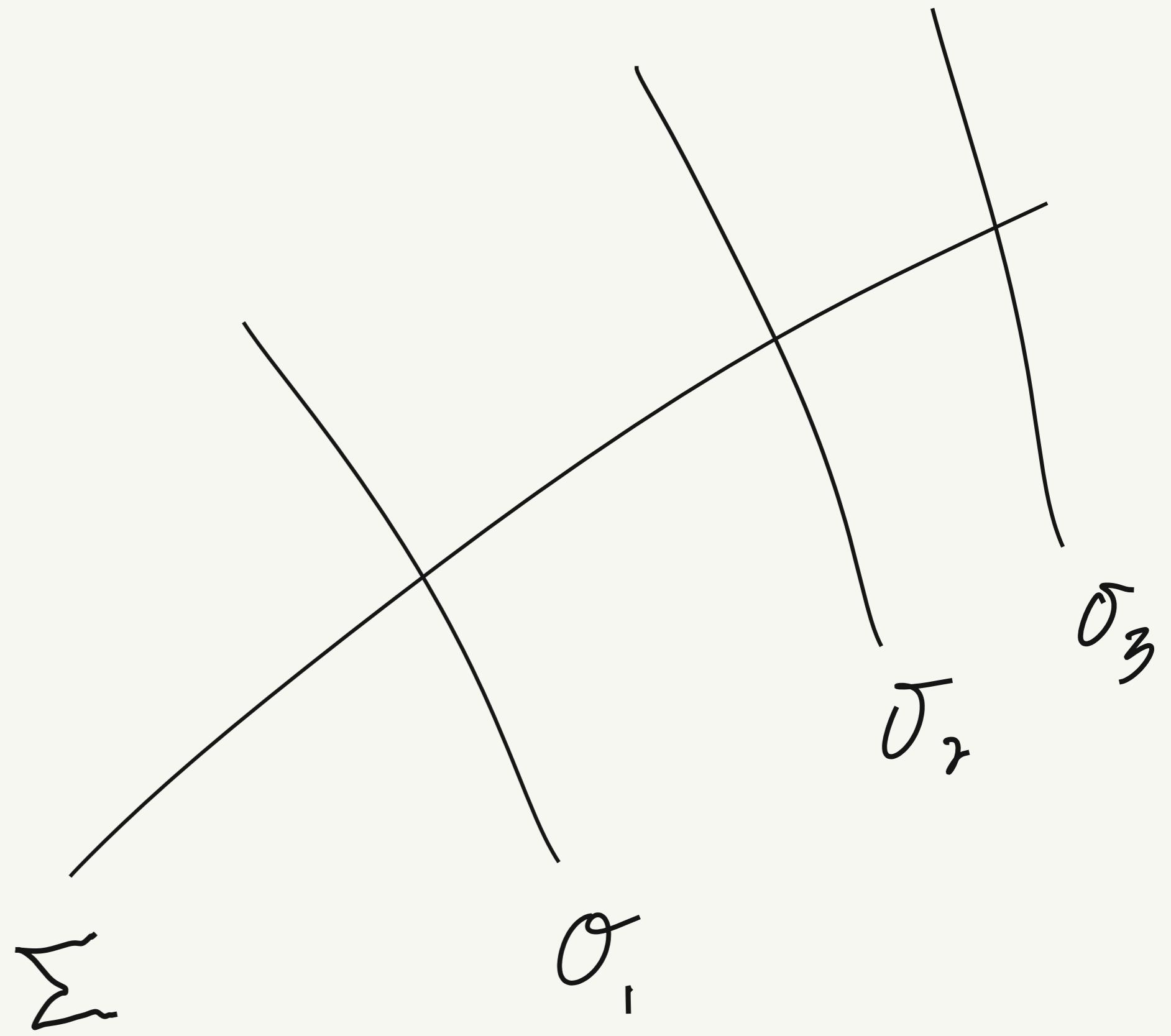


Solving Diffusion

with Geometry and

Max Cal

$$S[\gamma] = \int P(\gamma) \ln P(\gamma)$$

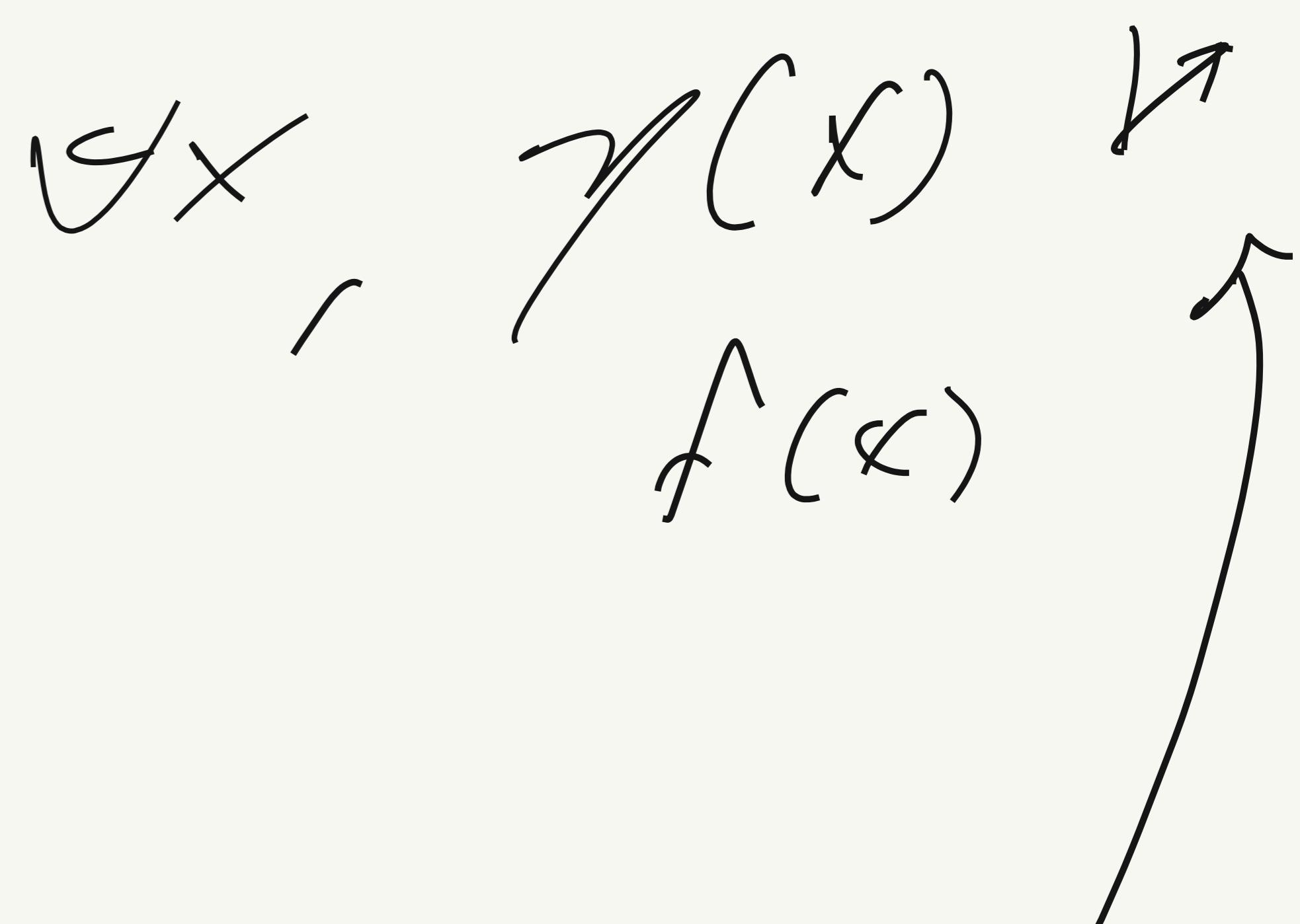


$$\dot{x} = f(x)$$

Phase plane

(1)  $\dot{x} = \underline{f}(x)$

$$y = \{ x(t), \dots, x(t_f) \}$$



$\cdot =$   
tangent  
to

$$(2) \quad \dot{x} = f(x) + n(t) \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} n \text{ ds}$$

$\Rightarrow$

$y$

P for FP

$FP \Rightarrow P(\gamma)$

$P(\gamma)$

$w_t$   $s_r$

$w_s - w_t$

$p(t)$

FP

=

$$\frac{\partial P}{\partial t}$$

$$= \alpha \frac{\partial^2}{\partial x^2} P(x, t) + \dots$$

$$L^f p = p$$

Solve FP

$P(\gamma)$

—

$$\min_S \left( \int h dt \right)$$

$$JS = 0$$

$$SS := 0 \Rightarrow \frac{d}{dt} \frac{\partial h}{\partial q_i} - \frac{\partial h}{\partial \dot{q}_i} = 0$$

