

Lasso/Ridge Regression + Eigenvalue Analysis + PCA

An Introduction to Statistical Learning

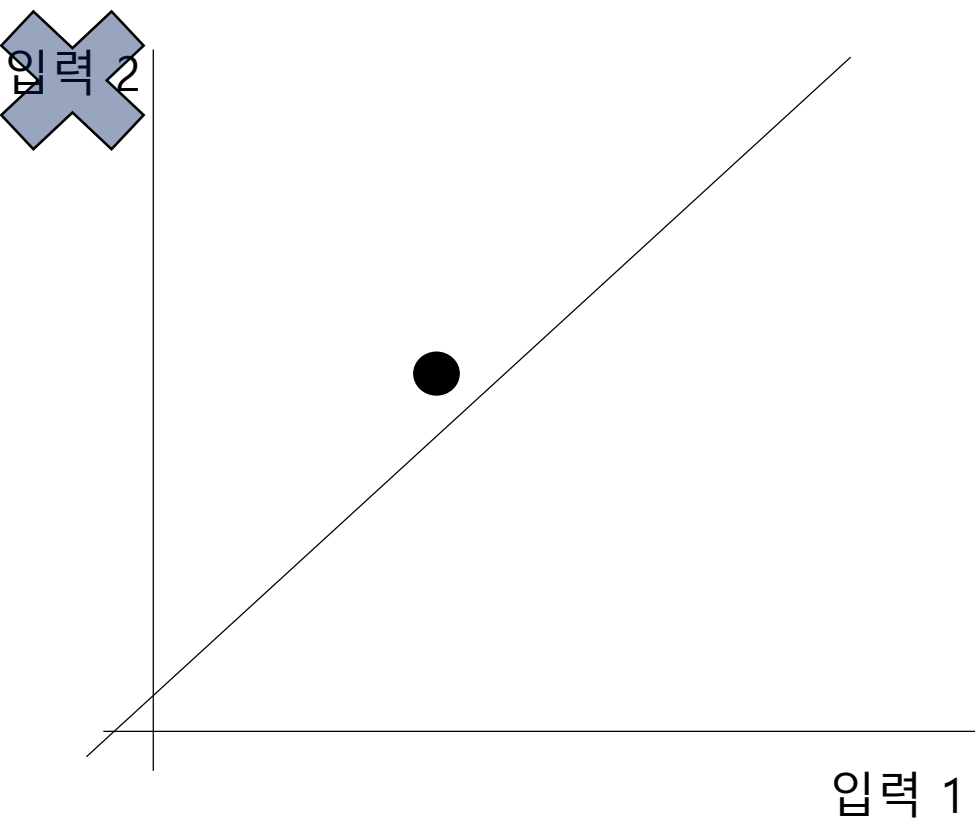
황성원

선형모델 확장 이유1: 예측 정확도 향상

선형 모델의 확장!

1. 예측 정확도 향상

2. 모델 해석 용이



$n < p$, 실제 입출력 관계: 선형

분산이 무한대가 된다

낮은 바이어스

유일한 최소자승 계수 못 구함

Test 관찰 값에서 예측 가능

선형모델 확장 이유2: 모델 해석 용이

선형 모델의 확장!

1. 예측 정확도 향상

2. 모델 해석 용이

표준 선형 모델

$$Y = \beta_0 + \beta_1 X_1 + \cdots + \beta_p X_p + \epsilon$$

입출력 사이의 관계가 단순해져 서로 간의 관계를 더욱 쉽게 파악!

→ 모델 해석 용이!

p(입력 종류 수) 줄이는 방법 (1/3)

1. 부분집합 선택(Subset Selection)

표준 선형 모델

$$Y = \beta_0 + \beta_1 \cancel{X_1} + \cdots + \beta_p X_p + \epsilon$$

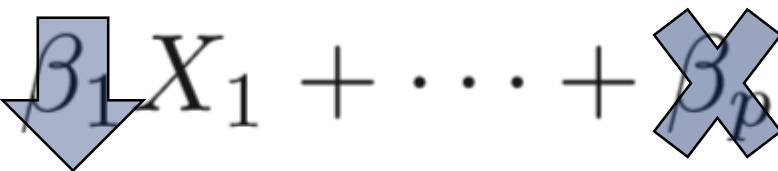
출력과 관계 없는 입력 변수 X 를 없애는 방법으로

최종적으로 줄어든 입력들로 최소자승 Fitting을 수행!

p(입력 종류 수) 줄이는 방법 (2/3)

2. Shrinkage or Regularization

표준 선형 모델

$$Y = \beta_0 + \beta_1 X_1 + \cdots + \beta_p X_p + \epsilon$$


1. 부분집합 선택
(Subset Selection)

계수를 줄이거나, 0으로 정확히(최소자승법으론 불가능) 수렴 시킨다

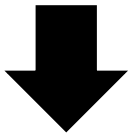
모든 p개의 입력들로 Fitting을 수행하지만, 최소자승이 아닌 다른 형태를 사용!

p(입력 종류 수) 줄이는 방법 (3/3)

3. 차원 축소 (Dimension Reduction)

표준 선형 모델

p차원 입력 공간



M차원 입력 공간

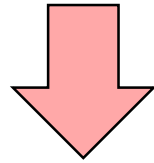
$$Y = \beta_0 + \beta_1 X_1 + \cdots + \beta_p X_p + \epsilon$$

$$Y = \beta_0 + \beta_1 V_1 + \cdots + \beta_M V_M + \epsilon$$

2. Shrinkage or Regularization

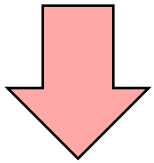
Ridge Regression (L2 Regularization)

1. 일반 선형 회귀 에러



$$\text{RSS} = \sum_{i=1}^n \left(y_i - \beta_0 - \sum_{j=1}^p \beta_j x_{ij} \right)^2$$

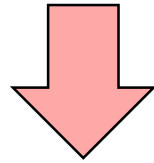
2. Ridge 회귀 에러



$$\text{RSS} + \lambda \sum_{j=1}^p \beta_j^2$$

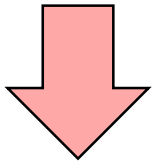
Lasso Regression (L1 Regularization)

1. 일반 선형 회귀 에러



$$\text{RSS} = \sum_{i=1}^n \left(y_i - \beta_0 - \sum_{j=1}^p \beta_j x_{ij} \right)^2$$

2. Lasso 회귀 에러



$$\text{RSS} + \lambda \sum_{j=1}^p |\beta_j|$$

Another Formulation for Lasso/Ridge

1. Lasso

RSS

$$\text{minimize}_{\beta} \left\{ \sum_{i=1}^n \left(y_i - \beta_0 - \sum_{j=1}^p \beta_j x_{ij} \right)^2 \right\} \quad \text{With} \quad \sum_{j=1}^p |\beta_j| \leq s$$

- 제한조건 -

2. Ridge

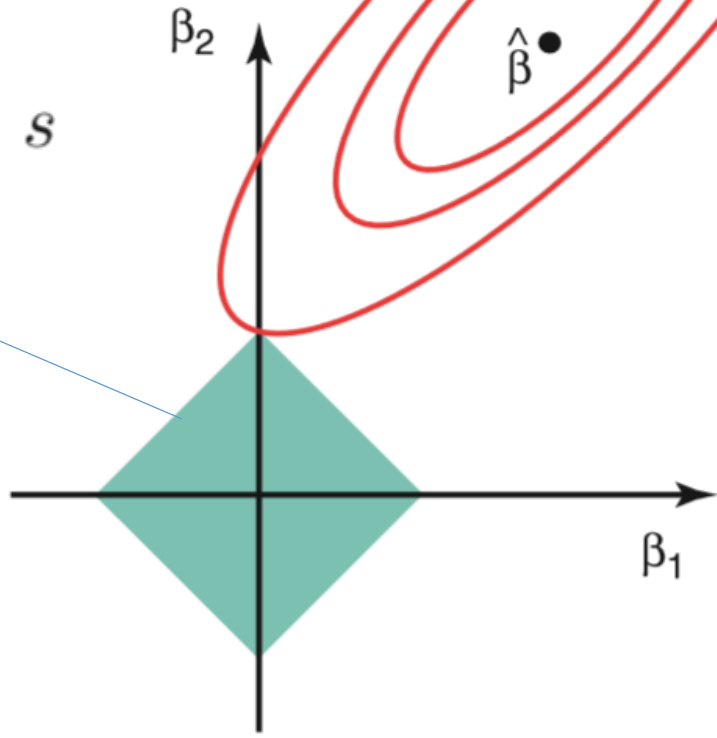
RSS

$$\text{minimize}_{\beta} \left\{ \sum_{i=1}^n \left(y_i - \beta_0 - \sum_{j=1}^p \beta_j x_{ij} \right)^2 \right\} \quad \text{With} \quad \sum_{j=1}^p \beta_j^2 \leq s$$

