfoiGegQ(
                                                   Fitness:
Generation: 14 String: I A-vn Yh; ksfo; Gegks
                                                   Fitness: 8
Generation: 15 String: I A-vn Yh;ksfo;Gegks
                                                   Fitness: 8
Generation: 16
                String: I A-vn Yh;ksfo;Gegks
                                                   Fitness:
Generation: 17
                 String:
                         I L[v/ GeVksfmUGeQks
                                                   Fitness:
Generation: 18 String: I L[v/ GeVksfmUGeQks
                                                   Fitness: 7
                String: I L[v/ GeVksfmUGeQks
Generation: 19
                                                   Fitness: 7
                 String: I L[v/ GeVksfmUGeQks
Generation: 20
                                                   Fitness:
Generation: 21
                String: I 1-vK Ge; ksfoUGeLks
                                                   Fitness: 6
Generation: 22 String: I 1-vK Ge;ksfoUGeLks
                                                   Fitness: 6
Generation: 23
                 String: I gove G=5ksfo;GeQks
                                                   Fitness:
Generation: 24
                 String: I gove G=5ksfo;GeQks
                                                   Fitness:
Generation: 25
                String: I gove G=5ksfo;GeQks
                                                   Fitness: 5
Generation: 26
                String: I gove G=5ksfo;GeQks
                                                   Fitness: 5
Generation: 27
                 String: I gove G=5ksfo; GeQks
                                                   Fitness:
Generation: 28
                String: I gove G=5ksfo;GeQks
                                                   Fitness: 5
Generation: 29
                String: I love Ge0ksfoUGeQks
                                                   Fitness:
Generation: 30
                String: I love Ge0ksfoUGeQks
                                                   Fitness:
Generation: 31
                 String: I love Ge0ksfoUGeQks
                                                   Fitness:
Generation: 32
                String: I love Ge0ksfoUGeQks
                                                   Fitness: 4
Generation: 33
                String: I love Ge0ksfoUGeQks
                                                   Fitness: 4
Generation: 34
                 String: I love Ge0ksfoUGeQks
                                                   Fitness:
Generation: 35 String: I love GeOksfoUGeQks
                                                   Fitness: 4
Generation: 36 String: I love Ge0ksfoUGeQks
                                                   Fitness: 4
Generation: 37
                 String: I love GeOksfoUGeOks
                                                   Fitness:
                                                   Fitness:
Generation: 38
                 String: I love Ge2ksfo; GeCks
Generation: 39 String: I love Ge2ksfo; GeCks
                                                   Fitness:
Generation: 40 String: I love Ge2ksfo;GeCks
                                                  Fitness: 3
                                                             Sign:
```