(1)
$$A = X \Omega_X = Ae \Omega_e + A\varphi \Omega_{\varphi} + A_{\varphi} \Omega_{\varphi}$$

 $Ae = A \cdot \Omega_{\varphi} = X \Omega_X \cdot \Omega_{\varphi} = X \cos \varphi = e^{-\cos^2 \varphi}$
 $A\varphi = A \cdot \Omega_{\varphi} = X \Omega_X \cdot \Omega_{\varphi} = X \cos(\varphi + \frac{\pi}{2}) = -x \sin \varphi = -e^{-\sin \varphi} \cos \varphi$
 $Az = A \cdot \Omega_{\varphi} = X \Omega_X \cdot \Omega_{\varphi} = 0$

$$A = e \cos^2 \phi \text{ all } - e \sin \phi \cos \phi \text{ all }$$

$$= e \cos \phi \text{ (as } \phi \text{ all } - \sin \phi \text{ all } \phi)$$

(2)
$$B = 2 \Omega_{T} = B_{x} \Omega_{T} + B_{y} \Omega_{y} + B_{z} \Omega_{z}$$

 $B_{x} = B_{x} \Omega_{T} + B_{y} \Omega_{y} + B_{z} \Omega_{z}$
 $B_{x} = B_{x} \Omega_{T} + B_{y} \Omega_{y} + B_{z} \Omega_{z}$
 $B_{x} = B_{x} \Omega_{T} + B_{y} \Omega_{y} + B_{z} \Omega_{z}$
 $B_{x} = 2 \Omega_{T} + B_{y} \Omega_{y} + B_{z} \Omega_{z}$
 $= 2 \Omega_{T} + \Omega_{$

$$B - B - ay = 2 ay = 2 sin 0 sin 6$$

$$= 2 \cdot \frac{\sqrt{x^2 + y^2}}{\sqrt{x^2 + y^2}} = \frac{2y}{\sqrt{x^2 + y^2}} = \frac{2y}{\sqrt{x^2 + y^2}}$$

(1)
$$E = \int \frac{e_s ds'(k-k')}{4\pi\epsilon_s |k-k'|^3} \qquad \begin{cases} k = 2 \alpha_t \\ k' = e' \alpha_t \end{cases} , ds' = e' de' de'$$

$$|k-k'| = \sqrt{2^2 + e'^2}$$

$$= \int_{0}^{2\pi} b \frac{e^{s} e^{s} (z dz - e^{s} de)}{4\pi \epsilon_{0} (z^{2} + e^{s})^{3/2}} de^{s} de^{s} de^{s}$$

$$= \int_{3}^{5} \frac{\ell_{s} e'_{z} d_{z}}{2\epsilon_{s} (z^{2}+\rho_{1}^{2})^{3/2}} de' = \frac{\ell_{s} z d_{z}}{2\epsilon_{s}} \int_{a}^{5} \frac{e'}{(z^{2}+\rho_{1}^{2})^{3/2}} de'$$

$$= \frac{\ell_{5} \neq 0 \ell_{7}}{2\epsilon_{5}} \int_{\mathbb{R}^{2}}^{2^{2} + 5^{2}} \frac{1}{2 + \frac{3}{2}} dt = \frac{\ell_{8} \neq 0 \ell_{7}}{2\epsilon_{5}} \left(\frac{1}{2} - \frac{1}{\sqrt{2^{2} + 5^{2}}} \right)$$

$$=\frac{\operatorname{Coll}_{2}\left(1-\frac{2}{\sqrt{2^{2}+b^{2}}}\right)$$

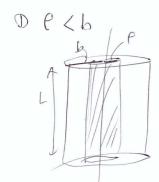
binomial expansion

(2)
$$E = \frac{e_1 ch_2}{2\epsilon_3} \left(1 - \frac{1}{\sqrt{1 + \frac{b^2}{2^2}}} \right) \stackrel{?}{=} \frac{e_1 ch_2}{2\epsilon_3} \left(1 - \frac{b^2}{2z^2} \right)$$

$$= \frac{\ell_{s} \Omega_{k}}{2\epsilon_{s}} \frac{L^{2}}{2\epsilon_{s}} = \frac{\ell_{s} L^{2}}{4\epsilon_{s} Z^{2}} \Omega_{k} = \frac{\ell_{s} L^{2}}{4\pi \epsilon_{s} Z^{2}} \Omega_{k} = \frac{Q}{4\pi \epsilon_{s} Z^{2}} \Omega_{k}$$

let D= De(P) We.

