

INSTAGAN: INSTANCE-AWARE IMAGE-TO-IMAGE TRANSLATION

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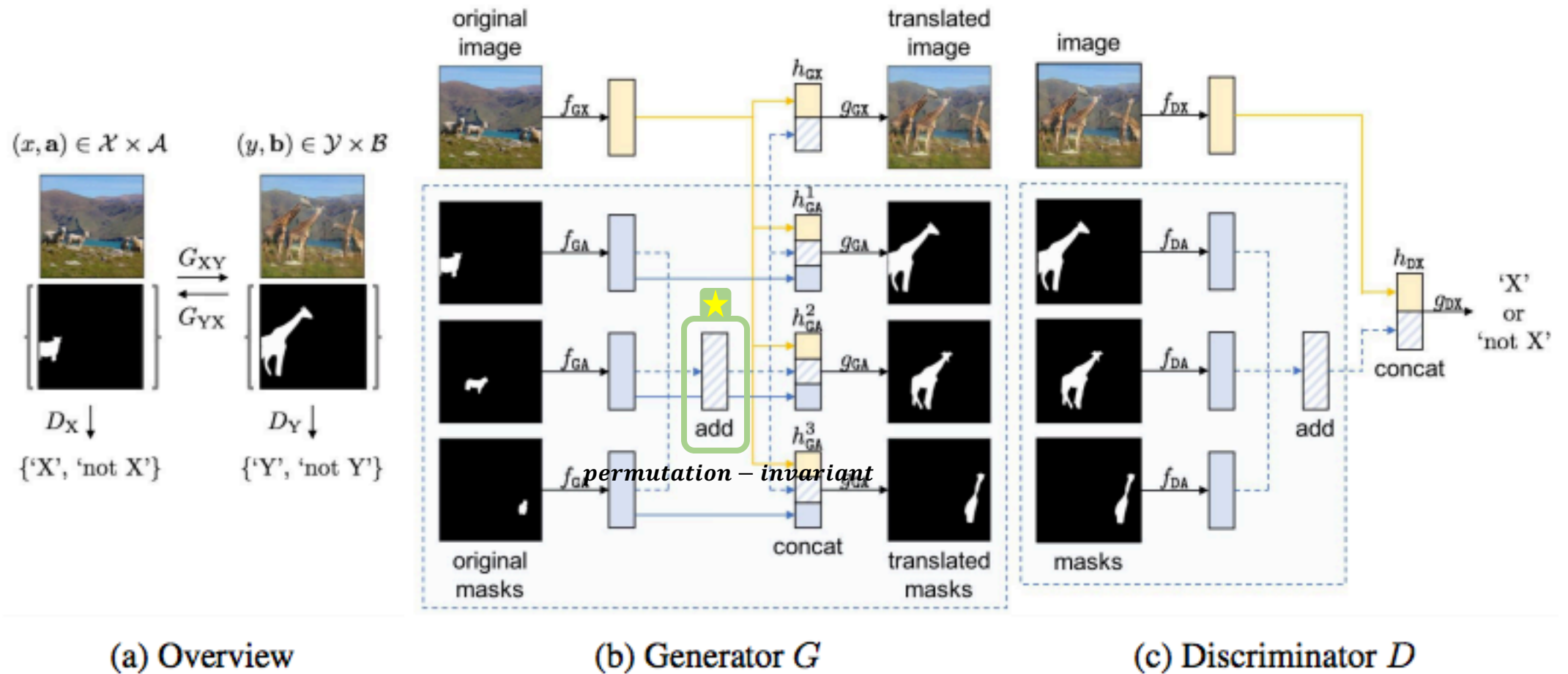
Abstract

