

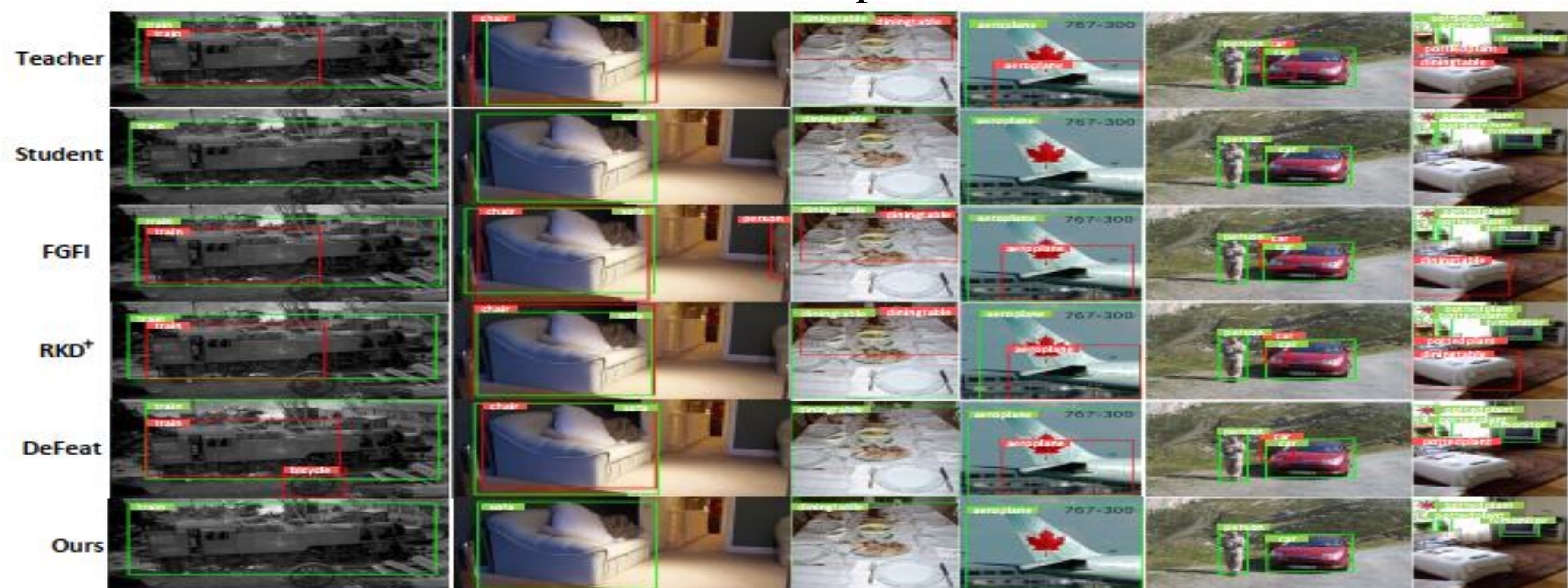
Distilling Object Detectors with Global Knowledge

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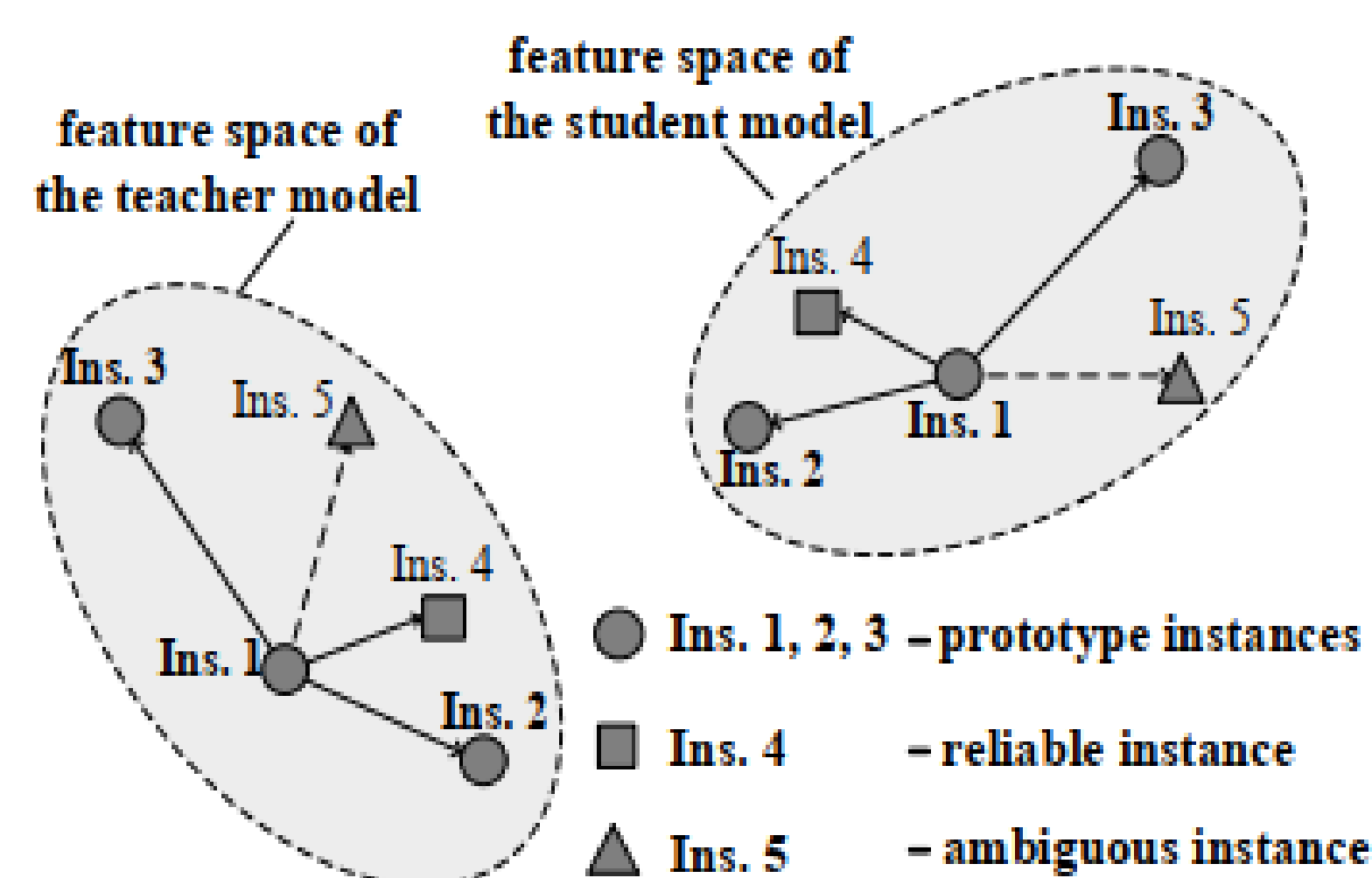
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Motivation

