



Informative and Consistent Correspondence Mining for Cross-Domain Weakly Supervised Object Detection

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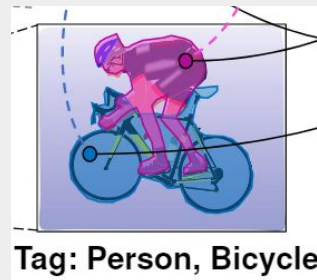
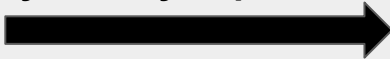
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PURPOSE



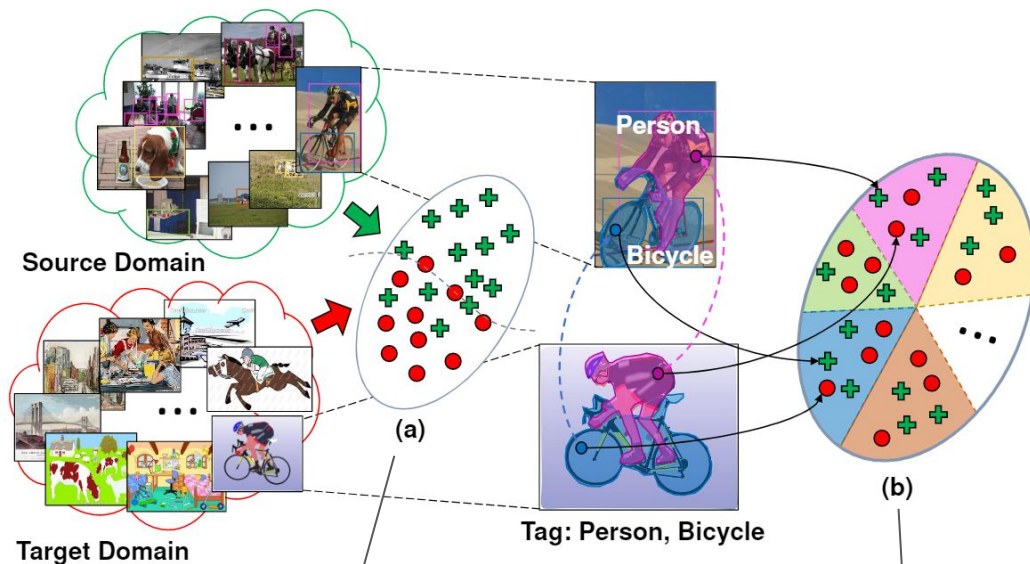
Source Domain (real-world)
Fully Annotated: class, bounding-box
(e.g. Pascal-VOC 2007 / 2012)

Domain Adaptation
by Weakly supervision



Target Domain (unreal)
Partially Annotated: presence of classes
(e.g. Clipart1k, Watercolor2k, Comic2k)

Introduction



(a) Conventional approaches (Domain-level)

- Project images from different domains into a unified feature space.
- Adversarially train discriminative classifier not to easily separate them.

(b) Our approach (Pixel-level)

- Explicitly establish pixel-wise correspondence among the semantic regions of cross-domain.
- Form semantic clusters in feature space for well explanation of source domain's region annotation.

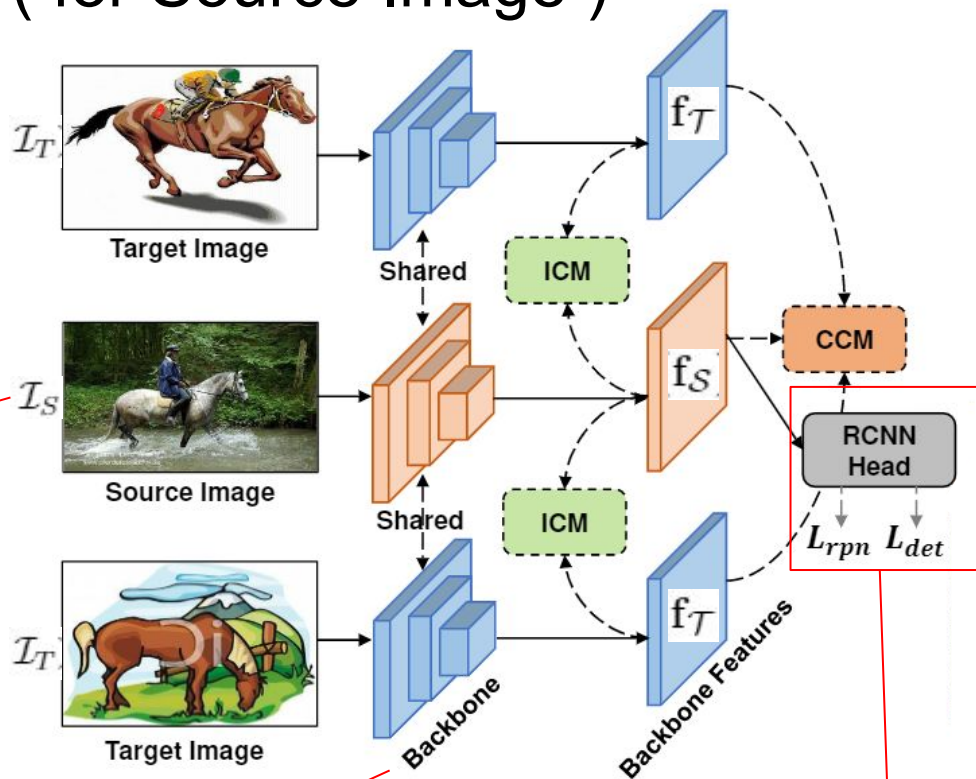
Overview : RCNN Head (for Source Image)