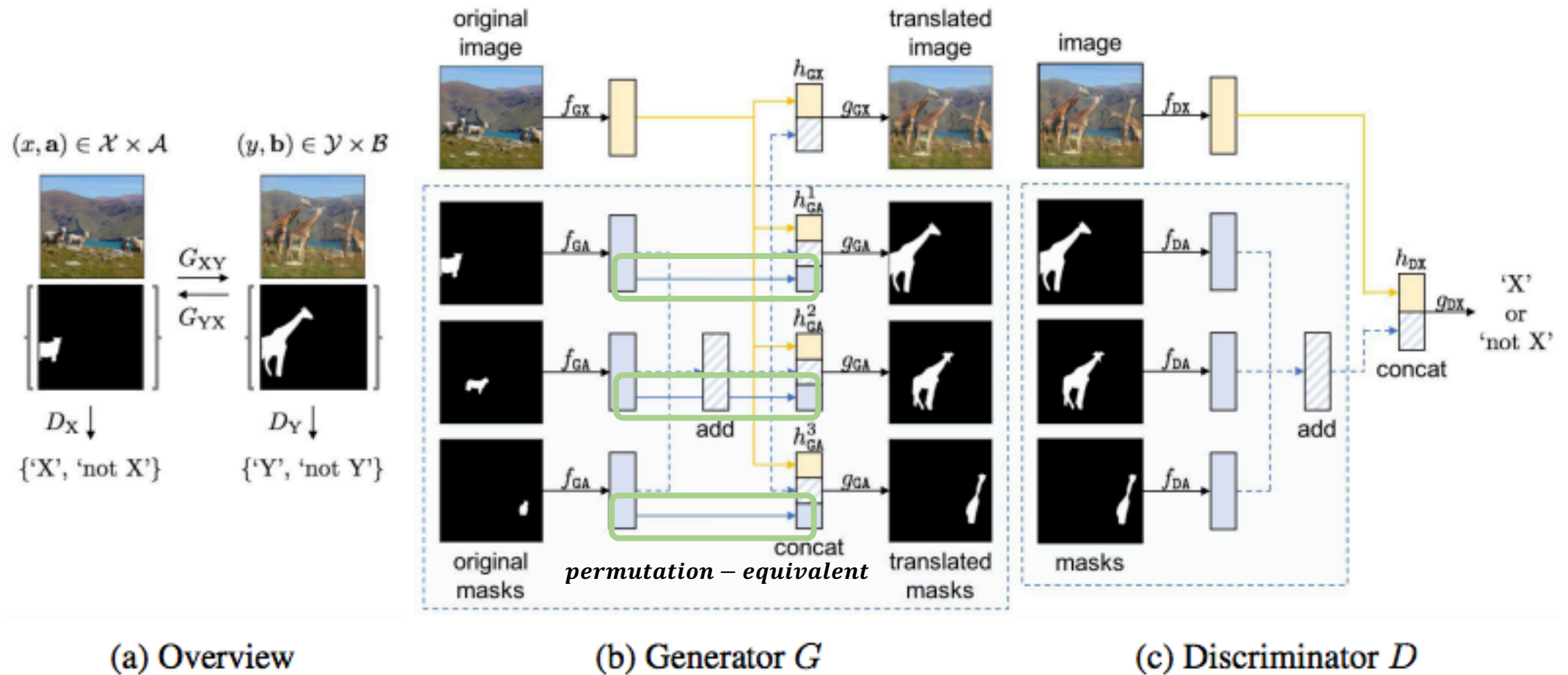
- Unsupervised image-to-image translation achieved outstanding improvement via generative adversarial networks (GANs)
- However, the task which demands dramatic changes in shape or multiple target instance, existing methods often fail.
- To tackle this problem, InstaGAN uses instance information(e.g. object segmentation masks) for overcoming aforementioned limitations
- Also, new techniques used to improve performance:
 - Context preserving loss
 - Sequential mini-batch inference/training
- Funny dataset and experiment results
 - At first glance, we can guess that the authors are korean :)

