

## **ORBITAL MECHANICS: ASSIGNMENT PRESENTATION**



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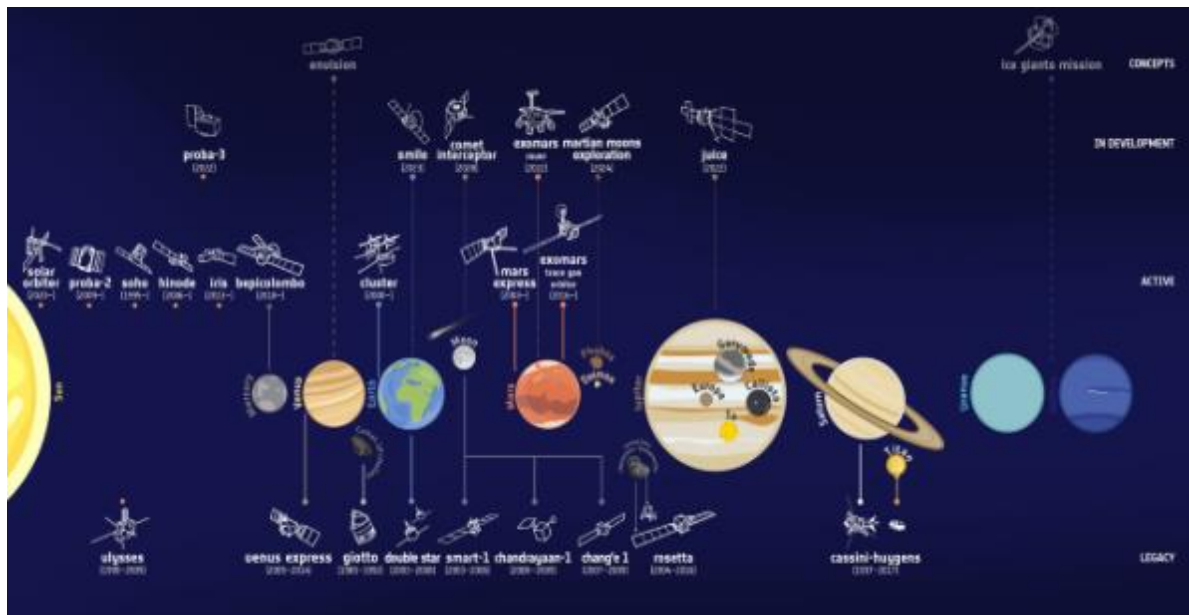
**David Reina**



## MISSION DESCRIPTION:

- Departure planet: Jupiter
- Fly-by planet: Earth
- Arrival planet: Mercury

Figure of merit:  $\Delta v_{tot}$





## DESIGN PROCESS: CONSTRAINTS

- Earliest departure: 01/06/2030
- Latest arrival: 01/06/2070
- Fly-by minimum altitude:  $h_{min} = 200 \text{ Km}$





## DESIGN PROCESS: ASSUMPTIONS

- Patched conics method
- Other planets ignored
- SRP neglected
- Initial heliocentric orbit equal to the one of the departure planet
- Final heliocentric orbit equal to the one of the arrival planet



## PRELIMINARY ESTIMATIONS

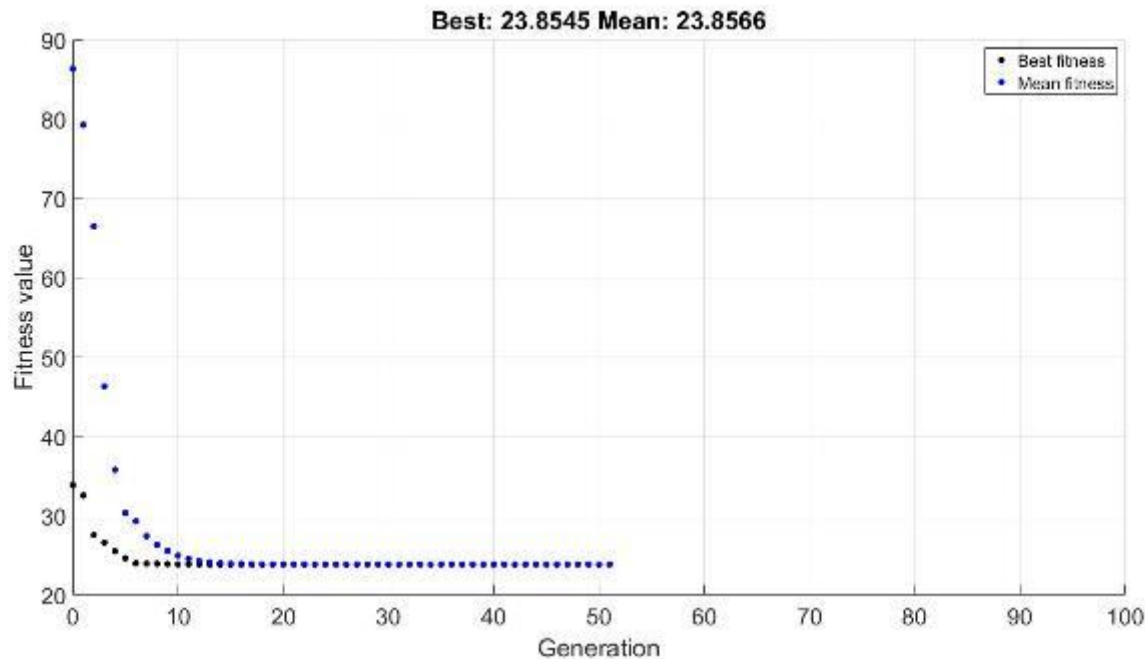
Planets	Relative synodic period
Jupiter and Earth	398.8699 days
Earth and Mercury	115.8774 days
Jupiter and Mercury	89.7916 days

Time window	Earliest date	Latest date
Departure	01/06/2030	13/04/2042
Fly-by	29/04/2032	31/01/2045
Arrival	12/07/2032	17/03/2046



## FIRST OPTIMIZATION: GENETIC ALGORITHM

- Heuristic method for search of the minimum
- Population size: 1000
- Number of generations: 100
- Number of iterations: 5





