DB 2

12 - Joins

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Torsten Grust Universität Tübingen, Germany

1 Q₁₁: One-to-Many Joins

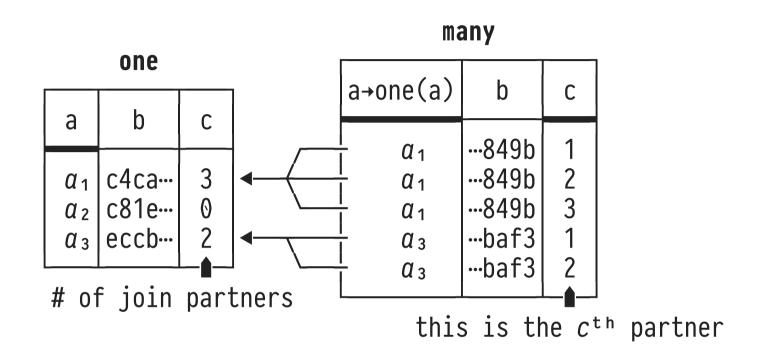


Join (⋈) is a core operation in query processing: given two tables,¹ form all pairs of related rows.

- A one row relates to 0...n rows of many: 1:n relationship.
 ⇒ Join size ∈ {0,...,n × |one|} rows. Largest possible result if n = |many| (Cartesian product).
- ¹ Note: the left and right tables may indeed be the same table. This is then coined a self-join.

A Sample One-to-Many Relationship (Playground)





- Join predicates:
 - 1. one.a = many.a (index-supported)
 - 2. md5(one.a) = one.b || many.b (||: string concat)

PostgreSQL: Join Algorithms



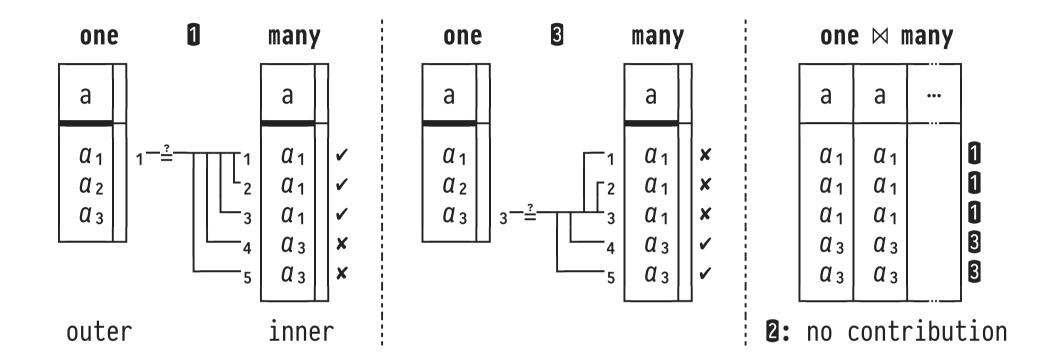
RDBMSs choose between several join algorithms based on

- the join **predicate type** (equi-join vs. θ -join)
- the existence of indexes on the join predicate columns,
- the availability of working memory, or
- interesting sort orders of join inputs and output:

Join Algorithm	Characteristic
	processes any θ , can benefit from index support
Hash Join	fast equi-joins if plenty working memory available
Merge Join	requires sorted input, produces sorted output

PostgreSQL implements all three kinds of join algorithms.





- Iterate 1...3 over rows of outer table (here: one) once.
 - For every outer row, iterate over inner table.
- Performs | outer | × | inner | join predicate evaluations.

Nested Loop Join (NL⋈) — "The Fallback"



- No restrictions regarding $\theta \in \{=, <, \leq, <>, \ldots\}$.
- No restrictions regarding sort order of outer/inner.
- Preserves sort order of *outer*.
- Indexes on *outer/inner* are ignored. ∇
- Benefits if inner can be iterated over quickly (e.g., materialized and/or fits into database buffer).