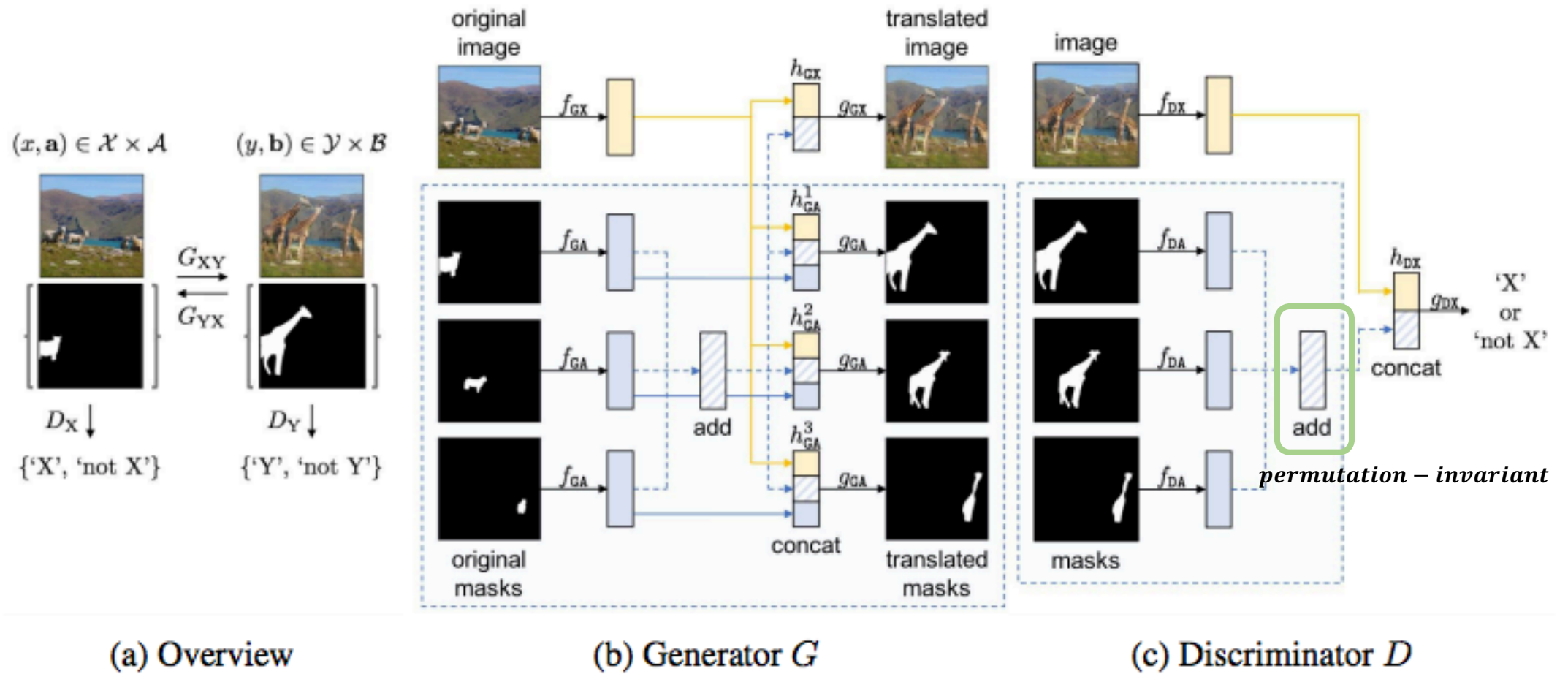
Key contributions

- An instance-augmented neural architecture is developed that translates an image and a corresponding set of attributes (segmentation masks).
- A context preserving loss that preserves the background while transforming the target instances
- A sequential mini-batch inference/training technique that allows the system to work on subsets of data rather than requiring the full set of data