$$m \ddot{x} = F$$

$$y(t) = \{x(t), \dots, x(t_f)\}$$

$$\max \left( - \int P(x) \ln(P(x)) dx \right)$$

$\gamma$

$$\Rightarrow \max \left( - \int P(\gamma) \ln(P(\gamma)) d\gamma \right)$$

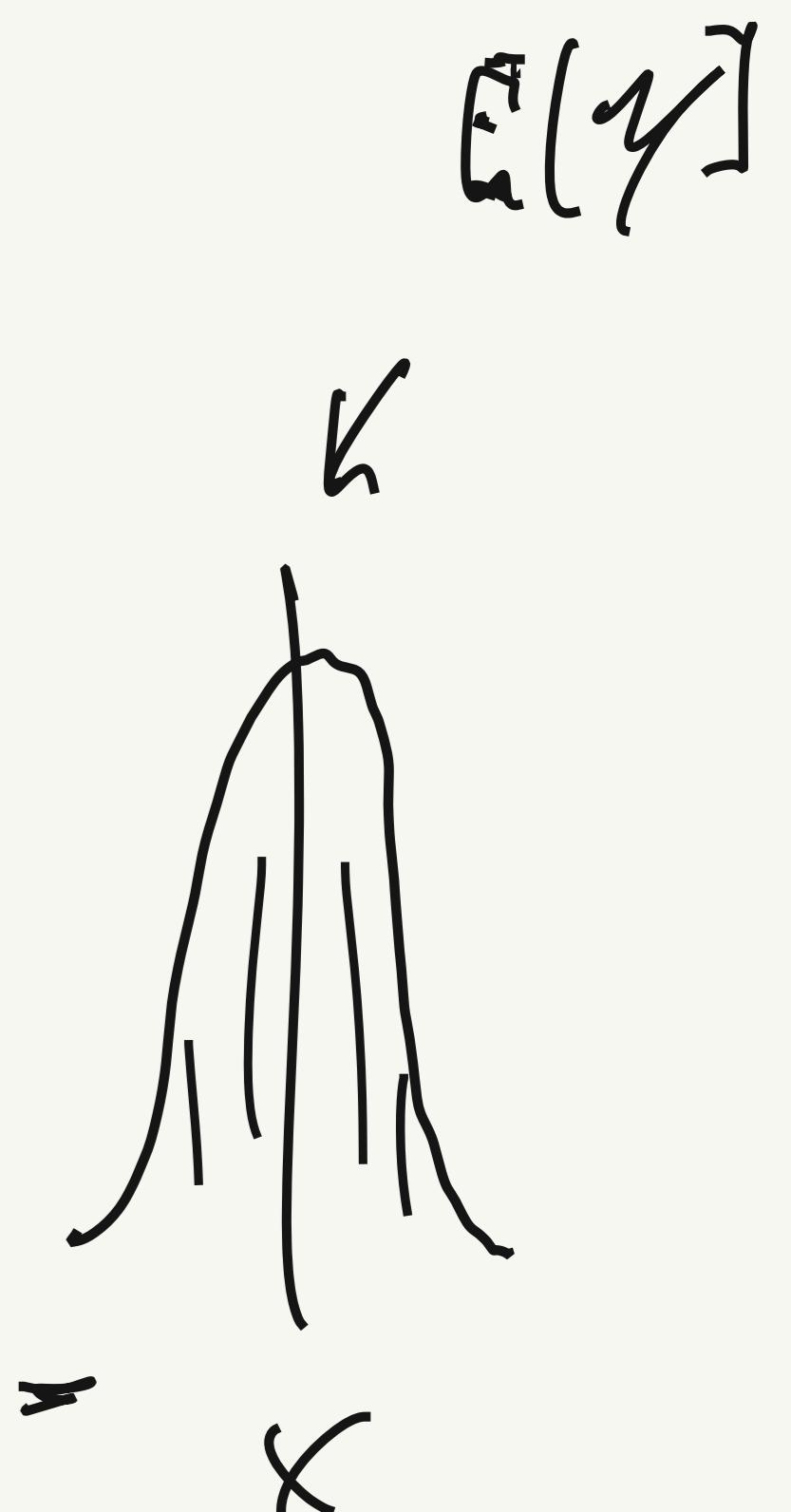
$$\max \left( - \int P(\gamma) \gamma \ln(P(\gamma | \gamma)) d\gamma \right)$$

for  $\gamma = \text{constraints}$

$$= \int P(\gamma|I) \ln \left( \frac{P(\gamma|I)}{P(\gamma)} \right) = S[\gamma]$$