Block Nested Loop Join (BNL⋈)



```
BlockNLJ(outer,inner,\theta):

j = \phi;

foreach block (of size b_0) bo \epsilon outer

\begin{bmatrix} \text{for } o \in bo \\ & \text{for } i \in bi \\ & & \text{inside the buffer} \end{bmatrix}

entirely performed inside the buffer

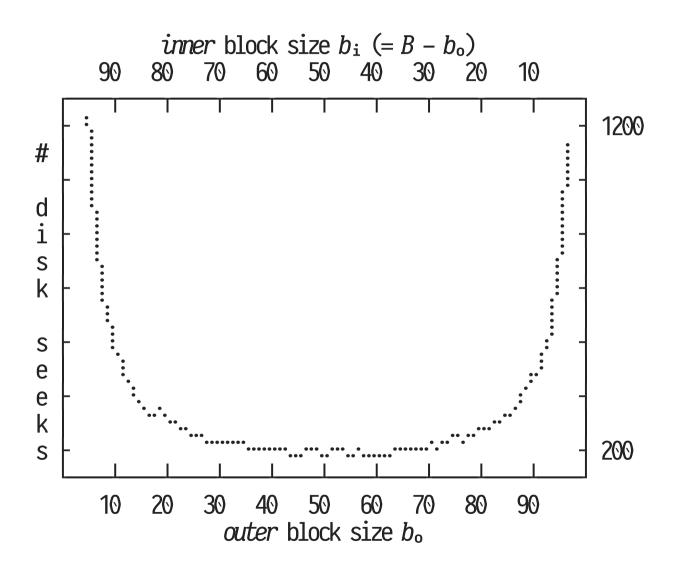
return j;
```

- Perform blocked I/O on outer/inner: less disk seeks.

 → # seeks on outer: [|outer|/b₀].
 - \circ # seeks on inner: $\lceil |outer|/b_o \rceil \times \lceil |inner|/b_i \rceil$.

Sharing a Buffer of Size B = 100 Slots





NL⋈: Materialization of the Inner Input



The inner $NL\bowtie$ input is scanned $\lceil |outer|/b_o \rceil$ times (see PostgreSQL EXPLAIN plans: \cdots loops=n \cdots).

- Plan operator Materialize:
 - 1. Evaluates its subplan once, saves rows in working memory or temporary file ("tuple store").
 - 2. Can scan tuple store more quickly than regular heap file pages (e.g., no xmin/xmax checking).

```
QUERY PLAN

:
-> Materialize (cost=...) (actual time=... loops=n)
-> \[ Subplan (cost=...) (actual time=... loops=1) \]
```



NL⋈ may be sped up considerably if the |outer| scans of inner can be turned into |outer| index scans on inner:

```
IndexNLJ(outer,inner,0):

j = \phi;

for o \in outer

for i \in Index[Only]Scan(I, o 0 <math>\Box)

for i \in Index[Only]Scan(I, o o condition)

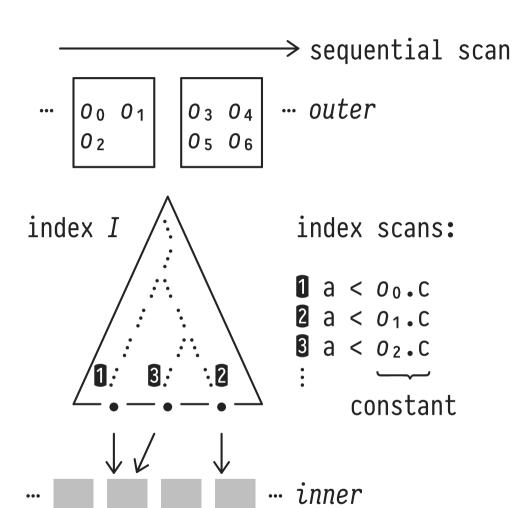
return finite{finite}

index condition
```