Intuition for Lasso/Ridge regression

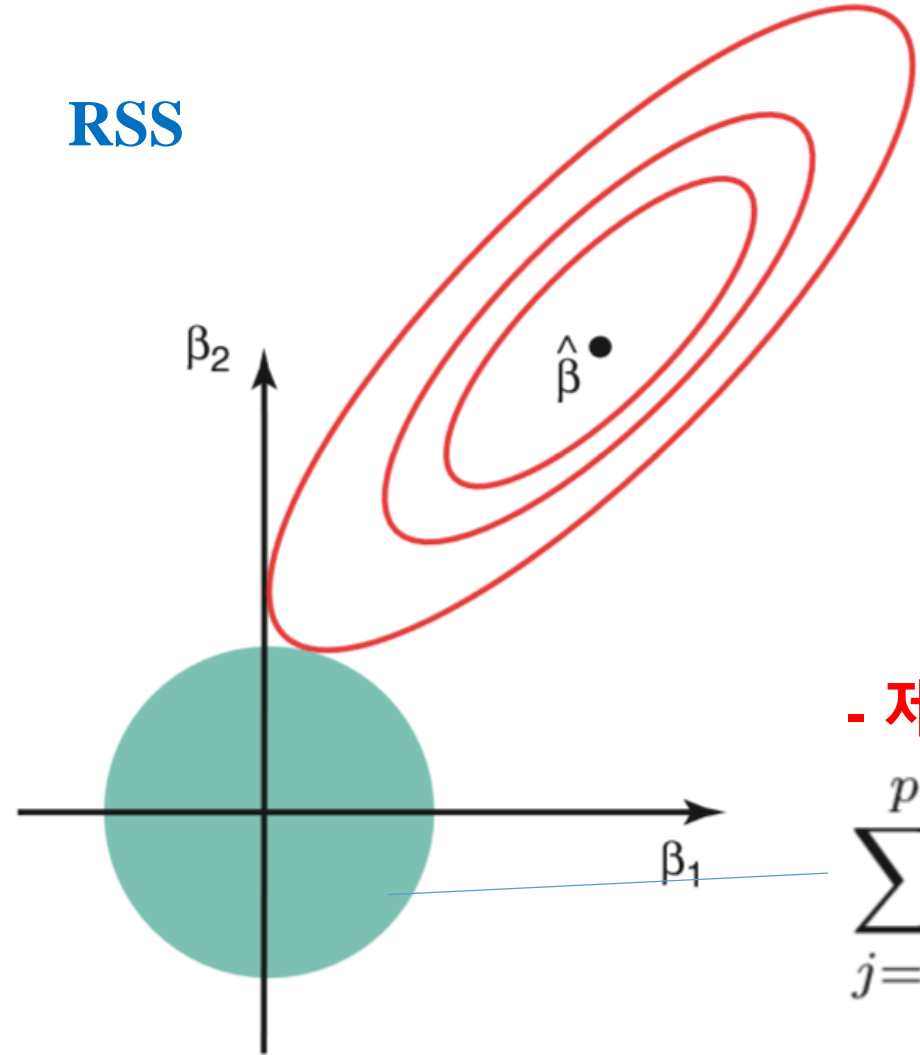
- 제한조건 -

$$\sum_{j=1}^p |\beta_j| \leq s$$



1. Lasso

RSS



- 제한조건 -

$$\sum_{j=1}^p \beta_j^2 \leq s$$

2. Ridge

Norm, Regularizer L1, L2, ...

Norm: 간단하게 벡터의 크기!

