

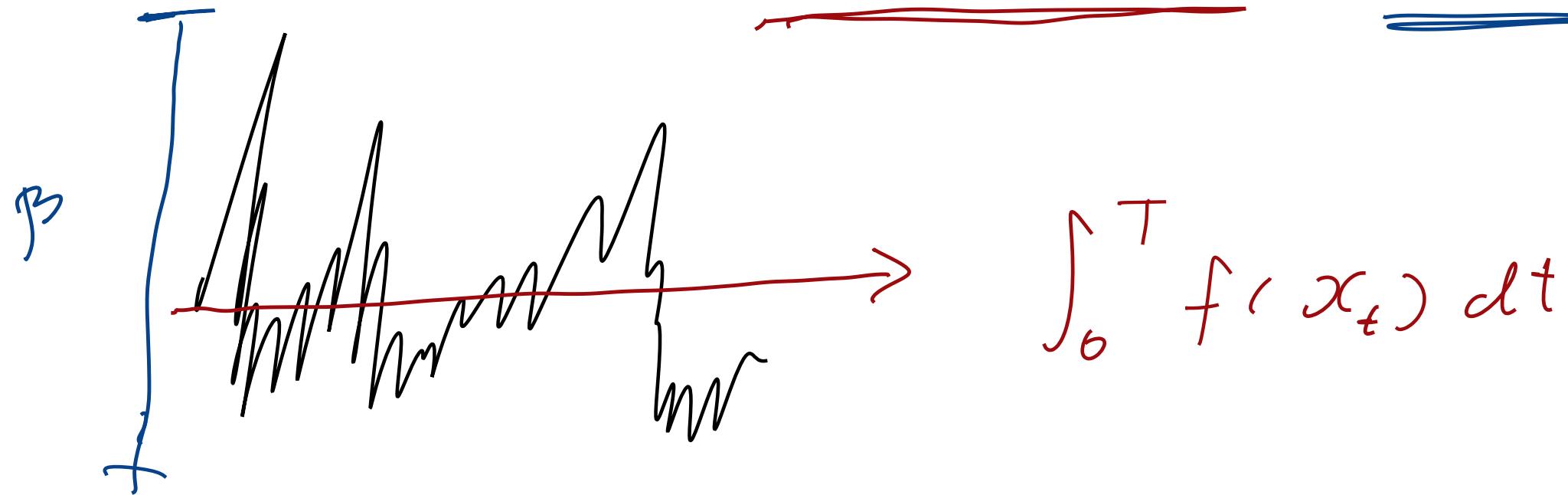
Approximate Bayesian inference
through the lens of large
deviations

One part technical discussion

One part "Where do we go
next?"

