

$$1. (1) A(x, y, z) = x a_x$$

$$A(x, y, z) \cdot a_\rho = x a_x \cdot a_\rho = x \cos \phi$$

$$A(x, y, z) \cdot a_\phi = x a_x \cdot a_\phi = -x \sin \phi$$

$$A(x, y, z) \cdot a_z = 0.$$

~~$$A(x, y, z) \cdot a_\rho$$~~

$$1. A(\rho, \phi, z)$$

$$\underline{= x \cos \phi a_\rho + (-x) \sin \phi a_\phi}$$

$$(2) B(r, \theta, \phi) = 2a r.$$

$$B(r, \theta, \phi) \cdot a_x = 2a r \cdot a_x = 2 \sin \theta \cos \phi$$

$$B(r, \theta, \phi) \cdot a_y = 2a r \cdot a_y = 2 \sin \theta \sin \phi$$

$$B(r, \theta, \phi) \cdot a_z = 2a r \cdot a_z = 2 \cos \theta$$

$$\therefore B(x, y, z) = 2 \sin \theta \cos \phi a_x + 2 \sin \theta \sin \phi a_y + 2 \cos \theta a_z$$

(10).

$$2. (1) dE = \frac{dQ (|r-r'|)}{4\pi\epsilon_0 (|r-r'|)^{3/2}}$$

$$|r| = z a_z, \quad |r'| = \rho a_\rho$$

$$|r-r'| = z a_z - \rho a_\rho$$

~~$$dS$$~~
$$dS = \rho d\rho d\phi$$

$$E = \int \frac{dQ (|r-r'|)}{4\pi\epsilon_0 (|r-r'|)^{3/2}} = \int \frac{\rho_s dS (|r-r'|)}{4\pi\epsilon_0 (|r-r'|)^{3/2}} = \int_0^b \int_0^{2\pi} \frac{\rho_s (z a_z - \rho a_\rho)}{4\pi\epsilon_0 (z^2 + \rho^2)^{3/2}} d\phi d\rho$$

$$= \int_0^b \int_0^{2\pi} \frac{\rho_s z a_z}{4\pi\epsilon_0 (z^2 + \rho^2)^{3/2}} d\phi d\rho = \frac{\rho_s z}{4\pi\epsilon_0} a_z \int_0^b \int_0^{2\pi} \frac{\rho}{(z^2 + \rho^2)^{3/2}} d\phi d\rho$$

$$= \frac{\rho_s z}{2\epsilon_0} a_z \int_0^b \frac{\rho}{(z^2 + \rho^2)^{3/2}} d\rho$$

$$\int_0^b \frac{\rho}{(z^2 + \rho^2)^{3/2}} d\rho = \left[-\frac{1}{\sqrt{z^2 + \rho^2}} \right]_0^b = \left[-\frac{1}{\sqrt{z^2 + b^2}} \right]_0^b = \frac{1}{z} - \frac{1}{\sqrt{z^2 + b^2}}$$

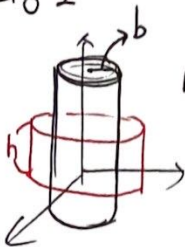
$$\therefore E = \frac{\rho_s z}{2\epsilon_0} \left(\frac{1}{z} - \frac{1}{\sqrt{z^2 + b^2}} \right) a_z$$

$$\rightarrow = \left(1 - \left(1 + \left(\frac{b}{z} \right)^2 \right)^{-\frac{1}{2}} \right)$$

$$(2) E = \frac{\rho_s}{2\epsilon_0} \left(1 - \frac{z}{\sqrt{z^2 + b^2}} \right) a_z = \frac{\rho_s}{2\epsilon_0} \left(1 - \frac{1}{\sqrt{1 + \left(\frac{b}{z} \right)^2}} \right) a_z \quad z \gg b \text{ or } z \gg$$

$$E \approx \frac{\rho_s}{2\epsilon_0} \left(1 - \left(1 - \frac{1}{2} \left(\frac{b}{z} \right)^2 \right) \right) a_z = \frac{\rho_s}{2\epsilon_0} \cdot \frac{1}{2} \cdot \frac{b^2}{z^2} a_z = \frac{\rho_s b^2}{4\epsilon_0 z^2} a_z \text{ 이 근사할 수 있다.}$$

3.



$$\rho_r = \rho_0.$$

$$V = \pi b^2 h.$$

(1).

