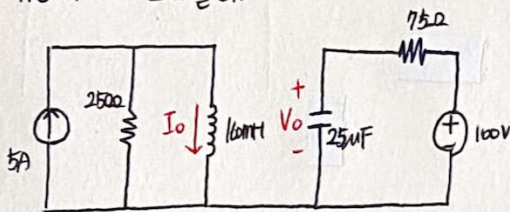
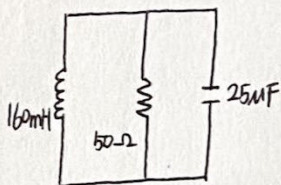


#8.11  $t < 0$  일 때인덕터에 걸리는 전류  $I_0 = 5[A]$ 축전기에 걸리는 전압  $V_0 = 100[V]$  $t > 0$  일 때, RLC 회로의 Natural Response.

$R = 50 \Omega$

$L = 160 \cdot 10^{-3} \text{ H}$

$C = 25 \cdot 10^{-6} \text{ F}$

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot 50 \cdot 25 \cdot 10^{-6}} = 400$$

$$\omega_0^2 = \frac{1}{LC} = \frac{1}{160 \cdot 10^{-3} \cdot 25 \cdot 10^{-6}} = (500)^2$$

$$\alpha^2 - \omega_0^2 = -90000 < 0. \quad \therefore \text{underdamped}$$

$$\omega_d = \sqrt{90000} = 300$$

$$V(t) = B_1 e^{-\alpha t} \cos \omega_d t + B_2 e^{-\alpha t} \sin \omega_d t$$

$$= B_1 e^{-400t} \cos 300t + B_2 e^{-400t} \sin 300t$$

$$V(0) = B_1 = V_0 = 100 [V] \quad \therefore B_1 = 100$$

$$\frac{dV(0)}{dt} = \frac{i_C(0)}{C} = \frac{1}{C} (-i_R - i_L) = \frac{1}{C} \left( -\frac{100}{50} - 5 \right) = \frac{1}{25 \cdot 10^{-6}} (-7) = -280000 = B_1 \alpha + B_2 \omega_d$$

$$= B_1 (-400) + B_2 \cdot 300$$

$$-400B_1 + 300B_2 = -280000$$

$$300B_2 = -280000 + 400 \cdot 100 = -240000. \quad \therefore B_2 = -800$$

$$\therefore V(t) = 100 e^{-400t} \cos 300t - 800 e^{-400t} \sin 300t [V]$$

#8.12.

$$I_0 = 5[A], \quad V_0 = 100[V] \text{로 동일.}$$

$$R = 40 \Omega, \quad L = 160 \cdot 10^{-3} \text{ H}, \quad C = 25 \cdot 10^{-6} \text{ F}$$

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot 40 \cdot 25 \cdot 10^{-6}} = 500$$

$$\omega_0 = 500 \text{ (#8.11과 동일)}$$

$$\alpha^2 - \omega_0^2 = 0. \quad \therefore \text{critically damped.}$$

$$V(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

$$= D_1 t e^{-500t} + D_2 e^{-500t}$$

$$V(0) = D_2 = V_0 = 100 \quad \therefore D_2 = 100$$

$$\frac{dV(0)}{dt} = \frac{i_C(0)}{C} = D_1 + D_2 (-\alpha) = D_1 - 500 D_2$$

$$= \frac{1}{C} \left( -\frac{V}{R} - i_L \right) = \frac{1}{25 \cdot 10^{-6}} \left( -\frac{100}{40} - 5 \right) = -300,000$$

$$\therefore D_1 = -300000 + 500 D_2 = -250000$$

$$\therefore V(t) = -250000 t e^{-500t} + 100 e^{-500t} [V]$$

#8.13

$$I_0 = 5[A], \quad V_0 = 100[V] \text{로 동일.}$$

$$R = 32 \Omega, \quad L = 160 \cdot 10^{-3} \text{ H}, \quad C = 25 \cdot 10^{-6} \text{ F}$$