- N.B.: In each of the |outer| invocations of IndexScan, row o essentially is a constant.
 - \circ Index I on *inner* must be able to support predicate θ .
- The index scan only delivers actual partners for o. 🖒

Index Nested Loop Join (INL⋈)





```
CREATE INDEX I ON many USING btree (a);

SELECT *
FROM one AS o, -- outer many AS m -- inner WHERE m.a < o.c;
```



Join algorithm **Merge Join** supports equality join predicates ("equi-joins") of the form $c_1 = c_r$:

- 1. left input must be sorted by c_1 , right input must be sorted by c_r ,
- 2. left input scanned once in order, right input scanned once but must support repeated *re-scanning* of rows,
- 3. the **join output is sorted** by c_1 (and thus c_r).
- NB. Merge Join's guaranteed output order can provide a true benefit during later query processing stages.

² Generalizations to predicates c_1 θ c_r with θ ϵ {<, ϵ , ...} have been defined but are seldomly found implemented in actual RDBMSs.



Merge Join performs synchronized forward (≡ sorted) scans:³

- Maintain row pointers into left/right inputs (←/→).
- Iterate:
 - Move row pointers forward in lock step:
 - If $c_1 < c_r$, advance ←. If $c_1 > c_r$, advance →.
 - If $c_1 = c_r$, emit joined row.
 - ∘ If required, save current position $(\frac{1}{2})$ of → so that we can reset $(\frac{1}{2})$ the scan of the right input back to $\frac{1}{2}$.
 - This resetting may lead to (limited) re-scanning of the right input.

³ Arrow symbols \leftarrow , \rightarrow , $\frac{1}{2}$, $\hat{\cdot}$ refer to the illustration on the next slide. Only the join columns c_1 , c_r (of type int) are shown.

Merge Join: Synchronized Scan Pointers



$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	$ \begin{array}{c cccc} & c_1 & c_r \\ & 1 & 2 & 3 \\ & 2 & 3 & 3 \\ & 4 & 4 & 4 \\ & 5 & & & & \\ \end{array} $	$ \begin{array}{c c} \hline c_1 \\ \hline c_r \\ \hline 2 \downarrow \\ 3 \\ 3 \\ 4 \\ 4 \\ 4 \\ 5 \end{array} $	$ \begin{array}{ c c c c } \hline c_1 & c_r \\ \hline 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 4 \\ 5 & & \\ \end{array} $	$ \begin{array}{c ccc} \hline c_1 \\ \hline c_r \\ \hline 2 \\ 3 \\ 4 \\ 4 \\ 4 \\ 5 \end{array} $	$ \begin{array}{c c} \hline c_1 & c_r \\ \hline 1 & 2 \\ 2 & 3 \pm \\ 3 & 4 \\ 4 & 4 \\ 5 & & 4 \end{array} $
$ \begin{array}{ c c c c } \hline c_1 & c_r \\ \hline 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 4 \\ 5 & & 4 \end{array} $	$ \begin{array}{c cccc} & c_1 & c_r \\ & 1 & 2 & \\ & 2 & 3 & \\ & 3 & \\ & 4 & \downarrow & \\ & 4 & \downarrow & \\ & 5 & & & \\ \end{array} $	$ \begin{array}{ c c c } \hline c_1 & c_r \\ \hline 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 4 \\ 5 & \rightarrow \\ \hline \end{array} $	$ \begin{array}{c c} \hline c_1 & c_r \\ \hline 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 4 \\ 5 & \hline{\hat{z}} \end{array} $	$ \begin{array}{ c c c c c } \hline c_1 & c_r \\ \hline 1 & 2 & \\ 2 & 3 & \\ 3 & 4 & \\ 4 & & 4 & \\ 5 & & & 4 \end{array} $	$ \begin{array}{c c} \hline c_1 & c_r \\ \hline 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 4 \\ 5 & \rightarrow \\ \end{array} $