- Original setting (image to image)
 - $G_{XY}: X \rightarrow Y$ & $G_{YX}: Y \rightarrow X$
- These mappings can be reformulated as finding conditional distributions $p(y|x), p(x|y)$ when we have marginal distributions $p(x), p(y)$
- The authors argue that aforementioned information is insufficient to approximate conditional distributions when sampling one is too complex.
- Author's setting (image x attribute to image x attribute)
 - $G_{XY}: X \times A \rightarrow Y \times B$ & $G_{YX}: Y \times B \rightarrow X \times A$

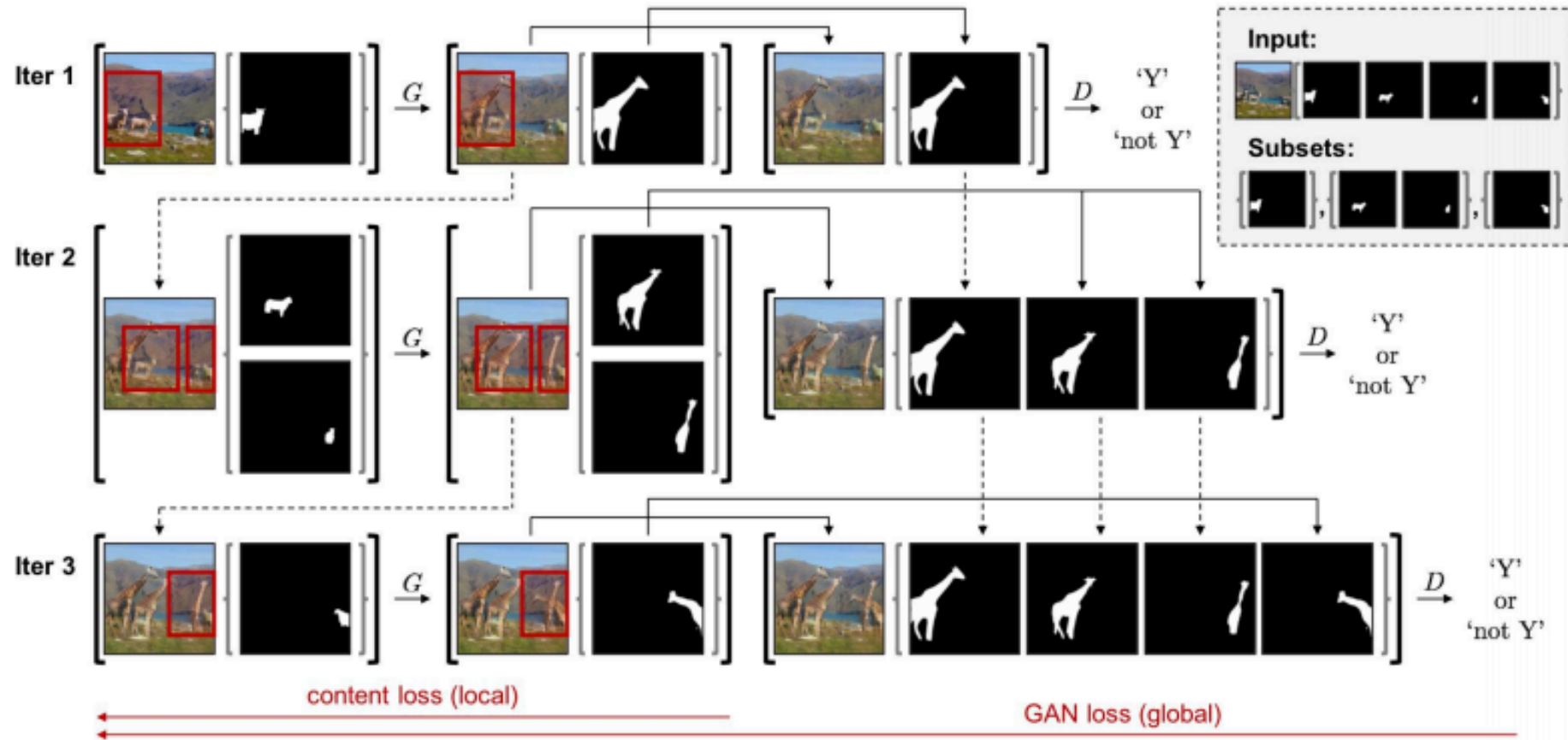




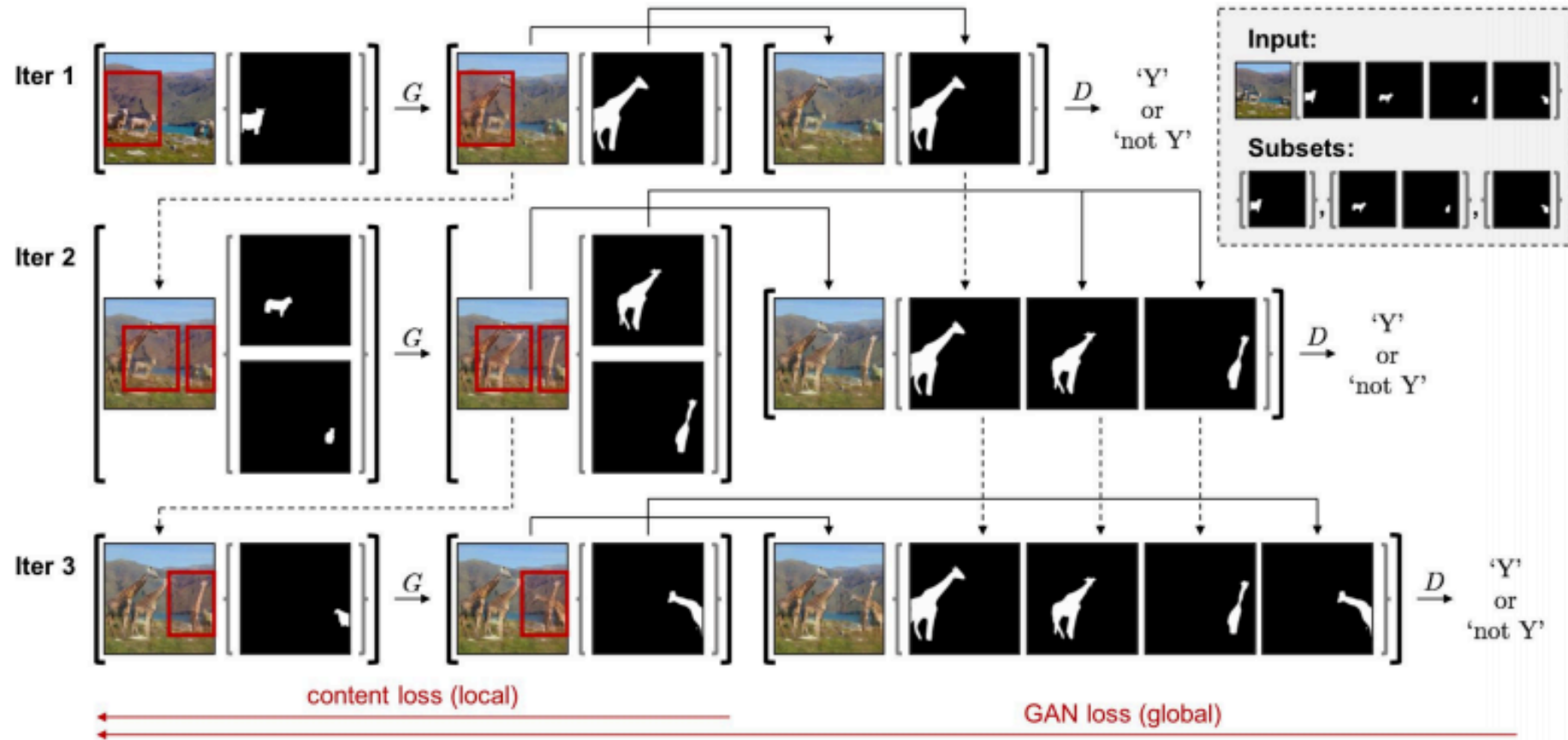


- **Domain loss which makes the generated outputs to follow the style of a target domain**
 - LSGAN loss
- **Content loss which makes the outputs to keep the original contents**
 - Cycle-consistency loss (*i.e.* $G_{YX}(G_{XY}(x, a)) - (x, a)$)
 - Identity mapping loss (*i.e.* $G_{XY}(y, b) - (y, b)$)