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot 32 \cdot 25 \cdot 10^{-6}} = 625$$

$$\omega_0 = 500, \quad \alpha^2 - \omega_0^2 > 0. \quad \therefore \text{overdamped!}$$

$$V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$s = -625 \pm \sqrt{625^2 - 500^2} = -625 \pm 375$$

$$s_1 = -250, \quad s_2 = -1000$$

$$V(t) = A_1 e^{-250t} + A_2 e^{-1000t}$$

$$V(0) = A_1 + A_2 = V_0 = 100$$

$$\frac{dV(0)}{dt} = \frac{di(0)}{C} = \frac{1}{C} \left( -\frac{100}{32} - 5 \right) = \frac{1}{25 \cdot 10^{-6}} \left( -\frac{100}{32} - 5 \right)$$

$$= -325,000 = s_1 A_1 + s_2 A_2 = -250 A_1 - 1000 A_2$$

$$A_1 + A_2 = 100$$

$$3A_2 = 200, \quad A_2 = 400$$

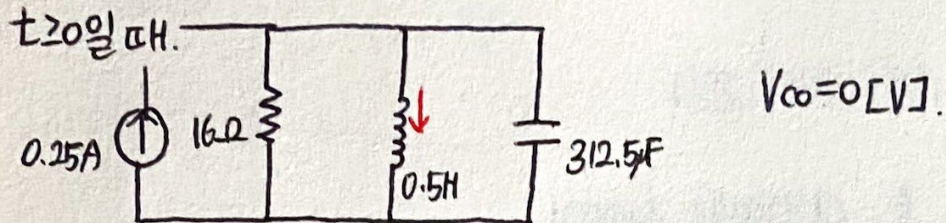
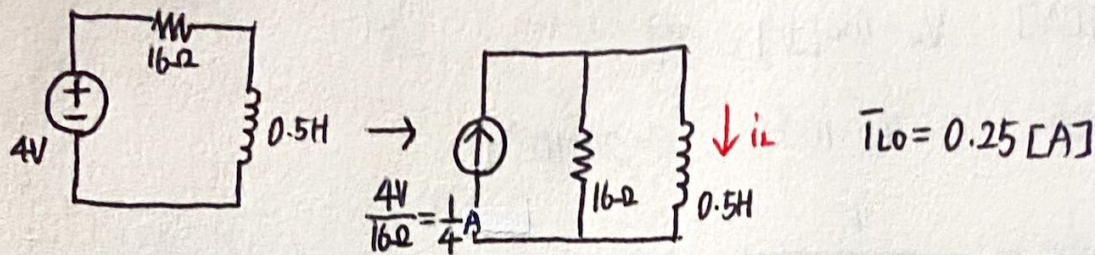
$$A_1 + 4A_2 = 1300$$

$$A_1 = -300$$

$$V(t) = -300 e^{-250t} + 400 e^{-1000t} [V]$$



#8.30  $t < 0$  일 때.



$$\alpha = \frac{1}{2RC} = \frac{1}{2 \cdot 16 \cdot 312.5 \cdot 10^{-6}} = 100. \quad \omega_0^2 = \frac{1}{LC} = 6400.$$

$$\alpha^2 - \omega_0^2 > 0. \quad \alpha^2 > \omega_0^2 \quad \approx \text{overdamped response.}$$

$$V(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}, \quad s = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -100 \pm 60$$

$$= A_1 e^{-40t} + A_2 e^{-160t} \quad = -40 \text{ or } -160.$$

$$V(0) = A_1 + A_2 = V_{C0} = 0.$$

$$\frac{dV(0)}{dt} = \frac{i_C(0)}{C} = \frac{1}{312.5 \cdot 10^{-6}} \cdot (-i_R - i_L + 0.25) = \frac{1}{312.5 \cdot 10^{-6}} (-0 - 0.25 + 0.25)$$

$$= 0. \quad = s_1 A_1 + s_2 A_2 = -40 A_1 - 160 A_2 = 0.$$

$$A_1 = A_2 = 0. \quad \therefore V(t) = 0.$$

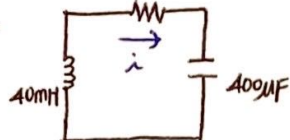


#8.46.  $t < 0$ .

$$I_0 = -150 \cdot 10^{-3} \text{ [A]}$$

문제에서 제시해준  
의 방향과 반대이므로 (-)

