

Neural Discrete Representation Learning

Van den Oord et al.

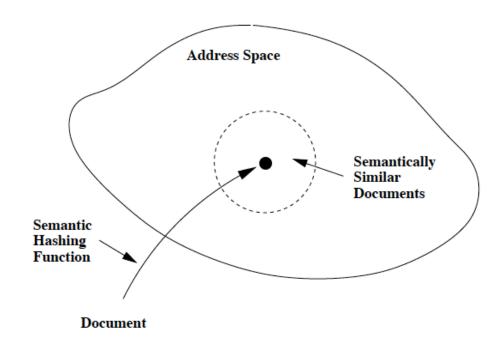
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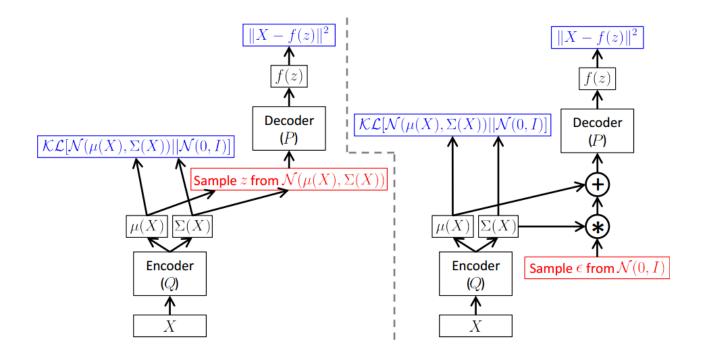
Why Discrete Latent Representation?



- Computational Efficiency
- Interpretability and Communication
- More Natural



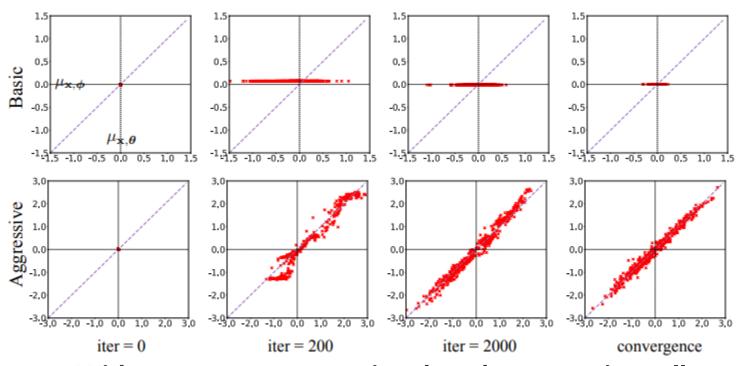
Auto-Encoding Variational Bayes



- Maximizing ELBO
- Ancestral sampling from Standard Normal D.



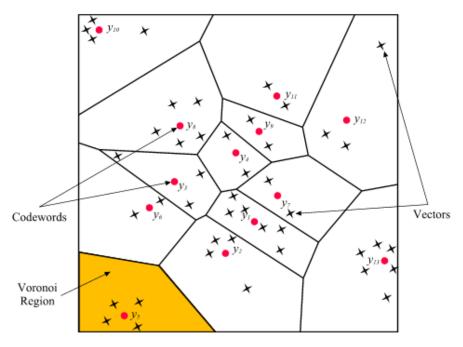
Posterior Collapse



- With strong autoregressive decoder, posterior collapse happens
- Not capturing meaningful representation



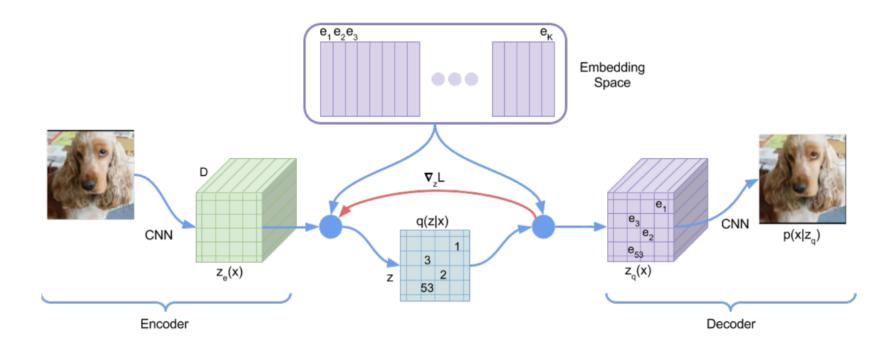
Vector Quantization



- Quantization technique for modeling probability density function by distribution of prototype vectors
- Originally used in lossy data compression



Overview





Categorical Distribution

Posterior and Prior are categorical distributions.