 - Context preserving loss (*i.e.* $w(a, b') \circ (x - y') \Leftrightarrow (1 - \max(a, b') \circ (x - y'))$)

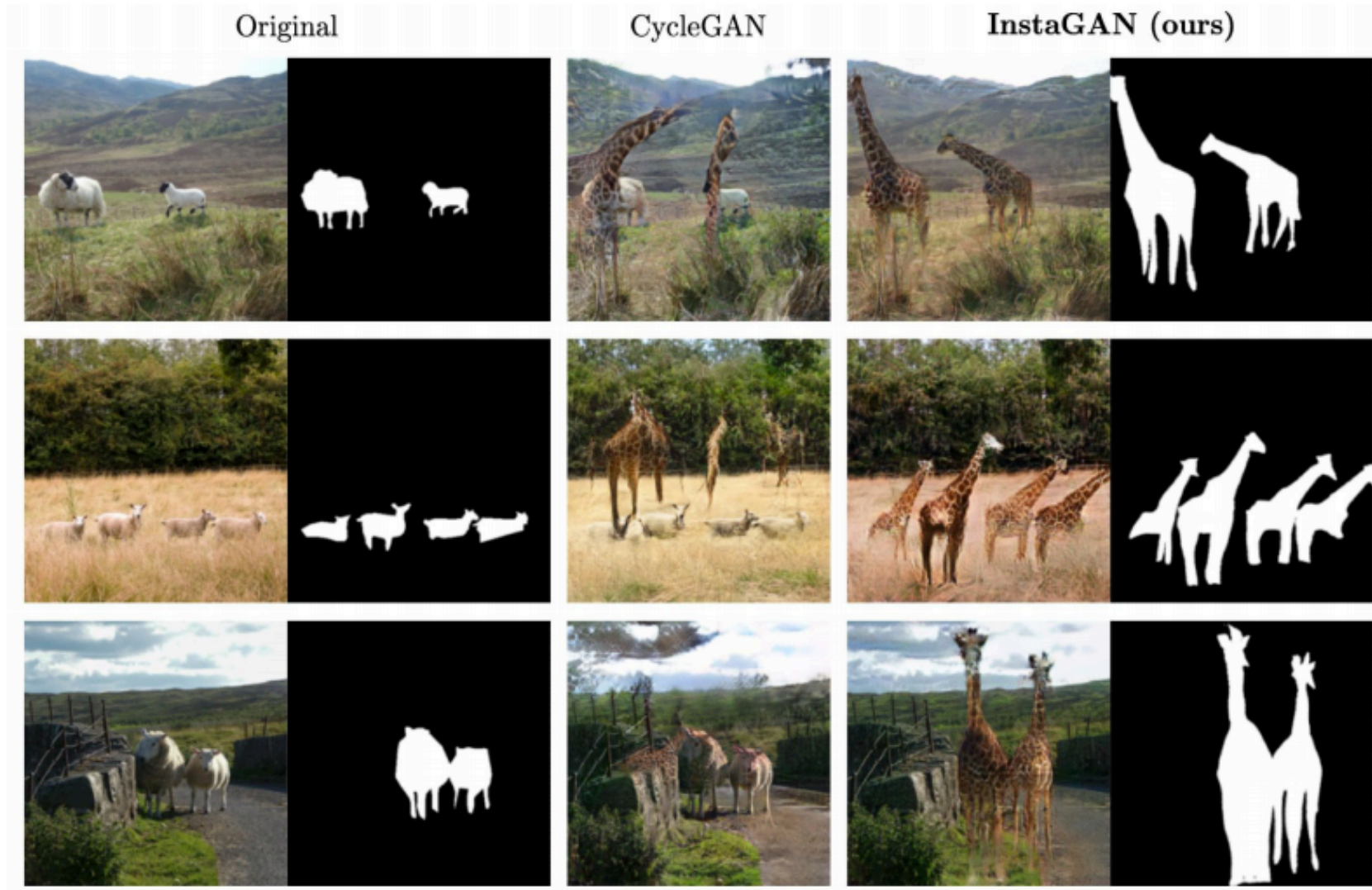
$$\mathcal{L}_{\text{InstaGAN}} = \underbrace{\mathcal{L}_{\text{LSGAN}}}_{\text{GAN (domain) loss}} + \underbrace{\lambda_{\text{cyc}}\mathcal{L}_{\text{cyc}} + \lambda_{\text{idt}}\mathcal{L}_{\text{idt}} + \lambda_{\text{ctx}}\mathcal{L}_{\text{ctx}}}_{\text{content loss}},$$



