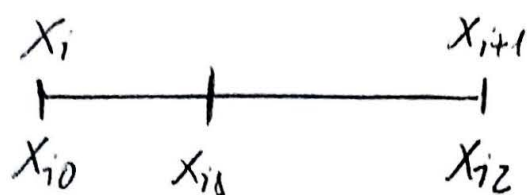


# MÉTODOS DE RUNGE-KUTTA (RK22)

$$p=2, q=2.$$



$$x_{i0} = x_i$$

$$x_{i1} = x_i + \theta_1 h.$$

$$x_{i2} = x_{i+1}$$

Consideramos el esquema:

$$\rightarrow y_{i0} = y_i$$

$$\rightarrow y_{i1} = y_i + h A_{10} f(x_{i0}, y_{i0}) = y_i + h A_{10} f(x_i, y_i) \quad \text{--- (1)}$$

$$\begin{aligned} \rightarrow y_{i2} &= y_i + h [A_{20} f(x_{i0}, y_{i0}) + A_{21} f(x_{i1}, y_{i1})] \\ &= y_i + h [A_{20} f(x_i, y_i) + A_{21} f(x_{i1}, y_{i1})] \quad \text{--- (2)} \end{aligned}$$

Para determinar los coeficientes  $A_{10}, A_{20}, A_{21}$  se considera el desarrollo de Taylor al rededor de  $x_i$  de la solución del P.V.I. local  $\tilde{y}(x)$

$$\begin{cases} \tilde{y}'(x) = f(x, \tilde{y}(x)), & x \in [x_i, x_{i+1}] \\ \tilde{y}(x_i) = y_i \end{cases}$$

y se compara hasta el término  $h^2$  con (1) y (2)

Para  $A_{10}$

$$\tilde{y}(x_i + \theta_1 h) = \tilde{y}(x_i) + \theta_1 h \tilde{y}'(x_i) + \frac{\theta_1^2 h^2}{2} \tilde{y}''(x_i) + \dots$$

$$\Rightarrow \tilde{y}(x_{i+1}) = \underbrace{y_i + \theta_1 h f(x_i, y_i)}_{(3)} + \frac{\theta_1^2 h^2}{2} \tilde{y}''(x_i) + \dots$$

Comparando (3) con (1) tenemos que  $A_{10} = \theta_1$  y por lo tanto:

$$\boxed{y_{i+1} = y_i + h \theta_1 f(x_i, y_i)} \quad (4)$$

Para  $A_{20}$  y  $A_{21}$

$$\tilde{y}(x_i + h) = \tilde{y}(x_i) + h \tilde{y}'(x_i) + \frac{h^2}{2} \tilde{y}''(x_i) + \frac{h^3}{6} \tilde{y}'''(x_i) + \dots$$

$$\Rightarrow \tilde{y}(x_{i+1}) = y_i + h f(x_i, y_i) + \frac{h^2}{2} \tilde{y}''(x_i) + \frac{h^3}{6} \tilde{y}'''(x_i) + \dots \quad (5)$$

Para la segunda derivada  $\tilde{y}''$  consideramos la regla de la cadena

$$f \begin{matrix} \nearrow x \\ \searrow y \end{matrix} \rightarrow x.$$

$$\begin{aligned} \tilde{y}''(x) &= [\tilde{y}'(x)]' = [f(x, \tilde{y}(x))]' = \frac{\partial f}{\partial x}(x, \tilde{y}(x)) + \frac{\partial f}{\partial \tilde{y}}(x, \tilde{y}(x)) \tilde{y}'(x) \\ &= \frac{\partial f}{\partial x}(x, \tilde{y}(x)) + \frac{\partial f}{\partial \tilde{y}}(x, \tilde{y}(x)) \cdot f(x, \tilde{y}(x)) \end{aligned}$$

Reemplutando en (5) tenemos:

$$\tilde{y}(x_{i+1}) = y_i + h f(x_i, y_i) + \frac{h^2}{2} \left[ \frac{\partial f}{\partial x}(x_i, y_i) + \frac{\partial f}{\partial y}(x_i, y_i) \cdot f(x_i, y_i) \right] + \frac{h^3}{6} y'''(x_i) + \dots$$

Recordemos el teorema de Taylor para 2 variables

$$f(a+h, b+k) = \sum_{n=0}^{\infty} \frac{1}{n!} \left( h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^n f(a, b)$$

en nuestro caso, considerando  $K = f(x_i, y_i)$

tenemos  $x_{i+1}$  (por (4))

$$f(x_i + \theta_1 h, y_i + \theta_1 h K) = f(x_i, y_i) + \theta_1 h \frac{\partial}{\partial x} f(x_i, y_i) + \theta_1 h K \frac{\partial}{\partial y} f(x_i, y_i) + \dots$$

$$\Rightarrow f(x_{i+1}, y_{i+1}) - f(x_i, y_i) = \theta_1 h \frac{\partial}{\partial x} f(x_i, y_i) + \theta_1 h K \frac{\partial}{\partial y} f(x_i, y_i) + \dots$$

$$\Rightarrow \frac{f(x_{i+1}, y_{i+1}) - f(x_i, y_i)}{\theta_1 h} = \frac{\partial}{\partial x} f(x_i, y_i) + \frac{\partial}{\partial y} f(x_i, y_i) \cdot f(x_i, y_i) + \dots$$

$$\Rightarrow \frac{\partial f}{\partial x}(x_i, y_i) + \frac{\partial f}{\partial y}(x_i, y_i) \cdot f(x_i, y_i) = \frac{f(x_{i+1}, y_{i+1}) - f(x_i, y_i)}{\theta_1 h} + \dots$$

Reemplutando en (6) tenemos:

$$y_{i+1} = y_i + h f(x_i, y_i) + \frac{h^2}{2} \left[ \frac{f(x_{i+1}, y_{i+1}) - f(x_i, y_i)}{\theta_1 h} + \dots \right] + \frac{h^3}{6} y'''(x_i) + \dots$$

$$\tilde{y}(x_{i+1}) = y_i + h f(x_i, y_i) + \frac{h}{2\theta_1} f(x_{i1}, y_{i1}) - \frac{h}{2\theta_1} f(x_i, y_i) - \dots + \frac{h^3}{6} \tilde{y}'''(x_i) + \dots$$

$$\Rightarrow \tilde{y}(x_{i+1}) = \underbrace{y_i + h \left(1 - \frac{1}{2\theta_1}\right) f(x_i, y_i) + h \frac{1}{2\theta_1} f(x_{i1}, y_{i1})}_{(1)} + \frac{h^3}{6} \tilde{y}'''(x_i) + \dots$$

Comparando (1) con (2) tenemos que  $A_{20} = \left(1 - \frac{1}{2\theta_1}\right)$   
 y  $A_{21} = \frac{1}{2\theta_1}$  y por lo tanto

$$y_{i2} = y_i + h \left(1 - \frac{1}{2\theta_1}\right) f(x_i, y_i) + h \frac{1}{2\theta_1} f(x_{i1}, y_{i1}) = y_{i+1}$$