$$J = \left\{ \begin{array}{cc} a & b \\ c & d \end{array} \right\}$$

$$\lambda^2 - (\alpha + d)\lambda + (ad - bc) = 0$$

(i)
$$A+X \xrightarrow{k_1} \geq X \qquad \frac{dx}{dt} = k_1 \times (t) A - k_2 \times^2 (t)$$

$$X+X \xrightarrow{k_2} Y$$

$$Y \xrightarrow{k_3} B \qquad Jt = k_2 \times^2 (t) - k_3 y(t)$$

(ii)
$$A k_{1} x^{ss} - k_{2} (x^{ss})^{2} = 0 , x^{ss} (A k_{1} - k_{2} x^{ss}) = 0$$

$$x^{ss} = 0 , y^{ss} = 0$$

$$x^{ss} = 0 , y^{ss} = 0$$

$$x^{ss} = \frac{A k_{1}}{k_{2}} (x^{ss})^{2}$$

$$x^{ss} = \frac{A k_{1}}{k_{2}} , y^{ss} = \frac{A k_{1}}{k_{3}}$$

(iiii)
$$J = \begin{cases} Ak_1 - 2k_2 X & 0 \\ 2k_3 X & -k_3 \end{cases} \Rightarrow \lambda_1 = a, \lambda_2 = d$$

$$\chi^{55} = 0 \qquad \begin{cases} \lambda_1 = Ak_1 \\ \lambda_2 = -k_3 \end{cases} \text{ unstable} \qquad \chi^{55} = \frac{Ak_1}{k_2} \qquad \begin{cases} \lambda_1 = -Ak_1 \\ \lambda_2 = -k_3 \end{cases}$$
 stable
$$\chi^{55} = 0 \qquad \begin{cases} \lambda_1 = -Ak_1 \\ \lambda_2 = -k_3 \end{cases}$$

(Vi)

$$\begin{array}{c}
A+X \longrightarrow 2X \quad [X] = 0 \\
X+X \longrightarrow Y \quad [X] = 0
\end{array}$$

$$\begin{array}{c}
\times +X \longrightarrow X \quad [X] = 0 \\
Y \longrightarrow B
\end{array}$$

Problem 4.8.6 - 2

(i)
$$A + X \longrightarrow 2X$$

$$X + Y \xrightarrow{k_2} 2Y$$

$$Y \xrightarrow{k_3} B$$

$$A + X \longrightarrow 2X$$

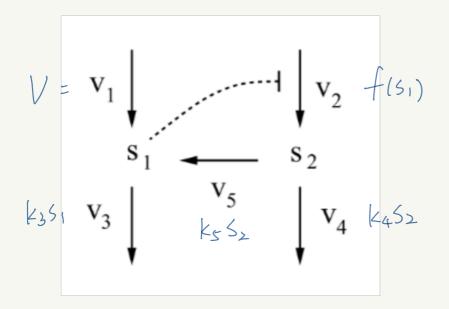
$$A + X \longrightarrow$$

(ii)
$$Ak_{1} X - k_{2} X y = 0 , \quad (Ak_{1} - k_{2} y) X^{ss} = 0 , \quad X^{ss} = 0 , \quad y^{ss} = 0$$

$$k_{2} X y - k_{3} y = 0 , \quad (k_{2} X - k_{3}) y^{ss} = , \quad X^{ss} = \frac{k_{3}}{k_{2}} , \quad y^{ss} = \frac{Ak_{1}}{k_{2}}$$

(iii)
$$J = \begin{cases} Ak_{1} - k_{2}y & -k_{2}x \\ k_{2}y & k_{2}x - k_{3} \end{cases} \qquad J = \begin{cases} Ak_{1} & 0 \\ 0 & k_{3} \end{cases} \qquad \lambda_{1} = Ak_{1} \qquad \lambda_{2} = -k_{3} \qquad \lambda_{3} = -k_{3} \qquad \lambda_{4} = -k_{4} \qquad \lambda_{5} = -k_{5} \qquad \lambda_{7} = \sqrt{Ak_{1}k_{5}} i \qquad \lambda_{7} = \sqrt{Ak_{1}k_{5}}$$

Problem 4.8.7



$$f(s_1) \Rightarrow \text{ take positive value},$$
is a decreasing function. $(s_1 \uparrow f(s_1) \downarrow)$

$$\frac{d}{dt} s_1(t) = V - k_3 s_1(t) + k_5 s_2(t)$$

$$\frac{d}{dt} s_2(t) = \frac{k_2}{1 + (s_1(t)/K)^n} - k_4 s_2(t) - k_5 s_2(t)$$

SI - nullcline is defined by

$$V - k_3 S_1(t) + k_5 S_2(t) = 0$$

$$S_1(t) = \frac{V + k_5 S_2(t)}{k_3}$$

Sz-nullcline is defined by

$$0 = \frac{k_2}{1 + (S_1(t)/K)^n} - k_4 S_2(t) - k_5 S_2(t)$$

$$S_{2}(t) = \frac{k_{2}}{[1+(S_{1}(t)/K_{2})^{n}](k_{4}+k_{5})}$$