Merge Join: Pseudo Code



```
MergeJoin(left, right, c_1, c_r):
 j \leftarrow \phi;
 while left \neq \frac{\pi}{4} \wedge right \neq \frac{\pi}{4}
                                      } reached end-of-table?
    while left.c_1 < right.c_r
     | advance left;
                                        move scans forward
    while left.c_1 > right.c_r
                                        in lock step
     | advance right;
    \pm + right;
                                       save current right pos
    while left.c_1 = \pm .c_r
                                     } scan repeating left group
                                      } reset right scan
        right + ±;
        while left.c_1 = right.c_r
           append <left, right> to j;
          advance right:
        advance left;
 return j;
```

Merge Join: Sorted Inputs



Merge Join requires inputs sorted on c_1/c_r . Options:

- 1. Introduce explicit Sort plan operator below Merge Join.
- 2. Input is Index Scan with key column prefix c_1/c_r .
- 3. Input table is (perfectly) clustered on c_1/c_r .
- 4. Subplan below Merge Join delivers rows in c_1/c_r order.

```
QUERY PLAN

Merge Join (cost=...) (actual time=... loops=n)

-> \[ Subplan left (cost=...) (actual time=... loops=1) \]

-> \[ Subplan right (cost=...) (actual time=... loops=1) \]
```

⁴ Q: Will Bitmap Index/Heap Scan also fit the bill here?

Merge Join: Re-Scanning the Right Input



Since Merge Join may need to reset the pointer in *right*, its subplan is required to support re-scanning of rows:

- Supported by Index Scan and in-memory buffers, but may be impossible and/or costly for complex subplans.
- Place Materialize above *right* to support re-scan:

```
QUERY PLAN

Merge Join (cost=...) (actual time=... loops=...)

-> 「Subplan left (cost=...) (actual time=... loops=1)

-> 「Aterialize (cost=...) (actual time=... loops=1)

-> 「Subplan right (cost=...) (actual time=... loops=1)

L
```

Interesting Orders



If a subplan *delivers* rows in a well-defined **interesting order**, the *downstream* query plan may

- save an explicit Sort operator—e.g., to implement ORDER BY or GROUP BY—that now becomes obsolete,
- employ order-dependent operators at no extra cost.

May reduce overall plan cost, even if the subplan itself does not benefit: sorting effort will only pay off later.

 Nested Loop Join and Merge Join can deliver rows in such interesting orders.

Merge Join: Low Memory Requirements



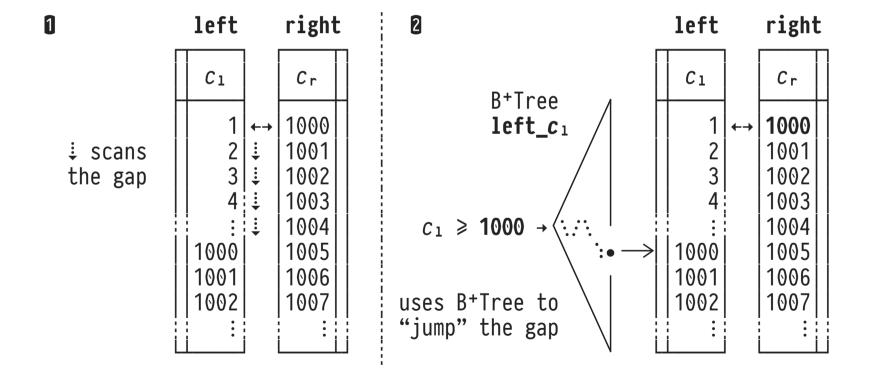
Hash Join (see below) is the go-to equi-join algorithm in modern RDBMSs including PostgreSQL. If memory is tight, however, Merge Join may be superior:

- If inputs are sorted, the actual *merging* requires as few as 3 buffer pages (2×input + 1×output).
 - Requirement: right needs no re-scanning, e.g., if
 left.c₁ is unique.
 - See Merge Join plan property: Inner Unique: true.
 - Algorithm MergeJoinUnique(left,right,c1,cr) requires no management of ± at all. Q: Simplified code?

