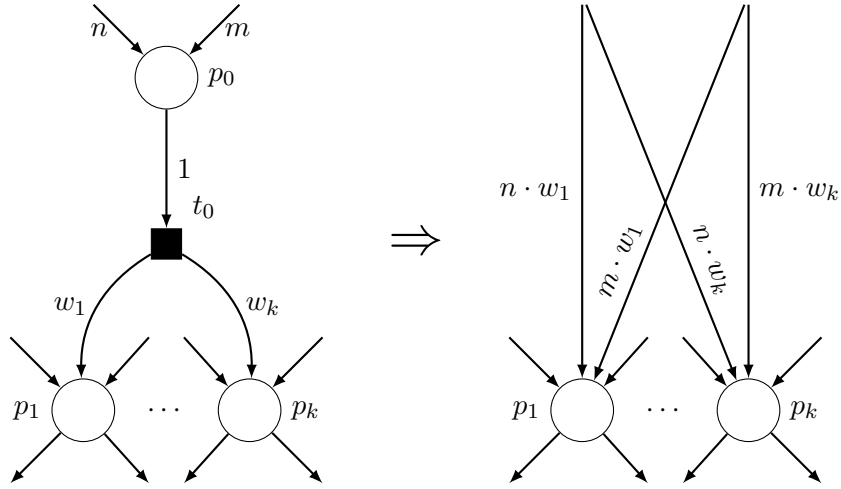


## Rule A: Sequential transition removal (P/T)

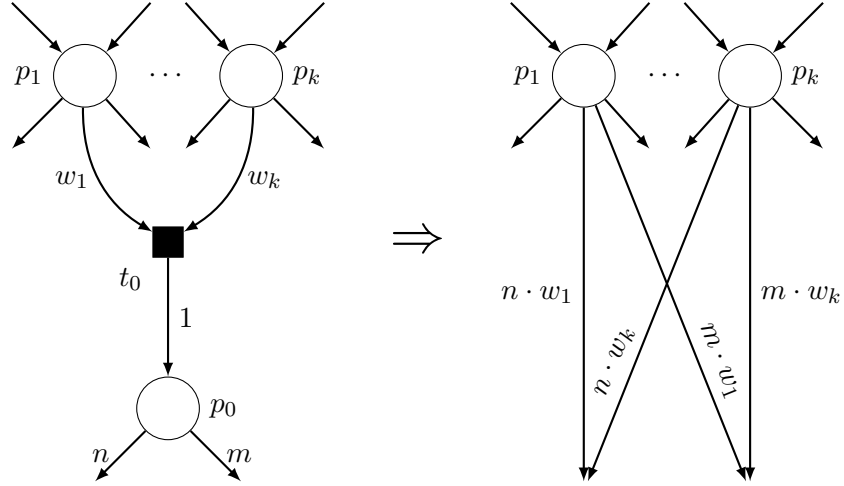
Rule A merges sequential transitions, i.e. a transition and another transition that must precede or follow it. Rule A is equivalent to a pre (or post) agglomeration with exactly one consumer (or producer) with a weight of 1. The two variants of Rule A can be seen in Figure 1 and Figure 2.

**Theorem 1** *The two variants of Rule A in Figure 1 and Figure 2 are both correct for  $LTL \setminus X$  cardinality properties.*



Precondition	Update
Fix $p_0$ and $t_0$ where $t_0^\bullet = \{p_1, \dots, p_k\}$ s.t.:	
A1) $\bullet t_0 = \{p_0\}$ and $\boxtimes(p_0, t_0) = 1$	UA1) For all $p \in \{p_1, \dots, p_k\}$ change the initial marking s.t. $M'_0(p) := M_0(p) + M_0(p_0) \cdot \boxtimes(t_0, p)$
A2) $p_0^\bullet = \{t_0\}$ and $p_0 \notin \{p_1, \dots, p_k\}$	UA2) For all $t \in \bullet p_0$ and all $p \in \{p_1, \dots, p_k\}$ set $\boxtimes'(t, p) := \boxtimes(t, p) + \boxtimes(t, p_0) \cdot \boxtimes(t_0, p)$
A3) $p_0^\circ = p_1^\circ = \dots = p_k^\circ = {}^\circ t_0 = \emptyset$	UA3) Remove $p_0$ and $t_0$
A4) $\{p_0, p_1, \dots, p_k\} \cap places(\varphi) = \emptyset$	

Figure 1: Rule A: Sequential transition removal (pre)



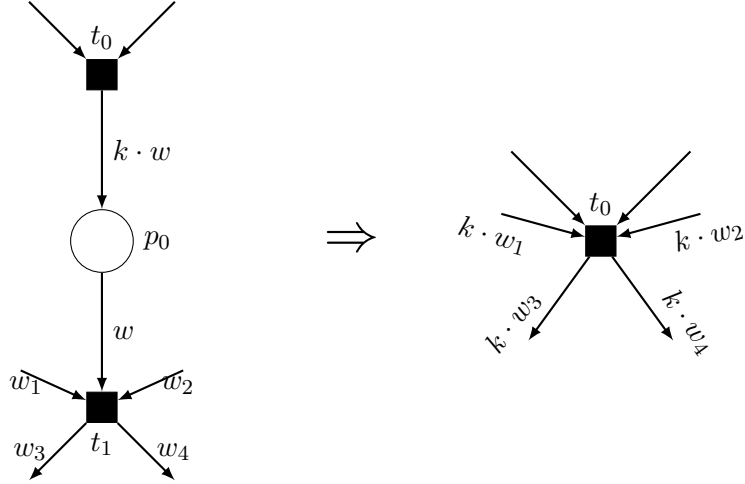
Precondition	Update
Fix $p_0$ and $t_0$ where $\bullet t_0 = \{p_1, \dots, p_k\}$ s.t.: A1) $t_0^\bullet = \{p_0\}$ and $\boxplus(t_0, p_0) = 1$ A2) $\bullet p_0 = \{t_0\}$ and $p_0 \notin \{p_1, \dots, p_k\}$ A3) $p_0^\circ = p_1^\circ = \dots = p_k^\circ = {}^\circ t_0 = \emptyset$ A4) $\{p_0, p_1, \dots, p_k\} \cap places(\varphi) = \emptyset$ A5) $M_0(p_0) = 0$	UA1) For all $t \in p_0^\bullet$ and all $p \in \{p_1, \dots, p_k\}$ set $\boxplus'(p, t) := \boxplus(p, t) + \boxplus(p_0, t) \cdot \boxplus(p, t_0)$ UA2) Remove $p_0$ and $t_0$

Figure 2: Rule A: Sequential transition removal (post)

## Rule B: Sequential place removal (P/T)

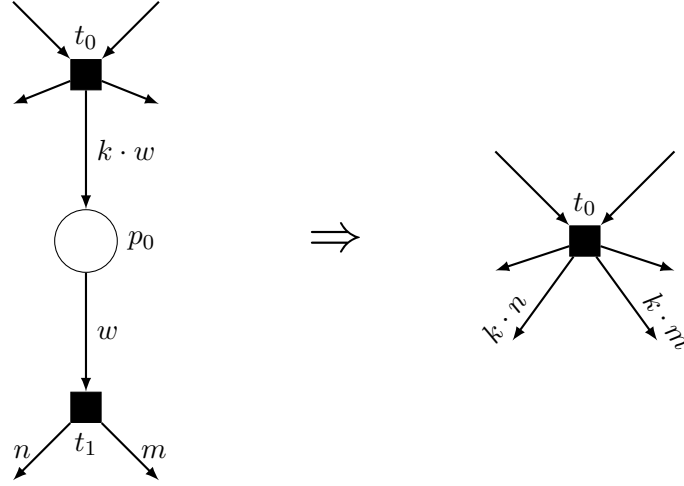
Rule B merges two transitions surrounding a place with no other transitions than the two. Rule B is equivalent to an agglomeration with exactly one producer and one consumer, but allow them to have different weights. Hence, there is a pre- and post-agglomeration variant of Rule B defined in Figure 3 and Figure 4, respectively.