## SECOND OPTIMIZATION:

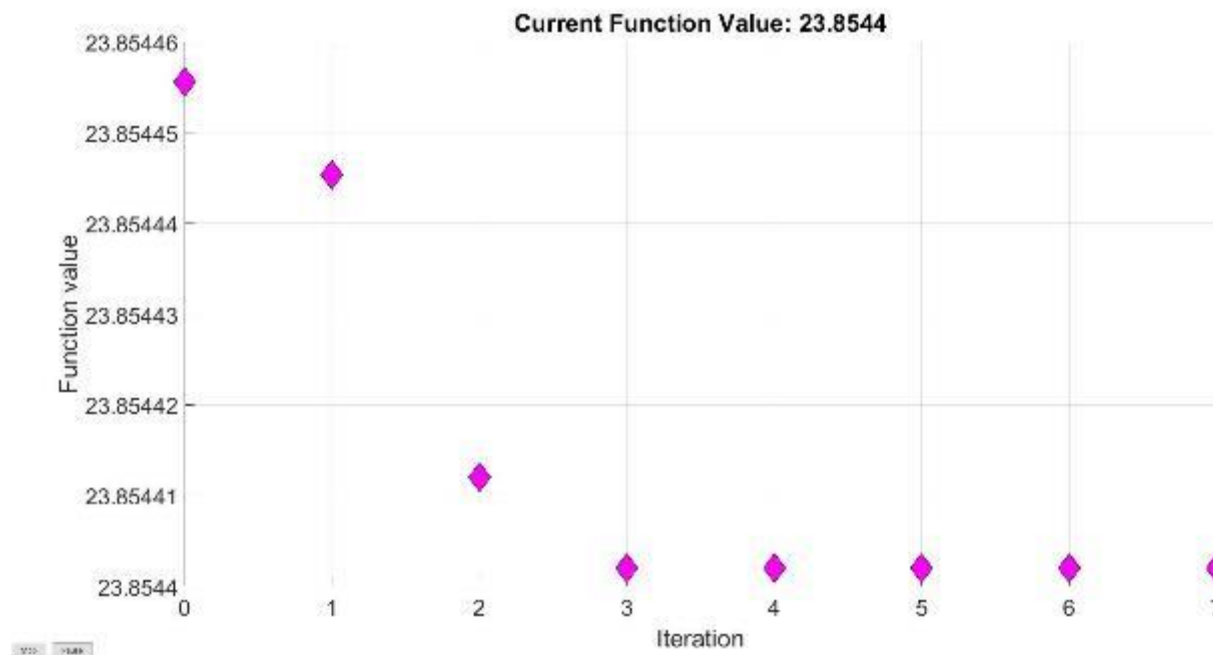
- Refinement of the minimum with:
  1. Gradient-based Optimizer
  2. Grid Search Method

D.O.F	Lower boundary	Upper boundary
Departure Date	$t_{1,ga} - \delta_1$	$t_{1,ga} + \delta_1$
Fly-by Date	$t_{2,ga} - \delta_2$	$t_{2,ga} + \delta_2$
Arrival Date	$t_{3,ga} - \delta_3$	$t_{3,ga} + \delta_3$



## SECOND OPTIMIZATION: GRADIENT-BASED OPTIMIZER

- Search for the minimum of non-linear constrained multi-variable functions
- Initial guess:  $x_0 = t_{ga} = \begin{Bmatrix} t_{1,ga} \\ t_{2,ga} \\ t_{3,ga} \end{Bmatrix}$







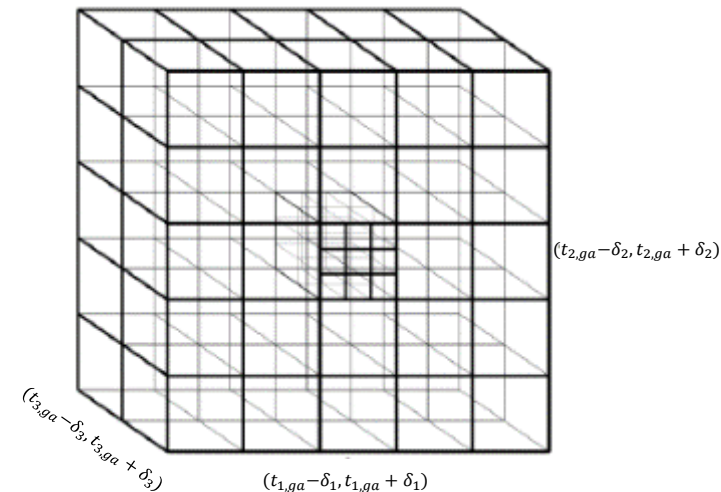
## SECOND OPTIMIZATION: GRID SEARCH METHOD

Three degrees of freedom:

- Departure date
- Fly-by date
- Arrival date

Three nested loop cycles that evaluate the minimum  $\Delta v$ :

```
for all possible departure dates around  $t_{1,ga}$ 
  for all possible fly-by dates around  $t_{2,ga}$ 
    for all possible arrival dates around  $t_{3,ga}$ 
      calculation of the total  $\Delta v$  of the transfer
    end
  end
end
```



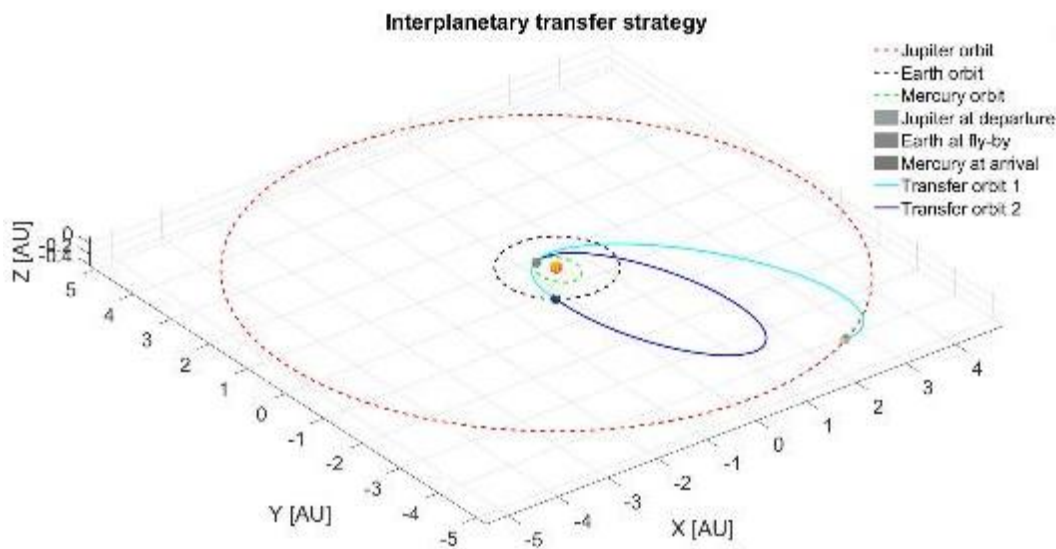


## OPTIMIZATION RESULTS

Method	$t_1$ [ <i>mjd2000</i> ]	$t_2$ [ <i>mjd2000</i> ]	$t_3$ [ <i>mjd2000</i> ]	$\Delta t$ [ <i>days</i> ]	$\Delta v$ [ <i>km/s</i> ]	$t_{comp}$ [ <i>s</i> ]
<b>G.A.</b>	11705.8494	12903.3103	13949.6986	2243.8492	23.8545	104.4523
<b>fmincon</b>	11705.8483	12903.3100	13949.6979	2243.8496	23.8544	0.4215
<b>Grid search</b>	11881.0989	12915.5913	13952.7313	2071.6323	23.6279	396.3988