① $\rho > b$ 일 때 (외부).

$$\oint \mathbf{D} \cdot d\mathbf{S} = Q = \rho_r V = \rho_0 V.$$

$$\mathbf{D} = D_\rho(\rho) \mathbf{a}_\rho.$$

$$dS = 2\pi \rho h \cdot a_\rho.$$

$$D_\rho(\rho) \mathbf{a}_\rho \cdot 2\pi \rho h \mathbf{a}_\rho = D_\rho(\rho) \cdot 2\pi \rho h = \rho_0 V = \rho_0 \pi b^2 h.$$

$$D_\rho(\rho) = \frac{\rho_0 \pi b^2 h}{2\pi \rho h} = \frac{\rho_0 b^2}{2\rho}$$

$$\mathbf{D} = \frac{\rho_0 b^2}{2\rho} \mathbf{a}_\rho, \Rightarrow \mathbf{E} = \frac{\rho_0 b^2}{2\rho \epsilon_0} \mathbf{a}_\rho.$$

② $\rho < b$ 일 때 (내부).

$$\oint \mathbf{D} \cdot d\mathbf{S} = \rho_0 V$$

$$D_\rho(\rho) \mathbf{a}_\rho \cdot 2\pi \rho h \mathbf{a}_\rho = D_\rho(\rho) \cdot 2\pi \rho h = \rho_0 V = \rho_0 \pi \rho^2 h.$$

$$D_\rho(\rho) = \frac{\rho_0 \pi \rho^2 h}{2\pi \rho h} = \frac{\rho_0 \rho}{2} \Rightarrow \mathbf{E} = \frac{\rho_0 \rho}{2\epsilon_0} \mathbf{a}_\rho.$$

(2).

① 외부

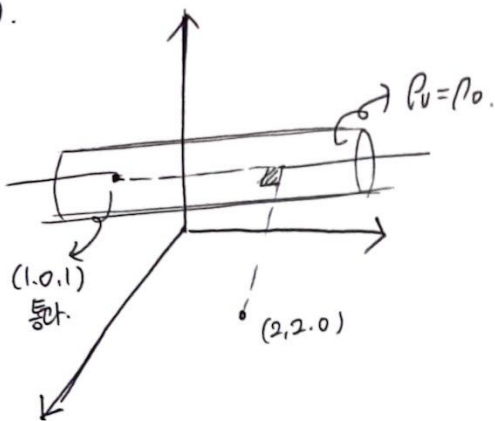
$$\nabla \cdot \mathbf{D} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho D_\rho) = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \cdot \frac{\rho_0 b^2}{2\rho} \right) = 0 \quad (\because \frac{\partial (\frac{\rho_0 b^2}{2})}{\partial \rho} = 0).$$

상승은 00000 상승.

② 내부.

$$\nabla \cdot \mathbf{D} = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \cdot \frac{\rho_0 \rho}{2} \right) = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\frac{\rho_0 \rho^2}{2} \right) = \frac{1}{\rho} \cdot \rho_0 \cdot \frac{2\rho}{2} = \rho_0. \text{ 이다.}$$

(3).



$$r = 2ax + 2ay$$

$$r' = ax + 2ay + az$$

$$r - r' = ax - az, \quad |r - r'| = \sqrt{2}$$

점 (2, 2, 0)은 원통 외부의 점이고, y축에 평행하므로.

$$E = \frac{\rho_0 b^2}{2\pi\epsilon_0} a_n \text{라 동일하다.}$$

ρ 은 (2, 2, 0)에서 원통의 중심에 대한 수선의 발과의 거리이므로.

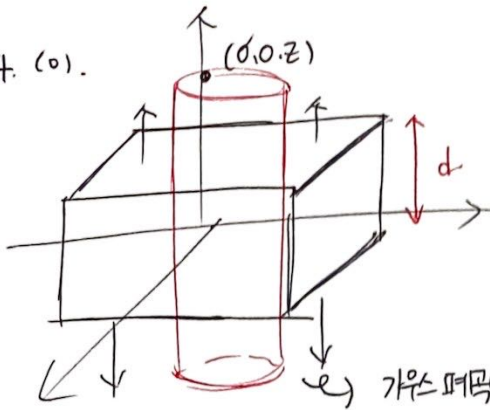
$$(2, 2, 0) \text{과 } (1, 2, 1) \text{과의 거리} \quad \rho = \sqrt{1+1} = \sqrt{2} \text{이다.}$$

$$E = \frac{\rho_0 b^2}{2\pi\epsilon_0} \frac{ax - az}{\sqrt{2}}$$

$$\frac{\rho_0 b^2}{4\epsilon_0} (ax - az)$$

$$\therefore E = \frac{\rho_0 b^2}{2\sqrt{2}\epsilon_0} \cdot \frac{ax - az}{\sqrt{2}} = \frac{\rho_0 b^2}{4\epsilon_0} (ax - az) \text{이다.}$$

4. (1).



$$\mathbf{D} = D_z(z) \mathbf{a}_z.$$

① $z > \frac{d}{2}$ 일 때...

$$\oint_S \mathbf{D} \cdot d\mathbf{S} = \rho_0 V.$$

$$= D_z(z) \cdot 2S = \rho_0 \cdot 2S \cdot d.$$

$$D_z(z) = \rho_0 d \Rightarrow \mathbf{D} = \rho_0 d \mathbf{a}_z. \quad \underline{\underline{\mathbf{E} = \frac{\rho_0 d}{\epsilon_0} \mathbf{a}_z.}}$$