**Theorem 2** *The two variants of Rule B in Figure 3 and Figure 4 are both correct for  $LTL \setminus X$  cardinality properties.*



Precondition	Update
Fix $p_0$ and $t_0, t_1$ where $t_0 \neq t_1$ s.t.:	
B1) $\bullet p_0 = \{t_0\}, p_0^\bullet = \{t_1\}, t_0^\bullet = \{p_0\}$	UB1) For all $p \in P \setminus \{p_0\}$ set $\Xi'(p, t_0) := \Xi(p, t_0) + k \cdot \Xi(p, t_1)$
B2) $\boxplus(t_0, p_0) = k \cdot \boxplus(p_0, t_1)$ for $k \geq 1$	UB2) For all $p \in P \setminus \{p_0\}$ set $\boxplus'(t_0, p) := \boxplus(t_0, p) + k \cdot \boxplus(t_1, p)$
B3) $p_0^\circ = {}^\circ t_0 = {}^\circ t_1 = \emptyset$	UB3) Remove $p_0$ and $t_1$
B4) $p_0 \notin places(\varphi)$ and $M_0(p_0) = 0$	
B5) $p^\circ = \emptyset$ and $p \notin places(\varphi)$ for all $p \in \bullet t_0$	

Figure 3: Rule B: Sequential place removal (pre)



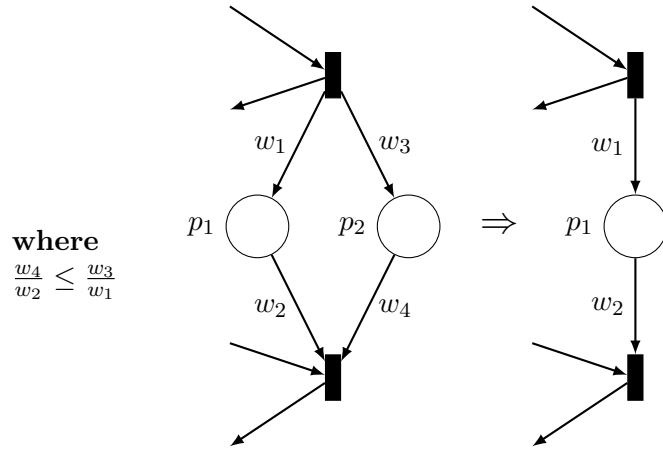
Precondition	Update
Fix $p_0$ and $t_0, t_1$ where $t_0 \neq t_1$ s.t.: B1) $\bullet p_0 = \{t_0\}, p_0^\bullet = \{t_1\}, \bullet t_1 = \{p_0\}$ B2) $\boxplus(t_0, p_0) = k \cdot \boxplus(p_0, t_1)$ for $k \geq 1$ B3) $p_0^\circ = {}^\circ t_0 = {}^\circ t_1 = \emptyset$ B4) $p_0 \notin places(\varphi)$ B5) $p^\circ = \emptyset$ and $p \notin places(\varphi)$ for all $p \in t_1^\bullet$	UB1) For all $p \in P \setminus \{p_0\}$ set $M'_0(p) := M_0(p) + \lfloor M_0(p_0) / \boxplus(p_0, t_1) \rfloor \cdot \boxplus(t_1, p)$ UB2) For all $p \in P \setminus \{p_0\}$ set $\boxplus'(t_0, p) := \boxplus(t_0, p) + k \cdot \boxplus(t_1, p)$ UB3) Remove $p_0$ and $t_1$

Figure 4: Rule B: Sequential place removal (post)

## Rule C: Parallel Places (P/T)

When two places are symmetrically parallel to each other and one may accumulate tokens, Rule C will remove it. See Figure 5. By convention  $\min \emptyset = -\infty$  and  $\max \emptyset = \infty$ . The fraction  $d$  describes how fast tokens can be consumed from  $p_2$  compared to  $p_1$ , while  $f$  describes how slow tokens can be fed to  $p_2$  compared to  $p_1$ . If  $d \leq f$  then  $p_2$  is always fed faster than it is emptied compared to  $p_1$ , which means  $p_2$  can be removed, since it will always be  $p_1$  which is missing tokens and disables their consumers.

**Theorem 3** *Rule C shown in Figure 5 are correct for  $CTL^*$  cardinality properties.*

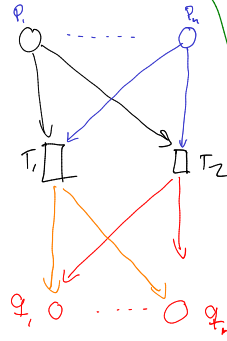


Precondition	Update
Fix places $p_1$ and $p_2$ s.t.: C1) $p_2 \notin places(\varphi)$ C2) $p_2^\circ = \emptyset$ C3) $p_1^\bullet \neq \emptyset$ C4) $p_1^\bullet \supseteq p_2^\bullet$ C5) $\bullet p_1 \subseteq \bullet p_2$ C6) $M_0(p_2) \geq M_0(p_1) \cdot d$ C7) $d \leq f$ where $d = \max_{t \in p_1^\bullet} \frac{\boxminus(p_2, t)}{\boxminus(p_1, t)}$ $f = \min_{t \in \bullet p_1} \frac{\boxplus(t, p_2)}{\boxplus(t, p_1)}$	UC1) Remove $p_2$

Figure 5: Rule C: Parallel places



Prob. Not  
Implemented



$\lambda \notin \mathcal{P}$

$\exists k \in \mathbb{N}, k > 0$

$\forall p \in \mathcal{P} \quad I(p, t_1) \geq I(p, t_2)$

$\forall p \in \mathcal{P} \quad w(p, t_1) \cdot k \leq w(p, t_2)$

$\forall p \in \mathcal{P} \quad w(t_1, p) \cdot k \geq w(t_2, p)$

$p \in \text{Places}(\mathcal{P}) \Rightarrow$  or  $\text{Inhib}(\mathcal{P})$

$w(p, t_1) \cdot k = w(p, t_2) \wedge$   
 $w(t_1, p) \cdot k = w(t_2, p)$

$\neg \text{ISReach}(\mathcal{P}) \Rightarrow k = 1$

$\text{LoopSensitive}(\mathcal{P}) \Rightarrow$

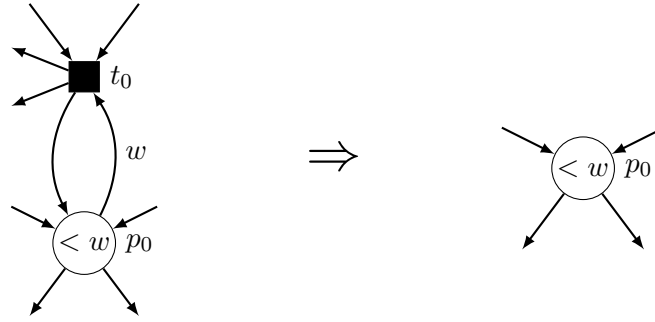
$\forall p \in \mathcal{P} \quad w(t_1, p) = w(t_2, p) \wedge$   
 $w(p, t_1) = w(p, t_2)$

$\forall p \in \mathcal{P} \quad I(p, t_1) \geq I(p, t_2)$

## Rule E: Dead transition removal (P/T)

If a transition is initially not enabled due to a lack of tokens in  $p_0$  and if  $p_0$  is not able to gain tokens, then the transition is dead and can be removed. See Figure 6.

**Theorem 4** *Rule E in Figure 6 is correct for  $CTL^*$  cardinality properties.*



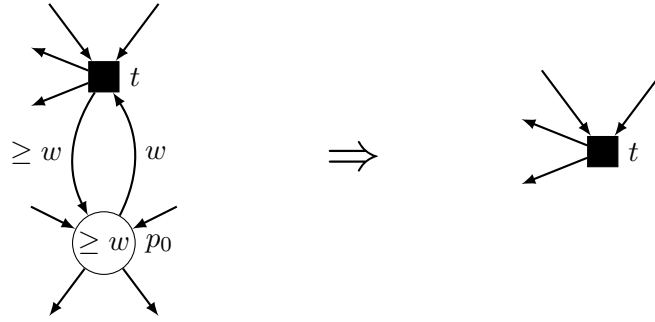
Precondition	Update
Fix place $p_0$ and transition $t_0$ s.t.: E1) $M_0(p_0) < \Xi(p_0, t_0)$ E2) $\Xi(t, p_0) \leq \Xi(p_0, t)$ or $M_0(p_0) < \Xi(p_0, t)$ for all $t \in T$	UE1) If $p_0^\bullet = \{t_0\}$ , $p_0^\circ = \emptyset$ , and $p_0 \notin places(\varphi)$ then remove $p_0$ . UE2) Remove $t_0$

Figure 6: Rule E: Dead transition removal

## Rule F: Redundant place removal (P/T)

Rule F defined in Figure 7 removes places which never inhibits any transitions. This is done by check the minimum number of tokens added to the given place and its initial marking.

**Theorem 5** *Rule F in Figure 7 is correct for CTL\*.*

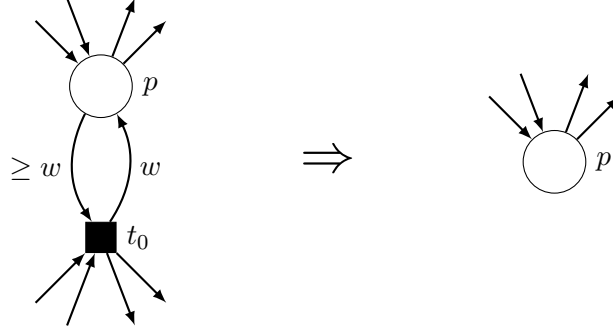


Precondition	Update
Fix place $p_0$ s.t.: F1) $p_0^\circ = \emptyset$ and $p_0 \notin places(\varphi)$ F2) $\boxplus(t, p_0) \geq \boxminus(p_0, t)$ and $M_0(p_0) \geq \boxminus(p_0, t)$ for all $t \in T$	UF1) Remove $p_0$

Figure 7: Rule F: Redundant place removal

## Rule G: Redundant transition removal (P/T)

Rule G in Figure 8 removes transitions that only remove tokens and thus disable behaviour.



