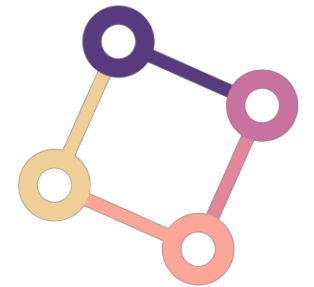


# Hypergraph Attention Networks for Multimodal Learning

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## Motivation

- Most of the previous researches on learning multimodal inputs commonly make input features of each modality as vector forms after applying pre-trained pre-processing methods
- And integrate the multiple input features into a common vector space
- And apply problem-specific modules (usually fully connected neural networks)
- The feature vectors from **different modalities are considered as abstracted information on the equivalent level**, even though those are obtained from totally different pre-processing steps

# Introduction

- One of the fundamental problems that arise in multimodal learning task is **the disparity of information levels between different modalities**
- There is a severe lack of consideration regarding the adequate form of the input representations of the multimodal data to learn
- This paper discovers that **alignment of the information levels between the modalities** is important
- The symbolic graphs are very powerful ways to represent the information of the low-level signals in alignment
- SOTA on GQA(Question Answering on Image Scene Graphs) dataset

# Hypergraph Attention Networks

- The main purpose of the suggested method is to align information levels and to integrate the inputs within the same information level

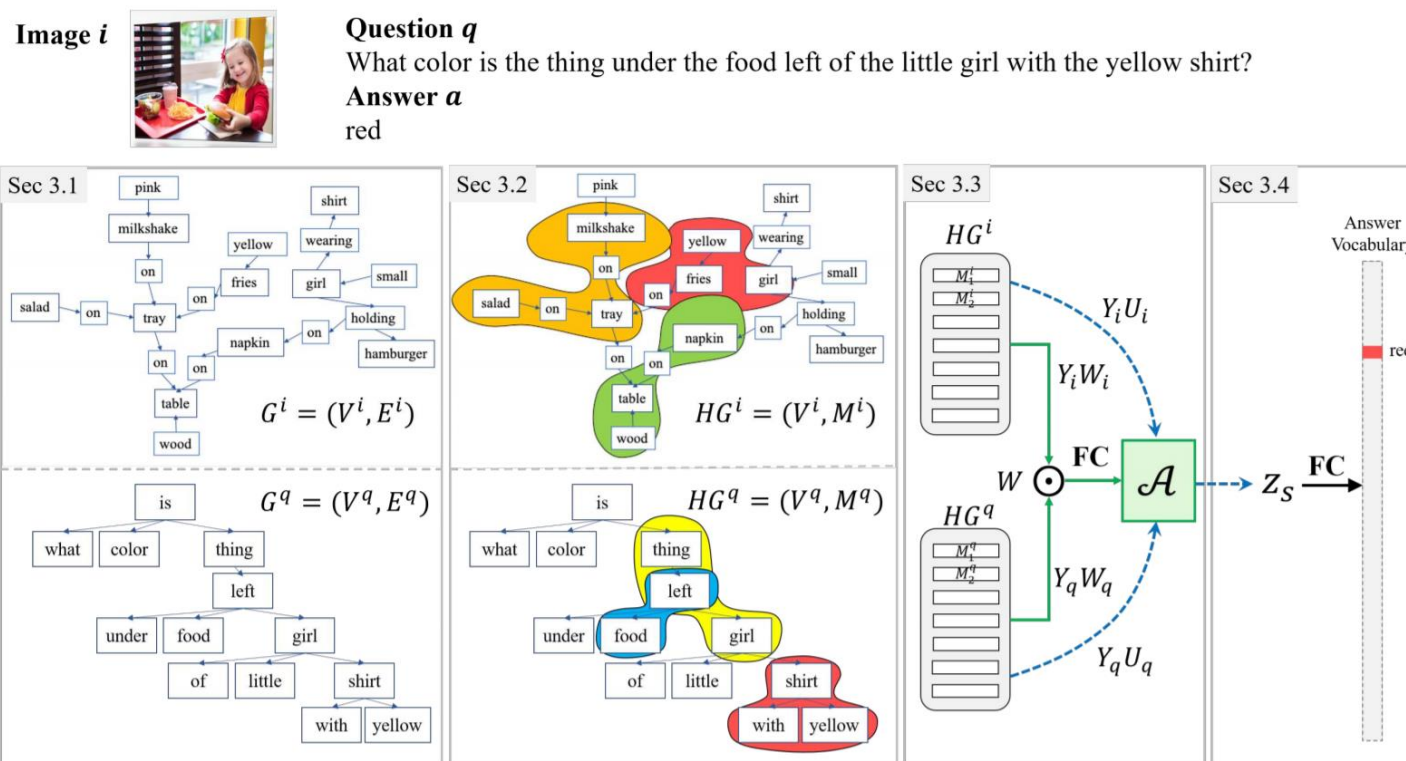
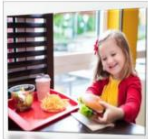