Challenges for Merge Join



- Large groups of repeating values in right input (i.e., positions of ± and → diverge). Q: Worst case?
- Large $left.c_1 \leftrightarrow right.c_r$ gaps. Consider $\mathbf{0}$:





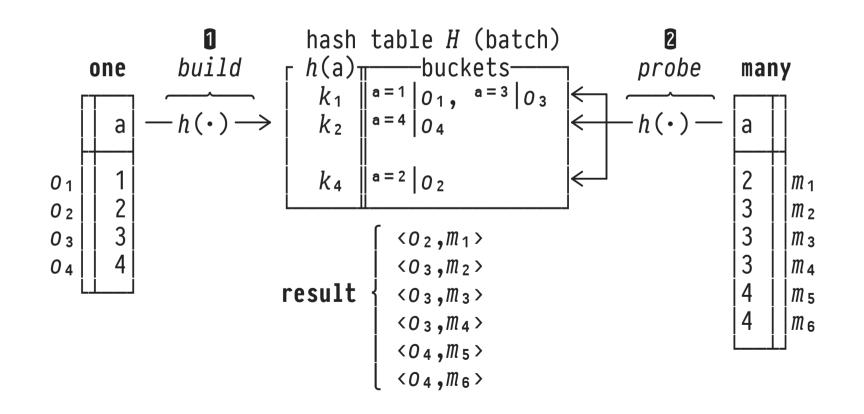
Equi-joins—e.g., foreign-key joins—are arguably the most prominent kinds of relational join. Merge Join relies on sorting while **Hash Join** uses hashing to perform equi-joins:

- 1. **Build:** Read and hash the rows of one input table to populate a **hash table** H. Requires memory to store H.
- 2. **Probe:** Iterate over and hash rows of other input table. Find potential join partner rows in hash bucket of H.
- If |H| > working memory, partition the build/probe tables, iterate phases (**Hybrid Hash Join**).
- Hash Join does not require input order and does not guarantee output order.

Hash Join: -- FROM one AS o, many AS m WHERE o.a = m.a



- Build + Probe: Apply hash function $h(\cdot)$ to columns a.
- **Probe:** Evaluate join predicate o.a = m.a for entries in hash bucket with key $k_i = h(m.a)$ only.



Hash Join: Pseudo Code



```
HashJoin(build, probe, c_1, c_r):
  j \leftarrow \phi;
  H \leftarrow [];
                                                     } empty hash table
   for b \in build
                                                                      1 build
    insert b into bucket H[h(b.c_1)];
   for p \in probe
      for b \in H[h(p.c_r)]

| if b.c_1 = p.c_r

| append \langle b,p \rangle to j;
   return j;
```



```
QUERY PLAN

Hash Join (cost=--) (actual time=-- loops=--)
Hash Cond: (-- = --)
-> 「Subplan probe (cost=--) (actual time=-- loops=1)
-> 「Hash (cost=--) (actual time=-- loops=1)
-> 「Subplan build (cost=--) (actual time=-- loops=1)

L
```

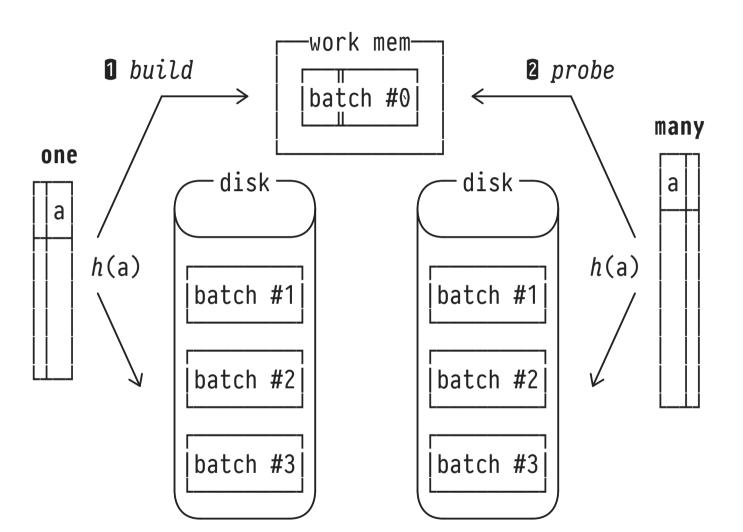
- Use smaller join input for build phase (reduces |H|).
- Indexes on *build* and *probe* inputs remain unused, even if defined on join predicate columns.