$$\left(\sum_i \|\theta_i\|^p \right)^{\frac{1}{p}}$$

$$p = 1$$

$$\sum_{j=1}^p |\beta_j| \leq s$$

1. Lasso

$$p = 2$$

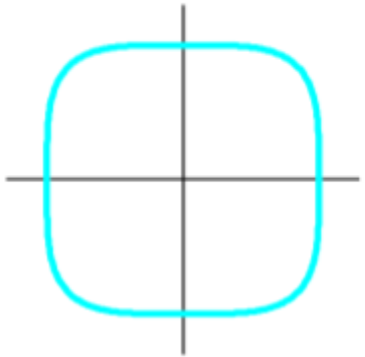
$$\sum_{j=1}^p \beta_j^2 \leq s$$

2. Ridge

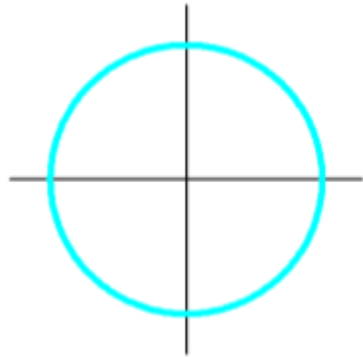
Extended Version

$$\sum_j |\beta_j|^q$$

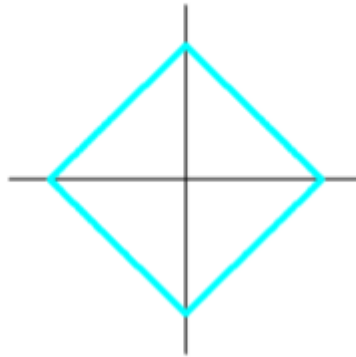
$q = 4$



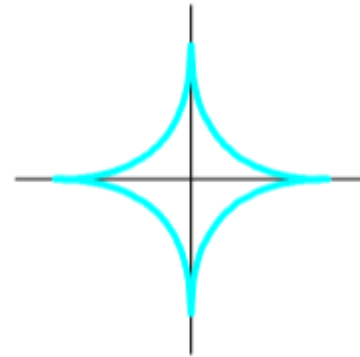
$q = 2$



$q = 1$



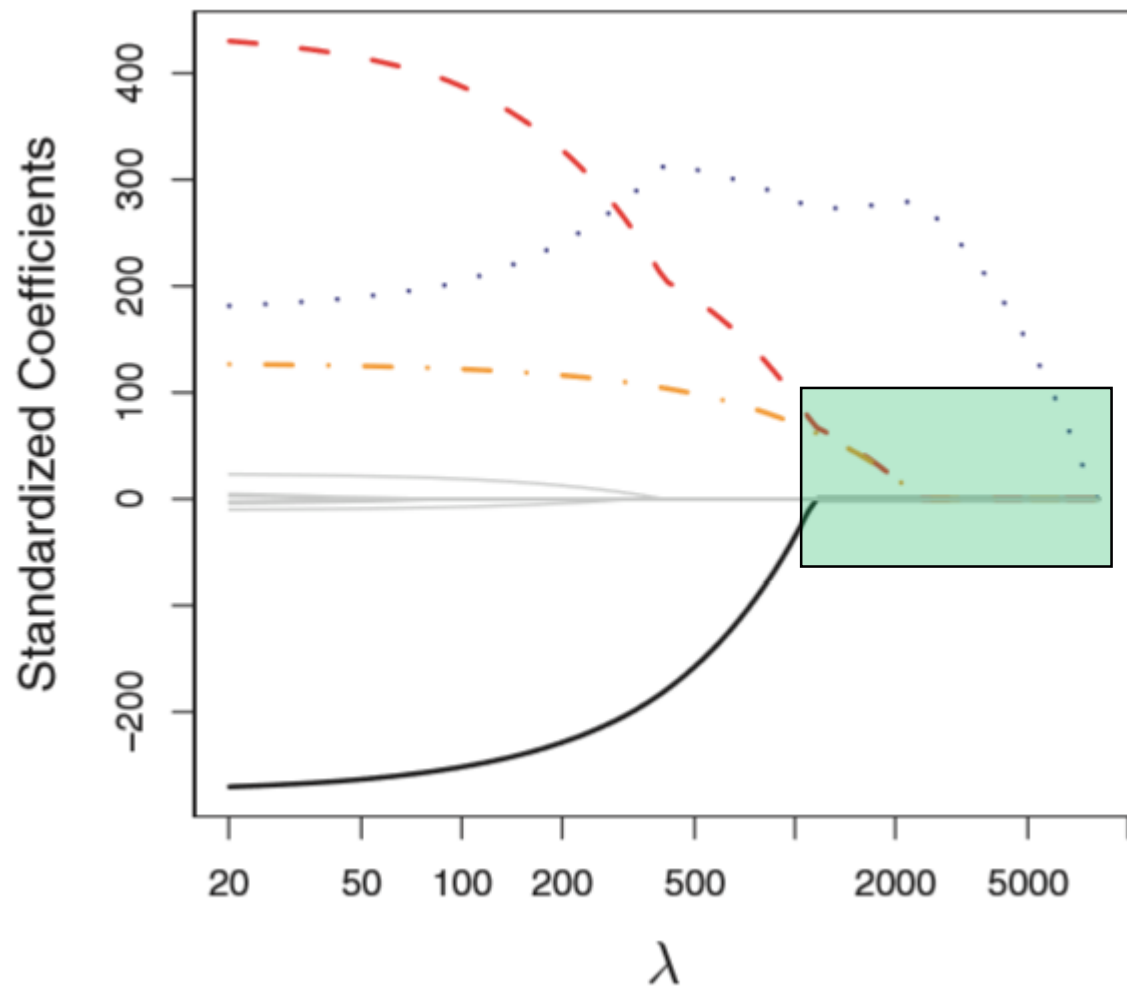
$q = 0.5$



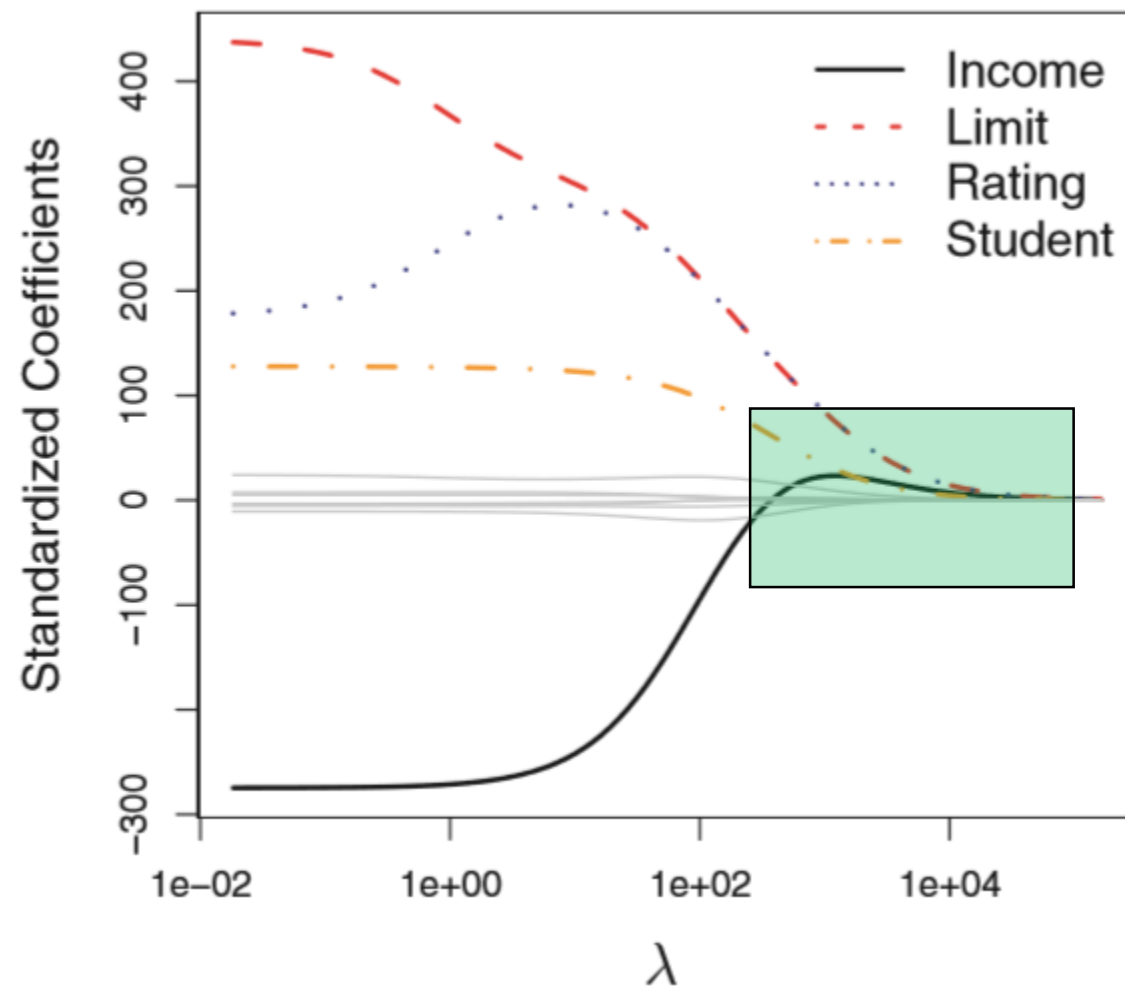
$q = 0.1$



Ridge VS. Lasso

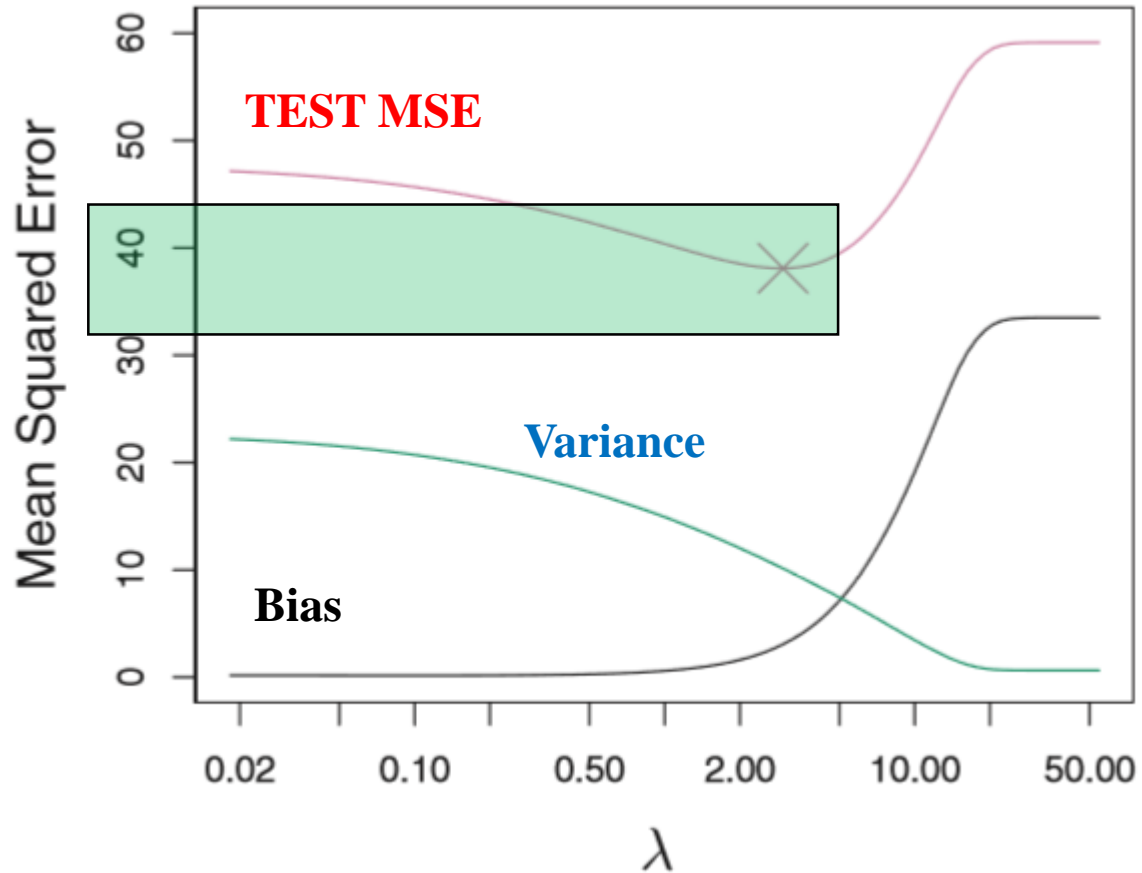


1. Lasso

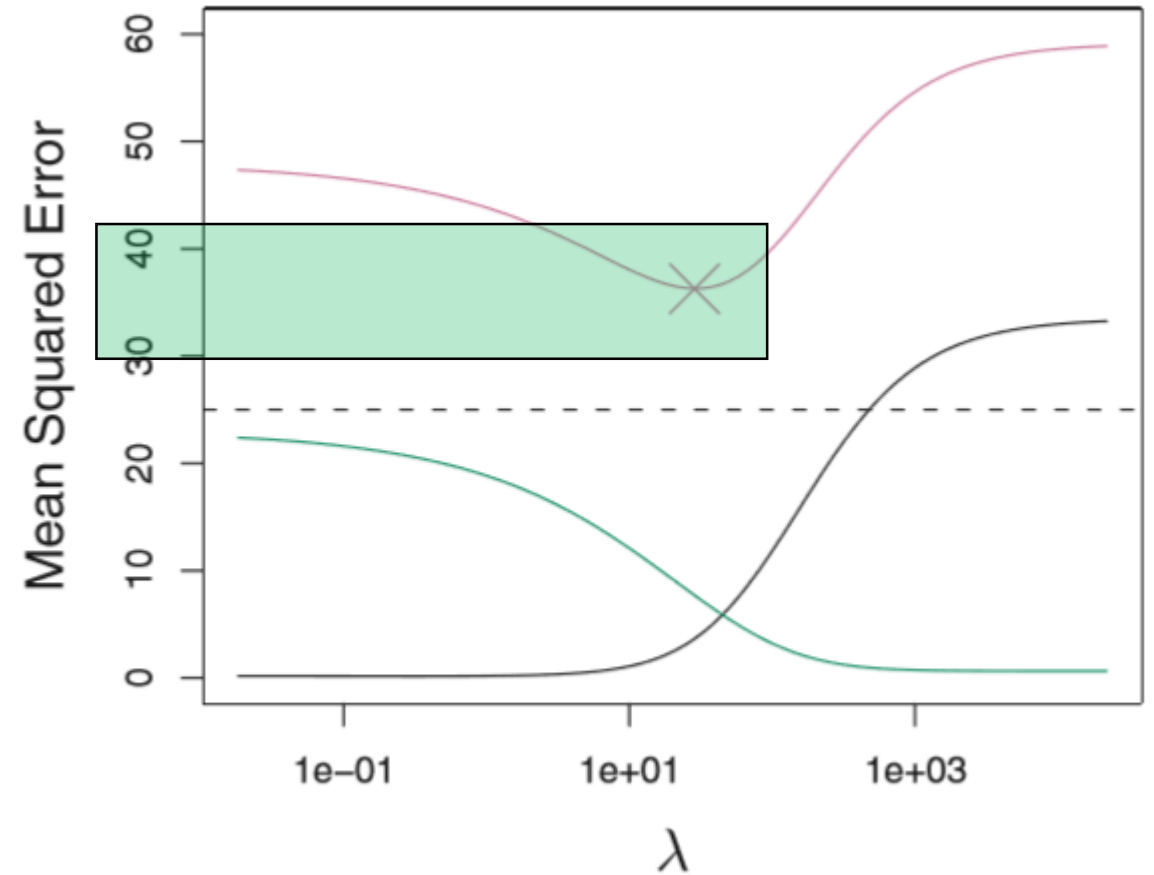


2. Ridge

Lasso VS. Ridge