$$L = \log p(x|z_q(x)) + \|\operatorname{sg}[z_e(x)] - e\|_2^2 + \beta \|z_e(x) - \operatorname{sg}[e]\|_2^2,$$

$$q(z = k|x) = \begin{cases} 1 & \text{for } k = \operatorname{argmin}_{j} ||z_{e}(x) - e_{j}||_{2}, \\ 0 & \text{otherwise} \end{cases},$$

$$z_q(x) = e_k$$
, where $k = \operatorname{argmin}_j ||z_e(x) - e_j||_2$



Resolving Posterior Collapse

As for vanilla VAE,

$$D_{KL}((q_{\phi}(\mathbf{z})||p_{\theta}(\mathbf{z})) = \int q_{\theta}(\mathbf{z}) \left(\log p_{\theta}(\mathbf{z}) - \log q_{\theta}(\mathbf{z})\right) d\mathbf{z}$$
$$= \frac{1}{2} \sum_{j=1}^{J} \left(1 + \log((\sigma_{j})^{2}) - (\mu_{j})^{2} - (\sigma_{j})^{2}\right)$$

As for VQ VAE,

$$D_{\mathrm{KL}}(P \parallel Q) = \sum_{x \in \mathcal{X}} P(x) \log \left(\frac{P(x)}{Q(x)} \right).$$

For specific k, p(x), posterior is 1 and 0 otherwise, therefore yielding

$$\log K$$

Thus, posterior collapse(KL term -> 0) problem doesn't happen



Autoregressive Prior

 After training with uniform prior, autoregressive model is fit for learning prior distribution, thus generating more realistic images



uniform



autoregressive



Generating Diverse High-Fidelity Images with VQ-VAE-2

Ali Razavi et al.

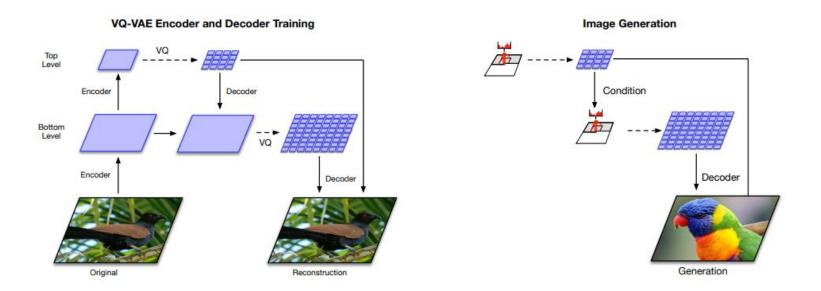
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Overview



Top CB for global structure, Bottom CB for the details



Algorithm

```
Algorithm 1 VQ-VAE training (stage 1)
                                                                        Algorithm 2 Prior training (stage 2)
Require: Functions E_{top}, E_{bottom}, D, \mathbf{x} 1: \mathbf{T}_{top}, \mathbf{T}_{bottom} \leftarrow \emptyset

    b training set

       (batch of training images)
                                                                          2: for x \in \text{training set do}
  1: \mathbf{h}_{top} \leftarrow E_{top}(\mathbf{x})
                                                                          3:
                                                                                     \mathbf{e}_{top} \leftarrow Quantize(E_{top}(\mathbf{x}))
                                                                          4:
                                                                                     \mathbf{e}_{bottom} \leftarrow Quantize(E_{bottom}(\mathbf{x}, \mathbf{e}_{top}))
      p quantize with top codebook eq 1
                                                                          5:
                                                                                     \mathbf{T}_{top} \leftarrow \mathbf{T}_{top} \cup \mathbf{e}_{top}
  2: \mathbf{e}_{top} \leftarrow Quantize(\mathbf{h}_{top})
                                                                                     \mathbf{T}_{bottom} \leftarrow \mathbf{T}_{bottom} \cup \mathbf{e}_{bottom}
                                                                          7: end for
 3: \mathbf{h}_{bottom} \leftarrow E_{bottom}(\mathbf{x}, \mathbf{e}_{top})
                                                                          8: p_{top} = TrainPixelCNN(\mathbf{T}_{top})
                                                                          9: p_{bottom} = TrainCondPixelCNN(T_{bottom}, T_{top})

    p quantize with bottom codebook eq 1

 4: \mathbf{e}_{bottom} \leftarrow Quantize(\mathbf{h}_{bottom})
                                                                               10: while true do
 5: \hat{\mathbf{x}} \leftarrow D(\mathbf{e}_{top}, \mathbf{e}_{bottom})
                                                                        11:
                                                                                     \mathbf{e}_{top} \sim p_{top}
                                                                        12:
                                                                                     \mathbf{e}_{bottom} \sim p_{bottom}(\mathbf{e}_{top})
      ▶ Loss according to eq 2
                                                                        13:
                                                                                     \mathbf{x} \leftarrow D(\mathbf{e}_{top}, \mathbf{e}_{bottom})
 6: \theta \leftarrow Update(\mathcal{L}(\mathbf{x}, \hat{\mathbf{x}}))
                                                                        14: end while
```

Experiment



Effect of Hierarchical Latent Representation



Figure 3: Reconstructions from a hierarchical VQ-VAE with three latent maps (top, middle, bottom). The rightmost image is the original. Each latent map adds extra detail to the reconstruction. These latent maps are approximately 3072x, 768x, 192x times smaller than the original image (respectively).