# **Understanding Principal Components Analysis for spectral analysis**

#### **Understanding Principal Components Analysis for spectral analysis**

Preamble

Note

Introduction

Setting things up: spectra as vectors

Spectra as dependent vectors

#### **Preamble**

The goal of this at this point is to understand Principal Components Analysis (PCA) in scikit-learn.decomposition.

I have done this by writing a sequence of tests that helped me understand what was going on.

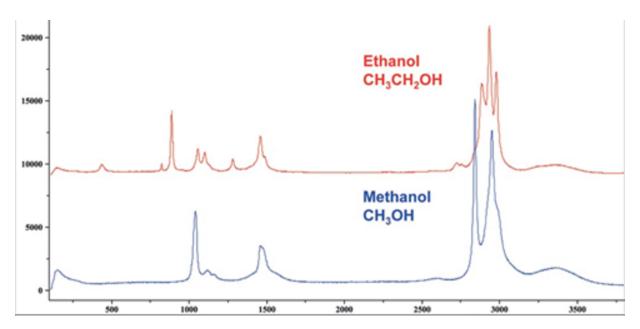
This document is a work in progress and sections will improve with my understanding.

#### **Note**

Use <u>Typora</u> to read this document to see the equations.

### Introduction

Spectroscopy is the optical method of choice to detect substances or identify tissues. We have learned from very early on that identifying the peaks in a spectrum can be done to infer the substances in our sample. For instance, if we have pure substances, it is relatively easy to identify Ethanol and Methanol with their Raman spectra, because their shapes are significantly different and many peaks do not overlap:



It may even be possible to separate both substances if we have a mixture of the two, by fitting  $c_e S_(\nu)_e + c_m S(\nu)_m$  to find the appropriate concentrations that can explain our final combined spectrum. However, what do we do if we have a mixture of several solutions? What if several peaks overlap? What if we don't know the original spectra?

We know intuitively that if peaks belong to the same molecule, they should vary together. If by chance none of the peaks from the different analytes overlap, then it becomes trivial: we only need to identify the peaks, find their amplitudes, and we will quickly get the concentrations of the respective analytes. But things get complicated if they have overlapping peaks, and even worse if we have more than a few components.

## Setting things up: spectra as vectors

From a mathematical point of view, we can consider a spectrum as a **vector** of intensities:

$$\mathbf{I} = \sum_{i=1}^{n} I_i \hat{\boldsymbol{\nu}}_i, \tag{1}$$

where each individual frequency  $\nu_i$  is in its own dimension, with  $\hat{\nu}_i$  the base vectors and  $I_i$  is the intensity at that frequency. Therefore, if we have 1024 points in our intensity spectrum  $\mathbf{I}$ , we are in an N-dimensional space, with the components being  $(I_1,I_2,\ldots I_N)$ , and we should assume (at least for now) that these components are all independent. If we define the norm of a vector from the dot product, we can say that the norm is equal to:

$$|\mathbf{I}|^2 = \sum_{i=1}^n I_i \hat{\nu}_i \cdot \sum_{j=1}^n I_j \hat{\nu}_j = \sum_{i=1}^n \sum_{j=1}^n I_i I_j \, \hat{\nu}_i \cdot \hat{\nu}_j = \sum_{i=1}^n |I_i|^2$$
 (2)

since the spectral base vectors  $\hat{\nu}_i$  are all orthonormal, which we can use to normalize a spectrum (or a vector). Finally, it is very convenient to work with matrix notation to express many of these things. We can express the spectrum  $\mathbf{I}$  in the basis  $\{\hat{\nu}_i\}$  with:

$$\mathbf{I} = \sum_{i=1}^{n} I_i \hat{\boldsymbol{\nu}}_i = (\hat{\boldsymbol{\nu}}_1 \ \hat{\boldsymbol{\nu}}_2 \dots \hat{\boldsymbol{\nu}}_n) \left( I_1 \ I_2 \dots I_n \right)^T = (\hat{\boldsymbol{\nu}}_1 \ \hat{\boldsymbol{\nu}}_2 \dots \hat{\boldsymbol{\nu}}_n) \begin{pmatrix} I_1 \\ I_2 \\ \dots \\ I_n \end{pmatrix} \tag{3}$$

If we consider these matrices as partitions, we can write in a form even more compact as:

$$\mathbf{I} = \hat{\nu} \cdot [I]_{\nu} \tag{4}$$

where the notation  $[I]_{\nu}$  means "the intensity coefficients in base  $\nu$  to multiply the base vectors  $\hat{\nu}$  and obtain the vector (spectrum)". We will use the transpose notation to keep expressions on a single line when needed.