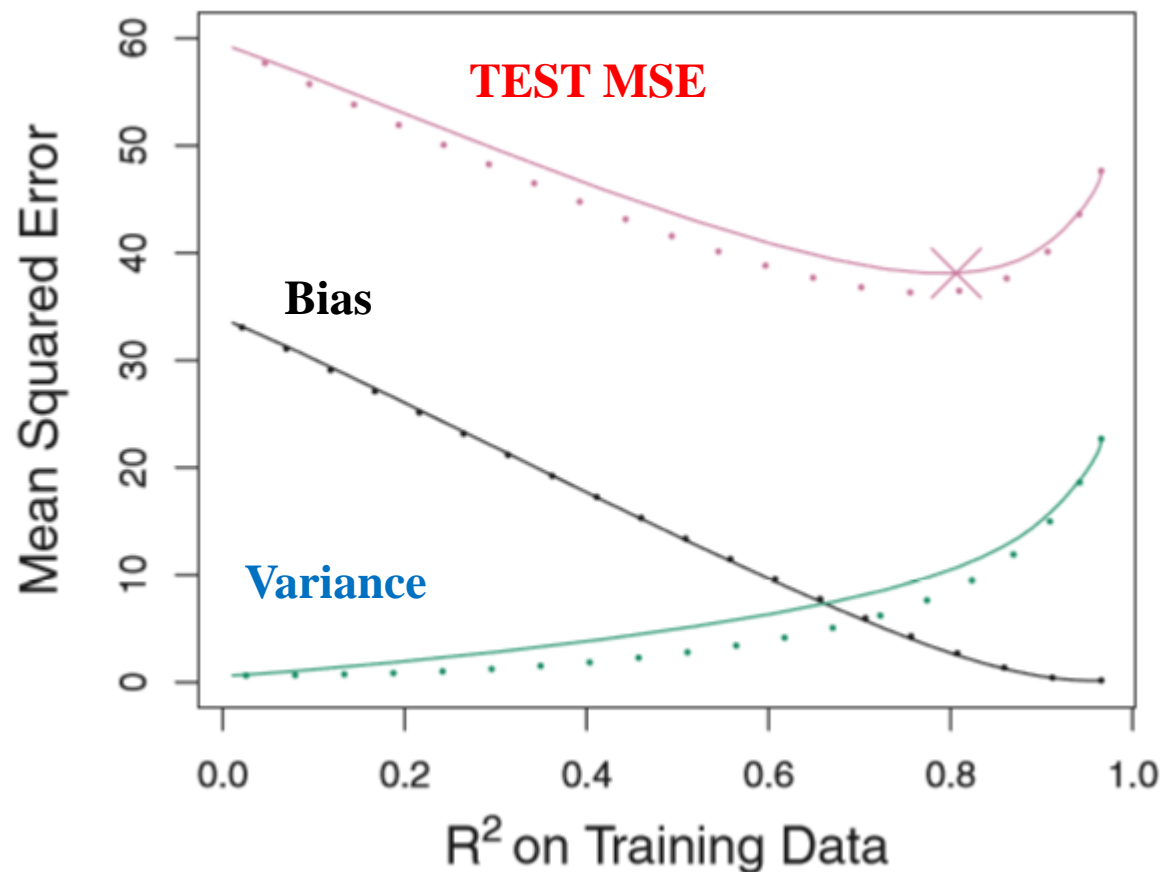
1. Lasso



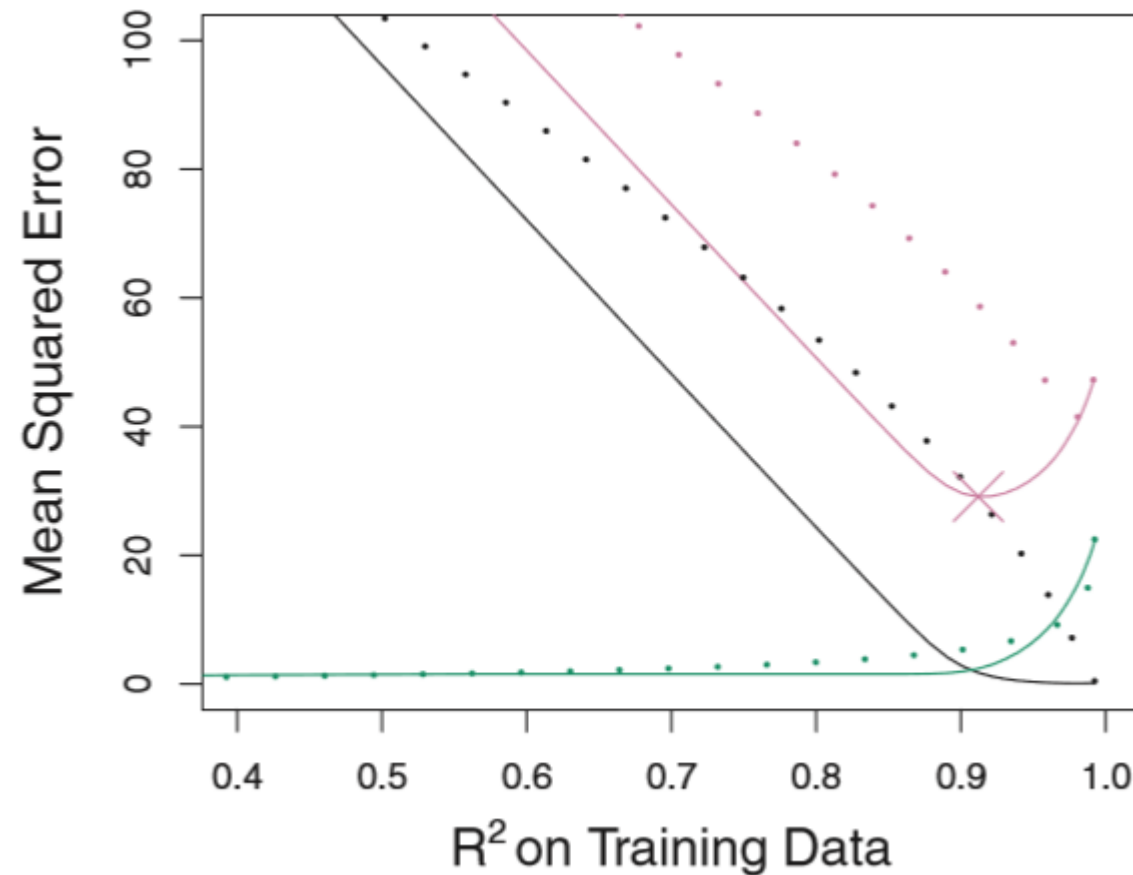
2. Ridge

Lasso VS. Ridge

실선 - Lasso
점선 - Ridge



45개 변수가 모두 연관된 경우



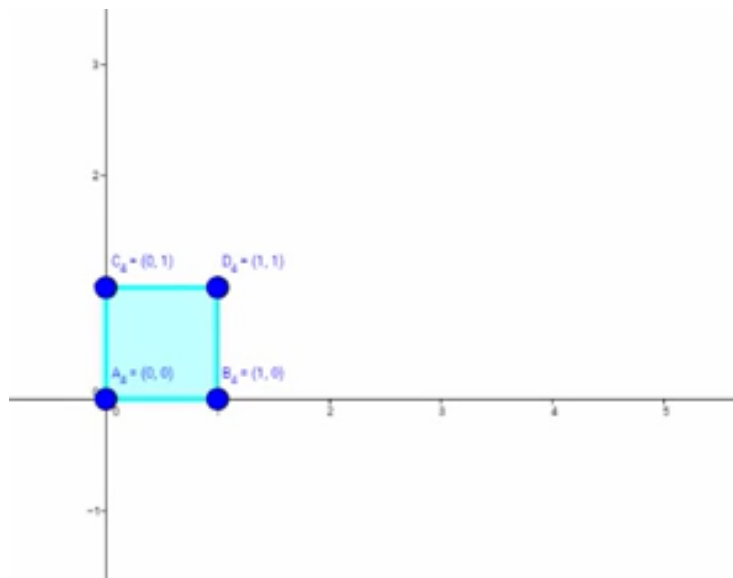
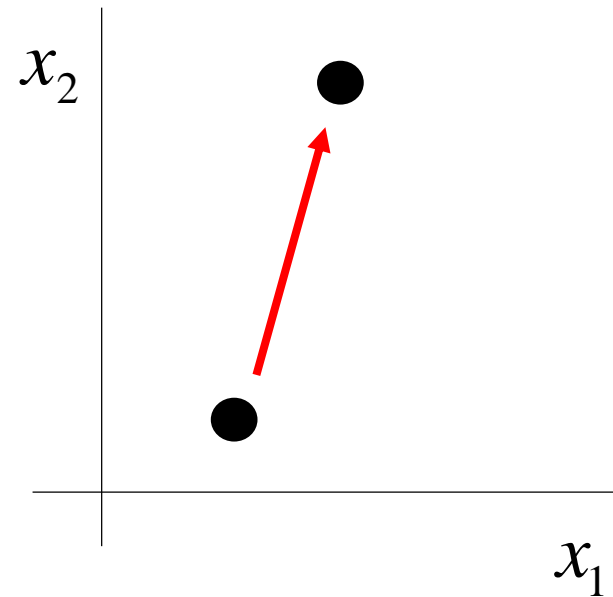
45개 변수 중 2개만 연관된 경우

3. Dimension Reduction

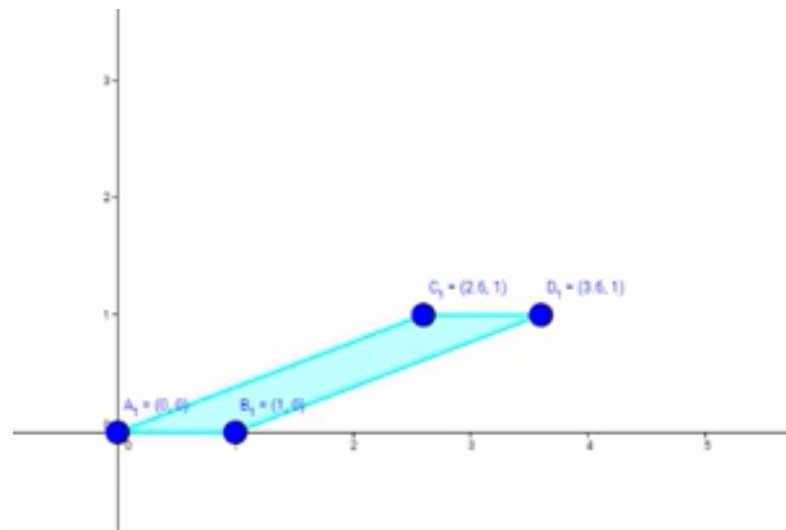
사전 지식 – 고유값, 고유벡터

선형 변환 (Linear Transformation)

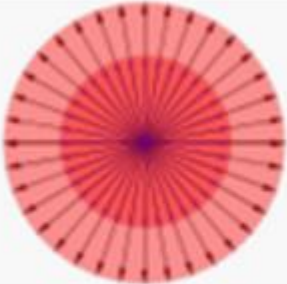
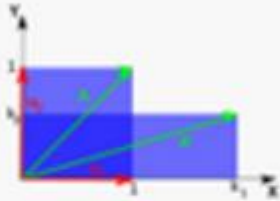

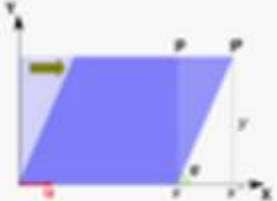
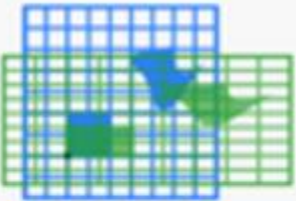
$$Ax = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x' = \begin{pmatrix} x_1' \\ x_2' \end{pmatrix}$$



