

FUNMANAbstraction

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1 Stratification Abstraction

The SIERHD model from the August monthly demo uses the model summarized by the Petrinet diagram in Figure 1.

The following transitions connect the variables S_c , S_{nc} , E_c , E_{nc} , I_c , and I_{nc} , R , H , D :

$$\begin{aligned} t_1 : (I_c, S_c) &\xrightarrow{r_1} (I_c, E_c) \\ t_2 : (I_{nc}, S_c) &\xrightarrow{r_2} (I_{nc}, E_c) \\ t_3 : (I_{nc}, S_{nc}) &\xrightarrow{r_3} (I_{nc}, E_{nc}) \\ t_4 : (I_c, S_{nc}) &\xrightarrow{r_4} (I_c, E_{nc}) \\ t_5 : (E_c) &\xrightarrow{r_5} (I_c) \\ t_6 : (E_{nc}) &\xrightarrow{r_6} (I_{nc}) \\ t_7 : (I_c) &\xrightarrow{r_7} (R) \\ t_8 : (I_{nc}) &\xrightarrow{r_8} (R) \\ t_9 : (I_c) &\xrightarrow{r_9} (H) \\ t_{10} : (I_{nc}) &\xrightarrow{r_{10}} (H) \\ t_{11} : (H) &\xrightarrow{r_{11}} (R) \\ t_{12} : (H) &\xrightarrow{r_{12}} (D) \\ t_{13} : (S_{nc}) &\xrightarrow{r_{13}} (S_c) \\ t_{14} : (S_c) &\xrightarrow{r_{14}} (S_{nc}) \\ t_{15} : (E_{nc}) &\xrightarrow{r_{15}} (E_c) \\ t_{16} : (E_c) &\xrightarrow{r_{16}} (E_{nc}) \\ t_{17} : (I_{nc}) &\xrightarrow{r_{17}} (I_c) \\ t_{18} : (I_c) &\xrightarrow{r_{18}} (I_{nc}) \end{aligned}$$

Abstracting this base model involves merging variables, such as S_c and S_{nc} into a composite variable S where $S = S_c + S_{nc}$. In this approach, a composite variable can represent any number of stratified copies of a variable (e.g., S stratified by ten age groups). We also abstract the base model transitions so that their source and target variables are composite variables. For example, if we define composite variables S , I , and E for the corresponding stratified variables in the base model, then transitions t_1 to t_4 become the composite transition $t_{1:4}$:

$$t_{1:4} : (I, S) \xrightarrow{r_{1:4}} (I, E)$$

$$\begin{aligned}
S(t+dt) &= S_c(t+dt) + S_{nc}(t+dt) \\
&= S_c(t) - (r_1 + r_2)dt + S_{nc}(t) - (r_3 + r_4)dt \\
&= S(t) - (r_1 + r_2 + r_3 + r_4)dt \\
&= S(t) - \left(\frac{I_c S_c \beta (1 - c_{m_0} \epsilon_{m_0})}{N} + \frac{I_{nc} S_c \beta (1 - c_{m_1} \epsilon_{m_1})}{N} + \right. \\
&\quad \left. \frac{I_{nc} S_{nc} \beta (1 - c_{m_2} \epsilon_{m_2})}{N} + \frac{I_c S_{nc} \beta (1 - c_{m_3} \epsilon_{m_3})}{N} \right) dt \\
&\leq S(t) - \left(\frac{I_c S_c \beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} + \frac{I_{nc} S_c \beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} + \right. \\
&\quad \left. \frac{I_{nc} S_{nc} \beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} + \frac{I_c S_{nc} \beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} \right) dt \\
&= S(t) - \frac{\beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} (I_c S_c + I_{nc} S_c + I_{nc} S_{nc} + I_c S_{nc}) dt \\
&= S(t) - \frac{\beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} ((I_c + I_{nc})(S_c + S_{nc})) dt \\
&= S(t) - \frac{\beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} (IS) dt \\
&\leq S^{ub}(t) - \frac{I^{lb} S^{lb} \beta (1 - c_m^{ub} \epsilon_m^{ub})}{N} dt \\
&= S^{ub}(t+dt)
\end{aligned}$$

where the upper bound $S^{ub}(t+dt)$ assumes that the negative rate terms have minimal magnitude (i.e., the upper bound decreases by the least amount). The terms are minimal when they are replaced by the appropriate bounds I^{lb} , S^{lb} , c_m^{ub} , ϵ_m^{ub} . The lower bound $S^{ub}(t+dt)$ uses a similar approach, instead selecting bounds with a maximum magnitude and decreasing the lower bound by greatest amount. Positive rate terms are handled similarly so that they are maximal when used to compute upper bounds and minimal for lower bounds.