$\Rightarrow$  relative entropy

$$\arg\max(S[\gamma]) = \overbrace{\hspace{1cm}}$$



$$S[\gamma] = \int P(\gamma | J) \ln(P(\gamma | J)) d\gamma$$

$$\frac{\partial S[\gamma]}{\partial P(\gamma)} = 0$$

$\Rightarrow$

$$\Rightarrow \ln(\gamma) + \lambda \cdot J = 0$$

$$\Rightarrow \gamma = e^{-\lambda J}$$

$$S'[\gamma] = S[\gamma_3 + \lambda \cdot J]$$

$$+ \lambda_1 J_1 + \lambda_2 J_2$$

$$\lambda \cdot \int_{-J}^J J(\gamma) P(\gamma) d\gamma$$

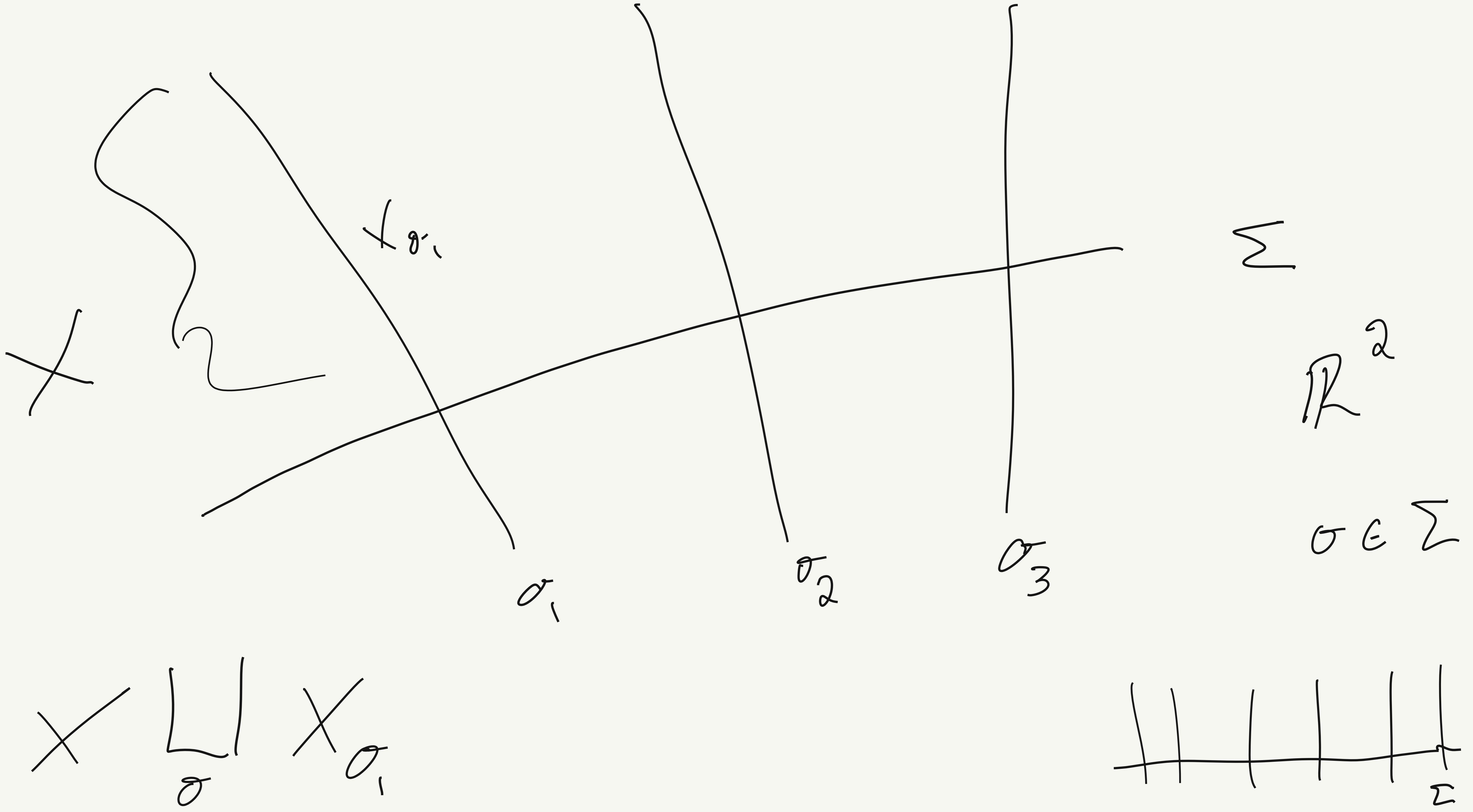
$$\lambda \int y P(y) dy$$

$$y = \frac{E}{T}$$