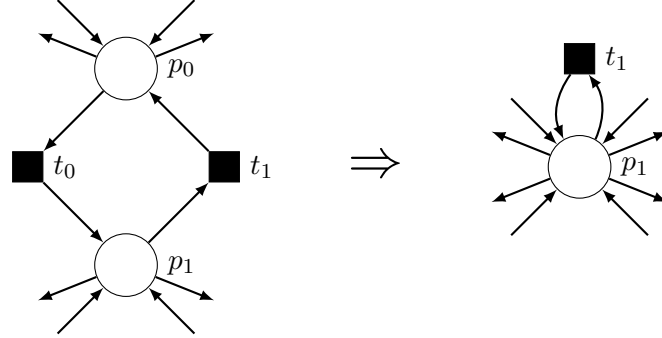
Precondition	Update
Fix transition $t_0$ s.t.: G1) ${}^\circ t_0 = \emptyset$ and $p^\circ$ for all $p \in \bullet t_0$ G2) $t_0^\bullet \supseteq \bullet t_0$ G2) For all $p \in \bullet t_0$ we have either <ul style="list-style-type: none"> <li>– <math>\boxminus(p, t_0) = \boxplus(t_0, p)</math>, or</li> <li>– <math>\boxminus(p, t_0) &gt; \boxplus(t_0, p)</math> and <math>p \notin places(\varphi)</math></li> </ul>	UG1) Remove $t_0$

Figure 8: Rule G: Redundant transition removal

**Theorem 6** *Rule G in Figure 8 is correct for reachability cardinality queries.*

## Rule H: Simple cycle removal (P/T)

Rule H in Figure 9 removes cycles consisting of two places and two transitions.



Precondition	Update
Fix different $p_0, p_1, t_0, t_1$ s.t.:	
H1) $\bullet t_0 = t_1^\bullet = \{p_0\}$	UH1) For all $t \in T$ :
H2) $\bullet t_1 = t_0^\bullet = \{p_1\}$	$\boxplus'(t, p_1) = \boxplus(t, p_1) + \boxplus(t, p_2)$
H3) $p_0^\circ = p_1^\circ = {}^\circ t_0 = {}^\circ t_1 = \emptyset$	$\boxminus'(p_1, t) = \boxminus(p_1, t) + \boxminus(p_2, t)$
H4) $p_0 \notin places(\varphi), p_1 \notin places(\varphi)$	UH2) $\boxplus(t_1, p_1) = \boxminus(p_1, t_1) = 1$
H5) $\boxminus(p_0, t_0) = \boxplus(t_0, p_1) =$ $\boxminus(p_1, t_1) = \boxplus(t_1, p_1) = 1$	UH3) $M'_0(p_1) = M_0(p_1) + M_0(p_0)$
	UH4) Remove $t_0$
	UH5) Remove $p_0$

Figure 9: Rule H: Simple cycle removal

**Theorem 7** *Rule H in Figure 9 is correct for reachability cardinality queries.*

## Rule I: Irrelevant places and transitions (P/T)

Only some places and transitions are relevant for the query. Algorithm 1 shows how to remove everything that is irrelevant by propagating relevance.

---

### Algorithm 1: Rule I: Irrelevant places and transitions

---

**Input:** A P/T net  $N = \langle P, T, \Xi, \boxplus, I \rangle$ , initial marking  $M_0$  and reachability formula  $\varphi$  without *deadlock*

**Output:** A reduced net  $N'$  and its initial marking  $M'_0$

```

1  $X := \emptyset$                                      /* Relevant transitions */
2  $Q := \text{transitions}(\varphi) \cup \bullet \text{places}(\varphi) \cup \text{places}(\varphi) \bullet$       /* Queue of
   transitions */
3 while  $Q \neq \emptyset$  do
4   Pick any  $t \in Q$ 
5    $Q := Q \setminus \{t\}$ 
6    $X := X \cup \{t\}$                                      /* Mark as relevant */
7    $Q := Q \cup \boxplus(\bullet t) \setminus X$                 /* Enqueue transitions that can
   enable  $t$  */
8    $Q := Q \cup (\circ t)^\boxminus \setminus X$ 
9  $P' := \bullet X \cup \circ X \cup \text{places}(\varphi)$ 
10  $T' := X$ 
11  $N' :=$  a copy of  $N$  but every place  $p \notin P'$  and every transition
    $t \notin T'$  have been removed.
12  $M'_0 :=$  a marking s.t.  $M'_0(p) = M_0(p)$  for all  $p \in P'$ .
13 return  $N'$  and  $M'_0$ 

```

---

**Theorem 8** *Rule I in Algorithm 1 is correct for reachability without deadlock.*

## **Rule J: Place downscaling (P/T)**

Divide the weight of all in- and out-going arcs and the initial marking with their greatest common divisor.

TODO

## **Rule K: Missing documentation (P/T)**

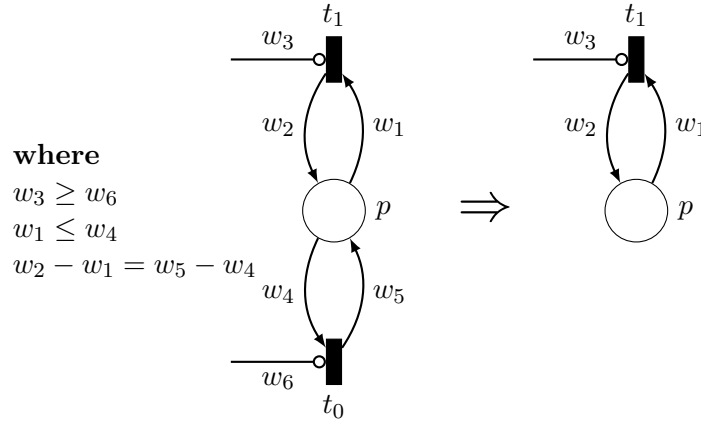
Rule K is to some extent similar to Rule I, but tries to preserve liveness.

TODO



## Rule L: Dominated Transition (P/T)

Rule L removes transitions that have the same effect as another transition, but with more preconditions. Since both transitions lead to the same state, we can therefore remove the one with the higher preconditions and use the other instead. See the formal description in Figure 10.



Precondition	Update
Fix transition $t_1$ and $t_0$ s.t.:	
L1) $I(t_1) \geq I(t_0)$	UL1) Remove $t_0$
L2) $\Xi(t_1) \leq \Xi(t_0)$	
L3) $E(t_1) = E(t_0)$	

Figure 10: Rule L: Dominated Transition

**Theorem 9** *Rule L in Figure 10 is correct for  $CTL^*$  cardinality properties.*

## Rule M: Effectively dead places and transitions (P/T)

The Rule M finds and removes effectively dead places and transitions. We define an effectively dead place to be a place that will never gain nor lose tokens. Effectively dead transitions are transitions that are initially disabled (and/or inhibited) by a place that cannot gain (and/or lose) tokens. These places and transitions are found using fixed-point iteration as defined in Algorithm 2.

---

### Algorithm 2: Rule M: Effectively dead places and transitions

---

**Input:** A net  $N = \langle P, T, \Xi, \Theta, I \rangle$ , initial marking  $M_0$  and CTL\* formula  $\varphi$

**Output:** A reduced net  $N'$  and its initial marking  $M'_0$

```

1  $S_{\leq} := P$                                 /* Places that cannot gain tokens */
2  $S_{\geq} := P$                                 /* Places that cannot lose tokens */
3  $F := T$                                     /* Transitions that cannot fire */
4 do
    |   /* Find transitions that may fire and update sets
    |   accordingly */
5   foreach  $t \in F$  where
    |    $\forall p \in P. (\Xi(p, t) \leq M_0(p) \vee p \notin S_{\leq}) \wedge (I(p, t) > M_0(p) \vee p \notin S_{\geq})$ 
    |   do
6   |    $F := F \setminus \{t\}$ 
7   |    $S_{\leq} := S_{\leq} \setminus t^{\Theta}$ 
8   |    $S_{\geq} := S_{\geq} \setminus \Xi t$ 
9 until  $S_{\leq}$ ,  $S_{\geq}$ , and  $F$  do not change
10  $P' := P \setminus (S_{\leq} \cap S_{\geq} \setminus \text{places}(\varphi))$ 
11  $T' := T \setminus F$ 
12 return  $N' = \langle P', T', \Xi, \Theta, I \rangle$  and  $M_0$ 
```

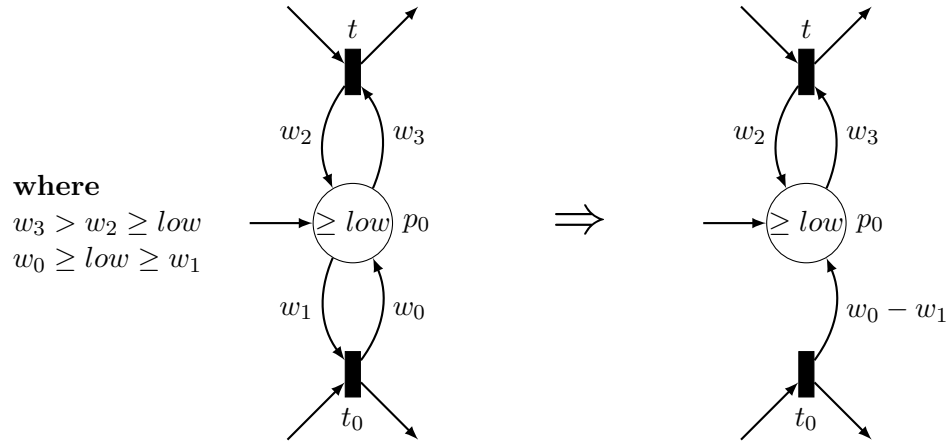
---

**Theorem 10** *Rule M in Algorithm 2 is correct for CTL\* cardinality properties.*

**Theorem 11** *Rule M supercedes Rule E.*

## Rule N: Redundant arc removal (P/T)

The lower bound number of tokens at a place  $p_0$  is given by the minimum of the initial marking and the number of tokens returned by any consuming transition with a negative effect on  $p_0$ . Using the lower bound we can then find transitions, which are never disabled by  $p_0$  and remove the transition's dependency on  $p_0$ , since it is unnecessary, as long as we maintain the effect of firing the transition.