② $z < \frac{d}{2}$ 일 때.

$$z > \frac{d}{2} \text{ 일 때와 크기 동일, 방향만 반대.} \quad \therefore \underline{\underline{\mathbf{E} = -\frac{\rho_0 d}{\epsilon_0} \mathbf{a}_z.}}$$

③ $0 < z < \frac{d}{2}$.

$$\oint_S \mathbf{D} \cdot d\mathbf{S} = D_z(z) \cdot 2S = \rho_0 V = \rho_0 \cdot 2S \cdot z.$$

$$D_z(z) = \rho_0 z \Rightarrow \mathbf{D} = \rho_0 z \mathbf{a}_z. \quad \therefore \underline{\underline{\mathbf{E} = \frac{\rho_0 z}{\epsilon_0} \mathbf{a}_z.}}$$

④ $-\frac{d}{2} < z < 0$.
 $0 < z < \frac{d}{2}$ 일 때와 크기 동일, 방향만 반대.

$$\therefore \underline{\underline{\mathbf{E} = -\frac{\rho_0 z}{\epsilon_0} \mathbf{a}_z.}}$$

#5. (o)

$$dS = r^2 \sin \theta \, d\theta \, d\phi$$

$$r_1 = 2. \quad \rho_{s1} = 20. \quad \rightarrow Q_{r1} = \int \rho_{s1} \cdot dS = \int_0^\pi \int_0^{2\pi} \rho_{s1} \cdot r^2 \sin \theta \, d\phi \, d\theta$$

$$r_2 = 4. \quad \rho_{s2} = -4.$$

$$r_3 = 6. \quad \rho_{s3}$$

$$= \rho_{s1} \cdot r^2 \int_0^\pi \int_0^{2\pi} \sin \theta \, d\phi \, d\theta = \rho_{s1} \cdot r^2 \cdot 2 \cdot 2\pi$$

$$= 20 \cdot 4 \cdot 4\pi = \underline{320\pi \text{ C.}}$$

$$\rightarrow Q_{r3} = \rho_{s3} \cdot 36 \cdot 4\pi$$

$$= 144\pi \cdot \rho_{s3}$$

$$\rightarrow Q_{r2} = \int \rho_{s2} \cdot dS = \int_0^\pi \int_0^{2\pi} \rho_{s2} \cdot r^2 \sin \theta \, d\phi \, d\theta = \rho_{s2} \cdot r^2 \cdot 2 \cdot 2\pi$$

$$= -4 \cdot 16 \cdot 2 \cdot 2\pi = \underline{-256\pi \text{ C.}}$$

(1). $r=1$ 위치에서의 전속밀도 D .

$\oint D \cdot dS = Q$ 인데. $r=1$ 내부에는 전하가 존재하지 않는다. 따라서 $Q=0$ 이고 $D=0$ 이다.

$r=3$ 위치에서의 $D = D_r(r) \, \text{arr}$. (가우스 폐곡면 : r)

$$\oint D \cdot dS = D_r(r) \cdot \text{arr} \cdot 4\pi r^2 = 320\pi \text{ C.} \quad (r=3 \text{ 인 구 내부에 전하량} = 320\pi \text{ C})$$

$$D_r(r) = \frac{320\pi}{4\pi \cdot 9} = \frac{80}{9} \quad \therefore D = \underline{\frac{80}{9} \text{ arr}}$$

$r=5$ 위치에서의 $D = D_r(r) \, \text{arr}$

$$\oint D \cdot dS = D_r(r) \cdot \text{arr} \cdot 4\pi \cdot 25 \cdot \text{arr} = 320\pi - 256\pi = 64\pi$$

$$D_r(r) = \frac{64}{4\pi \cdot 25} = \frac{16}{25\pi} \quad \therefore D = \underline{\frac{16}{25\pi} \text{ arr}}$$

$$\begin{array}{r} 320 \\ -256 \\ \hline 64 \end{array}$$

(2). $r=7$ 에서의 $D=0$ 이라는 것.

~~가우스 폐곡면~~ $r=7$ 인 가우스 폐곡면인 구 내부의 전하량이 0인 것이다

$$\text{따라서 } 320\pi - 256\pi + 144\pi \rho_{s3} = 0.$$

$$64 + 144\rho_{s3} = 0. \quad \rho_{s3} = -\frac{64}{144} = -\frac{16}{36} = \underline{-\frac{4}{9}}$$

$$\begin{array}{r} 2 \\ 16 \\ \times 4 \\ \hline 64 \end{array}$$

$$\begin{array}{r} 36 \\ 59 \\ \cdot 16 \\ \hline 144 \end{array}$$