Semantic label

$$\mathbb{Y}_S = \{y_B \in \{0, 1\}^{1 \times (|C|+1)} | B \in \mathbb{B}\}$$

Bounding-box coordinates

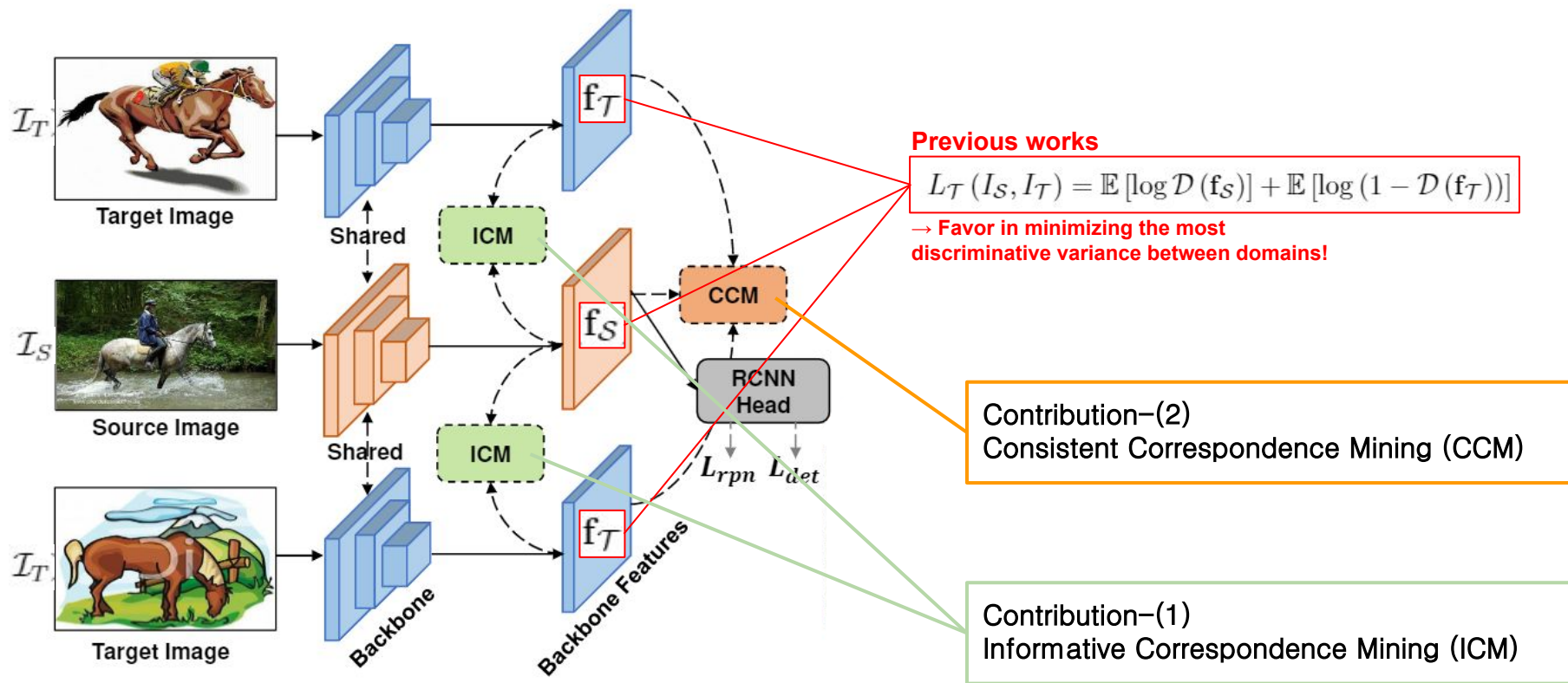
$$\mathbb{P}_S = \{p_B \in \mathbb{R}^{1 \times 4} | B \in \mathbb{B}\}$$



two-stage
Faster-RCNN

$$L_S(I_S, \mathbb{Y}_S, \mathbb{P}_S) = L_{rpn}(I_S, \mathbb{P}_S) + L_{det}(I_S, \mathbb{Y}_S, \mathbb{P}_S)$$

Overview : Contribution Points (Source-target DA)



Informative Correspondence Mining (ICM) - 1/4

"High-level idea : Drop the target partitions, not helping to explain source-domain region"

$$\min_{\Omega} \sum_{\substack{C_- \in \mathcal{C}_{S \cap T} \\ C_- \neq C_R}} I(\mathbf{w}_{\mathcal{R}}^{C_-}, \mathbf{w}_{\mathcal{R}}^{C_R} | \mathbb{I} = (\mathcal{I}_S, \mathcal{I}_T)) \quad \mathcal{C}_{S \cap T} \subseteq \mathcal{C} \cup \{C_0\}$$

assume to be constant ($P(\mathbf{w}_{\mathcal{R}}^{C_-} | \mathbb{I}) \rightarrow$ uniform distribution)

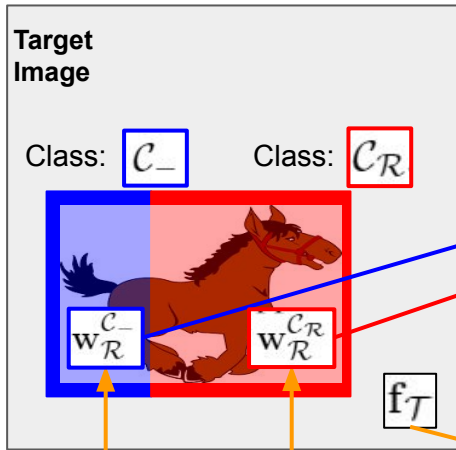
$$I(\mathbf{w}_{\mathcal{R}}^{C_-}, \mathbf{w}_{\mathcal{R}}^{C_R} | \mathbb{I}) = H(\mathbf{w}_{\mathcal{R}}^{C_-} | \mathbb{I}) - H(\mathbf{w}_{\mathcal{R}}^{C_-} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I})$$

$$H(X) = - \sum_{i=1}^n P(x_i) \log P(x_i)$$

Minimizing Mutual Information means.