Figure 1. The overall architecture of the suggested model. For a given pair of image and question, two symbolic graphs are constructed. After constructing the symbolic graphs  $G^i$  and  $G^q$ , two hypergraphs  $HG^i$  and  $HG^q$  with random-walk based hyperedge are constructed. By comparing the semantics of each hyperedges, a co-attention map  $\mathcal{A}$  is constructed. The two hypergraphs are combined by the co-attention map  $\mathcal{A}$ , and the final representation  $z_s$  is used to predict an answer for the given question.

# I. Constructing Symbolic Graphs

- The symbolic representations of the two modalities are defined with graph forms

Image  $i$



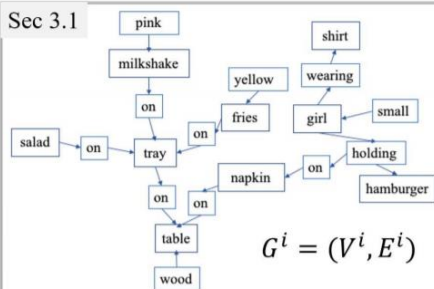
Question  $q$

What color is the thing under the food left of the little girl with the yellow shirt?

Answer  $a$

red

Sec 3.1

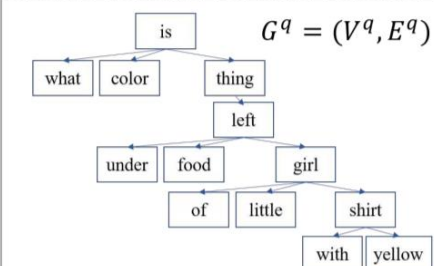


$$G^i = (V^i, E^i)$$

$G^i$ : Scene graph from image

$V^i$ : Set of nodes (objects, attributes, relations)

$E^i$ : Set of edges (object  $\sim$  attribute, object  $\sim$  relation)



$$G^q = (V^q, E^q)$$

$G^q$ : Dependency tree

$V^q$ : Set of tokens

$E^q$ : Dependency between the tokens

## 2. Constructing the Hypergraphs

- They consider each hyperedge as a sub-graph
- A hyperedge is a sequence of nodes sampled by random-walk algorithm along with directed edges

Image  $i$

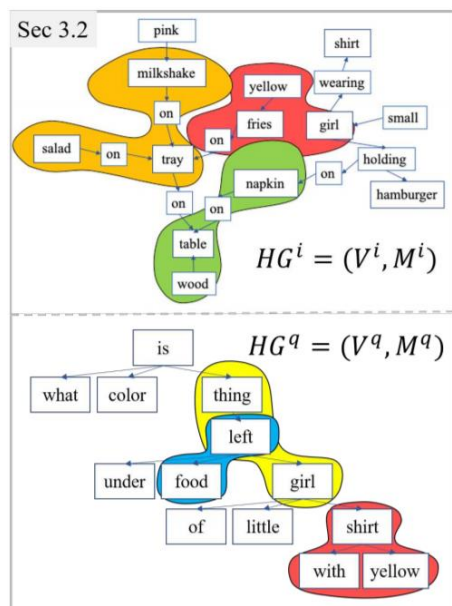


Question  $q$

What color is the thing under the food left of the little girl with the yellow shirt?

Answer  $a$

red



$HG^i$ : Hypergraph from image

$V^i$ : Set of nodes (objects, attributes, relations)

$M^i$ : Set of edges (object ~ attribute, object ~ relation)

$HG^q$ : Hypergraph from dependency tree

$V^q$ : Set of tokens

$M^q$ : Dependency between the tokens

### Random-walk Algorithm

The initial probability that a node  $v_i$  will be selected is defined with, where  $deg^+(v_i)$  represent the number of out-going edges from node  $v_i$

$$P_{v_i}^0 = \frac{deg^+(v_i) + \epsilon}{\sum_{j=1}^N deg^+(v_j)}$$

the transition probability is defined with,

$$P_{v,u} = \begin{cases} \frac{1-\epsilon}{deg^+(v)}, & \text{if } (v, u) \in E \\ \epsilon, & \text{if } (v, u) \notin E \end{cases}$$