$$\lambda^{-1} = k_B$$

$$\ln(\gamma) + \lambda y \Rightarrow y = \exp(-\lambda)$$

$$\exp \left( -\frac{\sum}{k_B T} \right)$$

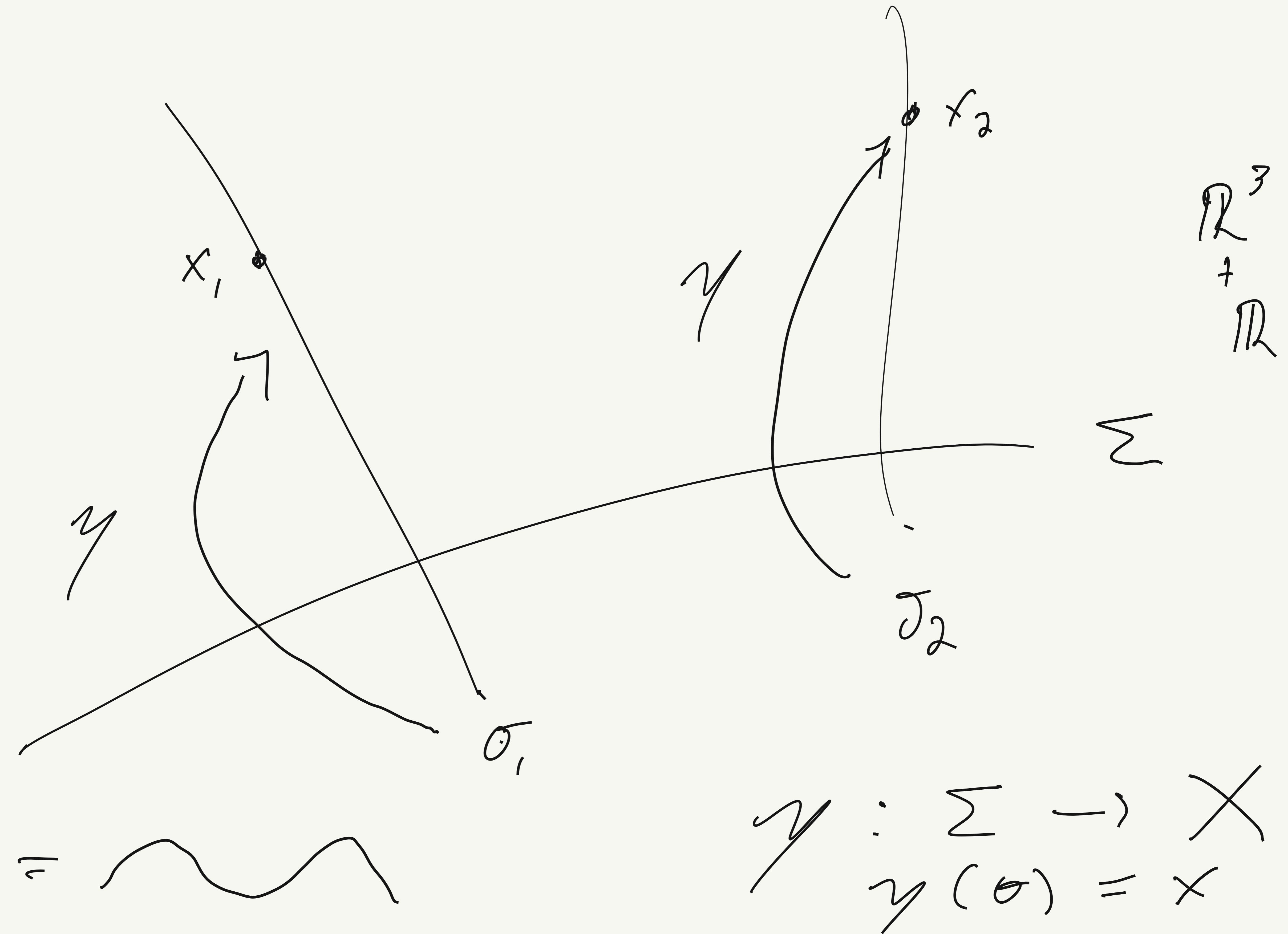


$x \in X$

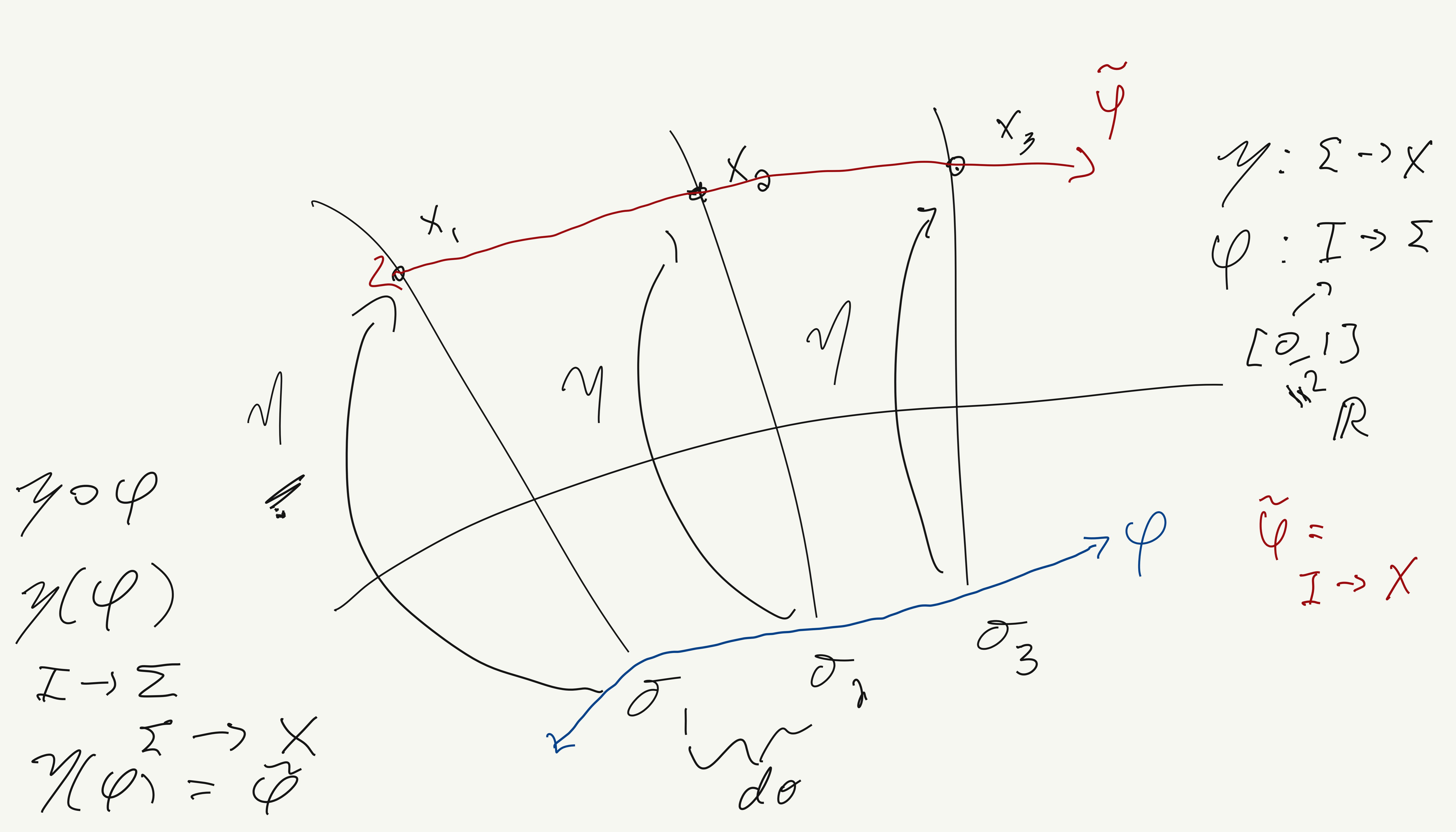
$$U(\gamma) = S'$$

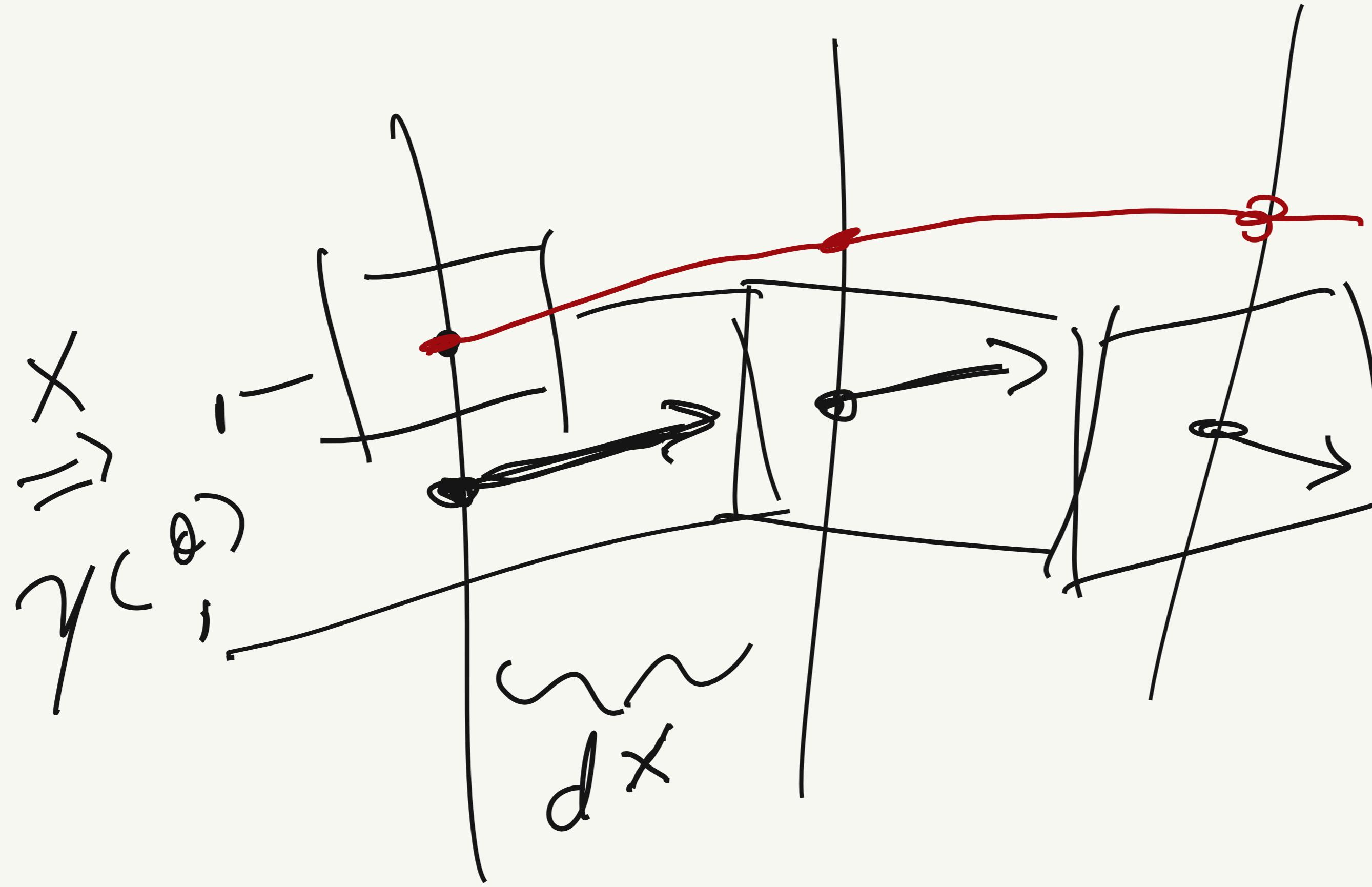
$$e^{i\theta} \in U(\gamma)$$

$$\gamma: \Sigma \rightarrow X$$
$$\psi(x) =$$



$$\gamma: \Sigma \rightarrow X$$
$$\gamma(\theta) = x$$





$\tilde{\varphi}'(x)$

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

(3)  $y(\theta) = x$

$H T_x x$

