apropl.r

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```
#!/usr/bin/r
# For different types of functions, different basis sets may be appropriate.
set.seed(123)
A1ps \leftarrow c(mp = 12.5, mc = 12.3, md = 12.4)
A1ps
##
   mp mc
## 12.5 12.3 12.4
A2ps \leftarrow c(pm = 12.5, pm = 12.3, pm = 12.4)
A2ps
   pm pm pm
## 12.5 12.3 12.4
# ordered different value compared fireworks update laptop
diff(A1ps >= A2ps)
## mc md
## 0 0
# Polynomials are often used, and there are some standard sets of orthogonal
# polynomials, such as Jacobi, Hermite, and so on.
poly(A1ps, A2ps, degree = 1, coefs = NULL, raw = FALSE, simple = FALSE)
##
                1.0
                              0.1
## mp 7.071068e-01 7.071068e-01
## mc -7.071068e-01 -7.071068e-01
## md 9.813078e-17 9.813078e-17
## attr(,"degree")
## [1] 1 1
## attr(,"coefs")
## attr(,"coefs")[[1]]
## attr(,"coefs")[[1]]$alpha
## [1] 12.4
##
## attr(,"coefs")[[1]]$norm2
## [1] 1.00 3.00 0.02
```

```
##
##
## attr(,"coefs")[[2]]
## attr(,"coefs")[[2]]$alpha
## [1] 12.4
##
## attr(,"coefs")[[2]]$norm2
## [1] 1.00 3.00 0.02
##
##
## attr(,"class")
## [1] "poly"
              "matrix"
# For periodic functions especially, orthogonal trigonometric
# functions are useful.
trigamma(A1ps)
##
                      mc
## 0.08328522 0.08469517 0.08398428
trigamma(A2ps)
##
           pm
                      pm
## 0.08328522 0.08469517 0.08398428
# 2.2.6 Approximation of Vectors In high-dimensional vector spaces, it is often
# useful to approximate a given vector in terms of vectors from a lower
# dimensional space.
cov(A1ps, A2ps)
## [1] 0.01
\# Suppose, for example, that V IR n is a vector space of dimension k
# (necessarily, k n) and x is a given n-vector.
k = 5
n = 1
if (k < n) {
    print(k < n)
} else {
  vector(mode = "logical", length = OL)
## logical(0)
# pipelines type procedure pass checkup method
# buffer lines ...
# We wish to determine a vector x in V that approximates x.
Vx \leftarrow c(c(runif(n, min = 0, max = 1), open = 1,
             encoding = getOption("A2ps")))
٧x
```

```
##
                  open
## 0.2875775 1.0000000
# Optimally of the Fourier Coefficients
googledrive::as_id("http://a2ps.vx")
## [1] NA
## attr(,"class")
## [1] "drive_id"
attr(A2ps, which = "http://a2ps.vx", exact = "http://a2ps.vx")
## NULL
drop(n + 1)
## [1] 2
window(k * n)
## [1] 5
## attr(,"tsp")
## [1] 1 1 1
attr(A2ps, which = "http://a2ps.vx", exact = "http://a2ps.vx/tse")
## NULL
# One obvious criterion would be based on a norm of the difference of the given
# vector and the approximating vector.
outer(A2ps, A1ps, FUN = "*")
##
         mp
                mc
## pm 156.25 153.75 155.00
## pm 153.75 151.29 152.52
## pm 155.00 152.52 153.76
# lollipop val breadcrumb water
loll \leftarrow c(pop = 2.4, bread = 2.4, water = 2.4)
1011
##
     pop bread water
##
     2.4 2.4 2.4
# This difference is a truncation error. Let u\ 1 , . . . , u\ k be an
# orthonormal basis set for V, and let
u1 <- trunc(loll, A1ps)
##
    pop bread water
##
             2
       2
```