## RESULTS: TOTAL TRANSFER

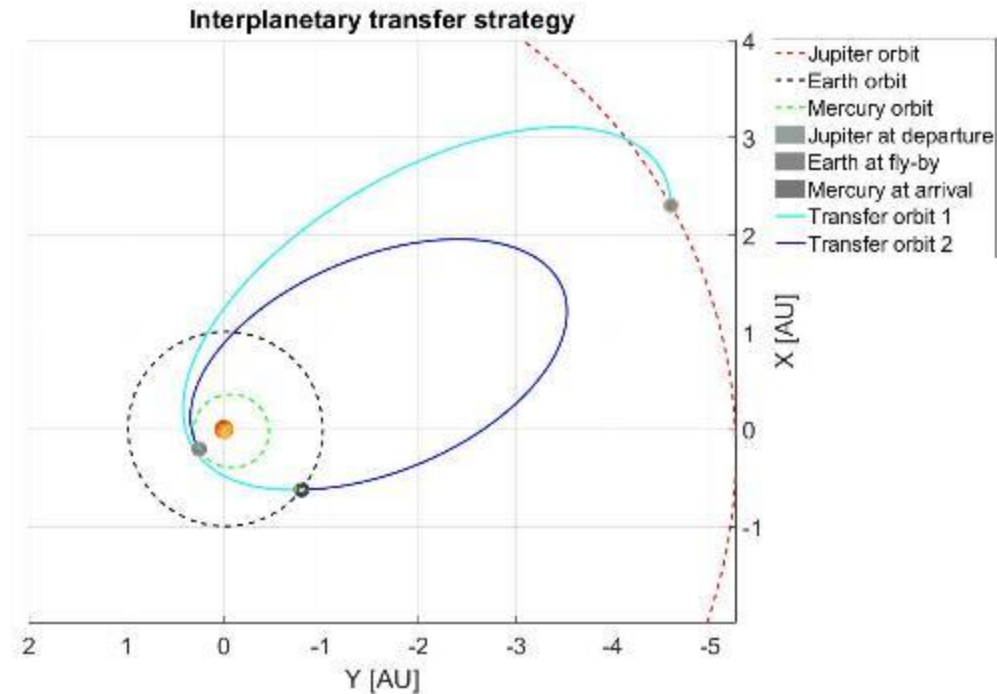


Manoeuvre	$\Delta v$ cost [km/s]
Injection in the first transfer leg	8.8694
Powered gravity assist	0.0063
Injection in the final orbit	14.7523
<b>Total transfer</b>	<b>23.6279</b>

Departure date	12/07/2032 – 14:22:30
Fly-by date	13/05/2035 – 02:11:27
Arrival date	15/03/2038 – 05:33:01



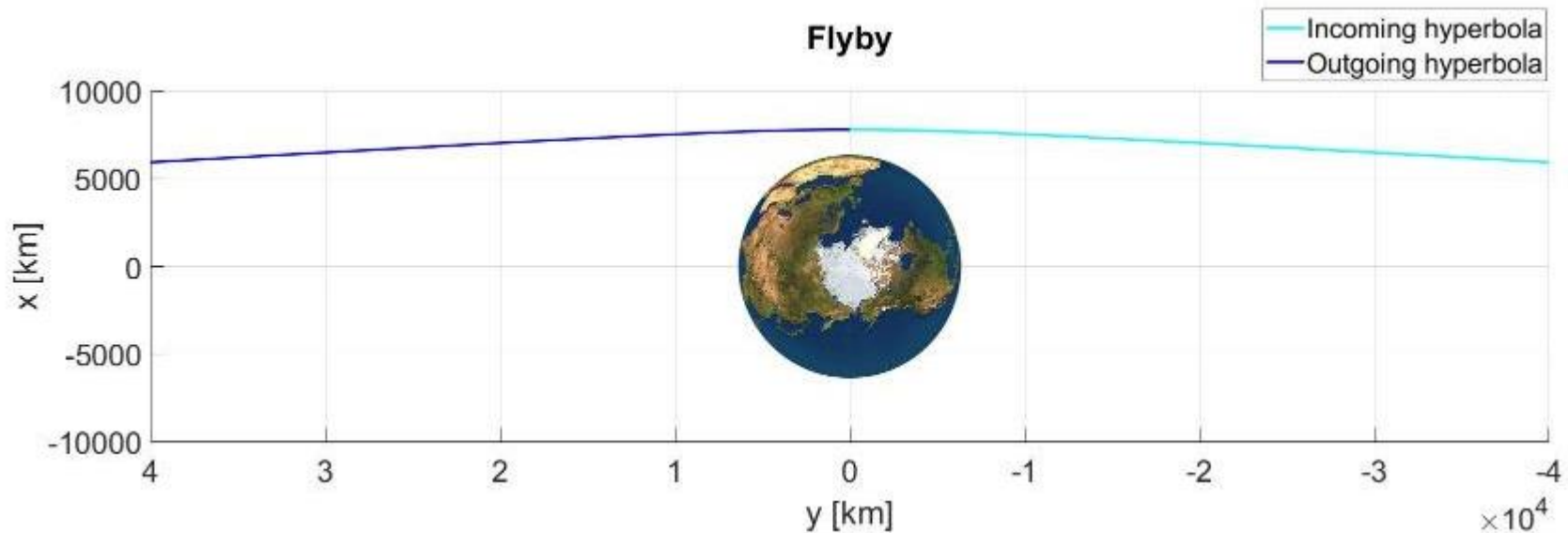
## RESULTS: TOTAL TRANSFER



	$a$ [km]	$e$ [-]	$i$ [deg]	$\Omega$ [deg]	$\omega$ [deg]	$\vartheta_i$ [deg]	$\vartheta_f$ [deg]
First transfer orbit	$4.1868 \cdot 10^8$	0.8680	0.3935	52.1902	68.5723	175.8502	111.4277
Second transfer orbit	$3.0779 \cdot 10^8$	0.8433	7.0936	52.1902	60.7631	119.2369	15.6349



## RESULTS: POWERED GRAVITY ASSIST



$$\vec{V}^+ = \begin{Bmatrix} 1.5826 \\ -37.9043 \\ -0.1682 \end{Bmatrix} [km/s]$$

