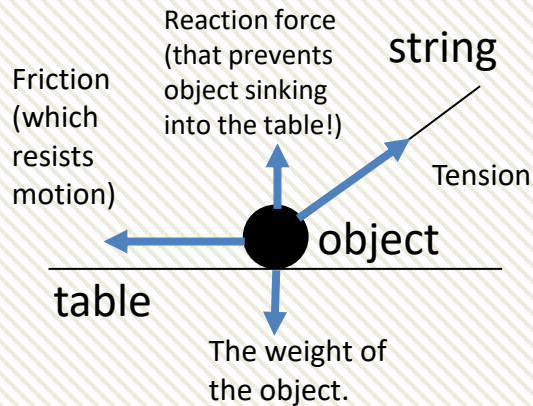

M1 Chapter 8: Modelling

Modelling in Mechanics

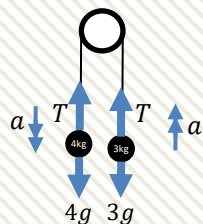
Mechanics, broadly speaking, concerns motion, forces, and how the two interrelate. This chapter just gives you an overview of what you'll be covering in Year 1 and how it all links together.

Forces

You will later encounter force diagrams. This considers the forces acting at a particular point. Some forces you might consider...



- Forces can be considered as vectors.
- The **magnitude** of the force vector gives the 'size' of the force.
- We often **consider forces in a particular direction**. e.g. If the object above is stationary, the forces left must equal the force right, and forces up equal forces down (Newton's 1st Law).
- Often we need to consider the forces at multiple different points if objects are connected, e.g. with pulleys:



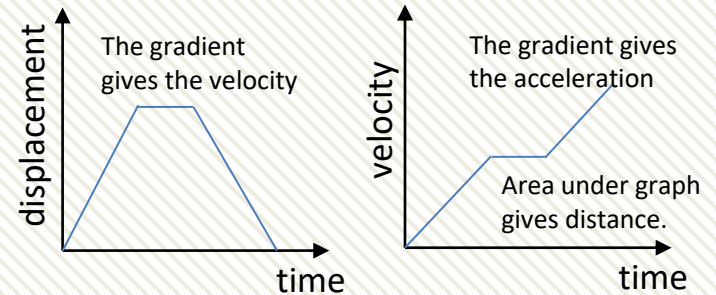
The bridge!

$$F = ma$$

Newton's 2nd Law allows us to connect the force world (F) with the motion world (acceleration a) if the object is moving.

Motion

At GCSE you may have encountered displacement-time and velocity-time graphs:



Given **constant acceleration** we have 5 quantities of motion ("*suvat*"):

s = displacement
 u = initial velocity
 v = final velocity
 a = acceleration
 t = time

which we will see are linked by various equations:

$$s = ut + \frac{1}{2}at^2$$

$$s = \left(\frac{u+v}{2}\right)t$$

$$v^2 = u^2 + 2as$$

$$v = u + at$$

If the **acceleration is not constant**, we can specify displacement/velocity/acceleration as a function of time and differentiate/integrate to change between them.

$$s = 2t^3 + 3t \quad \rightarrow \quad v = \frac{ds}{dt} = 6t^2 + 3$$

Modelling Assumptions

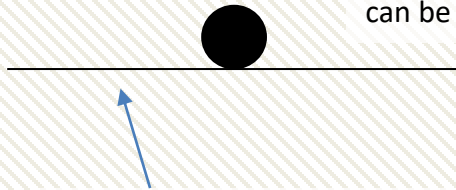
As with many areas of applied maths, we often have to make various modelling assumptions, to make the maths cleaner or to use well-known mathematical approaches.

Here are common modelling assumptions often made in Mechanics: 

Particle

Dimensions of object are negligible

Means: Mass of object concentrated at single point. Rotational forces/air resistance can be ignored.



Rough/Smooth surface

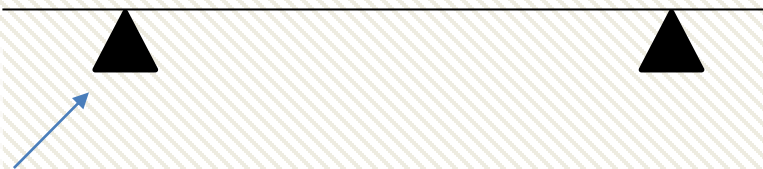
Means: Objects in contact with surface does/does not experience friction.



Peg/Support

A support from which a body can be suspended or rested.

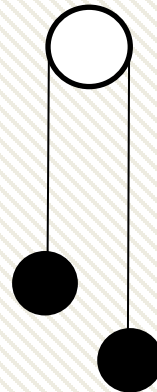
Means: Dimensionless and fixed. Can be rough or smooth depending on question.



Rod

One dimension is negligible, like a pole or beam.

Means: Mass is concentrated along line. Rigid.



Smooth/light pulley

No friction.

Means: Tension the same in string either side of pulley.
Pulley has no mass.

Inextensible string

String does not stretch under load.

Means: Acceleration the same in any connected objects.

Fro Tip:
Particularly make note of underlined text!