### 3. Building Co-attention Maps between Hyper-graphs

- The semantic of each hyperedge  $M$  can be defined by combining the word representations(e.g. GloVe) within the same hyperedge
- The co-attention map is based on comparing the semantics with the symbolic representations
- This method can consider the inherent structures by constructing the hypergraphs

Image  $i$

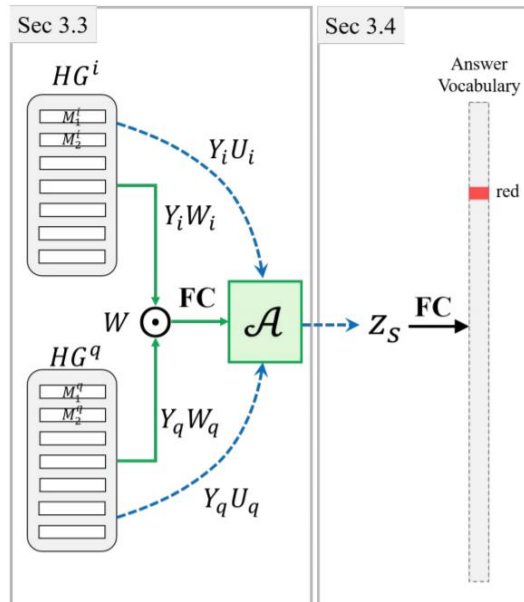


Question  $q$

What color is the thing under the food left of the little girl with the yellow shirt?