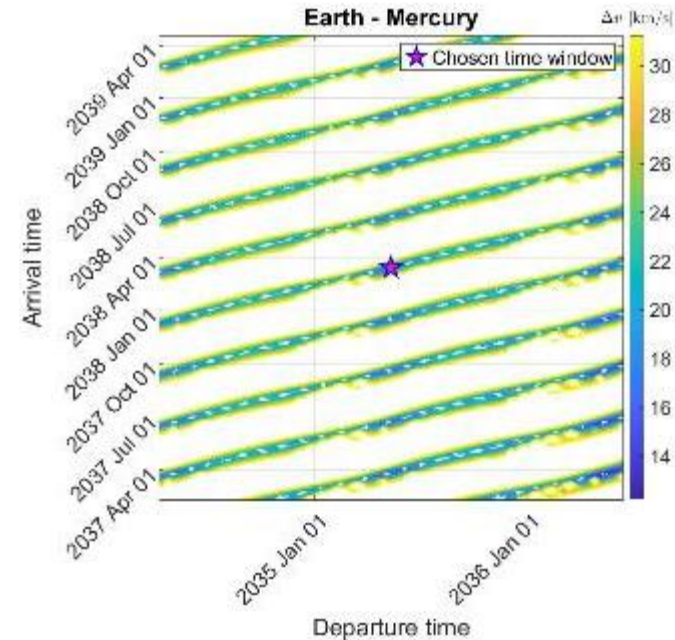
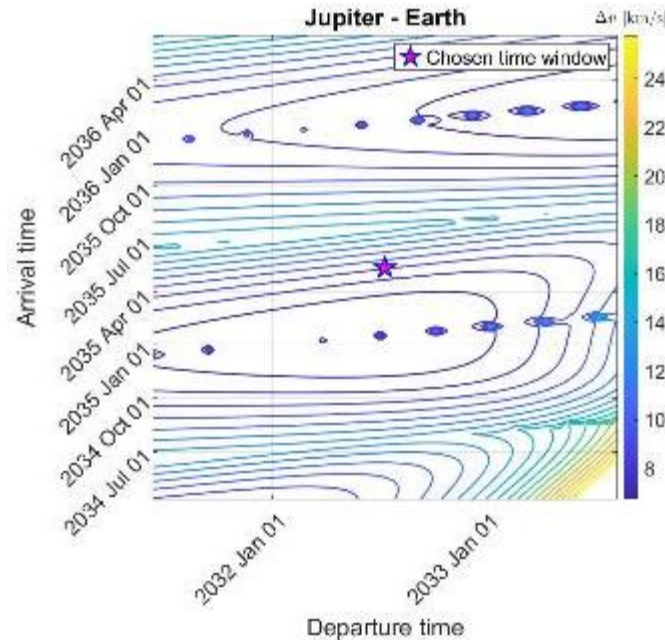
$$\vec{V}^- = \begin{Bmatrix} 0.3833 \\ -36.2912 \\ -2.8063 \end{Bmatrix} [km/s]$$

$$\Delta v_{flyby} = \|\vec{V}^+ - \vec{V}^-\| = 3.3166 km/s$$

	$h_p$ [km]	$v_p$ [km/s]	$v_\infty$ [km/s]	$e$ [–]	$a$ [km]
Incoming hyperbola	1127.0321	30.7293	29.0206	17.4983	–473.2876
Outgoing hyperbola	1127.0321	30.7356	29.0272	17.5059	–473.0710



## DISCUSSION



- Most expensive manoeuvre: injection in Mercury orbit, due to very different orbit inclination.
- Least expensive manoeuvre: powered gravity assist, very efficient.
- The first and last manoeuvres aren't the best possible, as seen in porkchop plots.
- To obtain a better solution, multiple fly-bys around Earth, Venus or Mercury itself may be considered, as done by ESA's mission BepiColombo.

## MISSION:

- Examination of given orbit and its ground tracks
- Study of  $J_2$  and Moon perturbations
- Accuracy comparison of the integration methods used
- Comparison with real case

## MISSION DATA:

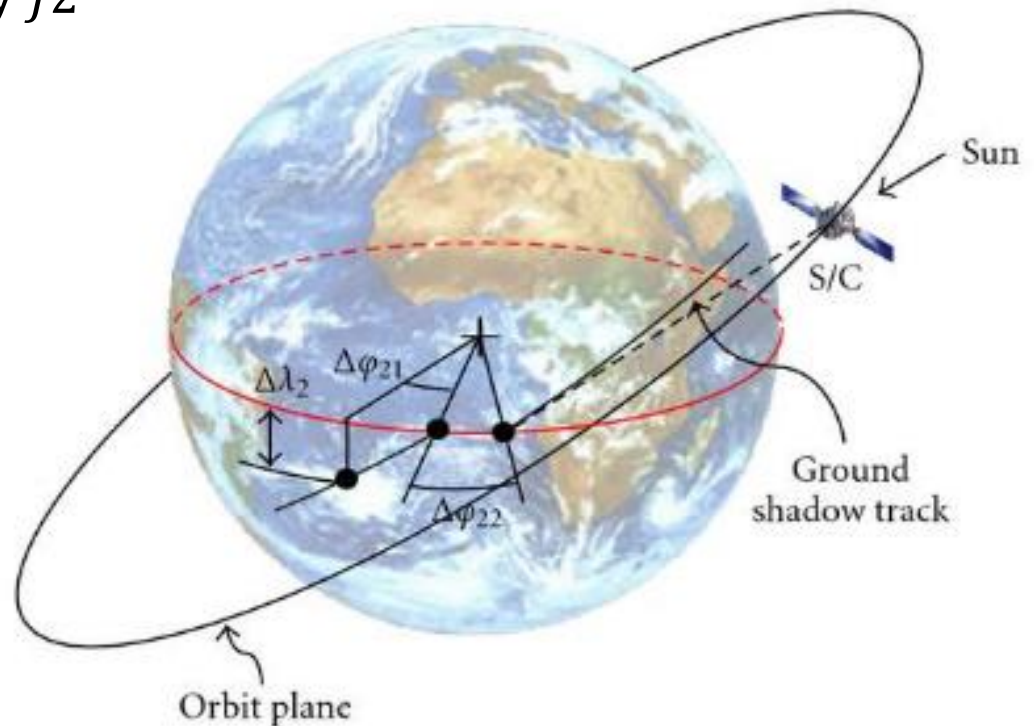
$a$ [km]	$e$ [—]	$i$ [deg]	$\Omega$ [deg]	$\omega$ [deg]	$\vartheta$ [deg]	$rp$ [km]	$m/k$ [—]
$3.9899 \cdot 10^4$	0.2510	56.6144	0	0	0	29884.351	1

## PERTURBATION MODELLING: J2

- Caused by Earth's oblateness and spheroid structure
- Zonal effect dominated by  $J_2$

Principal effects:

- Nodal Regression
- Perigee Precession







## PERTURBATION MODELLING: MOON PRESENCE

- Causes gravitational attraction

Principal effects:

- Change of  $e$ ,  $i$  and  $\omega$



## INTEGRATION METHODS:

### Integration in Cartesian Coordinates

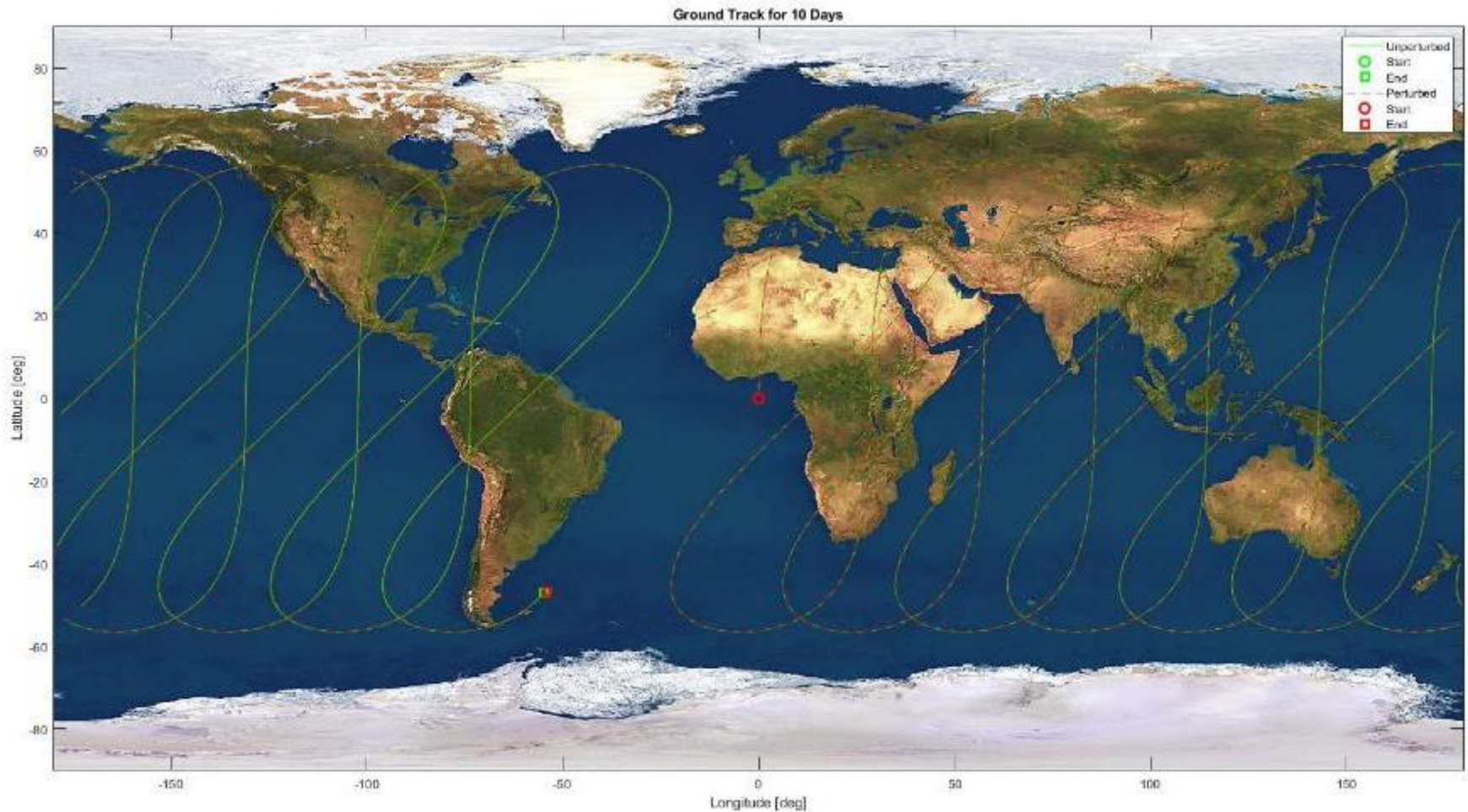
$$\frac{d}{dt} \begin{Bmatrix} \vec{r} \\ \vec{v} \end{Bmatrix} = \begin{Bmatrix} \vec{v} \\ -\frac{\mu}{r^3} \cdot \vec{r} + \vec{a}_{pert} \end{Bmatrix}$$