$$\mathcal{L}_{\text{InstaGAN-SM}} = \sum_{m=1}^M \mathcal{L}_{\text{LSGAN}}((x, \mathbf{a}), (y'_m, \mathbf{b}'_{1:m})) + \mathcal{L}_{\text{content}}((x_m, \mathbf{a}_m), (y'_m, \mathbf{b}'_m))$$



- Divided the instances into mini-batches $a_1 \dots a_M$ according to the decreasing order of the spatial sizes of instances -> Better performance than random order
- Small instances tend to be occluded by other instances in image s , thus often losing their intrinsic shape information







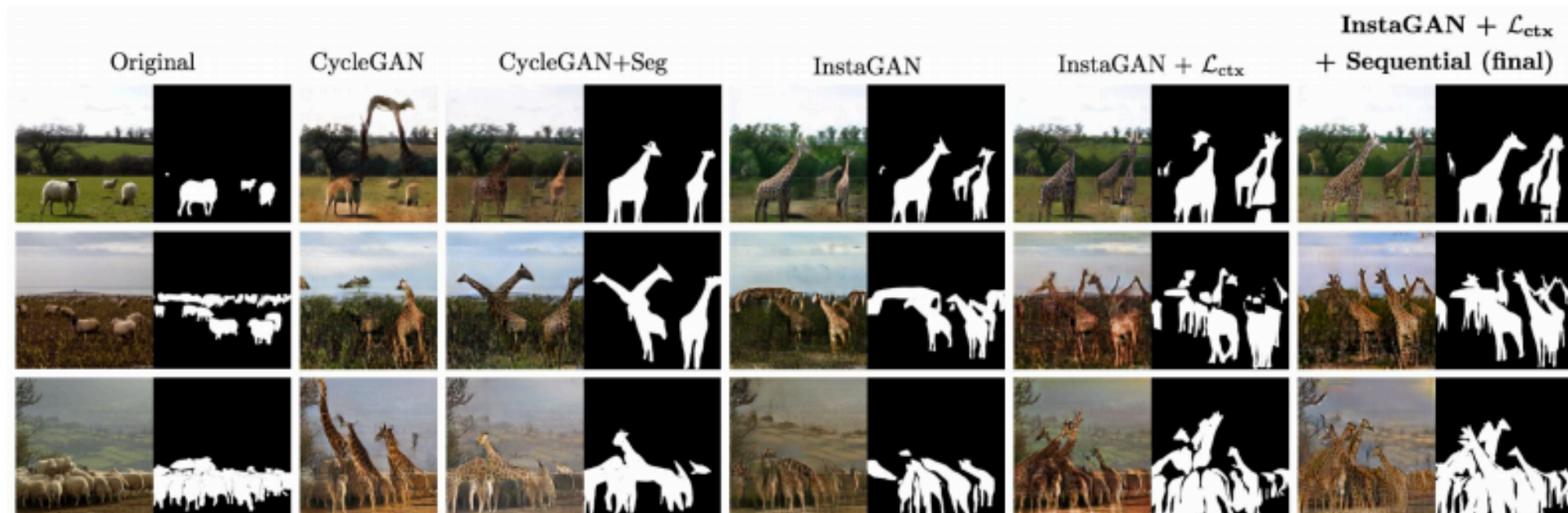