선형 변환



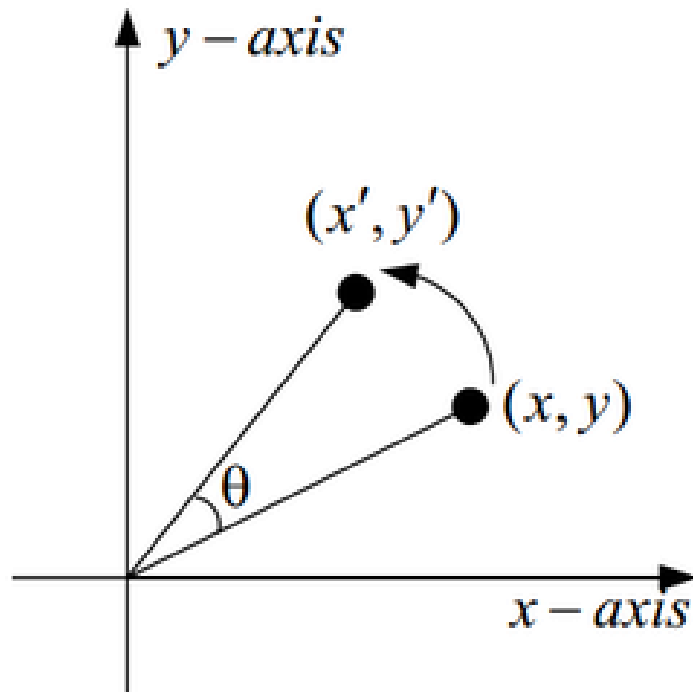
여러 가지 선형 변환

	scaling	unequal scaling	rotation	horizontal shear	hyperbolic rotation
illustration					
matrix	$\begin{bmatrix} k & 0 \\ 0 & k \end{bmatrix}$	$\begin{bmatrix} k_1 & 0 \\ 0 & k_2 \end{bmatrix}$	$\begin{bmatrix} c & -s \\ s & c \end{bmatrix}$ $c = \cos \theta$ $s = \sin \theta$	$\begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$	$\begin{bmatrix} c & s \\ s & c \end{bmatrix}$ $c = \cosh \varphi$ $s = \sinh \varphi$

$$Ax = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x'$$

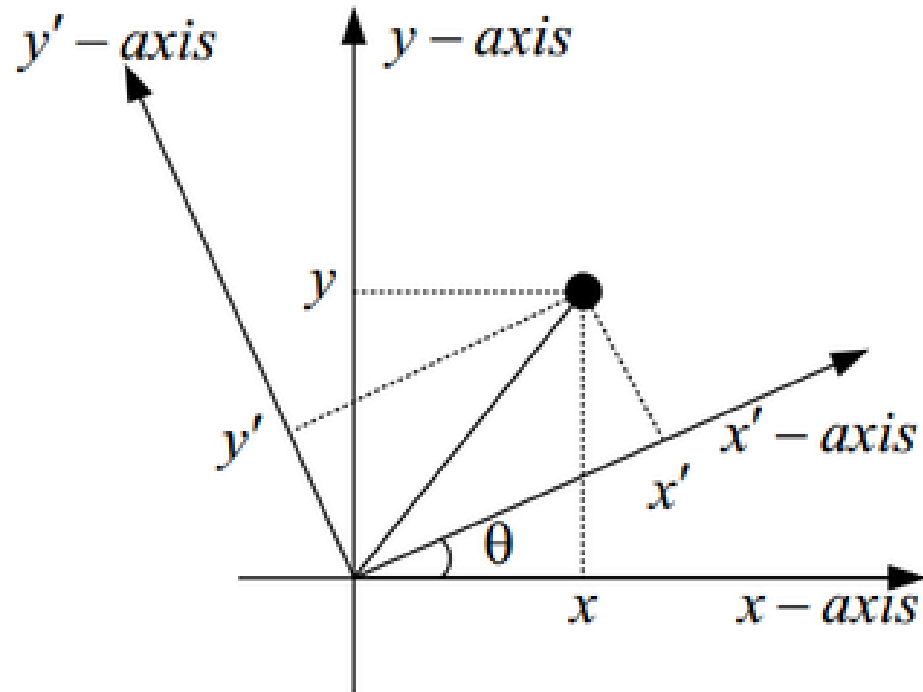
선형 변환 VS. 좌표 변환

■ 점의 회전이동



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

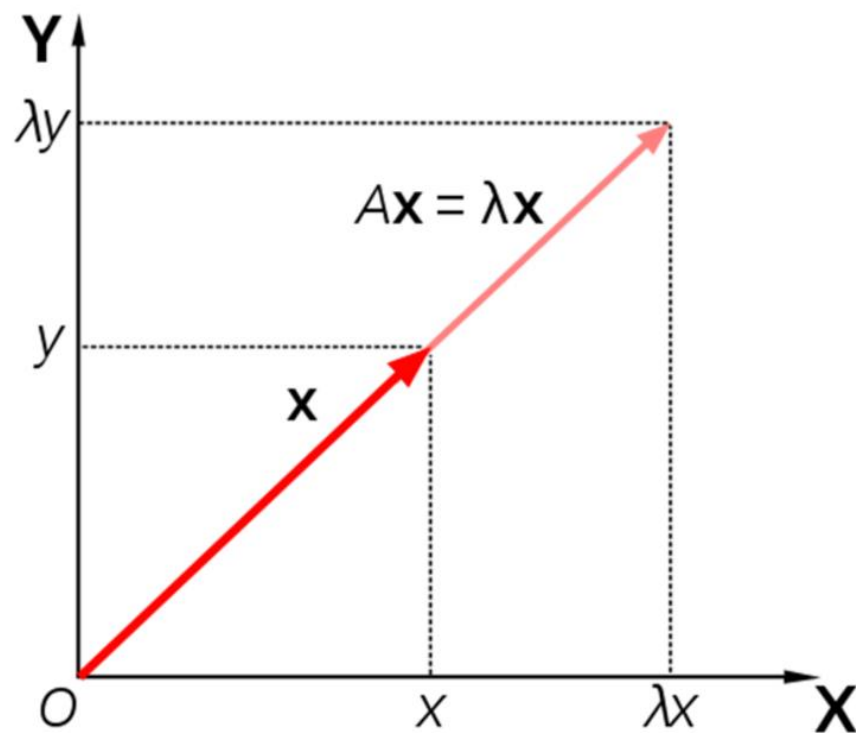
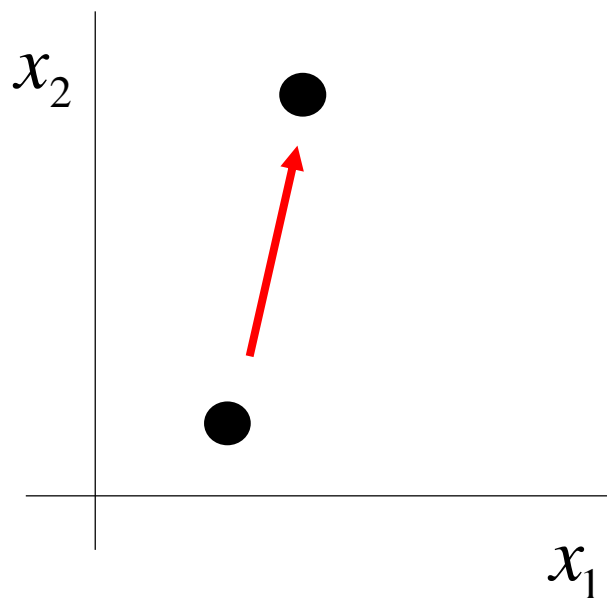
■ 좌표축의 회전이동



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

고유 값, 고유 벡터 (Eigenvalue, Eigenvector)

$$Ax = \lambda x$$



Reference for intuition of eigenvector!