Minimizing Entropy(Uncertainty) of Target Region for C_-

Maximizing Entropy(Uncertainty) of Target Region for C_- given Target Region for C_R

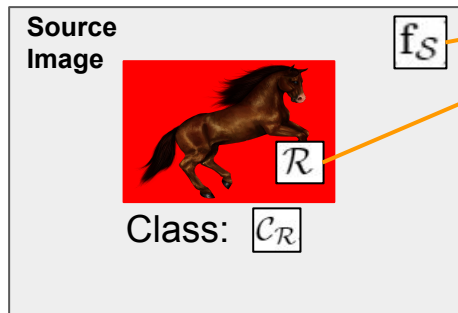


partition generator
(Single Conv layer)
 $g: f_T \rightarrow (0,1)^{H \times W \times x | \mathcal{C}|}$

Target to Source
Attention pooling

$$\mathbf{w}_{\mathcal{R}}^{C_-} = \text{avgpool}(\text{norm}(\mathbf{m}(\Omega_C) \odot \kappa(f_S, f_T)), \mathcal{R}),$$

where $\kappa(f_S, f_T) = \text{softmax}(f_S^T \mathbf{W} f_T)$.



The Problem here is computing posterior for $H(\mathbf{w}_{\mathcal{R}}^{C_-} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I}) \rightarrow P(\mathbf{w}_{\mathcal{R}}^{C_-} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I})$

Informative Correspondence Mining (ICM) - 2/4

Solution : Variational approximation !

$$P(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) \approx Q(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) = \int P(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) P(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbf{a}_{\mathcal{R}}, \mathbb{I}) d\mathbf{a}_{\mathcal{R}}, \quad (1)$$

Since $P(\mathbf{a} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) = \frac{P(\mathbf{w}_{\mathcal{R}}^{c_+} | \mathbf{a}, \mathbb{I}) P(\mathbf{a} | \mathbb{I})}{P(\mathbf{w}_{\mathcal{R}}^{c_+} | \mathbb{I})}$ it takes 1 when $\mathbf{a} = \mathbf{a}_{\mathcal{R}}$ and 0 otherwise. is delta distribution,

by marginalizing $\mathbf{a}_{\mathcal{R}}$, $(1) \rightarrow Q(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) = P(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{c_-}, \mathbb{I}) P(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbb{I})$ (2)
 s.t. $\mathbf{a}_{\mathcal{R}} = \arg \max_{\mathbf{a}} P(\mathbf{a} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I})$.

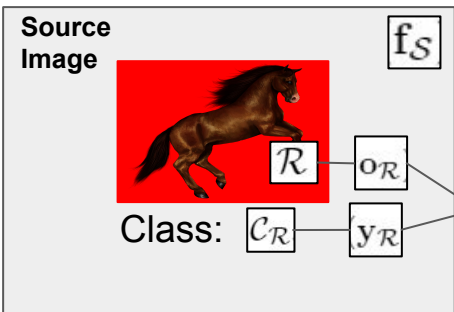
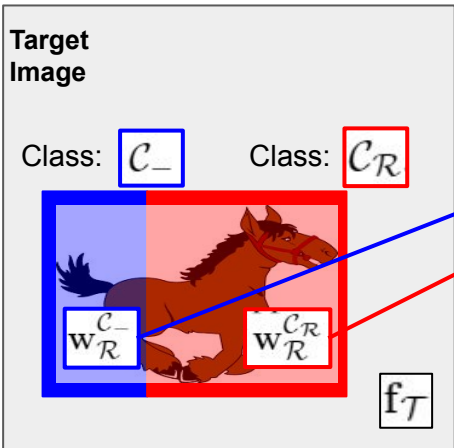
by rule of conditional entropy,

$$\begin{aligned} H(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) &\approx H_Q(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbf{w}_{\mathcal{R}}^{c_+}, \mathbb{I}) \\ &= H_Q(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{c_-}, \mathbb{I}) + H_Q(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbb{I}) - H_Q(\mathbf{a}_{\mathcal{R}} | \mathbb{I}), \end{aligned} \quad (3)$$

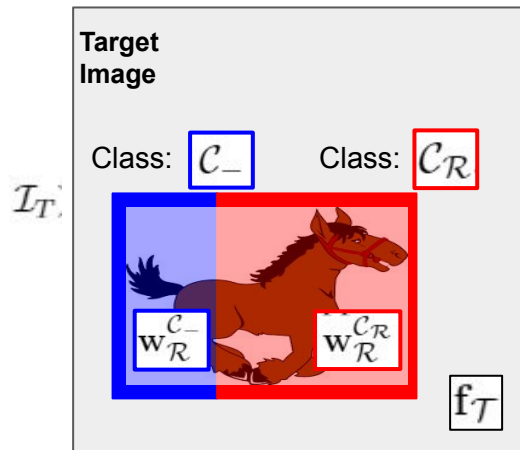
Since that $H(\mathbf{w}_{\mathcal{R}}^{c_-} | \mathbb{I})$ and $H(\mathbf{a}_{\mathcal{R}} | \mathbb{I})$ are constants,

$$\min_{\Omega} \sum_{\substack{C_- \in \mathcal{C}_{S \cap \mathcal{T}} \\ C_- \neq C_{\mathcal{R}}}} I(\mathbf{w}_{\mathcal{R}}^{C_-} | \mathbf{w}_{\mathcal{R}}^{C_{\mathcal{R}}} | \mathbb{I} = (\mathcal{I}_S, \mathcal{I}_{\mathcal{T}})) \xrightarrow{\text{Approximation}} \max_{\Omega} A(S, \mathcal{T}) = \frac{1}{Z_A} \sum_{\mathbb{I}} \sum_{\mathcal{R} \in \mathcal{R}_S} \sum_{C_-} H(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_-}, \mathbb{I})$$

s.t. $\mathbf{a}_{\mathcal{R}} = \arg \max_{\mathbf{a}} P(\mathbf{a} | \mathbf{w}_{\mathcal{R}}^{C_{\mathcal{R}}}, \mathbb{I})$,