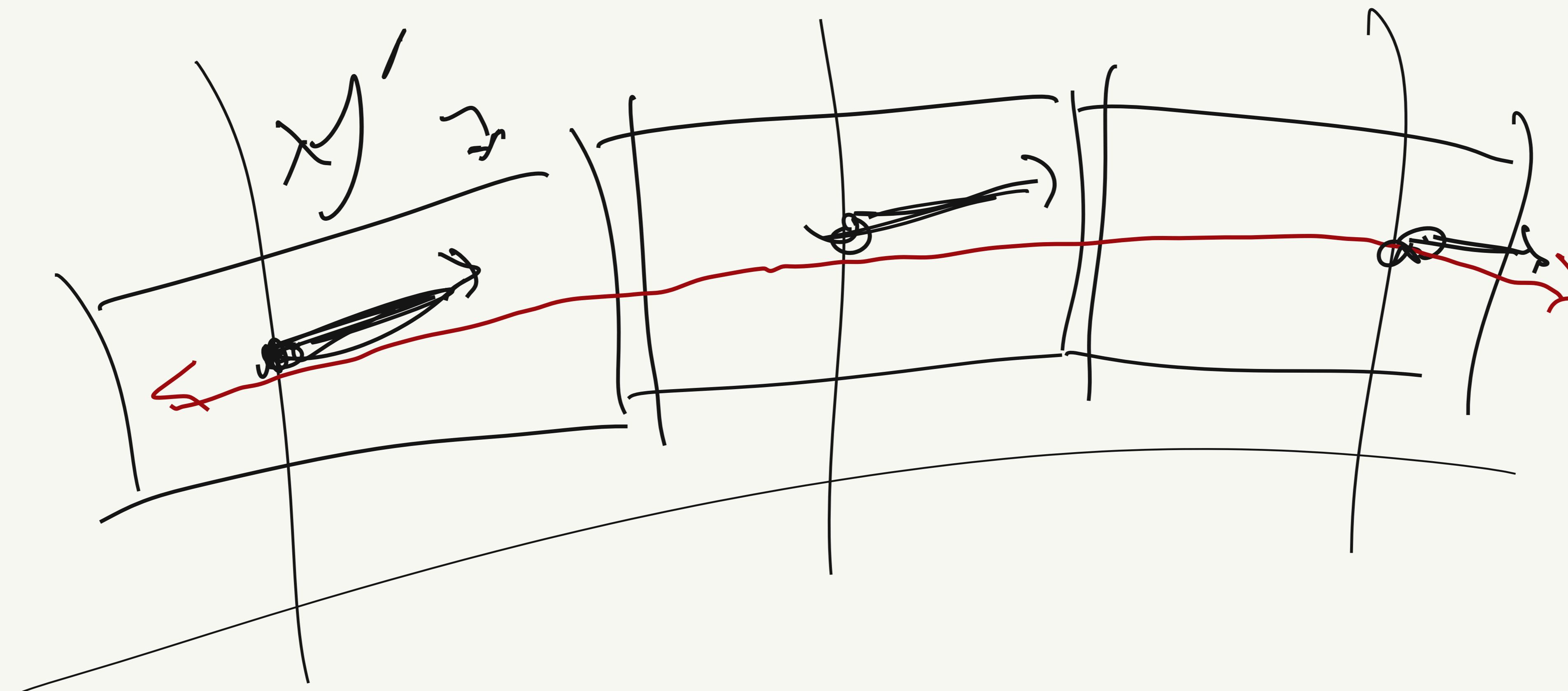
$y_0 \varphi = \tilde{\varphi}$

$d\gamma = T\Sigma \rightarrow$

$T \gamma_0 x$



$v \in T_x \Sigma \forall \sigma$



$$\nabla := H T_x X$$

$\Sigma$

$$dy \mapsto T_x^y$$

$$\tilde{\phi}'$$

$y^0 y$

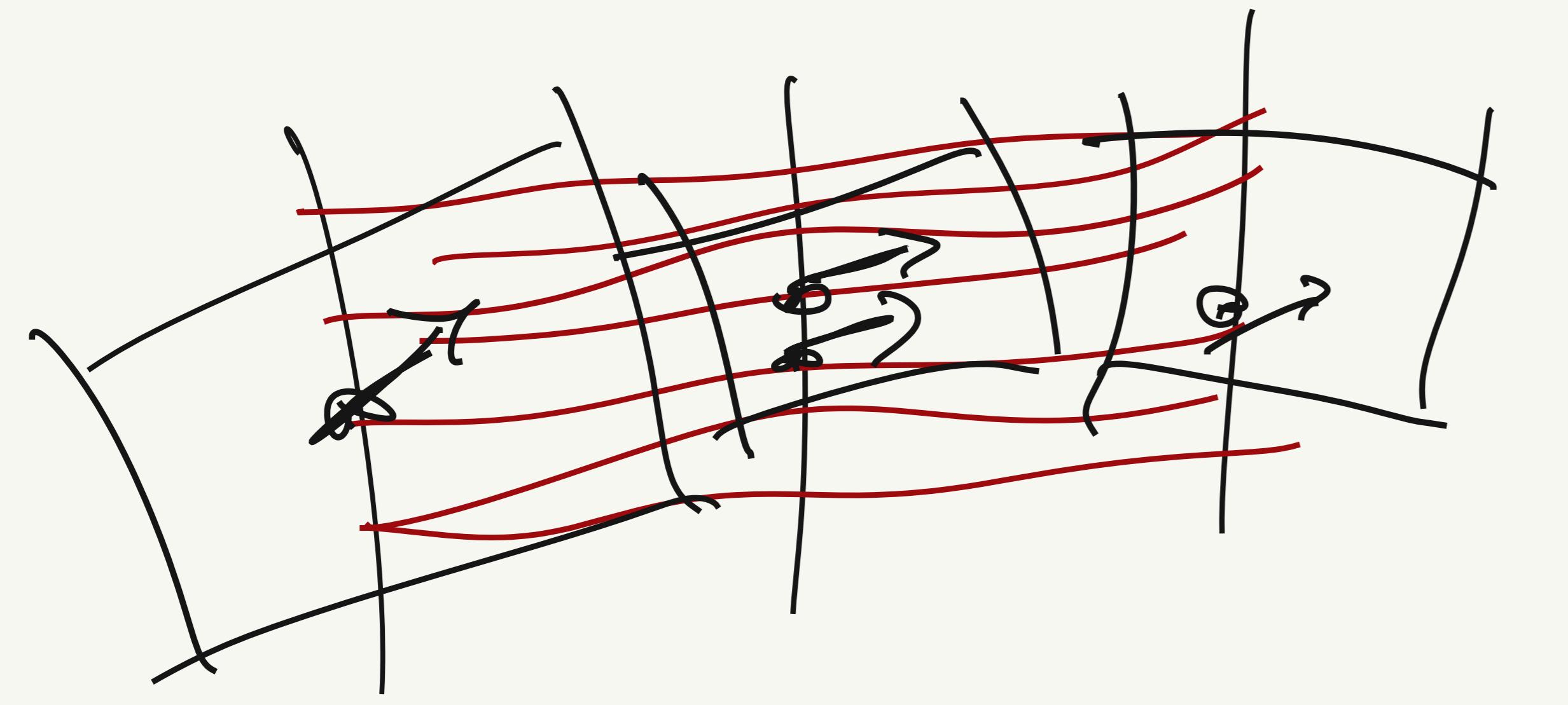
$\tilde{y}$  = Observable

$\tilde{x}$  = unknown data generating process  
 $y | \tilde{x}$

$$\nabla := H T_x X$$

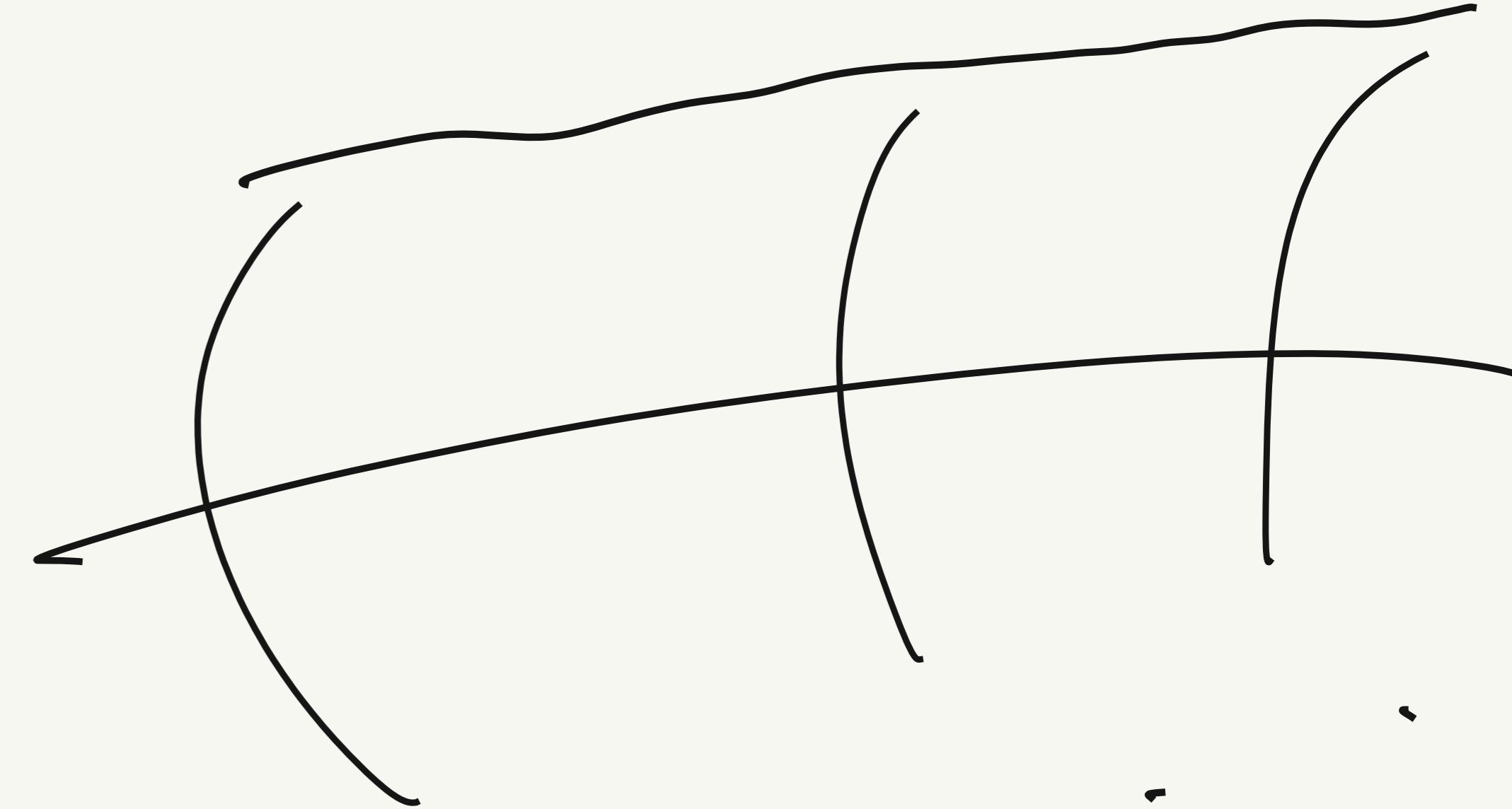
$$\xrightarrow{\quad} \tilde{\phi}'(x) = -x J'(x) \leftarrow \text{specifies possible tangent vectors}$$

$$x = y = \{x(t), \dots, x(t_f)\}$$