- local knowledge is of much discrepancy between the teacher and the student in object detection tasks, especially on the ambiguous instances which are blur, truncated, or small.
- The distilling process will suffer from the noisy local knowledge, e.g., the false positives and the localization errors, and lead to sub-optimal.



Idea



- Finding a group of common basis vectors in both the feature spaces of the teacher and the student detectors.
- Designing more robust distilling algorithm by measuring the discrepancy of the representations in the two feature spaces

Ablation

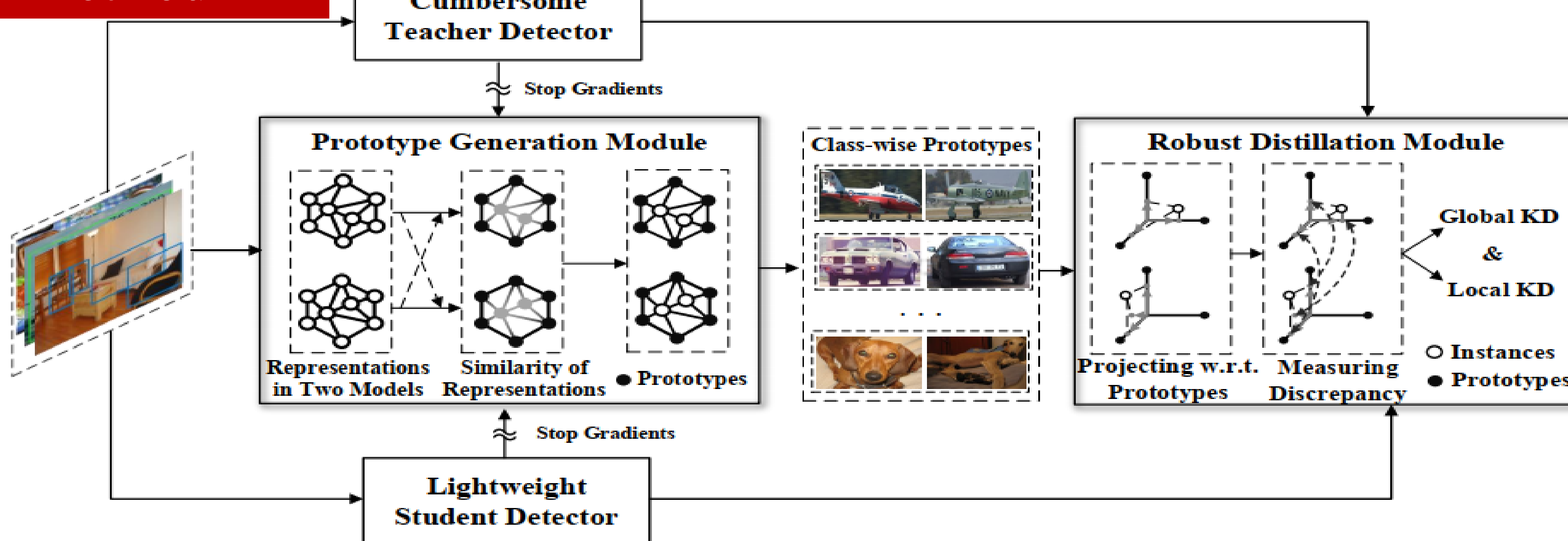
Method	Student	DeFeat [11]	RKD [†] [34]	Vanilla-KD [†] [16]
+prototypes		✓	✓	✓
AP ₅₀	81.3	82.0 82.4	81.6 82.0	81.8 82.2