### Integration of Gauss Planetary Equations

$$\frac{d}{dt} \{\vec{K}\} = fun(\vec{K}, a_{pert}^{RSW})$$

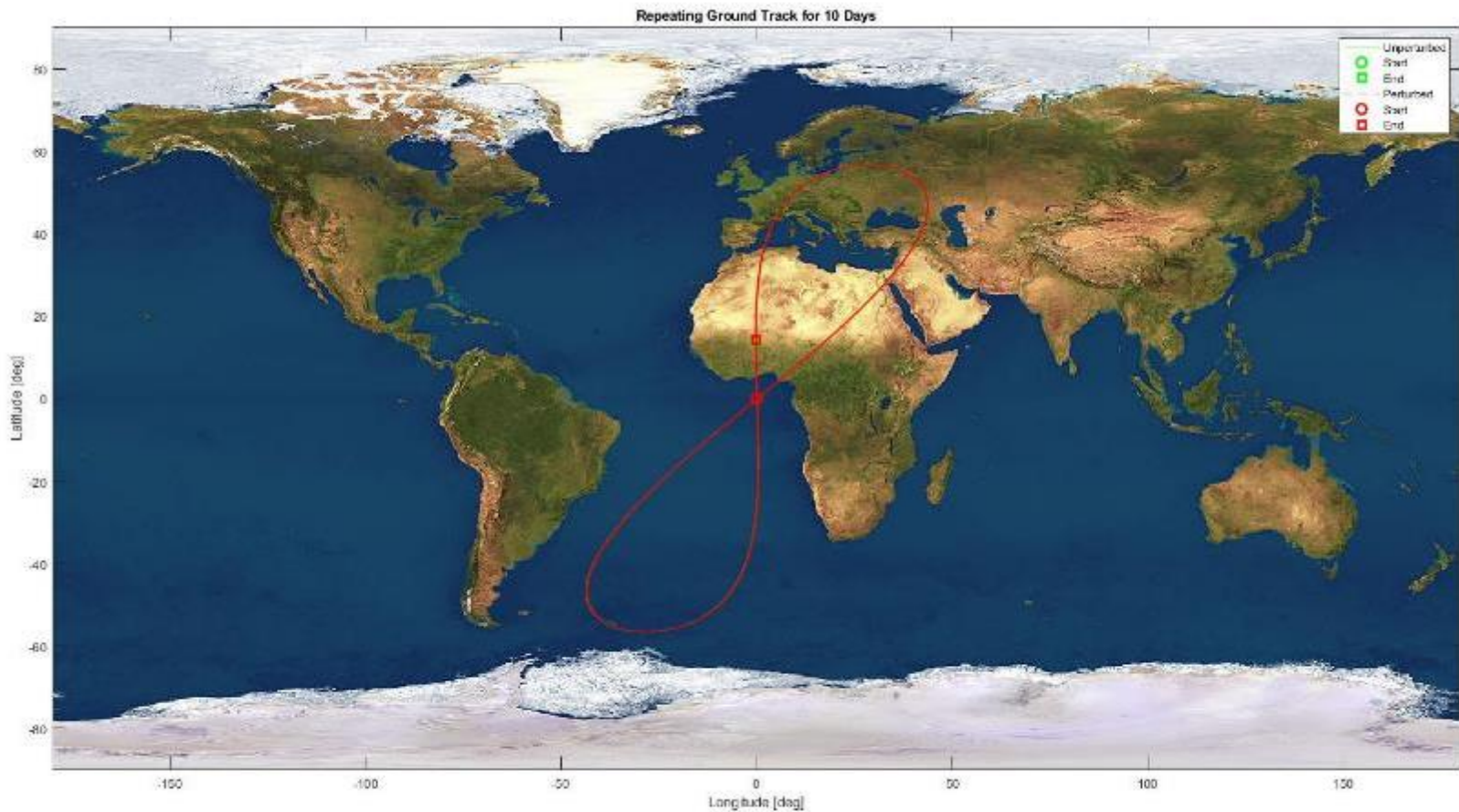


## GROUND TRACKS:





## REPEATING GROUND TRACKS:



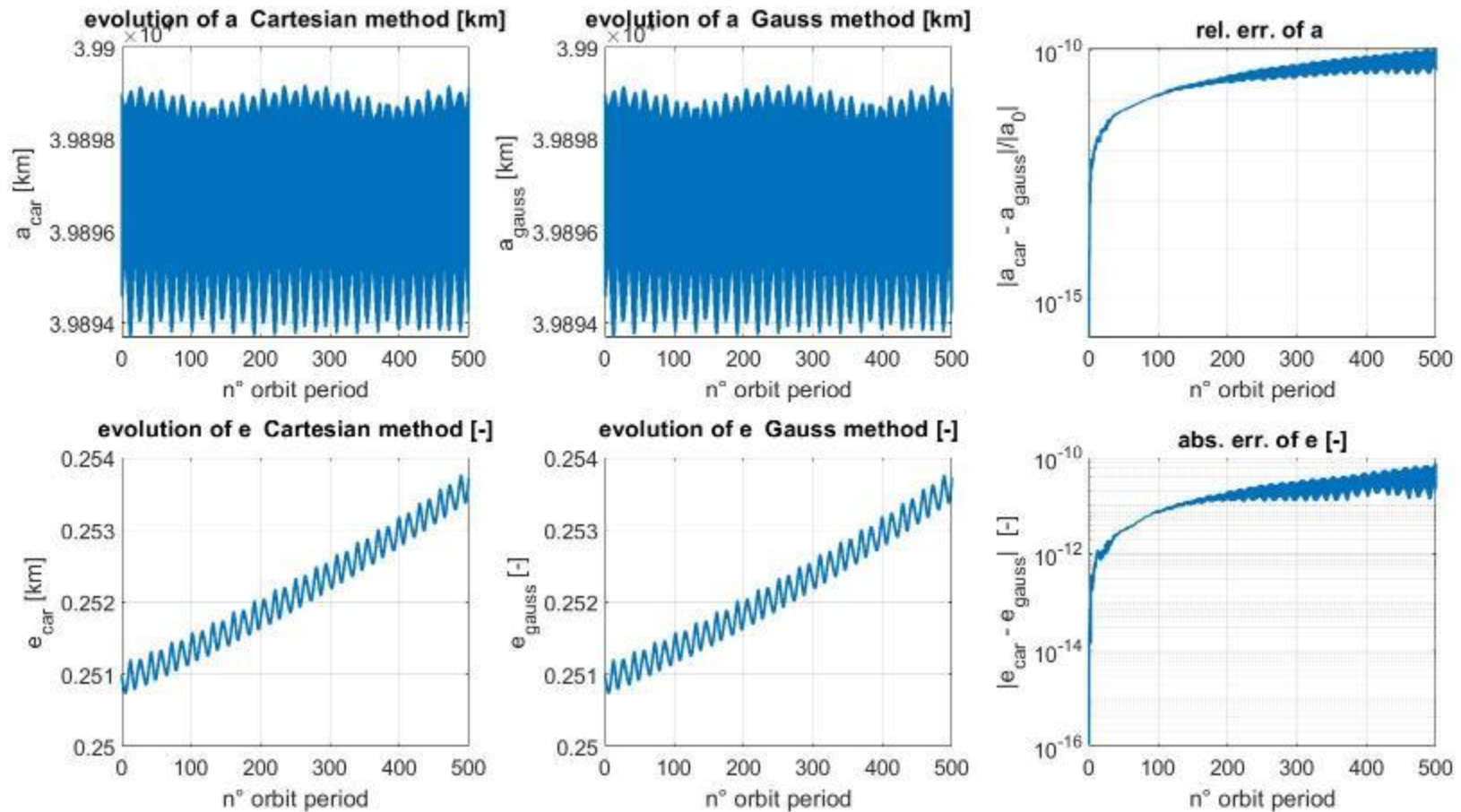
$$a_{rep} = 42166.17 \text{ km}$$

$$a_{rep_{J_2}} = 42165.77 \text{ km}$$



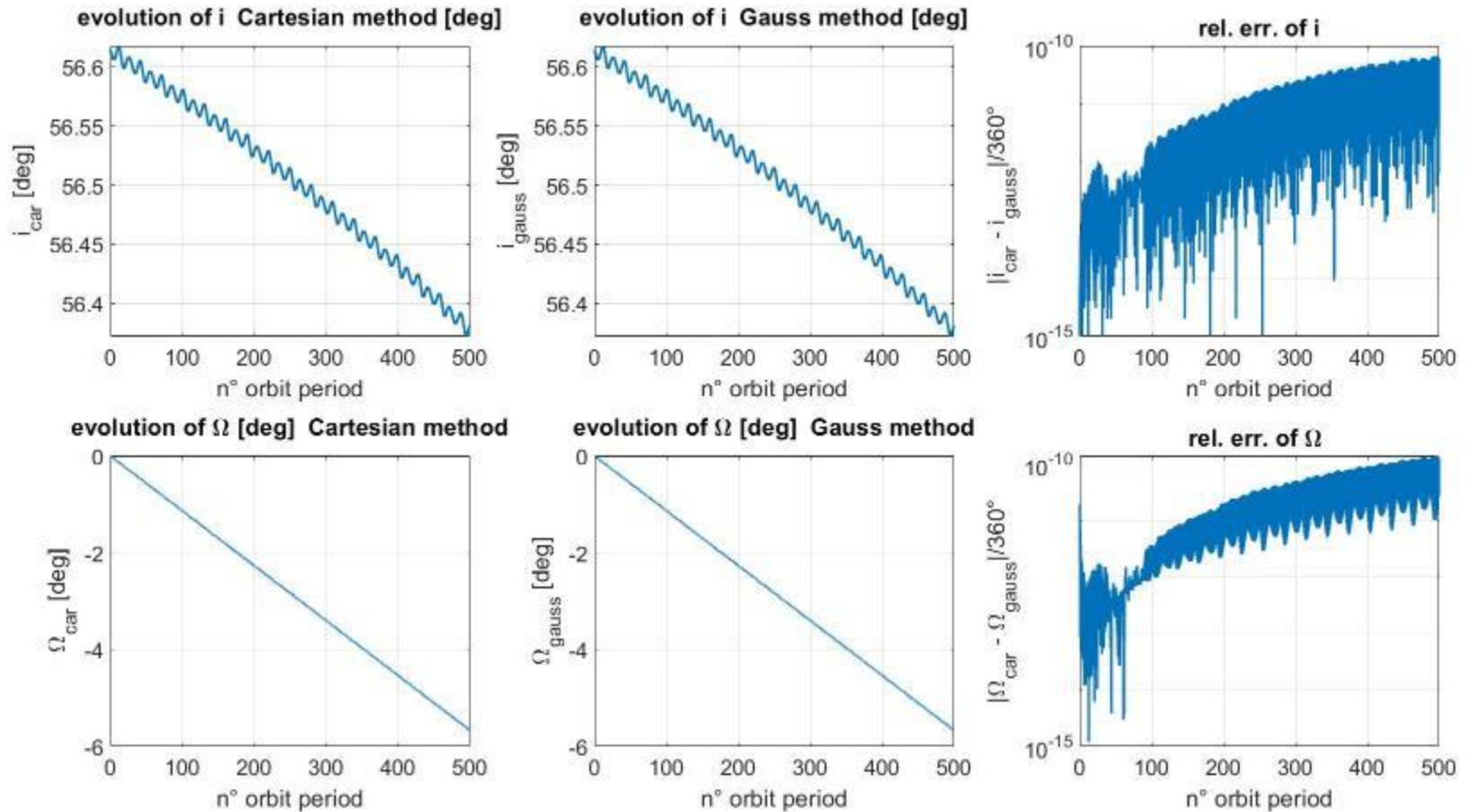


## INTEGRATION METHODS COMPARISON



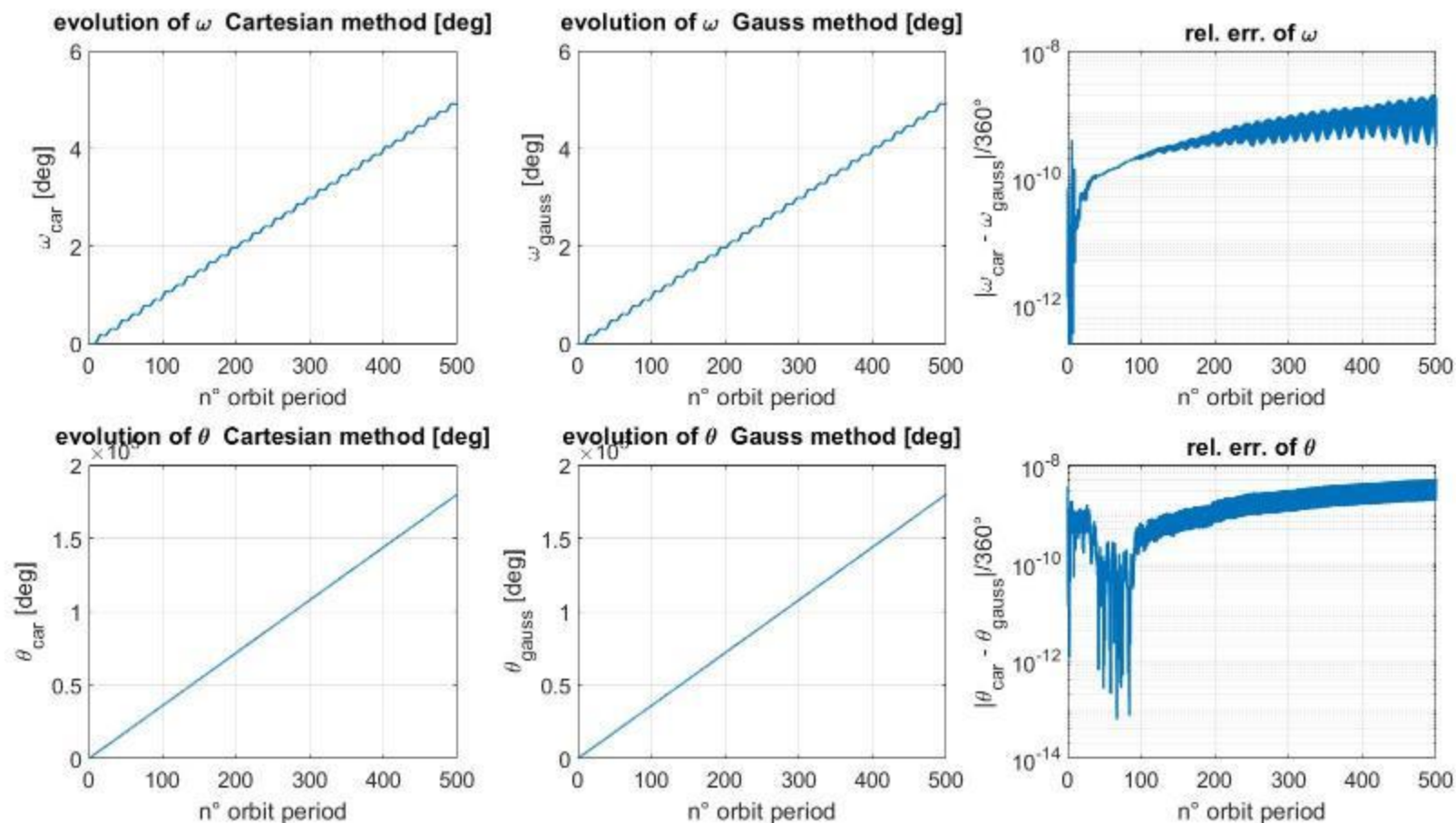