Informative Correspondence Mining (ICM) - 3/4



$$\max_{\Omega} A(\mathcal{S}, \mathcal{T}) = \frac{1}{Z_A} \sum_{\mathbb{I}} \sum_{\mathcal{R} \in \mathbb{R}_S} \sum_{\mathcal{C}_-} H(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_-}, \mathbb{I}) \rightarrow \text{Deemed as "adversarial correspondence drop"}$$

$$\text{s.t. } \mathbf{a}_{\mathcal{R}} = \arg \max_{\mathbf{a}} P(\mathbf{a} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I}),$$

By relaxing the constraints,

$$\min_{\mathbf{w}} \left(\lambda N(\mathcal{S}, \mathcal{T}) + \max_{\Omega} A(\mathcal{S}, \mathcal{T}) \right),$$

$$N(\mathcal{S}, \mathcal{T}) = -\frac{1}{Z_N} \sum_{\mathbb{I}} \sum_{\mathcal{R} \in \mathbb{R}_S} \log P(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I})$$

Now, what we need is only the posterior

$$P(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I})$$

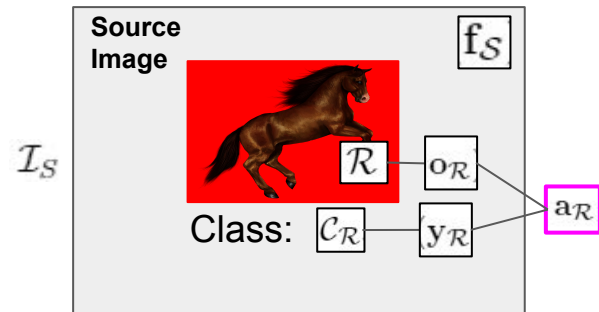
$$P(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I}) = P(\mathbf{y}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I}) P(\mathbf{o}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{C_R}, \mathbb{I}), \quad \mathbf{a}_{\mathcal{R}} = (\mathbf{y}_{\mathcal{R}}, \mathbf{o}_{\mathcal{R}})$$

$$\mathbf{f}_{\mathcal{R}}^C = (\mathbf{w}_{\mathcal{R}}^C)^T \mathbf{f}_T,$$

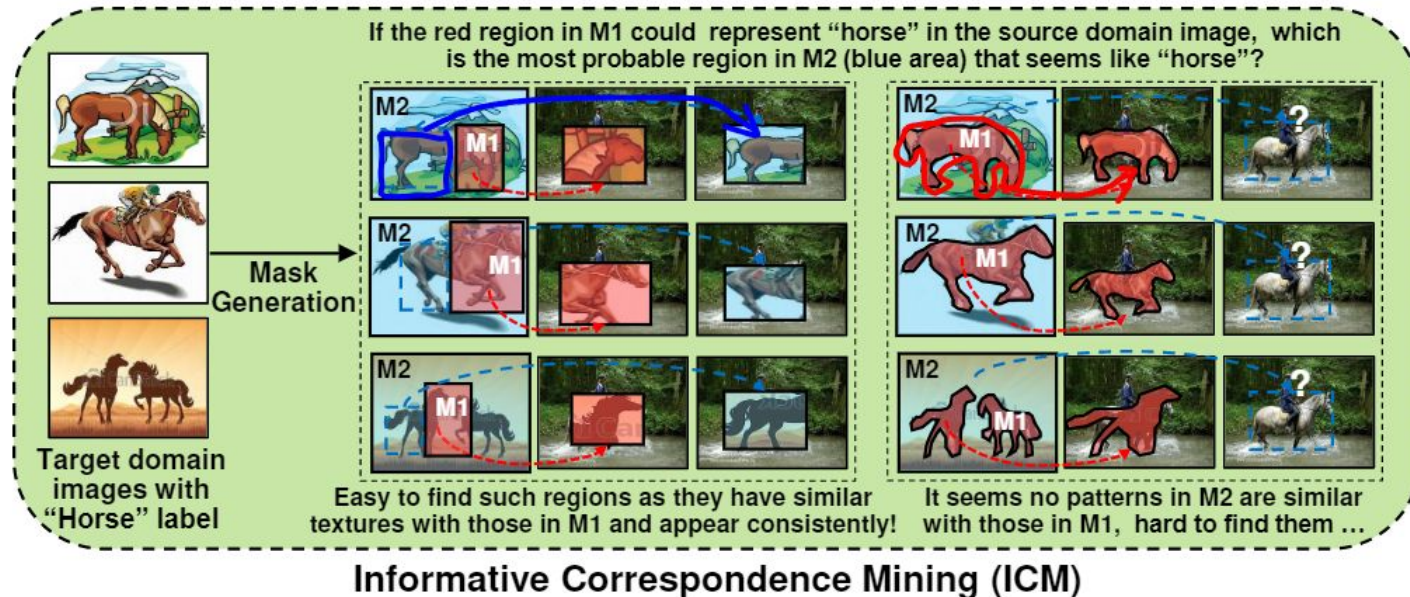
by using 2 separate FC layer,

$$P(\mathbf{y}_{\mathcal{R}}^C | \mathbf{w}_{\mathcal{R}}^C, \mathbb{I}) \sim \text{softmax}(\mathbf{y}_{\mathcal{R}}^C, \mathcal{F}_c(\mathbf{f}_{\mathcal{R}}^C)),$$

$$P(\mathbf{o}_{\mathcal{R}}^C | \mathbf{w}_{\mathcal{R}}^C, \mathbb{I}) \sim \exp\left(-\frac{\|\mathbf{o}_{\mathcal{R}}^C - \mathcal{F}_o(\mathbf{f}_{\mathcal{R}}^C)\|_1}{\sigma_o^2}\right).$$