Method	K-Means		DBSCAN [6]		Ambiguous	Ours
Features	Student	Teacher	Student	Teacher	-	Both
AP₅₀	82.3	82.1	82.4	82.2	81.8	82.9

Method	Backbone	mAP	AP ₅₀	AP ₇₅	AP _s	AP _m	AP _l
Cascade R-CNN (teacher)	ResNext101	47.3	66.3	51.7	28.2	51.7	62.7
Faster R-CNN (student)	ResNet50	38.4	59.0	42.0	21.5	42.1	50.3
FBKD [46]	ResNet50	41.5	62.2	45.1	23.5	45.0	55.3
Ours	ResNet50	41.5	61.9	45.1	23.5	45.1	55.4

- Prototypes can be easily combined by existing distilling methods and achieves better performance.
- Prototypes generated by proposed PGM shows better results than the cluster-like methods.
- It Shows competitive performance with much larger teacher.

Method



Algorithm 1 Algorithm for selecting prototypes in PGM.

Input:
 $\{(f_i^t, f_i^s)\}_{i=1}^N$: features of N instances in TS -space;
 Parameter:
 K : number of prototypes to be selected;
 λ : regularization weight;
 Output:
 \mathcal{I} : index set of the prototypes

- 1: initialize $n = 0$, the residuals $r_{0,i}^t = f_i^t$, and $r_{0,i}^s = f_i^s \quad \forall i = 1, \dots, N$;
- 2: while $n < K$ do
- 3: compute the optimal $w_{n+1,i}^t$ and $w_{n+1,i}^s$ by Eq. [5];
- 4: compute the \mathcal{L}_{n+1}^k with Eq. [4] for each instance by setting $g_{n+1}^t = f_k^t$ and $g_{n+1}^s = f_k^s, \forall k = 1, \dots, N$;
- 5: append the index k^* into \mathcal{I} where $k^* = \arg \min_k \{\mathcal{L}_{n+1}^k\} \quad \forall (g_k^t, g_k^s) \in \{(f_i^t, f_i^s)\}_{i=1}^N$; set $g_{n+1}^t = f_{k^*}^t$ and $g_{n+1}^s = f_{k^*}^s$;
- 6: update the residuals $r_{n+1,i}^t$ and $r_{n+1,i}^s$ by Eq. [3];
- 7: set $n = n + 1$;
- 8: end while
- 9: Return: \mathcal{I}

Contribution

- (1) A prototype generation module (PGM) is designed to find a group of common basis vectors as the prototypes in the two feature spaces by minimizing reconstruction errors of instances w.r.t. prototypes.
- (2) The global knowledge is formed by representing the instances under the prototypes, which shows a smaller gap between the two spaces.
- (3) The proposed method achieves new remarkable performance on distilling both single-stage and two-stage detectors on Pascal VOC and COCO benchmarks..



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Performance

Faster-Res101 (teacher)	39.8	60.1	43.3	22.5	43.6	52.8	53.0	32.8	56.9	68.6
Faster-Res50 (student)	38.4	59.0	42.0	21.5	42.1	50.3	52.0	32.6	55.8	66.1
FGFI [43]	39.3	59.8	42.9	22.5	42.3	52.2	52.4	32.2	55.7	67.9
DeFeat [11]	40.3	60.9	44.0	23.1	44.1	53.4	53.7	33.3	57.7	69.1
FBKD [46]	40.2	60.4	43.6	22.8	43.8	53.2	53.4	32.7	57.1	68.8
GID [4]	40.2	60.8	43.6	23.6	43.9	53.0	53.7	33.6	57.7	68.6
Ours	40.6	61.0	44.0	23.4	44.4	53.3	53.8	33.9	57.9	69.2
Retina-Res101 (teacher)	38.9	58.0	41.5	21.0	42.8	52.4	54.8	33.4	59.3	71.2
Retina-Res50 (student)	37.4	56.7	39.6	20.0	40.7	49.7	53.9	33.1	57.7	70.2
FGFI [43]	38.6	58.7	41.3	21.4	42.5	51.5	54.6	34.7	58.2	70.4
GID [4]	39.1	59.0	42.3	22.8	43.1	52.3	55.3	36.7	59.1	71.1
DeFeat [11]	39.3	58.2	42.1	21.7	42.9	52.9	55.1	33.9	59.6	71.5
FBKD [46]	39.3	58.8	42.0	21.2	43.2	53.0	55.4	34.6	59.7	72.2
FR [5]	39.3	58.8	42.0	21.5	43.3	52.6	-	-	-	-
PFI [23]	39.6	-	-	21.4	44.0	52.5	-	-	-	-
Ours	39.8	58.6	42.6	21.8	43.5	53.5	55.8	34.1	60.0	72.2