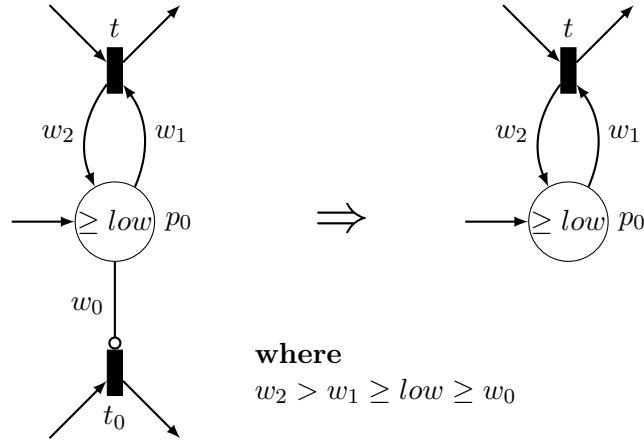
Precondition	Update
Fix place $p_0$ and transition $t_0$ s.t.:	
N1) $t_0 \in p_0^\bullet \setminus p_0^\boxminus$	UN1) Set $\boxplus(p_0, t_0) := \boxplus(p_0, t_0) - \boxminus(p_0, t_0)$
N2) $\boxminus(p_0, t_0) \leq low$	UN2) Set $\boxminus(p_0, t_0) := 0$
where	
$low = \min\{M_0(p_0)\} \cup \{\boxplus(p_0, t) \mid t \in p_0^\boxminus\}$	

Figure 11: Rule N: Redundant arc removal

**Theorem 12** *Rule N in Figure 11 is correct for CTL\*.*

## Rule O: Inhibited transition (P/T)

We can find the lower bound of tokens at a place  $p_0$ . Any inhibitor arc from  $p_0$  with a weight smaller than the lower bound always inhibits the given transition, which means that the transition can be removed. See Figure 12 for a formal description of Rule O.



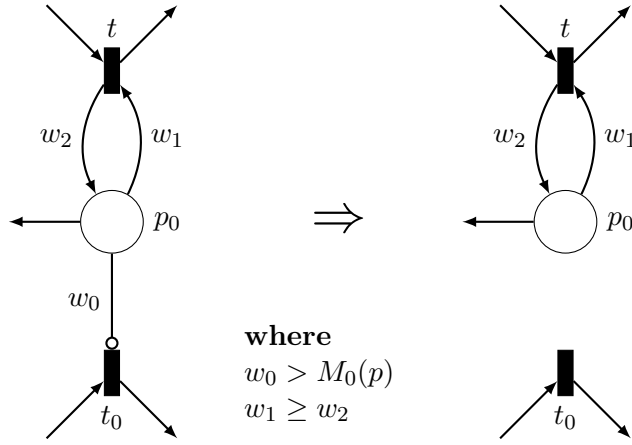
Precondition	Update
Fix place $p_0$ and transition $t_0$ s.t.: O1) $t_0 \in p_0^\circ$ O2) $I(p_0, t_0) \leq low$ where $low = \min\{M_0(p_0)\} \cup \{\boxplus(p_0, t) \mid t \in p_0^\boxminus\}$	UO1) Remove $t_0$ .

Figure 12: Rule O: Inhibited transition

**Theorem 13** *Rule O in Figure 12 is correct for CTL\* cardinality properties.*

## Rule P: Redundant inhibitor arc (P/T)

Sometimes we can find an upper bound on the number of tokens at a place  $p_0$ . This upper bound is given by the initial marking if all transitions have a non-positive effect on  $p_0$ . Any inhibitor arc from  $p_0$  with a weight higher than the upper bound of  $p_0$  therefore never inhibits, which means the inhibitor arc can be removed. See Figure 13 for a formal description of Rule P.



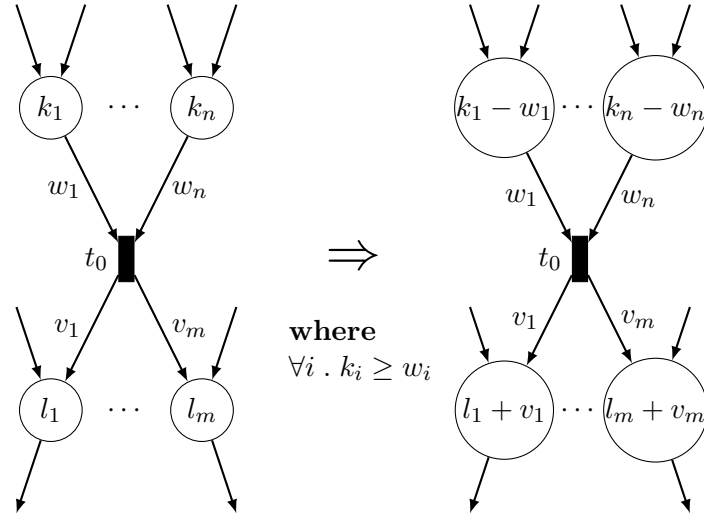
Precondition	Update
Fix place $p_0$ and transition $t_0$ s.t.: P1) $t_0 \in p_0^\circ$ P2) $I(p_0, t_0) > M_0(p_0)$ P3) $\boxplus_{p_0} = \emptyset$	UP1) $I(p_0, t_0) = \infty$ .

Figure 13: Rule P: Redundant inhibitor arc

**Theorem 14** *Rule P in Figure 13 is correct for CTL\*.*

## Rule Q: Preemptive transition firing (P/T)

Rule Q evaluates transitions that are initially enabled and are the only consumer of all places in its pre set. The formal description of Rule Q can be found in Figure 14. Remark that Rule Q can potentially put tokens into places which will prevent other reductions. Furthermore, it can be applied infinitely if  $\Xi(t_0) \leq \boxplus(t_0)$ , or if the Petri net contains a loop.



Precondition	Update
Fix transition $t_0$ s.t.: Q1) $(\bullet t)^\bullet = \{t_0\}$ Q2) $\Xi(t_0) \leq M_0 < I(t_0)$ Q3) $(\bullet t_0 \cup t_0^\bullet) \cap places(\varphi) = \emptyset$ Q4) $(\bullet t_0)^\circ = (t_0^\bullet)^\circ = \emptyset$	UQ1) $M_0 := M_0 + E(t_0)$ .

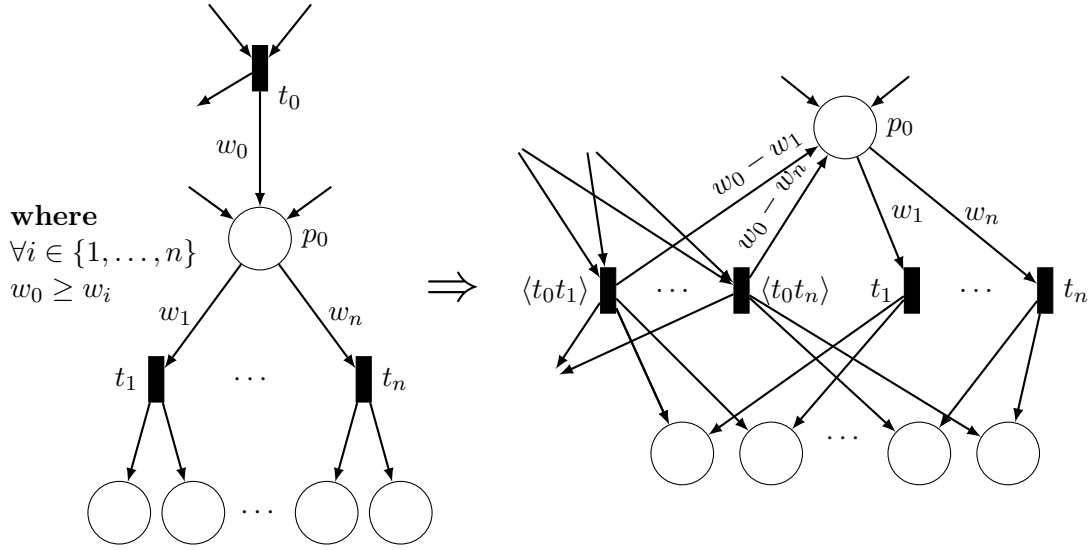
Figure 14: Rule Q: Preemptive transition firing

**Theorem 15** *Rule Q in Figure 14 is correct for  $CTL \setminus X$  cardinality properties.*

## Rule R: Atomic post-agglomerable producer (P/T)

Rule R is similar to a post agglomeration rule and a formal description of Rule R is in Figure 15. In Rule R we look for a place  $p_0$  with a producer  $t_0$  such that  $t_0$  can always be followed by a firing of any consumer of  $p_0$  without inhibiting other transitions or affecting places in  $places(\varphi)$ . The producer  $t_0$  is then replaced with new transitions, one for each consumer, and these new transitions combine the effect of firing  $t_0$  and the given consumer. Similarly to an agglomeration rule, Rule R removes interleavings despite potentially increasing the size of the Petri net. However, Rule R is more general, since it only operates on one producer at a time and leaves  $p_0$  untouched, allowing tokens in  $p_0$  in the initial marking, which a post agglomeration does not. Additionally, Rule R does not require the weights of the arcs to and from the agglomerated place to be equal, making R usable in many cases.