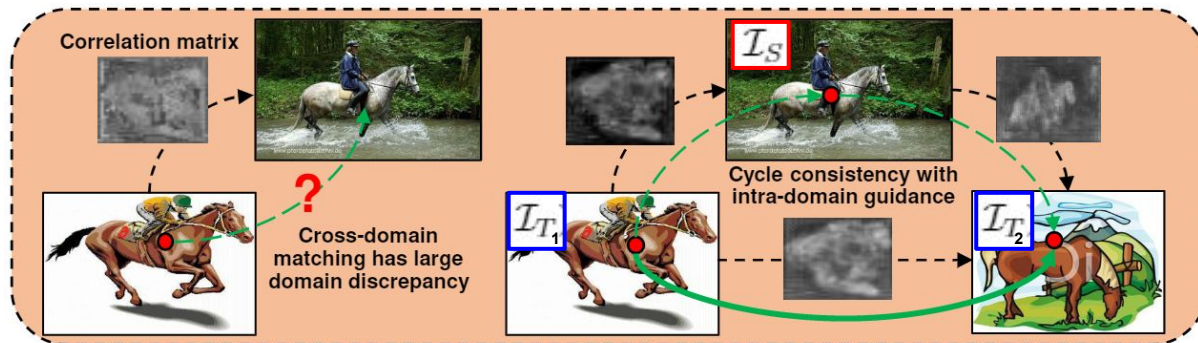
Informative Correspondence Mining (ICM) - 4/4



By doing this procedure, the model adversarially drops the information on the target image to make the correspondence searching harder.

Consistent Correspondence Mining (CCM) - 1/2

“High-level idea : intra-intra ($A \rightarrow A$) domain matching should be equal to intra-inter-intra ($A \rightarrow B \rightarrow A$) domain matching”



Consistent Correspondence Mining (CCM)

$$C(\mathcal{S}, \mathcal{T}) = \frac{1}{Z_C} \sum_{\mathbb{J}} \mathbf{R}_{\mathbb{J}} \|\mathbf{K}_{\mathcal{T}_1 \leftarrow \mathcal{T}_2} - \mathbf{K}_{\mathcal{T}_1 \leftarrow \mathcal{S}} \mathbf{K}_{\mathcal{S} \leftarrow \mathcal{T}_2}\|_2^2,$$

$$\mathbb{J} = (\mathcal{I}_S, \mathcal{I}_{T_1}, \mathcal{I}_{T_2})$$

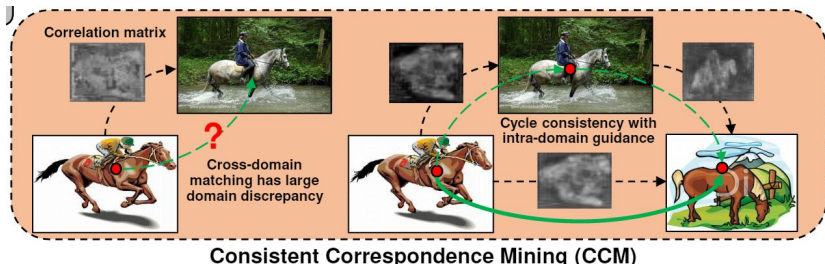
$$\mathbf{K}_{B \leftarrow A} = \kappa(\mathbf{f}_A, \mathbf{f}_B) \mathbf{f}_B$$

$$\kappa(\mathbf{f}_S, \mathbf{f}_T) = \text{softmax}(\mathbf{f}_S^T \mathbf{W} \mathbf{f}_T)$$

$\mathbf{R}_{\mathbb{J}}$ is $H \times W$ matrix quantifies “transferability” \rightarrow

\mathcal{I}_{T_1} and \mathcal{I}_{T_2} share a class that is absent in \mathcal{I}_S , we cannot expect to reconstruct the warping $\mathcal{T}_1 \leftarrow \mathcal{T}_2$ faithfully everywhere using the immediate warpings $\mathcal{T}_1 \leftarrow \mathcal{S}$ and $\mathcal{S} \leftarrow \mathcal{T}_2$.

Consistent Correspondence Mining (CCM) - 2/2



For $B \leftarrow A$ B is assumed as source image

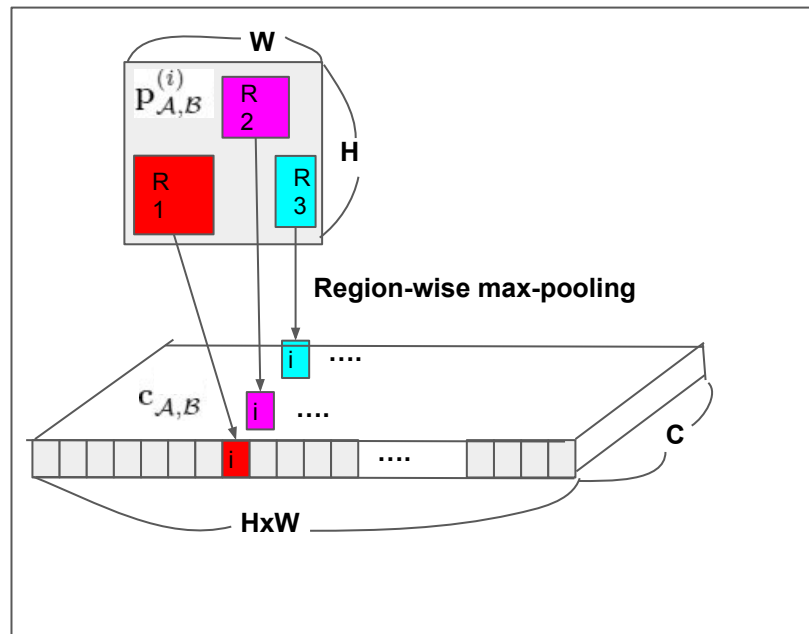
$$P_{A,B}^{(i)} = \text{softmax}((f_A^{(i)})^T W f_B) \xrightarrow{\text{Region-wise max-pooling}} c_{A,B}^{(i)} \in (0, 1)^{1 \times (|C|+1)}$$

Transferability $B \leftarrow A$: $r_{A,B}^{(i)} = \exp(-H(c_{A,B}^{(i)}))$.

if $f_A^{(i)}$ is a confident match, $c_A^{(i)}$ tends to have peaks, leading to low uncertainty (high transferability).