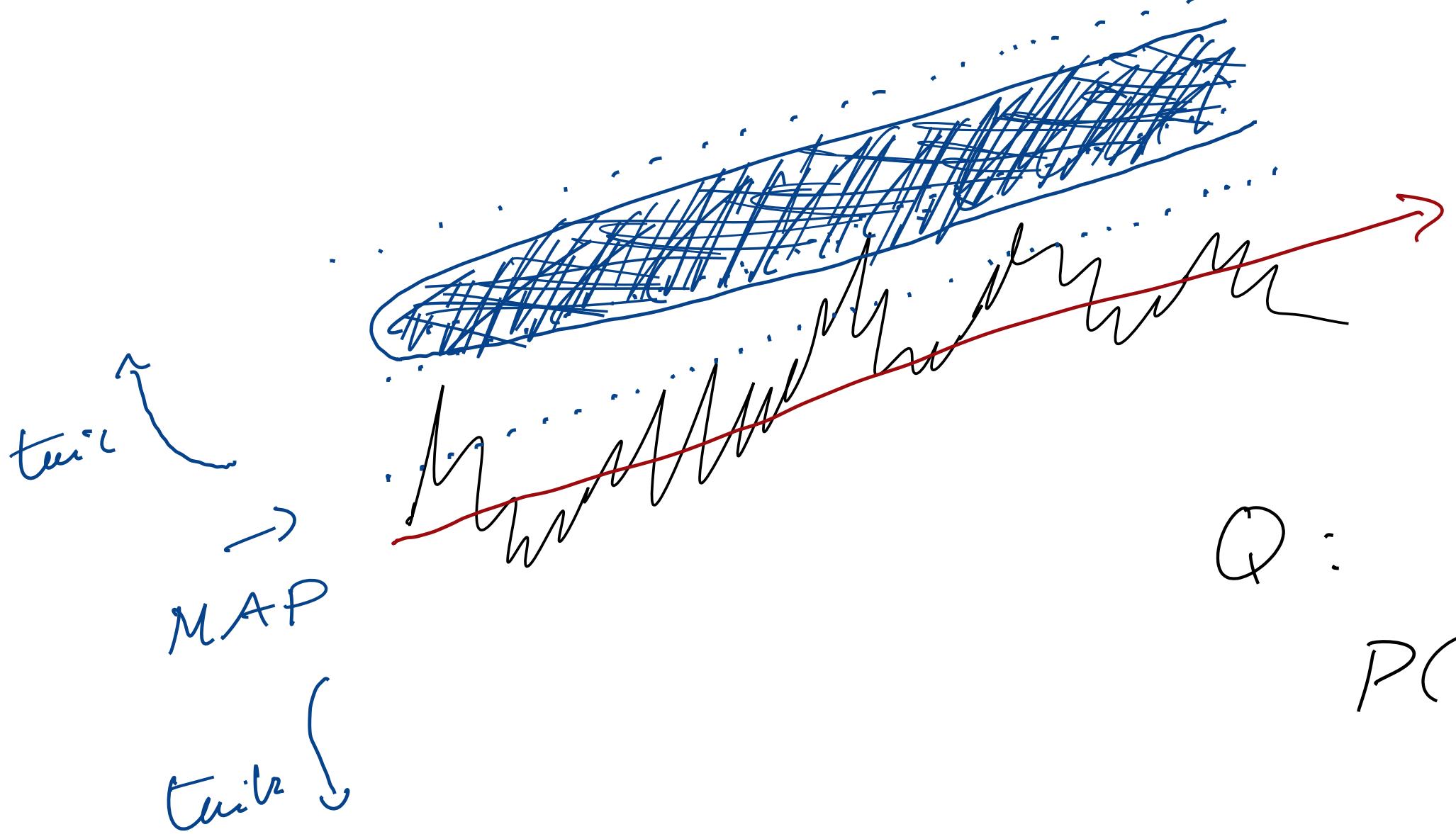
$$dx_t = f(x_t)dt + \beta dW_t$$

Itô
SDE



↓
Rough
paths

$$dx_t = f(x_t)dt + \beta(x_t)dY_t$$



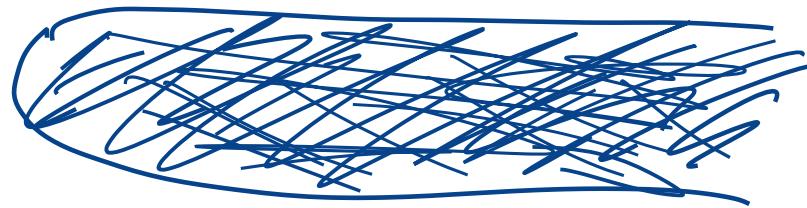
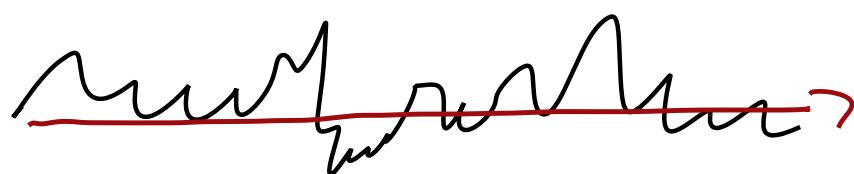
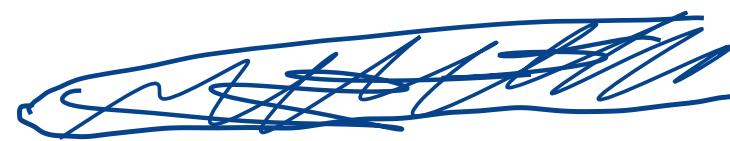
Q : What is

$$P(x_t \in A)$$

$$\sim e^{-C\|x - m\|^2}$$

A (intuitive) : - how large is β
- how far away is A

for small β and/or
far away A , $P \approx \emptyset$.