**Theorem 16** *Rule R in Figure 15 is correct for  $LTL \setminus X$  cardinality properties.*



Precondition	Update
Fix place $p_0$ and transition $t_0$ s.t.: R1) $t_0 \in \bullet p_0 \wedge p_0^\bullet \neq \emptyset$ R2) $\bullet p_0 \cap p_0^\bullet = \emptyset$ R3) $p_0^\circ = {}^\circ(p_0^\bullet) = ((p_0^\bullet)^\bullet)^\circ = \emptyset$ R4) $(\{p_0\} \cup (p_0^\bullet)^\bullet) \cap places(\varphi) = \emptyset$ R5) $\bullet(p_0^\bullet) = \{p_0\}$ R6) $\boxplus(t_0, p_0) \geq \boxminus(p_0, t)$ for all $t \in p_0^\bullet$	UR1) For each transition $t \in p_0^\bullet$ create a transition $\langle t_0 t \rangle$ with the following arcs: $\boxminus(\langle t_0 t \rangle) = \boxminus(t_0)$ $\boxplus(\langle t_0 t \rangle) = \boxplus(t_0) + \boxplus(t) - \boxminus(t)$ $I(\langle t_0 t \rangle) = I(t_0)$ UR2) Remove $t_0$

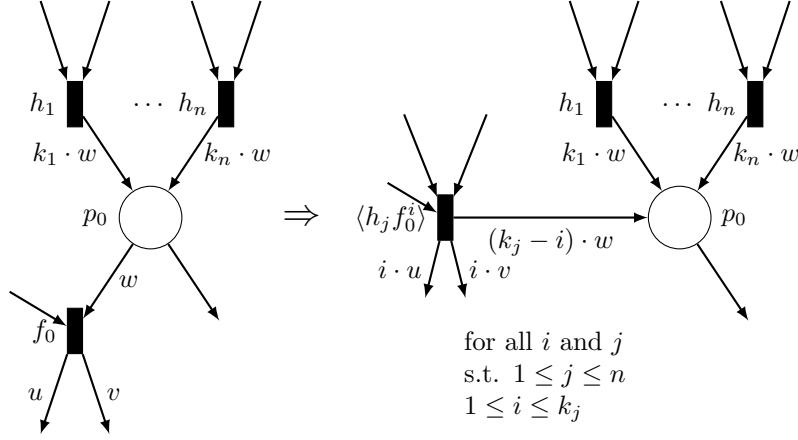
Figure 15: Rule R: Atomic post-agglomerable producer



## Rule S: Atomic free agglomeration (P/T)

A free agglomeration is a pre agglomeration, which does not require that the pre set of the preset of  $p_0$  has a single consumer. In turn, it is only correct for reachability with deadlocks. The atomic free agglomeration is similar to the free agglomeration, but is able to agglomeration one consumer at a time. See Figure 16 for its definition. Rule S also handles cases where the producer  $h$  produces  $k$  times more tokens than what the consumer  $f_0$  consumes. In this case, a transition  $\langle hf_0^i \rangle$  is created for each  $i \in [1, k]$ . Thus all relevant markings remain reachable.

**Theorem 17** *Rule S shown in Figure 16 is correct for deadlock-insensitive reachability properties.*



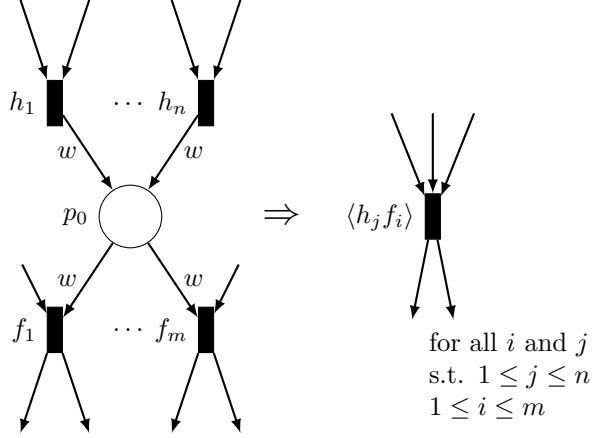
Precondition	Update
Fix place $p_0$ and transition $f_0$ s.t.: S1) $\{p_0\} \cap places(\varphi) = \emptyset$ S2) $(f_0 \cup \bullet p_0) \cap transitions(\varphi) = \emptyset$ S3) $M_0(p_0) < \boxplus(p_0, f_0)$ S4) $\bullet p_0 \cap p_0^\bullet = \emptyset$ S5) $f_0 \in p_0^\bullet$ and for all $h \in \bullet p_0$ there exists a $k \in \mathbb{N}$ s.t.: S6) $h^\bullet = \{p_0\}$ S7) $\bullet h \cap places(\varphi) = \emptyset$ S8) $p_0^\circ = {}^\circ h = (\bullet h)^\circ = \emptyset$ S9) $\boxplus(h, p_0) = k \cdot \boxplus(p_0, f_0)$ S10) $k > 1 \implies (f_0^\bullet)^\circ = \emptyset$ S11) $k > 1 \implies \bullet f_0 = \{p_0\}$	Create transition $\langle hf_0^i \rangle$ for all $i \in [1, k]$ , for $k = \boxplus(h, p_0) / \boxplus(p_0, f_0)$ , for all $h \in \bullet p_0$ . For each such transition: US1) $\boxplus(\langle hf_0^i \rangle, p_0) = \boxplus(h, p_0) - i \cdot \boxplus(p_0, f_0)$ and for all $p \in P \setminus \{p_0\}$ : US2) $\boxplus(p, \langle hf_0^i \rangle) = \boxplus(p, h) \uplus \boxplus(p, f_0)$ US3) $\boxplus(\langle hf_0^i \rangle, p) = i \cdot \boxplus(f_0, p)$ US4) $I(p, \langle hf_0^i \rangle) = I(p, f_0)$ and US5) Remove $f_0$ US6) If $p_0^\bullet = \emptyset$ , remove $p_0$ and all transi- tions in $\bullet p_0 \setminus transitions(\varphi)$

Figure 16: Rule S: Atomic free agglomeration

## Rule T: Pre agglomeration (P/T)

Rule T in Figure 17 is a pre agglomeration. In a pre agglomeration  $h \in \bullet p_0$  is invisible to the query and once enabled, it stays enabled. Hence, it can be delayed until an  $f \in p_0^\bullet$  needs it. Thus Rule T creates a transition  $\langle hf \rangle$  for every pair  $h \in \bullet p_0$  and  $f \in p_0^\bullet$ .

**Theorem 18** *Rule T described in Figure 17 is correct for  $LTL \setminus X$ .*



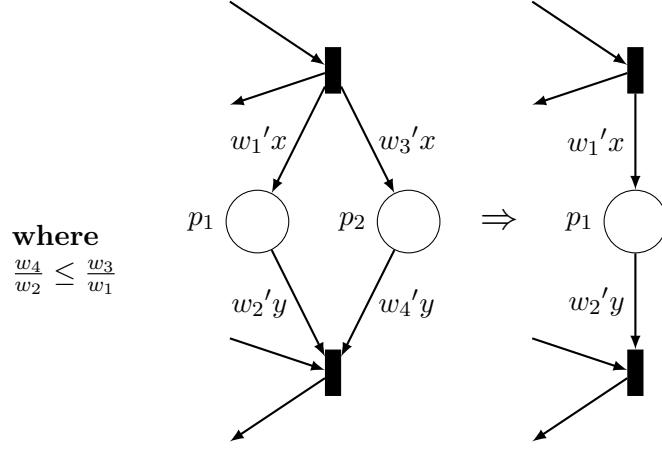
Precondition	Update
Fix place $p_0$ s.t.: T1) $(\{p_0\} \cap places(\varphi) = \emptyset$ T2) $(p_0^\bullet \cup {}^\bullet p_0) \cap transitions(\varphi) = \emptyset$ for all $h \in {}^\bullet p_0$ and $f \in p_0^\bullet$ : T3) $M_0(p_0) < \Xi(p_0, f)$ T4) ${}^\bullet p_0 \cap p_0^\bullet = \emptyset$ T5) $({}^\bullet h)^\bullet = \{h\}$ T6) $h^\bullet = \{p_0\}$ T7) ${}^\bullet h \cap places(\varphi) = \emptyset$ T8) $p_0^\circ = {}^\circ h = ({}^\bullet h)^\circ = \emptyset$ T9) $\boxplus(h, p_0) = \boxminus(p_0, f)$	Create transition $\langle hf \rangle$ for all $h \in {}^\bullet p_0$ and $f \in p_0^\bullet$ s.t. for all $p \in P \setminus \{p_0\}$ : UT1) $\boxminus(p, \langle hf \rangle) = \boxminus(p, h) + \boxminus(p, f)$ UT2) $\boxplus(\langle hf \rangle, p) = \boxplus(f, p)$ UT3) $I(p, \langle hf \rangle) = I(p, f)$ and UT4) Remove ${}^\bullet p_0$ , $p_0^\bullet$ and $p_0$

Figure 17: Rule T: Pre agglomeration

## Rule C: Parallel place removal (CPN)

When two places are symmetrically parallel to each other and one may accumulate tokens, Rule C will remove it. See Figure 18. By convention  $\min \emptyset = -\infty$  and  $\max \emptyset = \infty$ . The fraction  $d$  describes how fast tokens can be consumed from  $p_2$  compared to  $p_1$ , while  $f$  describes how slow tokens can be fed to  $p_2$  compared to  $p_1$ . If  $d \leq f$  then  $p_2$  is always fed faster than it is emptied compared to  $p_1$ , which means  $p_2$  can be removed, since it will always be  $p_1$  which is missing tokens and disables their consumers.