Accumulated Transferability $T_1 \leftarrow T_2$: $R_{\mathbb{J}} = r_{T_1,S} \odot (K_{T_1 \leftarrow T_2} r_{T_2,S})$

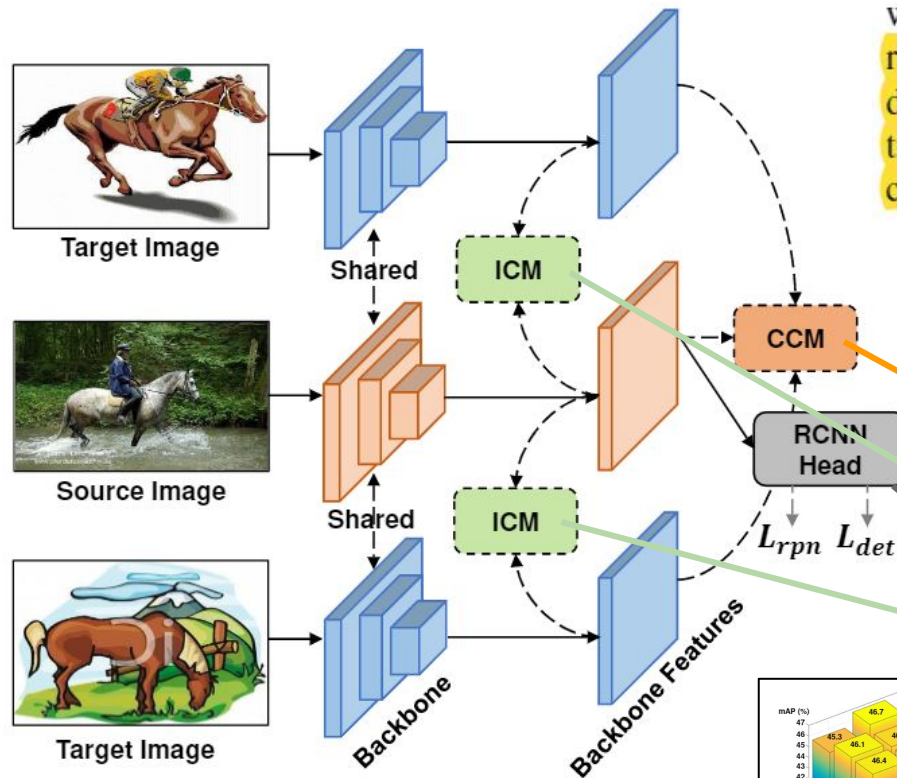
Detached when training due to gradient instability



$$C(S, T) = \frac{1}{Z_C} \sum_{\mathbb{J}} R_{\mathbb{J}} \|K_{T_1 \leftarrow T_2} - K_{T_1 \leftarrow S} K_{S \leftarrow T_2}\|_2^2,$$

Minimizing intra-domain attention-sum with intra-domain attention-sum through inter-domain (Weighted by transferability)

Final training objective



Class-agnostic ICM. The original multi-class version of ICM repeats correspondence learning for every class, which would be slow if the number of classes is large. A walk-around is to unify all the object classes as “foreground”, rendering it a binary foreground/background setting. In practice, we do not observe performance degeneration for this class-agnostic setting, yet saving training time significantly.

Used gradient reversal for adversarial training

$$\min_{\theta_0} \left(L_S + \alpha (\mathcal{N} + \max_{\theta_\Omega} A) + \beta C \right), \quad (7)$$

OD ICM CCM

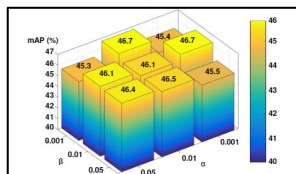


Figure 6. Mean average precision as a function of parameters α and β defined in Eqn. (7), evaluated on the Clipart1k dataset.

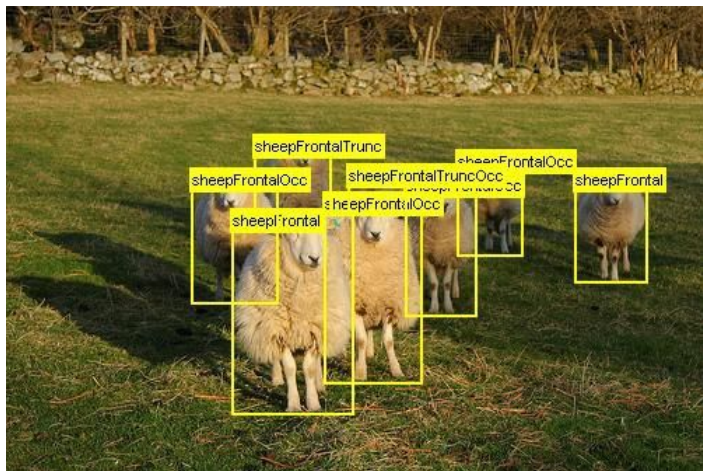
α and β in (7) with 0.001 and 0.01,

Datasets

Source domain : Pascal-VOC 2007 / 2012 (16551 real-world photo, 20 classes)

Target domain : Clipart1k (20 classes) , Watercolor2k (6 classes) , Comic2k (6 classes)

→ 1000 for each train/eval split



Pascal-VOC



(a) Clipart1k



(b) Watercolor2k



(c) Comic2k

Experimental results

WS : Weakly Supervised → w/o Domain Adaptation

UDA : Unsupervised Domain Adaptation → Assumed unlabeled target

CDWS : Cross-Domain Weakly Supervised → Assumed weakly labeled target

Table 1. Average Precisions (AP) and mean AP on Clipart1k. Bold highlights the top place while underline the second place.