$t > 0$ .



$$R = 20 \Omega$$

$$L = 40 \cdot 10^{-3} \text{ H}$$

$$C = 400 \cdot 10^{-6} \text{ F}$$

< Series, natural response >

$$\alpha = \frac{R}{2L} = \frac{20}{2 \cdot 40 \cdot 10^{-3}} = 250 \text{ [rad/s]}$$

$$\omega_0^2 = \frac{1}{LC} = \frac{1}{40 \cdot 10^{-3} \cdot 400 \cdot 10^{-6}} = (250)^2 \text{ [rad}^2/\text{s}^2]$$

$\alpha^2 = \omega_0^2$  이므로 Critically damped!

$$I(t) = D_1 t e^{-\alpha t} + D_2 e^{-\alpha t}$$

$$I(0) = D_2 = I_0 = -150 \cdot 10^{-3}$$

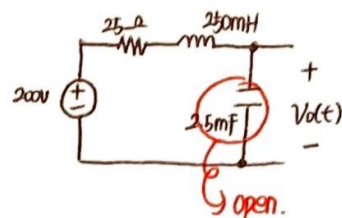
$$\frac{dI(0)}{dt} = \frac{1}{L} (-V_R - V_C) = \frac{1}{40 \cdot 10^{-3}} (-20) \cdot (-150 \cdot 10^{-3}) - 0$$

$$= \frac{1}{40 \cdot 10^{-3}} \cdot 20 \cdot 150 \cdot 10^{-3} = 75 = D_1 - \alpha D_2$$

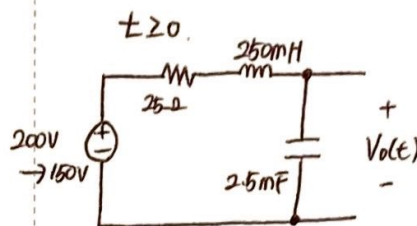
$$D_1 = 75 + \alpha D_2 = 75 + 250 \cdot (-150 \cdot 10^{-3}) = 37.5$$

$$I(t) = 37500 t e^{-250t} - 150 e^{-250t} \text{ [mA]}$$

#8.53.  $t < 0$ .



$$V_0 = 200 \text{ [V]}$$



$$V_P = 150 \text{ [V]}$$

Series, step response.

$$R = 25 \Omega$$

$$L = 250 \cdot 10^{-3} \text{ H}$$

$$C = 25 \cdot 10^{-3} \text{ F}$$

$$\alpha = \frac{R}{2L} = \frac{25}{2 \cdot 250 \cdot 10^{-3}} = 50 \text{ [rad/s]}$$

$$\omega_0^2 = \frac{1}{LC} = \frac{1}{250 \cdot 10^{-3} \cdot 25 \cdot 10^{-3}} = 1600 \text{ [rad}^2/\text{s}^2]$$

$\alpha^2 < \omega_0^2$ ,  $\therefore$  overdamped!

$$V_C(t) = V_P + A_1' e^{s_1 t} + A_2' e^{s_2 t}$$

$$S = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -50 \pm \sqrt{2500 - 1600} = -50 \pm 30$$

$$S_1 = -20, S_2 = -80$$

$$V_C(0) = V_P + A_1' + A_2' = V_0 = 200$$

$$A_1' + A_2' = 200 - V_P = 200 - 150 = 50 \quad -①$$

$$\frac{dV_C(0)}{dt} = \frac{I_0}{C} = 0 \quad (\because I_0 = 0)$$

$$= A_1' S_1 + A_2' S_2 = -20 A_1' - 80 A_2' = 0 \quad -②$$

$$② \rightarrow 20 A_1' = -80 A_2', \quad A_1' = -4 A_2'$$

$$① \text{ 대입 } -3 A_2' = 50, \quad A_2' = -\frac{50}{3}, \quad A_1' = -4 \cdot A_2' = \frac{200}{3}$$

$$A_1' = 66.67, \quad A_2' = -16.67$$

$$\therefore V_C(t) = 150 + 66.67 e^{-20t} - 16.67 e^{-80t} \text{ [V]}$$