2D 기존 원리 바탕으로 한 고유벡터 설명

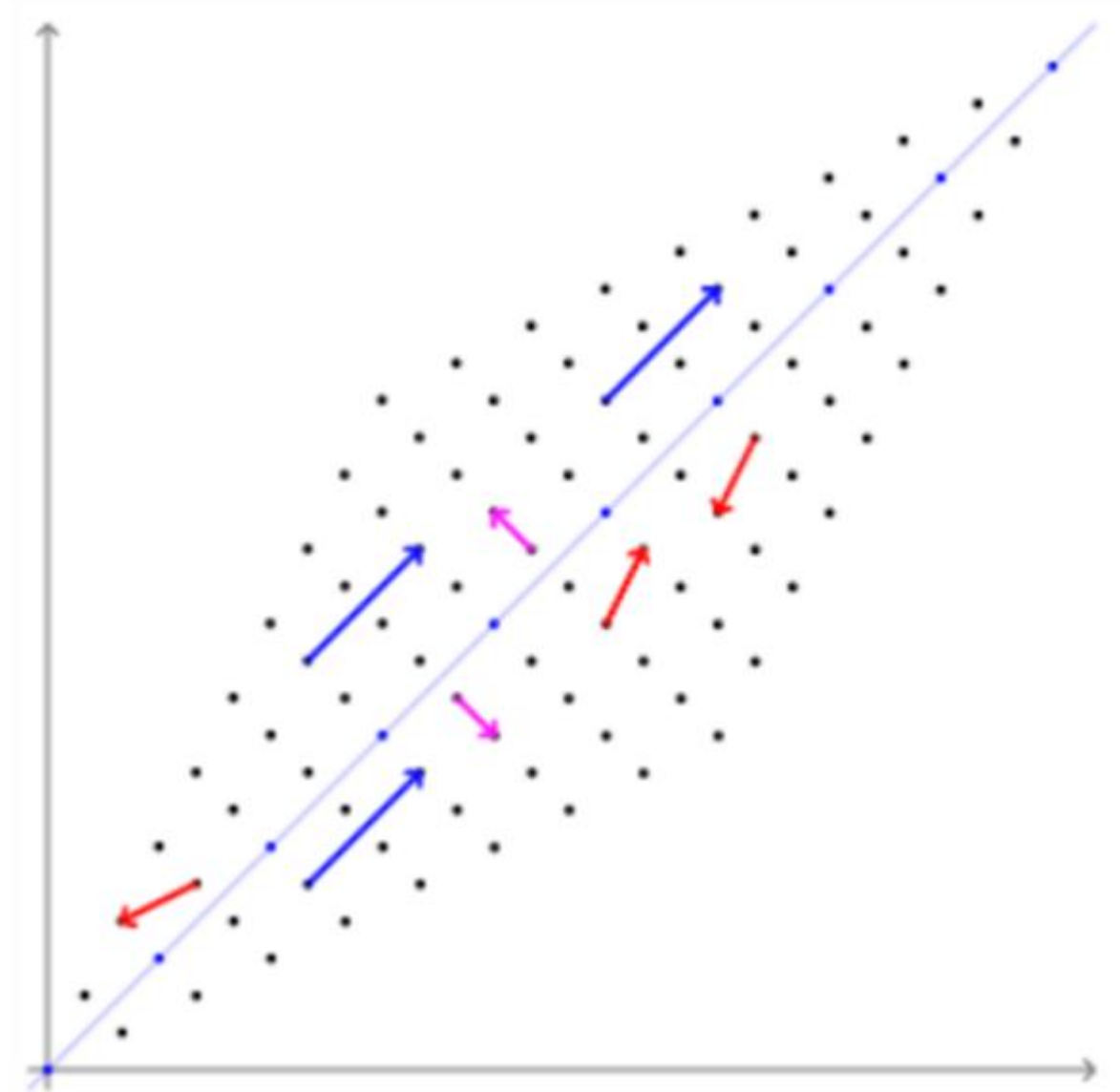
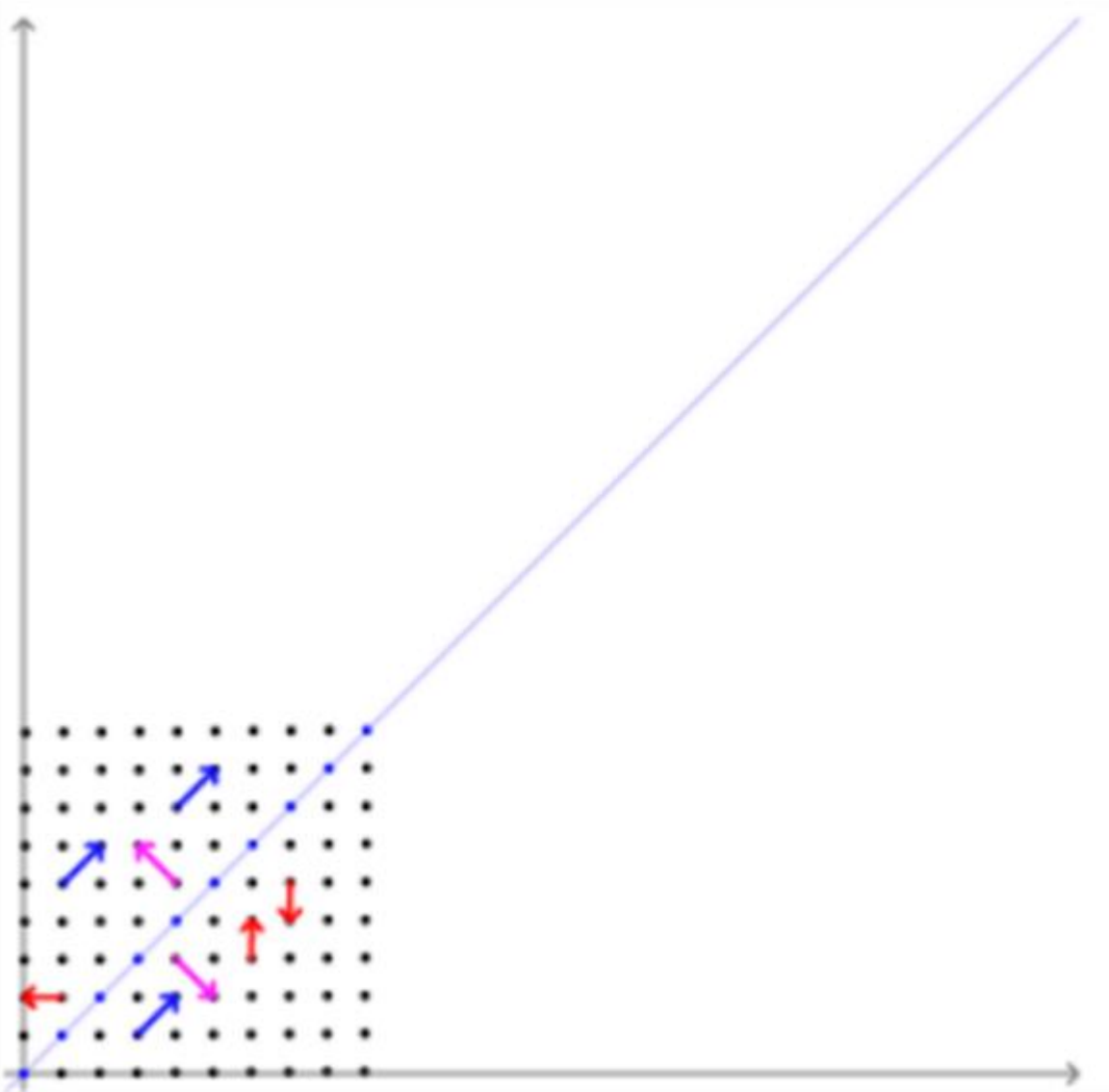
<https://www.youtube.com/watch?v=wXCRcnbCsJA>

<https://www.youtube.com/watch?v=8UX82qVJzYI>

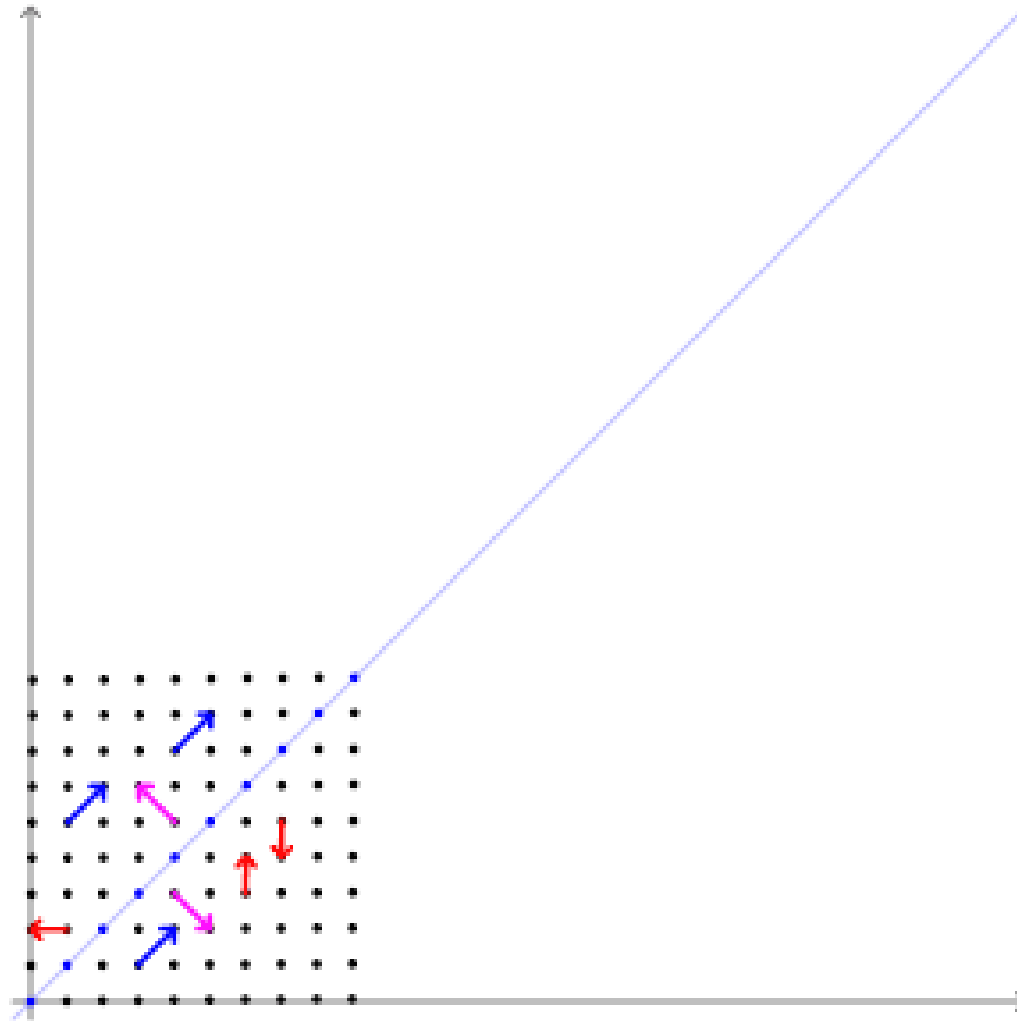
3D 예제

<https://www.youtube.com/watch?v=ue3yoeZvt8E>

Simple Example – Graphical Explanation



Simple Example – Animation

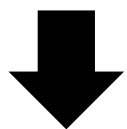


고유 값, 고유 벡터 (Eigenvalue, Eigenvector)

$$Ax = \lambda x$$



$$(A - \lambda I)x = 0$$



$$\det |A - \lambda I| = 0$$

[역 행렬]

$$(A - \lambda I)^{-1} = \frac{1}{\det |A - \lambda I|} \times \dots$$

*역 행렬 존재할 경우: Trivial Solution (x=0인 자명해)