Answer  $a$

red



$$Y_q \in \mathbb{R}^{N^q \times 300}$$

$$Y_i \in \mathbb{R}^{N^i \times 300}$$

$$W_q, W_i \in \mathbb{R}^{300 \times h}$$

$$W \in \mathbb{R}^{N^q \times N^i}$$

$$U_q, U_i \in \mathbb{R}^{300 \times h}$$

$$\mathcal{A} = \text{softmax}(W \circ (Y_q W_q)(Y_i W_i)^\top)$$

$$\mathbf{z}_s = (Y_q U_q)^\top \mathcal{A}(Y_i U_i)$$



# Results

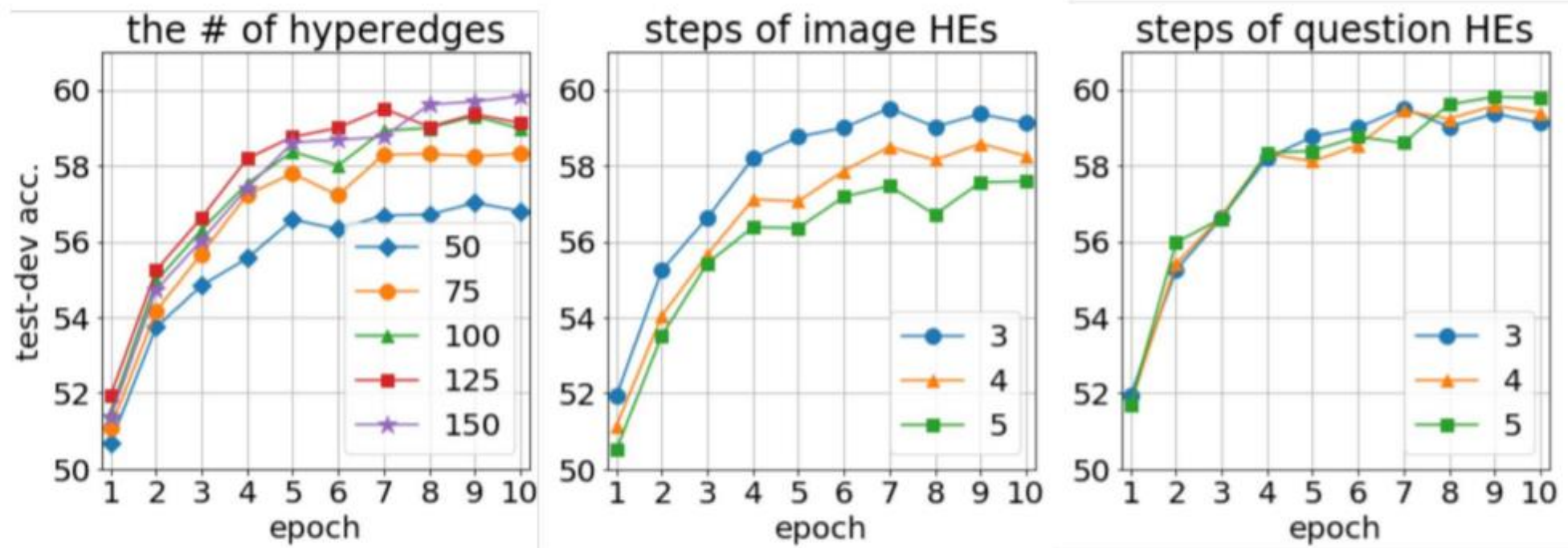


Figure 2. Test-dev accuracies with various hyper-parameter combinations. **Left:** Test-dev accuracy with various number of image hyperedges when the number of hyperedges for questions are fixed to 50. **Middle:** Accuracy with various number of steps ( $k$ ) of image hyperedges with three-step question hyperedges. **Right:** Accuracy with various number of steps ( $k$ ) of question hyperedges with three step image hyperedges.



# Results

Table 1. As a plug-in module for the attention (Att.), HANs are combined with state-of-the-arts VQA algorithms, BAN [15] and MFB [38]. Those are used as bilinear module  $B$ . For the most of the metrics, HANs improves the GQA performance. For the distribution (Dist.) metric, the lower score, the better.

Method					Performance Measures with Test-dev Split					
No.	Feature	HE	Att.	$B$	Binary	Open	Plaus.	Valid.	Dist.	Overall Acc.
1	Symbol	No	No	MFB [38]	60.02	47.24	81.86	95.09	0.74	53.22
2	Symbol	Yes	HAN	MFB [38]	61.70	47.49	81.83	95.02	0.68	54.14
3	Symbol	No	No	BAN [15]	60.27	50.06	82.80	95.94	0.86	54.84
4	Symbol	Yes	HAN	BAN [15]	65.89	58.36	83.39	96.50	0.49	61.88
5	Image	No	No	MAC [10]	71.23	38.91	84.48	96.16	5.34	54.06
6	Image	No	No	BAN [15]	76.00	40.41	85.58	96.16	10.52	57.10
7	Image	No	No	NSM [12]	78.94	49.25	84.28	96.41	3.71	63.17
8	Symbol+Image	Yes+GNN	HAN	BAN [15]	71.87	63.03	82.95	95.79	2.49	69.46