Multiple Rounds: (Parallel) Hybrid Hash Join



- Input in round 0: tables one and many.
- Input in round i≥1: batches #i read from temp files.
- Prepare 2ⁿ batches,
 first n bits of h(a)
 determine batch #:

batches #0: 00... #1: 01... #2: 10... #3: 11...





- If working memory cannot hold entire hash table H, use hash key $h(\cdot)$ to split build input into 2^n batches.
 - Probe input hashed into batch #0 is joined as usual (round 0).
 - ∘ All other batches processed in 2ⁿ-1 rounds (in //).
- Allocate additional skew batch in working memory:

Place row t in $\left\{\begin{array}{l} \text{skew batch, if } t.\text{a among most common a-values in } probe \text{ input,} \\ \text{batch } \#i \ , \text{ based on } h(t.\text{a}), \text{ otherwise.} \end{array}\right.$

6 | Q₁₁: Equi-Joins in MonetDB





```
SELECT o.b AS b1, m.b AS b2
FROM one AS o,
many AS m
WHERE o.a = m.a
```

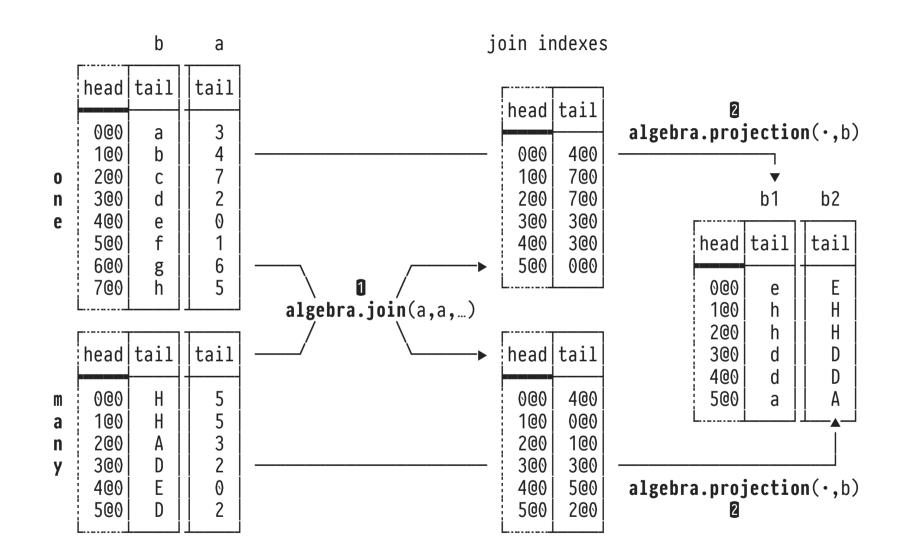
Since database instances reside on hosts with plenty of RAM, **Hash Join** is the go-to join method for MMDBMSs.

In MonetDB, a join computes **join index** BATs⁵ to identify rows in one, many that find a join partner.

⁵ Much like filtering is implemented in terms of **selection vectors**.