Exercise 8A, 8B

Pearson Stats/Mechanics Year 1

- 1) Exercise 8.1 pages 52-53
- 2) Exercise 8.2 pages 53-54

Homework Exercise

- 1 The motion of a golf ball after it is struck by a golfer can be modelled using the equation $h = 0.36x - 0.003x^2$, where h m is the height of the golf ball above the ground and x m is the horizontal distance travelled.
 - a Find the height of the golf ball when it is:
 - i struck
 - ii at a horizontal distance of 100 m.
 - b Use the model to predict the height of the golf ball when it is 200 m from the golfer.
 - c Comment on the validity of this prediction.
- 2 A stone is thrown into the sea from the top of a cliff. The height of the stone above sea level, h m at time t s after it is thrown can be modelled by the equation $h = -5t^2 + 15t + 90$.
 - a Write down the height of the cliff above sea level.
 - b Find the height of the stone:
 - i when $t = 3$
 - ii when $t = 5$.
 - c Use the model to predict the height of the stone after 20 seconds.
 - d Comment on the validity of this prediction.
- 3 The motion of a basketball as it leaves a player's hand and passes through the net is modelled using the equation $h = 2 + 1.1x - 0.1x^2$, where h m is the height of the basketball above the ground and x m is the horizontal distance travelled.
 - a Find the two values of x for which the basketball is exactly 4 m above the ground.

This model is valid for $0 \leq x \leq k$, where k m is the horizontal distance of the net from the player. Given that the height of the net is 3 m:
 - b Find the value of k .
 - c Explain why the model is not valid for $x > k$.

Homework Exercise

- 4 A car accelerates from rest to 60 mph in 10 seconds. A quadratic equation of the form $d = kt^2$ can be used to model the distance travelled, d metres in time t seconds.
- a** Given that when $t = 1$ second the distance travelled by the car is 13.2 metres, use the model to find the distance travelled when the car reaches 60 mph.
- b** Write down the range of values of t for which the model is valid.
- 5 The model for the motion of a golf ball given in question 1 is only valid when h is positive. Find the range of values of x for which the model is valid.
- 6 The model for the height of the stone above sea level given in question 2 is only valid from the time the stone is thrown until the time it enters the sea. Find the range of values of t for which the model is valid.
- 7 A football is kicked by the goalkeeper from one end of the football pitch.
State the effect of the following assumptions on any calculations made using this model:
- a** The football is modelled as a particle. **b** Air resistance is negligible.
- 8 An ice puck is hit and slides across the ice.
State the effect of the following assumptions on any calculations made using this model:
- a** The ice puck is modelled as a particle. **b** The ice is smooth.

Problem-solving

Use the information given to work out the value of k .

Homework Exercise

- 9 A parachute jumper wants to model her descent from an aeroplane to the ground. She models herself and her parachute as particles connected by a light inextensible string. Explain why this may not be a suitable modelling assumption for this situation.
- 10 A fishing rod manufacturer constructs a mathematical model to predict the behaviour of a particular fishing rod. The fishing rod is modelled as a light rod.
- a Describe the effects of this modelling assumption.
 - b Comment on its validity in this situation.
- 11 Make a list of the assumptions you might make to create simple models of the following:
- a The motion of a golf ball after it is hit
 - b The motion of a child on a sledge going down a snow-covered hill
 - c The motion of two objects of different masses connected by a string that passes over a pulley
 - d The motion of a suitcase on wheels being pulled along a path by its handle.



Homework Answers

- 1 a i $h = 0$ ii $h = 6 \text{ m}$
b $h = -48 \text{ m}$.
c Model is not valid when $x = 200$ as height would be 48 m below ground level.
- 2 a 90 m b i $h = 90 \text{ m}$ ii $h = 40 \text{ m}$
c $h = -1610 \text{ m}$
d Model is not valid when $t = 20$ as height would be 1610 m below sea level.
- 3 a $x = 2.30 \text{ m}$ or 8.70 m b $k = 10 \text{ m}$
c When $k = 10$ seconds the ball passes through the net so model not valid for $k > 10$
- 4 a 1320 m
b Model is valid for $0 \leq t \leq 10$
- 5 $0 \leq x \leq 120$
- 6 $0 \leq t \leq 6$
- 7 a Ignore the rotational effect of any external forces that are acting on it, and the effects of air resistance.
b Ignore the frictional effects on the football due to air resistance.
- 8 a Ignore the rotational effect of any external forces that are acting on it, and the effects of air resistance.
b Ignore any friction between the ice puck and the ice surface.
- 9 Parachute jumper and parachute should be considered together as one particle as they move together.
- 10 a If modelled as a light rod, the fishing rod is considered to have no thickness and is rigid.
b If the fishing rod had no thickness and was rigid it would be unsuitable for fishing.
- 11 a Model golf ball as a particle, ignore the effects of air resistance.
b Model child on sledge as a particle, consider the hill as smooth.
c Model objects as particles, string as light and inextensible, pulley as smooth.
d Model suitcase and handle as a particle, path as smooth, ignore friction.

Homework Answers