**Theorem 19** *Rule C shown in Figure 18 are correct for  $CTL^*$  properties.*



Precondition	Update
<p>Fix places <math>p_1</math> and <math>p_2</math> s.t.:</p> <p>C1) <math>\mathcal{X}(p_1) = \mathcal{X}(p_2)</math></p> <p>C2) <math>p_2 \notin places(\varphi)</math></p> <p>C3) <math>p_2^\circ = \emptyset</math></p> <p>C4) <math>p_1^\bullet \neq \emptyset</math></p> <p>C5) For all <math>t \in T</math>:</p> <p style="padding-left: 40px;"><math>\mathbf{Supp}(\boxminus(p_1, t)) = \mathbf{Supp}(\boxminus(p_2, t)) \wedge</math></p> <p style="padding-left: 40px;"><math>\mathbf{Supp}(\boxplus(t, p_1)) = \mathbf{Supp}(\boxplus(t, p_2))</math></p> <p>C6) <math>\mathbf{Supp}(M_0(p_1)) = \mathbf{Supp}(M_0(p_2)) \wedge</math></p> <p style="padding-left: 40px;"><math>M_0(p_1) \cdot d \subseteq M_0(p_2)</math></p> <p>C7) <math>d \leq f</math></p> <p>where</p> $d = \max_{t \in p_1^\bullet, V \in \boxminus(p_1, t)} \frac{\boxminus(p_2, t)(V)}{\boxminus(p_1, t)(V)}$ $f = \min_{t \in \bullet p_1, V \in \boxplus(t, p_1)} \frac{\boxplus(t, p_2)(V)}{\boxplus(t, p_1)(V)}$	<p>UC1) remove <math>p_2</math></p>

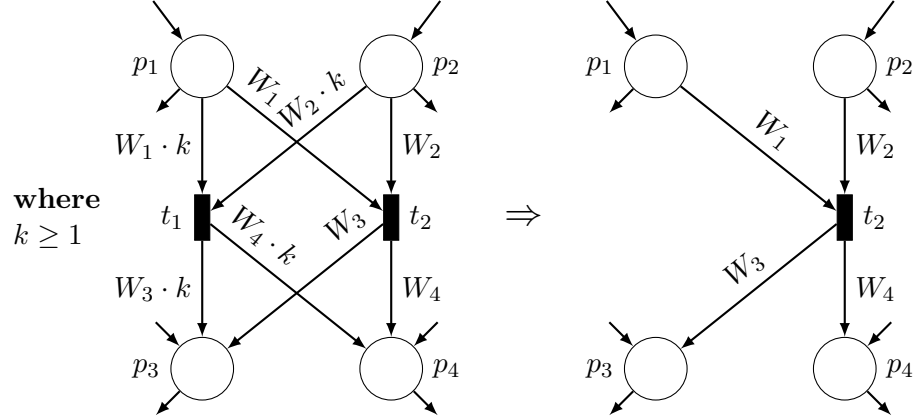
Figure 18: Rule C: Parallel places (CPN)

## Rule D: Parallel transition removal (CPN)

Rule D handles symmetrically parallel transitions where the effect of firing one of them is equivalent to firing the other exactly  $k$  times. In such a case, we remove the transition with higher arc-weights. The definition of Rule D can be seen in Figure 19. In precondition D2 states that the valid bindings of the guard  $G(t_1)$  must be a subset of the valid bindings of  $G(t_2)$ , i.e.  $\vec{B}(t_1) \subseteq \vec{B}(t_2)$ . This can be expensive to check depending on the complexity of the guards and the number of variables in the guard. A cheap overapproximation is to check whether  $G(t_1) = G(t_2)$  or  $G(t_2) = \top$  instead.

**Theorem 20** *Rule D described in Figure 19 is correct for  $LTL \setminus X$ .*

**Theorem 21** *Rule D described in Figure 19 is correct for  $CTL^*$  if  $k = 1$ .*



Precondition	Update
Fix transitions $t_1$ and $t_2$ and $k \in \mathbb{N}$ s.t.: D1) $t_1 \notin \text{transitions}(\varphi)$ D2) $\vec{B}(t_1) \subseteq \vec{B}(t_2)$ D3) $\varphi \in \text{CTL} \vee X \in \varphi \implies k = 1$ D4) For all $p \in P$ : $\boxminus(p, t_1) = \boxminus(p, t_2) \cdot k$ $\boxplus(t_1, p) = \boxplus(t_2, p) \cdot k$ D5) ${}^\circ t_2 \cap t_2^\bullet = \emptyset$ D6) $\forall p \in P. I(p, t_1) \leq I(p, t_2)$ D7) $\varphi \notin \text{Reach} \implies (\bullet t_1 \cup t_1^\bullet) \cap (\text{places}(\varphi) \cup \bullet \text{transitions}(\varphi)) = \emptyset$	UD1) remove $t_1$

Figure 19: Rule D: Parallel transitions



## Rule E: Dead transition removal (CPN)

Rule E in Figure 20 removes transitions that are never enabled. If too many bindings exists to check E1, then checking the cardinalities is a valid overapproximation.

Precondition E3 can be ignored  $\varphi$  if all instances of  $en(t_0)$  are replaced with  $\neg\top$  instead in the update.

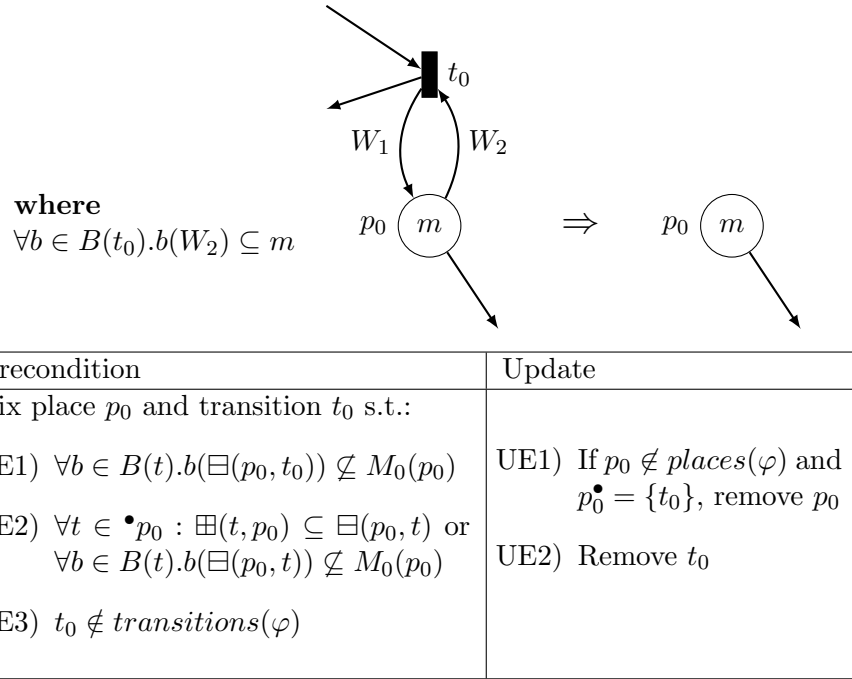
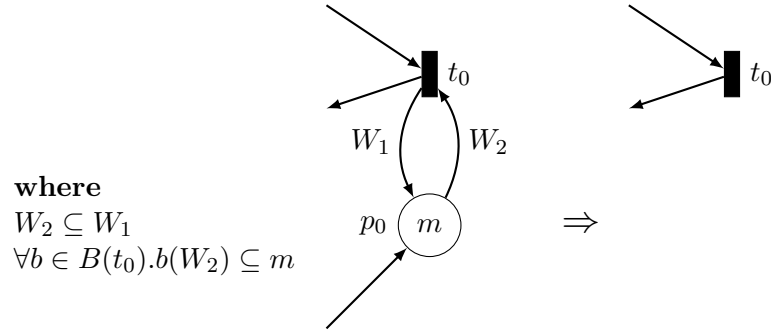


Figure 20: Rule E: Dead transitions

**Theorem 22** *Rule E in Figure 20 is correct for CTL\* queries.*

## Rule F: Redundant place removal (CPN)

Rule F in Figure 21 removes places which never disables its consumers.