Equi-Joins and Join Indexes in MonetDB

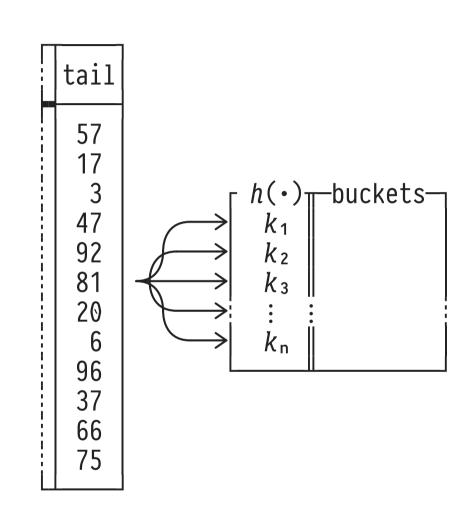




Partitioning BATs Into (Too) Many Buckets

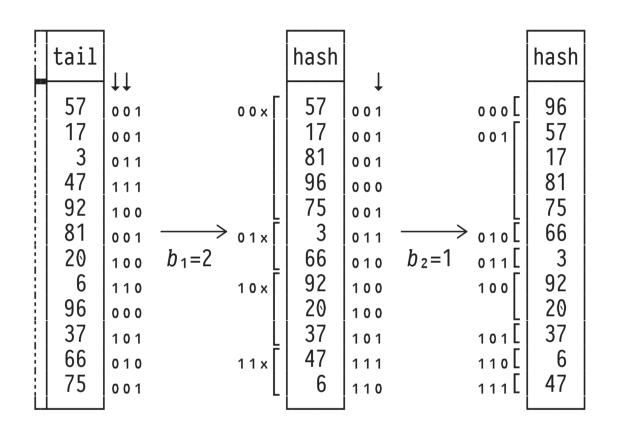


- To prepare Hash Join, use
 h(·) to distribute rows into hash buckets.
- Requires random writes into n different memory locations.
- If *n* is (too) large:
 - Cache thrashing (# of cache lines exceeded). ♥
 - ∘ TLB⁶ misses. ♥
- Reduce number of buckets considered at any one time.



⁶ The CPU's *Translation Lookaside Buffer* stores recent translations from virtual into physical memory locations.





- To distribute by B bits in p passes:
 - 1 Define b_i such that

$$B = \sum_{i=1}^{p} b_i$$

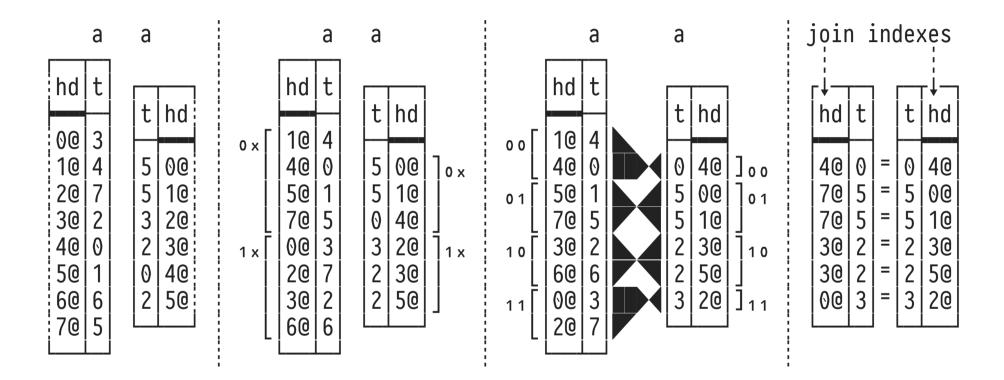
- 2 In pass i, distribute by b_i bits of the hash.
- # of buckets created:

ullet Only write to 2^{b_i} buckets in each pass to avoid cache thrashing and TLB misses.

Radix-Cluster Equi-Join in Q_{11} (o.a = m.a)



• Two-pass (p = 2) radix-clustering with $b_1 = b_2 = 1$:



Rows for cluster-local joins → fit into the CPU cache.