# Results

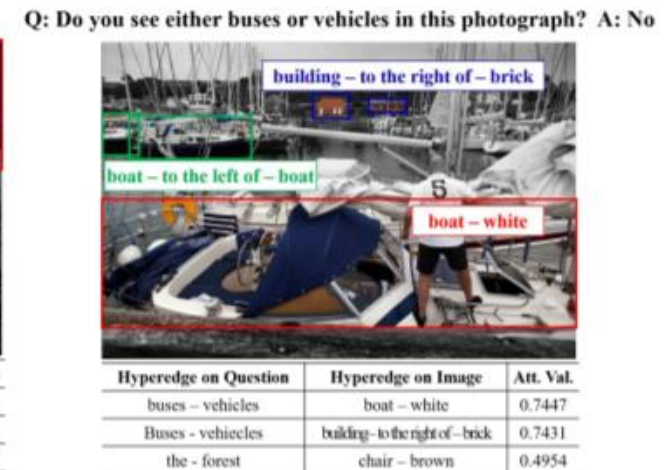
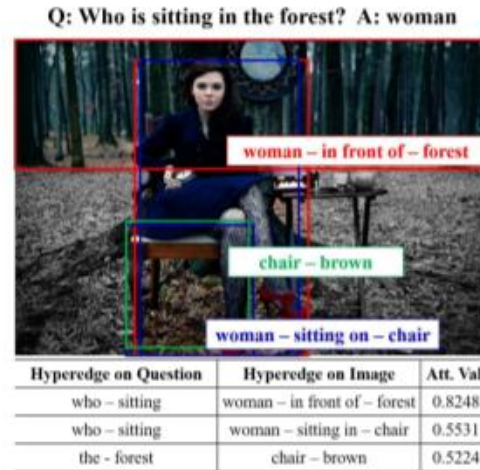
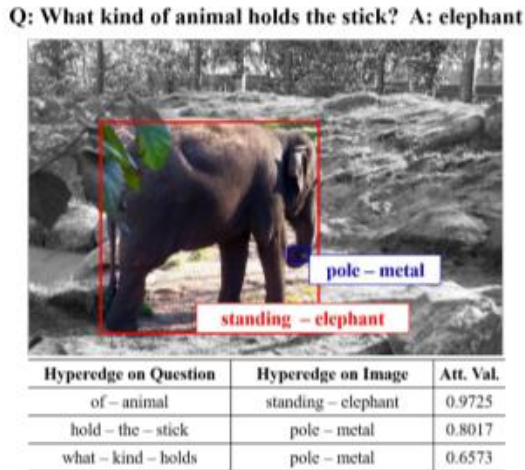
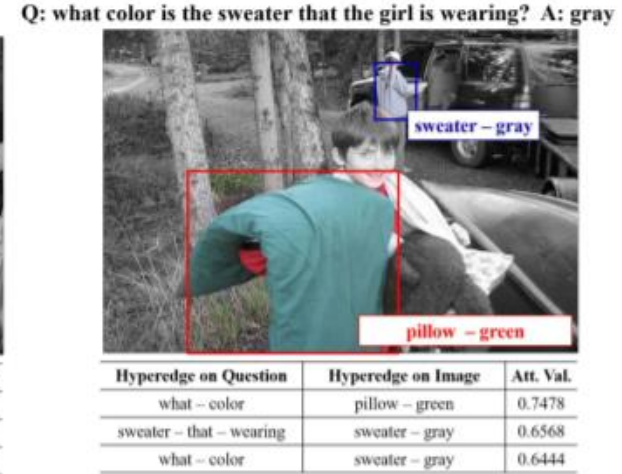
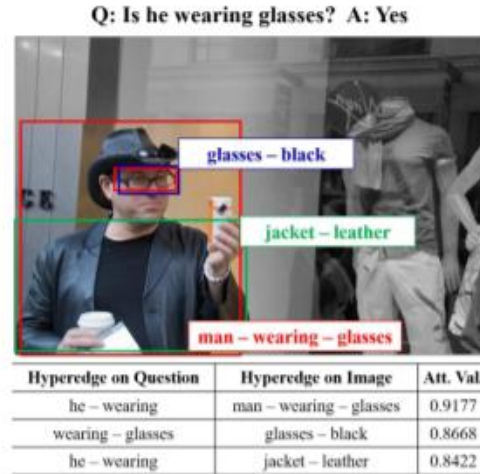
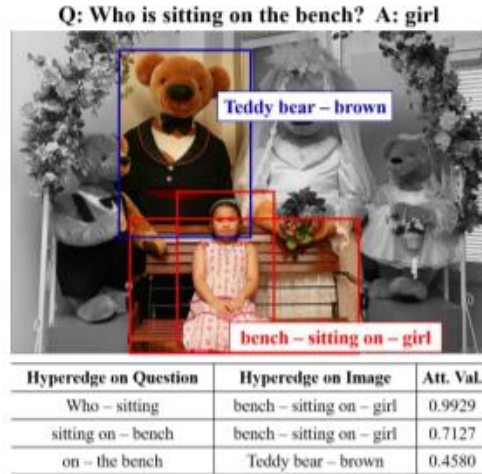


Figure 3. The visualization for co-attention maps  $\mathcal{A}$  of HANs with six examples. Among the all pairs of images and question hyperedges, three hyperedge pairs with top-3 attention-value are presented. The question is shown on the top of the image and the hyperedge pairs are on the bottom. Corresponding regions attended by HANs are represented on the image.

# Appendix

- Merging Visual Features

$$Y'_q \in \mathbb{R}^{N^q \times d'}$$

$$Y'_i \in \mathbb{R}^{N^v \times d'}$$

$$U'_q \in \mathbb{R}^{d' \times h}$$

$$U'_i \in \mathbb{R}^{d' \times h}$$

$$\mathbf{z}_v = (\hat{Y}_q \hat{U}_q)^\top \mathcal{A}^* (\hat{V}_i \hat{U}_i)$$

- Graph Neural Network

$$X \in \mathbb{R}^{S \times d}$$

$$A \in \{0, 1\}^{S \times S} \quad \text{adjacency matrix}$$

$$D_{in}, D_{out} \in \mathbb{R}^{N \times N} \quad \text{indegree, outdegree matrix of } A$$

$$X_{new} \in \mathbb{R}^{S \times d}$$

$$Z_{in} = \sigma(D_{in}^{-1} A X W_{in} + X W_{in})$$

$$Z_{out} = \sigma(D_{out}^{-1} A^\top X W_{out} + X W_{out})$$

$$X_{new} = \sigma((Z_{in} \circ Z_{out}) W_{mrg})$$