

Diego Armando Salinas Lugo

CE889

Neural Networks and Deep Learning

Postgraduate: 2401168

username: ds24353

After collecting data of the game, I have a file to normalize the data.

```
import pandas as pd

from sklearn.preprocessing import MinMaxScaler

# To read my csv with my last weights achieved after training

file_path = r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\OneDrive_;

# Loading it

data = pd.read_csv(file_path, header=None)

# Assigning the column order

data.columns = ['x1', 'x2', 'y1', 'y2']

# Applying Min-Max normalization

scaler = MinMaxScaler()

normalized_data = pd.DataFrame(scaler.fit_transform(data), columns=data.columns)

# Saving the new normalized file to work with

output_file_path = r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\One
normalized_data.to_csv(output_file_path, index=False)

print(f"Normalized data has been saved to {output_file_path}")
```

Then, I have my most important file which I called try5.py. In this file, I have a class called Neural Network in which I split the data in 0.7 for trainning and 0.3 for testing.

In try5

This file contains the methods for forward propagation and backward propagation.

Adapted with some functions to ellaborate the whole process.

```
if __name__ == "__main__":
    neurons = 5
    weights = [random.uniform(-1, 1) * (1 / neurons ** 0.5) for _ in range(neurons * 2 + neurons * 2)]
    b = 1  # Initial bias to be updated
    # At the beginning I was trying to work with the parameters i got from matlab but my model wasnt working.
    # They were 5 neurons, lambda 0.05 and trainparam of 0.9, but after trying plenty of times, these values showed more movement in the rocket
    nn = NeuralNetwork(N=0.08, weights=weights, M=1.05, b=b, neurons=neurons)

# Path to my CSV file with the normalize data
    csv_file_path = r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\OneDrive_2024-11-25\Assignment Code\normalized_ce889_dataCollection.csv"

# Trainning and evaluating
    nn.train_and_evaluate(csv_file_path, epochs=150)
```

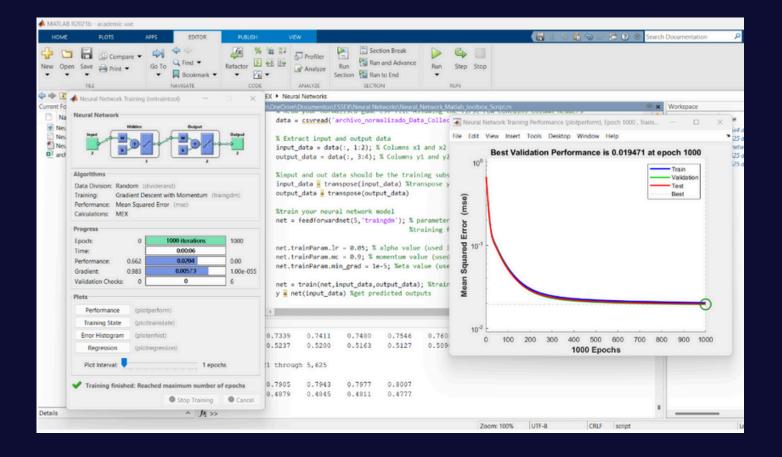
This part shows the last lines of my code.

Here I dictate the parameters to use, the direction of my csv and I run the train_and_evaluate function that consists in running all the functions in the class.

At initializing the nodes I implemented the Xavier Initialization principle since I discovered that it ensures balanced gradients for efficient learning and preventing issues like vanishing or exploding gradients.

I started working with 150 epochs since with 100 epochs and other parameters I tought the loss would be better, however, at last moment I got better parameters and noticed that the number of epochs can be less, nevertheless, i didn't change this number.

After collecting data of the game, I have a file to normalize the data.



At the beginning I was trying to work with the parameters i got from matlab but my model wasn't working, the rocket was just falling showing not movement at all.

They were 5 neurons, lambda 0.05 and trainparam of 0.9, but after trying plenty of times, these other values showed more and better movement in the rocket:

neurons = 5, λ = 0.08 and trainparam of 1.05.