따라서, Non-trivial Solution을 찾기 위해 역 행렬 존재 x

Simple Example

$$\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} x = \lambda x$$

eigenvalue = $\lambda = 1$,
eigenvector = $(1, -1)$

$$\begin{pmatrix} 2 - \lambda & 1 \\ 1 & 2 - \lambda \end{pmatrix} x = 0$$

eigenvalue = $\lambda = 3$,
eigenvector = $(1, 1)$

$$(2 - \lambda)^2 - 1 = 0$$

$$\lambda = 1, 3$$

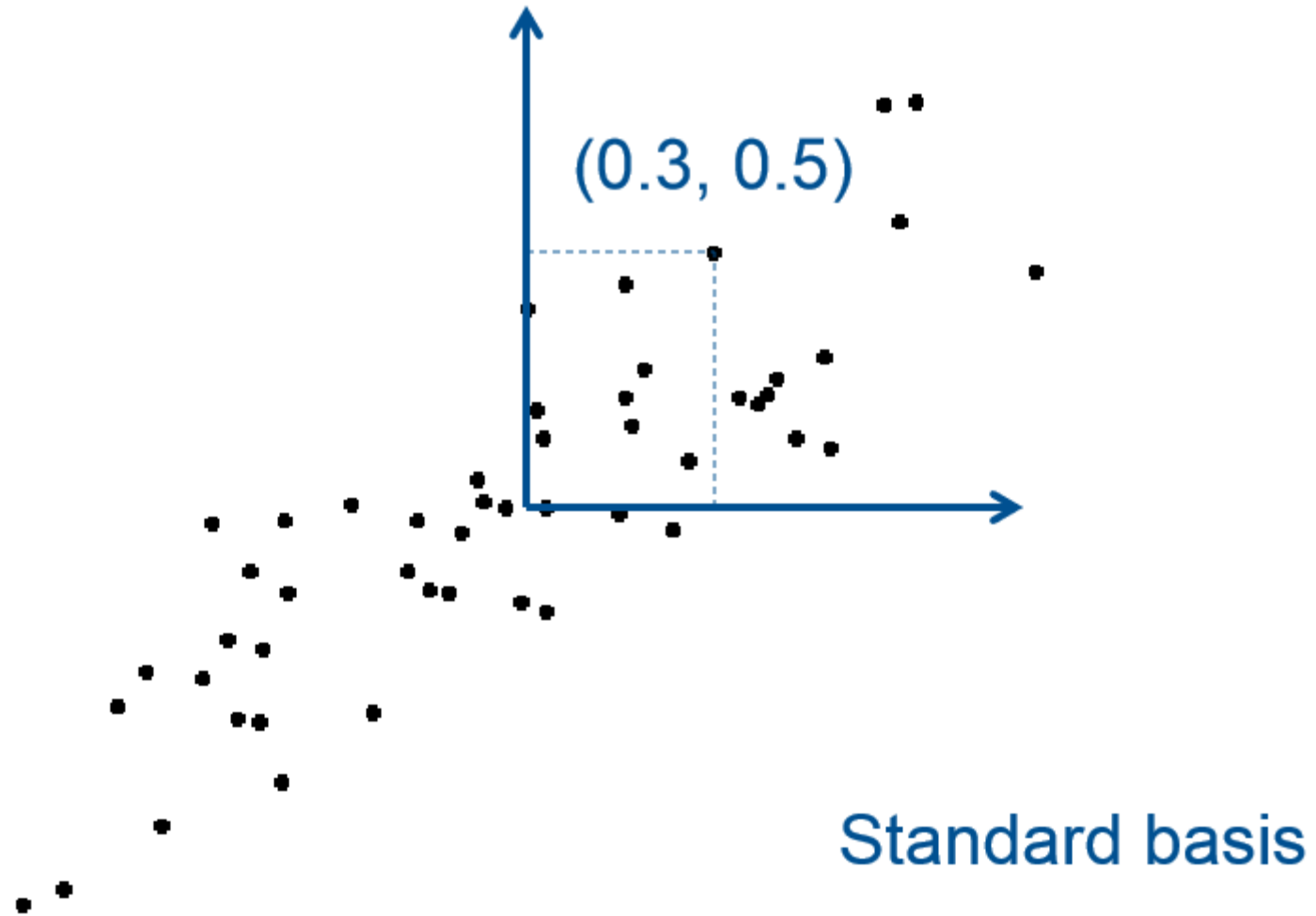
Principle Component Analysis (PCA)