Note that the vector itself  $\mathbf{I}$  is different from the *components of that vector in a given basis*  $[I]_{\nu}$ . For more information about the notation for vector, base vectors and coefficients:

- Read <u>Greenberg Section 10.7</u> on bases and base changes.
- Watch the video (in French) that explains in even more details where this comes from.
- Watch <u>an example</u> (in French) for problem 10.7.1 that discussed an application of this notation and formalism to perform a base change.

## Spectra as dependent vectors

However, we know from experience that in a spectrum, intensities are not completely independent: for instance, in the methanol spectrum above, the peak around 1000 cm<sup>-1</sup> has a certain width and therefore those intensities are related and are not independent. In fact, for the spectrum of a single substance, *all intensities* are related because they will come from a scaled version of the original spectrum. Therefore, if we have the reference methanol spectrum for a unity concentration:

$$\hat{\mathbf{B}}_{M} = \sum_{i=0}^{n} I_{M,i} \hat{\boldsymbol{\nu}}_{i},\tag{5}$$

where  $I_{M,i}$  is the relative intensity at that frequency  $\nu_i$  any other solution of methanol of scalar concentration  $c_M$  would simply yield the spectrum:

$$\mathbf{I} = c_M \mathbf{\hat{B}}_M = c_M \sum_{i=0}^n I_{M,i} \hat{\nu}_i. \tag{6}$$

So if we have several base solutions  $\left\{\hat{\mathbf{B}}_{j}\right\}$  from which we create a mixture of concentrations  $c_{j}$ , we can write its spectrum  $\mathbf{I}$  as:

$$\mathbf{I} = \sum_{i} c_{j} \hat{\mathbf{B}}_{j} = \left(\hat{\mathbf{B}}_{1}, \hat{\mathbf{B}}_{2}, \dots, \hat{\mathbf{B}}_{n}\right) \left(c_{1}, c_{2}, \dots, c_{n}\right)^{T} = \hat{\mathbf{B}}[c]_{\mathbf{B}}$$

$$(7)$$

Again, we read the last expression  $[c]_{\mathbf{B}}$  as "the coefficients in base  $\{\mathbf{B}\}$  to multiply the base vectors  $\mathbf{B}_i$  to obtain the final spectrum  $\mathbf{I}$ ". It stresses the point that the vector  $\mathbf{I}$  and its components in a given basis are not the same thing. This will become critical below when we look a Principal Components.

Finally, if we want to describe a collection of m spectra obtained from mixing these base solutions  ${\bf B}$  with concentrations  $c_{ij}$  for the i-th spectrum and the j-th base solution, we can write:

$$\mathbf{I}_i = \sum_j c_{ij} \hat{\mathbf{B}}_j. \tag{8}$$

This can be rewritten in matrix notation:

$$(\mathbf{I}_{1}, \mathbf{I}_{2}, \dots, \mathbf{I}_{n}) = (\hat{\mathbf{B}}_{1}, \hat{\mathbf{B}}_{2}, \dots, \hat{\mathbf{B}}_{n}) \begin{pmatrix} c_{11} & c_{21} & \dots & c_{m1} \\ c_{12} & c_{22} & \dots & c_{m2} \\ \dots & \dots & \dots & \dots \\ c_{1n} & c_{2n} & \dots & c_{mn} \end{pmatrix}$$
(9)

to yield this very compact form:

$$\mathbf{I} = \hat{\mathbf{B}}[\mathbf{C}]_{\mathbf{B}} \tag{11}$$