The function with which I run the whole performance.

```
# To get into the training and then the testing
def train_and_evaluate(self, file_path, epochs):
    x1_train, x2_train, y_train, x1_test, x2_test, y_test = self.train_test_split(file_path)

for epoch in range(epochs):
    self.train_batch(x1_train, x2_train, y_train)
    train_loss = self.compute_loss(x1_train, x2_train, y_train)
    print(f"Epoch {epoch + 1}: Train Loss = {train_loss:.6f}")
    print(f"Epoch {epoch + 1}: Updated Weights = {self.weights}")
    print(f"Epoch {epoch + 1}: b = {self.b}")

test_loss = self.compute_loss(x1_test, x2_test, y_test)
    print(f"Final Test Loss: {test_loss:.6f}")
```

The functions called in the train_evaluate, that are in charge to split the data and train the batch

```
# Trainning the network
def train_batch(self, x1_list, x2_list, y_list):
    for x1, x2, y in zip(x1 list, x2 list, y list): #Looping through the input and output, using zip
       h, yp = self.forward_propagate(x1, x2) # To perform forward with the inputs
        self.backward_propagate(x1, x2, y, h, yp) # To adjust the weights with new data
# Splitting the data into to its manage
def train_test_split(self, file_path, train_ratio=0.7):
    x1_list, x2_list, y_list = [], [], [] # Initializing the lists to store the data
    with open(file path, newline='') as csvfile:
        reader = csv.reader(csvfile)
        next(reader) # To skip the header
        for row in reader:
            x1, x2, y1, y2 = map(float, row) # Converting the values to float
           x1 list.append(x1)
           x2 list.append(x2)
           y_list.append([y1, y2]) #Adding the ouput pair to a list. As there are two outputs, I sto
    data = list(zip(x1 list, x2 list, y list)) # zip combines the three lists (x1 list, x2 list, y list)
    random.shuffle(data)
    train size = int(len(data) * train ratio)
    train data = data[:train size] # data to train
    test_data = data[train_size:] # data to test
    x1 train, x2 train, y train = zip(*train data) # Separating the inp and outp and converting to 1
    x1 test, x2 test, y test = zip(*test data)
    return list(x1 train), list(x2 train), list(y train), list(x1 test), list(x2 test), list(y test)
```

The forward propagation, backward propagation and loss

```
def forward propagate(self, x1, x2):
   v = [] # Pre activation values
   h = [] # Hidden layer outputs
   yp = [] # Output layer outputs
   # Activations for the hidden layer
   for i in range(self.neurons):
       v hidden = x1 * self.weights[i] + x2 * self.weights[i + self.neurons] + self.b # Multiplying the first an second in
       v.append(v_hidden) # Storing pre-activation
   for v hidden in v:
       h.append(self.sigmoid(v hidden)) # Applying sigmoid activation adn appending
   # Activations for the output layer
   for i in range(2): # Output layer has 2 neurons
       v output = sum(h[j] * self.weights[self.neurons * 2 + i * self.neurons + j] for j in range(self.neurons)) + self.b
       v.append(v output) # Storing pre activation
       yp output = self.sigmoid(v_output) # Applying sigmoid activation
       yp.append(yp_output) # Adding to its corresponding list
   return h, yp # Returning the hidden layer and output layer activations
```

Following the formulas of:

- Pre-activation and Activation Values
- Sigmoid Activation Function
- Error Calculation
- Backpropagation and Gradients:
 - Output Layer Gradients (Delta): δoutput = learning rate · error · sigmoid'(y^)
 - ∘ Hidden Layer Gradients (Delta) : δ hidden = learning rate * h · (1−h) * $j\Sigma(\delta)$ outputj · wij)
- Weight Update Rule
- Mean Squared Error Loss

```
class NeuralNetwork:
   # To update weights and bias
    def backward propagate(self, x1, x2, y, h, yp):
       zeta output = [] # To store the output layer errors
       zeta hidden = [] # Hidden layer errors
       # Calculating errors for the output layer
       for i in range(2):
           error = y[i] - yp[i]
           delta_output = self.M * error * yp[i] * (1 - yp[i]) # Derivative of sigmoid, i could have adde
           zeta_output.append(delta_output) # Appending the errors
       # For the hidden layer is a more complex procedure
       for i in range(self.neurons):
           sum delta weights = sum( #Calculates the sum
                zeta output[j] * self.weights[self.neurons * 2 + j * self.neurons + i] for j in range(2) #
            delta hidden = self.M * h[i] * (1 - h[i]) * sum delta weights # The formula for getting the de
            zeta hidden.append(delta hidden) #Appending to the list
       # Updating the weights for the output layer
       for i in range(2):
           for j in range(self.neurons):
                self.weights[self.neurons * 2 + i * self.neurons + j] += self.M * zeta output[i] * h[j]
       # Updating weights for the hidden layer
       for i in range(self.neurons):
           self.weights[i] += self.M * zeta hidden[i] * x1
           self.weights[i + self.neurons] += self.M * zeta hidden[i] * x2
       for i in range(2):
           self.b += self.M * zeta_output[i]
       for i in range(self.neurons):
           self.b += self.M * zeta hidden[i]