## INTEGRATION METHODS COMPARISON



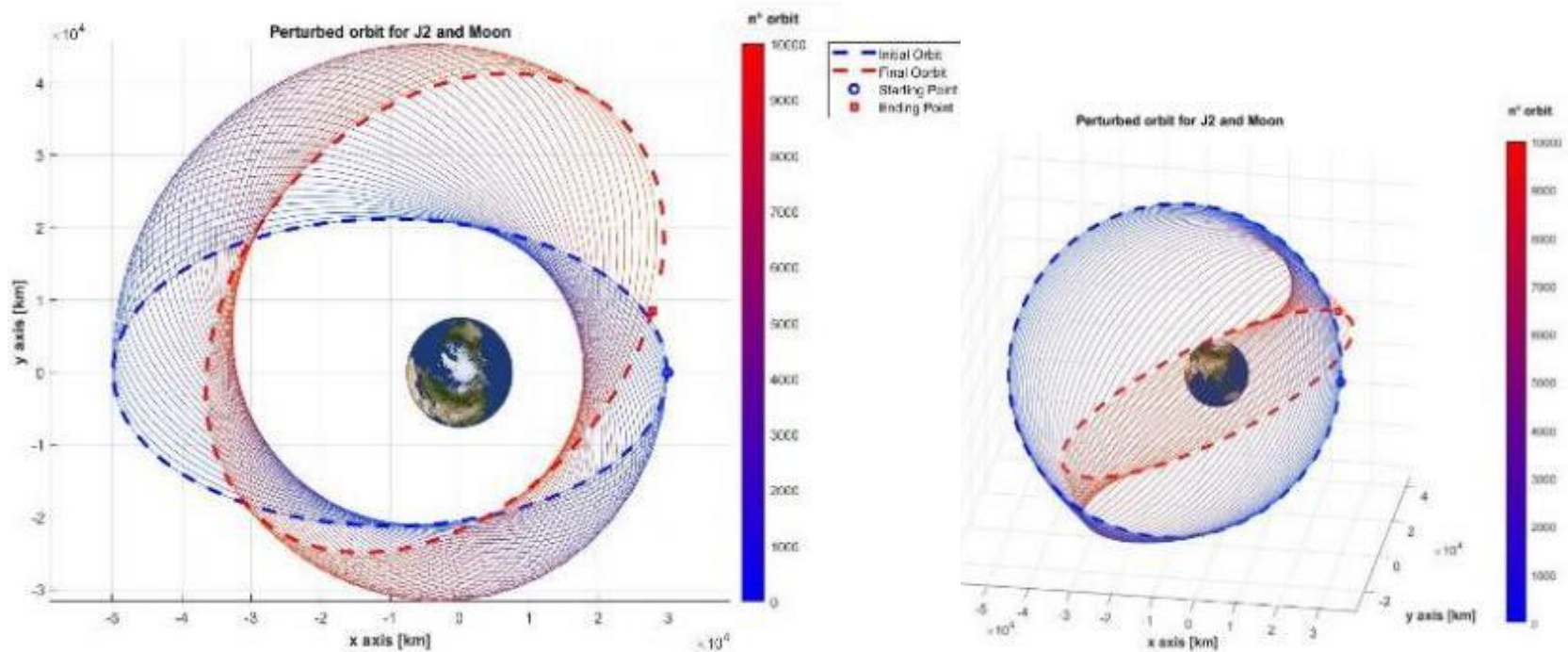


## INTEGRATION METHODS COMPARISON





## EVOLUTION OF PERTURBED ORBIT:

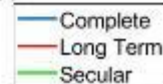
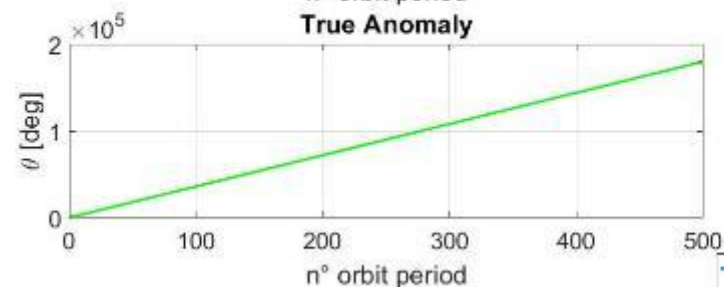
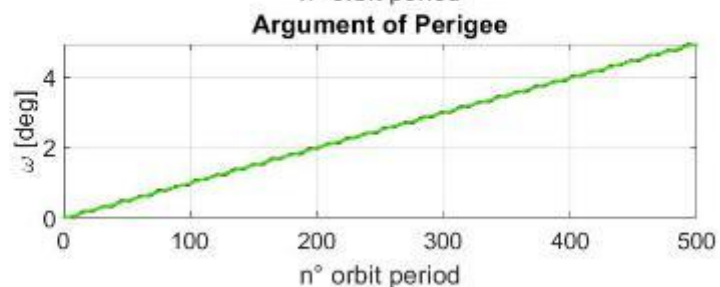
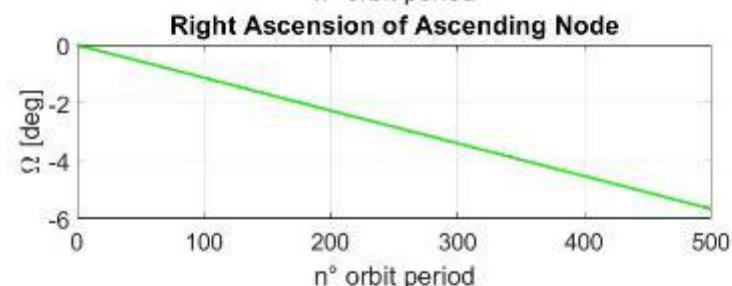
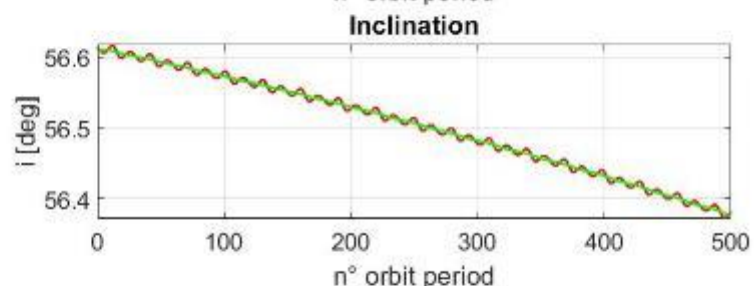
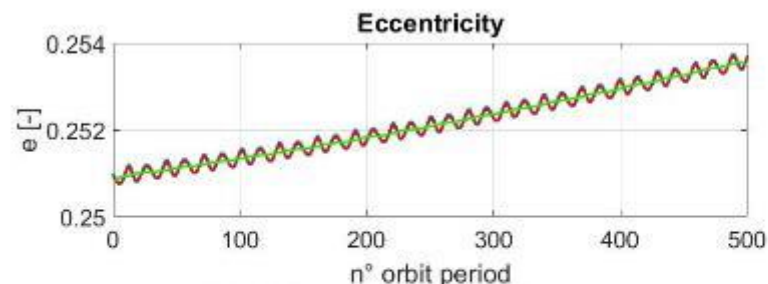
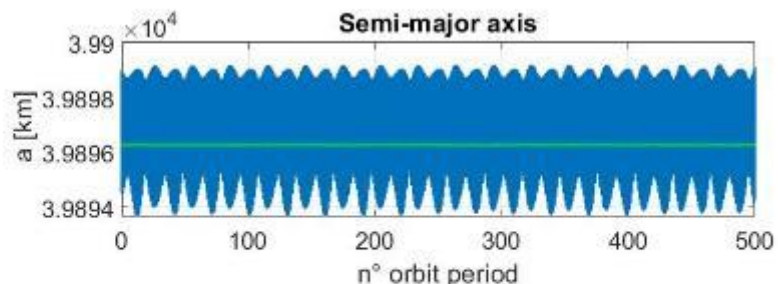


INITIAL ORBIT PARAMETERS:					
$a$	$e$	$i$	$\Omega$	$\omega$	$\vartheta$
39899.0 km	0.2510	56.6144°	0.0°	0.0°	0.0°
FINAL ORBIT PARAMETERS:					
$a$	$e$	$i$	$\Omega$	$\omega$	$\vartheta$
39897.54 km	0.3200	46.6746°	-136.52°	76.14°	0.0°





## FILTERING OF KEPLERIAN ELEMENTS:





## REAL DATA COMPARISON

Satellite used: *ZHONGXING-7*

Properties:

- Telecom satellite
- Set on graveyard orbit
- Almost same altitude as study orbit





## REAL DATA COMPARISON