Precondition	Update
Fix place $p_0$ s.t.: F1) $p_0^\circ = \emptyset$ F2) $p_0 \notin places(\varphi)$ and for all $t \in p_0^\bullet$ : F3) $\boxminus(p_0, t) \subseteq \boxplus(t, p_0)$ F4) $\forall b \in B(t). b(\boxminus(p_0, t)) \subseteq M_0(p_0)$	UF1) remove $p_0$

Figure 21: Rule F: Redundant places

**Theorem 23** *Rule F in Figure 21 is correct for CTL\*.*

## Rule I: Irrelevant places and transitions (CPN)

Only some places and transitions are relevant for the query. Algorithm 3 shows how to remove everything that is irrelevant by propagating relevance. Note that  $\nabla p = \{t \in \bullet p \mid \boxplus(t, p) \neq \boxminus(p, t)\}$  is the transmuting preset of  $p \in P$  and in line 7 we enqueue  $\nabla(\bullet t)$  which is the union of the transmuting presets of the places in the preset of  $t$ .

---

### Algorithm 3: Rule I: Irrelevant places and transitions

---

**Input:** A CPN  $N = \langle P, T, \mathcal{X}, \boxminus, \boxplus, I, G \rangle$ , initial marking  $M_0$  and EF formula  $\varphi$  without *deadlock*

**Output:** A reduced net  $N'$  and its initial marking  $M'_0$

```

1  $X := \emptyset$  /* Relevant transitions */
2  $Q := \text{transitions}(\varphi) \cup \bullet \text{places}(\varphi) \cup \text{places}(\varphi)^\bullet$  /* Queue of transitions */
3 while  $Q \neq \emptyset$  do
4   Pick any  $t \in Q$ 
5    $Q := Q \setminus \{t\}$ 
6    $X := X \cup \{t\}$  /* Mark as relevant */
7    $Q := Q \cup \nabla(\bullet t) \setminus X$  /* Enqueue transitions that can enable  $t$  */
8    $Q := Q \cup (\circ t)^\boxminus \setminus X$ 
9  $P' := \bullet X \cup \circ X \cup \text{places}(\varphi)$ 
10  $T' := X$ 
11  $N' :=$  a copy of  $N$  but every place  $p \notin P'$  and every transition  $t \notin T'$  have been removed.
12  $M'_0 :=$  a marking s.t.  $M'_0(p) = M_0(p)$  for all  $p \in P'$ .
13 return  $N'$  and  $M'_0$ 

```

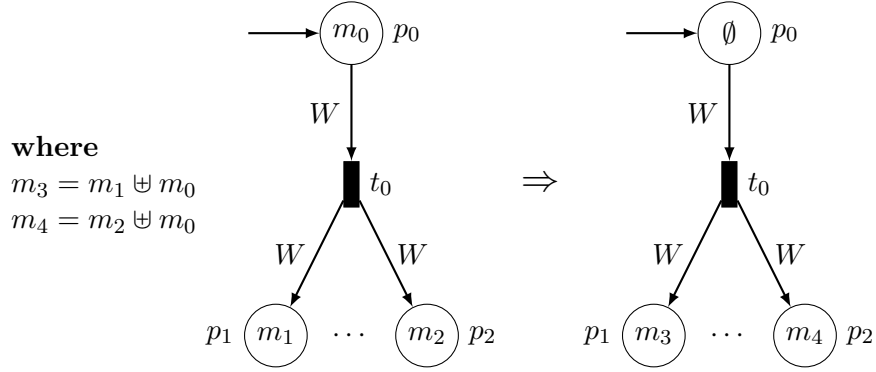
---

**Theorem 24** *Rule I in Algorithm 3 is correct for reachability without deadlock.*

## Rule Q: Preemptive transition firing (CPN)

Rule Q, defined in Figure 22, does not reduce the structure of the net, but will instead move tokens by simulating firing of transitions. In some nets Rule Q can be applied indefinitely.

**Theorem 25** *Rule Q in Figure 22 is correct for  $CTL^* \setminus X$ .*



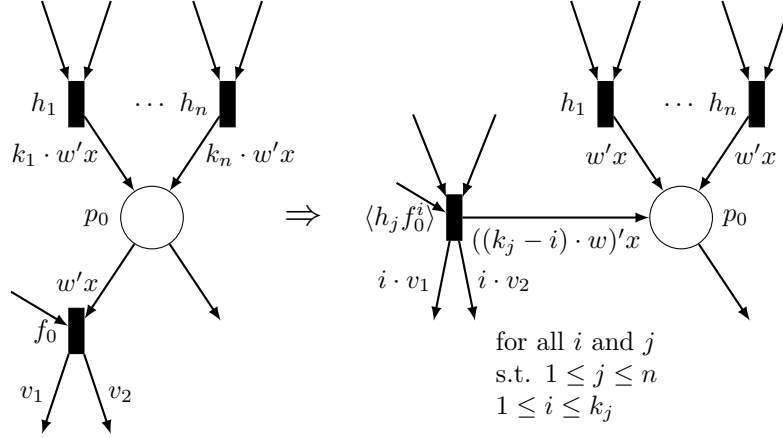
Precondition	Update
Fix place $p_0$ and transition $t_0$ s.t.:	
Q1) $p_0^\bullet = \{t_0\}$ and ${}^\bullet t_0 = \{p_0\}$	UQ1) $\forall p \in t_0^\bullet. M'_0(p)M_0(p) \uplus M_0(p_0)$
Q2) $G(t_0) = \top$	UQ2) $M'_0(p_0) := \emptyset$
Q3) $(\{p_0\} \cup t_0^\bullet) \cap places(\varphi) = \emptyset$ and $(\{t_0\} \cup (t_0^\bullet)^\bullet) \cap transitions(\varphi) = \emptyset$	
Q4) $p_0^\circ = \emptyset$ and $(t_0^\bullet)^\circ = \emptyset$	
Q5) ${}^\circ t_0 = \emptyset$	
Q6) $\exists k \in .k \cdot   \boxminus (p_0, t_0)   =  M_0(p_0) $	
Q7) ${}^\bullet p_0 \neq \emptyset \implies   \boxminus (p_0, t_0)   = 1$	
Q8) $ \mathbf{Supp}(M_0(p_0))  = 1$ or $\forall \vec{x} \in \boxminus (p_0, t_0)(\vec{x}) = 1$	
and for all $p \in t_0^\bullet$ :	
Q8) $\mathcal{X}(p) = \mathcal{X}(p_0)$	
Q9) $\boxminus (p_0, t_0) = \boxplus (t_0, p)$	

Figure 22: Rule Q: Preemptive firing

## Rule S: Atomic free agglomeration with k-scaling (CPN)

A free agglomeration is a pre agglomeration, which does not require that the pre set of the preset of  $p_0$  has a single consumer. In turn, it is only correct for reachability with deadlocks. The atomic free agglomeration is similar to the free agglomeration, but is able to agglomeration one consumer at a time. See Figure 23 for its definition. Rule S also handles cases where the producer  $h$  produces  $k$  times more tokens than what the consumer  $f_0$  consumes. In this case, a transition  $\langle hf_0^i \rangle$  is created for each  $i \in [1, k]$ . Thus all relevant markings remain reachable.

**Theorem 26** *Rule S in Figure 23 is correct for reachability without deadlock.*



Precondition	Update
Fix place $p_0$ and transition $f_0$ s.t.: S1) $(\{p_0\} \cap places(\varphi) = \emptyset$ S2) $(\bullet p_0 \cup p_0^\bullet \cup (\bullet\bullet p_0)^\bullet) \cap transitions(\varphi) = \emptyset$ S3) $M_0(p_0) = \emptyset$ S4) $\bullet p_0 \cap p_0^\bullet = \emptyset$ S5) $f_0 \in p_0^\bullet$ S6) $ \mathbf{Supp}(\boxplus(p_0, f_0))  = 1$ and for all $h \in \bullet p$ : S7) $h^\bullet = \{p_0\}$ S8) $\bullet h \cap places(\varphi) = \emptyset$ S9) $p_0^\circ = {}^\circ h = (\bullet h)^\circ = \emptyset$ S10) $ \boxplus(h, p_0)  = k *  \boxplus(p_0, f_0) $ S11) $k > 1 \implies \bullet f_0 = \{p_0\}$ S12) $k > 1 \implies (f_0^\bullet)^\circ = \emptyset$ And for each variable $v \in ((\boxplus(h, p_0) \cup \boxplus(p_0, f_0)) \cap (\mathbf{Vars}(G(h)) \cup \mathbf{Vars}(G(f_0))))$ there exists a $p \in P \setminus \{p_0\}$ such that: S13) $v \in (\mathbf{Vars}(\boxplus(h, p)) \cup \mathbf{Vars}(\boxplus(p, f_0)))$	For all $h \in \bullet p_0$ , create a transition $\langle hf \rangle$ s.t. for all $p \in P \setminus \{p_0\}$ , for all $i \in [1, k]$ for the $k$ such that $ \boxplus(h, p_0)  = k *  \boxplus(p_0, f_0) $ : US1) For all $v \in \mathbf{Vars}(f_0)$ , $rename(f_0, v, v')$ with some $v' \in \mathbf{Var}_{\mathcal{X}(p)} \setminus \mathbf{Vars}(h)$ US2) $\boxplus(p, \langle hf_0^i \rangle) := \boxplus(p, h) \uplus \boxplus(p, f_0)$ US3) $\boxplus(\langle hf_0^i \rangle, p) := i * \boxplus(f_0, p)$ $\boxplus(\langle hf_0^i \rangle, p_0) := (k - i) * \boxplus(p_0, f_0)$ US4) $G(\langle hf_0^i \rangle) := G(h) \wedge G(f_0)$ US5) $I(\langle hf_0^i \rangle) := I(f_0)$ US6) Given that $\boxplus(h, p_0) = \{x_1, x_2, \dots, x_n\}$ and $\boxplus(p_0, f_0) = \{y_1, y_2, \dots, y_n\}$ For $j \in [1, n]$ Let $l$ be the smallest number s.t. $x_l = x_i$ holds: $rename(\langle hf_0^i \rangle, x_j, y_l), rename(\langle hf_0^i \rangle, y_j, y_l)$ and US7) Remove $f_0$ US8) If $p_0^\bullet = \emptyset$ , remove $p_0$ and all transi- tions in $\bullet p_0 \setminus transitions(\varphi)$