Formalise:

$$P \sim e^{-\frac{1}{\beta} I(A)}$$

$P(X_t \in A)$ depends on

$\text{int } A = F$

o dist $\cdot |F|$

$$e^{-\frac{1}{\beta} \|F - m\|_T^2}$$

Norm on the path space
(of \mathcal{W}_t)

$$\left(\int_0^T \dot{x}_t^2 dt \right)^{1/2}$$

$$\langle a, a \rangle$$

$$= \|a\|$$

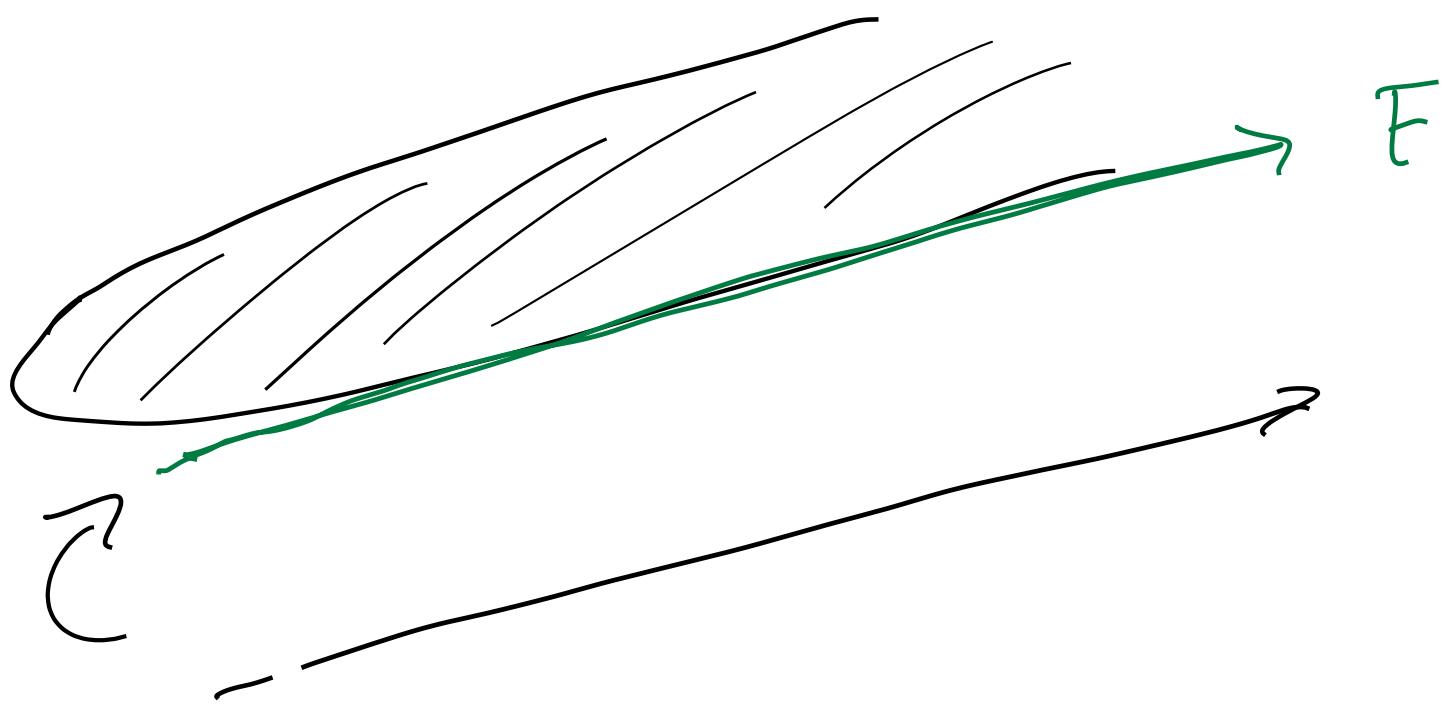
$$a \cdot a =$$

$$\|a\|^2 = a^2$$

$$\|x_T\|_P^2 = \int_0^T \dot{x}_t^2 dt$$

Cameron - Martin then
 \implies

$$I(x_t) = \int_0^T (\dot{x}_t - \dot{m}_t)^2 dt$$



$$I(F) =$$

$$\int_0^T (\dot{F}_t - \dot{m}_t)^2 dt$$

$$\underline{P(X_t \in A) \sim e^{-c_p I(\inf A)}}$$

$$\underline{\underline{c_p \rightarrow \infty \text{ as } n \rightarrow \infty}}$$

$$e^{-\infty I(\inf A)}$$

$$P(X_t \in F) + P(X_t \in F+k)$$

$$+ P(X_t + 2k) + \dots$$

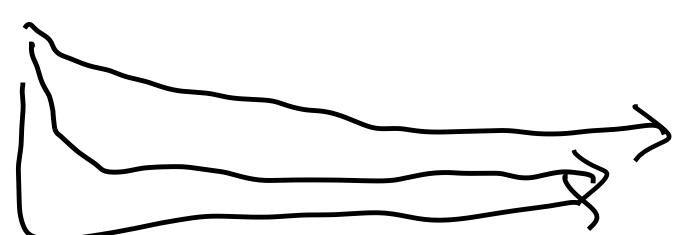
$$I = \emptyset$$

$$\underline{\underline{e^{-c I(F)}}}$$

$$+ \underline{\underline{e^{-c I(F+k)}}} + \dots$$

$$e^{-\infty \cdot \emptyset}$$

$$= c' = 1$$



Slap.