```

The outputs showed in the terminal are the weights updated, the loss, the bias by epoch and the final loss.

I save the last weights printed and store them in a csv file, to then in the NeuralNetholder.py call the class and make the forward propagation run with these new weights.

```
from try5 import NeuralNetwork # Import the NeuralNetwork class
class NeuralNetHolder:
    def __init__(self):
        super().__init__()
        # The path file
        self.weights_path = r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\trained_weights_try_5.csv"
        self.network = NeuralNetwork(\lambda=0.08, weights=[], M=1.05, b = 1, neurons=5)
        trained weights = self.load weights(self.weights path) #To load the weights
        self.network.weights = trained weights # Assigning the loaded weights to the neural network
        # Normalization scale
        self.input scale = 100
    def load weights(self, weights path):
        weights = [] # to store the weights
        with open(weights_path, "r", encoding="utf-8-sig") as file:
            reader = csv.reader(file)
            for row in reader:
```

Eventhough the bias was being updating, here I let it as 1 because if I apply the last bias, the rocket would just fall. With one, the rocket moves.

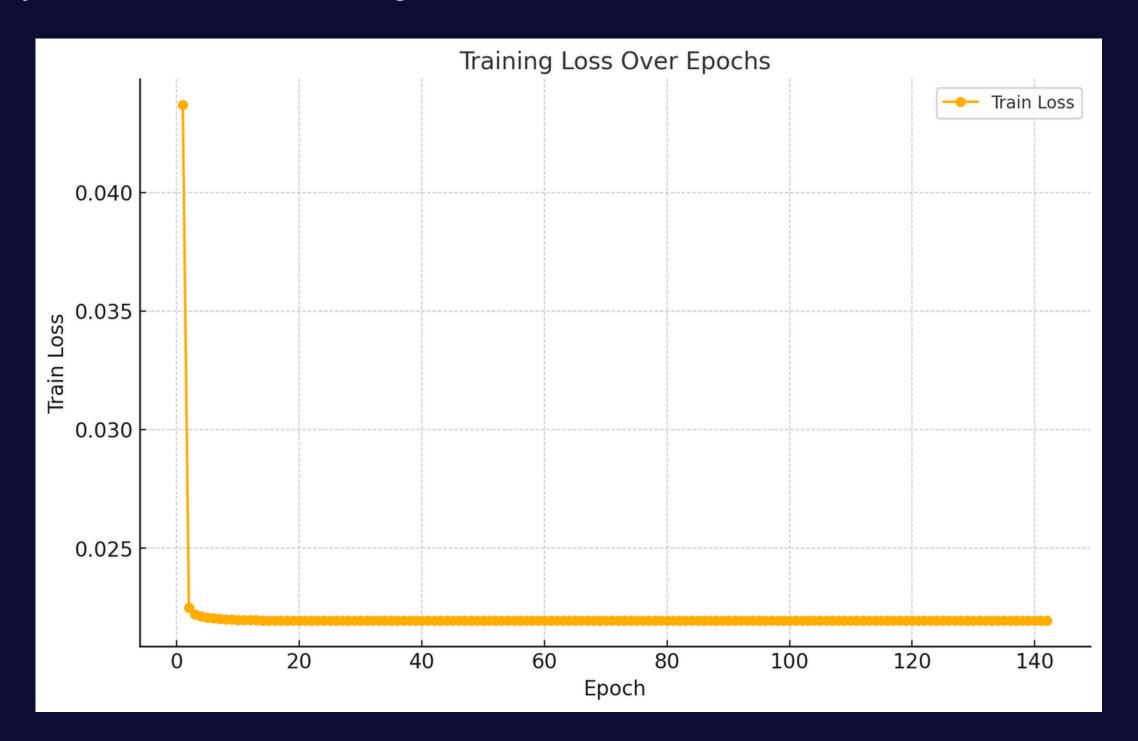
```
def predict(self, input_row):
    x1, x2 = map(float, input_row.split(','))  # Assigning x1,x2 and ensuring its floating type
    # Normalizing the inputs
    x1_normalized = x1 / self.input_scale
    x2_normalized = x2 / self.input_scale

# After the trainning, for this, only forward_propagate is applied
    _, outputs = self.network.forward_propagate(x1_normalized, x2_normalized)

# Taking them to their original sacle
    y1 = outputs[0] * self.input_scale
    y2 = outputs[1] * self.input_scale

# Finally returning the predictions
    return y1, y2
```