```
# where the c i are the Fourier coefficients of x, x, u i . Now l
# et v = a \ 1 \ u \ 1 + \cdot \cdot \cdot \cdot + a \ k \ u \ k be any other vector in V, and consider
xx <- c(from = u1, to = loll, strict = TRUE)
##
     from.pop from.bread from.water
                                         to.pop
                                                   to.bread
                                                              to.water
                                                                           strict
##
          2.0
                     2.0
                                            2.4
                                                                   2.4
                                 2.0
                                                        2.4
                                                                               1.0
# Therefore we have x x v, and so x is the best approximation of
# x with respect to the Euclidean norm in the k-dimensional vector space V.
if (xx != xx || xx != xx){
    c(xx) + spacetime::geometry(obj = u1)
}
хx
     from.pop from.bread from.water
##
                                         to.pop
                                                  to.bread to.water
                                                                           strict
          2.0
                     2.0
                                            2.4
                                                       2.4
                                                                   2.4
                                                                               1.0
# Choice of the Best Basis Subset
# Now, posing the problem another way, we may seek the best k-dimensional
# subspace of IR n from which to choose an approximating vector.
IR <- subset.default(xx, missing(u1), A2ps)</pre>
## named numeric(0)
# This question
\# is not well-posed (because the one-dimensional vector space determined by x
# is the solution), but we can pose a related interesting question: suppose we
# have a Fourier expansion of x in terms of a set of n orthogonal basis vectors,
\# u 1 , . . . , u n , and we want to choose the "best" k basis vectors from this
\# set and use them to form an approximation of x.
k = n
un <- c(k, color = 99, conf.level = 0.95,
             std = 12, margin = c(1, 2),
             space = 0.2, main = NULL, mfrow = NULL, mfcol = NULL)
ıın
##
                   color conf.level
                                            std
                                                   margin1
                                                               margin2
                                                                             space
##
         1.00
                   99.00
                                0.95
                                          12.00
                                                       1.00
                                                                  2.00
                                                                             0.20
# (This restriction of the problem is
# equivalent to choosing a coordinate system.)
later::create loop(autorun = FALSE)
## <event loop>
   id: 1
# We see the solution immediately
# from inequality (2.42): we choose the k u i s corresponding to the k
# largest c i s
# in absolute value, and we take
call("k", u1, c(i = 2.42))
```

```
## k(c(pop = 2, bread = 2, water = 2), c(i = 2.42))
call("n", xx)
## n(c(from.pop = 2, from.bread = 2, from.water = 2, to.pop = 2.4,
## to.bread = 2.4, to.water = 2.4, strict = 1))
outer(n, xx, FUN = "*")
        from.pop from.bread from.water to.pop to.bread to.water strict
## [1,]
              2
                         2
                                    2
                                         2.4
                                                  2.4
                                                            2.4
# 2.2.7 Flats, Acne Spaces, and Hyperplanes
# Given an n-dimensional vector space of order n, IR n for example, consider a
# system of m linear equations in the n-vector variable x,
Acne \leftarrow c(n, k, A2ps)
Acne
##
              pm pm pm
## 1.0 1.0 12.5 12.3 12.4
m = 12
n = 1
# where c 1, . . . , c m are linearly independent n-vectors (and hence m n).
c1 \leftarrow m < n
c1
## [1] FALSE
# The set of points defined by these linear equations is called a rat.
PlantGrowth
     weight group
##
## 1
       4.17 ctrl
       5.58 ctrl
## 2
## 3
       5.18 ctrl
## 4
       6.11 ctrl
## 5
       4.50 ctrl
       4.61 ctrl
## 6
## 7
       5.17 ctrl
## 8
       4.53 ctrl
## 9
       5.33 ctrl
## 10
       5.14 ctrl
## 11
       4.81 trt1
## 12
       4.17 trt1
       4.41 trt1
## 13
## 14
       3.59 trt1
## 15
       5.87 trt1
```

16

3.83 trt1

17 6.03 trt1

```
## 18
       4.89 trt1
## 19
       4.32 trt1
## 20
       4.69 trt1
## 21
       6.31 trt2
## 22
       5.12 trt2
## 23
       5.54 trt2
## 24
       5.50 trt2
## 25
       5.37 trt2
## 26
       5.29 trt2
## 27
       4.92 trt2
## 28
       6.15 trt2
## 29
       5.80 trt2
## 30
       5.26 trt2
```