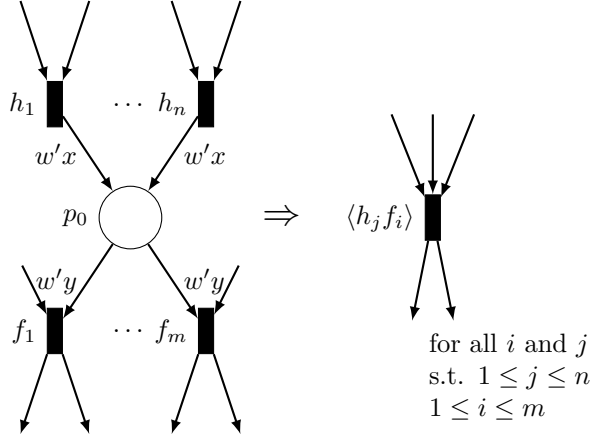
Figure 23: Rule S: Atomic free agglomeration with k-scaled

## Rule T: Pre agglomeration (CPN)

Rule T in Figure 24 is a pre agglomeration. In a pre agglomeration  $h \in \bullet p_0$  is invisible to the query and once enabled, it stays enabled. Hence, it can be delayed until an  $f \in p_0^\bullet$  needs it. Thus Rule T creates a transition  $\langle hf \rangle$  for every pair  $h \in \bullet p_0$  and  $f \in p_0^\bullet$ .

**Theorem 27** *Rule T described in Figure 24 is correct for  $LTL \setminus X$ .*





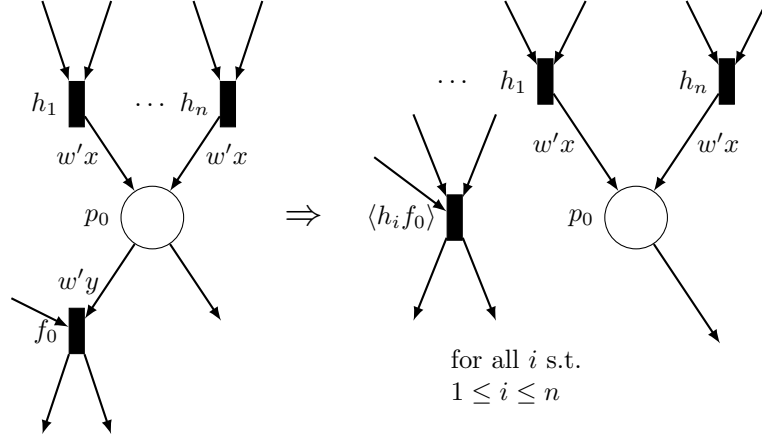
Precondition	Update
Fix place $p_0$ s.t.:	For all $h \in \bullet p$ , for all $f \in p^\bullet$ , create a transition $\langle hf \rangle$ s.t. for all $p \in P \setminus \{p_0\}$ :
T1) $(\{p_0\} \cap places(\varphi) = \emptyset$	UT1) For all $v \in \mathbf{Vars}(f)$ , $rename(f, v, v')$ with some $v' \in \mathbf{Vars}_{\mathcal{X}(p)} \setminus \mathbf{Vars}(h)$
T2) $(p_0^\bullet \cup \bullet p_0) \cap transitions(\varphi) = \emptyset$	UT2) $\boxminus(p, \langle hf \rangle) := \boxminus(p, h) \uplus \boxminus(p, f)$
T3) $M_0(p_0) = \emptyset$	UT3) $\boxplus(\langle hf \rangle, p) := \boxplus(f, p)$
T4) $\bullet p_0 \cap p_0^\bullet = \emptyset$	UT4) $G(\langle hf \rangle) := G(h) \wedge G(f)$
and for all $h \in \bullet p_0$ :	UT5) $I(\langle hf \rangle) := I(f)$
T5) $(\bullet h)^\bullet = \{h\}$	UT6) Given that $\boxplus(h, p_0) =$ $w'\langle x_1, x_2, \dots, x_n \rangle$ and $\boxminus(p_0, f_0) =$ $w'\langle y_1, y_2, \dots, y_n \rangle$ For $i \in [1, n]$ Let $a$ be the smallest index s.t. $x_a = x_i$ holds: $rename(\langle hf \rangle, x_i, y_a)$ $rename(\langle hf \rangle, y_i, y_a)$
T6) $h^\bullet = \{p_0\}$	
T7) $\bullet h \cap places(\varphi) = \emptyset$	
T8) $p_0^\circ = {}^\circ h = (\bullet h)^\circ = \emptyset$	
and for all $f \in p_0^\bullet$	
T9) $ \mathbf{Supp}(\boxplus(h, p_0)) $ $ \mathbf{Supp}(\boxminus(p_0, f))  = 1$	
T10) $ \boxplus(h, p_0)  =  \boxminus(p_0, f) $	
	and after all such transitions are made:
	UT7) Remove $p^\bullet$ , $\bullet p_0$ , and $p_0$

Figure 24: Rule T4Pre agglomeration

## Rule U: Atomic free agglomeration (CPN)

Rule U is a atomic free agglomeration similar to Rule S. However, it restricts  $k = 1$ . See Figure 25 for the definition of Rule U.

**Theorem 28** *Rule U in Figure 25 is correct for reachability without deadlock.*



Precondition	Update
Fix place $p_0$ and transition $f_0$ s.t.:	For all $h \in \bullet p_0$ , create a transition $\langle hf_0 \rangle$ s.t. for all $p \in P \setminus \{p_0\}$ :
U1) $(\{p_0\} \cap places(\varphi) = \emptyset$	UU1) For all $v \in \mathbf{Vars}(f_0)$ , $rename(f_0, v, v')$ with some $v' \in \mathbf{Var}_{\mathcal{X}(p)} \setminus \mathbf{Vars}(h)$
U2) $(\bullet p_0 \cup p_0^\bullet \cup (\bullet(\bullet p_0)^\bullet)) \cap transitions(\varphi) = \emptyset$	UU2) $\boxplus(p, \langle hf_0 \rangle) := \boxplus(p, h) \uplus \boxplus(p, f_0)$
U3) $M_0(p_0) = \emptyset$	UU3) $\boxplus(\langle hf_0 \rangle, p) := \boxplus(f_0, p)$
U4) $\bullet p_0 \cap p_0^\bullet = \emptyset$	UU4) $G(\langle hf_0 \rangle) := G(h) \wedge G(f_0)$
U5) $f_0 \in p_0^\bullet$	UU5) $I(\langle hf_0 \rangle) := I(f_0)$
and for all $h \in \bullet p$ :	
U6) $ \mathbf{Supp}(\boxplus(h, p_0)) $ $ \mathbf{Supp}(\boxplus(p_0, f_0))  = 1$	= UU6) Given that $\boxplus(h, p_0) = w'\langle x_1, x_2, \dots, x_n \rangle$ and $\boxplus(p_0, f_0) = w'\langle y_1, y_2, \dots, y_n \rangle$ For $i \in [1, n]$ Let $a$ be the smallest index s.t. $x_a = x_i$ holds: $rename(\langle hf_0 \rangle, x_i, y_a)$ $rename(\langle hf_0 \rangle, y_i, y_a)$
U7) $h^\bullet = \{p_0\}$	and
U8) $\bullet h \cap places(\varphi) = \emptyset$	UU7) Remove $f_0$
U9) $p_0^\circ = {}^\circ h = (\bullet h)^\circ = \emptyset$	UU8) If $p_0^\bullet = \emptyset$ , remove $p_0$ and all transitions in $\bullet p_0 \setminus transitions(\varphi)$
U10) $ \boxplus(h, p_0)  =  \boxplus(p_0, f_0) $	

Figure 25: Rule U: Atomic free agglomeration