Figure 9: Ablation study on the effect of each component of our method: the InstaGAN architecture, the context preserving loss, and the sequential mini-batch inference/training algorithm, which are denoted as InstaGAN, \mathcal{L}_{ctx} , and Sequential, respectively.

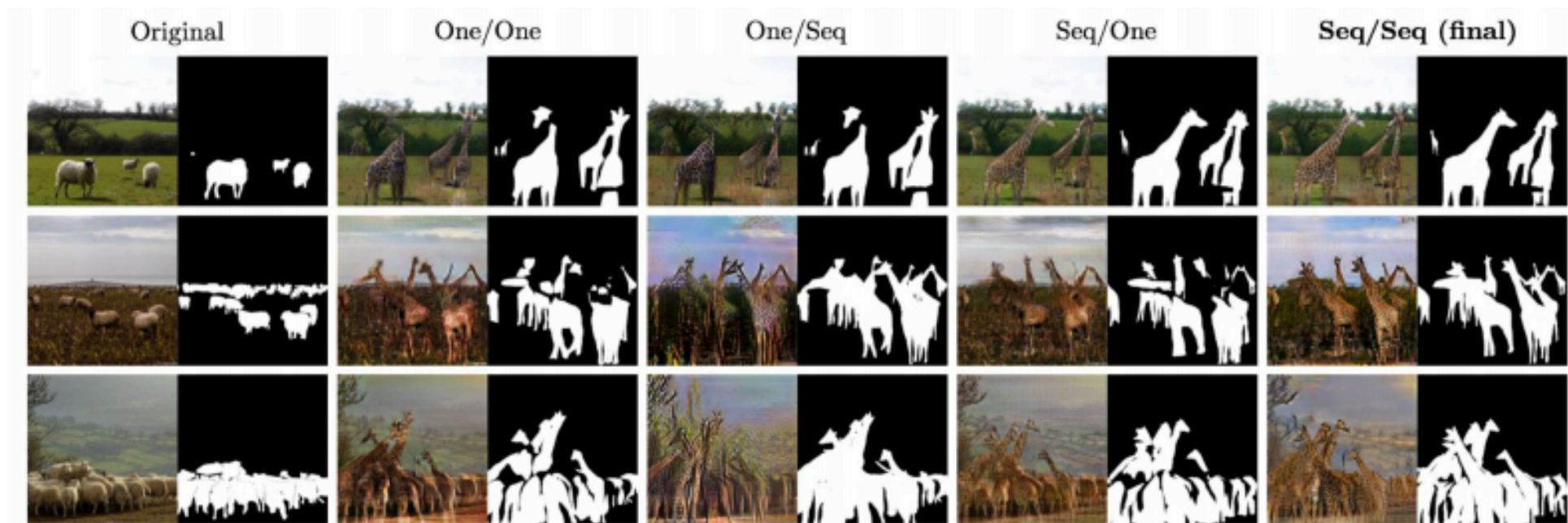


Figure 10: Ablation study on the effects of the sequential mini-batch inference/training technique. The left and right side of title indicates which method used for training and inference, respectively, where “One” and “Seq” indicate the one-step and sequential schemes, respectively.