After running my try5.py of my neuralnetwork which is being trained with the normalized data, I obtained 150 losses, that in graphic look llike this:



It shows a strong decrease at the beggining and then it stabalizes, which means for these last parameters used, less epochs can be applied.

The performance of my rocket

Some videos of the rocket performance:

https://youtube.com/shorts/LeMxOrQFNtU?feature=share

https://youtube.com/shorts/9aWIaSHWF5U?feature=share

https://youtube.com/shorts/XIR4RJvBst4?feature=share

DEEP LEARING TASK

Rossmann operates over 3,000 drug stores in 7
European countries. Currently, Rossmann store
managers are tasked with predicting their daily sales
for up to six weeks in advance. Store sales are
influenced by many factors, including promotions,
competition, school and state holidays, seasonality,
and locality. With thousands of individual managers
predicting sales based on their unique circumstances,
the accuracy of results can be quite varied.
Reliable sales forecasts enable store managers to
create effective staff schedules that increase
productivity and motivation.



Data Explorer 39.85 MB sample_submission.csv store.csv test.csv train.csv

The files given are: train (contains historical data), test (data to model and predict) and store (to provide additional information about each store).

First of all, preprocessing the data is truly important in order to proceed with the modelling for the predictions

For that, I created a file called Preprocessed.py, in which:

```
mport pandas as pd # Data manipulation
                                                                                                                          train_data = pd.merge(train_data, store_data, how='left', on='Store')
                                                                                                                          test_data = pd.merge(test data, store data, how='left', on='Store')
store_data = pd.read_csv(r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\store.csv")
                                                                                                                          train data['CompetitionOpen'] = 12 * (train data['Year'] - train data['CompetitionOpenSinceYear']) + \
                                                                                                                                                          (train data['Month'] - train data['CompetitionOpenSinceMonth'])
                                                                                                                          test data['CompetitionOpen'] = 12 * (test data['Year'] - test data['CompetitionOpenSinceYear']) + \
store_data['CompetitionDistance'] = store_data['CompetitionDistance'].fillna(store_data['CompetitionDistance'].median())
                                                                                                                                                         (test data['Month'] - test data['CompetitionOpenSinceMonth'])
                                                                                                                          train data['CompetitionOpen'] = train data['CompetitionOpen'].apply(lambda x: max(0, x))
store data['CompetitionOpenSinceMonth'] = store data['CompetitionOpenSinceMonth'].fillna(0)
store\_data['CompetitionOpenSinceYear'] = store\_data['CompetitionOpenSinceYear'].fillna(\theta)
                                                                                                                          test_data['CompetitionOpen'] = test_data['CompetitionOpen'].apply(lambda x: max(0, x))
store data['Promo2SinceWeek'] = store data['Promo2SinceWeek'].fillna(0)
store data['Promo2SinceYear'] = store data['Promo2SinceYear'].fillna(0)
                                                                                                                          train_data['Promo2Open'] = 12 * (train_data['Year'] - train_data['Promo2SinceYear']) + \
                                                                                                                                                     (train_data['WeekOfYear'] - train_data['Promo2SinceWeek']) / 4.0
store data['PromoInterval'] = store data['PromoInterval'].fillna('')
                                                                                                                          test_data['Promo2Open'] = 12 * (test_data['Year'] - test_data['Promo2SinceYear']) + \
                                                                                                                                                    (test_data['WeekOfYear'] - test_data['Promo2SinceWeek']) / 4.0
test data['Open'] = test data['Open'].fillna(1)
                                                                                                                          train_data['Promo2Open'] = train_data['Promo2Open'].apply(lambda x: max(0, x))
                                                                                                                          test_data['Promo2Open'] = test_data['Promo2Open'].apply(lambda x: max(0, x))
train data['Date'] = pd.to datetime(train data['Date'], format='%d/%m/%Y')
test data['Date'] = pd.to datetime(test data['Date'], format='%d/%m/%Y')
                                                                                                                          columns_to_drop = ['Date', 'Customers', 'CompetitionOpenSinceMonth', 'CompetitionOpenSinceYear',
                                                                                                                                              'Promo2SinceWeek', 'Promo2SinceYear', 'PromoInterval']
for dataset in [train data, test data]:
   dataset['Year'] = dataset['Date'].dt.year # Extracting the year
   dataset['Month'] = dataset['Date'].dt.month # Extracting the month
   dataset['Day'] = dataset['Date'].dt.day # Extracting the day
```

Saving the preprocessed datasets and creating the new cleaned files

train_data.to_csv(r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\train_preprocessed.csv", index=False)

test_data.to_csv(r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\test_preprocessed.csv", index=False)

store_data.to_csv(r"C:\Users\Salin\OneDrive\Documentos\ESSEX\Neural Networks\store_preprocessed.csv", index=False)

print("Data preprocessing complete. Preprocessed files saved.")



- Loads the three provided CSV files into Pandas DataFrames for processing.
- Handles Missing Values
- Converts Date columns to DateTime Format
- Extracts Date Features
- Combines the store-specific information from store.csv into the train and test datasets using the Store column as a key.
- Calculates Competition Open Duration
- Calculates Promo2 Active Duration
- Drops columns that are redundant or irrelevant for modeling.
- Saves the preprocessed data in new files to now work with the cleaned data

The way it was cleaned

For handling Missing Data:

- Fills Competition Distance with the median value.
- Fills CompetitionOpenSinceMoth and Year with 0, same with Promo2SinceWeek and Year
- Replaces missing PromoInterval with an empty string.
- Assumes stores in the test data were open if Open was missing.

Feature Engineering:

- Created time-based features:
 - Year, Month, Day, Week of the Year, Day of the Year.
- Derived new features:
 - CompetitionOpen: Duration (in months) since the store's competitor started operating.
 - Promo2Open: Duration (in months) since the store's promotion started.

Integration:

• Merged store.csv with train.csv and test.csv with the Store as key.