반기름 P 및 원통 며호 Gano 변으로 경역 정통





$$Q = \pi 5 L c$$

$$Q = \pi 5 L c$$

$$Q = \frac{5^2 c}{2p}$$

$$\frac{f \cdot \ell}{2} = \begin{cases} \frac{f \cdot \ell}{2} & \text{ar} & (\ell < b) \\ \frac{b^2 \ell}{2 \ell} & \text{ar} & (\ell > b) \end{cases}$$

$$E = \begin{cases} \frac{lol}{2E_0} & \text{al} & (ll) \\ \frac{lol}{2E_0} & \text{al} & (ll) \end{cases}$$

$$\nabla \cdot D = \frac{1}{e} \frac{\partial}{\partial e} \left(e D e \right) = \frac{1}{e} \frac{\partial}{\partial e} \left($$

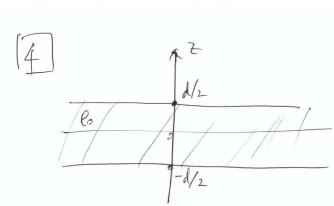
(3)
$$(2,2,0)$$
 = $\frac{15}{28}$ = $\frac{15}{26}$ $\frac{15}{26}$ $\frac{15}{26}$ $\frac{15}{26}$ $\frac{15}{26}$ $\frac{15}{26}$

$$= \frac{dz - dz}{\sqrt{z}}$$

$$= \frac{dz - dz}{\sqrt{z}}$$

$$= \frac{b^2 f_0 \left(dx - dz \right)}{\sqrt{z}}$$

$$= \frac{b^2 f_0 \left(dx - dz \right)}{\sqrt{z}}$$

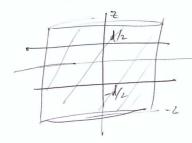


Lt of S, 30 77 (270) 1 -28012 Gans surface 2 760 Gans 527 309

$$\frac{1}{dl_2}$$

$$\frac{1}{dl_2}$$

$$\frac{1}{2}$$



$$\frac{z}{M_{2}}$$

$$\frac{1}{2}$$

$$D = \begin{cases} \frac{1}{2} d_{2} & (2) \frac{d}{2} \\ \frac{1}{2} d_{2} & (2) \frac{d}{2} \end{cases}$$

$$= \begin{cases} \frac{1}{2} d_{2} & (-\frac{1}{2}(2)) \\ -\frac{1}{2} d_{2} & (2) \frac{d}{2} \end{cases}$$

$$(2) r = 3$$

$$D_{r}(3) 4\pi.3^{2} = C_{1}.4\pi h^{2} = 20.4\pi.2^{2} = 3207$$

$$D_{+}(3) = \frac{30}{9}$$

$$\oint D \cdot dS = \frac{1}{6}$$

$$D_{r}(3) 4 \pi \cdot 5^{2} = \frac{1}{6} (4 \pi r_{1}^{2} + \frac{1}{6} + \frac{$$

$$D_r(3) = \frac{80 - 64}{25} = \frac{16}{25}$$

$$\frac{30}{9} \text{ M} + (r=1)$$

$$\frac{1}{2} \qquad \frac{1}{2} \qquad \frac{1$$

(2)
$$\int D \cdot ds = Q$$

$$Q = P_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = P_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_2^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_3^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2 + P_{S_3} 4\pi r_1^2$$

$$Q = Q_{S_1} 4\pi r_1^2 + P_{S_2} 4\pi r_1^2 + P_{S_3} 4\pi r_$$

$$\frac{1}{6} \cdot \frac{1}{6} = \frac{4 \cdot 4\pi \cdot 16 - 320\pi}{4\pi \cdot 36} = \frac{64 - 80}{36}$$

$$=\frac{-16}{36}=-\frac{4}{9}$$