Method	aero	bike	bird	boat	bottle	bus	car	cat	chair	cow	table	dog	horse	mbike	person	plant	sheep	sofa	train	tv	mAP
Source only	35.6	52.5	24.3	23.0	20.0	43.9	32.8	10.7	30.6	11.7	13.8	6	36.8	45.9	48.7	41.9	16.5	7.3	22.9	32	27.8
<i>WL Group</i>	→ performance degradation may due to style diversity of target domain																				
WSDDN [1]	1.6	3.6	0.6	2.3	0.1	11.7	4.5	0.0	3.2	0.1	2.8	2.3	0.9	0.1	14.4	16.0	4.5	0.7	1.2	18.3	4.4
CLNet [17]	3.2	22.3	2.2	0.7	4.6	4.8	17.5	0.2	4.8	1.6	6.4	0.6	4.7	0.6	12.5	13.1	14.1	4.1	8.0	29.7	7.8
EDRN [34]	2.7	13.5	1.2	4.2	1.8	10.3	25.7	0.4	8.4	0.3	3.2	2.7	1.1	0.7	29.4	17.2	5.2	1.6	2.9	19.1	7.6
PCL [37]	3.4	10.6	2.3	1.7	5.2	3.4	23.3	1.2	5.6	0.4	7.8	3.7	5.6	0.3	24.5	19.7	11.9	3.6	9.2	25.4	8.4
<i>UDA Group</i>	→ performance degradation may due to inaccurate pseudo labels																				
ADDA [38]	20.1	50.2	20.5	23.6	11.4	40.5	34.9	2.3	39.7	22.3	27.1	10.4	31.7	53.6	46.6	32.1	18.0	21.1	23.6	18.3	27.4
SWDA [32]	26.2	48.5	32.6	<u>33.7</u>	38.5	54.3	37.1	<u>18.6</u>	34.8	<u>58.3</u>	17.0	12.5	33.8	65.5	61.6	52.0	9.3	24.9	54.1	<u>49.1</u>	38.1
STABR [19]	28.0	<u>64.5</u>	23.9	19.0	21.9	<u>64.3</u>	<u>43.5</u>	16.4	<u>42.2</u>	25.9	30.5	7.9	25.5	67.6	54.5	36.4	10.3	31.2	57.4	43.5	35.7
HTD [2]	<u>33.6</u>	<u>58.9</u>	<u>34.0</u>	23.4	45.6	<u>57.0</u>	39.8	12.0	39.7	51.3	21.1	<u>20.1</u>	<u>39.1</u>	<u>72.8</u>	<u>63.0</u>	43.1	<u>19.3</u>	<u>30.1</u>	<u>50.2</u>	51.8	<u>40.3</u>
<i>CDWS Group</i>																					
CDWSDA [15]	32.0	40.9	29.5	29.3	32.0	84.7	38.2	12.4	24.3	54.8	24.7	15.4	36.1	72.1	51.0	41.9	19.0	18.5	47.2	21.4	36.3
Proposed	39.8	66.7	37.2	42.5	<u>43.3</u>	48.1	48.1	21.3	46.5	73.0	<u>29.0</u>	29.8	57.3	78.6	67.8	<u>48.7</u>	46.3	19.3	42.8	48.5	46.7

Minor poputation categories : train, tv

Experimental results

WS : Weakly Supervised → w/o Domain Adaptation

UDA : Unsupervised Domain Adaptation → Assumed unlabeled target

CDWS : Cross-Domain Weakly Supervised → Assumed weakly labeled target

Table 2. Average Precisions (AP) and mean AP on Watercolor2k. Bold highlights the top place while underline the second place.

Method	bike	bird	car	cat	dog	person	mAP
Source only	68.8	46.8	37.2	32.7	21.3	60.7	44.6
<i>WL Group</i>							
WSDDN [1]	1.5	26.0	14.6	0.4	0.5	33.3	12.7
CLNet [17]	4.5	27.9	19.6	14.3	6.4	31.4	17.4
EDRN [34]	5.2	29.3	15.3	1.4	0.9	34.9	14.5
PCL [37]	6.7	28.8	20.2	9.5	5.4	27.4	16.3
<i>UDA Group</i>							
ADDA [38]	79.9	49.5	39.5	35.3	29.4	65.1	49.8
SWDA [32]	<u>82.3</u>	55.9	46.5	32.7	<u>35.5</u>	<u>66.7</u>	<u>53.3</u>
STABR [19]	75.6	45.8	49.3	34.1	30.3	64.1	49.4
HTD [2]	69.2	<u>49.5</u>	<u>49.5</u>	34.9	30.8	61.2	49.2
<i>CDWS Group</i>							
CDWSDA [15]	68.6	46.6	37.7	<u>35.2</u>	36.0	62.5	47.8
Proposed	86.6	64.2	52.6	32.4	41.2	67.4	57.4

Table 3. Average Precisions (AP) and mean AP on Comic2k. Bold highlights the top place while underline the second place.