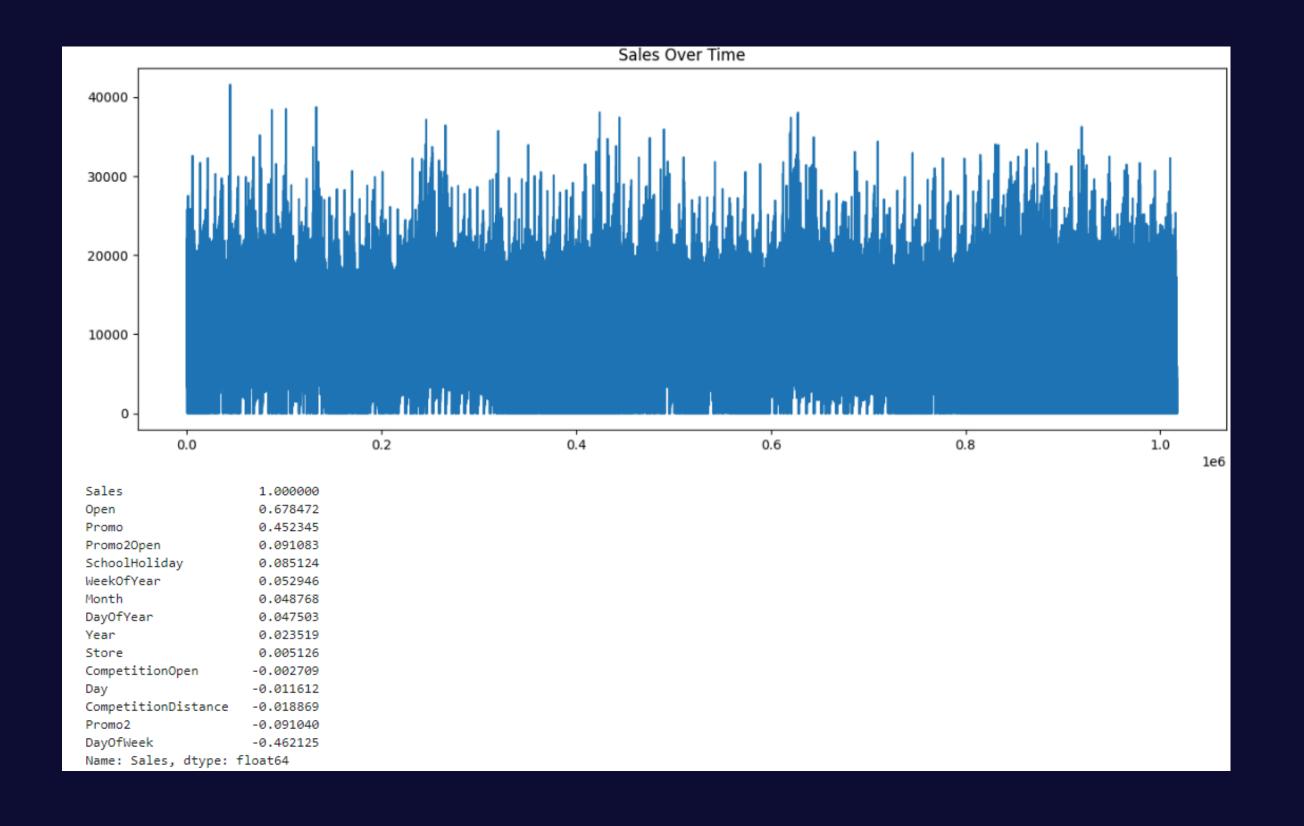
Columns removed:

- Customers: Not available in the test set; could bias the model.
- Promo2SinceYear, CompetitionOpenSinceMonth: Replaced with engineered features.
- Date: Used for extracting time-based features but not directly relevant for training.



The final columns were selected to focus on features that directly affect sales, such as temporal attributes (Year, Month, WeekOfYear), store details (CompetitionDistance, Promo2), and engineered features (CompetitionOpen, Promo2Open) that quantify competition and promotions. The columns no longer existing is beacuase they are redundant or uncosistent in matching, like Date and Customers which were removed to simplify the dataset and ensure consistency.