The abstract model that de-stratifies the base model defines 12 compartments (lower and upper bound for each variable after defining the composite variables), and 12 transitions (lower and upper bound for each composite transition). While the resulting model has fewer transitions, it has more compartments. However, we would have constructed the same size abstraction for a stratified model with an arbitrary number of levels. For example, if the base model used ten levels instead of two, then it would have 33 compartments and significantly more transitions.

We developed two abstract models from the base model. The first, as described above, de-stratifies the S , E , and I variables. The second, de-stratifies only S and E , allowing I to remain stratified.

Figure 2 illustrates the bounds computed by simulating the base and abstract models with FUNMAN. Each subplot is one compartment variable, and each series is one of the bounds or base model value. For example, the second plot illustrates I , which includes:

- Base model: $I_{\text{compliant}}$ and $I_{\text{noncompliant}}$,
- De-stratified S , E , and I : I_{lb} and I_{ub} ,
- De-stratified S , and E : $I_{\text{compliant_lb}}$, $I_{\text{compliant_ub}}$, $I_{\text{noncompliant_lb}}$ and $I_{\text{noncompliant_ub}}$,

The abstractions provide different bounds for each variable. In general, as abstraction increases, the model will provide looser bounds, but with a smaller model. Using abstraction refinement techniques, it is possible to start with an abstract model and only refine the relevant variables. Selectively refining models will trade off multiple abstract model simulations against a single, potentially large model simulation. In cases where

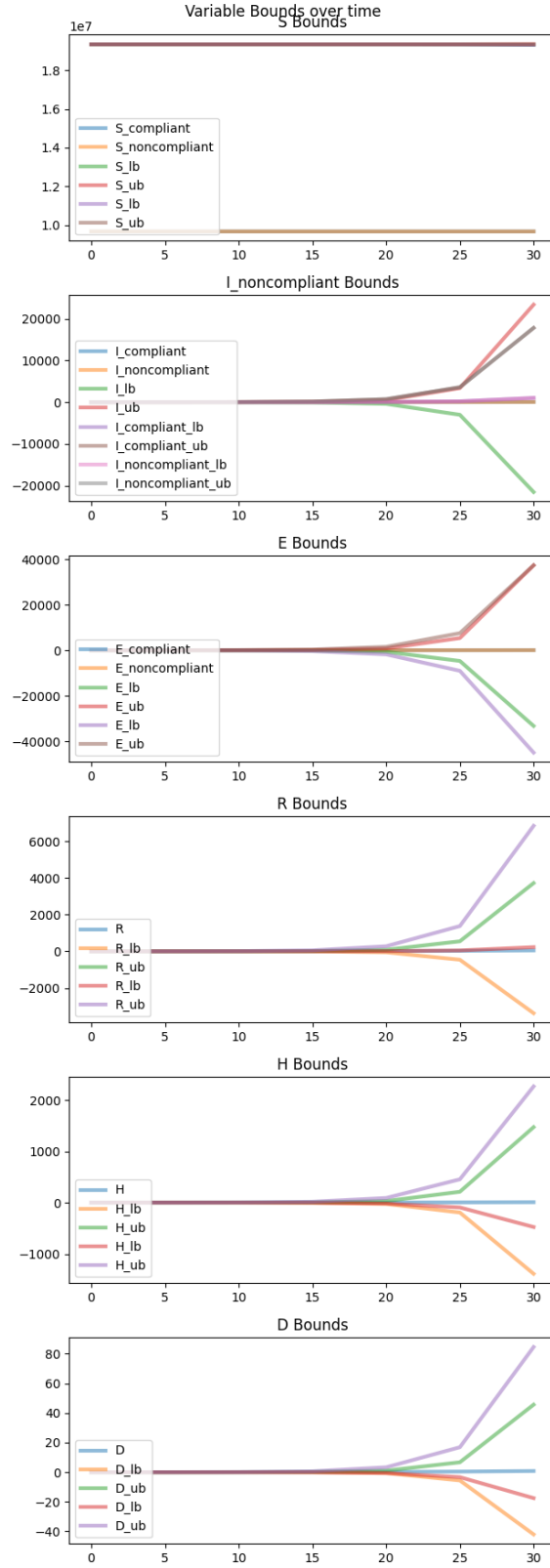


Figure 2: SEIRHD Model Bounds

the bounds are enough to answer a query (or check a constraint), the abstract model simulation can lead to significant scale up.