주성분 분석

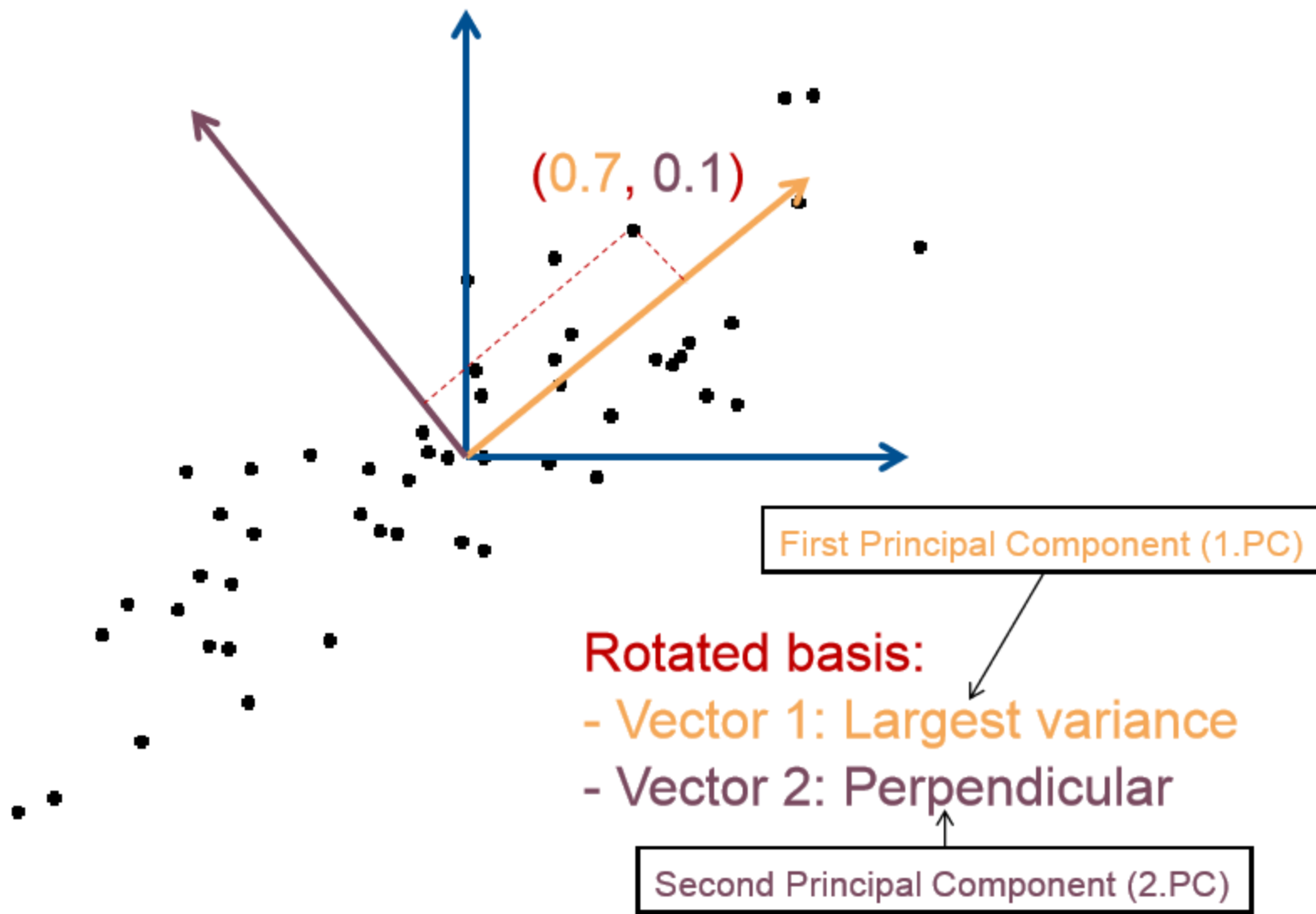
결론



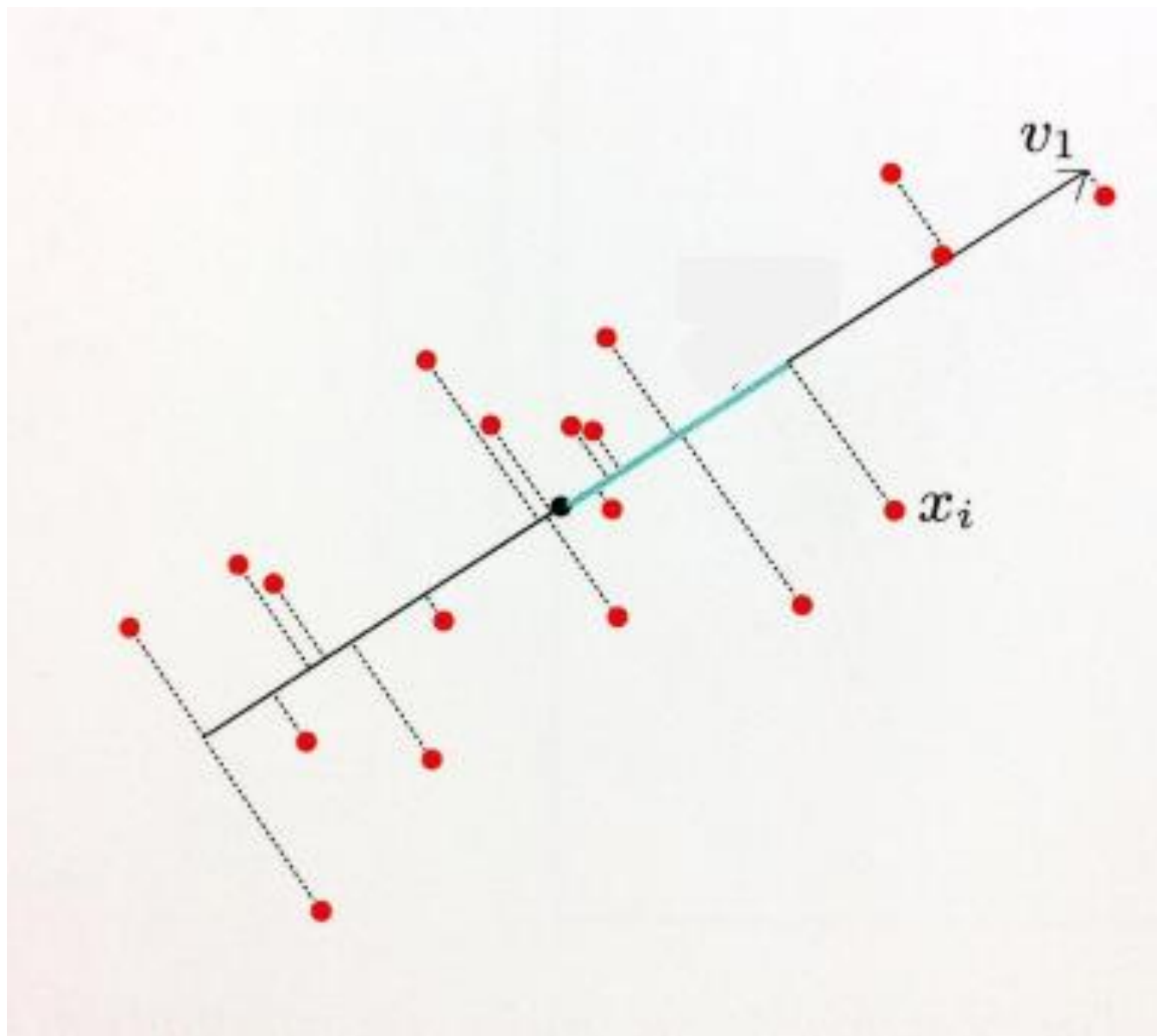
결론



결론



결론

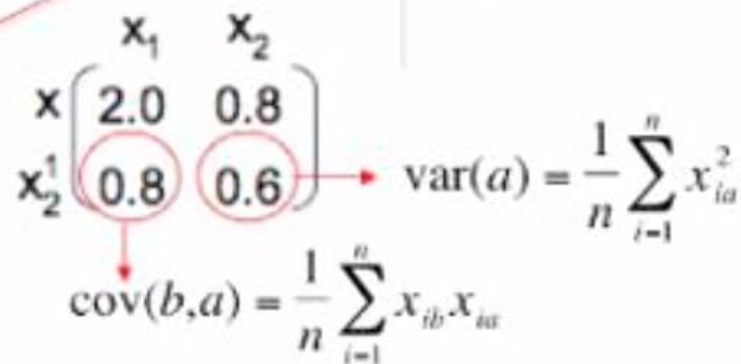


고유벡터에서 행렬 A는 PCA에서는?

$$Ax = \lambda x$$

$$\Sigma x = \begin{pmatrix} \sigma_x & \sigma_{xy} \\ \sigma_{yx} & \sigma_y \end{pmatrix} x = \lambda x$$

Principal components



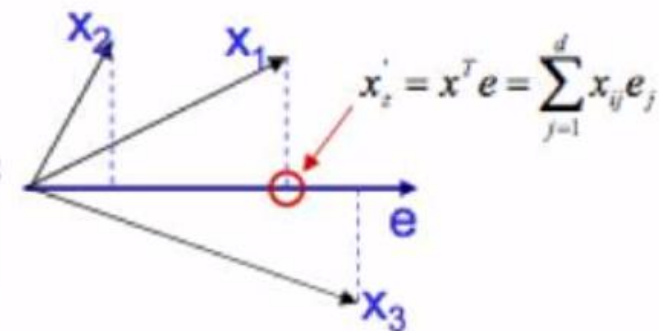
- slope: 0.400 0.450 0.454 0.454

PCA

- Select dimension \mathbf{e} which maximizes the variance

- Points \mathbf{x}_i “projected” onto vector \mathbf{e} :

- Variance of projections: $\frac{1}{n} \sum_{i=1}^n \left(\sum_{j=1}^d x_{ij} e_j - \mu \right)^2 = \frac{1}{n} \sum_{i=1}^n \left(\sum_{j=1}^d x_{ij} e_j \right)^2$



- Maximize variance

– want unit length: $||\mathbf{e}||=1$

– add Lagrange multiplier

$$V = \frac{1}{n} \sum_{i=1}^n \left(\sum_{j=1}^d x_{ij} e_j \right)^2 - \lambda \left(\left(\sum_{k=1}^d e_k^2 \right) - 1 \right)$$

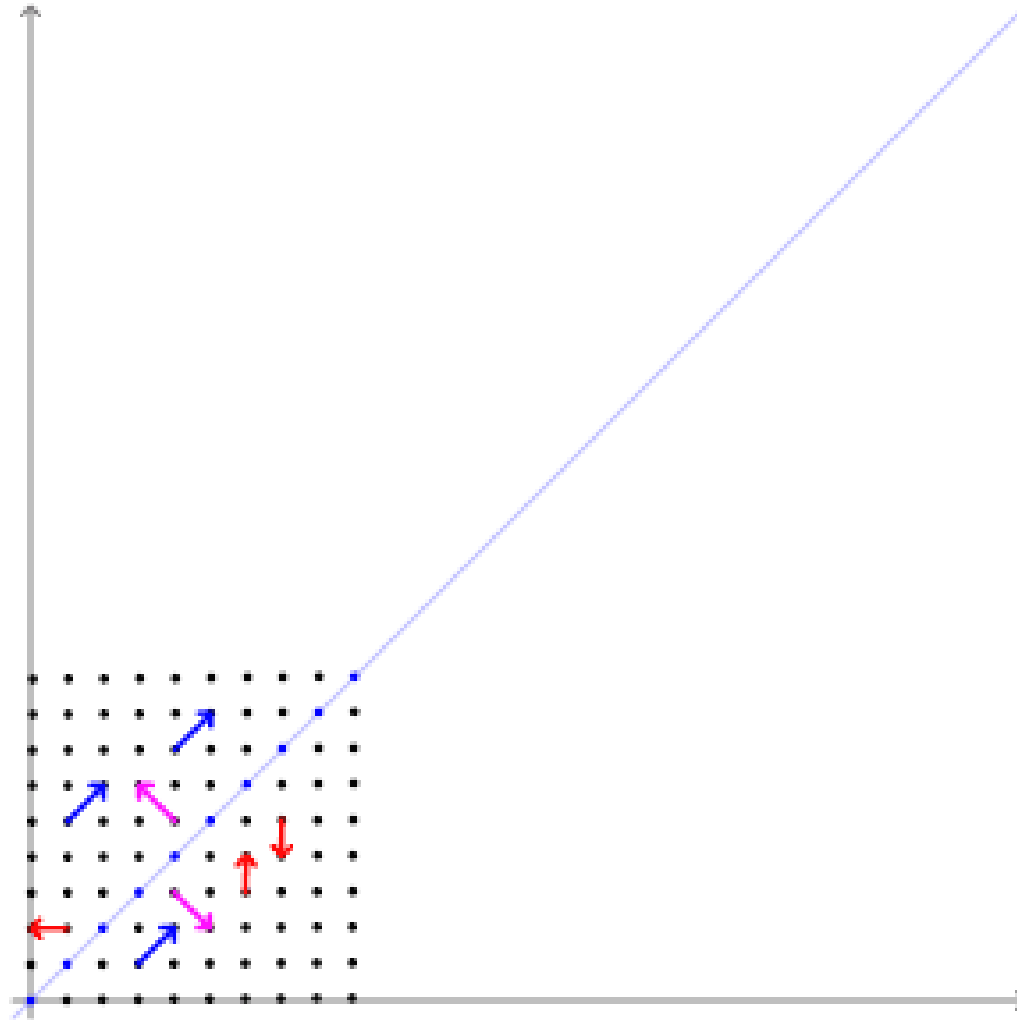
$$\frac{\partial V}{\partial e_a} = \frac{2}{n} \sum_{i=1}^n \left(\sum_{j=1}^d x_{ij} e_j \right) x_{ia} - 2\lambda e_a = 0$$

$$\left\{ \begin{array}{l} \sum_{j=1}^d \text{cov}(1,j) e_j = \lambda e_1 \\ \vdots \\ \sum_{j=1}^d \text{cov}(d,j) e_j = \lambda e_d \end{array} \right\}$$

hold for $a=1..d$

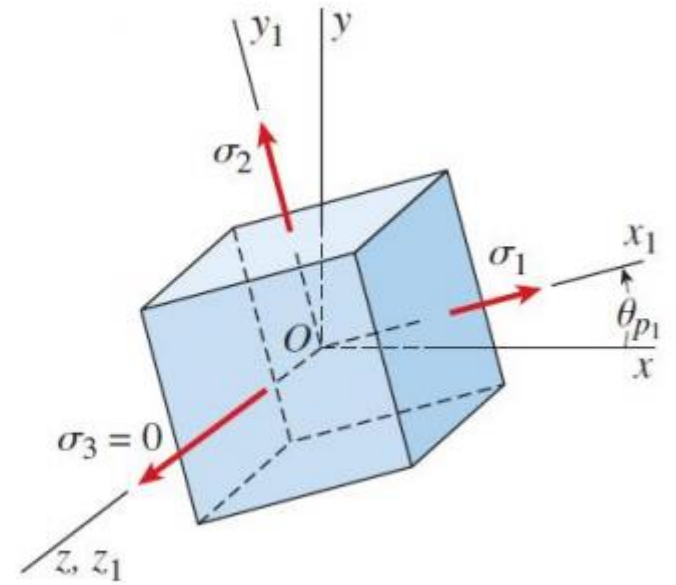
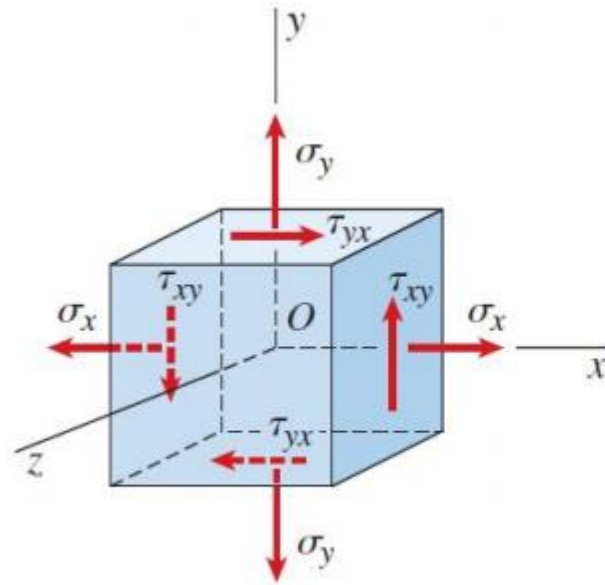
$$2 \sum_{j=1}^d e_j \underbrace{\left(\frac{1}{n} \sum_{i=1}^n x_{ia} x_{ij} \right)}_{\text{covariance of } a,j} = 2\lambda e_a$$

마지막으로 생각할 부분 – 힘과 분산!



마지막으로 생각할 부분 – 주응력

$$A = \begin{pmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \sigma_y & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_z \end{pmatrix}$$



Thank you!