Some visualization and correlations results



Modelling

With the processed data. I am choosing to work with Feedforward Neural Network (FNN), also known as a Multilayer Perceptron (MLP) for modelling and doing the predictions since after researching I found out that:

- This model is designed specifically for structured/tabular data.
- Neural networks can model complex, non-linear relationships between features and the target variable.
- It works well with large datasets and can handle many features.
- Modern techniques can be applied as: adding dropout, early stopping, and scaling ensures better performance and generalization.

Which suits well with Rossmann Sales proyect, since:

- It has structured/tabular data like the features.
- The dataset is large enough for a neural network to learn meaningful patterns.
- The problem involves complex relationships between features and sales, which FNNs can model effectively.

This model is a Deep Learning model because it has multiple layers, is built using a Deep Learning framework (TensorFlow/Keras), and is designed to learn complex patterns in the data.

FNN: Architecture Overview

• Input Layer: Accepts the preprocessed features, like temporal variables (Year, Month) and store metrics (CompetitionOpen, Promo2Open), ensuring all key factors influencing sales are included.

• Hidden Layers:

- Structure: Three dense layers with decreasing nodes (128, 64, 32).
- Activation: ReLU for capturing non-linear patterns in sales trends.
- Regularization: Dropout layers to prevent overfitting by randomly deactivating nodes during training.
- Output Layer: A single neuron with no activation to predict continuous sales values.
 - Optimization:
 - Loss Function: Mean Squared Error (MSE) to minimize large prediction errors.
 - Optimizer: Adam, for efficient learning and adaptive adjustments to the model's parameters. A popular optimization algorithm that adjusts the learning rate during training.
- Hyperparameters:
 - Epochs: The model is trained for a maximum of 100 epochs, with early stopping implemented to prevent overfitting if the validation loss stops improving.
 - Batch Size: Set to 32, meaning the model processes 32 samples at a time before updating weights. This balances training efficiency and gradient stability.
 - Callbacks: Early stopping is included to monitor validation loss and stop training early if no improvement is observed, optimizing training time.

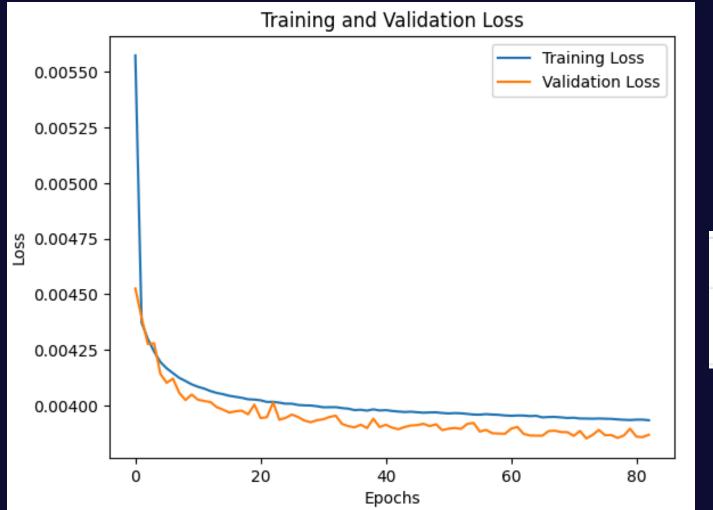
RESULTS

```
# Evaluating the model

val_loss, val_mse = nn_model.evaluate(X_val_scaled, y_val_scaled, verbose=0)
val_rmse_scaled = val_mse ** 0.5
print(f"Validation RMSE (scaled): {val_rmse_scaled:.2f}")

# Converting scaled MSE back to RMSE in the original scale
# Scaler's `data_max_` and `data_min_` to calculate the range
data_range = target_scaler.data_max_[0] - target_scaler.data_min_[0] # Extract scalar values
val_rmse = (val_mse ** 0.5) * data_range # Scale back RMSE
print(f"Validation RMSE (original scale): {val_rmse:.2f}")

Validation RMSE (scaled): 0.06
Validation RMSE (original scale): 2388.28
```





I create a file with the predictions and I upload it to Kaggle which gives me the result:



Thank You

Diego Armando Salinas Lugo

ds24353