Unlikely events happen in
the least unlikely way

- F. Holland

2.5 other

examples of

hDPs

Therm

Lct

Street week

• x a microstate

• $M(x) =$ a macrostate

• any max $P(M(x)) =$
an eq. state

• n = system size.

The mesodynamics

as $N \rightarrow \infty$ the system
goes to eq state

Therm. limit \leftarrow

\Rightarrow fluctuations away from min I $\rightarrow \emptyset$

\Rightarrow Therm. satisfies a hDP



Another example :

as $n \rightarrow \infty$

emp. dist^w Converges
to the stationary meas.

$$D_{KL} (P_{\text{emp}} \| P) \rightarrow 0$$

$$x \rightarrow \gamma$$

[Sauer's thm]

Lemme: Janov's theorem holds on
the path space.

ensemble of sample paths

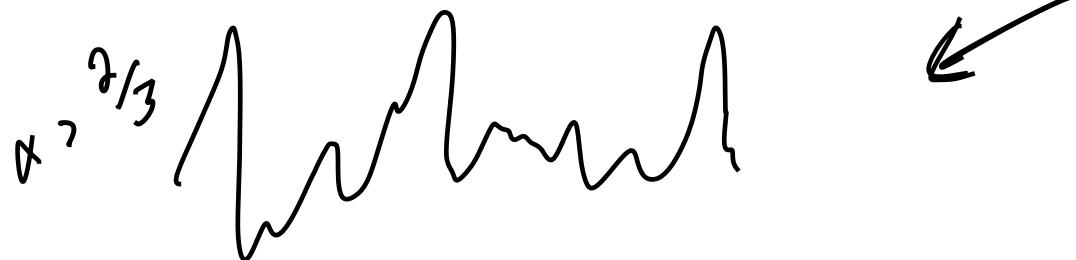
Remark
 $C([0, T], \mathbb{R})$ as $N \rightarrow \infty$ $D_{KL}(\rho(x)_{\text{emp}} \| \rho(x))$
is a Polish space
 \implies weak
converge



Further remark :



The space of geometric rough paths for any Hölder exp. is Polish



Can prove Søren's thus

$$C_g^\alpha(-)$$

Main theorem

Remark:

whole
conv.
will be
valid
for

Start.

given
an
app.
correction -
term.

Start w 2 ways

$$t \mapsto X_t$$

$$t \mapsto Y_t$$

families of
by time

driven by

RV indexed

an Itô SDE

in state-dep
diffusion
coeff.



Max Cost \Rightarrow the stats. of
sample paths tend towards the
ensemble P

If the sample paths themselves
are constrained by some cost
 \Rightarrow the cost is reflected
in $P(\text{sample})$

Intertwining
of limits

} So as $n \rightarrow \infty$ for fixed β ,
 Sanov's thm $\Rightarrow -\log p = \frac{1}{\beta} V$
 to first order in β
 and $n \rightarrow \infty$ with $\beta \rightarrow \emptyset \Rightarrow$
 $p \rightarrow S_{p.l.a}(x_t)$

\Rightarrow Sanov's thm produces state-wise hDPs

(which we knew!)

$$p = \max D_{KL} = e^{-\frac{1}{\beta} V}$$

which satisfies an LDP)

Friedlin
Henzzell
as

Natural cost on sample paths:

= speed
var.



$$-\log P(x_t) = C_p \int_0^T (\dot{x}_t - \partial_t \mathbb{E} x_t)^2 dt := C_p \|w\|_2^2$$

$$-\log q(y_t) = C_p \int_0^T (\dot{y}_t - \partial_t \mathbb{E} y_t)^2 dt := C_p \|\nu\|_2^2$$

• Set an additional cost

$$\mathbb{E}_p x_t = o(\mathbb{E}_q y_t)$$

Then as $\beta \rightarrow \theta$ path of
least is synchronisation

But recall: this
requires sampler under
cost
 $\min(DKL_{\pi})$

Main
Results

Statement based on
intervention:

win FET to find
the path sets

win h to get synched.

Fin