Method	bike	bird	car	cat	dog	person	mAP
Source only	28.8	13.5	18.6	14.8	15.9	33.9	20.9
<i>WL Group</i>							
WSDDN [1]	1.5	0.1	11.9	6.9	1.4	12.1	5.6
CLNet [17]	0.0	0.0	2.0	4.7	1.2	14.9	3.8
EDRN [34]	1.6	0.5	13.2	7.2	2.5	13.2	6.4
PCL [37]	1.2	0.4	8.9	2.9	2.3	15.6	5.2
<i>UDA Group</i>							
ADDA [38]	39.5	9.8	17.2	12.7	20.4	43.3	23.8
SWDA [32]	30.3	19.6	28.8	15.2	24.9	<u>46.9</u>	27.6
STABR [19]	50.6	13.6	<u>31.0</u>	7.5	16.4	41.4	26.8
HTD [2]	35.4	14.8	26.6	13.7	26.9	40.0	26.2
<i>CDWS Group</i>							
CDWSDA [15]	47.0	<u>21.1</u>	30.1	<u>29.0</u>	<u>29.6</u>	40.6	<u>32.9</u>
Proposed	50.6	23.3	35.4	32.3	33.8	47.1	37.1

Experimental results

Good at multiple objects

Good at cluttered scene



Figure 3. Representative results generated by different approaches (visualized in different rows). Best viewed with zoom in.

Ablation study

$$\max_{\Omega} A(\mathcal{S}, \mathcal{T}) = \frac{1}{Z_A} \sum_{\mathbb{I}} \sum_{\mathcal{R} \in \mathbb{R}_S} \sum_{\mathcal{C}_-} H(\mathbf{a}_{\mathcal{R}} | \mathbf{w}_{\mathcal{R}}^{\mathcal{C}_-}, \mathbb{I})$$

→ Deemed as
“adversarial correspondence drop”

$$\text{s.t. } \mathbf{a}_{\mathcal{R}} = \arg \max_{\mathbf{a}} P(\mathbf{a} | \mathbf{w}_{\mathcal{R}}^{\mathcal{C}_-}, \mathbb{I}),$$

Table 4. Contributions to the final mAP by different component evaluated on the Clipart1k dataset.

Source	w/o adv.	ICM full	w/o reg.	CCM	mAP
✓					27.8
✓	✓				44.3
✓		✓			45.0
✓	✓			✓	45.7
✓			✓	✓	45.5
✓		✓		✓	46.7

→ demonstrating the advantage of pixel-wise knowledge transfer.

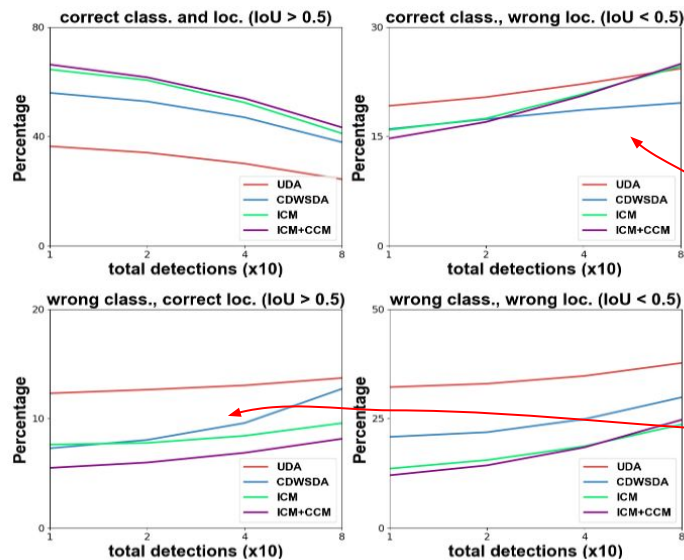
→ demonstrating adversarial mask generation effectiveness. (Full ICM)

→ demonstrating CCM effectiveness (Full ICM + CCM)

→ demonstrating objection position regression in ICM is beneficial for domain adaptation.



Analysis of error reduction



because ICM does not have pseudo labeling process that may introduce undesired labeling noise. (?????)



Figure 4. Percentage of detections within each type as a function of the number of detections. Top-left: detections with correct classification and localization. Top-right: classification is correct, but localization is weak ($0.1 < \text{IoU} < 0.5$). Bottom-left: wrong classification, but correct localization (IoU with at least one object exceeds 0.5). Bottom-right: detections with wrong labels and localization ($\text{IoU} < 0.1$). Note that higher percentage is preferred for only the top-left figure, as it counts for true positive detections.

Visualizing the effect of ICM and CCM

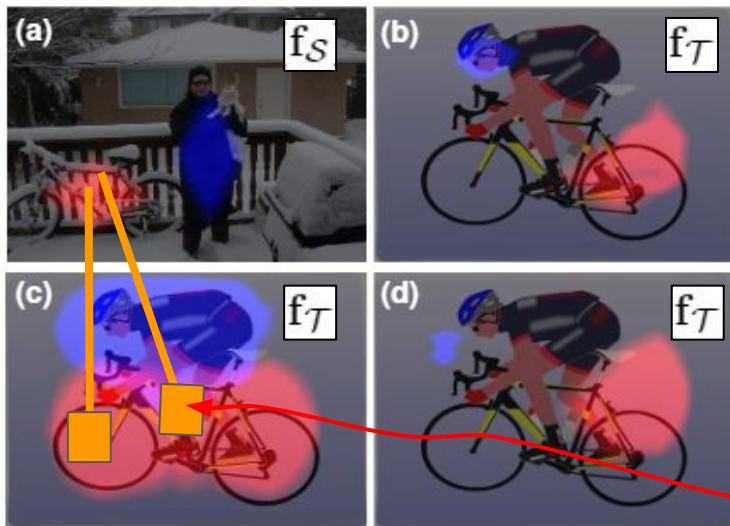


Figure 5. Visualizing the effect of Informative Correspondence Mining (ICM) and Consistent Correspondence Mining (CCM). (a) Seeds on the source domain image, weighted with a spatial Gaussian. (b) (c) (d): Visualization of the distribution of matched regions, corresponding to: (b) with naive ICM, but without adversarial masking; (c) the full ICM module; (d) without CCM.

$$\kappa(f_S, f_T) = \text{softmax}(f_S^T W f_T)$$

→ HW x HW
(matched position)

seeds are weighted by spatial Gaussian

Accumulated predicted bounding-box with 1 matched position's target feature as input to RCNN head

Thank you