$$-J' = \tilde{\psi}' V \tilde{\psi}$$

$$-J' \Rightarrow \nabla_{\tilde{\psi}} \tilde{\psi} = 0$$



$$U_k \Rightarrow$$

$$\nabla_x^* \nabla = \Rightarrow$$

$$A_k \quad A = \sum_k A_k d\omega^\ell$$

$$\nabla(\gamma) \quad (\gamma: \Sigma \rightarrow X) \mapsto x^\nabla \mapsto A$$

$$\alpha \in U_\alpha$$

$$y'_k = \underbrace{A_k(\varphi)}_{y^* \triangleright} y_k$$

$$y = \underbrace{\sum}_{\Sigma} A_k(\varphi) \}$$

$$y = \underbrace{- \int}_{\Sigma} x_j' \}$$

$$y = \text{exp} \left\{ -xy^3 \right\} \quad (4)$$

$$\text{tra}(y)$$

$$\int e^{S_{kin}} \cdot \text{tra}(y) \downarrow$$

$$dx$$

$$\epsilon \in \mathcal{A}(\text{Norm}(y))$$

$$\cancel{dx \in \text{tra}(y)}$$

$$J = - \int P(y) \ln(P(y)) dy$$

$$= -\lambda \left( \int P(y) dy - 1 \right)$$

$$J_k \stackrel{2}{=} F(y)_h$$

$$\stackrel{1}{=} E(J(z))$$

$$= \mu \int C(y) P(y) dy - C$$

$$= \nu \left( \int W(y) P(y) dy - S \right)$$

$$= \eta \left( \int H(y) P(y) dy + \Sigma \right)$$

$$0 = \partial S = \ln(P(\gamma)) - \lambda_0 \gamma$$
$$e^{-(\lambda_0 \gamma)}$$

$$\langle \gamma \rangle = \gamma$$